SNARK Flipper

Flip and prove multiple instances efficiently

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Fabra

In Brief

Flip := Folding via IPP





What are SNARKs?

zk-SNARK Succinctness proof size independent Zero-Knowledge of NP witness size does not leak anything about the witness **Non-Interactivity** zk-SNARK no exchange between prover and verifier **Argument Knowledge Soundness** soundness holds only a witness can be efficiently against computationally extracted from the prover bounded provers



Proof of storage

Storage Providers

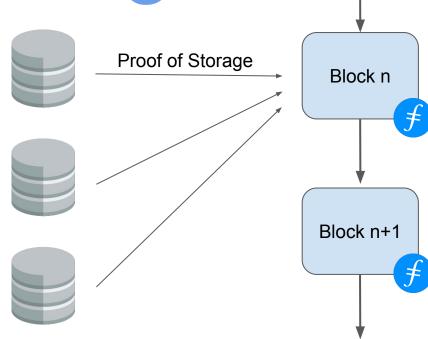
- onboard storage capacity
- earn block rewards
- regularly prove the storage

= Provers

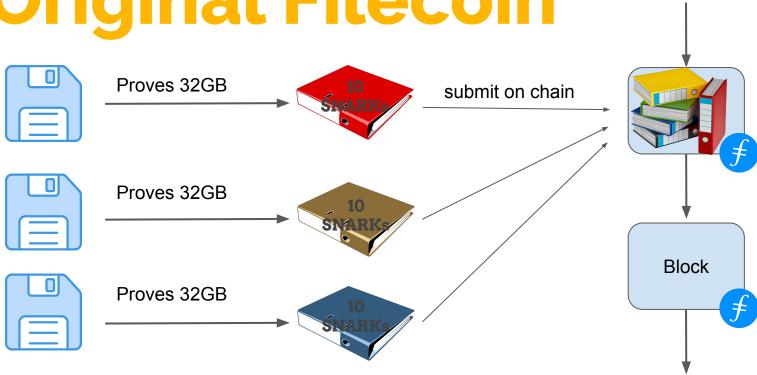
Nodes in network

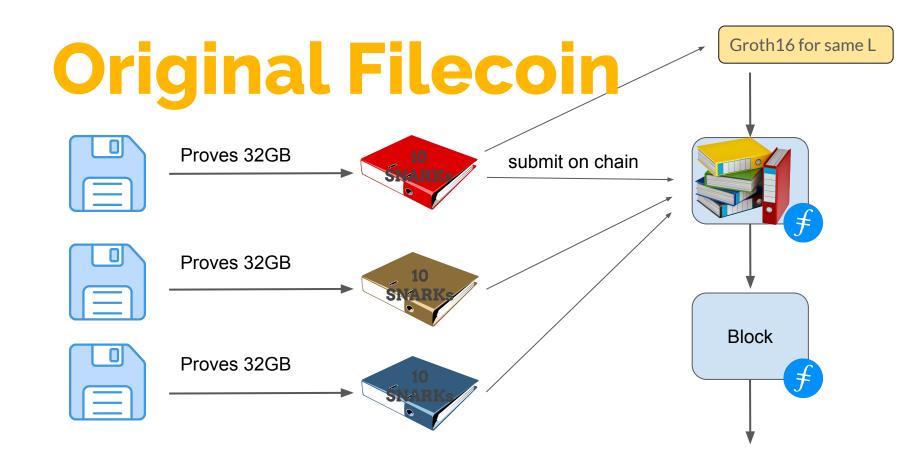
- ensure data is being stored, maintained, and secured
- need to check proofs of space

= Verifiers



Original Filecoin







How it works?

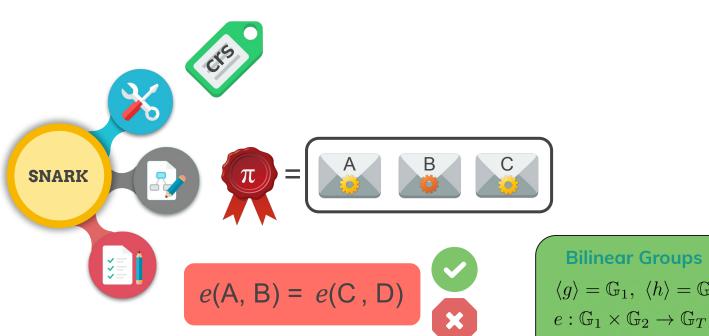
Groth16



Bilinear Groups

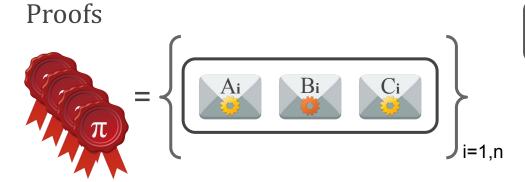
$$\langle g \rangle = \mathbb{G}_1, \ \langle h \rangle = \mathbb{G}_2$$
 $e : \mathbb{G}_1 \times \mathbb{G}_2 \to \mathbb{G}_T$
 $e(g^a, h^b) = e(g, h)^{ab}$

Groth16



$$e(g^a, h^b) = e(g, h)^{ab}$$

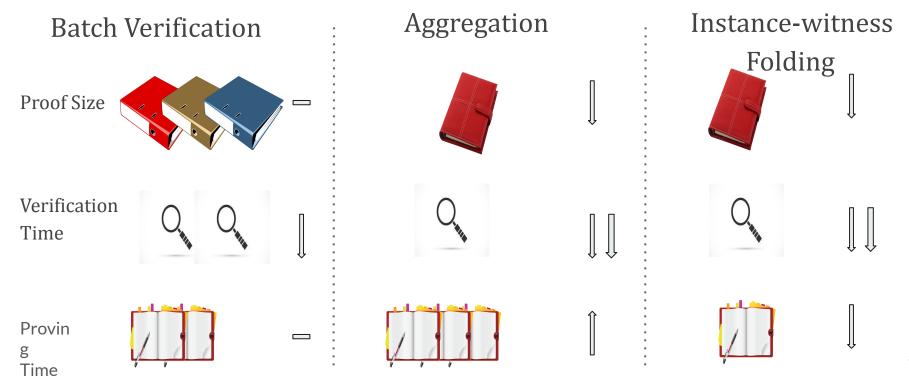
Many SNARKs



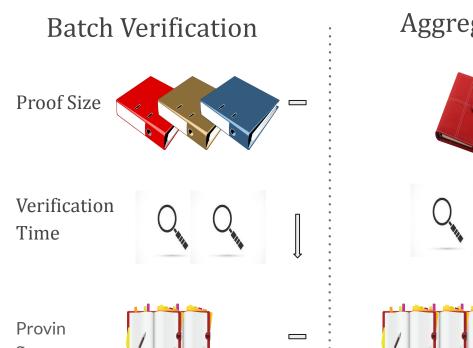
$$e(A_1, B_1) = e(C_1, D)$$
 $e(A_2, B_2) = e(C_2, D)$

$$e(A_n, B_n) = e(C_n, D)$$

Verify many SNARKs

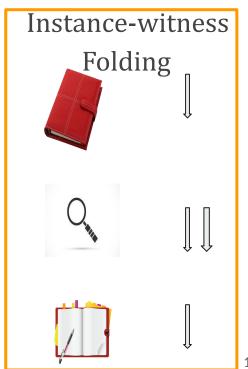


Verify many SNARKs



Time





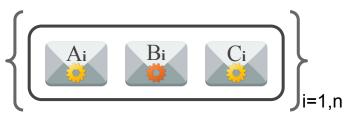


SnarkPack Aggregation

(Gailly, Maller, Nitulescu)

SNARK Aggregation

Aggregation



$$Z_{AB} = \prod e(A_i, B_i^{r^i})$$

$$Z_{c} = \prod C_{i}^{r^{i}}$$



$$Z_{AB} = Z_{C}$$

Tools: GIPP

Proofs for Inner Pairing Products and Applications - Bünz, Maller, Mishra, Tyagi, Vesely

$$\langle \mathbf{A}, \mathbf{b} \rangle = \prod A_{\mathbf{i}}^{b_{\mathbf{i}}}$$

$$\langle \mathbf{A}, \mathbf{B} \rangle = \prod e(\mathbf{A}_i, \mathbf{B}_i)$$

$$A_i \in \mathbb{G}_1, B_i \in \mathbb{G}_2, b_i \in \mathbb{Z}_q$$



$$\langle A, B \rangle = e(A_1, B_1) e(A_2, B_2)... e(A_n, B_n)$$

$$\mathbf{A} = (A_1, A_2, ... A_n)$$
 $\mathbf{B} = (B_1, B_2 ... B_n)$

$$B = (B_1, B_2 ... B_n)$$

$$\langle A, B \rangle = e(A_1, B_1) e(A_2, B_2) \dots e(A_n, B_n)$$

$$A = (A_1, A_2, ... A_n)$$

Aleft

Aright

$$B = (B_1, B_2 ... B_n)$$

Bleft

Bright

$$\langle \mathbf{A}, \mathbf{B} \rangle = e(A_1, B_1) \ e(A_2, B_2) \dots \ e(A_n, B_n)$$

$$\mathbf{A} = (A_1, A_2, \dots A_n) \qquad \mathbf{B} = (B_1, B_2 \dots B_n)$$

$$\mathbf{A}_{left} \qquad \mathbf{A}_{right} \qquad \mathbf{B}_{left} \qquad \mathbf{B}_{right}$$

$$\mathbf{L} = \langle \mathbf{A}_{left}, \mathbf{B}_{right} \rangle$$

$$\langle A, B \rangle = e(A_1, B_1) e(A_2, B_2) \dots e(A_n, B_n)$$

$$A = (A_1, A_2, \dots A_n)$$

$$B = (B_1, B_2 \dots B_n)$$

$$A' = (A'_1, \dots A'_{n/2})$$

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$$\langle A, B \rangle = e(A_1, B_1) e(A_2, B_2)... e(A_n, B_n)$$

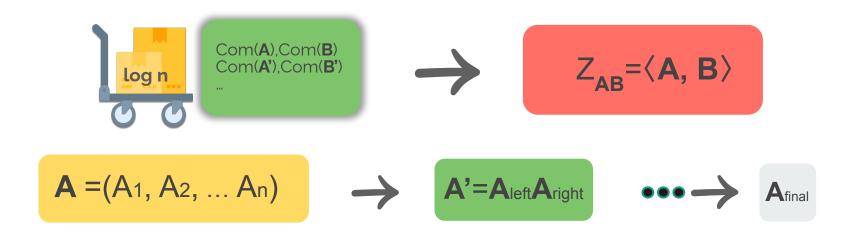
$$A = (A_1, A_2, ... A_n)$$

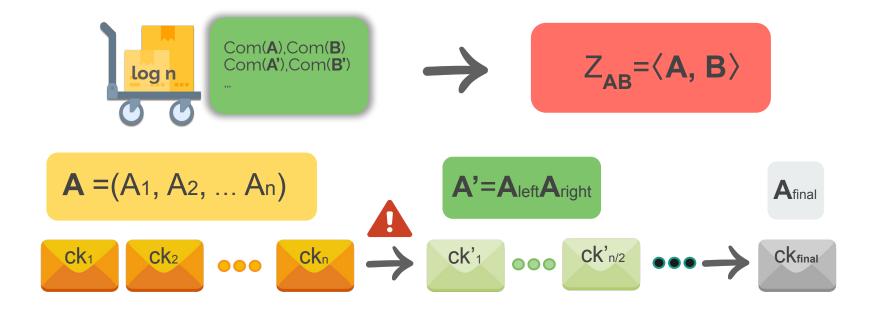
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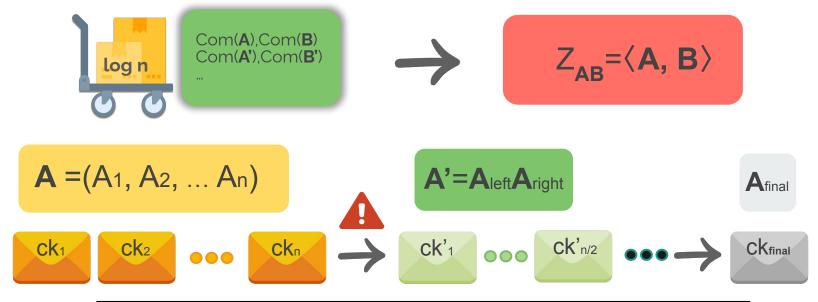
 $\langle A', B' \rangle$

$$A' = (A'_{1, \dots} A'_{n/2})$$



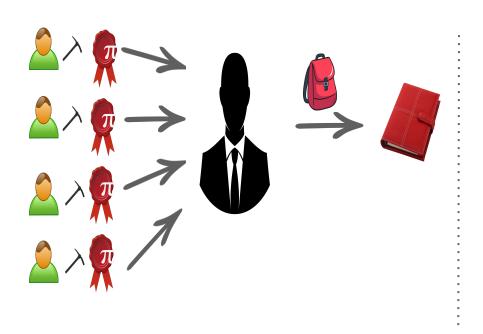




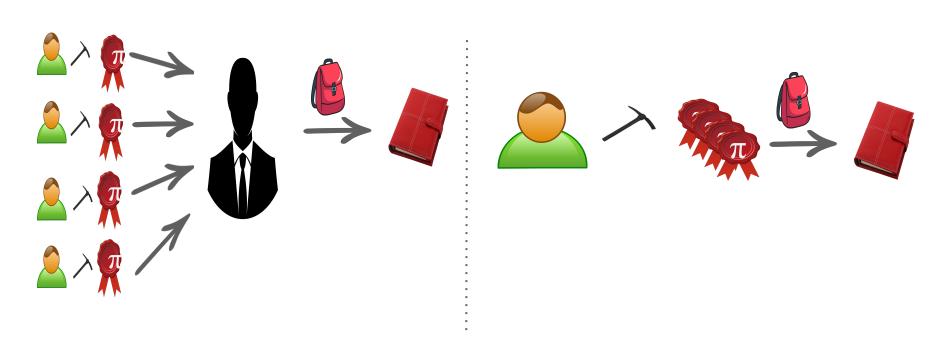




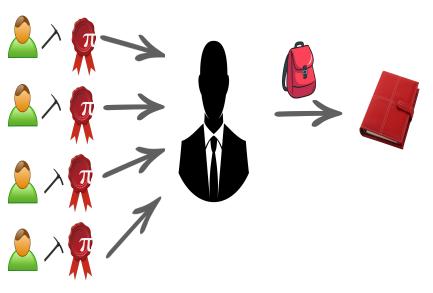
SnarkPack aggregation

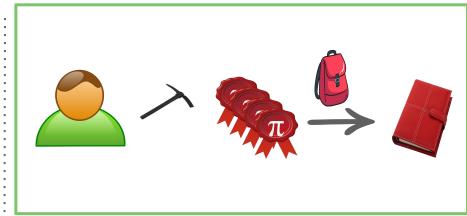


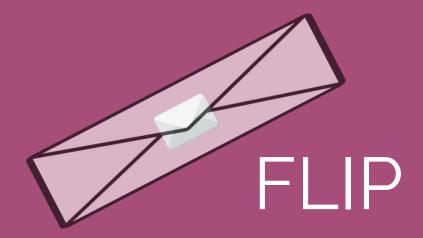
SnarkPack aggregation



SnarkPack aggregation







R1CS Extensions

Relaxed

$$\mathcal{L}_{\mathbf{A},\mathbf{B},\mathbf{C}}^{\text{relaxed}} = \left\{ (u, \mathbf{x}, \mathbf{e}) \in \mathbb{F} \times \mathbb{F}^l \times \mathbb{F} \mid \exists \mathbf{w} \in \mathbb{F}^{m-l} \text{ s.t.} \right.$$
$$\mathbf{z} = \begin{pmatrix} u \\ \mathbf{x} \\ \mathbf{w} \end{pmatrix} \land \mathbf{Az} \circ \mathbf{Bz} = u\mathbf{Cz} + \mathbf{e} \right\}$$

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Committed Relaxed

$$\mathcal{L}_{\mathsf{ck}_{1},\mathbf{A},\mathbf{B},\mathbf{C}}^{c\text{-relaxed}} = \left\{ (u,\mathbf{x},[e]_{1},[w]_{1}) \in \mathbb{F} \times \mathbb{F}^{l} \times \mathcal{C}^{2} \mid \exists (\mathbf{w},\mathbf{e}) \in \mathbb{F}^{m-l} \times \mathbb{F}^{m} \text{ s.t.} \right.$$

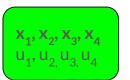
$$[w]_{1} = \mathsf{Com}_{\mathsf{ck}_{1}}(\mathsf{pp},\mathbf{w}) \wedge [e]_{1} = \mathsf{Com}_{\mathsf{ck}_{1}}(\mathsf{pp},\mathbf{e}) \wedge$$

$$((u,\mathbf{x},\mathbf{e}),\mathbf{w}) \in \mathcal{R}_{\mathbf{A},\mathbf{B},\mathbf{C}}^{\mathrm{relaxed}} \right\}$$

Nova style Folding

```
i \in \{1, 2\}: x_i = (\mathbf{x}_i, u_i, [e_i]_1, [w_i]_1), w_i = (\mathbf{w}_i, \mathbf{e}_i)
                                          P: q_i = (x_i, w_i)
                                                                                                                                                               V: x_i
                                           \mathbf{z}_i = (u_i, \mathbf{x}_i^\top, \mathbf{w}_i^\top)^\top
                                           \mathbf{t} = \mathbf{A}\mathbf{z}_1 \circ \mathbf{B}\mathbf{z}_2 + \mathbf{A}\mathbf{z}_2 \circ \mathbf{B}\mathbf{z}_1
                                                             -u_1Cz_2 - u_2Cz_1
                                                                                                                               [t]_1
                                           [t]_1 = \mathsf{Com}_{\mathsf{ck}_1}(\mathsf{pp}_1, \mathbf{t})
                                                                                                                                X
                                                                                                                                                               \chi \leftarrow \mathbb{F}
                                                                                                                                                                [e]_1 = [e_1]_1 + \chi[t] + \chi^2[e_2]_1
                                           \mathbf{e} = \mathbf{e}_1 + \chi \mathbf{t} + \chi^2 \mathbf{e}_2
                                                                                                                                                                [w]_1 = [w_1]_1 + \chi[w_2]_1
                                           \mathbf{w} = \mathbf{w}_1 + \chi \mathbf{w}_2
                                                                                                                                                                u = u_1 + \chi u_2
                                                                                                                                                               \mathbf{x} = \mathbf{x}_1 + \chi \mathbf{x}_2
                                           w = (\mathbf{w}, \mathbf{e})
                                                                                                                                                                x = (u, \mathbf{x}, [e]_1, [w]_1)
```

Nova style Folding











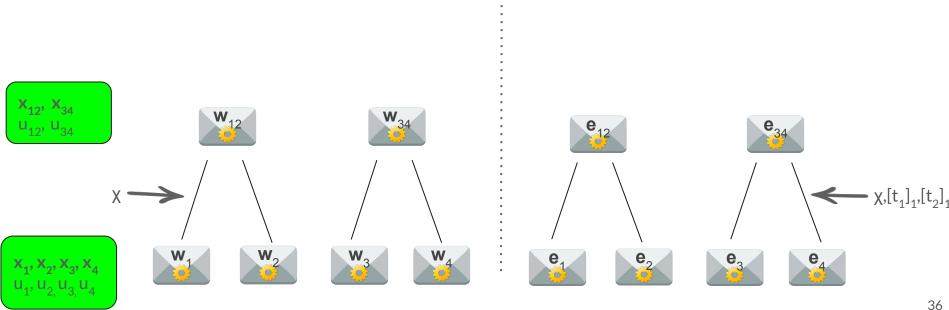




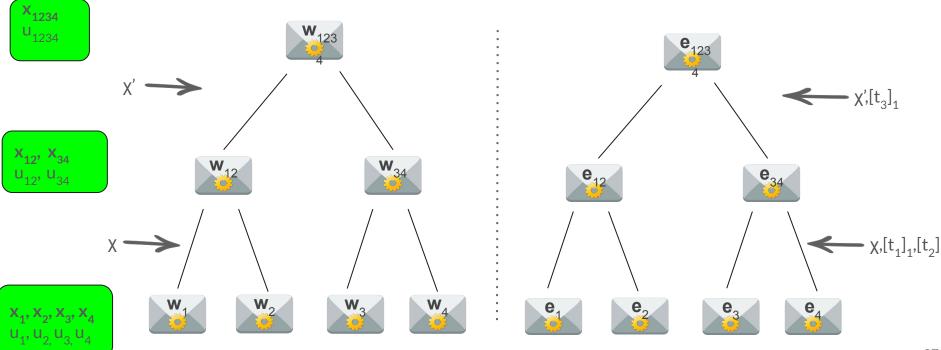


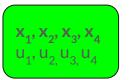


Nova style Folding



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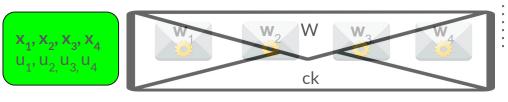


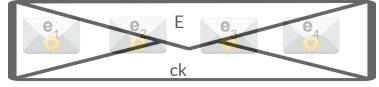


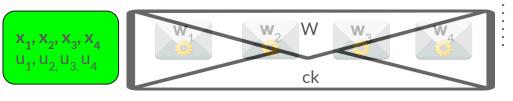


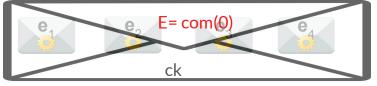


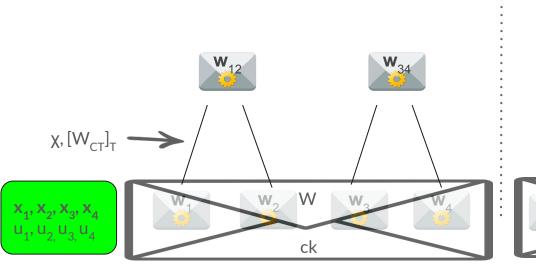


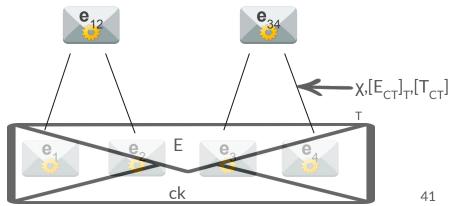


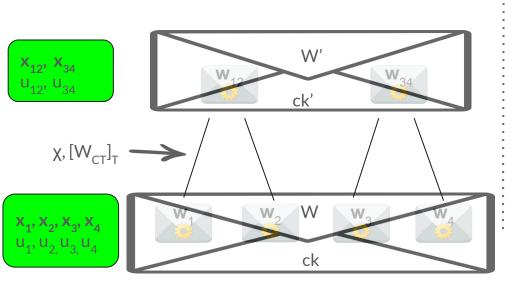


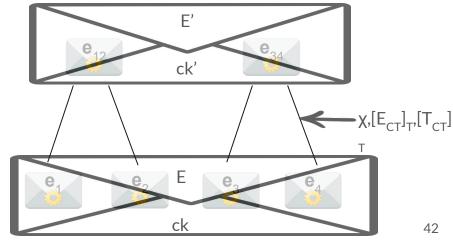


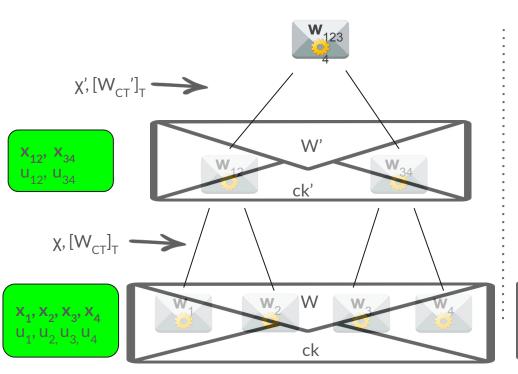


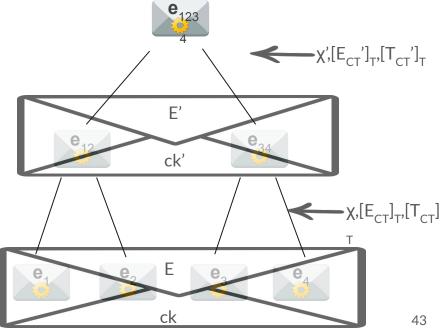


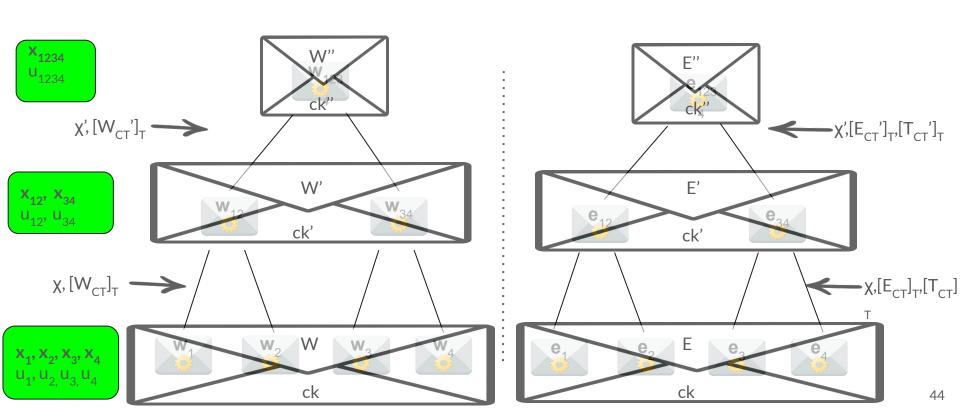


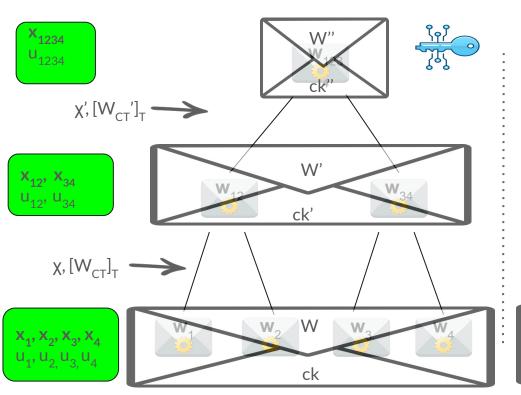


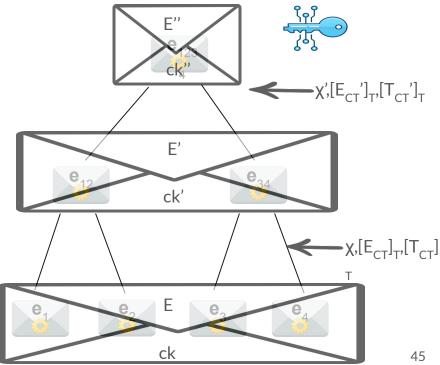


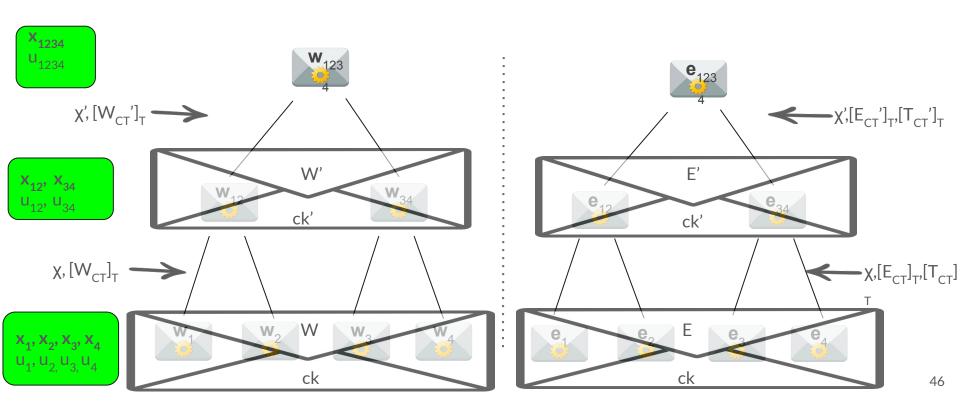


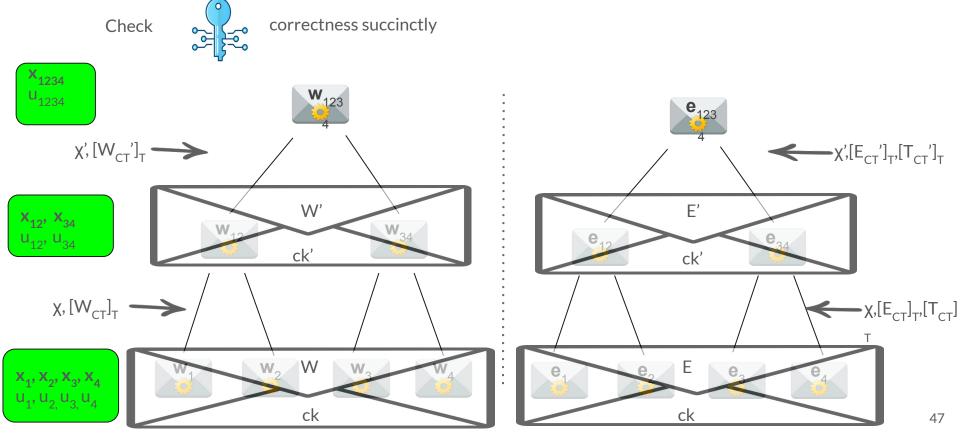














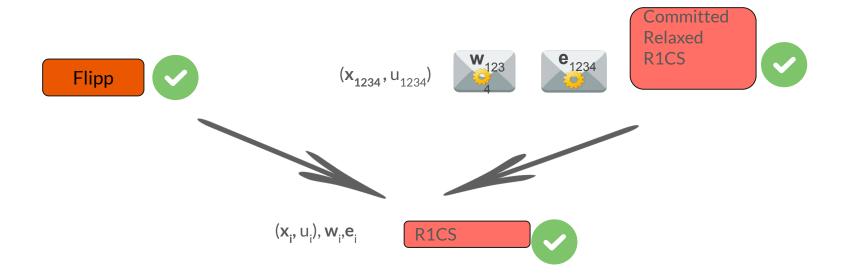














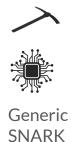






Generic SNARK

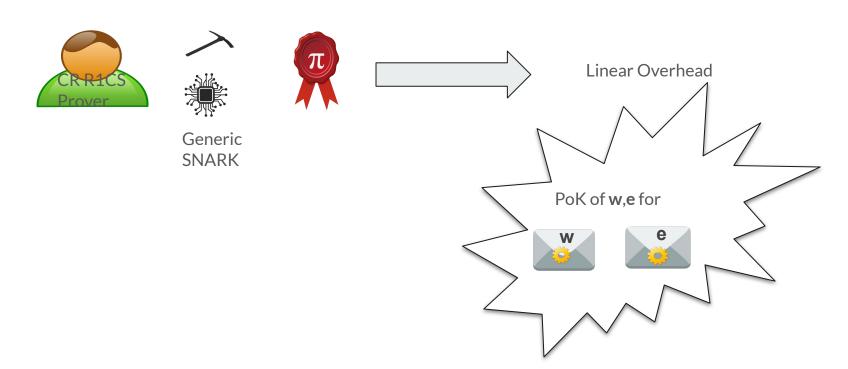


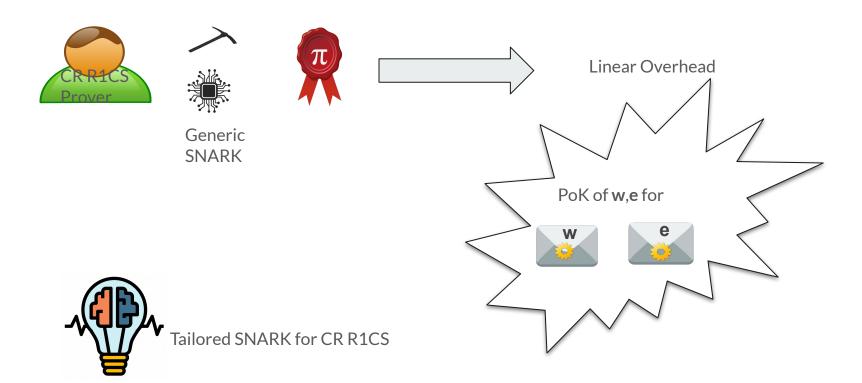






Linear Overhead















OR

use generic commit and prove or sparse matrix lincheck techniques











OR

use generic commit and prove or sparse matrix lincheck techniques









use generic commit and prove or sparse matrix lincheck techniques











$$(\mathsf{srsp}, \mathsf{srsv}) := \mathsf{srs} \leftarrow \begin{pmatrix} \left[\alpha, \beta, \delta, \{x^i\}_{i=0}^{n-1}, \{u_j(x)\beta + v_j(x)\alpha + w_j(x) + \gamma \ell_j(x)\}_{j=0}^l, \\ \left\{ \frac{u_j(x)\beta + v_j(x)\alpha + w_j(x) + \gamma \ell_j(x)}{\delta} \right\}_{j=l+1}^m, \{x^i t(x)/\delta\}_{i=0}^{n-2} \right]_1, \\ \left[\beta, \delta, \gamma, \{x^i\}_{i=0}^{n-1}]_2, \ [\alpha\beta, t(x)]_T, H \end{pmatrix}$$





$$(\mathsf{srsp},\mathsf{srsv}) := \mathsf{srs} \leftarrow \begin{pmatrix} \left[\alpha,\beta,\delta,\{x^i\}_{i=0}^{n-1},\{u_j(x)\beta+v_j(x)\alpha+w_j(x)+\underline{\gamma\ell_j(x)}\}_{j=0}^l,\\ \left\{\frac{u_j(x)\beta+v_j(x)\alpha+w_j(x)+\underline{\gamma\ell_j(x)}}{\delta}\right\}_{j=l+1}^m,\{x^it(x)/\delta\}_{i=0}^{n-2}\right]_1,\\ \left[\beta,\delta,\underline{\gamma},\{x^i\}_{i=0}^{n-1}]_2,\; [\alpha\beta,t(x)]_T,H \end{pmatrix}$$





$$[A]_{1}[B]_{2} - [C]_{1}[\delta]_{2} - \left(\sum_{j=0}^{l} z_{j} [u_{j}(x)\beta + v_{j}(x)\alpha + w_{j}(x) + \gamma \ell_{j}(x)]_{1} - [e]_{1} u^{-1}\right) [1]_{2} + [w]_{1}[\gamma]_{2} = u [\alpha \beta]_{T}$$





$$[A]_{1}[B]_{2} - [C]_{1}[\delta]_{2} - \left(\sum_{j=0}^{l} z_{j} [u_{j}(x)\beta + v_{j}(x)\alpha + w_{j}(x) + \underline{\gamma \ell_{j}(x)}]_{1} - \underline{[e]_{1} u^{-1}}\right) [1]_{2} + \underline{[w]_{1} [\gamma]_{2}} = u [\alpha \beta]_{T}$$

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• **Flipp**: a protocol that uses inner pairing product techniques to fold with logarithmic communication committed relaxed R1CS instances.

 Committed Relaxed Groth16: a modification of Groth16 for proving committed relaxed R1CS instances.

Conclusion

Flip and prove aggregation:

- massive reduction in prover time compared to SnarkPack, in the setting of a single prover
- no need for expensive arithmetization of verifier circuit inside the prover
- no need for (half) cycles of elliptic curves

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Flip and prove aggregation:

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Committed Relaxed Groth 16:

Can be potentially used as an alternative for proving the last step of Nova

