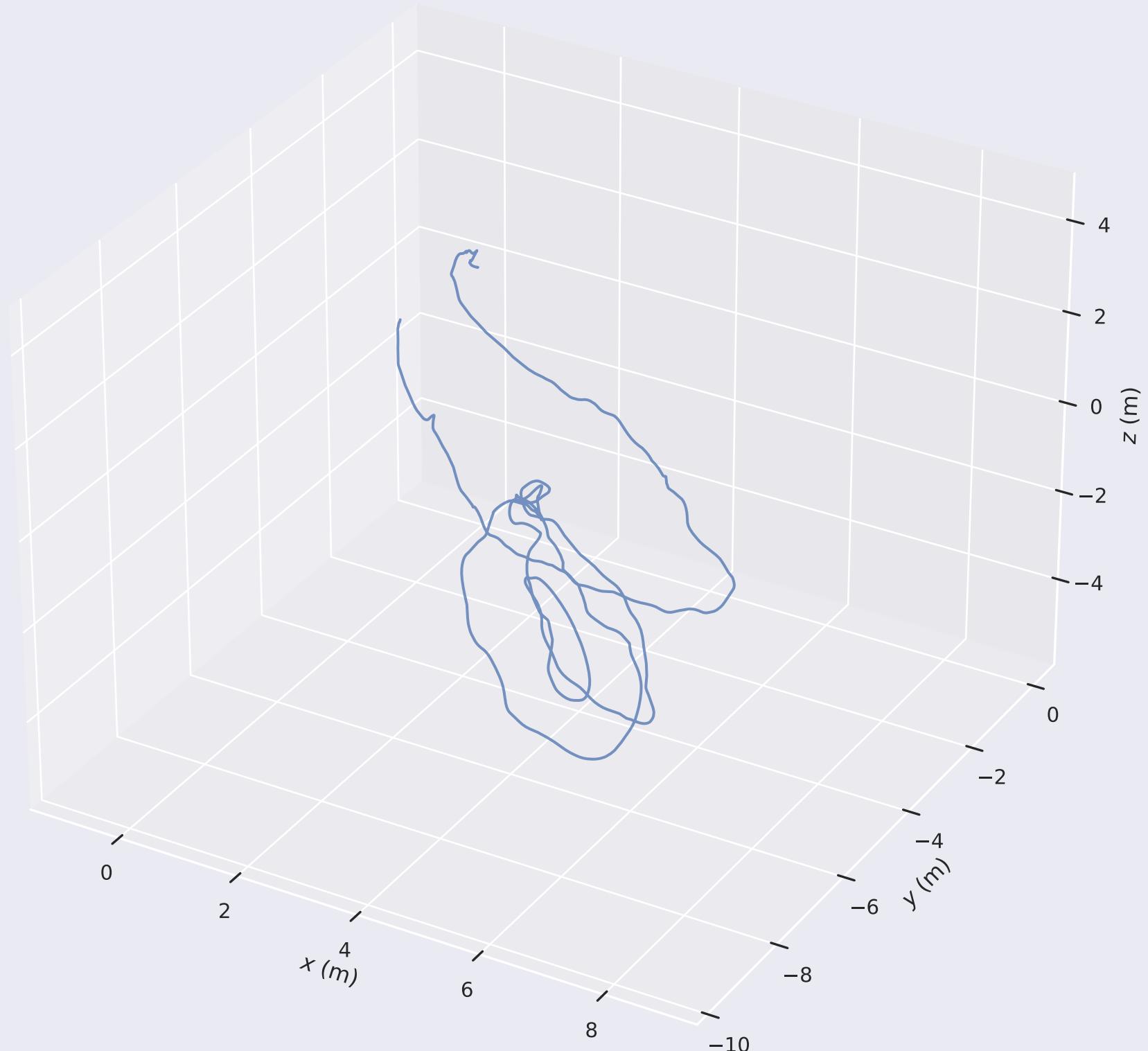
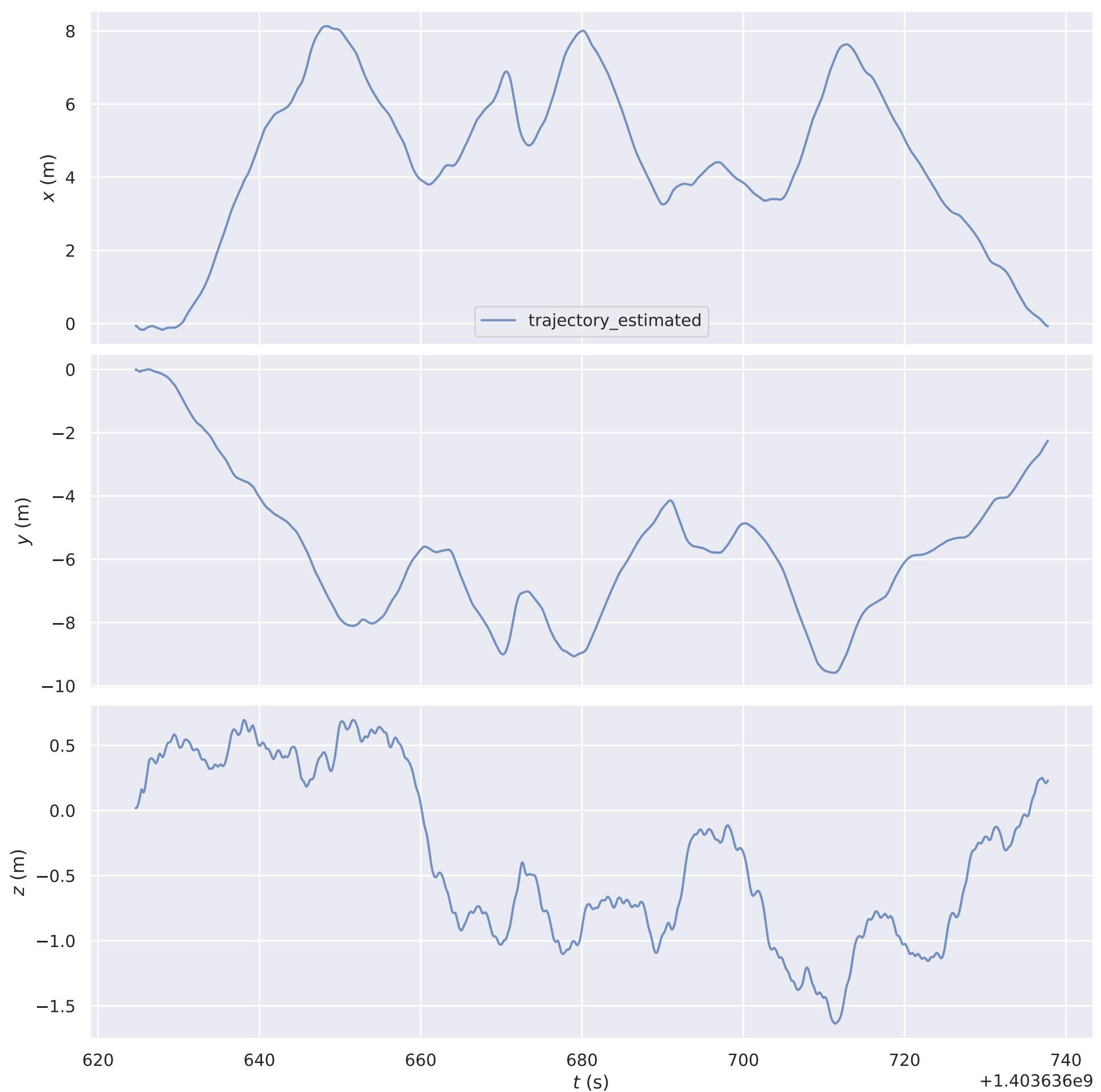
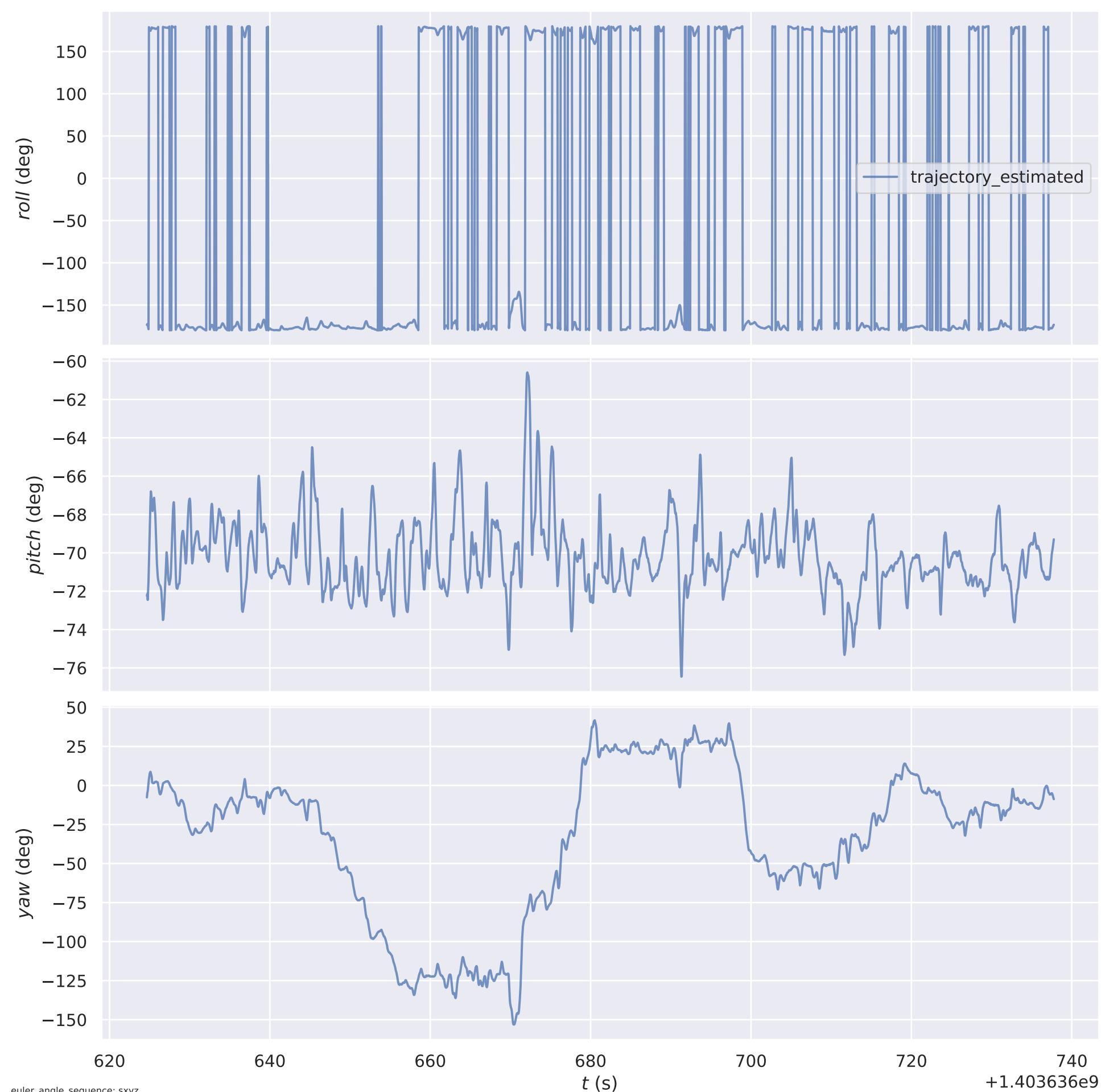


— trajectory_estimated





+1.403636e9



euler_angle_sequence: sxyz

