## 1 Petri Dish Image Processing: Main Execution Block

### 1.1 Import and Initialization

### **Explanation:**

- Initializes the process\_series function with parameters series\_prefix, series, min\_radius, and min\_count.
- Prints output file names based on series\_prefix and dish coordinates.
- Issues a warning if fewer than 6 dishes (number of petridishes in the initial raw image) are found.

### 1.2 Image Handling and Initial Frame Extraction

### **Explanation:**

- Initializes last\_frame to store images.
- Iterates over file paths to read and mask images.
- Extracts Petri dish regions from each image, applies curve transformation, and updates last\_frame.

### 1.3 Frame Processing Loop

```
this_frame_index = 1
frame_index = 0
for filepath in files:
    frame = cv2.imread(filepath)
    frame_index = int(filepath.split('_')[-1].split('.')[0])
    if frame is None:
        continue
    while this_frame_index < frame_index:</pre>
        for i, (x, y, r) in enumerate(dish_coords):
            this_last_frame = last_frame[i].copy()
            cv2.putText(this_last_frame, f'f{this_frame_index:03}', (105, 105),
            \rightarrow cv2.FONT_HERSHEY_SIMPLEX, 3, (255, 255, 255), 2)
            cv2.circle(this_last_frame, (50, 50), 40, (50, 50, 250), -1)
             cv2.imwrite(f'PREPROCESSED/{series_prefix}_{i+1:02}_{this_frame_index:03}.jpg',

    this_last_frame)

        this_frame_index += 1
```

#### **Explanation:**

- Initializes this\_frame\_index and frame\_index to track frames.
- Processes each file, skipping empty frames.
- Saves missing frames by creating copies from last\_frame with timestamps (provision inclusion in case of missing timeframes in experimental data collection.)

### 1.4 Mask Application and Rotation

```
if dish_coords is not None and mask is not None:
   masked_frame = cv2.bitwise_and(frame, mask)
   for i, (x, y, r) in enumerate(dish_coords):
       x, y, r = max(x, min_radius), max(y, min_radius), min(min_radius, min(x,

    y, masked_frame.shape[1] - x, masked_frame.shape[0] - y))

       dish = masked_frame[y - min_radius:y + min_radius, x - min_radius:x +

→ min_radius]
       if dish_angles[i] != 0:
           rotation_matrix = cv2.getRotationMatrix2D((int(min_radius),

    int(min_radius)), dish_angles[i]*180/np.pi, 1)

           dish = cv2.warpAffine(dish, rotation_matrix, (2*int(min_radius),
            if dish.size > 0 and dish.shape[0] > 0 and dish.shape[1] > 0:
           dish = apply_curve_transformation(dish,

→ piecewise_linear_transformation, 0.0, 0.85)
           last_frame[i] = dish.copy()
```

#### **Explanation:**

- Applies mask to each frame and extracts Petri dish regions.
- Rotates dishes if necessary based on dish\_angles.
- Applies curve transformation to the dishes and updates last\_frame.

# 1.5 Output Saving

### **Explanation:**

• Saves preprocessed Petri dish images to the 'PREPROCESSED' directory with appropriate filenames.

# **Explanation Summary**

The process\_series function processes a series of Petri dish images by extracting and transforming regions of interest, applying masks, and rotating images as needed. It handles missing frames by generating them based on the previous frames and saves all processed images to the specified output directory. The function ensures that the images are properly masked and transformed, adhering to specified parameters for dish coordinates and rotation angles.