Julia Di

U.S. Citizen | 566 Arguello Way, Apt 254 Stanford, CA 94305, USA juliadi@stanford.edu | @astroboticist | www.juliadi.com | (301) 906-6221

EDUCATION

Stanford University, Stanford, CA, USA

Ph.D. in Mechanical Engineering | Minor in Entreprenuership Sep 2018 – Jun 2024 Courses: Advanced Robotic Manipulation, Multi-Limbed Manipulation, Deep Learning, Applied Machine Learning, ME218: Mechatronics, Building an Aerospace Startup

Columbia University, New York, NY, USA

B.S. in Electrical Engineering | Minor in Computer Science Aug 2014 – May 2018 GPA: 3.90 / 4.00 | Magna Cum Laude

WORK

NASA Jet Propulsion Laboratory, Pasadena, CA, USA

EXPERIENCE NASA Space Technology Research Fellow (NSTRF) Jun 2019 - Aug 2019

• Design inherently flexible fold angle detection sensors for origami-inspired robots

Generation Orbit Launch Services, Inc., Atlanta, GA, USA

Brooke Owens Fellow May 2018 – Jul 2018

Designed flight computer and other key circuit boards for hypersonic Air Force rocket X-60A

Lockheed Martin Space Systems, Sunnyvale, CA, USA

Electro-Optical Engineering Research Intern

Jun 2017 – Aug 2017

Developed algorithms on FPGAs for aerial realtime onboard image processing capabilities

NASA Marshall Space Flight Center, Huntsville, AL, USA

Robotics Academy Research Associate

Jun 2016 – Aug 2016

Designed and tested a 3 DOF robotic arm with electrostatic gripper to capture orbital debris

RESEARCH

Biomimetics and Dexterous Manipulation Lab, Stanford University

EXPERIENCE NASA NSTRF Graduate Fellow, Mechanical Engineering Department Dec 2018 – present

Developing tactile sensors and multimodal sensor algorithms for robotic perception

CHARM Lab, Stanford University

NASA NSTRF Graduate Fellow, Mechanical Engineering Department Sep 2018 – Dec 2018

Building a soft sensor array for detecting finger location on a multimodal haptic skin

Creative Machines Lab, Columbia University

Undergraduate Research Assistant, Mechanical Engineering Department Sep 2016 – May 2018

Built a 3D-printed quadruped with image recognition capabilities as a machine learning platform

Columbia Laboratory for Unconventional Electronics, Columbia University

Undergraduate Research Assistant, Electrical Engineering Department Jan 2015 – May 2015

• Designed and constructed an ion sputterer to microfabricate thin-film bulk acoustic resonators

SELECTED LEADERSHIP **EXPERIENCE**

Columbia Space Initiative, Columbia University

Co-Founder and Co-President

Sep 2015 – Mar 2017

• Accepted to three technical NASA challenges and featured in University's Fall 2016 magazine

Women in Computer Science, Columbia University

Apr 2015 – May 2018

Through WiCS mentorship and scholarship efforts, department became 45% female in Fall 2017

Columbia MakerSpace, Columbia University

Superuser Apr 2016 – May 2018

Responsible for weekly office hours to teach students about prototyping and 3D printing skills

HONORS & AWARDS

TVF Entrepreneurial Leaders Fellow, Stanford University

Nov 2018 - Jun 2019

Brooke Owens Fellow, Brooke Owens Fellowship

Jan 2018

King's Crown Leadership and Excellence Award, Columbia University

Apr 2017

Aviation Week's Top 20 Twenties Laureate, Aviation Week Magazine

Feb 2017

LANGUAGES Python • Julia • C/++ • Verilog • VHDL • MatLab • LATEX • HTML • Java • LabView

3D Printing • Deep Learning • Git • Machine Learning • Microcontrollers • PCBs • Perception **SKILLS**