view frames Result Recorded at time: 1724943424.1815393 world Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1000\overline{0}.0$ Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 base link base link m Broadcaster: /robot state publisher Broadcaster: /base_link_m_to_oak_rgb_camera_optical_frame_tf Broadcaster: /d405/base link m to d405 link tf Broadcaster: /robot state publisher Average rate: $10.0\overline{92}$ Average rate: 99.482 Average rate: 99.503 Average rate: $10.0\overline{87}$ Buffer length: 4.856 Buffer length: 4.986 Buffer length: 4.985 Buffer length: 4.858 Most recent transform: 1724943424.166 Most recent transform: 1724943424.081 Most recent transform: 1724943424.165 Most recent transform: 1724943424.088 Oldest transform: 1724943419.18 Oldest transform: 1724943419.23 Oldest transform: 1724943419.226 Oldest transform: 1724943419.181 link 1 link_1_m d405 link oak rgb camera optical frame Broadcaster: /d405/camera/realsense2 camera manager Broadcaster: /d405/camera/realsense2 camera manager Broadcaster: /robot state publisher Broadcaster: /d405/camera/realsense2 camera manager Broadcaster: /robot state publisher Average rate: $10.0\overline{9}2$ Average rate: 10000.0 Average rate: 10000.0 Average rate: 10000.0 Average rate: 10.087Buffer length: 0.0 Buffer length: 4.856 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 4.858 Most recent transform: 0.0 Most recent transform: 1724943424.081 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 1724943424.088 Oldest transform: 0.0 Oldest transform: 1724943419.226 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 1724943419.23 link 2 link 2 m d405 depth frame d405 color frame d405 aligned depth to color frame Broadcaster: /robot state publisher Broadcaster: /d405/camera/realsense2 camera manager Broadcaster: /d405/camera/realsense2 camera manager Broadcaster: /robot state publisher Average rate: $10.0\overline{92}$ Average rate: 10000.0 Average rate: 10000.0 Average rate: $10.0\overline{87}$ Buffer length: 0.0 Buffer length: 4.856 Buffer length: 0.0 Buffer length: 4.858 Most recent transform: 1724943424.081 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 1724943424.088 Oldest transform: 1724943419.226 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 1724943419.23 link 3 d405_depth_optical_frame link 3 m d405 color optical frame Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $10.0\overline{92}$ Average rate: $10.0\overline{87}$ Buffer length: 4.856 Buffer length: 4.858 Most recent transform: 1724943424.081 Most recent transform: 1724943424.088 Oldest transform: 1724943419.226 Oldest transform: 1724943419.23 link_4_m link_4 Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $10.0\overline{92}$ Average rate: $10.0\overline{87}$ Buffer length: 4.858 Buffer length: 4.856 Most recent transform: 1724943424.081 Most recent transform: 1724943424.088 Oldest transform: 1724943419.226 Oldest transform: 1724943419.23 link 5 link_5_m Broadcaster: /robot state_publisher Broadcaster: /robot state publisher Average rate: $10.0\overline{92}$ Average rate: $10.0\overline{87}$ Buffer length: 4.856 Buffer length: 4.858 Most recent transform: 1724943424.081 Most recent transform: 1724943424.088 Oldest transform: 1724943419.226 Oldest transform: 1724943419.23 link 6 link 6 m Broadcaster: /robot state publisher Broadcaster: /d435/link 6 to d435 link tf Broadcaster: /robot state publisher Average rate: $1000\overline{0}.0$ Average rate: $9\overline{9}.4\overline{9}9$ Average rate: $1000\overline{0}.0$ Buffer length: 4.985 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 1724943424.165 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 1724943419.18 Oldest transform: 0.0 Oldest transform: 0.0 d435 link gripper_m camera mount Broadcaster: /d435/camera/realsense2 camera manager Broadcaster: /robot state publisher Broadcaster: /d435/camera/realsense2 camera manager Broadcaster: /d435/camera/realsense2 camera manager Broadcaster: /robot state publisher Average rate: 10000.0 Average rate: 10000.0 Average rate: 10000.0 Average rate: 10000.0 Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 d435 depth frame d435 color frame d435 aligned depth to color frame gripper base m camera Broadcaster: /d435/camera/realsense2 camera manager Broadcaster: /d435/camera/realsense2 camera manager Broadcaster: /robot state publisher Average rate: 10000.0 Average rate: 10000.0 Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 d435 depth_optical_frame d435 color optical frame gripper_tcp_m