

<p>This file contains all the parts you need to build PAROL6 robot!</p> <p>Most items have links where you can buy the item, and some of them are affiliate links.</p> <p>Items like screws, belts and bearings can be bought locally or from many other vendors.</p>				

	<b>Screws and nuts:</b>			
	diameter , length	quantity	<b>Description</b>	<a href="#">Link</a>
	M4x10mm	20	DIN 912 / ISO 4762 (hexagon socket head cap)	
	M3x8mm	10	2 mm head height	
	M3x8mm	50	DIN 912 / ISO 4762 (hexagon socket head cap)	
	M3x14mm	30	DIN 912 / ISO 4762 (hexagon socket head cap)	
	M3 nut	10	DIN 912 / ISO 4762 (hexagon socket head cap)	
	M3x25mm	10	DIN 912 / ISO 4762 (hexagon socket head cap)	
	M2x10mm	10	DIN 912 / ISO 4762 (hexagon socket head cap)	
	M3x16mm	10	DIN 912 / ISO 4762 (hexagon socket head cap)	
	M3x6mm	10	Pan head philips	
	M3x12mm	30	DIN 912 / ISO 4762 (hexagon socket head cap)	
	M3x35mm	10	DIN 912 / ISO 4762 (hexagon socket head cap)	
	M4x16mm	30	DIN 912 / ISO 4762 (hexagon socket head cap)	
	M4x14mm	10	DIN 912 / ISO 4762 (hexagon socket head cap)	
	M4x50mm	10	DIN 912 / ISO 4762 (hexagon socket head cap)	
	M3x15mm	2	Tapered screw head	
	<b>Gearboxes:</b>			
<b>Name in building instructions</b>	<b>Type</b>	<b>quantity</b>	<b>Description</b>	<a href="#">Link</a>
For cheaper gearbox options you can use MG series planetary gearboxes. They have bigger backlash but are cheaper. <a href="#">Link</a> <a href="#">Aliexpress Link</a>				
Gearbox 20:1	Nema 17 20:1 EG precision planetary	2	<a href="#">Link</a>	<a href="#">Aliexpress Link</a>
Gearbox 10:1	Nema 17 10:1 EG precision planetary	1	<a href="#">Link</a>	<a href="#">Aliexpress Link</a>
	<b>Motors:</b>			
<b>Name in building instructions</b>	<b>Type</b>	<b>quantity</b>	<b>Description</b>	<a href="#">Link</a>
Stepper 1	Nema 17 16Nm,42x42x20mm	1	<a href="#">Link</a>	<a href="#">Aliexpress Link</a>
Stepper 2	Nema 17 45Nm,42x42x40mm	3	<a href="#">Link</a>	<a href="#">Aliexpress Link</a>
Stepper 3	Nema 17 65Nm,42x42x60mm	2	<a href="#">Link</a>	<a href="#">Aliexpress Link</a>
	<b>Belts:</b>			
<b>Name in building instructions</b>	<b>Type</b>	<b>quantity</b>	<b>Description</b>	<a href="#">Link</a>
Joint 1 belt	HTD3 396	1	6 mm width	<a href="#">Link</a>
Joint 3 belt	HTD3 342	1	6 mm width	<a href="#">Link</a>
Joint 4 belt	HTD3 201	1	6 mm width	<a href="#">Link</a>
Joint 5 belt	HTD3 246	1	6 mm width	<a href="#">Link</a>
	<b>Pulleys:</b>			
<b>Name in building instructions</b>	<b>Type</b>	<b>quantity</b>	<b>Description</b>	<a href="#">Link</a>
J4 pulley, J5 pulley	HTD3M 12 tooth 5mm bore 10mm width	2	<a href="#">Link</a>	
J1 pulley	HTD3M 15 tooth 5mm bore 10mm width	1	<a href="#">Link</a>	
	<b>Mechanical stuff:</b>			
<b>Name in building instructions</b>	<b>Type</b>	<b>quantity</b>	<b>Description</b>	<a href="#">Link</a>
Shaft coupler	Shaft coupler	3	8 mm hole shaft, M4 screw holes	<a href="#">Link</a>
	<b>Bearings:</b>			
<b>Name in building instructions</b>	<b>Type</b>	<b>quantity</b>	<b>Description</b>	<a href="#">Link</a>
Bearing 1	AKX3552	1	35X52X4, needs to have top and bottom plate	<a href="#">Link</a>
Bearing 2	NSK HR32906J	5	Joint 5, 4 and 3	<a href="#">Link</a>
Bearing 3	NSK HR32907J	4	Joint 1 and 2	<a href="#">Link</a>
Tension bearing	Ball bearing 3x8x4	20	Used for belt tension	<a href="#">Link</a>
Tension bearing	Ball bearing 3x10x4	20	Used for belt tension	<a href="#">Link</a>
	<b>Electronics:</b>			
<b>Name in building instructions</b>	<b>Type</b>	<b>quantity</b>	<b>Description</b>	<a href="#">Link</a>
PAROL control board	1	<a href="#">source-robotics.com</a>	<a href="#">Link</a>	
TMC5160	6	<b>Drivers from the links are tested. Use any other at own risk:</b> <a href="#">Link1</a> <a href="#">Link2</a>	<a href="#">Link</a>	
Thermal paste	2	Needed only if your control board has no drivers!	<a href="#">Link</a>	
On/Off button	1	12mm 3-6V	<a href="#">Link</a>	
JST PH 2.0mm 200mm 4PIN	1	For power button	<a href="#">Link</a>	
Noctua NF-A4x20 5V 40mm	1			
Power connector - male + female	1	GX16 2PIN	<a href="#">Link</a>	
Gripper connector (electric)	1	M8 sensor Female 4 pin	<a href="#">Link</a>	
Power supply	1	Any 24V 5A supply	<a href="#">Link</a>	
Limit switches	3	Type ZW12-3	<a href="#">Link</a>	
Inductive sensor 1	1	4mm NPN NO - <a href="#">alternative link</a>	<a href="#">Link</a>	
Inductive sensor 2	1	GX-F8A	<a href="#">Link</a>	
Inductive sensor 3	1	M5_ NPN NO - <a href="#">alternative link</a>	<a href="#">Link</a>	
Estop	1	Any NC estop	<a href="#">Link</a>	
Cable gland for estop	1	PG7 type	<a href="#">Link</a>	
M3 brass insert	4	M3, 6mm length	<a href="#">Link</a>	
Pneumatic connector - robot	4	4 mm type PM	<a href="#">Link</a>	
Pneumatic Gripper	1	MHZ2-16D	<a href="#">Link</a>	
Pneumatic gripper connector	2	PC4 - M5	<a href="#">Link</a>	
Pneumatic tube	5 meters	1 meter, 4x2.5mm	<a href="#">Link</a>	
xt30 connector female	1	used to deliver power to PAROL6 PCB	<a href="#">Link</a>	
Stlink	1	Use link! Pin order needs to be: SWCLK,SWDIO,GND,3V3,5V	<a href="#">Link</a>	
USB B cable	1	Comms to the PC		
5/2 solenoid air valve	1	4mm tube connectors, 5/2, 24V	<a href="#">Link</a>	
	<b>Vacuum gripper</b>			
<b>Name in building instructions</b>	<b>Type</b>	<b>quantity</b>	<b>Description</b>	<a href="#">Link</a>
Suction cup gripper	1		<a href="#">Link</a>	
Vacuum generator	1		<a href="#">Link</a>	
4mm to 6mm coupler	1		<a href="#">Link</a>	