## Deep Reinforcement Learning

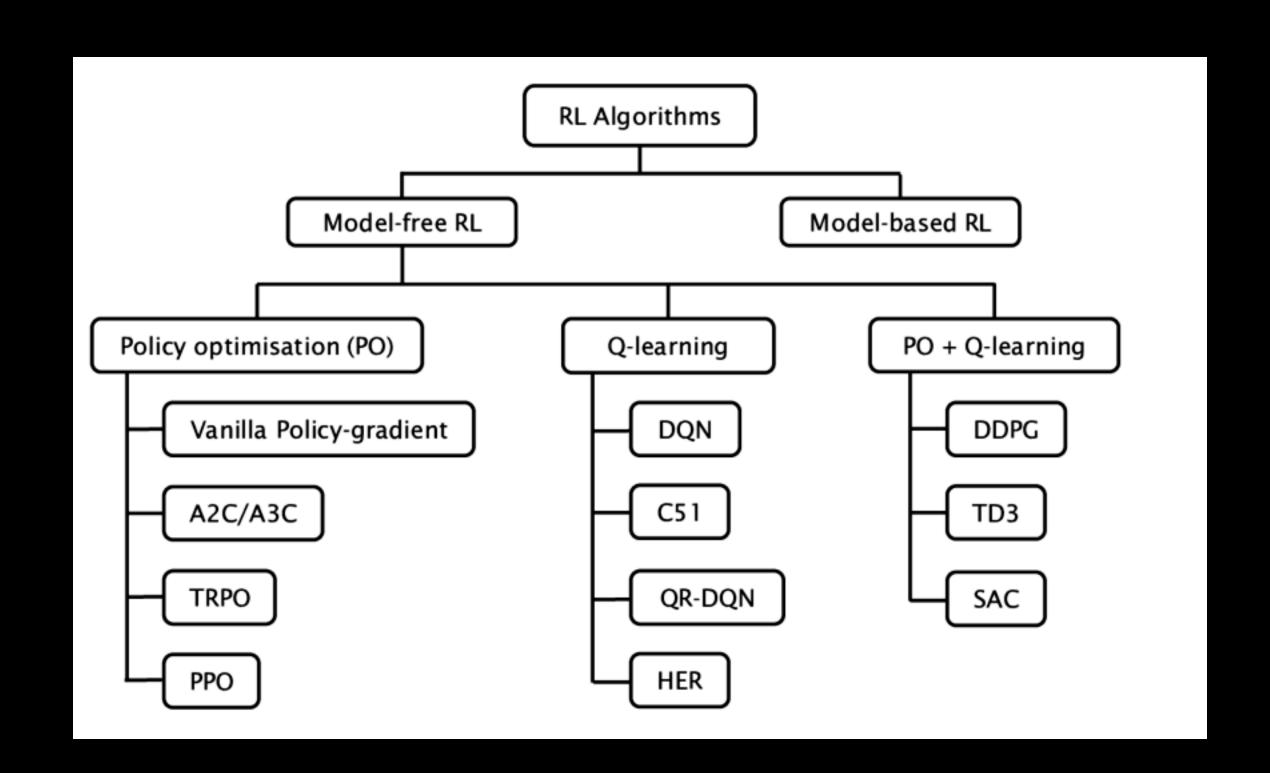
### Overview of DRL algorithms

#### Model Based:

- State transition probabilities are **known** (the game/environment is known)
- Useful for single player games with entire game state known
- "Plan" (or brute-force) the best possible action

#### Model Free:

- Rely on "learning"
- Unbiased assumptions about environment
- Accurate value or optimal policy functions are learned through trial and error



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### **Deep Learning and Neural Networks**

- Inspired by human brain
- Learn/optimize by deriving tensor calculations (during backpropogation) to minimize/maximize the error/loss.
- They are <u>universal function</u> <u>approximators</u>

