```
┌─────────────────────────────────────────┐
│          view_frames Result             │
│                                         │
│  Recorded at time: 1691680085.0401576   │
└─────────────────────────────────────────┘
```

world

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

base_link

base_link_m

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 1691680084.986
Oldest transform: 1691680080.086

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 1691680084.986
Oldest transform: 1691680080.086

link_1

link_1_m

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 1691680084.986
Oldest transform: 1691680080.086

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 1691680084.986
Oldest transform: 1691680080.086

link_2

link_2_m

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 1691680084.986
Oldest transform: 1691680080.086

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 1691680084.986
Oldest transform: 1691680080.086

link_3

link_3_m

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 1691680084.986
Oldest transform: 1691680080.086

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 1691680084.986
Oldest transform: 1691680080.086

link_4

link_4_m

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 1691680084.986
Oldest transform: 1691680080.086

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 1691680084.986
Oldest transform: 1691680080.086

link_5

link_5_m

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 1691680084.986
Oldest transform: 1691680080.086

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 1691680084.986
Oldest transform: 1691680080.086

link_6

link_6_m

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

gripper_m