Computer Science and Artificial Intelligence (P3)

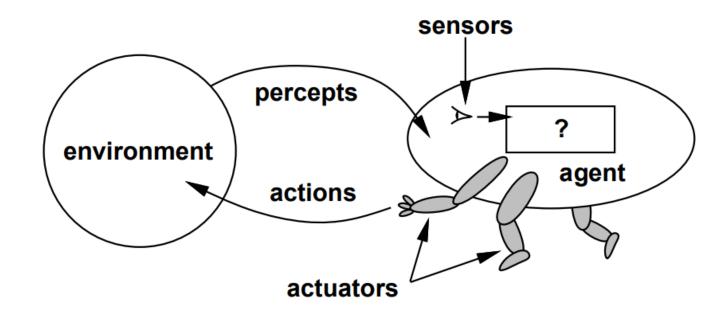




Content

- Agent
- Perception
- Reasoning
- Additional Areas of Research





AGENTS AND ENVIRONMENTS



What is Agent?

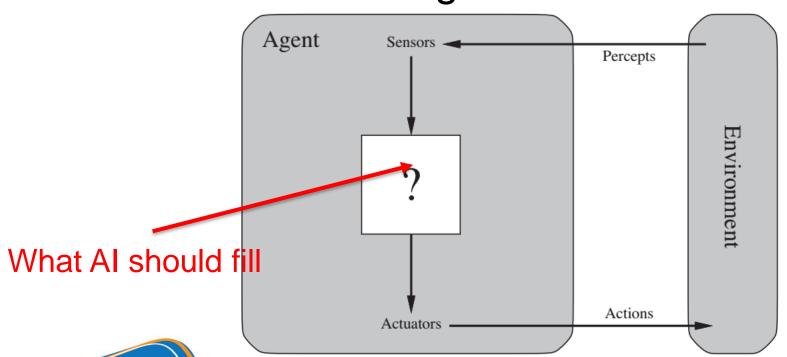
- Al studies how to make computers do things that people are better at if they could
 - Extend what they do to huge data sets
 - Do it fast, in near real-time
 - Not make mistakes
- Such systems are called Agents.





What is Agent?

An agent perceives its environment through sensors and acts upon that environment through actuators.



Agents interact with environments through sensors and actuators.



Examples of agents



Human agent

Sensors: eyes, ears, and other organs.

Actuators: hands, legs, vocal tract, etc.



Robotic agent

Sensors: cameras, infrared range finders, etc.

Actuators: levels, motors, etc.



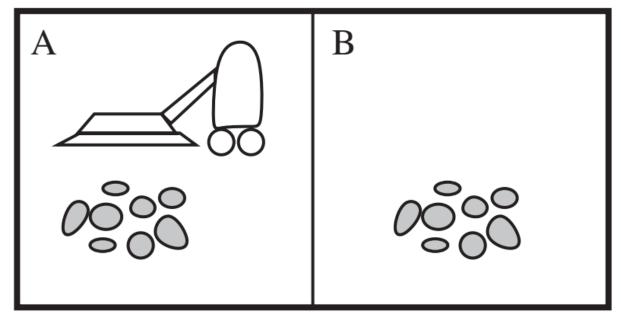
Software agent

Sensors: keystrokes, file contents, network packets, etc.

Actuators: monitor, physical disk, routers, etc.



The Vacuum-cleaner world

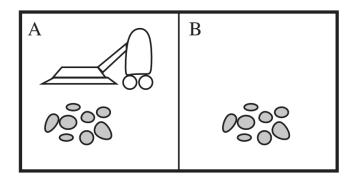


A vacuum-cleaner world with just two locations

- Percepts: location and contents, e.g., [A,Dirty]
- Actions: Left, Right, Suck, Do Nothing



The Vacuum-cleaner world



function REFLEX-VACUUM-AGENT([location,status]) returns an action

if status = Dirty **then return** Suck

else if *location = A* **then return** *Right*

else if *location = B* **then return** *Left*

The agent program for a simple reflex agent in the two-state vacuum environment.



Why do we need agents?

- Research in artificial intelligence can be characterized in the context of building agents that behave intelligently
- □ The actions of the agent's actuators must be rational responses to the data received though its sensors.
- In turn, we can classify this research by considering different levels of these responses



Why do we need agents?

- A tool for analyze systems
- All areas of engineering can be seen as designing artifacts that interact with the world.
- Al designs artifacts that have significant computational resources and the task environment requires nontrivial decision making





THE CONCEPT OF RATIONALITY



Rational agents

- A rational agent is one that does the right thing.
- What is "right" thing?
 - The actions that cause the agent to be most successful
- We need ways to measure success.



Performance measure

- An agent, based on its percepts → generates actions sequence → environment goes to sequence of states
 - If this sequence of states is desirable, then the agent performed well.
- Performance measure evaluates any given sequence of environment states (remember, not agent states!!!).
 - □ An objective function that decides how the agent does successfully. E.g., 90%? 30%?



Design performance measures

- ☐ General rule: Design performance measures according to
 - What one **actually wants** in the environment Not how one **thinks** the agent should behave
- □ For example, in vacuum-cleaner world
 - ☐ The amount of dirt cleaned up in a single eight-hour shift, or
 - □ The floor clean, no matter how the agent behaves
 - Which one is better?



Rationality

What is rational at any given time depends on

Performance measure

Define the criterion of success

Prior knowledge

What the agent knows about the environment

Percept sequence

The agent's percept to date

Actions

What the agent can perform



Definition of a rational agent

For each possible percept sequence, a rational agent should select an action that is expected to maximize its performance measure, given the evidence provided by the percept sequence and whatever built-in knowledge the agent has.

- ☐ For example, in an exam,
 - Maximize marks based on the questions on the paper and your knowledge





The Vacuum-cleaner agent

- Performance measure
 - Award one point for each clean square at each time step, over 10000 timesteps
- Prior knowledge about the environment
 - The geography of the environment (2 squares)
 - The effect of the actions
- Actions that can perform
 - Left, Right, Suck and Do Nothing
- Percept sequences
 - Where is the agent?
 - Whether the location contains dirt?
- Under this circumstance, the agent is rational.



Types of agent programs

Simple based reflex agent

Goal-based agents

Utilitybased agents





Simple reflex agents

- The simplest kind of agent, limited intelligence
- Select actions based on the current percept, ignoring the rest of the percept history
- The connection from percept to action is represented by condition-action rules.

IF current percept THEN action

- □ E.g., IF *car-in-front-is-braking* THEN *initiate-braking*.
- Limitations
 - Knowledge sometimes cannot be stated explicitly → low applicability
 - Work only if the environment is fully observable



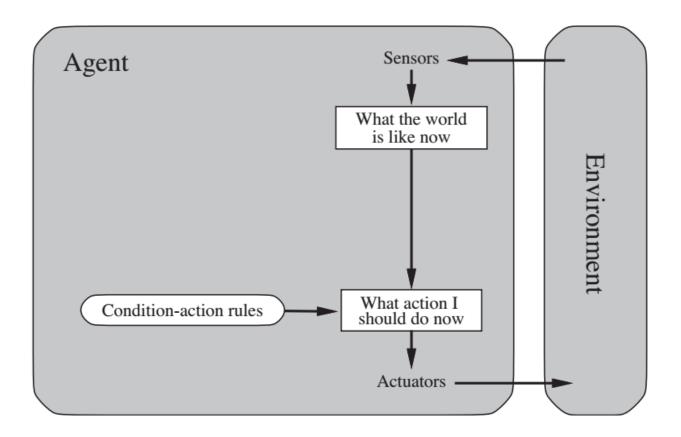
Simple reflex agents

function Reflex-Vacuum-Agent([location,status]) returns an action

if status = Dirty then return Suck else if location = A then return Right else if location = B then return Left

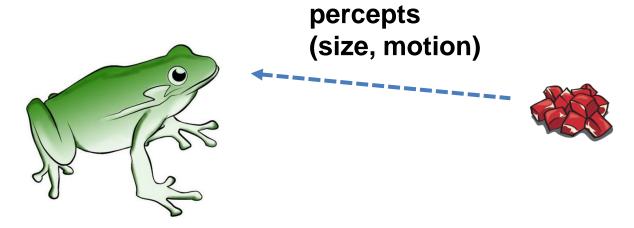
- The vacuum agent program is very small compared to the corresponding table
- The most obvious reduction: ignoring the percept history, which cuts down the number of possibilities from 4^T to just 4
- A further, small reduction comes from the fact that when the current square is dirty, the action does not depend on the location.







A Simple reflex agent in nature



Action: SNAP or AVOID or NOOP

RULES:

- (1) If small moving object, then activate SNAP
- (2) If large moving object, then activate AVOID and inhibit SNAP

ELSE (not moving) then NOOP

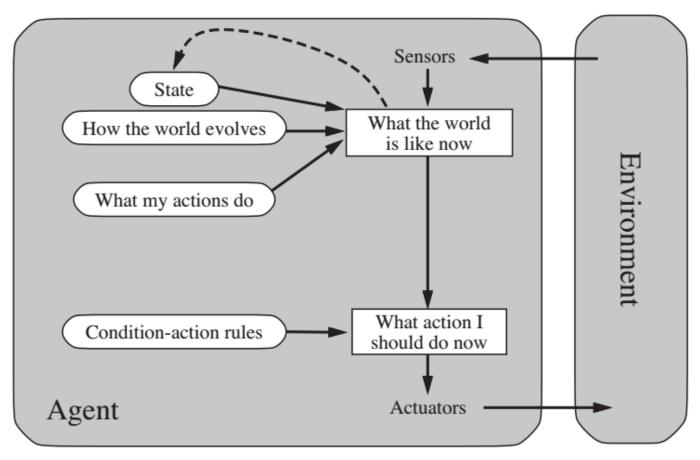


Model-based reflex agents

- □ The agent must keep track of an internal state in partially observable environments.
 - It depends on the percept history and reflects some of the unobserved aspects, e.g., driving a car and changing lane.
- The agent program updates the internal state information as time goes by by encoding two kinds of knowledge
 - How the world evolves independently of the agent
 - How the agent's actions affect the world

model of the world





Example table agent with internal state

 $\frac{2}{2}$

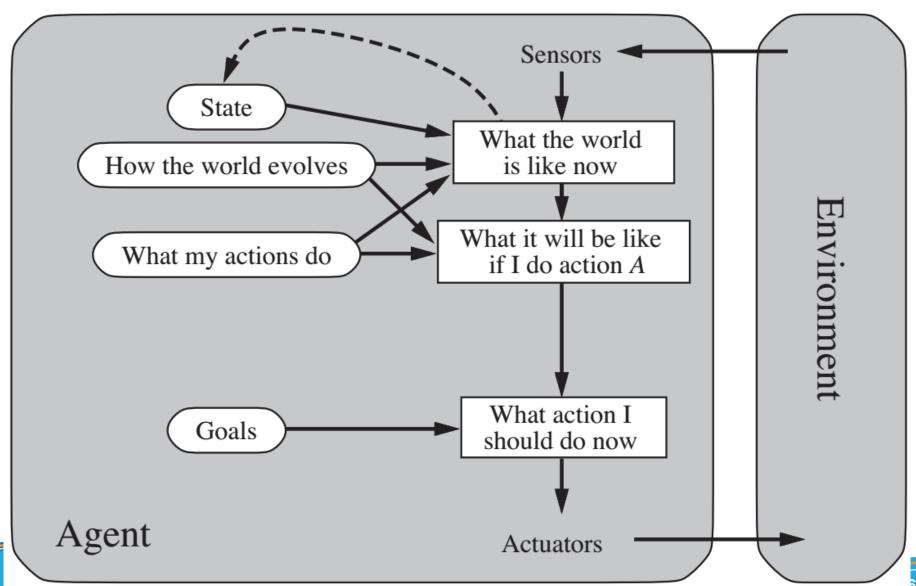


Goal-based agents

- Current state of the environment is always not enough
- The agent further needs some sort of goal information that describes desired situations.
 - □ E.g., at a road junction, the taxi can turn left, turn right, or go straight on, depending on where the taxi is trying to get to.
- Less efficient but more flexible
 - Knowledge supporting the decisions is represented explicitly and can be modified.



Goal-based agents



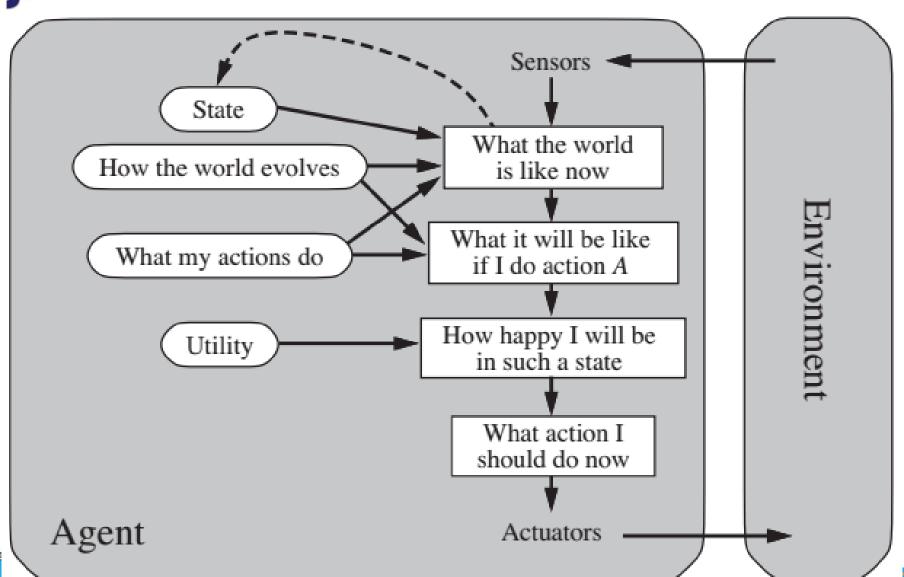


Utility-based agent

- Goals are inadequate to generate high-quality behavior in most environments.
 - Many action sequences can get the goals, some are better, and some are worse, e.g., go home by taxi or Grab car?
- An agent's utility function is essentially an internalization of the performance measure.
 - Goal → success, utility → degree of success (how successful it is)
 - If state A is more preferred than others, then A has higher utility.



Utility-based agent



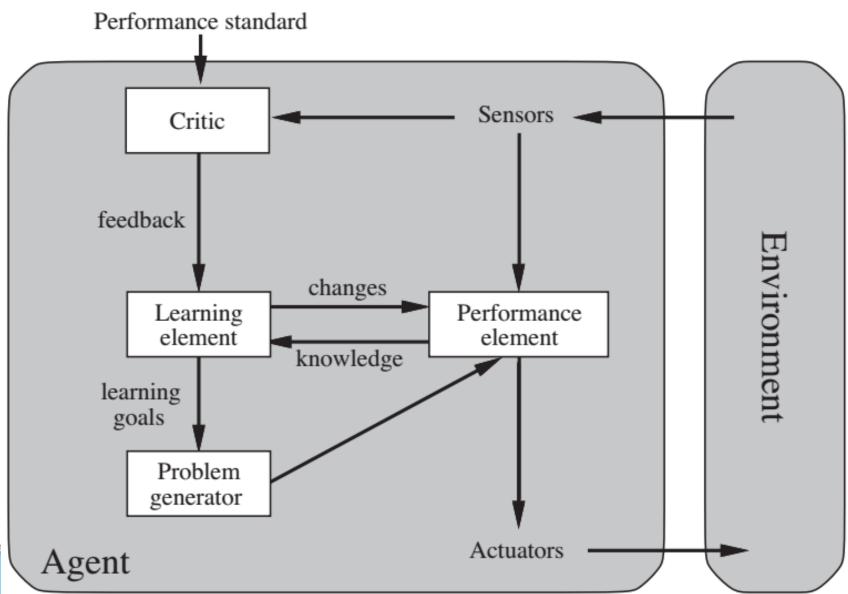


Learning agents

- After an agent is programmed, can it work immediately?
 - No, it still need teaching
- Once an agent is done, what can we do next?
 - □ Teach it by giving it a set of examples
 - Test it by using another set of examples
- □ We then say the agent learns → learning agents



Learning agents



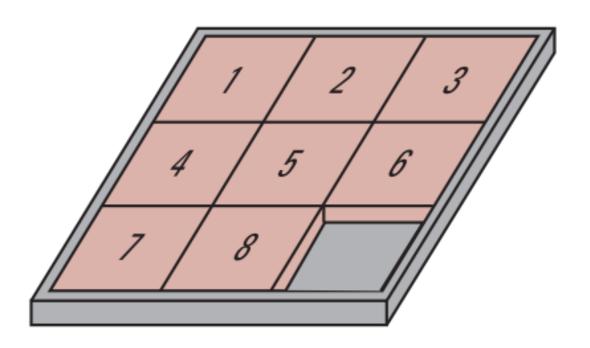


Learning agents

- A learning agent is divided into four conceptual components
 - 1. Learning element → Make improvement
 - 2. Performance element → Select external actions
 - Critic → Tell the Learning element how well the agent is doing with respect to fixed performance standard. (Feedback from user or examples, good or not?)
 - Problem generator → Suggest actions leading to new and informative experiences

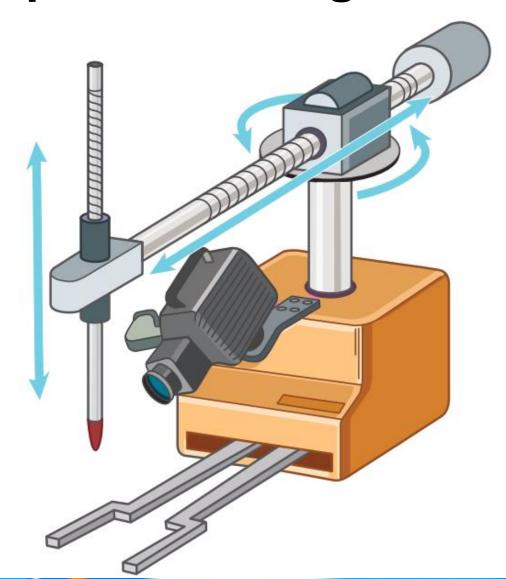


The eight-puzzle in its solved configuration





Our puzzle-solving machine





Content

- Agent
- Perception
- Reasoning
- Additional Areas of Research

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Perception

Four

- □ To respond intelligently to the input from its sensors, an agent must be able to understand that input (perceive).
- Two areas of research in perception that have proven to be especially challenging:

□ Understanding images (Computer Vision) and language (NLP).

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Computer vision

- □ Computer vision is a field of artificial intelligence (AI) that enables computers and systems to derive meaningful information from digital images, videos and other visual inputs and take actions or make recommendations based on that information.
- If Al enables computers to think, computer vision enables them to see, observe and understand.



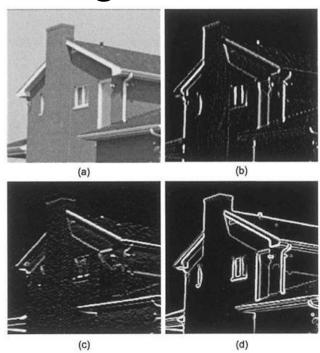
Techniques for Understanding Images

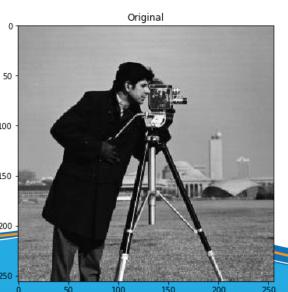
- Template matching
- Image processing (identifying characteristics of
 - the image)
 - edge enhancement
 - region finding
 - smoothing

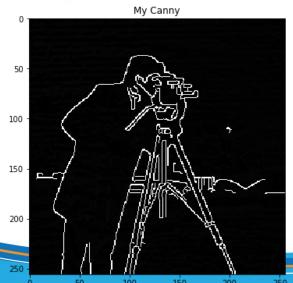
- Image analysis (the process of understanding what these characteristics mean)
- Some demo: https://setosa.io/ev/image-kernels/

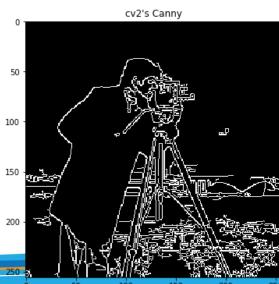


Edge enhancement











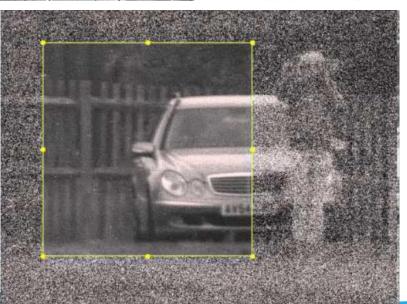
Region finding





Smoothing





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Image analysis





man sitting

on a table

blue jeans

the ground

Image analysis

people are in the background

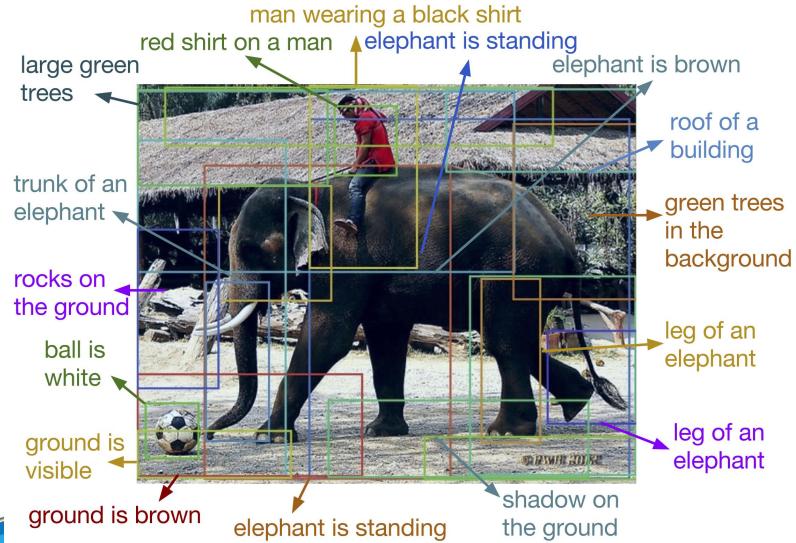


floor is brown

man sitting on a table



Image analysis



https://github.com/jcjohnson/densecap/blob/master/imgs/resultsfig.png



Natural language processing

- Natural language processing (NLP) is the intersection of computer science, linguistics and machine learning.
- NLP is all about making computers understand and generate human language.



Natural language processing

- Speech recognition
 - □ The translation of spoken language into text.
- Natural language understanding
 - a computer's ability to understand language.
- Natural language generation
 - the generation of natural language by a computer.



Language Processing

- Programming languages are constructed from well-designed primitives so that each statement has only one grammatical structure and only one meaning.
- A statement in a natural language can have multiple meanings depending on its context or even the manner in which it is communicated.
- To understand natural language, humans rely heavily on additional knowledge.



Language Processing

- Consider these sentences:
 - Norman Rockwell painted people.
 - Cinderella had a ball.
 - Do you know what time it is?



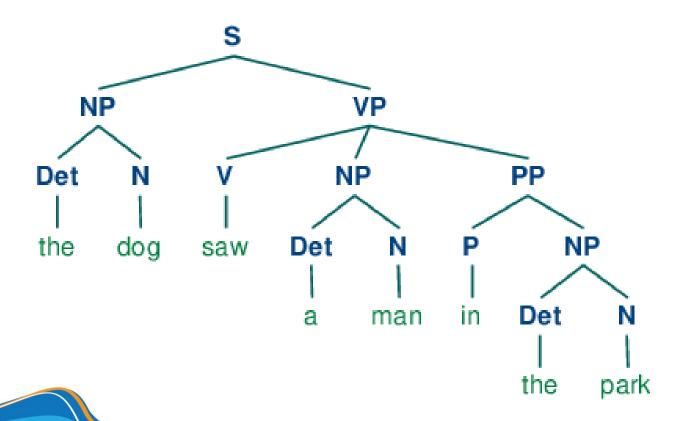
Language Processing

- To understand the meaning of a statement in a natural language requires several levels of analysis
 - Syntactic Analysis
 - Semantic Analysis
 - Contextual Analysis



Syntactic analysis

Identifies the grammatical role of each word





Syntactic analysis

- Identifying the semantic role of each word.
- A technique that can analyze the meaning of a text
- Syntactic analysis focuses on "form" and syntax, meaning the relationships between words in a sentence.
- Semantic analysis focuses on "meaning," or the meaning of words together and not just a single word.



Syntactic analysis

- Example:
 - ☐ The customer, says Mister Johnson, is satisfied.
 - The customer says: Mister Johnson is satisfied.
- Understanding the logical meaning that connects the parts of a sentence



Contextual analysis

- The context of the sentence is brought into the understanding process
- Example:
 - The bat fell to the ground.
 - Do you know what time it is?



Other research in NLP

- Information retrieval
 - □ Task of identifying documents that relate to the topic at hand.
 - □ Search sites for key words. "Automobiles" vs "cars."
 - Needed a search mechanism that understands the contents of the sites being considered.

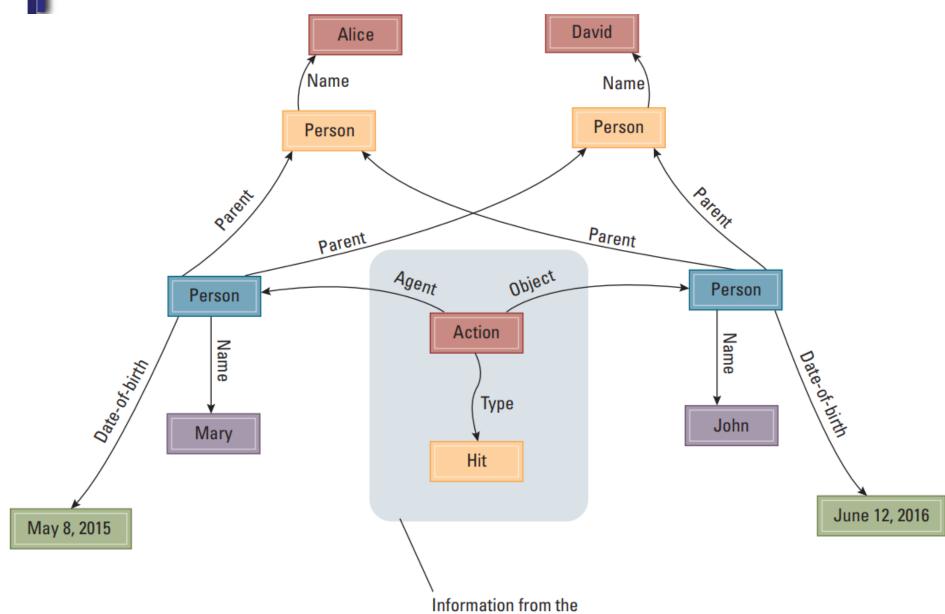


Other research in NLP

- Information extraction
 - □ Task of extracting information from documents so that it takes a form that is useful in other applications
 - ☐ Frame and semantic net



A semantic net

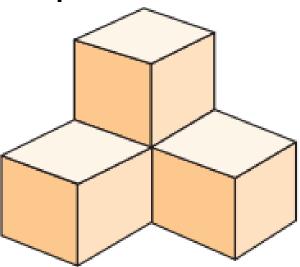


sentence "Mary hit John."



Quiz 1

- How many blocks are in the stack represented next?
- How could a machine be programmed to answer such questions accurately?





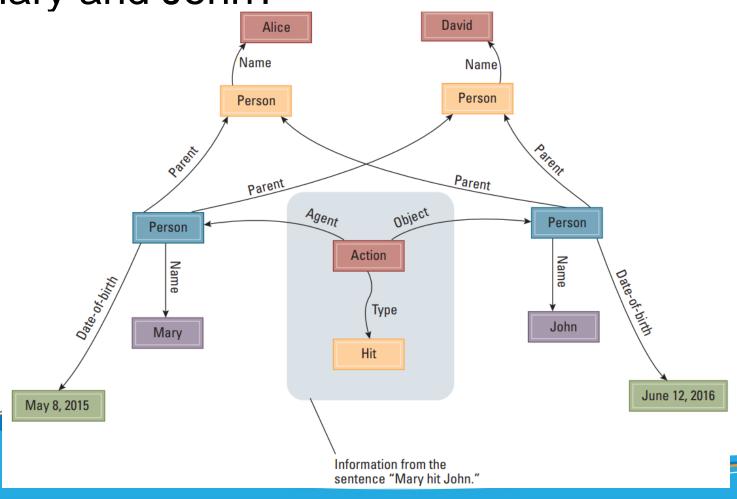
Quiz 2

- Compare the results of parsing the following two sentences. Then, explain how the sentences differ semantically
 - □ The farmer built the fence in the field.
 - The farmer built the fence in the winter.



Quiz 3

What is the family relationship between Mary and John?





Content

- Intelligence and Machines
- Perception
- Reasoning
- Additional Areas of Research
- Artificial Neural Networks
- Robotics
- Considering the Consequences
- □ About Computer Science Department



Reasoning

- Reasoning is the act of deriving a conclusion from certain premises using a given methodology.
- Reasoning is a process of thinking.
- Reasoning is logically arguing.
- Reasoning is drawing inference.
- It must figure out what it needs to know from what it already knows



Reasoning Example

If we know:

Robins are birds, and

All birds have wings

Then if we ask:

Do robins have wings?

To answer this question - some reasoning must go.



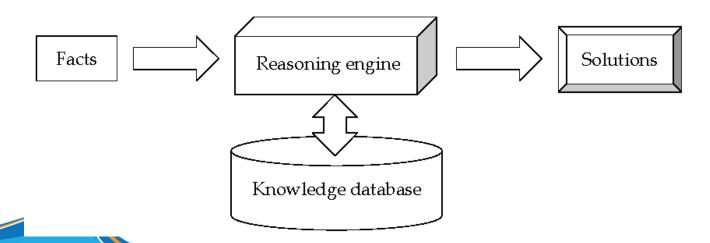
Uncertainty in Reasoning

- □ The world is an uncertain place; often the Knowledge is imperfect (Incomplete, Inconsistent, Changing) which causes uncertainty.
 - Therefore reasoning must be able to operate under uncertainty.
- Al systems must have ability to reason under conditions of uncertainty.



Reasoning under uncertainty

- Many reasoning systems provide capabilities for reasoning under uncertainty.
- ☐ This is important when building situated reasoning agents which must deal with uncertain representations of the world.





Reasoning Systems

- Production systems
- Theorem provers
- Deductive retrieval systems
- Semantic networks
- ...



Production Systems

- 1. Collection of states
 - Start (or initial) state
 - Goal state (or states)
- 2. Collection of productions: rules or moves
 - A production is an operation that can be performed in the application environment to move from one state to another
 - Each production may have preconditions
- 3. Control system: decides which production to apply next

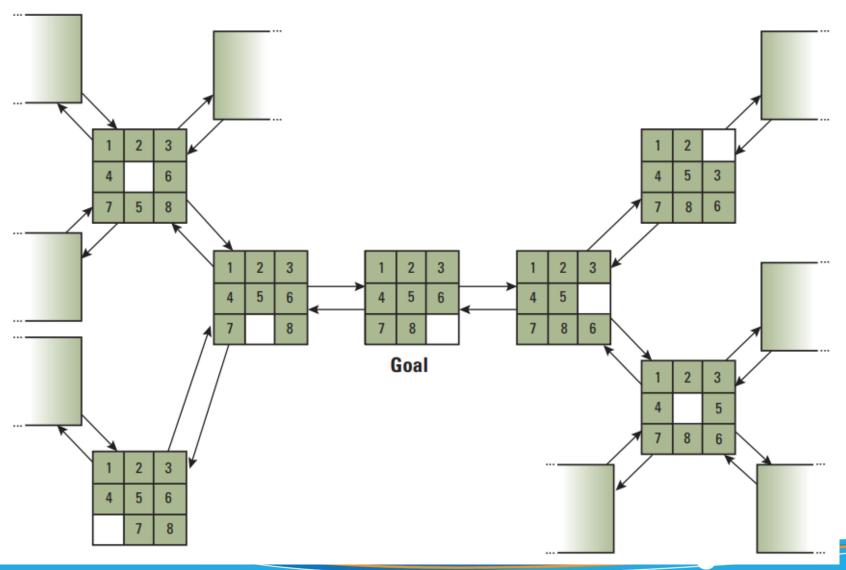


Reasoning by Searching

- State Graph: All states and productions
- Search Tree: A record of state transitions explored while searching for a goal state
 - Breadth-first search
 - Depth-first search



A small portion of the eightpuzzle's state graph





Reasoning by Searching

- □ The problem faced by the control system becomes that of finding a sequence of arrows that leads from the start state to the goal state.
- The task of the control system can be viewed as that of finding a path through a state graph.
- If a problem can be characterized in terms of a production system, then its solution can be formulated in terms of searching for a path.
- Ex: chess



Deductive reasoning in the context of a production system

Start state

Socrates is a man. All men are humans. All humans are mortal.

Socrates is a man.
All men are humans.]—=> Socrates is a human.

Socrates is a man. All men are humans. All humans are mortal. Socrates is a human.

Intermediate state

Socrates is a man.
All men are humans.
All humans are mortal.
Socrates is a human.
Socrates is mortal.

All humans are mortal. Socrates is a human.

Goal state

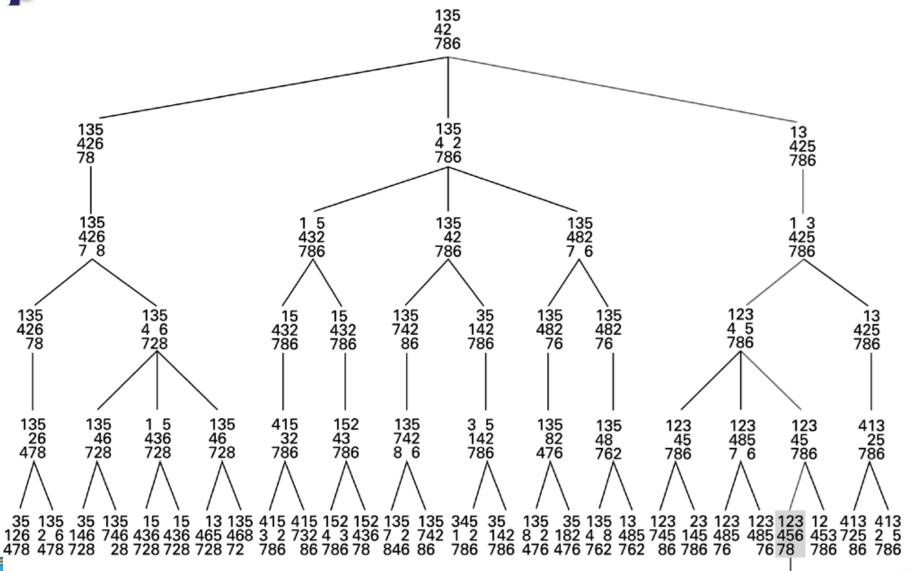


An unsolved eight-puzzle

1	3	5
4	2	
7	8	6



A sample search tree



Goal

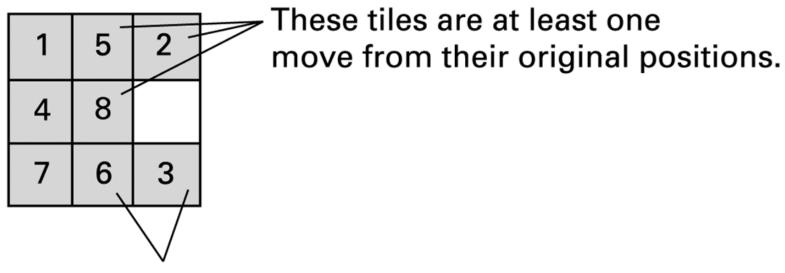


Heuristic Strategies

- Heuristic: A "rule of thumb" for making decisions
- Requirements for good heuristics
 - Must be easier to compute than a complete solution
 - Must provide a reasonable estimate of proximity to a goal



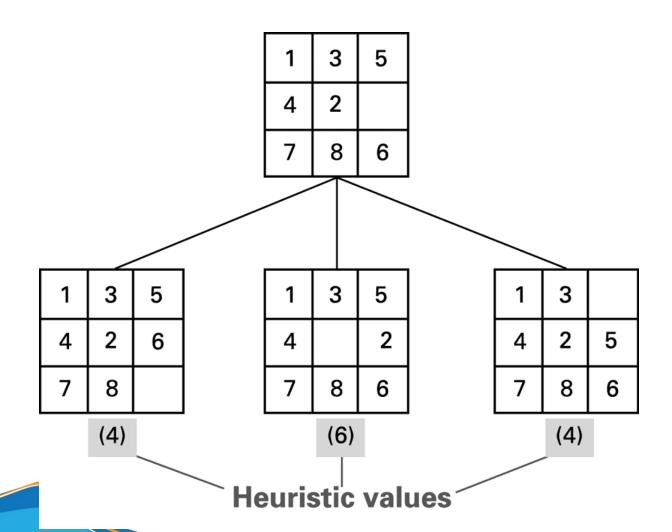
An unsolved eight-puzzle



These tiles are at least two moves from their original positions.

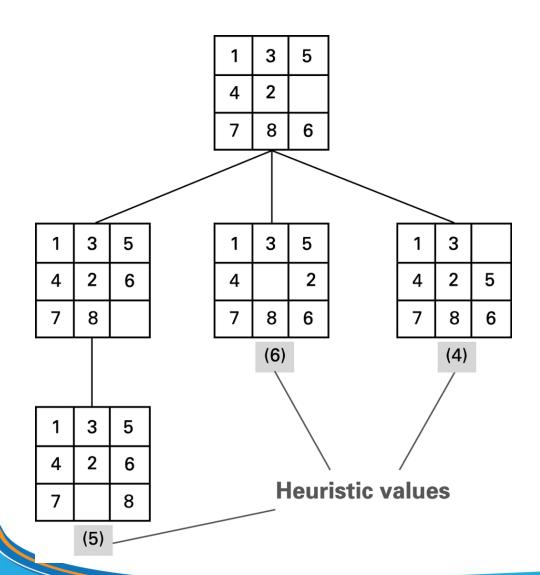


The beginnings of heuristic search



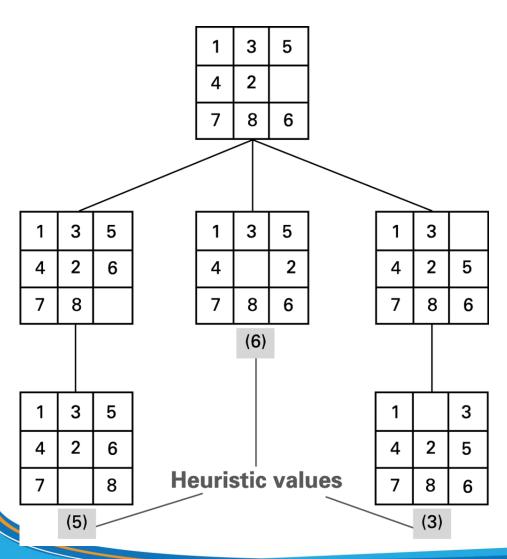


The search tree after two passes

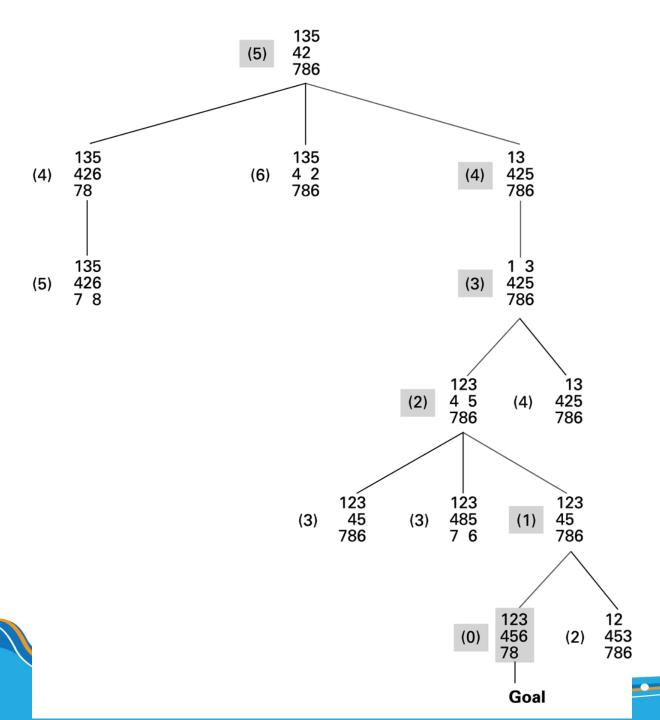




The search tree after three passes









Content

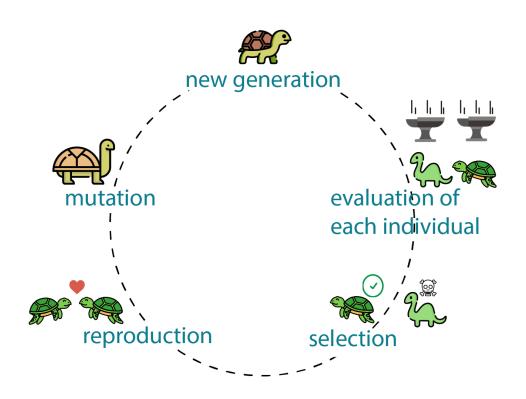
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- There are some problems that are too complex to be solved such as:
 - execution exceeds available memory or
 - cannot be completed within a reasonable amount of time.
- A solution can sometimes be discovered through an evolutionary process involving many generations of trial solutions.
 - This strategy is the foundation for what is called genetic algorithms.









- Begins by generating a random pool of trial solutions:
 - Each solution is a chromosome
 - Each component of a chromosome is a gene
- Repeatedly generate new pools
 - Each new chromosome is an offspring of two parents from the previous pool
 - Probabilistic preference used to select parents
 - Each offspring is a combination of the parent's genes



