



Hackathon 2025

Data Files



barber-motorsports-park.zip



circuit-of-the-americas.zip



indianapolis.zip



road-america.zip



sebring.zip



sonoma.zip



virginia-international-raceway.zip

Track Maps



Barber Motorsports Park



Circuit of the Americas



Indianapolis

Additional Data Sources



Official Timing Results

- Series: SRO
- For 2025 season, find TGRNA GR CUP NORTH AMERICA
- For 2024 season, find Toyota GR Cup

Notes and known issues about telemetry and lap start/end/time files

meta_time: The time the message was received.

timestamp: The time on the electronic control unit (ECU) of the vehicle. The time on the ECU may not be accurate.

Vehicle identification: Example: For GR86-004-78, the chassis number is 004 and the car number is 78 (the sticker on the side of the car). If the car number is 000, it hasn't been assigned to the ECU yet. You can still uniquely identify a vehicle by its chassis number though. In a later race, you might see the car number updated.

lap: Sometimes the lap count is lost or erroneously reported (often as lap #32768). The time values should still be accurate, and the lap may be determined by it.

Vehicle Telemetry Parameters

Speed & Drivetrain



Sebring



Sonoma

Virginia International
Raceway

Sections/sectors on track maps correspond to "analysis with sections" files. Sections on the map are split up by red lines and the start/finish line. Each section is divided in two by the white line. S1.a, S1.b, S2.a, S2.b, S3.a, and S3.b respectively correspond to IM1a, IM1, IM2a, IM2, IM3a, and FL.

Gear

Current gear selection

nmot

Engine RPM

Throttle & Braking

ath

Throttle blade position (0% = fully closed, 100% = wide open)

aps

Accelerator pedal position (0% = no acceleration, 100% = fully pressed)

pbrake_f

Front brake pressure (bar)

pbrake_r

Rear brake pressure (bar)

Acceleration & Steering

accx_can

Forward/backward acceleration in G's (positive = accelerating, negative = braking)

accy_can

Lateral acceleration in G's (positive = left turn, negative = right turn)

Steering_Angle

Steering wheel angle in degrees (0 = straight, negative = counterclockwise, positive = clockwise)

Position & Lap Data

VBOX_Long_Minutes

GPS longitude (degrees)

VBOX_Lat_Min

GPS latitude (degrees)

Laptrigger_lapdist_dls

Distance from start/finish line (meters)

