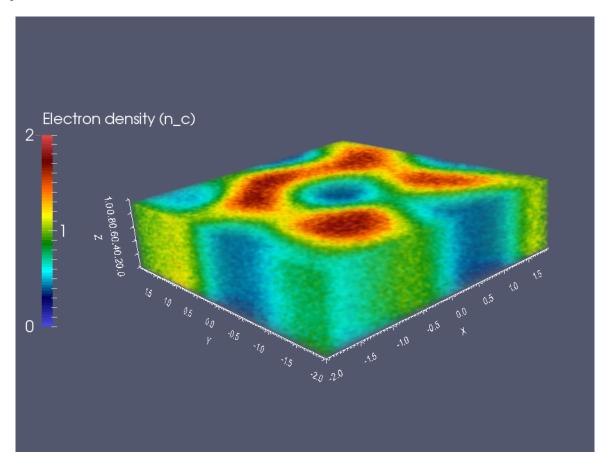
Introduction

piccante, the code described in this document, is a massively parallel fully-relativistic 3D particle-incell code. The user is able to define an arbitrary number of particle species with arbitrary density functions and an arbitrary number of Gaussian laser pulses.

The code is proved to scale very well up to 32768 MPI processes.

In its present state, the code could be considered in "beta status".

This document should provide all the information needed to compile the code, run simulations and analyse the results.



How to get and compile the code

Please refer to the BUILD.md document in the project root folder to have latest information on how to get and build the code.

2.0.1 Ask a contributor

If you need further information, ask one of the contributors:

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How to prepare a simulation

In order to prepare a new simulation, among the source files only main-piccante.cpp needs to be modified.

In this chapter, the structure of this file is described in detail.

Please refer to simple_1d_wakefield.cpp in the example directory, which should be renamed main-piccante.cpp in the source directory, if you want to compile and launch this example.

Other example main files are described in the next chapter.

3.1 Headers and definitions

```
#include <mpi.h>
#include <cstdio>
#include <iostream>
#include <fstream>
#include <malloc.h>
#include <cmath>
#include <iomanip>
#include <cstring>
#include <ctime>
#include <cstdarg>
#include <cstdarg>
#include <vector>
```

This section doesn't need to be modified. Standard libraries and GNU Scientific Library headers are included.

Set the dimensionality of the simulation

```
#define DIMENSIONALITY 1
```

The first parameter which the user needs to modify is the dimensionality of the code. It is very important to define DIMENSIONALITY before including "access.h". Possible values are 1,2 and 3. An error at compilation time occurs if other values are selected or if DIMENSIONALITY is not defined.

```
#include "access.h"
#include "commons.h"
#include "grid.h"
#include "structures.h"
#include "current.h"
#include "em_field.h"
#include "particle_species.h"
```

```
#include "output_manager.h"
```

Here, the header files of the code are included. These lines should not be modified by the user.

Restart

```
#define _RESTART_FROM_DUMP 1
#define _DO_RESTART false
#define DO_DUMP true
#define TIME_BTW_DUMP 50
```

These lines control the behaviour of the restart function. This simulation is not a restart (so _DO_RESTART is false and _RESTART_FROM_DUMP is ignored). However, since DO_DUMP is true, files for a simulation restart are dumped every 50 time units (as set by TIME_BTW_DUMP).

Parallelization: set the number of MPI task

```
#define NPROC_ALONG_Y 1
#define NPROC_ALONG_Z 1
```

NPROC_ALONG_Y and NPROC_ALONG_Z set the number of MPI processes along y and along z. The total number of MPI processes when the application is launched (see chapter 4) should be a multiple of NPROC_ALONG_Y \times NPROC_ALONG_Z. The number of processes along x is *automatically* selected so that [number of processes along x] \times NPROC_ALONG_Y \times NPROC_ALONG_Z is equal to the total number of MPI processes.

```
#define DIRECTORY_OUTPUT "TEST"

#define DIRECTORY_DUMP "TEST"

#define RANDOM_NUMBER_GENERATOR_SEED 5489

#define FREQUENCY_STDOUT_STATUS 5
```

These lines set, respectively, the output directory (which should be created manually by the user if Boost is not used), the dump files directory, the seed of the random number generator (more on that later) and the frequency of the visual status report when the code is in execution.

```
int main(int narg, char **args)
{
         GRID grid;
         EM_FIELD myfield;
         CURRENT current;
         std::vector<SPECIE*> species;
         vector<SPECIE*>::const_iterator spec_iterator;
         int istep;
         gsl_rng* rng = gsl_rng_alloc(gsl_rng_ranlxd1);
```

These lines should not be modified.

grid contains all the information related to the simulation grid (coordinates of grid points, number of processors ...). Moreover, it contains other important parameters of the simulation (simulation time, moving window properties ...).

myfield evolves the electromagnetic field.

current is used for current and density deposition.

species is a vector of SPECIE objects. The user is able to define an arbitrary number of species (see section 3.5).

3.2 Grid settings

```
grid.setXrange(-50.0, 0.0);
grid.setYrange(-1.0, 1.0);
grid.setZrange(-1.0, +1.0);
```

```
grid.setNCells(2500, 0, 0);
grid.setNProcsAlongY(NPROC_ALONG_Y);
grid.setNProcsAlongZ(NPROC_ALONG_Z);
```

These code lines define the main properties of the simulation grid.

The first three lines define the ranges of the simulation box in X, Y and Z.

grid.setNCells(1500, 0, 0) defines 1500 grid points along x and 0 grid points along y and z. If DIMENSIONALITY is 1, the number of grid points along y and z is ignored.

Finally grid.setNProcsAlongY(NPROC_ALONG_Y); and grid.setNProcsAlongZ(NPROC_ALONG_Z); respectively set the number of processes along y according to NPROC_ALONG_Y and the number of processes along z according to NPROC_ALONG_Z.

```
// grid.enableStretchedGrid();
// grid.setXandNxLeftStretchedGrid(-15.0,1000);
// grid.setYandNyLeftStretchedGrid(-5.0, 70);
// grid.setXandNxRightStretchedGrid(15.0,1000);
// grid.setYandNyRightStretchedGrid(5.0, 70);
```

The stretched grid is commented out in this example (so in this example the simulation grid is not stretched). However, this feature is described in subsection 3.2.1.

```
grid.setBoundaries(xOpen | yOpen | zPBC);
```

grid.setBoundaries(...) sets the boundary conditions of the simulation.

The available options at the moment are: xOpen xPBC yOpen yPBC zPBC (so, open boundary conditions are not yet implemented along z).

Boundary conditions may not be compatible with other simulation parameters. For instance, xPBC is incompatible with the moving window. Moreover, while open boundaries are fine for EM fields, if a particle suddenly disappear from the simulation, disruptive numerical instabilities may occur (in this case, using the stretched grid feature is suggested). Of course particles can disappear safely from the left x boundary if there's a moving window with $\beta = 1.0$.

```
grid.mpi_grid_initialize(&narg, args);
```

This line initialises the grid (the user should not modify it).

```
grid.setCourantFactor(0.98);
```

The Courant Factor should be always less than 1.0 to insure numerical stability of the algorithm. 0.98 is a good value if periodic boundary conditions are exploited. Instead, it may be necessary to reduce the Courant Factor to achieve numerical stability when open boundaries are used (0.8 may be a safer value in these cases).

```
grid.setSimulationTime(60.0);
```

Here the total simulation time in units of τ_L ($\tau_L = \ell_0$) is set.

```
grid.with_particles = YES;
grid.with_current = YES;
```

The use of these two lines is suggested for debug purposes.

The first line enables (YES) or disables (NO) particle creation, while with the second line it is possible to disable current deposition. If YES for the first parameter and NO for the second are selected, particles are created and advanced, but current is ignored for EM fields evolution.

```
grid.setStartMovingWindow(0);
grid.setBetaMovingWindow(1.0);
grid.setFrequencyMovingWindow(FREQUENCY);
```

These lines set the properties of the moving window: the start time, the β parameter and the frequency of movement (every how many time steps the window moves).

If the first line is commented out, no moving window is set. Instead, the second and the third lines are optional. Commenting out these lines results in selecting the default values for β (1) and frequency (20).

```
grid.setMasterProc(0);
```

grid.setMasterProc(0) sets the master MPI task to zero (if needed the user can properly choose a different MPI ID).

```
srand(time(NULL));
grid.initRNG(rng, RANDOM_NUMBER_GENERATOR_SEED);
```

Here the seeds of the random number generators for each MPI task are set (each task ends up with a different seed). These lines should not be modified.

```
grid.finalize();
grid.visualDiag();
```

These lines (which should not be modified) conclude the initialization of the grid and display some information on the standard output.

3.2.1 Stretched grid

```
grid.enableStretchedGrid();
grid.setXandNxLeftStretchedGrid(-15.0,1000);
grid.setXandNxRightStretchedGrid(15.0,1000);

grid.setYandNyLeftStretchedGrid(-5.0, 70);
grid.setYandNyRightStretchedGrid(5.0, 70);

grid.setZandNZLeftStretchedGrid(-5.0, 70);
grid.setZandNZRightStretchedGrid(5.0, 70);
```

These lines set the properties of the stretched grid. If the first line is commented no stretched grid is set, no matter the presence of some of the other lines. grid.setXandNxLeftStretchedGrid(X_START_LEFT, NP_LEFT) sets respectively the coordinate of the left boundary of the uniform grid (i.e. the beginning of the stretching) and the number of grid points in the stretched region. The same idea is used for the right boundary and for the Y and Z directions.

Figure 3.1: Stretching function (left) and inverse derivative (right)

The stretched grid is obtained considering a uniform grid in an auxiliary variable $\xi_i = \xi_{min} + \Delta \xi i$ and a piece-wise defined transfer function

$$x(\xi) = \begin{cases} x_{\text{right}} + \alpha_{\text{right}} \tan \left(\left| \xi - x_{\text{right}} \right| / \alpha_{\text{right}} \right), & \text{if } \xi > x_{\text{right}} \\ \xi, & \text{if } x_{\text{left}} < \xi < x_{\text{right}} \\ x_{\text{left}} - \alpha_{\text{left}} \tan \left(\left| \xi - x_{\text{left}} \right| / \alpha_{\text{left}} \right), & \text{if } \xi < x_{\text{left}} \end{cases}$$

See Fig. 3.1.

3.3 EM fields

```
myfield.allocate(&grid);
myfield.setAllValuesToZero();
```

Here the EM field is allocated and initialised to zero.

3.3.1 Laser pulse

```
laserPulse pulse1;
pulse1.setCos2PlaneWave();
pulse1.setPPolarization();
```

```
pulse1.setDurationFWHM(5.0);
pulse1.setPulseInitialPosition(-6.0);
pulse1.setLambda(1.0);
pulse1.setNormalizedAmplitude(1.0);

myfield.addPulse(&pulse1);
```

Here a 1D laser pulse is added to the EM field.

setCos2PlaneWave() sets the pulse type (use only setCos2PlaneWave() in 1D).

setPPolarization() sets the polarization of the laser pulse (options are: setPPolarization(),

setSPolarization() and setCircularPolarization()).

tsetDurationFWHM(5.0) sets the FWHM of the pulse.

setPulseInitialPosition(-6.0) sets the initial position along x of the center of the pulse.

setLambda(1.0) sets the wavelength of the pulse.

setNormalizedAmplitude(1.0) sets the normalized amplitude of the pulse.

3.3.2 Gaussian laser pulse

```
laserPulse pulse1;
pulse1.setGaussianPulse();
pulse1.setPPolarization();
pulse1.setDurationFWHM(5.0);
pulse1.setPulseInitialPosition(-6.0);
pulse1.setLambda(1.0);
pulse1.setNormalizedAmplitude(1.0);

pulse1.setWaist(3.0);

pulse1.setFocusPosition(0.0);

pulse1.setRotationAngleAndCenter(2.0*M_PI*(-90.0 / 360.0),0.0);

myfield.addPulse(&pulse1);
```

This is an example of the definition of a Gaussian laser pulse.

In addition to the setCos2PlaneWave() pulse, in this case waist and focus_position.

In 2 or 3 dimensions, if an oblique incidence pulse is required,

 $setRotationAngleAndCenter(2.0*M_PI*(-90.0 / 360.0), 0.0)$ enables rotation and set the angle in radians (first argument) and rotation center on the x axis (second argument).

3.3.3 EM field finalization

```
myfield.boundary_conditions();

current.allocate(&grid);

current.setAllValuesToZero();
```

These lines need to be called after pulse generation. They apply boundary conditions for the EM field and they allocate current (which is initialized to zero).

3.4 Plasma

```
PLASMA plasma1;
plasma1.density_function = left_soft_ramp;
plasma1.setXRangeBox(0.0,100.0);
plasma1.setYRangeBox(grid.rmin[1],grid.rmax[1]);
plasma1.setZRangeBox(grid.rmin[2],grid.rmax[2]);
plasma1.setDensityCoefficient(0.01);
```

```
plasma1.setRampLength(20.0);
plasma1.setRampMinDensity(0.0);
```

These lines define a plasma profile shaped as in figure 3.2.

The density function is $left_soft_ramp$ (sin^2 followed by constant density). set*RangeBox calls select the size of the box surrounding the plasma, while setDensityCoefficient sets the density (in units of n_c) of the constant density region of the plasma. The length of the ramp is set by setRampLength and setRampMinDensity sets the density before the ramp (0.0 in this example).

Figure 3.2: left_soft_ramp plasma profile

3.4.1 Other simple default plasma functions

box

This plasma shape is just a uniform box whose extremes are defined by the range parameters. Parameters related to the ramp are simply ignored.

left_linear_ramp

It's basically the same of the left_soft_ramp function. Simply the ramp is linear.

left_grating

This plasma function defines a grating target.

In addition to the settings for the soft ramp target, some additional parameters should be set as follows:

```
PLASMA plasma1;
plasma1.density_function = left_grating;
plasma1.setXRangeBox(0.0,5.0);
plasma1.setYRangeBox(grid.rmin[1],grid.rmax[1]);
plasma1.setZRangeBox(grid.rmin[2],grid.rmax[2]);
plasma1.setDensityCoefficient(100);
plasma1.setRampLength(0.05);
plasma1.setRampMinDensity(0.0);
double grating_peak_to_valley_depth = 1.0;
double grating_lambda = 0.5;
double grating_phase = 0.0;
double additionalParams[3];
additionalParams[0] = grating_peak_to_valley_depth;
additionalParams[1] = grating_lambda;
additionalParams[2] = grating_phase ;
plasma1.setAdditionalParams(additionalParams);
```

left_grating will be used as an example in subsection 3.4.3. Please refer to this subsection for further information.

3.4.2 Other functions

There are other plasma functions, such as box_minus_box and rough_target. Please refer to subsection 3.4.3 and to structures.cpp source file for further information.

3.4.3 How to implement a user-defined plasma function

If you want to implement a new plasma function, you have to define it in main-piccante.cpp file before use. In the following lines the definition of left_grating is reported as an example:

```
double left_grating(double x, double y, double z,
                         PLASMAparams plist, int Z, int A){
        double g_y0 = (plist.rmaxbox[1] - plist.rminbox[1])*0.5;
        double* paramlist = (double*)plist.additional_params;
        double g_depth = paramlist[0] * 0.5;
        double g_lambda = paramlist[1];
        double g_phase = paramlist[2];
        double phase = 2.0 * M_PI * ((y - g_y0) + g_phase) / g_lambda;
        double xminbound = plist.rminbox[0] +
                g_depth*(1.0 - cos(phase));
        if ((xminbound <= x) && (x <= plist.rmaxbox[0]) &&</pre>
        (plist.rminbox[1] <= y) && (y <= plist.rmaxbox[1]) &&
        (plist.rminbox[2] <= z) && (z <= plist.rmaxbox[2])){
                if ((x - xminbound) <= plist.ramp_length){</pre>
        return (plist.density_coefficient-plist.ramp_min_density)*
                         (x - xminbound) / plist.ramp_length +
                         plist.ramp_min_density;
                }
                else{
                         return plist.density_coefficient;
                }
        }
        else{
                return -1;
        }
```

It is worth to mention that, during the particle creation phase, the number of particles to be created is pre-calculated. This means that the density function is evaluated twice over each grid point. Consequently, care should be taken if something in the plasma function depends on randomly generated quantities (the best approach in this case is to pre-calculate all the random parameters in a separate function).

3.5 Species

```
SPECIE electrons1(&grid);
electrons1.plasma = plasma1;
electrons1.setParticlesPerCellXYZ(100, 1, 1);
electrons1.setName("ELE1");
electrons1.type = ELECTRON;
electrons1.creation();
species.push_back(&electrons1);
```

These lines create and initialize an electron species. A PLASMA object should be passed to define the plasma shape (in this case the plasma will be a left_soft_ramp).

setParticlesPerCellXYZ sets the number of particles per cell along x, y and z (100x1x1 in this case). setName sets the species name. Each species should have a different name, or part of the simulation output may be overwritten.

type selects the species type. Options are: ELECTRON, IONS and POSITRON. Finally, the lines

```
electrons1.creation();
species.push_back(&electrons1);
```

create the species electrons1 and add it to the species vector.

```
SPECIE ions1(&grid);
ions1.plasma = plasma1;
ions1.setParticlesPerCellXYZ(100, 1, 1);
ions1.setName("ION1");
ions1.type = ION;
ions1.Z = 6.0;
ions1.A = 12.0;
ions1.creation();
species.push_back(&ions1);
```

Here, carbon ions are created, with the same plasma profile of electrons1. In addition to the previous options, here Z and A should be set. Actually, only the ratio of Z over A is important.

```
tempDistrib distribution;
distribution.setMaxwell(1.0e-5);

electrons1.add_momenta(rng, 0.0, 0.0, 0.0, distribution);
ions1.add_momenta(rng,0.0, 0.0, 0.0, distribution);
```

These lines apply a Maxwell distribution to the species, with a temperature of 10^{-5} in code units (see appendixes).

It is also possible to add a momentum to each particle. In this case, momenta extracted from the temperature distribution are assigned in the reference frame co-moving with the plasma and then a Lorentz transformation is performed. For example, if a drift motion along z is required:

```
electrons1.add_momenta(rng, 0.0, 0.0, 1.0, distribution);
```

The available distribution functions are listed hereunder:

```
setWaterbag(p0)
setWaterbag3Temp(p0_x, p0_y,p0_z)
setUnifSphere(p0)
setSupergaussian(p0, alpha)
setMaxwell(temp)
```

Waterbag distribution (momenta between $-p_0$ and p_0) the same, but with three different momenta on x,y,z momentum distribution is a uniform sphere of radius p_0 spherical supergaussian distribution (radius p_0 , exponent α) Maxwell distribution

WARNING: multiple assignments of a temperature distribution to a species will result in the last assignment overwriting the previous ones.

WARNING: at the moment, if the moving window is activated, new particles entering in the simulation area are cold and with no drift. This will be fixed in future releases of the code.

3.6 Diagnostics

The following lines set up the diagnostics of the simulation.

```
OUTPUT_MANAGER manager(&grid, &myfield, &current, species);
```

An OUTPUT_MANAGER object is deputed to manage all the diagnostics of the simulation. If some of the arguments are not valid, the output manager may not function properly.

```
manager.addEFieldFrom(0.0, 2.0);
manager.addBFieldFrom(0.0, 2.0);
```

```
manager.addSpeciesDensityFrom(electrons1.name, 0.0, 2.0);
manager.addSpeciesDensityFrom(ions1.name, 0.0, 2.0);
manager.addCurrentFrom(0.0, 5.0);
manager.addSpeciesPhaseSpaceFrom(electrons1.name, 0.0, 5.0);
manager.addDiagFrom(0.0, 1.0);
```

These lines of code can be modified by the user according to its needs: they define exactly which diagnostics will be saved on disk and how frequently this will be done.

```
manager.addEFieldFrom(0.0, 2.0);
manager.addBFieldFrom(0.0, 2.0);
```

For example, the first two lines ask for the binary output of EM field every 2 τ_L , starting from time 0.0.

It is also possible to ask for the output between two times with a given frequency or at a precise time. In these cases, the calls are as follows:

```
manager.addEFieldFromTo(START, FREQUENCY, END);
manager.addEFieldAt(TIME);
```

For the density output and the phase space output, it is necessary to specify also the name of the target species, as defined in section 3.5. Make sure that the name is written correctly, or the requested output will be ignored (a warning message is displayed in this case).

If two output requests overlap, this is automatically detected by the output manager and no duplicated output is saved on disk.

A quick reference of the available diagnostics is given in the following table. A more detailed discussion about how to handle the output files can be found in chapter 5

${f EField}$	binary output of the E field
BField	binary output of the B field
EBField	binary output of the E and B fields (separate files)
${\bf EBFieldProbe}$	text output: EB fields time evolution on a given point (one file) see 3.6
SpeciesDensity	binary output of the charge density of a given species
SpeciesPhaseSpace	binary output of the phase space of a given species
Current	binary output of the total current density
Diag	lightweight text output (total energy, maximum momentum)

Output domains

For grid based output (fields current and densities) it is possible to select an output subdomain (i.e. a plane or a lineout). This is accomplished by "freezing" one or more dimensions (i.e. in a 3D simulation the x, y plane is selected by freezing the "z dimension). The prototype call for the \mathbf{E} on a x, y plane passing through the point (1, 2, 3) is as follows.

```
outDomain *plane1= new outDomain;
plane1->setPointCoordinate(1.0, 2.0, 3.0);
plane1->setFreeDimensions(1,1,0);
plane1->setName("a_nice_domainname");
manager.addEFieldFrom(plane1, 0.0, 5.0);
```

Output EB field probe

For EM fields is possible to create one or more files (text outputs) with the interpolated values of the 6 components on point chosen by the user. Multiple probe can be created and one separate file for each of them will be created. The prototype call for a probe on the point (1,2,3) is as follows which will output the EM fields values every $0.1\tau_L$

```
emProbe *probe1=new emProbe;
probe1->setPointCoordinate(1.0, 2.0, 3.0);
probe1->setName("a_nice_probename");
manager.addEBFieldProbeFrom(probe1,0.0,0.1);
```

```
manager.initialize(DIRECTORY_OUTPUT);
```

The output manager should always be initialized passing DIRECTORY_OUTPUT as an argument.

3.7 Temporal cycle

The user should not modify the temporal cycle without a good reason. Anyway, the code is described here for reference purposes.

```
if (grid.myid == grid.master_proc){
  printf("----\sum START_temporal_cicle_----\n");
 fflush(stdout);
 }
int Nstep = grid.getTotalNumberOfTimesteps();
int dumpID=1, dumpEvery;
if(DO_DUMP){
  dumpEvery= (int)TIME_BTW_DUMP/grid.dt;
grid.istep=0;
if (_DO_RESTART){
  dumpID=_RESTART_FROM_DUMP;
  restartFromDump(&dumpID, &grid, &myfield, species);
while(grid.istep <= Nstep)</pre>
  {
    grid.printTStepEvery(FREQUENCY_STDOUT_STATUS);
    manager.callDiags(grid.istep);
    myfield.openBoundariesE_1();
    myfield.new_halfadvance_B();
    myfield.boundary_conditions();
    current.setAllValuesToZero();
    for (spec_iterator = species.begin();
    spec_iterator != species.end(); spec_iterator++){
      (*spec_iterator)->current_deposition_standard(&current);
    current.pbc();
    for (spec_iterator = species.begin();
    spec_iterator != species.end(); spec_iterator++){
      (*spec_iterator)->position_parallel_pbc();
    }
```

```
myfield.openBoundariesB();
  myfield.new_advance_E(&current);
  myfield.boundary_conditions();
  myfield.openBoundariesE_2();
  myfield.new_halfadvance_B();
  myfield.boundary_conditions();
  for (spec_iterator = species.begin();
  spec_iterator != species.end(); spec_iterator++){
    (*spec_iterator)->momenta_advance(&myfield);
  grid.time += grid.dt;
  moveWindow(&grid, &myfield, species);
  grid.istep++;
  if(DO_DUMP){
    if (grid.istep!=0 && !(grid.istep % (dumpEvery))) {
      dumpFilesForRestart(&dumpID, &grid, &myfield, species);
    }
 }
}
```

3.8 Finalization

```
manager.close();
MPI_Finalize();
exit(1);
```

In these last lines of the code, manager executes its closing routine, MPI_Finalize() is called and the program exits with code 1. No modification by the user is required.

How to run a simulation

First of all, make sure that the output directory has been created.

4.1 Run as a serial job

To run as a serial job, make sure that in main-piccante.cpp source file you have:

```
#define NPROC_ALONG_Y 1
#define NPROC_ALONG_Z 1
```

Then, cd to the directory containing the source file, build it and type simply:

\$./piccante

You should get something like:

```
d8b
                                            888
        Y8P
                                            888
                                            888
8888b.
        888
            .d8888b .d8888b
                            8888b.
                                           888888 .d88b.
                                   8888b.
888 "88b 888 d88P"
                   d88P"
                               "88b 888 "88b 888
                                                 d8P
                                                     Y8b
                           .d888888 888
   888 888 888
                   888
                                        888 888
                                                 8888888
                   Y88b.
888 d88P 888 Y88b.
                           888
                               888 888
                                        888 Y88b. Y8b.
88888P"
        888
           "Y8888P "Y8888P "Y888888 888
                                        888
                                            "Y888 "Y8888
888
888
888
                 version 1.5.0
====== GRID_INITIALIZATION =======
master_proc=0:
        =2500 :
Ncells
                   (2500,
Nprocs
             8:
                     (
                          8,
                                1,
                                       1)
Xrange = [
            -50:
                      0 ]
Yrange = [
             -1:
                       1 ]
                       1]
Zrange = [
             -1:
-----
                             ========
dt=0.019600
dx=0.020000
dy=2.000000
dz=2.000000
Nstep=3063
Boundaries (X,Y,Z) : OPEN , PBC , PBC
```

```
---- START temporal cicle ----
    0/3063 0.000000
                        12:04:39
                                   (03/06/2014)
                                                          1 sec.
    5/3063
            0.098000
                        12:04:39
                                   (03/06/2014)
                                                          1 sec.
   10/3063
            0.196000
                        12:04:39
                                   (03/06/2014)
                                                          1 sec.
                        12:04:39
   15/3063
            0.294000
                                   (03/06/2014)
                                                          1 sec.
   20/3063
            0.392000
                        12:04:39
                                   (03/06/2014)
                                                          1 sec.
```

These lines contains some information about the simulation. As far as the simulation time is of concern, please consider that the load balancing can vary during the simulation and thus the simulation speed may increase or decrease. It is worth to remember that writing output files on disk may be very time-consuming for large files.

You may want to redirect the standard output to a text file. If this is the case, launch the simulation as follows:

\$./piccante > output.txt &

4.2 Run as a parallel job on a single multi-core machine

Make sure that NPROC_ALONG_Y times NPROC_ALONG_Z (in the main-piccante.cpp) is a multiple of the number of MPI tasks you want to launch.

Suppose, for example, that you want to launch a 2D simulation on a 8-core machine and that you have:

```
#define NPROC_ALONG_Y 4
#define NPROC_ALONG_Z 1
```

Launching the code with:

```
$mpirun -np 8 ./piccante
```

will result in having 4 processes along y and 2 along x.

You should get on the standard output a longer initial message, detailing the boundaries of each process.

If you want to redirect the standard output to a text file, type:

\$ mpirun -np 8 ./piccante > output.txt &

4.3 Run on a BG/Q supercomputer

Ask one of the contributors for the appropriate compile script.

How to analyse the results

Most of the output files are in binary format. The code comes with a reader tool, which is able to covert the binary file into a text file. Then, the text file can be visualized using Gnuplot(http://www.gnuplot.info/) or Paraview(http://www.paraview.org/). Paraview is suggested for 3D plots.

5.1 Get the reader

reader is available as an open-source repository. To get the reader, simply type (see ??):

git clone https://github.com/ALaDyn/tools-piccante.git

5.2 Compile the reader

To compile *reader*, it should be enough to do a make in the tools-piccante root folder. Then, you may want to launch *reader* from any location on your system. To make it possible, copy the *reader.exe* executable in the \usr\bin folder.

\$ sudo cp reader.exe /usr/bin/reader

If you don't want to do this, or you just cannot do it, please refer to your *reader.exe* location in the following guide, instead of just the command *reader* we are going to use.

5.3 Human readable outputs

5.3.1 diag.dat file

diag.dat is a text file created by the *master proc* at the beginning of the simulation. Each call to this output produces a new line in the file.

diag.dat contains information about the total energy of the simulation and how it is distributed among fields and particle species.

From left to right, the columns in the file are:

- simulation step
- simulation time
- total energy
- energy contribution of E_x EM field component
- energy contribution of E_y EM field component
- energy contribution of E_z EM field component

- energy contribution of B_x EM field component
- energy contribution of B_y EM field component
- energy contribution of B_z EM field component
- energy contribution of species 1
- energy contribution of species 2
- ...

For the visualisation in a terminal, due to the large number of columns, you may want to use the command:

\$ less -S diag.dat

5.3.2 EXTREMES_{*} files

If the *Diag* output is enabled, one *Extremes* file will be produced for the EM field (EXTREMES_EMfield.dat). In addition, for each species in the simulation, an *Extremes* file will be written on disk (for "ELE1" species, it will be EXTREMES_ELE1.dat).

The columns of the Extremes file for the EM field are:

- simulation step
- simulation time
- minimum value of E_x EM field component
- maximum value of E_x EM field component
- ... (the same for each field component)
- maximum value of |**E**|
- maximum value of $|\mathbf{B}|$

For the $\it Extremes$ file of a species the columns are:

- simulation step
- simulation time
- \bullet minimum value of the x coordinate of the particles
- \bullet maximum value of the x coordinate of the particles
- ... (the same for y, z, p_x, p_y, p_z)
- minimum value of $\gamma 1$ factor
- maximum value of $\gamma 1$ factor

If there are no particles in a given time-step (this may happen for example if you use the moving window), large numbers ($\pm 1.0e30$) are reported in the *Extremes* file. Also for these files, you may want to use the command less -S due to the large number of columns.

5.3.3 SPECTRUM_* files

This diagnostic is enabled with *Diag* output and it produces a separate file for each species and each output time. The syntax of these files is SPECTRUM_NAME_TIME.dat.

Each file contains an energy spectrum of a given species at a given time. You can visualize these spectra with *gnuplot*:

```
$ gnuplot
```

```
> plot "SPECTRUM_ELE1_020.000.dat" u ($1+$2):3 w 1
```

5.3.4 EMProbe* files

EMProbe_PROBENAME_PROBEID.txt contains the interpolated values of the electromagnetic fields at the position given via the emProbe object during the call. PROBENAME is chosen by the user by setting it via the emProbe object. PROBEID is a progressive number to avoid overwriting a probe which may incidentally have the same name.

- simulation step
- simulation time
- value of E_x
- value of E_y
- value of E_z
- value of B_x
- value of B_u
- value of B_z

5.3.5 *.map files

These files are basically for debug purpose only. They always come in pair with a binary file and they contain some of the information included in the binary header in a human readable format.

5.4 Binary outputs

Among the binary (*.bin) output files, all but the phase space files require reader to be analysed.

5.4.1 EM field files

These files (Efield_TIME.bin and Bfield_TIME.bin) and their subdomains' equivalent (E_FIELD_DOMAINNAME_DO contains the EM field of the simulation at a given time-step.

First, launch *reader* passing the file name as an argument (this is usually extremely fast for 1D simulation, while it can take several minutes for 2D or 3D simulations):

```
$ reader Efield_050.000.bin
```

This command produces a file with a .txt extension (Efield_050.000.bin.txt) in this case. The columns of this file are, respectively: x, y, z, E_x, E_y, E_z . So, if you want to plot the E_x field component of a 2D simulation with gnuplot, launch the application and type:

```
$ gnuplot
```

```
> plot "Efield_050.000.bin.txt" u 1:2:4 w image
```

If you have used the stretched grid feature, plotting with image won't work correctly. In this case you have to type:

```
> set pm3d map
> splot "Efield_050.000.bin.txt" u 1:2:4 w pm3d
```

You can avoid launching the reader for every single file implementing some simple bash scripts. The following script, for example, plots the E_x field component and saves it as a .png file for each Efield file in the TEST directory:

For the visualization of 3D data it is strongly suggested to use paraview.

5.4.2 binary output formats

After some analysis it has been decided that netCDF and HDF5 is indeed the path you want to follow for structured - well organized - multiformats output. However using libraries, at the very beginning, might appear cumbersome; so while the library output is on its (fast) way, we have also developed an owner format.

The binary format has the following structure:

5.4.3 Density files

Most of what has been said for EMfield files is valid for Density files. They have their subdomain version too DENS_SPECNAME_DOMAINNAME_DOMAINID_TIME.bin Their name structure is DENS_SPECNAME_TIME.bin and, once converted with reader, they are 4 columns files (x, y, z, ρ) . The charge density is always positive.

Suppose that you want the *total charge density* in a simulation where you have one electron species "ELE1" and one ion specie "ION1". With *qnuplot* you can accomplish this as follows:

```
> plot "< paste DENS_ION1_024.000.bin.txt DENS_ELE1_024.000.bin.txt" u 1:($4-$8) w 1
```

5.4.4 Current files

Most of what has been said for *EMfield* files is valid for *Density* files. Their name structure is $J_{\text{TIME.bin}}$ and, once converted with *reader*, they are 6 columns files (x, y, z, J_x, J_y, J_z) .

5.4.5 PhaseSpace files

The *PhaseSpace* files (PHASESPACE_NAME_TIME.bin) have a very simple structure: for each particle, 7 float numbers are saved. These numbers are, respectively: x, y, z, p_x, p_y, p_z and the weight of the particle. Due to their simplicity, these files can be plotted with gnuplot:

> plot "PHASESPACE_ELE1_055.000.bin" binary format="%f%f%f%f%f%f%f%f" u 1:4 w d

For example, this command plots the $x-p_x$ projection of the phase space. Since these files are usually very large, you may want to plot just a fraction of the particles. Suppose that you want to plot one particle every 100:

> plot "PHASESPACE_ELE1_055.000.bin" binary format="%f%f%f%f%f%f%f%f%f" every 100 u 1:4 w d

Main files collection

In this section, the example main files in the Example directory are briefly discussed. To launch these simulations, you have to copy the corresponding main file in the source directory, rename it main-piccante.cpp and compile the code.

The 2D and 3D simulations provided in the Example folder are designed to be launched on a super-computer, due to the large computational requirements. However, it is possible to run "small" 2D simulations also on personal computers.

6.1 1D wakefield with moving window

main file name	simple_1d_wakefield.cpp
short description	simple simulation of a nonlinear wakefield with moving window
dimensionality	1D
expected execution time	around 1 minute on a modern machine (4 MPI processes)

In this simulation, a P polarized laser pulse with a normalized amplitude of 1.0 enters in an underdense plasma (density of 0.01, with a soft sin² ramp). The moving window feature is used. It is worth to remind that, for the moment, new plasma is added with zero temperature.

Figure 6.1 reports the phase space of the electrons after 50.0 periods.

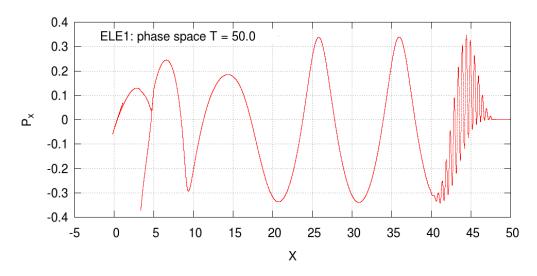


Figure 6.1: 1D wakefield: electrons phase space

6.2 1D simple TNSA simulation

main file name	1d_TNSA.cpp
short description	simple simulation of TNSA ion acceleration
dimensionality	1D
expected execution time	around 1 minute on a modern machine (4 MPI processes)

A P polarized laser pulse with a normalized amplitude of 8.0 interacts with a thin (1.5 λ) carbon target("ION1"). There's a very thin layer of hydrogen contaminants on the rear side of the target. Picture 6.2 shows the phase space of carbon ions.

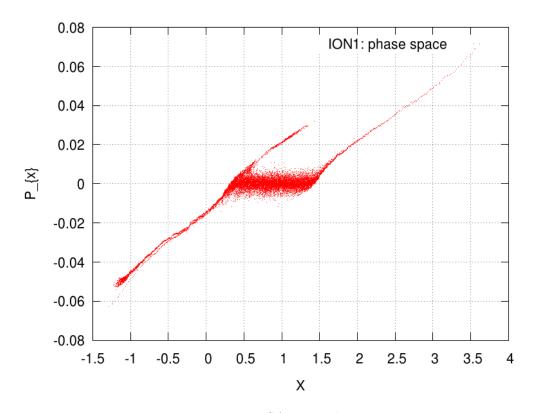


Figure 6.2: 1D TNSA: ion1 phase space

6.3 2D grating with stretched grid and 2 laser pulses

main file name	2d_grating.cpp
short description	two laser pulses a grating target
${f dimensionality}$	2D
expected execution time	around 1.5 hours on a supercomputer (1024 MPI processes on a BG/Q)

In this simulations, two inclined laser pulses interact with an overdense grating target. Several features of emphpiccante code are used in this simulation, such as the stretched grid, complex target shapes and multiple laser pulses. Figure 6.3 shows the initial setup of this simulation.

6.4 3D two stream instability

main file name	3d_twostream.cpp
short description	two counter-streaming electron clouds
${f dimensionality}$	3D
expected execution time	several hours on a supercomputer (1024 MPI processes on a BG/Q)

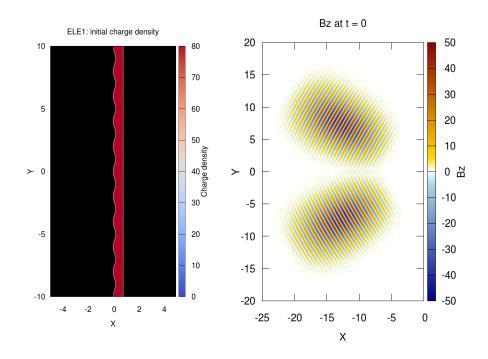


Figure 6.3: 2D grating: The initial setup (target and Bz field component)

In this simulation there are two counter-streaming electron clouds with normalized momentum along z equal to 1. There is a very small initial temperature.

An instability develops and a significant fraction of the initial kinetic energy is converted into EM field energy.

Figure 6.4 shows the charge density of one of the electron species after a few plasma periods.

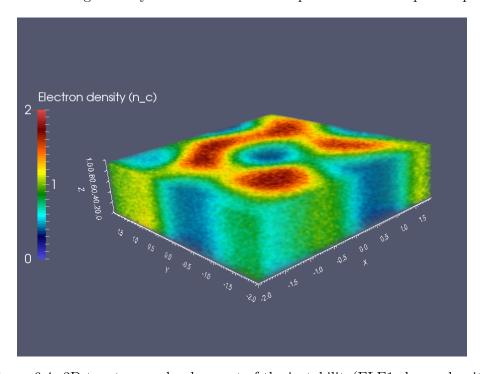


Figure 6.4: 3D twostream: development of the instability(ELE1 charge density)

Appendix A: code normalization

Everything in the code scales with ℓ_0 scale-length. m_e and q_e are, respectively, the mass and the charge of an electron, while c is the speed of light.

Normalization of code quantities

$$q = \tilde{q} q_e$$

$$m = \tilde{m} m_e$$

$$\mathbf{E} = \tilde{\mathbf{E}} \frac{m_e c^2}{q_e \ell_0}$$

$$\mathbf{B} = \tilde{\mathbf{B}} \frac{m_e c^2}{q_e \ell_0}$$

$$t = \tilde{t} \frac{\ell_0}{c}$$

$$l = \tilde{l} \ell_0$$

$$\mathbf{p} = \tilde{\mathbf{p}} \tilde{m} m_e c$$

$$\mathbf{v} = \tilde{\mathbf{v}} c$$

$$\mathbf{J} = \tilde{\mathbf{J}} \frac{m_e c^3 \pi}{q_e \ell_0}$$

Normalized Particle equations

$$\begin{cases} \partial_{\widetilde{t}} \widetilde{p} = & \frac{\widetilde{q}}{\widetilde{m}} \left(\widetilde{\mathbf{E}} + \widetilde{\mathbf{v}} \times \widetilde{\mathbf{E}} \right) \\ \widetilde{\mathbf{J}} = & \widetilde{q} \sum_{n} \frac{W_{n}}{\Delta \widetilde{V}} \widetilde{\mathbf{v}}_{n} \end{cases}$$

Normalized Maxwell equations

$$\begin{cases} \partial_{\widetilde{t}}\widetilde{\mathbf{B}} = & -\widetilde{\nabla}\times\widetilde{\mathbf{E}} \\ \partial_{\widetilde{t}}\widetilde{\mathbf{E}} = & \widetilde{\nabla}\times\widetilde{\mathbf{B}} - 4\pi^2\widetilde{\mathbf{J}} \end{cases}$$