

# Square Packing

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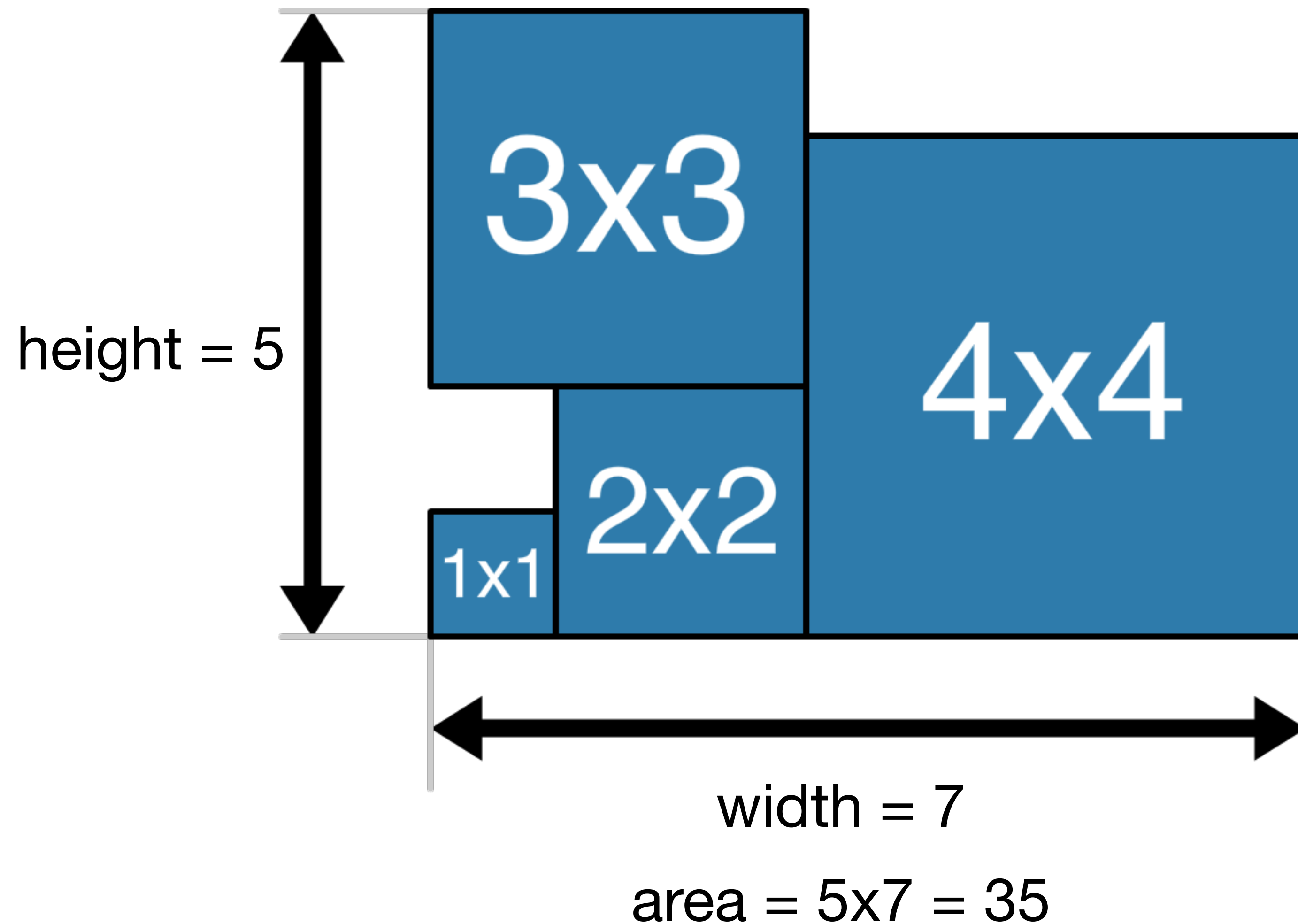


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# Multiple Square Packing

- Given
  - $k_1$  1 by 1 squares
  - $k_2$  2 by 2 squares
  - ...
  - $k_n$  n by n squares
- Pack the squares into a rectangle of the **smallest area**

# Square Packing Visualized



# Data and Variables

```

int: n; % number of square sizes
enum Sizes = Size(1..n);
array[Sizes] of int: ncopy;
int: maxl = sum(i in 1..n)(i*ncopy[Size(i)]);
int: mina = sum(i in 1..n)(i*i*ncopy[Size(i)]);

```

```

var n..maxl: height;
var n..maxl: width;
var mina .. n*maxl: area = height * width;

```

```

enum Squares = Square(1..sum(ncopy));
array[Squares] of var 0..maxl: x;
array[Squares] of var 0..maxl: y;

```

Note the **tight bounds** on the variables

# Determining Square Sizes

```
array[Squares] of int: size =  
    array1d(Squares,  
        [ i | i in 1..n, j in 1..ncopy[Size(i)]]  
    );
```

For example

```
ncopy = [3, 2, 5, 4, 3]  
size = [1, 1, 1, 2, 2, 3, 3, 3, 3, 3, 4, 4, 4, 4, 5, 5, 5]
```

# Square Packing Constraints

- Squares fit in the rectangle

```
constraint forall(s in Squares) (  
    x[s] + size[s] <= width /\  
    y[s] + size[s] <= height  
);
```

- Squares do not overlap

```
constraint forall(s1, s2 in Squares where s1 < s2) (  
    x[s1] + size[s1] <= x[s2] \/   
    x[s2] + size[s2] <= x[s1] \/   
    y[s1] + size[s1] <= y[s2] \/   
    y[s2] + size[s2] <= y[s1]  
);
```

- Objective

```
solve minimize area;
```

# Solving the Model

- A toy instance

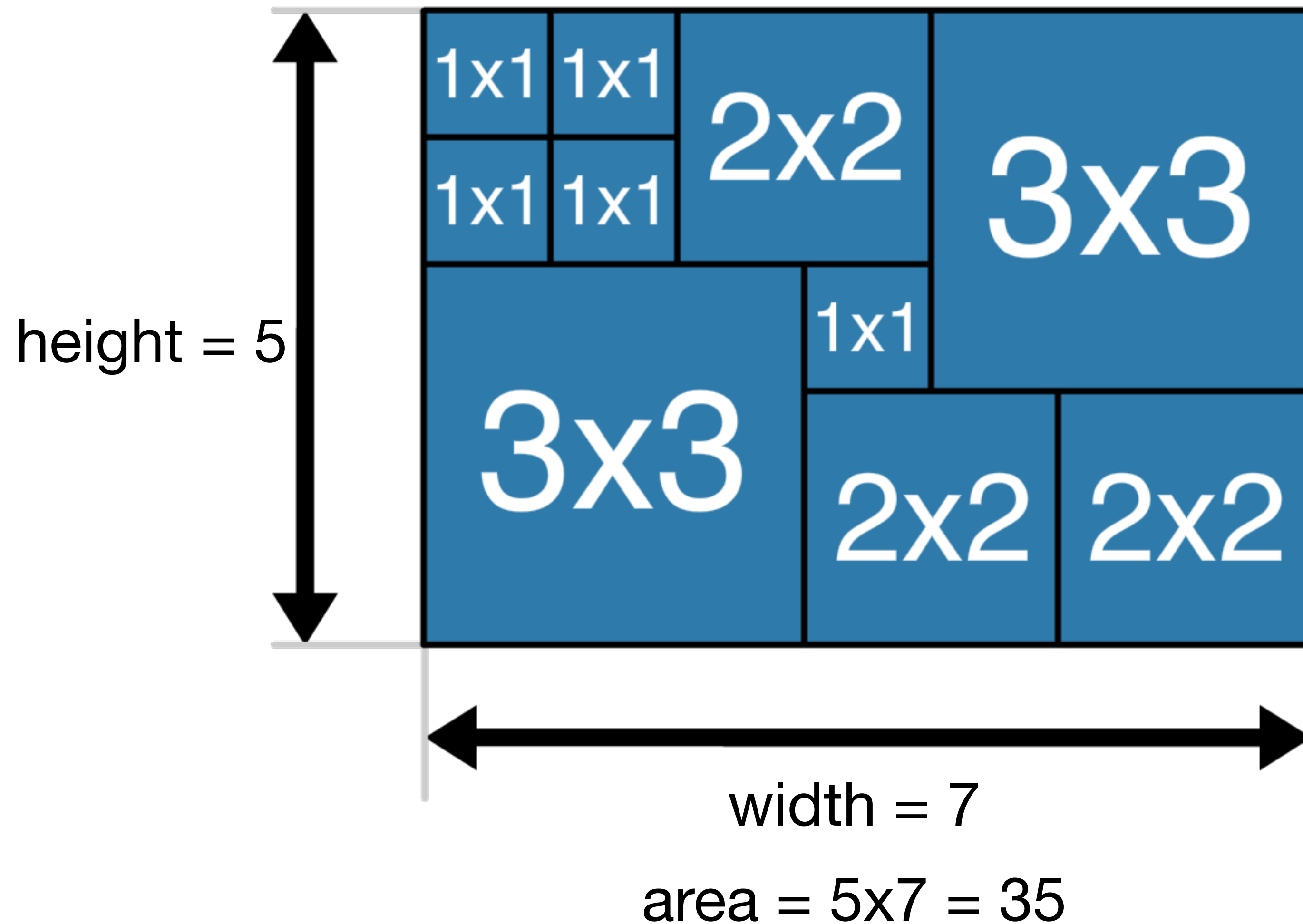
```
n = 3;  
ncopy = [5, 3, 2];
```

- Output

```
area = 35  
height = 5  
width = 7  
x = [0, 0, 0, 0, 0, 1, 3, 5, 1, 4]  
y = [0, 1, 2, 3, 4, 0, 0, 0, 2, 2]  
-----  
=====
```

Finished in 161 msec

# A Solution to the Toy Problem





# Solving the Model Again

- A bigger instance

```
n = 7;  
ncopy = [4, 3, 0, 5, 4, 3, 4];
```

- After 6s

```
area = 520
```

- After 1m

```
area = 507
```

- After 7m and up to 1h

```
area = 504
```

# Improving the Model

- Global constraints
- Redundant constraints
- Symmetry breaking

# The `diffn` Global Constraint

- The `diffn` global constraint captures exactly 2d non overlap (it should be called `diff2`)

```
diffn([x1, ..., xn], [y1, ..., yn],
      [dx1, ..., dxn], [dy1, ..., dyn])
```

ensure no two objects at positions  $(x_i, y_i)$  with dimensions  $(dx_i, dy_i)$  overlap

```
predicate diffn(array[int] of var int: x,
                array[int] of var int: y,
                array[int] of var int: dx,
                array[int] of var int: dy);
```

- Squares do not overlap

```
diffn(x, y, size, size);
```

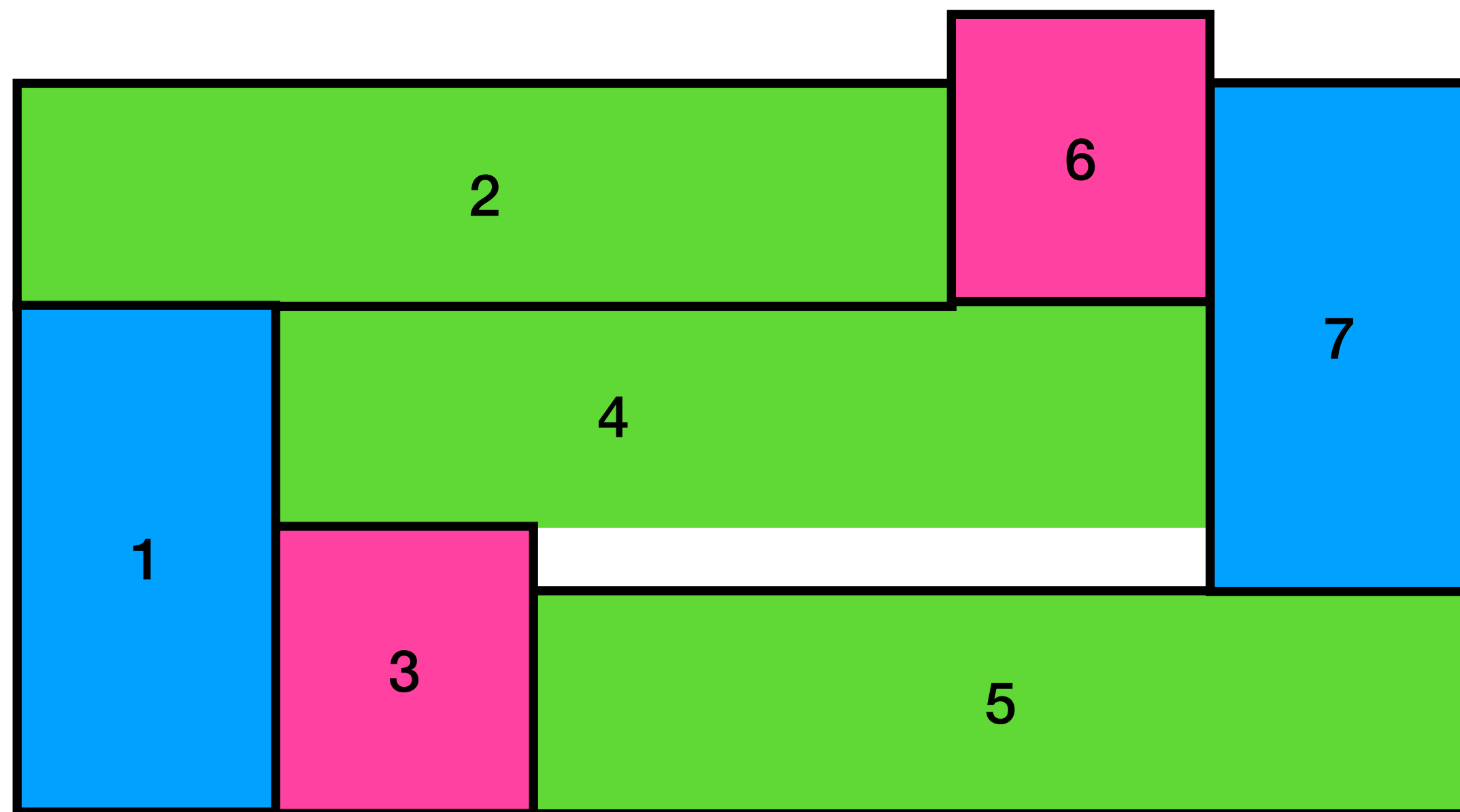
# Packing and Cumulative

- If there is a packing, then the cumulative constraint must hold!
- We can add **redundant** cumulative constraints to packing problems
  - improves propagation (and hence solving)
- Squares do not overlap in the x and y dimension respectively

```
cumulative(x, size, size, height);  
cumulative(y, size, size, width);
```

# Packing and Cumulative

- In general cumulative constraints **do not** enforce packing, even when the the x positions are fixed



# Symmetries!

- Squares of the **same size** are interchangeable, creating multiplicity of solution possibilities
- Impose an ordering on the placements of such squares
- What ordering can we use for coordinates ( $x$ ,  $y$ )?
- Strict lexicographical ordering

$$(x_1, y_1) >_{\text{lex}} (x_2, y_2)$$

- $x_1 > x_2$ ; or
- if  $x_1 = x_2$ , then  $y_1 > y_2$

# The `lex_greater` Global Constraint

- The `lex_greater` global constraint imposes the lexicographic ordering on two  $n$ -tuples (encoded as arrays)

`lex_greater([x1, ..., xn], [y1, ..., yn])`

ensures that  $(x_1, \dots, x_n) >_{\text{lex}} (y_1, \dots, y_n)$

```
predicate lex_greater(array [int] of var int: x,  
                      array [int] of var int: y)
```

# Ordering Squares

- The placement of a square is specified by the coordinates of its lower left hand corner
- Order squares of the same size

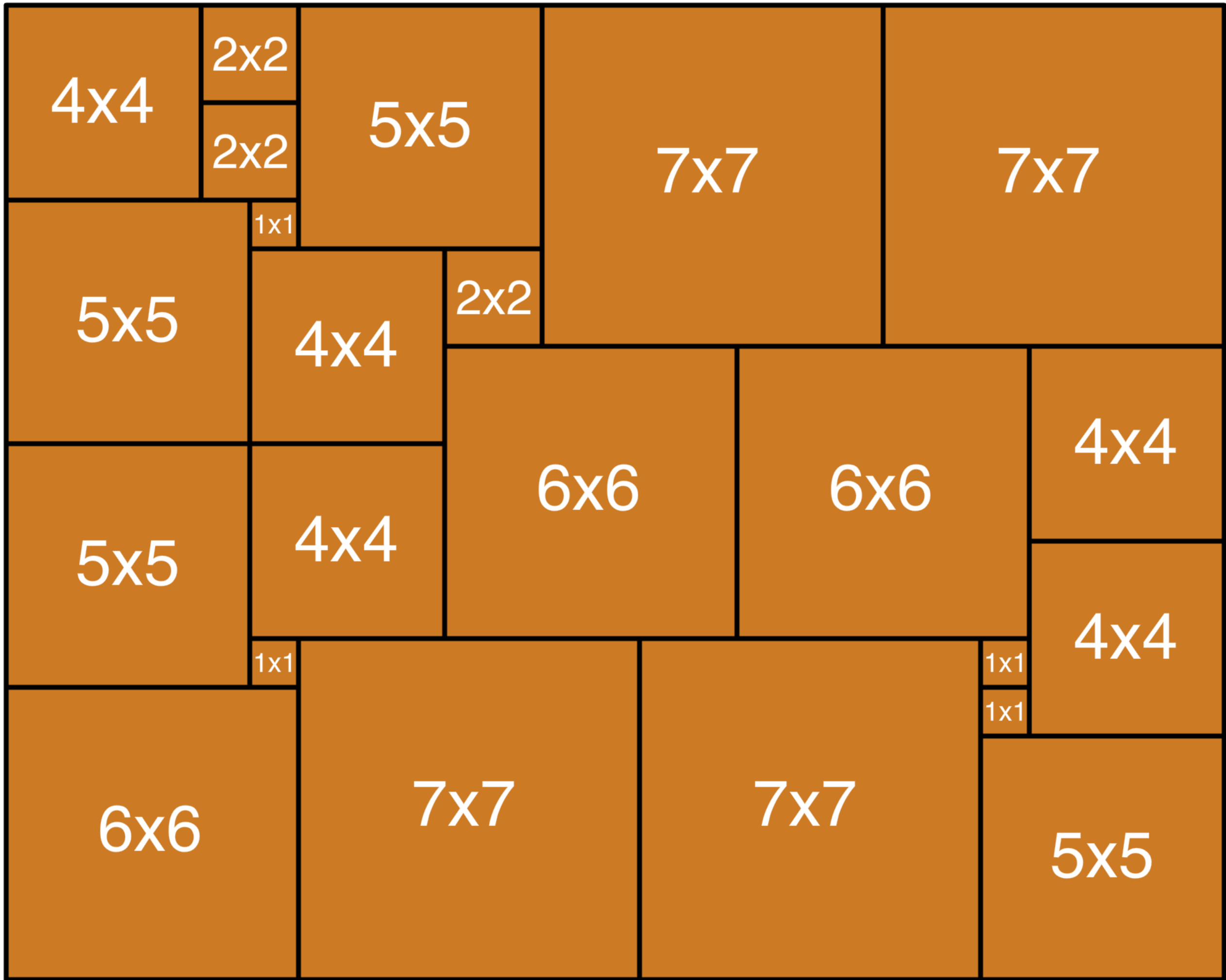
```
include "lex_greater.mzn";  
constraint  
forall(s in Squares diff {max(Squares)}  
      t = enum_next(s)) (  
  if size[s]=size[t] then  
    lex_greater(  
      [x[s], y[s]],  
      [x[t], y[t]]  
    )  
  endif  
);
```



# Solving the Model Again

```
area = 500
height = 20
width = 25
x = [20, 20, 5, 5, 9, 4, 4, 21, 21, 5, 5,
0, 20, 6, 0, 0, 15, 9, 0, 18, 13, 11, 6]
y = [14, 13, 13, 4, 5, 2, 0, 11, 7, 9, 5,
0, 15, 0, 9, 4, 7, 7, 14, 0, 13, 0, 13]
-----
=====
Finished in 42s 792msec
```

# Solving the Model Again



# Summary

- Packing problems
  - are another **common** uses of CP in the real world
  - come in lots of varieties
  - are complex discrete optimization problems
- `diffn` encodes 2D non-overlap
  - `disjunctive` encodes 1D non-overlap
- `cumulative` constraints are **redundant** for packing, but useful for improving solving

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