world Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1000\overline{0.0}$ Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 base link base link m Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10.204 Average rate: 10.204 Buffer length: 4.9 Buffer length: 4.9 Most recent transform: 1719087576.004 Most recent transform: 1719087576.004 Oldest transform: 1719087571.104 Oldest transform: 1719087571.104 link 1 link 1 m Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10.204 Average rate: 10.204 Buffer length: 4.9 Buffer length: 4.9 Most recent transform: 1719087576.004 Most recent transform: 1719087576.004 Oldest transform: 1719087571.104 Oldest transform: 1719087571.104 link 2 link 2 m Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $10.2\overline{04}$ Average rate: $10.2\overline{04}$ Buffer length: 4.9 Buffer length: 4.9 Most recent transform: 1719087576.004 Most recent transform: 1719087576.004 Oldest transform: 1719087571.104 Oldest transform: 1719087571.104 $link_3$ $link_3_m$ Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $10.\overline{204}$ Average rate: $10.2\overline{04}$ Buffer length: 4.9 Buffer length: 4.9 Most recent transform: 1719087576.004 Most recent transform: 1719087576.004 Oldest transform: 1719087571.104 Oldest transform: 1719087571.104 link_4_m $link_4$ Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $10.2\overline{04}$ Average rate: $10.2\overline{04}$ Buffer length: 4.9 Buffer length: 4.9 Most recent transform: 1719087576.004 Most recent transform: 1719087576.004 Oldest transform: 1719087571.104 Oldest transform: 1719087571.104 link 5 link 5 m Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $10.2\overline{04}$ Average rate: $10.2\overline{04}$ Buffer length: 4.9 Buffer length: 4.9 Most recent transform: 1719087576.004 Most recent transform: 1719087576.004 Oldest transform: 1719087571.104 Oldest transform: 1719087571.104 link 6 link 6 m Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1000\overline{0}.0$ Average rate: $1000\overline{0}.0$ Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 camera camera mount gripper m Broadcaster: /robot state publisher Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 gripper_base_m Broadcaster: /robot state publisher Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 gripper tcp m

view frames Result

Recorded at time: 1719087576.0343046