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mopa (MOdelling with Pseudo Absences): A framework for species distribution modelling with improved pseudo-absence generation

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1 Introduction

This is a tutorial containing a full worked example of species distribution modelling using the RSEP method and the three-step methods (TS and TSKM methods) for pseudo-absence generation presented in Iturbide et al., 2015, combining environmental profiling and spatial extent restriction of the background (see Fig. 2 in the cited article). We illustrate the steps followed to produce some of the analyses presented in the article using the R package mopa (MOdelling Pseudo Absences).

NOTE: Most functions presented are implemented in mopa. In the few cases in which functions from other packages are used, the package name is always explicitly indicated.

1.1 Installing the mopa package

The mopa package is available on GitHub. The stable release for the package is on the master branch.

We recommend the devtools package to download and install mopa directly from the stable branch of the repository:

Once installed, we load the package:

> library(mopa)

2 Modelling steps

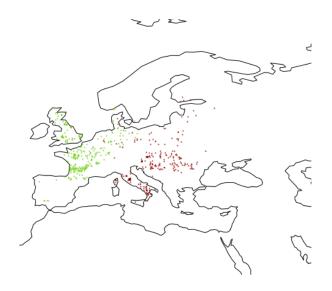
2.1 Data pre-processing

In Iturbide et al., 2015, we indicate the adequacy of using different ecotypes for modelling species distributions. Thus, functions in the mopa package are

intended to deal with more than one group of presences simultaneously. In this example, we use a list of 2 different Oak haplotypes (H11 and H5, see Table 1 in the manuscript), but the same steps may be followed in a joint analysis of multiple species. Of course, the most typical case (i.e., dealing with with a single group of species) can be also easily accomplished by providing a data.frame.

The data set of species in this example is Oak_phylo2 and is provided with the mopa package. This is a modified subset of the Quercus sp Europe Petit 2002 database (Petit et al., 2002b), which is available in the Georeferenced Database of Genetic Diversity or (GD)². To aid in map representation, a dataset called wrld containing a World map is also included in the package.

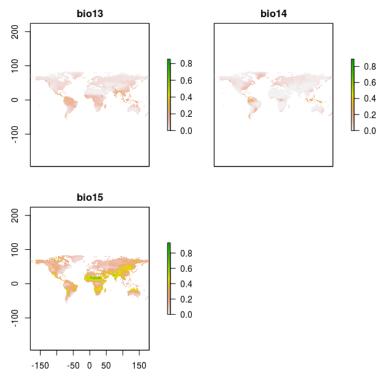
```
> # Load map and Oak data
> data(wrld)
> data(Oak_phylo2)
> # Map
> plot(wrld, asp = 1, xlim= c(-10,50), ylim=c(40,60))
> for (i in 1:length(Oak_phylo2)) {
+ points(Oak_phylo2[[i]], pch = "*",
+ cex = 0.5, col = colors()[i*50])
+ }
```



Predictor variables are typically stored in raster files. The different raster layers can be efficiently handled in R using the utilities of the raster package. mopa uses as input this type of raster objects. In particular, multiple layers can be arranged in a collection of RasterLayers objects called a RasterStack (see ?raster::raster for more information on raster objects).

> # RatserStack of environmental variables

- > data(biostack)
- > plot(biostack)



The regularly distributed grid points covering the continental area can be created with functions from the raster and sp packages as follows:

```
> # Extract raster values at grid coordinates
> ac <- xyFromCell(biostack[[1]], 1:ncell(biostack[[1]]))
> ex <- extract(biostack[[1]], ac)
> # Convert to a Spatial object and define projection
> sp_grid <- SpatialPoints(ac[-which(is.na(ex)), ])
> projection(sp_grid) <- CRS("+proj=longlat +init=epsg:4326")</pre>
```

For ease of use, the previous steps can be skipped, as the sp_grid object is already included in the mopa package, covering the whole world at 10 km resolution.

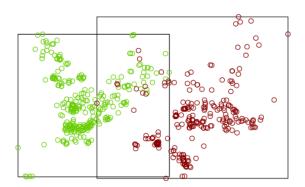
> data(sp_grid)

Function boundingCoords creates a matrix of bounding coordinates around the known presence localities of the target species. In this case, since the <code>Oak_phylo2</code> list contains two groups of points (one for each haplotype considered), a list of two matrices is created.

> oak.extension <- boundingCoords(xy = Oak_phylo2)</pre>

Function delimit creates a rectangular polygon shape from the bounding coordinates and does the intersection of the background points. A list with

two objects is obtained: (1) bbs: polygon shape of the bounding boxes and (2) bbs.grid: a list of data frames of the background point grid limited by the bounding coordinates.

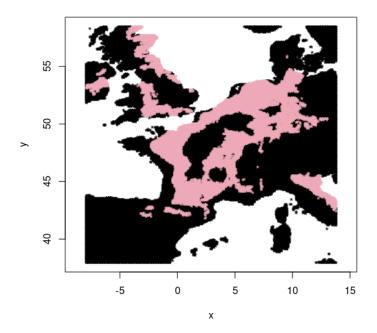


2.2 Three-step pseudo-absences generation

In this section we illustrate the steps followed to generate pseudo-absences following the RSEP, TS and TSKM procedures described in the manuscript.

2.2.1 STEP1: environmental profiling

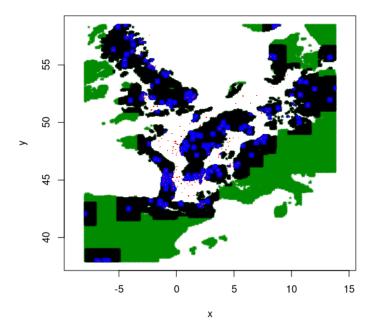
The first step is the selection of the environmentally unsuitable areas using a presence-only algorithm. In mopa this is done using a support vector machine-based algorithm that performs a preliminary binary classification of the study region (suitable/unsuitable) using as input the environmental conditions of the presence localities. This is done by function <code>OCSVMprofiling</code> which runs the one-class support vector machine algorithm (OCSVM) for each Oak group of the example:



If the RSEP method (as described in Iturbide et al., 2015) is selected for pseudo-absence data generation, only the first step is needed, thus, at this point we can create random pseudo-absences in the unsuitable background and perform SDM. The same functions as in the TS and TSKM methods might be used for this purpose, these are PseudoAbsences and allModeling, which are detailed in the section below (STEP2).

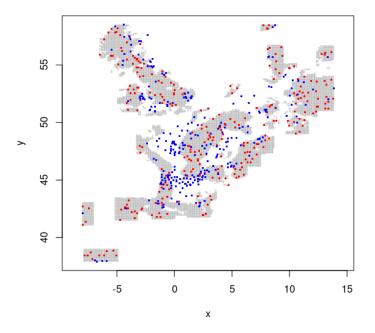
2.2.2 STEP 2: SDM performing with pseudo-absences generated into different extents of the unsuitable background

In the second step, SDMs are performed with pseudo-absences generated into different extents of the unsuitable background. Several functions are involved in this step. Function bgRadio performs the partition of the background space considering multiple distance thresholds. In other words, it creates backgrounds of different spatial extent for each species/population. In the example below, extents are created for a sequence of 10 km between distances, from 20 km to half the length of the diagonal of the bounding box, as described in Sec. 2.4 of the manuscript. A list of matrices containing xy coordinates is returned, each matrix corresponding to a different background extent tested.

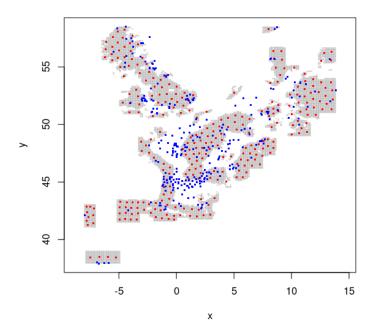


Function PseudoAbsences creates pseudo-absences either at random (TS method) or using the k-means clustering approach (TSKM method) for all the background extents considered. Prevalence (proportion of presences against pseudo-absences) and the exclusion buffer (minimum distance to be kept to presences without pseudo-absences) can also be set in this function using the arguments prevalence and exclusion.buffer.

At random (TS method). In the example below, pseudo-absences are generated at random, in equal number to presences (prevalence) and keeping a 10 km distance to presences (exclusion buffer).



With k-means clustering (TSKM method.) In the example below, pseudo-absences are generated with k-means clustering, in equal number to presences (prevalence) and keeping a 10 km distance to presences (exclusion buffer).



Function bindPresAbs binds presence and absence data for each background extension.

```
> presausTS <- bindPresAbs(presences = Oak_phylo2,
+ absences = pa_random)</pre>
```

The allModeling function performs the species distribution modelling and the k-fold cross-validation for a set of presence/absence data per species, corresponding to different background extents. Algorithms supported are "glm", "svm", "maxent", "mars", "randomForest", "cart.rpart" and "cart.tree". In the example below, we perform a 10-fold cross validation using the "mars" modelling algorithm.

Named .Rdata objects are stored in the specified directory in destdir. Each file is automatically named, indicating the algorithm, background extent, and species/population in this order (if a single species is provided, no name is given for the species). For instance, the file $mars_bgkm20_hgH11.Rdata$ stores the R object (a list) containing the SDM results for the MARS algorithm, considering a 20 km background extent and the Oak group H11. In particular, the output list contains the following components:

(1) allmod: fitted model with all data for training, (2) auc: AUC statistic in the cross validation, (3) kappa: kappa statistic in the cross validation, (4) tss: true skill statistic in the cross validation, (5) mod: fitted model with partitioned data, (6) p: cross model prediction.

2.2.3 STEP3: selection of the optimum background extent and corresponding fitted model

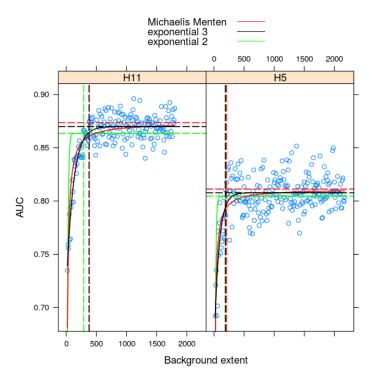
In the third step, AUCs obtained and corresponding extents are fitted to a Michaelis-Menten model to extract the Vm coefficient (equation 1 in the manuscript). Then, the minimum extent at which the AUC surpasses the Vm value is selected as the threshold extent (see Figure 3 in the manuscript), being the corresponding fitted SDM the definitive to predict suitability probabilities in the study area.

We next indicate how to plot the results of the optimal spatial extent selection using the lattice package. First we load the data generated with the allModeling function and extract the corresponding AUC values. Function loadTestValues loads and stores AUC data in a matrix:

Model fitting is done by function indextent, that internally uses the nls function of R package stats. An index of the threshold extents is obtained. A fitted model plot (as in Fig. 3 in Iturbide et al., 2015) is also returned if argument diagrams is set to TRUE.

```
> ind <- indextent(testmat = auc_mars, diagrams = TRUE)
> ind

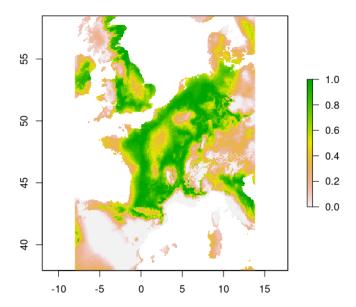
km380 km190
37 18
```



The ind object in the example above gives the index to extract the best model components and associated data, by means of function loadDefinitive-Model.

```
> def <-loadDefinitiveModel(data = presausTS,
+ extents = ind, slot = "allmod", algorithm = "mars")</pre>
```

Once the optimal SDMs are chosen, we can generate the resulting suitability maps. In the example below we use function biomat for preparing a matrix with the variables for prediction in the study area. Then, the predictions are converted to a raster format with functions SpatialPixelsDataFrame (from the sp package) and raster (from the raster package).



We can combine functions in mopa to apply alternative methods of pseudoabsence data generation. Functions performing each step in RSEP, TS and TSKM are indicated in the conceptual diagram of the manuscript (Fig. 2). Functions involved in the TS and TSKM methods are:

```
boundingCoords + delimit + OCSVMprofiling + bgRadio +
pseudoAbsences + bindPresAbs + allModeling + loadTestValues +
indextent + loadDefinitiveModel,
```

while the RSEP method only applies the first step of the Three-step methods, being the involved functions:

```
boundingCoords + delimit + OCSVMprofiling +
pseudoAbsences + allModeling.
```

If we want to establish a threshold distance of the background but are not interested in doing an environmental profiling of the background in the previous step, we can combine functions this way:

```
boundingCoords + delimit + bgRadio + pseudoAbsences +
bindPresAbs + allModeling + loadTestValues + indextent +
loadDefinitiveModel.
```

```
> print(sessionInfo())
```

```
R version 3.2.0 (2015-04-16)
Platform: x86_64-pc-linux-gnu (64-bit)
```

Running under: Ubuntu 14.04.2 LTS

locale:

[1]	LC_CTYPE=en	IIS IITF-8	T.C	NUMERIC=C
LTJ	PO_OIIIP_6II	_00.011 0		INDITITION OF

[3] LC_TIME=es_ES.UTF-8 LC_COLLATE=en_US.UTF-8
[5] LC_MONETARY=es_ES.UTF-8 LC_MESSAGES=en_US.UTF-8

[7] LC_PAPER=es_ES.UTF-8 LC_NAME=C
[9] LC_ADDRESS=C LC_TELEPHONE=C

[11] LC_MEASUREMENT=es_ES.UTF-8 LC_IDENTIFICATION=C

attached base packages:

[1] stats graphics grDevices utils datasets methods base

other attached packages:

[1] lattice_0.20-31 mopa_0.2.0 raster_2.3-40 sp_1.1-0

loaded via a namespace (and not attached):

[1]	tensor_1.5	MASS_7.3-39	spatstat_1.42-0
[4]	PresenceAbsence_1.1.9	plotmo_3.1.1	tools_3.2.0
[7]	rgdal_0.9-3	grid_3.2.0	lpSolve_5.6.11
[10]	spam_1.0-1	nlme_3.1-120	mgcv_1.8-6
[13]	sampling_2.6	dismo_1.0-12	plotrix_3.5-12
[16]	e1071_1.6-4	deldir_0.1-9	class_7.3-12
[19]	abind_1.4-3	goftest_1.0-2	<pre>randomForest_4.6-10</pre>
[22]	Matrix_1.2-0	splancs_2.01-37	rpart_4.1-9
[25]	polyclip_1.3-2	earth_4.4.0	TeachingDemos_2.9
โลดา	tree 1 0-35		

[28] tree_1.0-35

3 References

Iturbide, M., Bedia, J., Herrera, S., del Hierro, O., Pinto, M., Gutiérrez, J.M., 2015. A framework for species distribution modelling with improved pseudo-absence generation. Ecological Modelling DOI:10.1016/j.ecolmodel.2015.05.018.

Petit, R. J., Csaikl, U. M., Bordács, S., Burg, K., Coart, E., Cottrell, J., van Dam, B., Deans, J. D., Dumolin Lapégue, S., Fineschi, S., Finkeldey, R., Gillies, A., Glaz, I., Goicoechea, P. G., Jensen, J. S., Konig, A. O., Lowe, A. J., Madsen, S. F., Mátyás, G., Munro, R. C., Olalde, M., Pemonge, M.H., Popescu, F., Slade, D., Tabbener, H., Taurchini, D., de Vries, S. G. M., Ziegenhagen, B., Kremer, A., 2002b. Chloroplast DNA variation in european white oaks: Phylogeography and patterns of diversity based on data from over 2600 populations. Forest Ecology and Management 156 (1-3), 5-26.