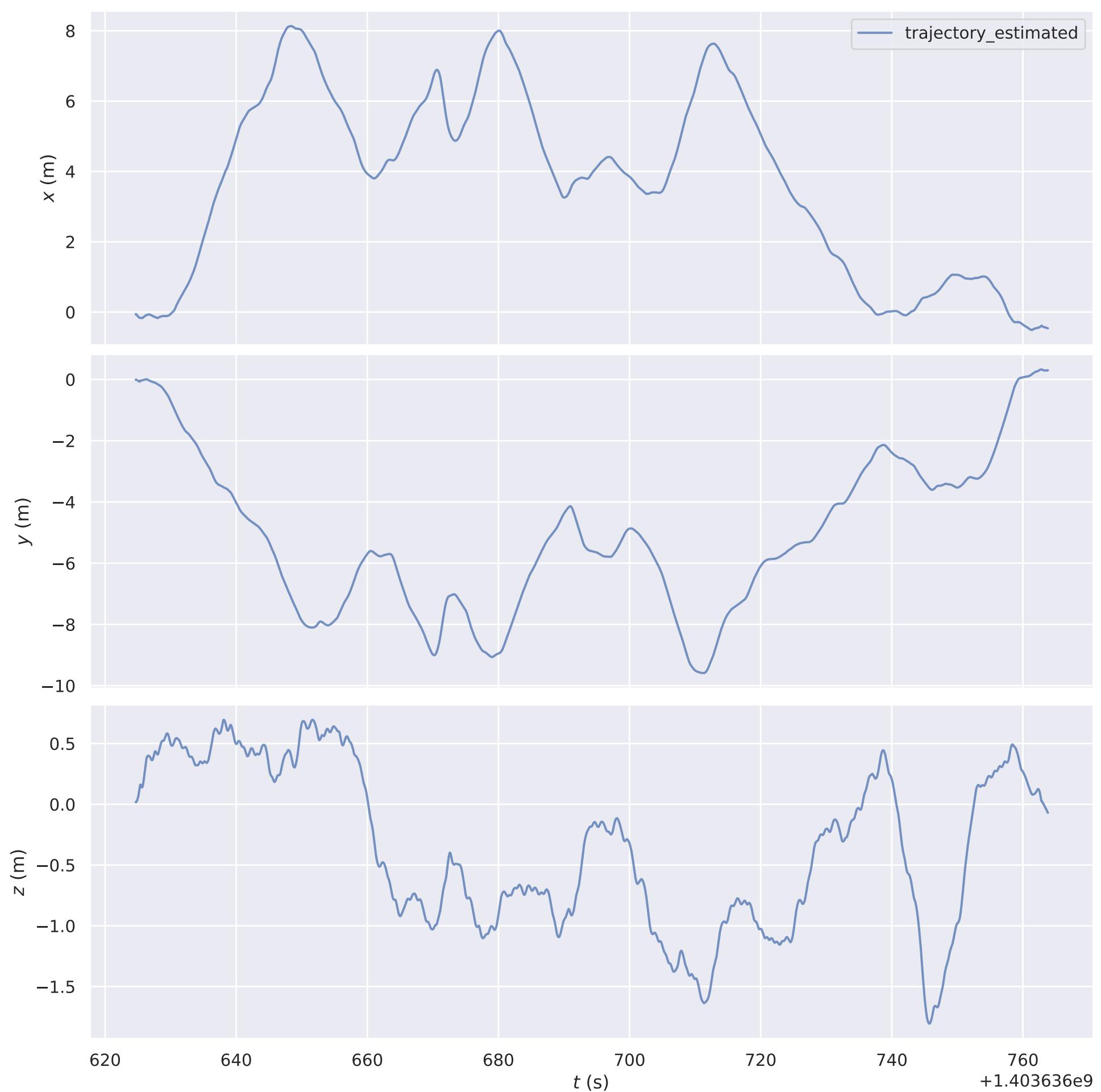
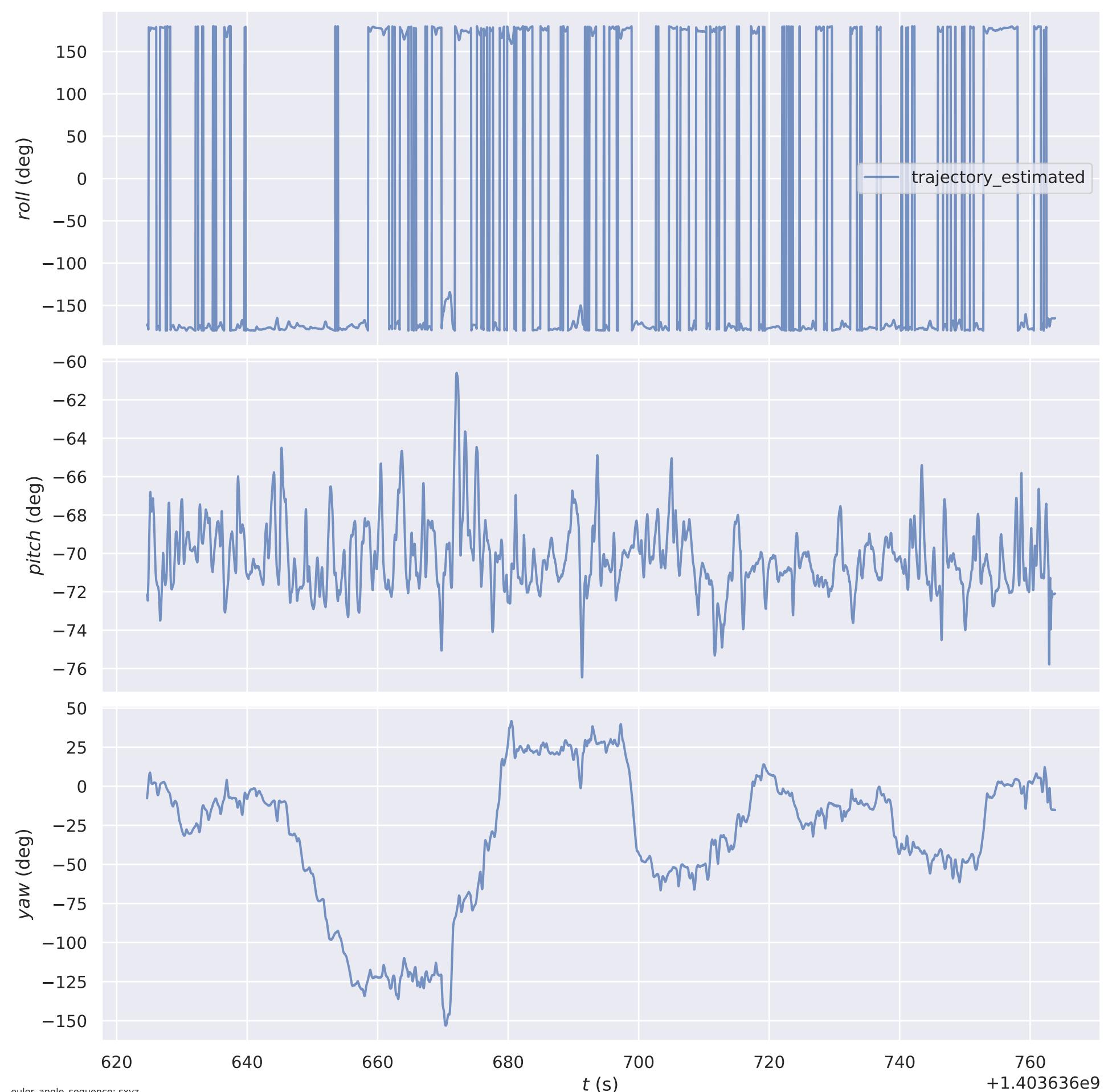
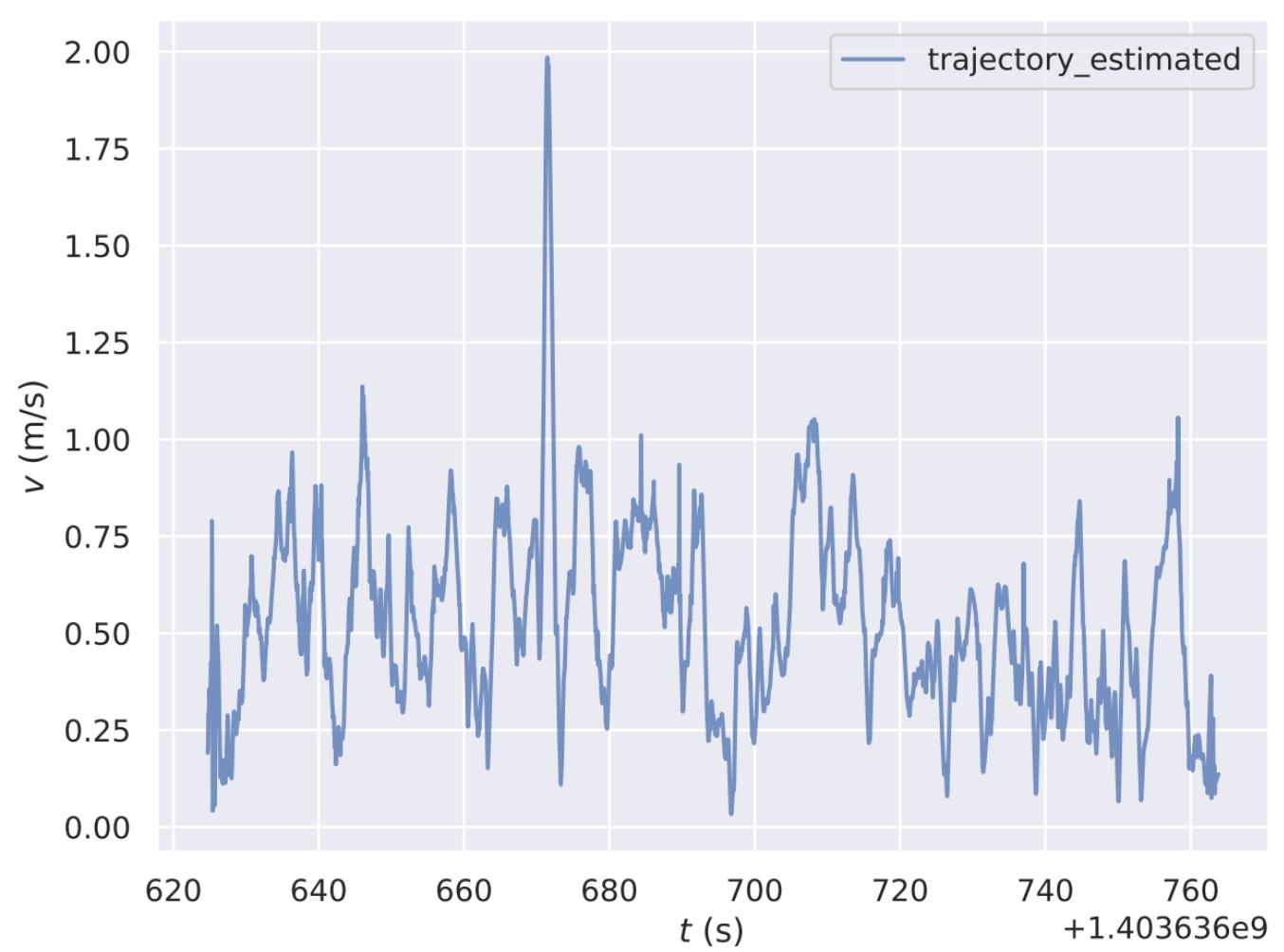


— trajectory\_estimated







+1.403636e9