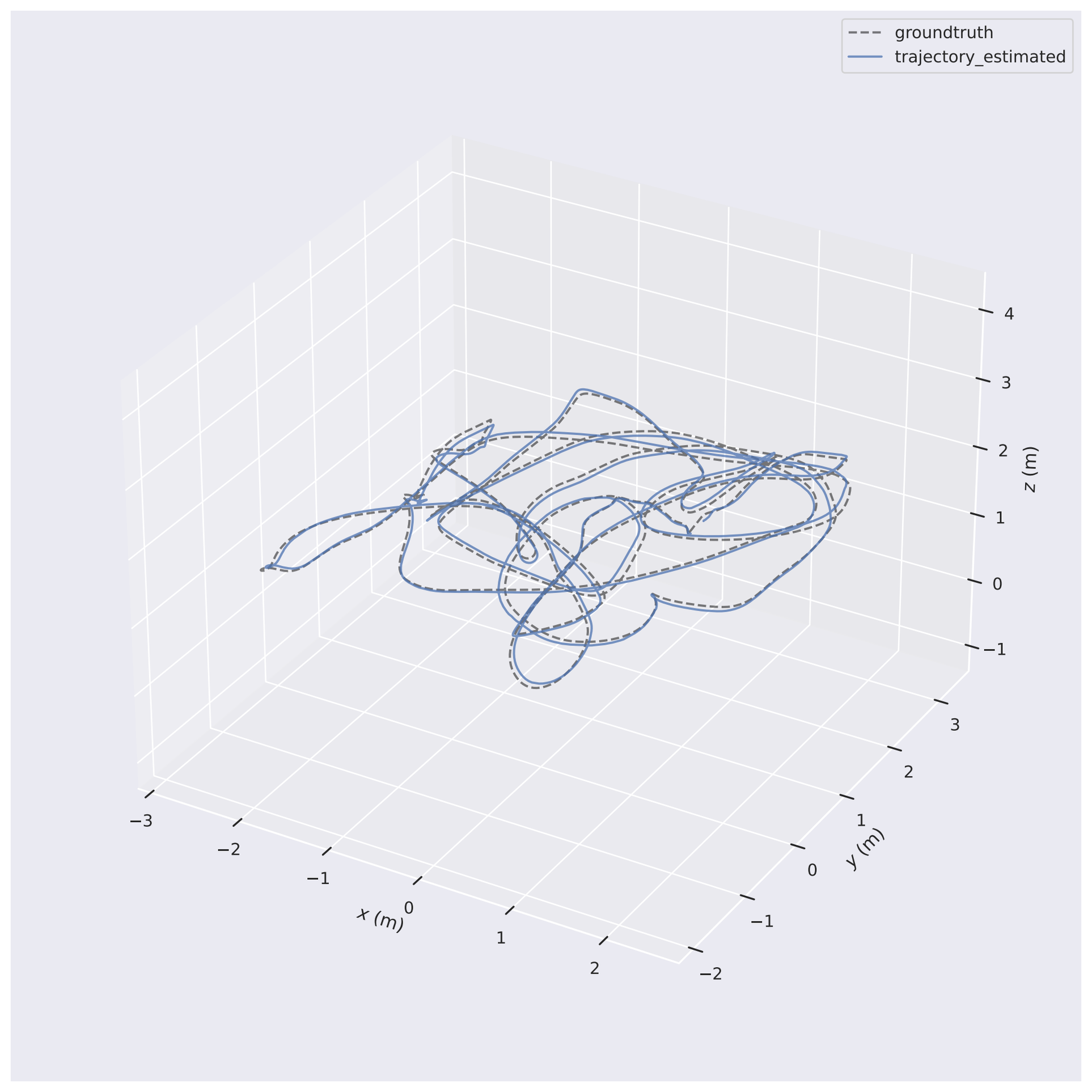
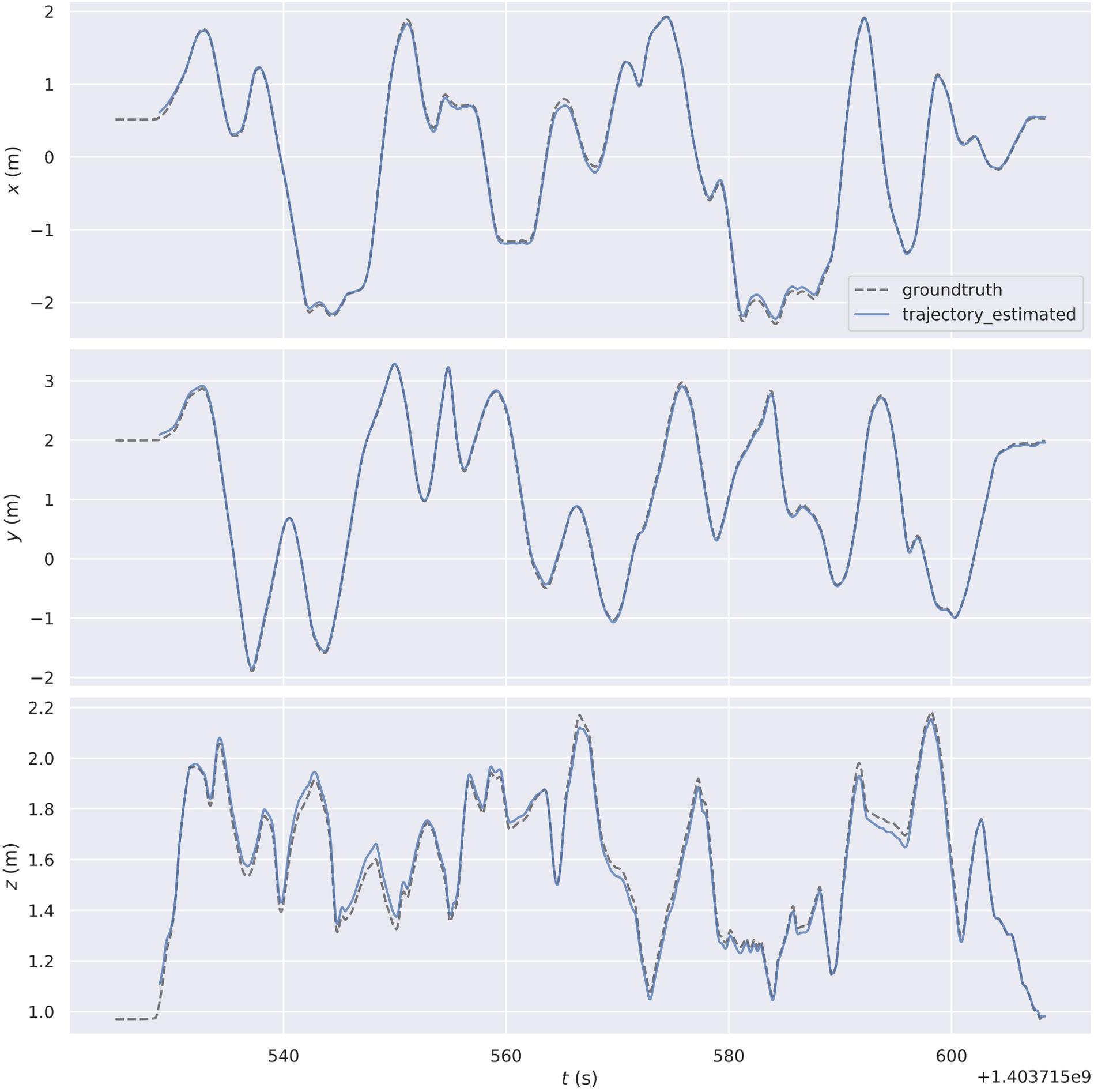
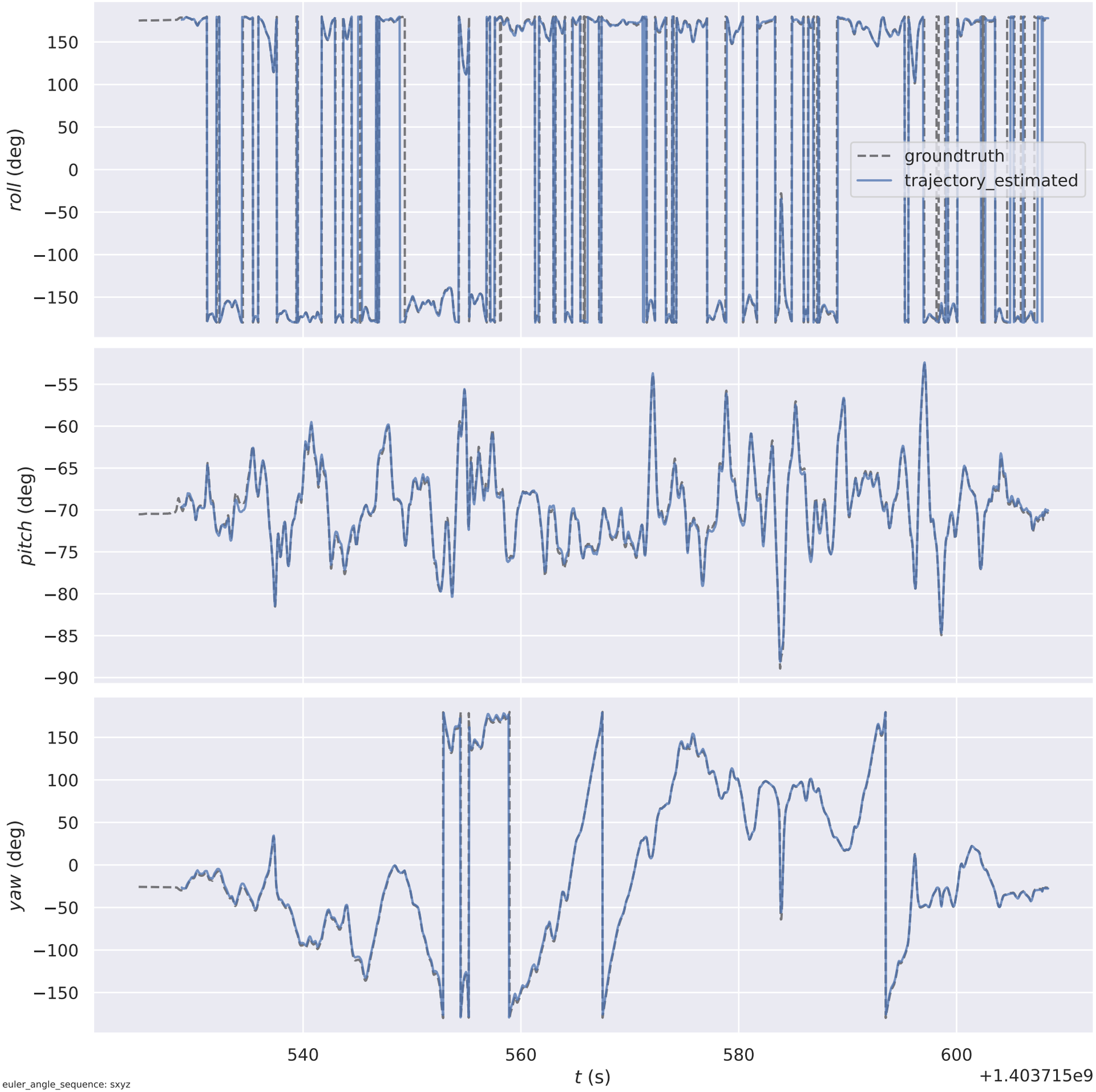
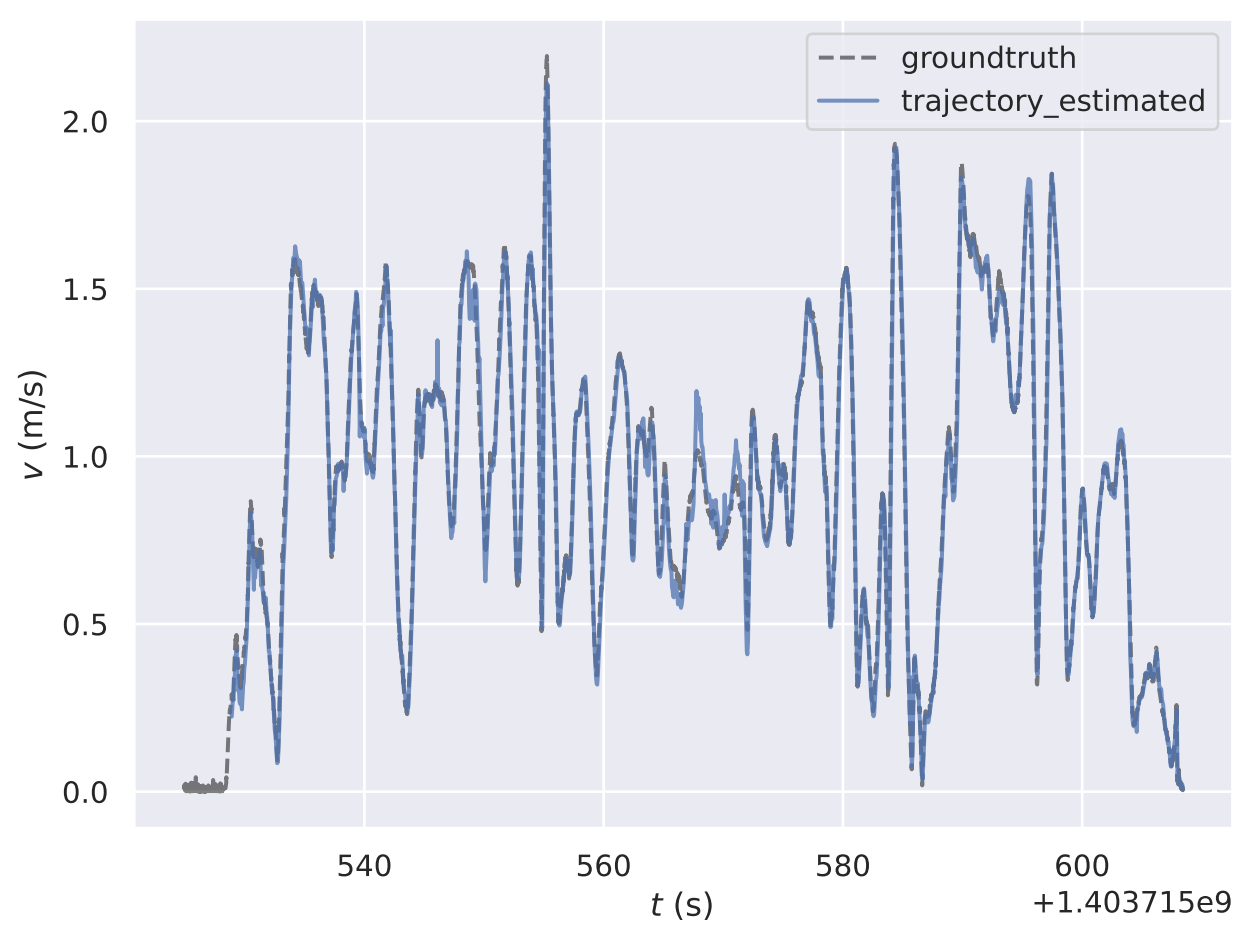

groundtruth
trajectory_estimated
x (m)
y (m)
z (m)
−3
−2
−1
0
1
2
−2
−1
0
1
2
3
−1
0
1
2
3
4


x (m)
y (m)
z (m)
groundtruth
trajectory_estimated
540
560
580
600
t (s)
+1.403715e9


roll (deg)
pitch (deg)
yaw (deg)
groundtruth
trajectory_estimated
t (s)
+1.403715e9
euler_angle_sequence: sxyz


groundtruth
trajectory_estimated
2.0
1.5
1.0
0.5
0.0
v (m/s)
540
560
580
600
t (s)
+1.403715e9