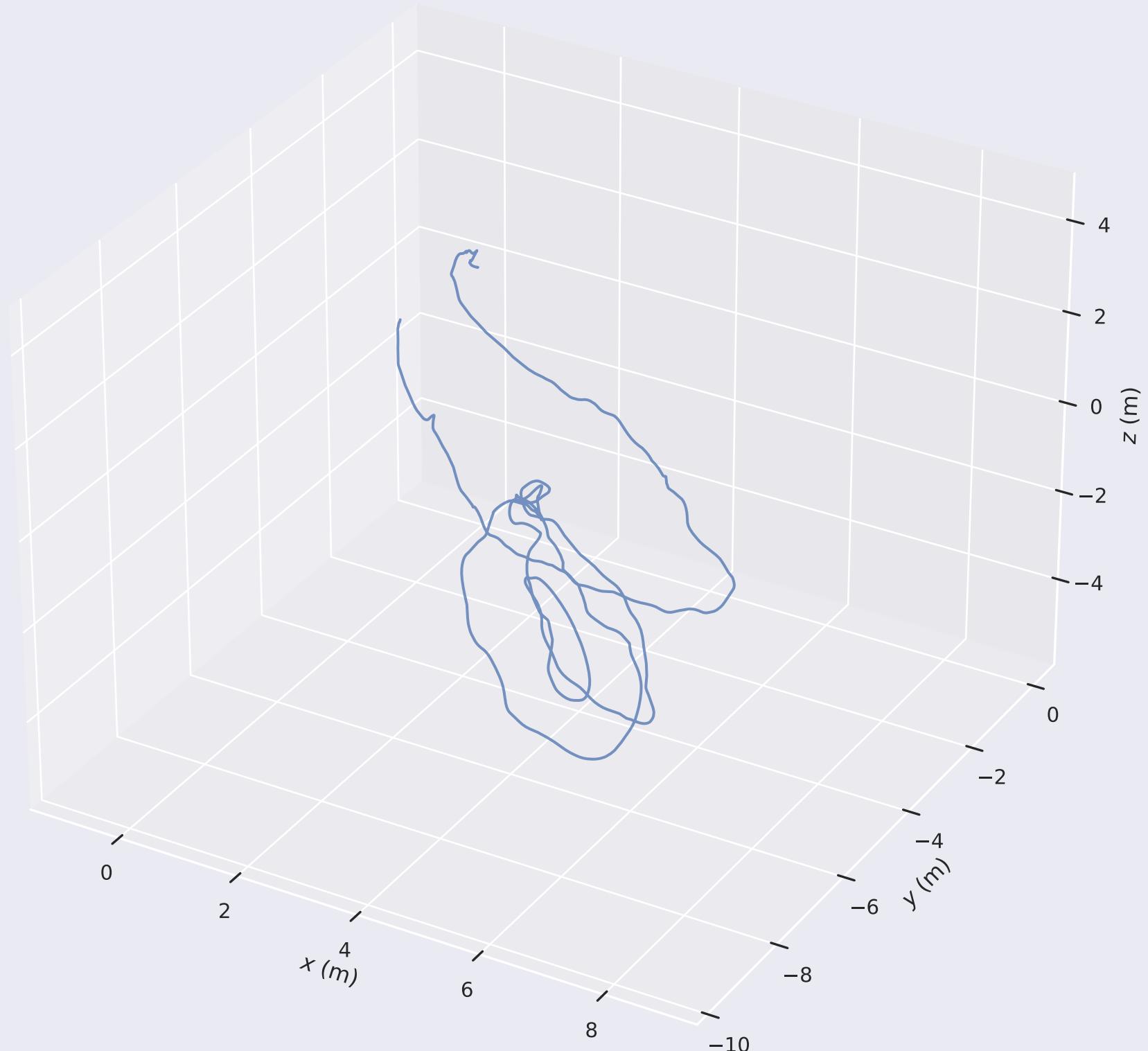
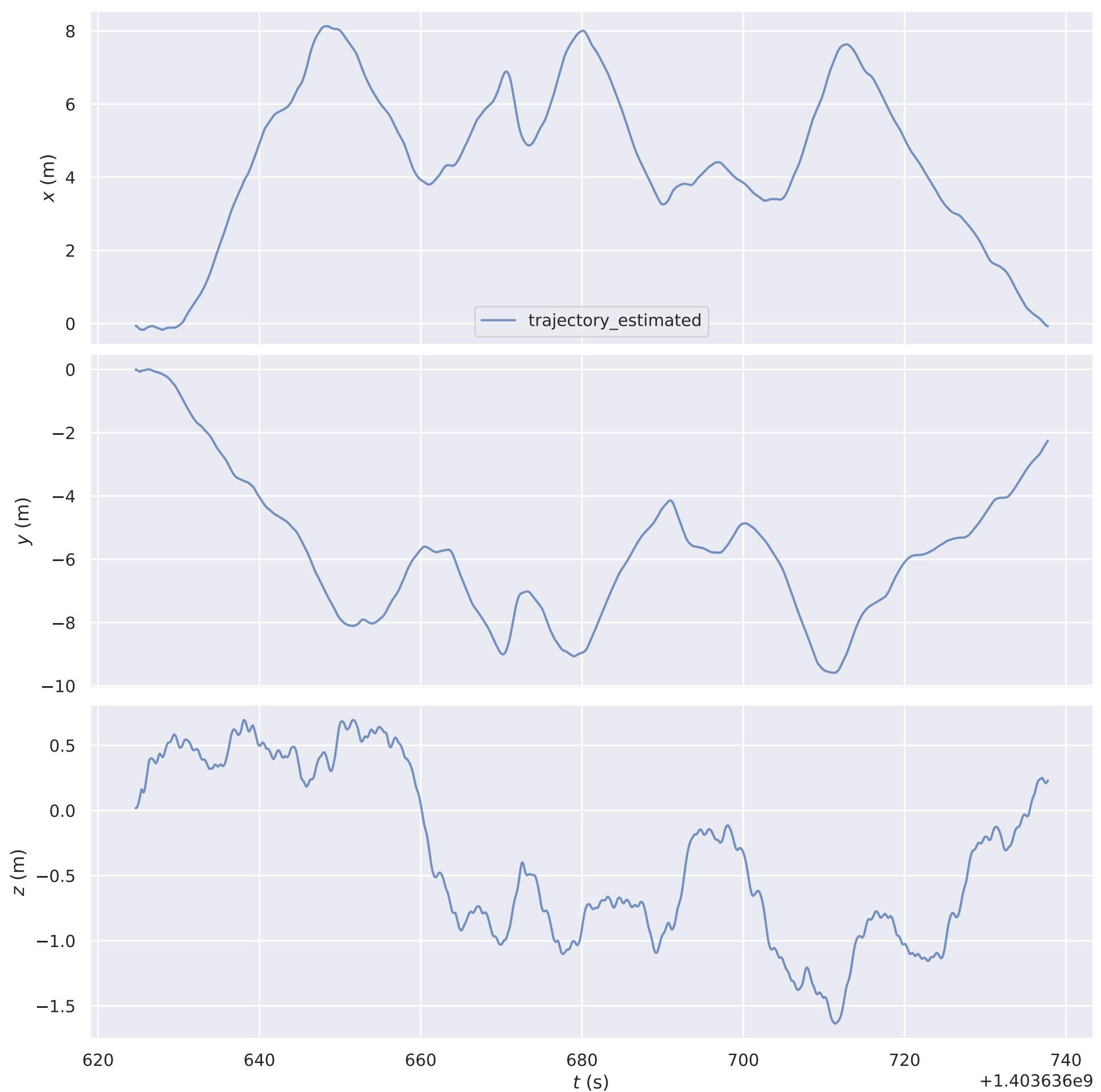


— trajectory_estimated





+1.403636e9

