



ProtoBot parts list:

- 2 x [N20 Gear motors](#) (300RPM, 12V)
- [Plastic Wheels](#) (39mm dia, for D type axle - Enough for 5 robots)
- [Tactile Switches](#) (Bump Sensors, Enough for 5 robots)
- [L293D Motor Driver IC](#) (Enough for 10 robots)
- [Wires](#) (Female to female jumper wires - Enough for 4 robots)
- [Headers](#) (For use with the jumper wires)
- [9V battery Clips](#) (Enough for 10 robots)
- [10K resistors](#) (Enough for 25 robots)
- [220 Ohm resistors](#) (enough for 50 robots)
- [Arduino Nano](#) (ATEMGA328P module, *not* interface base module)
- [Reflective IR optical sensor](#) (Enough for 5 robots)
- [Female header pins](#) (Not entirely necessary, but nice for battery connections + to make the Arduino Nano removeable)
- PCBs - Gerber, SVG, and PDF available on [the GitHub](#)
- 3D printed parts - Base and Antenna, available on [the Github](#)

Notes:

- Quantities listed above are for a total of 1 complete ProtoBot. You will have extra parts left over, though.
- Most of the items on eBay are from China, free EPacket shipping, which will take as much as 2 months to get to people in the USA (3 months, in extreme cases)
- For my PCBs, I use a PCB prototyping service, PCBway.com. So far, they seem to produce decent PCBs at a very low cost.

From the ProtoBots Github: <https://github.com/Bobcatmodder/ProtoBots>



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