



A SHORT INTRODUCTION TO MATLAB

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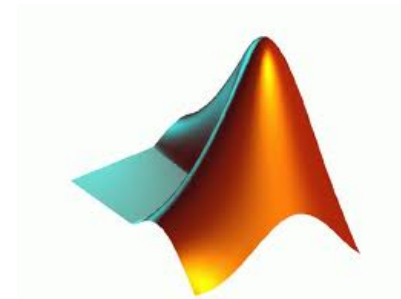
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CHAPTER I

Introduction

- MatLab is an acronym for matrix laboratory and is owned by MathWorks.
- It was conceptualized in University of New Mexico and Stanford University before being commercialized via MathWorks in 1984.
- The latest version is MatLab R2012b.
- MatLab is a programming software to
 - aid visualization of mathematical functions
 - aid algorithmic development
 - compute complex functions
 - and many more



- A typical algorithm development cycle involves the following

Setting the goal (aim)



Problem formulation



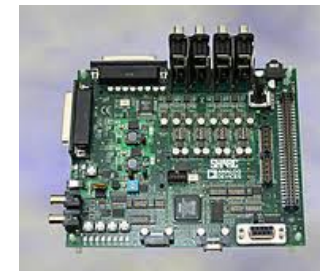
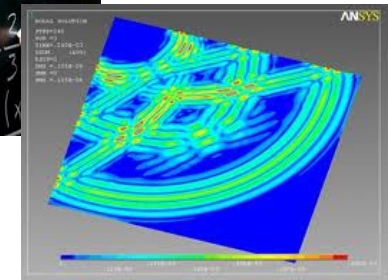
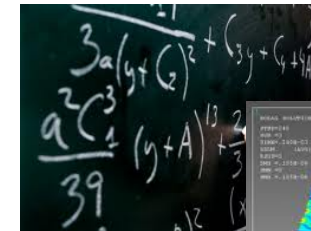
**Real-time
implementation**



- Acoustic source localization
- Face detection
- Fingerprint authentication
- Footstep detection

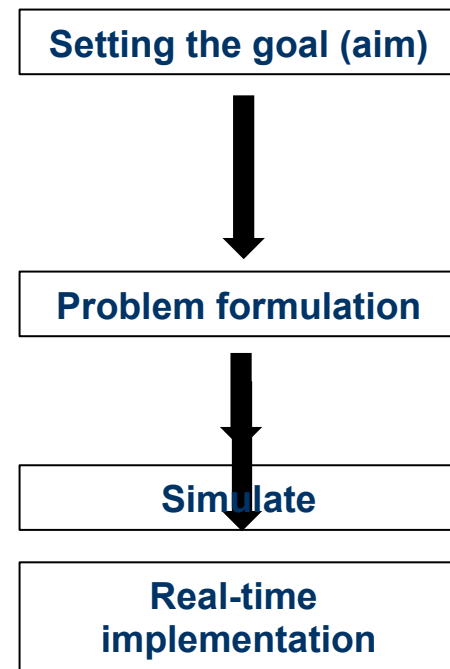
- Signal processing tools
- Mathematical formulation
- Wave propagation
- Contrast detection

- PC-based (C/C++)
- DSP implementation (TI, Analog Devices)
- Android based (Arduino)
- Field programmable gate array (FPGA)

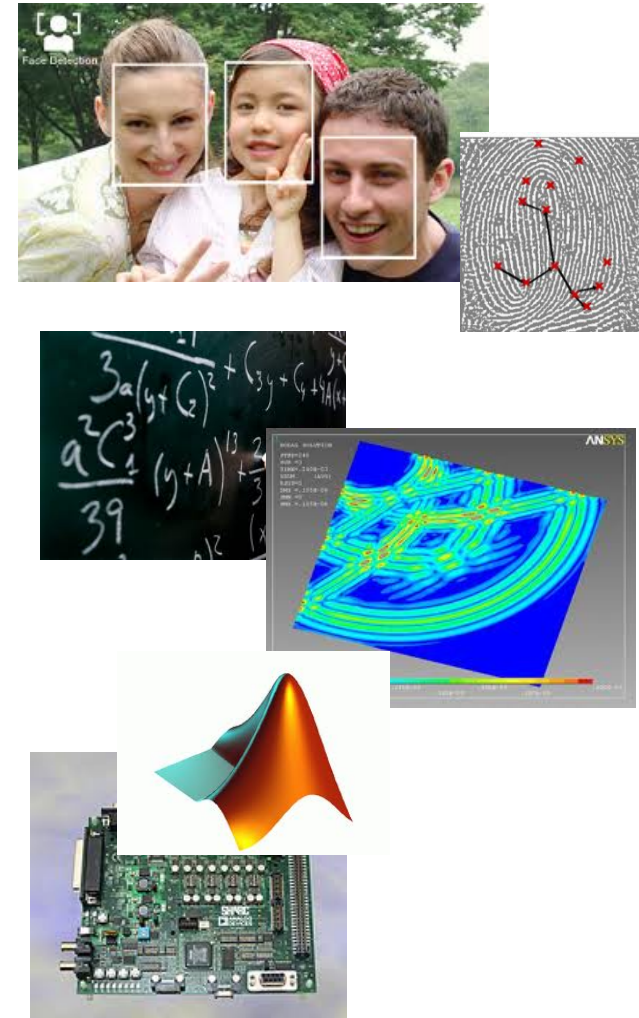


1.1 What is MatLab

- A typical algorithm development cycle involves the following

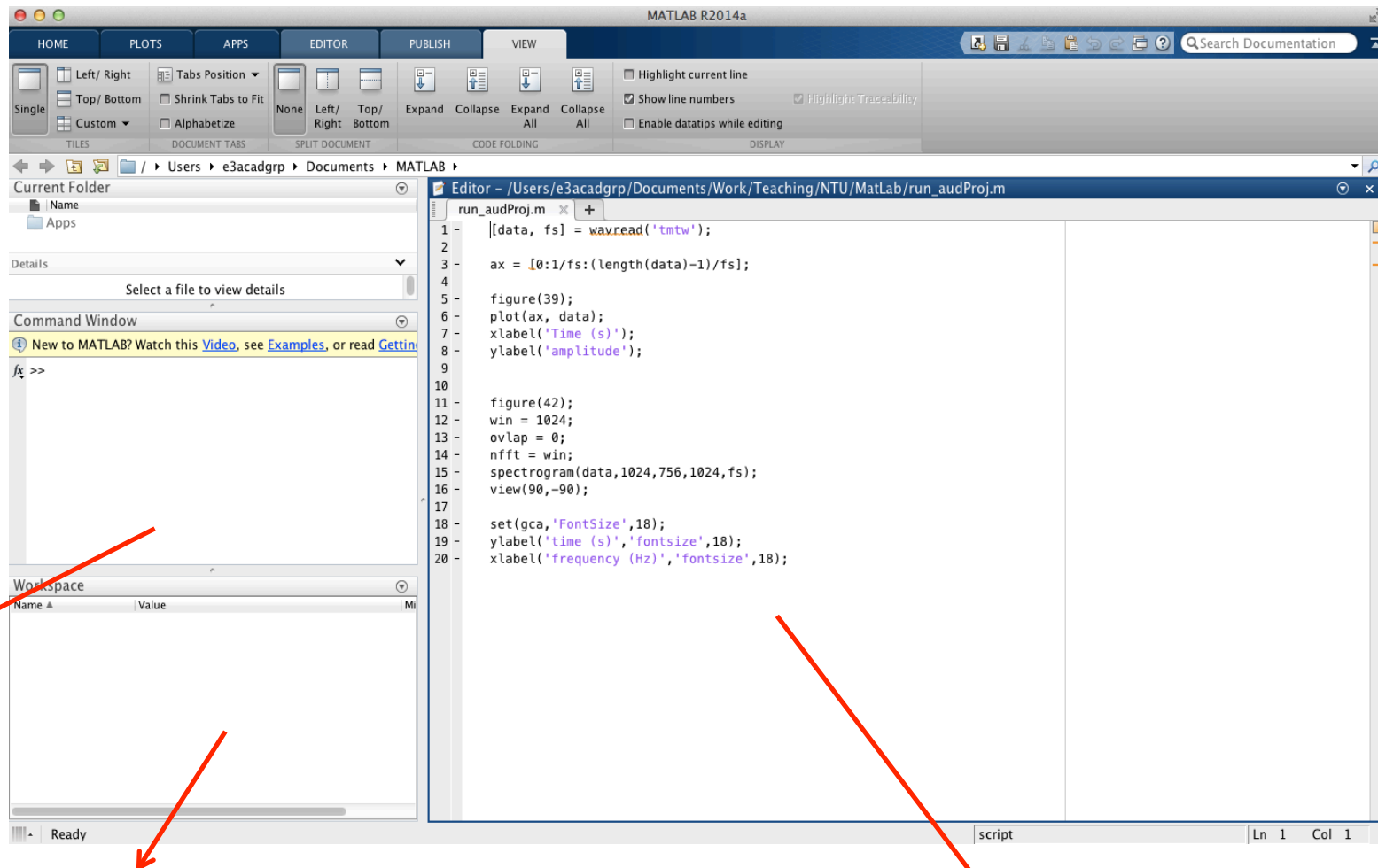


- Acoustic source localization
- Face detection
- Fingerprint authentication
- Footstep detection
- Signal processing tools
- Mathematical formulation
- Wave propagation
- Contrast detection
- MatLab
- PC-based (C/C++)
- DSP implementation (TI, Analog Devices)
- Android based (Arduino)
- Field programmable gate array (FPGA)



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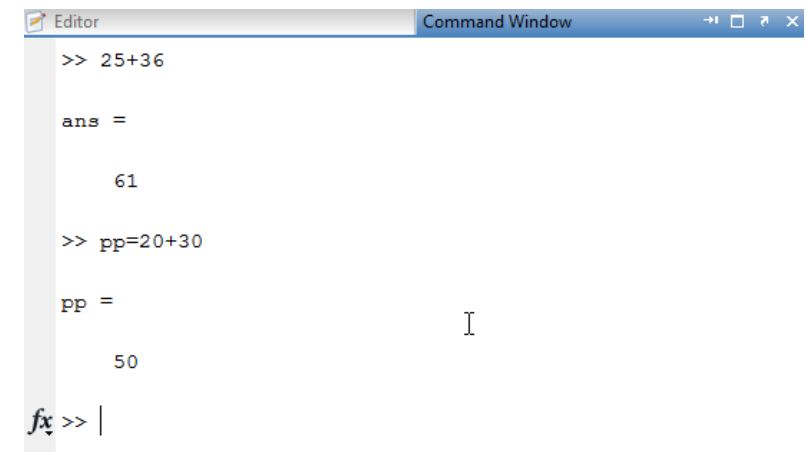
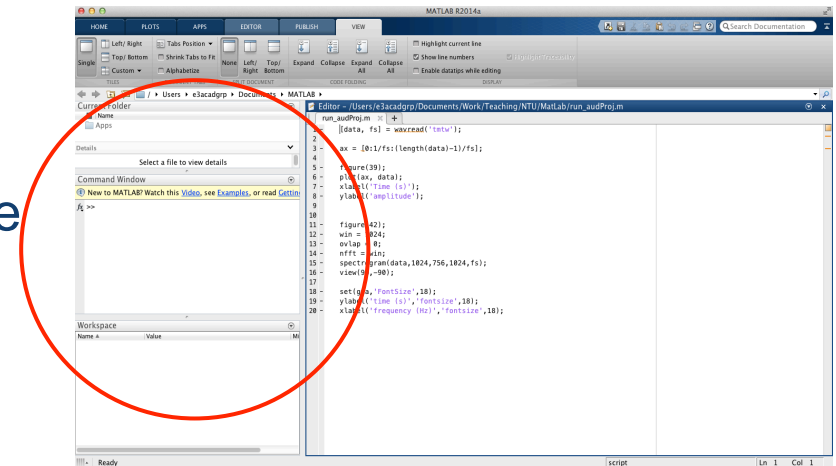
1.2 Interface



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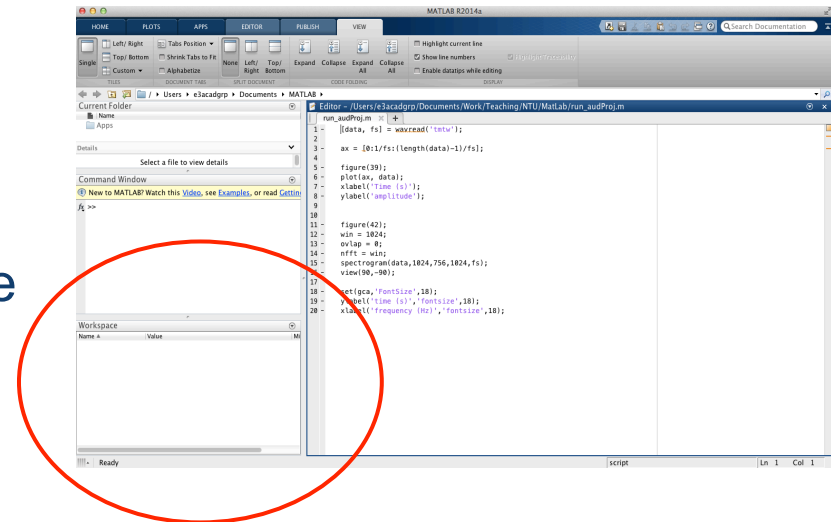
1.3 Command window

- The command window is where a lot of researchers will do their programming.
- It offers a fast and easy way to compute equations just like an ordinary calculator.
- Try the following: `>> 25+36`
- And you will get: `ans = 61`
- Try also the following:
`>> pp = 20+30`



1.4 Workspace

- Very often, in a research project, we define a lot of variables (> 30).
- The workspace is where we would like to keep track of variables and their values.
- It is a place where researchers know:
 - what has been defined
 - the maximum and minimum values
- Double-clicking the variables will allow you to see the variables in a form similar to excel spreadsheet.

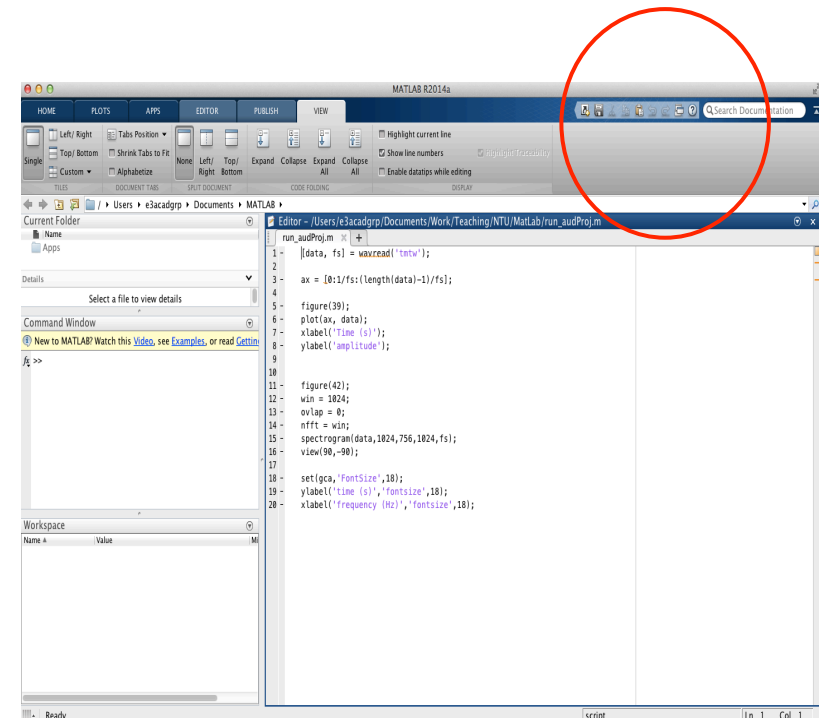


Current Folder		Workspace		
		Stack: Base	Select data to plot	
Name	Value	Min	Max	
ans	61	61	61	
pp	50	50	50	

Variable Editor - pp						
File Edit View Graphics Debug Desktop Window Help						
Stack: Base No valid plots for: pp(1,1)						
pp <1x1 double>						
	1	2	3	4	5	6
1	50					
2						
3						

- Very often, we enter a lot of commands and it is sometimes useful to keep track of them.
- To repeat some computations without re-typing them, simply hit the “up” arrow key in the command window
- Another way to repeat any previous commands is
 - to place the cursor in the command window
 - hit the “up” or “down” arrow keys to cycle through previous commands

- MatLab has documented a comprehensive set of help files.
- These files can be accessed from the “Help” menu.
- Try accessing it via
Help → Product Help
- You may search different functions by typing keywords into the search box.
- Try typing “mean” into the search box



1.7 Clearing memory and command window



- For large projects, one often have to declare lots of variables.
- Some variables may hold many numbers and if the program is not using them, it may be wise to free up the memory by deleting these variables.
- To delete a particular variable, say the variable “pp”, use
`>> clear pp`
You will notice the variable “pp” disappearing from the workspace.
- To delete all variables, i.e., to clear all memory simply type
`>> clear`
- To clear the command window, use
`>> clc`

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CHAPTER 2

Vectors and Matrices

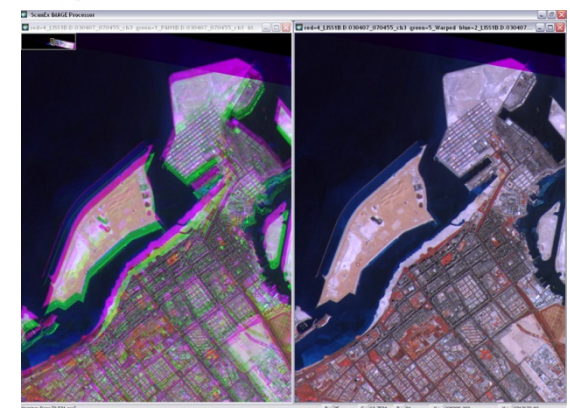
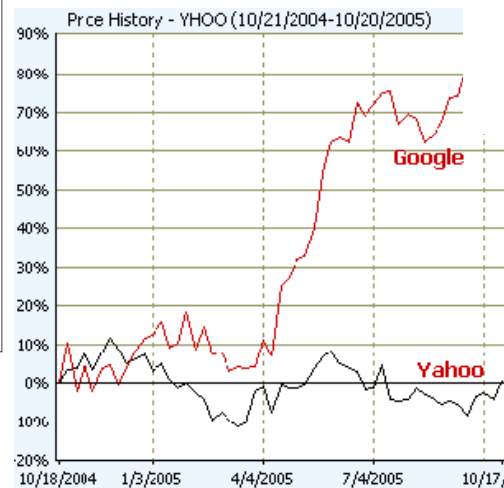
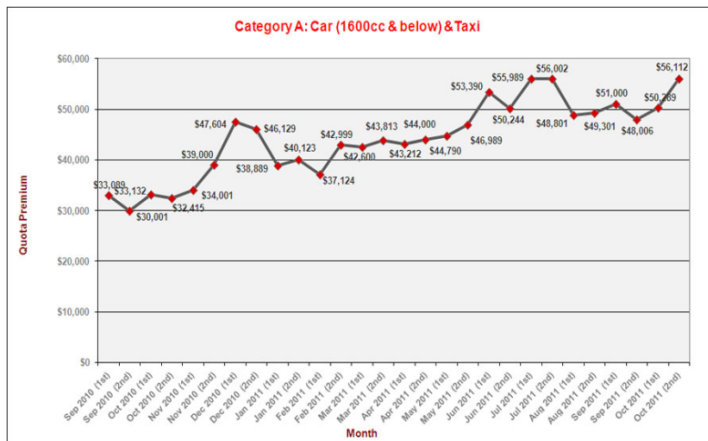
2.1 Defining vectors and matrices

- Vectors are arrays that store a series of numbers
- Vectors can be classified into row and column vectors

$$\begin{bmatrix} 1 & 40 & 2 & 200 & 12 \end{bmatrix}$$

$$\begin{bmatrix} 2.4 \\ 3.2 \\ 3 \end{bmatrix}$$

- Many real-world signals can be expressed in the form of vectors/matrices



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2.1 Defining vectors and matrices

- To define a row vector use

```
>> rowVecA = [1 4 2]
```

$$\text{rowVecA} = \begin{bmatrix} 1 & 4 & 2 \end{bmatrix}$$

- The semi-colon “;” is used to concatenate numbers to the next row. Useful to form a column vector:

```
>> colVecB = [2; 1; 3]
```

$$\text{colVecB} = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}$$

- The above can be extended to form a matrix.
 - First define the row
 - To define the next row, use the semi-colon
 - Remember to make sure each row has the same number of elements

```
>> matC = [ 1 3 5; 3 2 6; 1 1 3]
```

$$\text{matC} = \begin{bmatrix} 1 & 3 & 5 \\ 3 & 2 & 6 \\ 1 & 1 & 3 \end{bmatrix}$$

2.1 Defining vectors and matrices

- Sometimes its clumsy to list down all elements manually if the numbers exhibits certain characteristics.
- We can use the colon “:” operator which is the same as counting from a number “to” another number (in steps of 1).
- Example: To generate a vector called “num” containing numbers 30 to 50, we use

```
>> num = [30:50]
```

```
num = [ 30  31  ...  50 ]
```

- We can use two colons if we want to count in steps other than 1.
- Example: To generate a vector of even numbers from 30 to 50

```
>> eveNum = [30:2:50]
```

```
eveNum = [ 30  32  34  ...  50 ]
```

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2.2 Referencing elements

- To reference an element within a vector/matrix, we use the elemental position of the variable.
- Therefore, to reference an element, we use the format

```
>> variableName(rowIndex,columnIndex)
```

- To reference the 2nd element of the vector “rowVecA”, defined in Section 2.1, we use

```
>> rowVecA(2)
```

$$\text{rowVecA} = [1 \quad 4 \quad 2]$$

- To reference the 2nd row, 3rd column of the matrix “matC”, defined in Section 2.1, we use

```
>> matC(2,3)
```

$$\text{matC} = \begin{bmatrix} 1 & 3 & 5 \\ 3 & 2 & 6 \\ 1 & 1 & 3 \end{bmatrix}$$

2.2 Referencing elements

- We can also use the colon operator “:” to reference a range of elements.
- Therefore, to reference the 2nd to 3rd element of “rowVecA”, we use

```
>> rowVecA(2:3)
```

$$\text{rowVecA} = \begin{bmatrix} 1 & 4 & 2 \end{bmatrix}$$

- To reference the last element of the vector, we can use the keyword “end”

```
>> rowVecA(end)
```

$$\text{rowVecA} = \begin{bmatrix} 1 & 4 & 2 \end{bmatrix}$$

- To determine the length of the vector, we can use the keyword “length”

```
>> lenVecA = length(rowVecA)
```

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2.3 Matrix/vector transpose

- To transpose a matrix, use the “prime” key, located on the immediate left of the “Enter” key.

- Transpose of the column vector “colVecB” will form a row vector:

>> transpVecB = colVecB'

$$\text{colVecB} = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}$$

$$\text{transpVecB} = \begin{bmatrix} 2 & 1 & 3 \end{bmatrix}$$

- To transpose a matrix, we use the same prime notation

>> transpmatC = matC'

$$\text{matC} = \begin{bmatrix} 1 & 3 & 5 \\ 3 & 2 & 6 \\ 1 & 1 & 3 \end{bmatrix}$$

$$\text{transpmatC} = \begin{bmatrix} 1 & 3 & 1 \\ 3 & 2 & 1 \\ 5 & 6 & 3 \end{bmatrix}$$

2.3 Matrix/vector multiplication

- Unlike scalar multiplication, matrix/vector multiplication can only be performed when we take the dimension into account.

- In general,

$$\mathbf{A}_{M \times N} \times \mathbf{B}_{N \times P} = \mathbf{C}_{M \times P}$$

- Example

```
>> A = [1 3 4; 2 4 7]
```

```
>> B = [5; 6; 1]
```

```
>> C = A*B
```

$$\mathbf{A}_{2 \times 3} = \begin{bmatrix} 1 & 3 & 4 \\ 2 & 4 & 7 \end{bmatrix} \quad \mathbf{B}_{3 \times 1} = \begin{bmatrix} 5 \\ 6 \\ 1 \end{bmatrix}$$

$$\begin{aligned} \mathbf{C}_{2 \times 1} &= \begin{bmatrix} 1 & 3 & 4 \\ 2 & 4 & 7 \end{bmatrix} \begin{bmatrix} 5 \\ 6 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} (1 \times 5) + (3 \times 6) + (4 \times 1) \\ (2 \times 5) + (4 \times 6) + (7 \times 1) \end{bmatrix} \\ &= \begin{bmatrix} 27 \\ 41 \end{bmatrix} \end{aligned}$$

- Would the following work?

```
>> D=B*A
```

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2.4 Element-by-element multiplication

- It is possible to perform element-by-element multiplication using the dot-multiplication notation, i.e., “.*”
- For element-by-element operation, make sure they are of the same dimensions.

- Example

```
>> A = [1 3 4; 2 4 7]
```

```
>> D = [2 8 1; 1 1 5]
```

```
>> E = A.*D
```

$$\mathbf{A}_{2 \times 3} = \begin{bmatrix} 1 & 3 & 4 \\ 2 & 4 & 7 \end{bmatrix} \quad \mathbf{D}_{2 \times 3} = \begin{bmatrix} 2 & 8 & 1 \\ 1 & 1 & 5 \end{bmatrix}$$

$$\begin{aligned} \mathbf{E}_{2 \times 3} &= \begin{bmatrix} (1 \times 2) & (3 \times 8) & (4 \times 1) \\ (2 \times 1) & (4 \times 1) & (7 \times 5) \end{bmatrix} \\ &= \begin{bmatrix} 2 & 24 & 4 \\ 2 & 4 & 35 \end{bmatrix} \end{aligned}$$

- Are the following valid?

```
>> E = A*D
```

```
>> F = A*D'
```

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2.5 Solving simultaneous equations

- MatLab offers an excellent tool for solving simultaneous equations.

- Consider the following example:
$$\begin{aligned}3x + 4y - 2z &= 6 \\4x - 6y + 2z &= 1 \\2x + y + 0.2z &= 2\end{aligned}$$

- To find the unknown variables x, y and z , we re-write in matrix form

$$\begin{bmatrix} 3 & 4 & -2 \\ 4 & -6 & 2 \\ 2 & 1 & 0.2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 6 \\ 1 \\ 2 \end{bmatrix}$$

$$\mathbf{A}\mathbf{q} = \mathbf{p}$$

- To find the unknown, i.e., elements in the vector \mathbf{q} , we only need to use the following

$$\mathbf{q} = \mathbf{A}^{-1}\mathbf{p}$$

2.5 Solving simultaneous equations

- So how do we solve it in MatLab?

$$\begin{bmatrix} 3 & 4 & -2 \\ 4 & -6 & 2 \\ 2 & 1 & 0.2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 6 \\ 1 \\ 2 \end{bmatrix}$$

$$\mathbf{A}\mathbf{q} = \mathbf{p}$$

$$\mathbf{q} = \mathbf{A}^{-1}\mathbf{p}$$

- Define all variables. Compute the unknown by calculating the inverse of a matrix using “inv()”

2.6 Condition number and invertibility

- Consider the following example:

$$\begin{aligned}3x + 4y &= 6 \\6x + 8y &= 12\end{aligned}$$

- To find the unknown variables x, y and z , we re-write in matrix form

$$\begin{bmatrix} 3 & 4 \\ 6 & 8 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 6 \\ 12 \end{bmatrix}$$

$$\mathbf{A}\mathbf{q} = \mathbf{p}$$

- To find the unknown, i.e., elements in the vector \mathbf{q} , we only need to use the following

$$\mathbf{q} = \mathbf{A}^{-1}\mathbf{p}$$

- In MatLab

2.6 Condition number and invertibility

- The above generates the result

$$\mathbf{q} = \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} \text{inf} \\ \text{inf} \end{bmatrix}$$

with the warning message

Warning: Matrix is singular to working precision.

- The above implies that there are no solutions for x , and y
- This can be verified by the high condition number of the matrix \mathbf{A}
`>> cond(A)`
- A high conditional number of \mathbf{A} implies that it is non-invertible.
- An invertible \mathbf{A} has a low condition number of 1.



CHAPTER 3

Complex Numbers

3.1 Defining complex numbers

- In addition to real numbers, MatLab also supports complex numbers.
- This is achieved via the variables “i” and “j” (if they haven’t been defined). These variables have already been pre-defined as complex numbers in MatLab

```
>> i
```

$$i = 0 + 1i$$

```
>> j
```

$$j = 0 + 1j$$

- We can define complex numbers using

```
>> val = 3+2j
```

$$\text{val} = 3 + 2j$$

- An array of complex numbers can then be defined using

```
>> cplAry = [2; 3; 9] + j*[0.2; 3; 0.5]
```

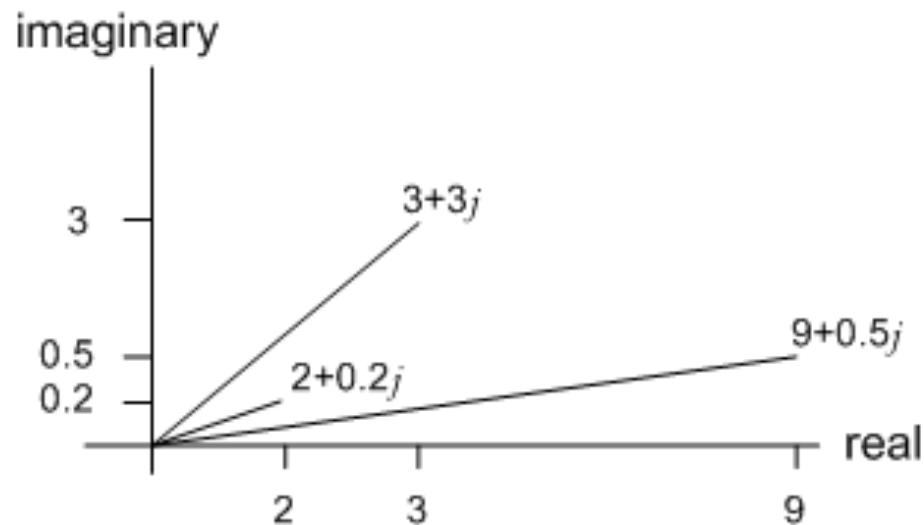
or

```
>> cplAry = [2+0.2j; 3+3j; 9+0.5j]
```

$$\text{cplAry} = \begin{bmatrix} 2 \\ 3 \\ 9 \end{bmatrix} + j \begin{bmatrix} 0.2 \\ 3 \\ 0.5 \end{bmatrix} = \begin{bmatrix} 2 + 0.2j \\ 3 + 3j \\ 9 + 0.5j \end{bmatrix}$$

3.2 Magnitude and phase

- Any complex numbers can be characterized by its magnitude and phase



$$\text{cplAry} = \begin{bmatrix} 2 + 0.2j \\ 3 + 3j \\ 9 + 0.5j \end{bmatrix}$$

3.2 Magnitude and phase

- To compute the magnitude use “abs()”

```
>> absAry = abs(cplAry)
```

$$\text{cplAry} = \begin{bmatrix} 2 + 0.2j \\ 3 + 3j \\ 9 + 0.5j \end{bmatrix}$$

$$\text{absAry} = \begin{bmatrix} \sqrt{2^2 + 0.2^2} \\ \sqrt{3^2 + 3^2} \\ \sqrt{9^2 + 0.5^2} \end{bmatrix} = \begin{bmatrix} 2.01 \\ 4.24 \\ 9.01 \end{bmatrix}$$

- The phase can be computed via “phase()”

```
>> phAry = phase(cplAry)
```

$$\text{phAry} = \begin{bmatrix} \tan^{-1}(0.2/2) \\ \tan^{-1}(3/3) \\ \tan^{-1}(0.5/9) \end{bmatrix} = \begin{bmatrix} 0.0997 \\ 0.7854 \\ 0.0555 \end{bmatrix}$$

- Note that since, by default, MatLab computes angles in radians, angles in degrees can be computed easily using

```
>> phAry = phase(cplAry).*180/pi
```

$$\begin{aligned} \text{phAry} &= \begin{bmatrix} \tan^{-1}(0.2/2) \\ \tan^{-1}(3/3) \\ \tan^{-1}(0.5/9) \end{bmatrix} \times 180/\pi \\ &= \begin{bmatrix} 5.71 \\ 45.00 \\ 3.18 \end{bmatrix} \end{aligned}$$

3.3 Real and imaginary

- To extract the real parts within an array, simply use “real()”

```
>> rlAry = real(cplAry)
```

$$\text{cplAry} = \begin{bmatrix} 2 + 0.2j \\ 3 + 3j \\ 9 + 0.5j \end{bmatrix}$$

- To extract the real part of a particular element, you may apply Section 2.2. Therefore, to extract the real part of the 3rd element in the variable “cplAry”, use

```
>> real(cplAry(3))
```

$$\text{rlAry} = \begin{bmatrix} 2 \\ 3 \\ 9 \end{bmatrix}$$

- To extract the imaginary parts within an array, use “imag()”

```
>> imAry = imag(cplAry)
```

$$\text{imAry} = \begin{bmatrix} 0.2 \\ 3 \\ 0.5 \end{bmatrix}$$

CHAPTER 4

Plotting

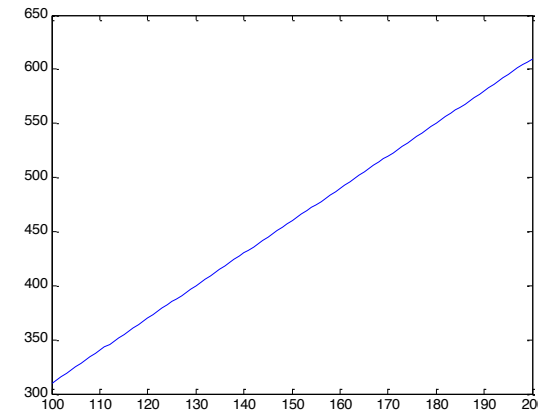


- Compared to C/C++, MatLab offers an excellent and simple way to visualize functions.
- Plotting is done via the “plot()” function and specifying the abscissa and ordinate values.
- The plot function has two arguments (inputs)
 - a vector containing abscissa values
 - a vector containing ordinate values
 - plot (abscissaValues, ordinateValues)
- Note that the number of elements in both vectors must be the same.

4.1 Plotting lines



- Example: To plot the function of $y = 3x + 10$ within the range of $x = 100 \dots 200$
 - Create a new figure
`>> figure(20)`
 - Specify a vector containing the abscissa (counting from 100 to 200)
`>> x = [100:200];`
 - Compute the ordinate values
`>> y = 3*x+10;`
 - Plot the function
`>> plot(x,y)`

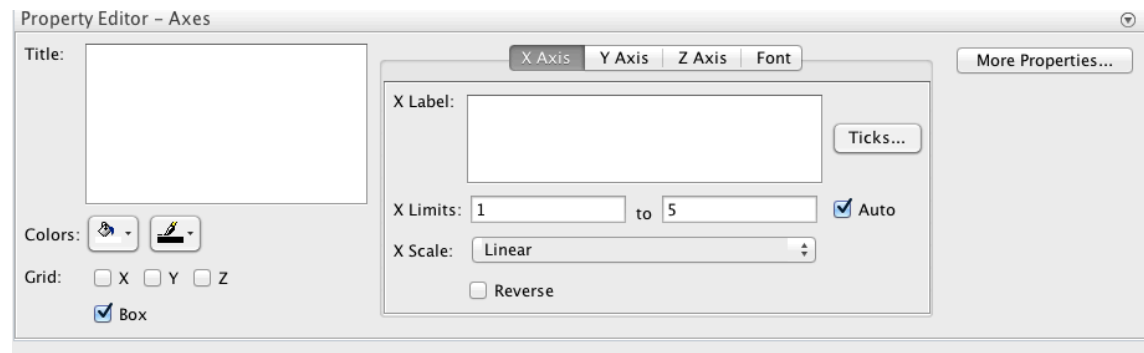
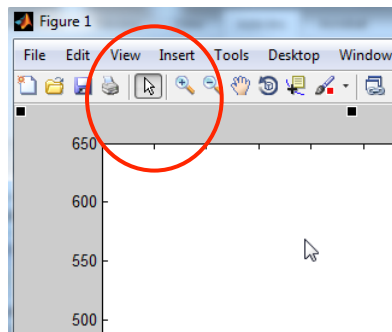


- The number “20” after the “figure” keyword is to identify which figure MatLab should plot the data. If there is no figure 20, it will create a new one.
- The semi-colon “;” at the end of the 2nd and 3rd command is there to prevent MatLab from listing down the elements of the vector.
- It is very useful particularly if you do not want to display long vectors.

4.2 Axes labelling, titles, font size

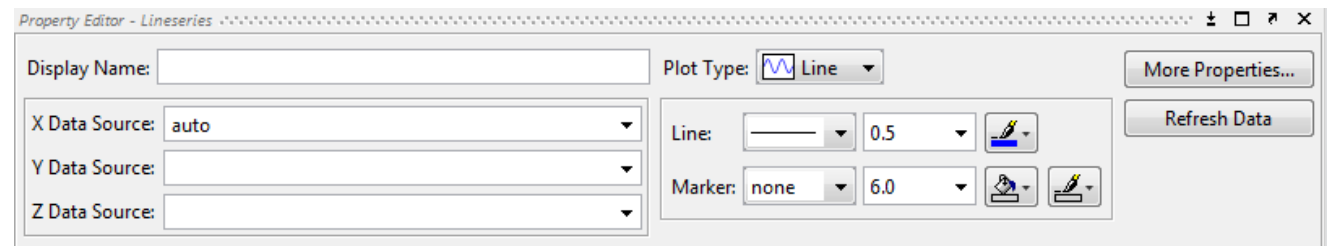
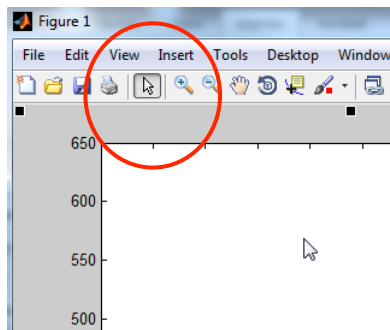
- As engineers its very important to label the axes of the plots.
- The programming way to label the axes is to employ

```
>> xlabel('x values')
>> ylabel('y values')
```
- One can also use the graphical approach.
 - Click on the arrow icon in the figure you have plotted
 - Double-click on the white space of your plot
 - Use the property-editor at the bottom of your plot to change/insert information.



4.3 Color and markers

- It is also very useful to plot the lines in different colors and place markers on the lines.
- The graphical approach offers a simple way to do that
 - Click on the arrow icon in the figure you have plotted
 - Double-click on the line you have plotted
 - Use the property-editor at the bottom of your plot to change/insert information.



- “Holding” allows researchers to plot multiple equations on the same graph.
- You may use the following command to “hold” a figure
`>> hold on;`

- Example: Plot the following equations for $x = 1$ to 40

$$y_1 = 3x - 10$$

$$y_2 = x + 10$$

- Generate an array of x values
- Generate the output vectors for each equation
- Plot the figures



$$y_1 = 3x - 10$$

$$y_2 = x + 10$$

- Generate an array of x values

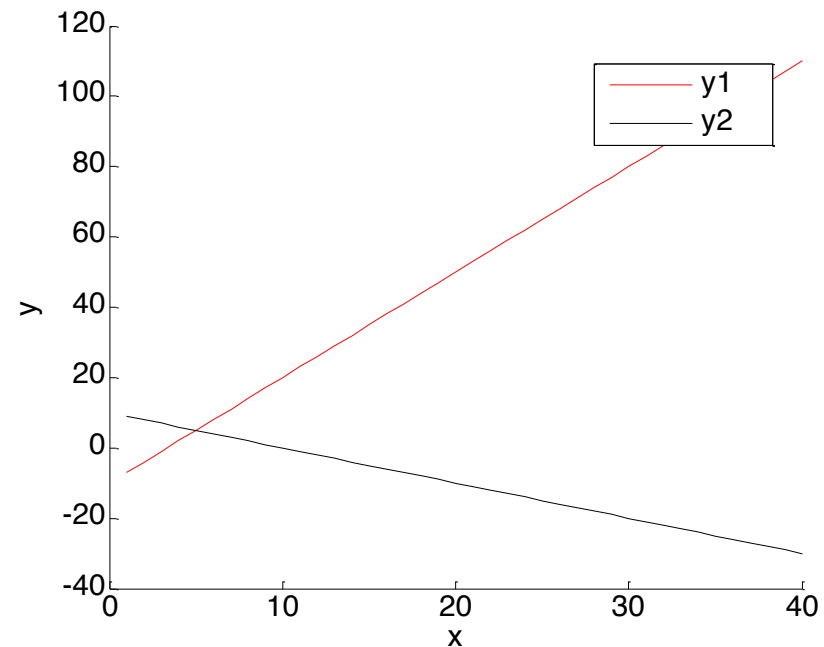
```
>> x=[1:40];
```

- Generate the output vectors for each equation

```
>> y1 = 3*x-10;
```

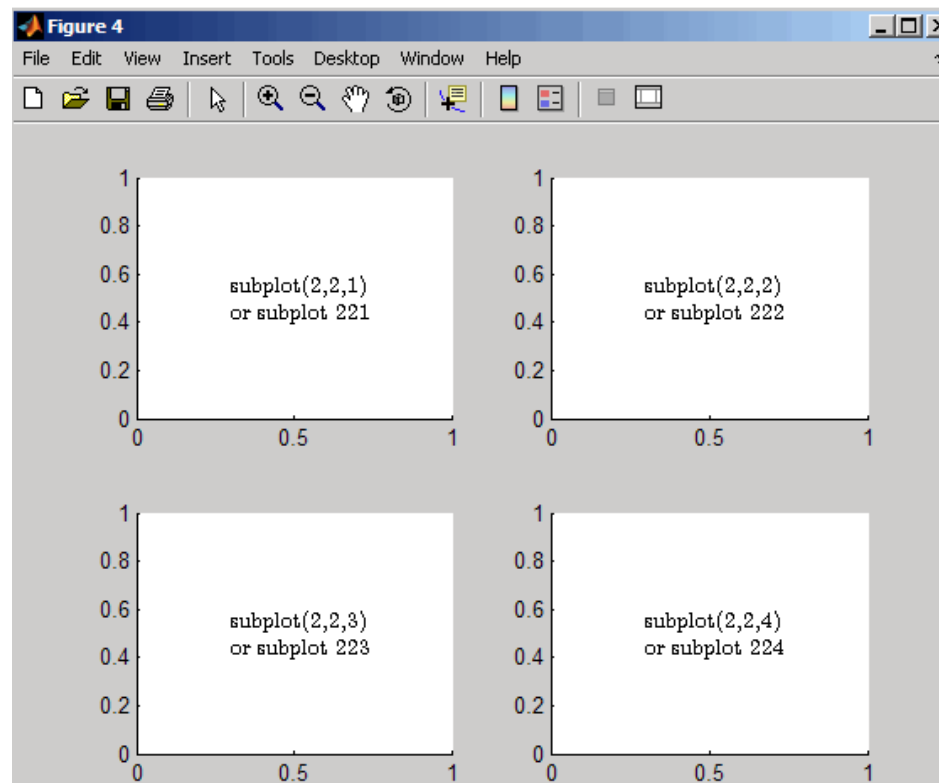
```
>> y2 = -x+10;
```

- Plot the figures



4.5 Subplots

- Subplot allows one to plot two or more functions on separate axes.
- The function “subplot(m,n,p)”
 - breaks the figure into m-by-n matrix
 - the integer “p” defines the subplot index

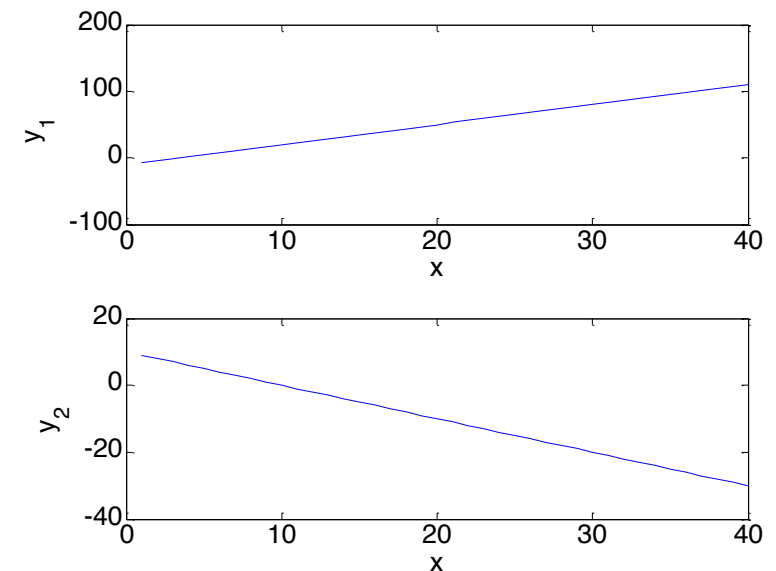


- Consider the case where you may want to plot the following separately.

$$y_1 = 3x - 10$$

$$y_2 = x + 10$$

- Generate a new figure
`>> figure(39);`
- Define the 1st subplot position and plot 1st graph
`>> subplot(2,1,1);`
`>> plot(x,y1);`
- Define the 2nd subplot position and plot 2nd graph
`>> subplot(2,1,2);`
`>> plot(x,y2);`





CHAPTER 5

Scripts and Functions

5.1 Saving your scripts

- Thus far, all commands have been entered into the “Command window”
- Advantages of using this command window include
 - simple interface for users to type in commands
 - providing a quick way to validate computations
- However, disadvantages of using the command window include
 - not being able to save the commands for future reference
 - the need to re-key commands all over again
 - if there is a typo error
 - on a separate occasion (after you close MatLab)
 - not being able to execute multiple commands in a single run (commands are currently executed after every line)
- The use of scripts allows one to save the commands in a file, and run multiple commands

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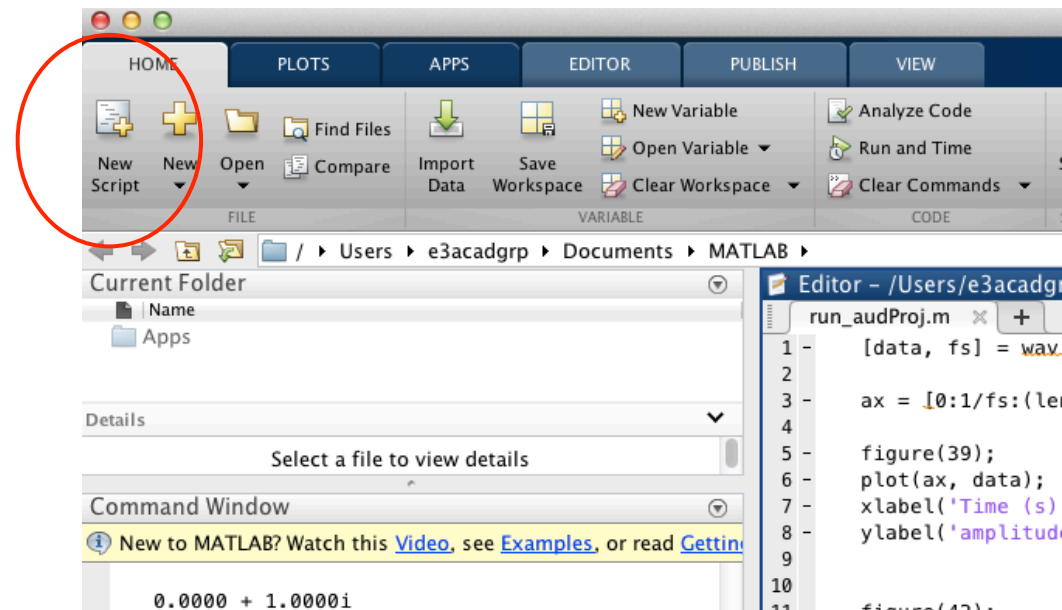
5.1 Saving your scripts

- Here, we will create a script which solves the following equations and verifies the answer graphically.

$$2x + 10y = 54$$

$$3x - 5y = -19$$

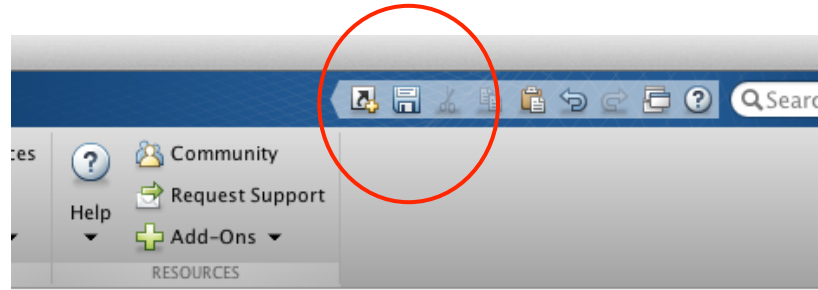
- First create a folder under desktop and name it “projects”
- Create a script by clicking the “New Script” button at the “Home” tab



7/27/16

5.1 Saving your scripts

- You will be brought to the “Editor” page with a filename “Untitled”
- Save this file as “run_solveSimEqns” in the desktop folder you created



- Formulate the problem in Matrix notation according to Section 2.5

$$2x + 10y = 54$$

$$3x - 5y = -19$$

$$\begin{bmatrix} 2 & 10 \\ 3 & -5 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 54 \\ -19 \end{bmatrix}$$

$$\mathbf{A}\mathbf{q} = \mathbf{p}$$

$$\mathbf{q} = \mathbf{A}^{-1}\mathbf{p}$$

5.1 Saving your scripts

- Key in the following commands

```
>> A = [2 10; 3 -5];
```

```
>> p = [54; -19];
```

```
>> q = inv(A)*p;
```

- To verify the result graphically, we use

$$2x + 10y = 54$$

$$3x - 5y = -19$$

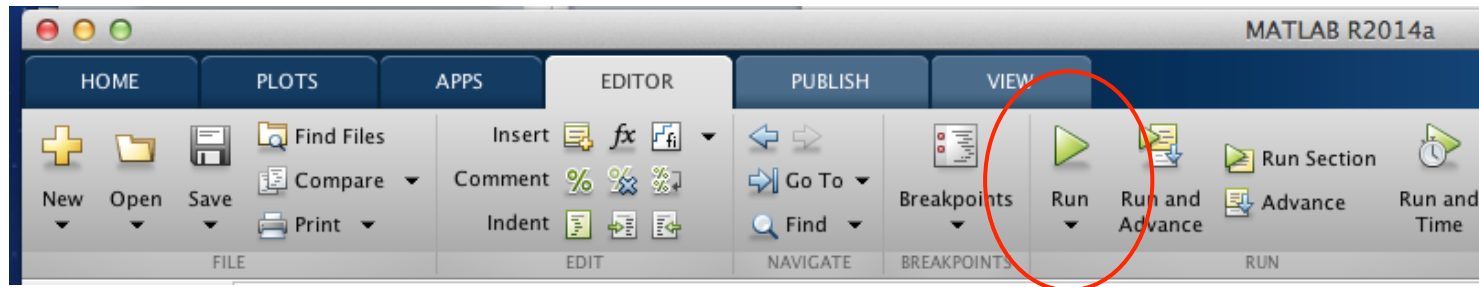
$$\begin{bmatrix} 2 & 10 \\ 3 & -5 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 54 \\ -19 \end{bmatrix}$$

$$\mathbf{A}\mathbf{q} = \mathbf{p}$$

$$\mathbf{q} = \mathbf{A}^{-1}\mathbf{p}$$

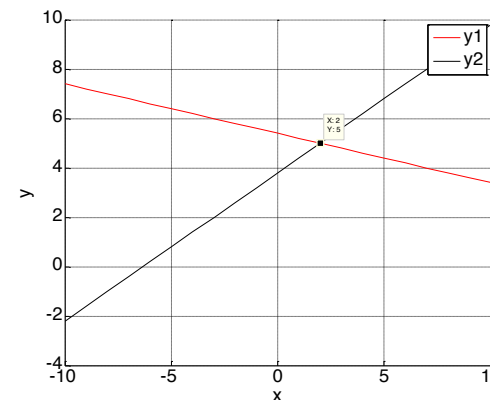
5.1 Saving your scripts

- Click on the “run” icon after all commands have been entered



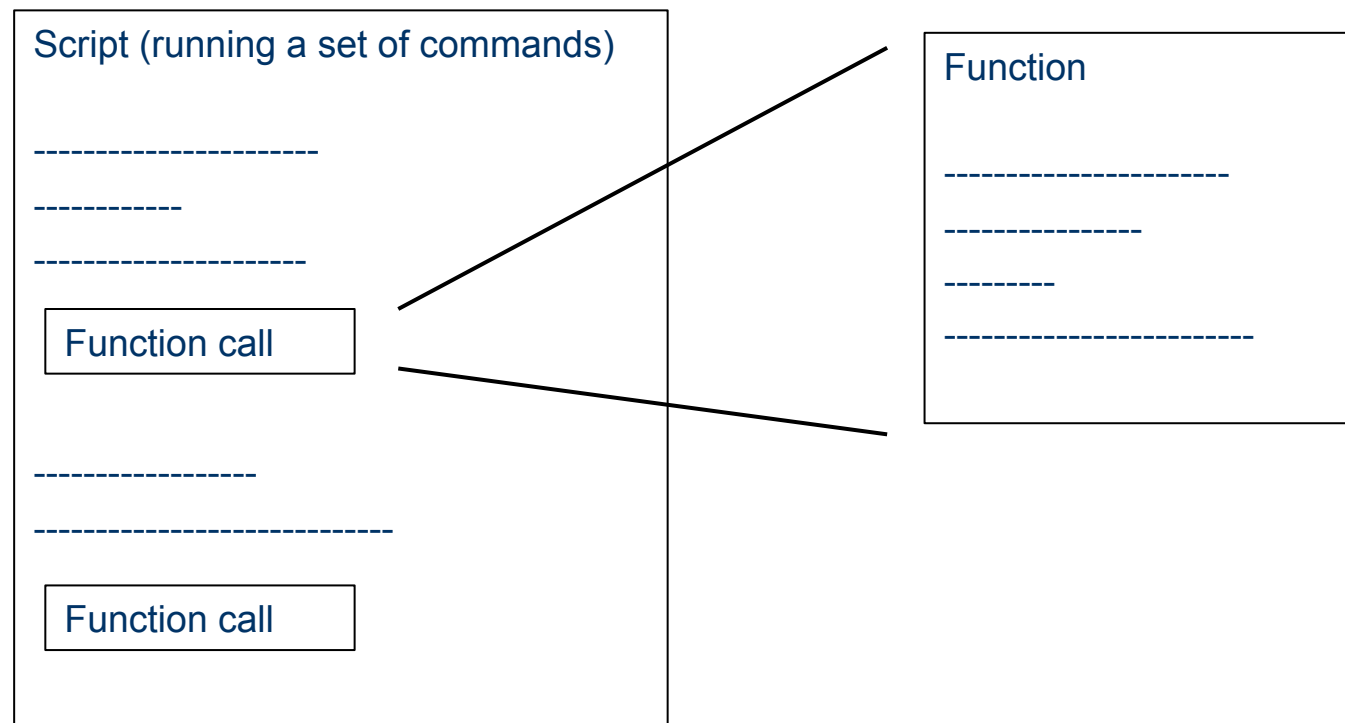
- Error messages, if any, will appear in the command window.
- The unknowns can be found by double clicking the **q** variable in the Workspace.

$$\mathbf{q} = \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2 \\ 5 \end{bmatrix}$$

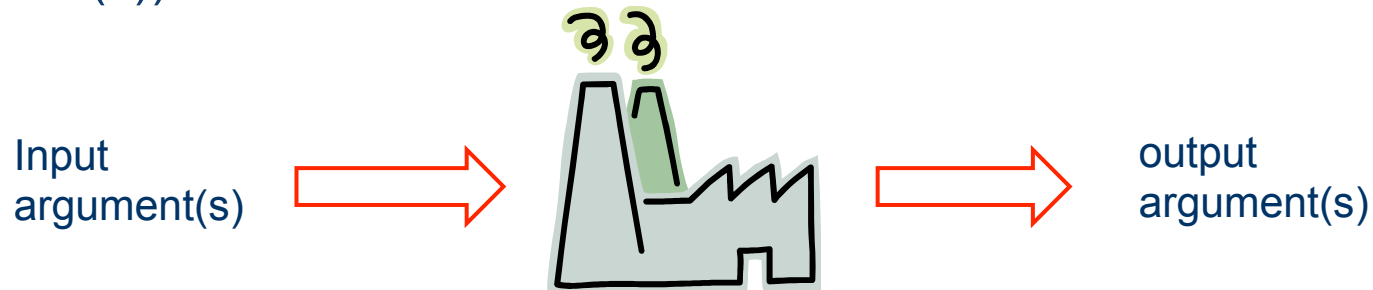


- You may now solve any simultaneous equations by changing the values of variables **A** and **p** in the script without having to key in all the commands.

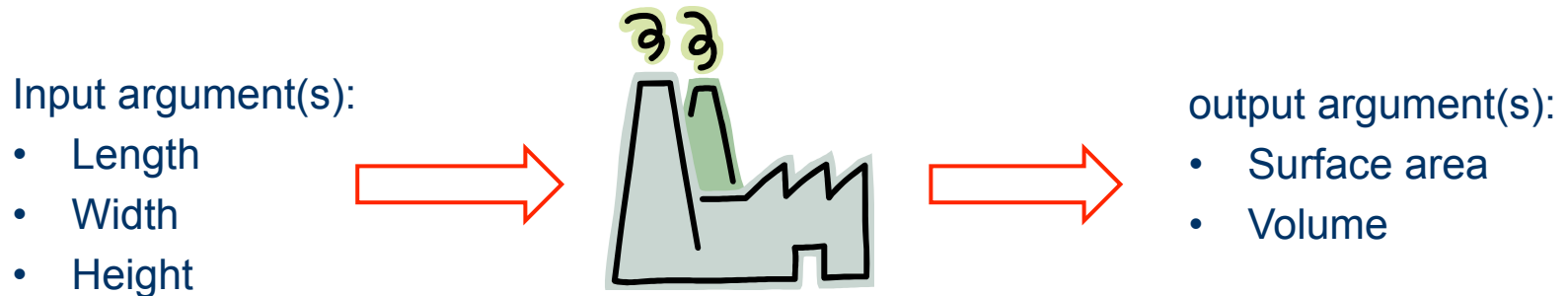
- Functions are a neat way to organize your codes, particularly if you are working on large projects.
- The relationship between “functions” and “scripts” can best be described using the following figure.



- Functions are analogous to an automation factory; it takes in raw materials (input argument(s)) and generates products (output argument(s)).



- For example, we can have a function which computes the volume and the surface area of a cuboid.



- Example: Write a script and a function to compute the surface area and volume of a cuboid.
 - We first create the script by clicking on “New Script” under the “Home” tab
 - Save this script as “*run_solveCuboid.m*” in the desktop folder you created. Use “Save” under the “Editor” tab.

- Key in the following commands

```
>> length = 4;
```

```
>> width = 3;
```

```
>> height = 2.5;
```

```
>> [volCubd, surfAreaCubd] = compCubd (length, width, height);
```



Output arguments

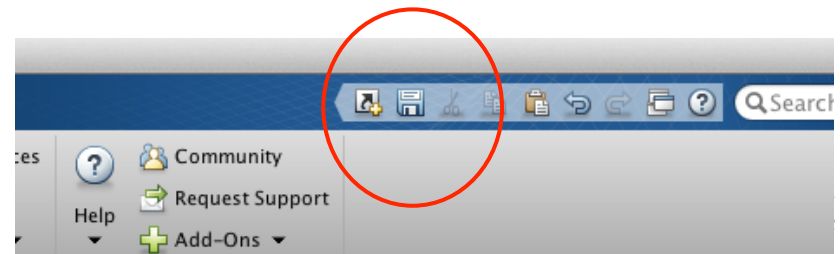


Function name

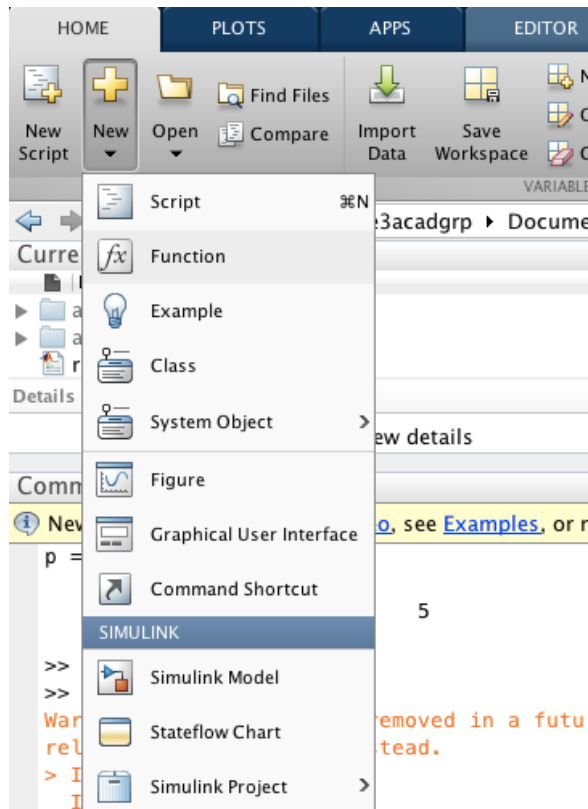


Input arguments

- Save the file by clicking the save icon



- Create the function using
- Change the first line to
`function [vol, area] = compCubd (len, wid, hgt);`

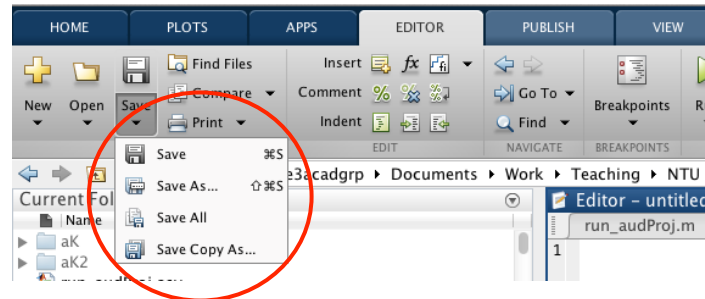


```
Untitled*
1  function [ output_args ] = Untitled( input_args )
2  %UNTITLED Summary of this function goes here
3  % Detailed explanation goes here
4
5  end
```



```
Untitled*
1  function [ vol, area ] = compCubd( len, wid, hgt )
2  %UNTITLED Summary of this function goes here
3  % Detailed explanation goes here
4
5  end
6
```

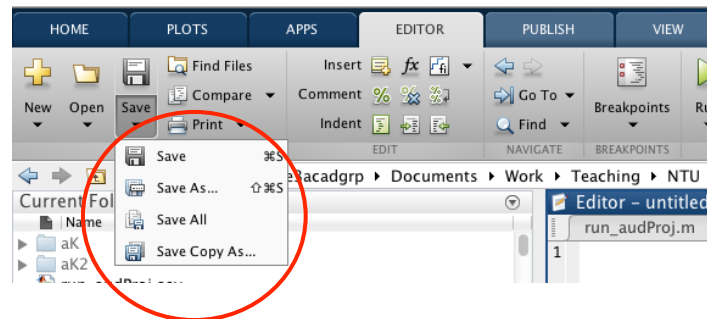
- Click the save icon, save the file under the default file name “*compCubd.m*” in the same folder as the script.



- Key in the following commands

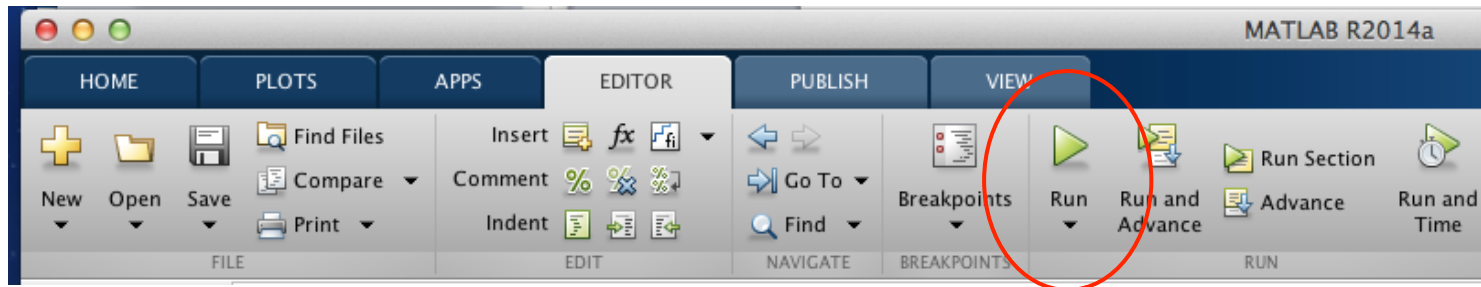
$$>> \text{vol} = \text{len} * \text{wid} * \text{hgt};$$

$$>> \text{area} = 2 * (\text{len} * \text{wid}) + 2 * (\text{len} * \text{hgt}) + 2 * (\text{wid} * \text{hgt});$$
- Click the save icon

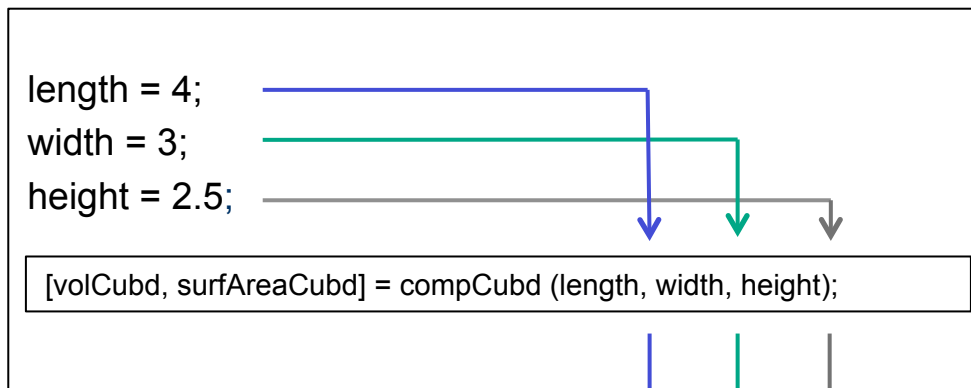


5.2 Functions

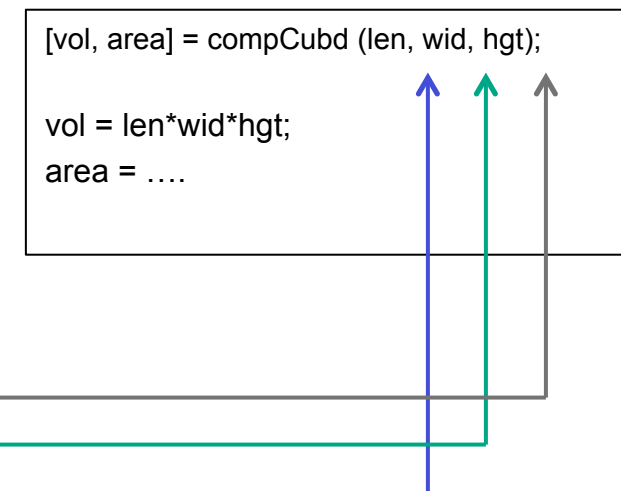
- Open the “*run_solveCuboid.m*” script and run it



script



function



CHAPTER 6

Sine/Cosine Plots

- An analog sinusoid is in the form of

$$\begin{aligned}x(t) &= A \cos(2\pi f t) \\ &= A \cos(\omega t)\end{aligned}$$

Therefore, by definition,

$$\begin{aligned}f &: \text{ analog frequency in cycles/sec (Hz)} \\ \omega &: \text{ angular (analog) frequency in rad/sec}\end{aligned}$$

- A digital sinusoid is in the form of

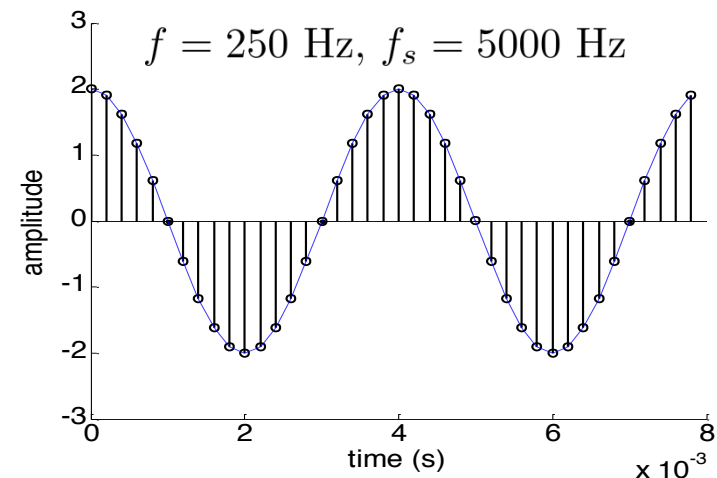
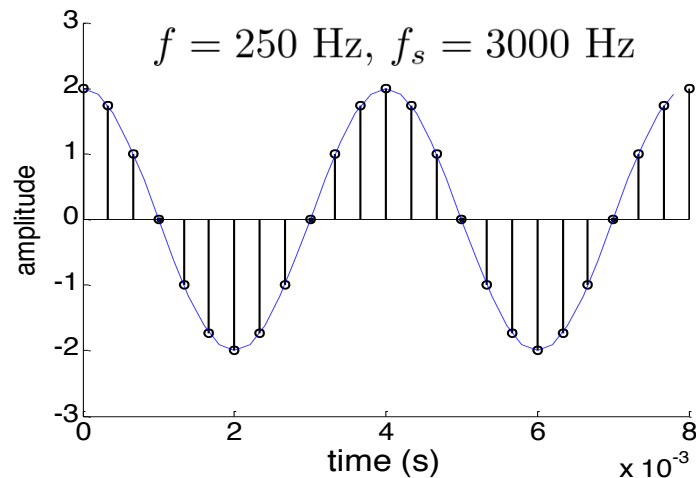
$$\begin{aligned}x[n] &= A \cos(2\pi f_0 n) \\ &= A \cos(\omega_0 n)\end{aligned}$$

Therefore, by definition,

$$\begin{aligned}f_0 &: \text{ digital frequency in cycles/sample} \\ \omega_0 &: \text{ angular (digital) frequency in rad/sample}\end{aligned}$$

6.2 Discrete-time signal from continuous-time signal

- Sampling a continuous-time signal results in a discrete-time signal.
- We often write $x[n] = x_{\text{continuous}}(nT)$
 $T = 1/f_s$ is the sampling period in sec
 f_s : sampling frequency in Hz
- A higher f_s implies that the analog signal is sampled more frequently.



6.2 Discrete-time signal from continuous-time signal

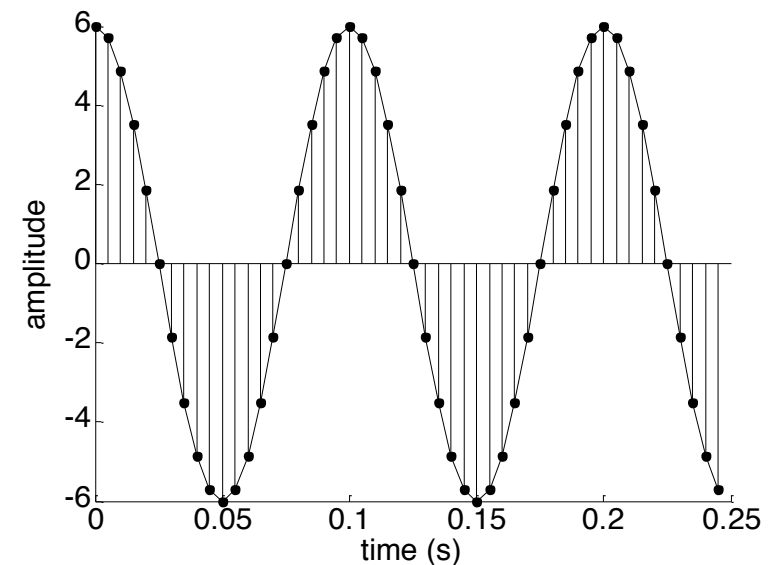
Consider an analog signal $x(t) = 6 \cos(20\pi t)$. Given a sampling rate of $f_s = 200$ Hz, find the discrete representation of the signal.

A sampling rate of $f_s = 200$ Hz corresponds to a sampling period of $T = 1/200 = 0.005$ sec.

This implies that we have a digital signal at sample index n every 0.005 s.

Sampling $x(t)$ at this period will result in

$$\begin{aligned} x[n] &= 6 \cos(20\pi \times nT) \\ &= 6 \cos(0.1\pi n) \end{aligned}$$

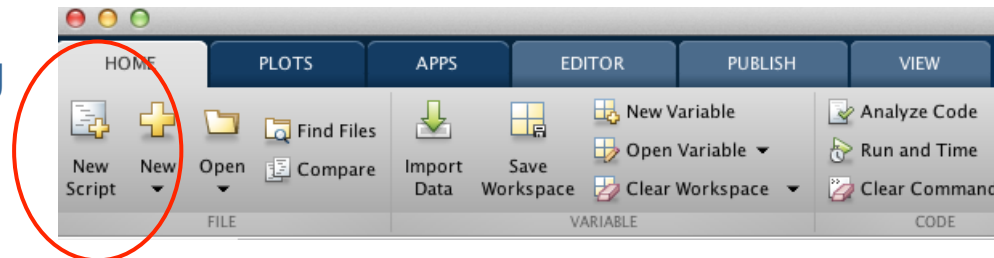


6.3 Plotting a discrete cosine wave



- Example: To plot the first 200 samples of the signal $x(t) = \cos(200\pi t)$ at a sampling rate of $f_s = 200$ Hz

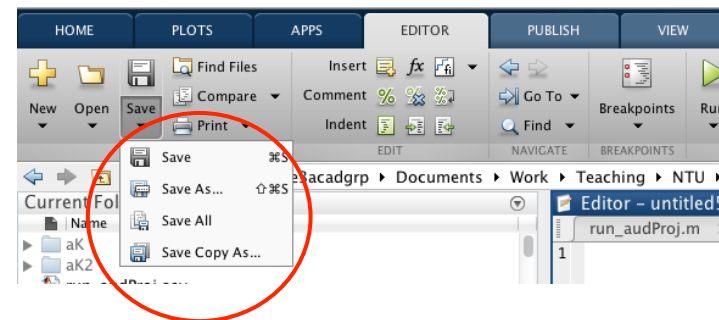
- First create the script using



- Save this script as “*run_sinegen.m*” in the desktop folder you created

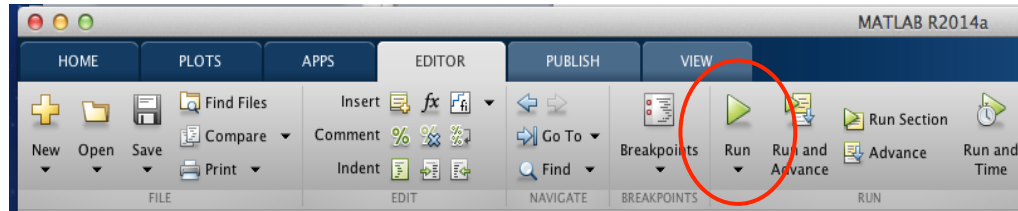
- Key in the following commands

```
>> fs = 8000;  
>> fsig = 100;  
>> nsamp = 200;  
>> t = [0:1/fs:(nsamp-1)/fs];  
>> sig = sin(2*pi*fsig*t);
```

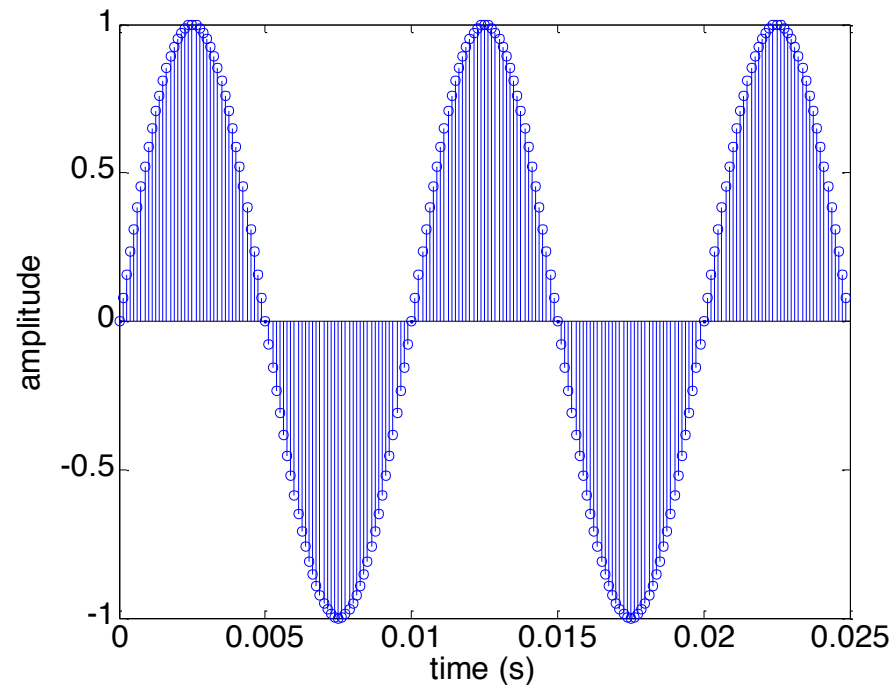


6.3 Plotting a discrete cosine wave

```
>> figure(25);  
>> stem(t,sig);  
>> xlabel('time (s)');  
>> ylabel('amplitude');
```



- Save and run this script





CHAPTER 7

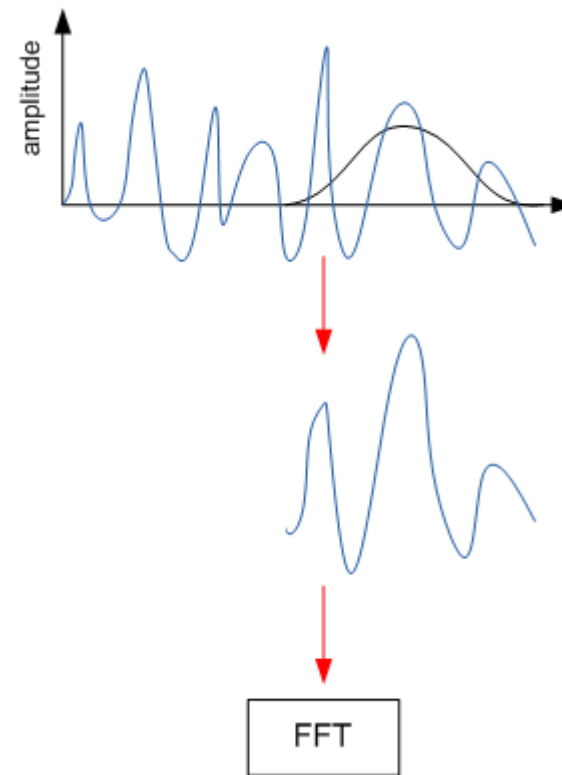
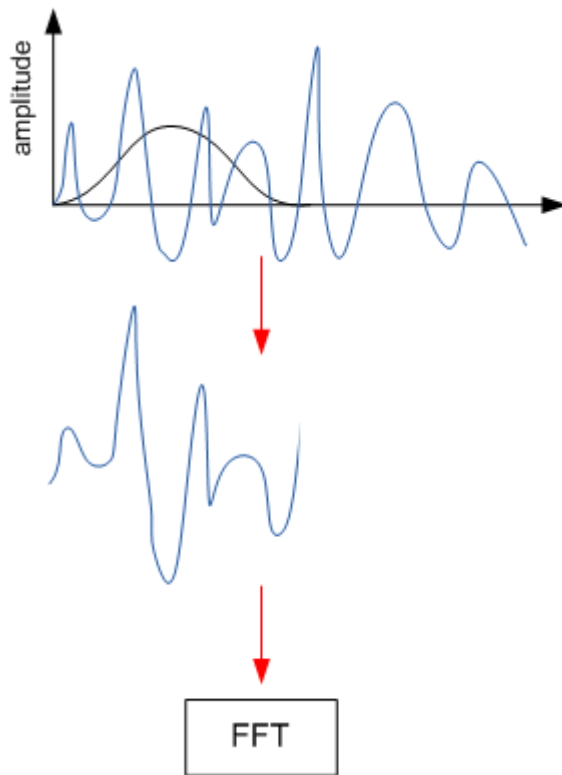
Applications

7.1 Acoustic signal processing

- It is very easy to read audio files into MatLab and process them using signal processing technique(s).
- For versions before MatLab 2012, you may read .wav files using the function “wavread()”
- For versions MatLab 2012 or later, you may read audio files using the function “audioread()”. This supports the following file formats
 - AU, SND
 - FLAC
 - OGG
 - WAV
 - MP4 and any formats supported by Microsoft Media Foundation
- You may also write a processed signal using the following functions “wavwrite()” or “audiowrite()”

7.1 Acoustic signal processing

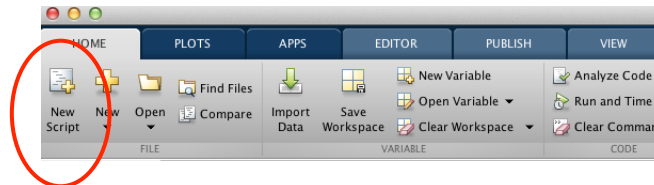
- One important tool when analyzing the audio signal is to determine how the frequency changes with time.
- This is known as the short-time Fourier transform.



7.1 Acoustic signal processing

- In this example, we will
 - ✓ generate a script,
 - ✓ read in an audio file
 - ✓ plot the signal
 - ✓ view its frequency content of the signal
- Copy the wav file “tmtw.wav” into a desktop folder.

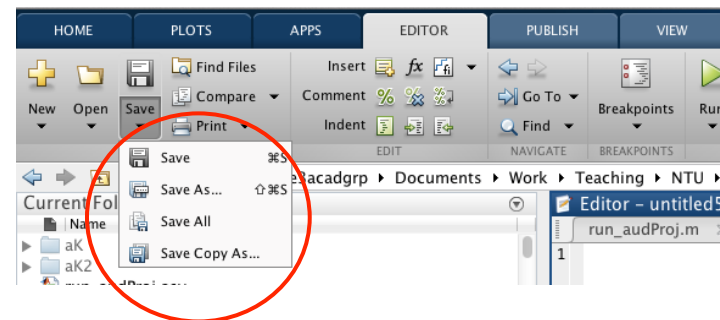
- Create a new script



- Save this script as “run_audProj.m” in the desktop folder you created

- Read the wav file

```
>> [data, fs] = wavread('tmtw');
```

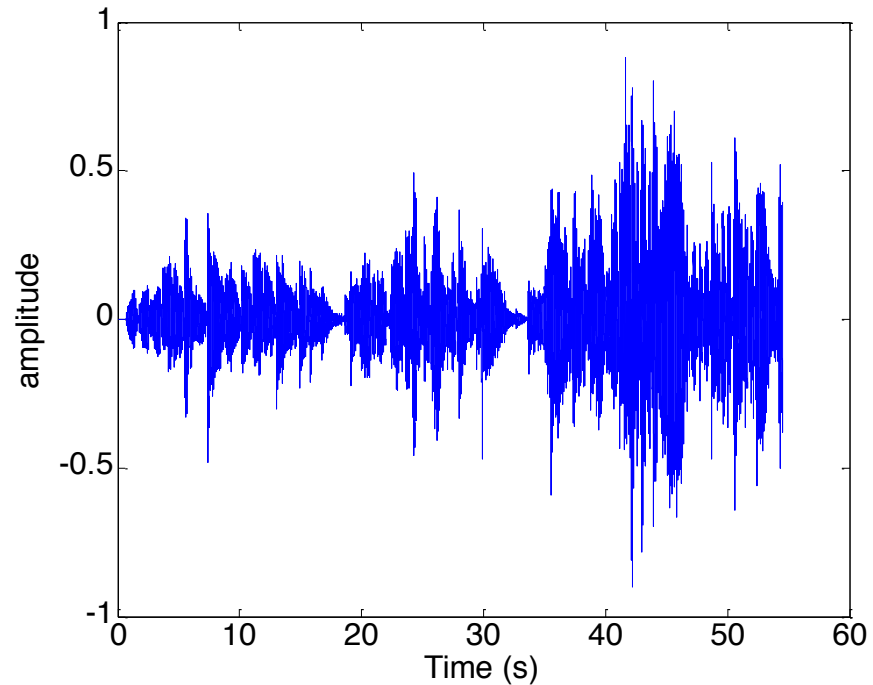


7.1 Acoustic signal processing

- Generate a vector containing the time sequence starting from 0 to the length of data minus 1. Since the sampling rate is f_s , the time step will be $1/f_s$.

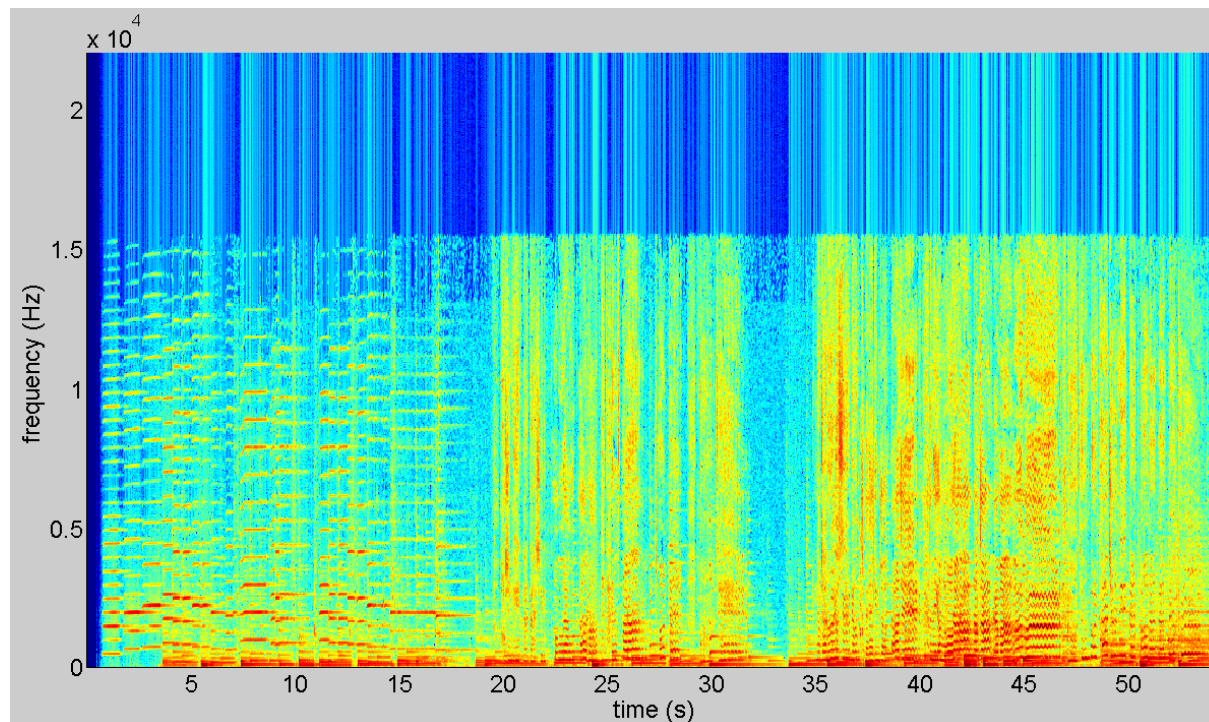
```
>> ax = [0:1/fs:(length(data)-1)/fs];
```

- We can now plot the figure



7.1 Acoustic signal processing

- Generate the spectrogram using the following



7.2 Image signal processing

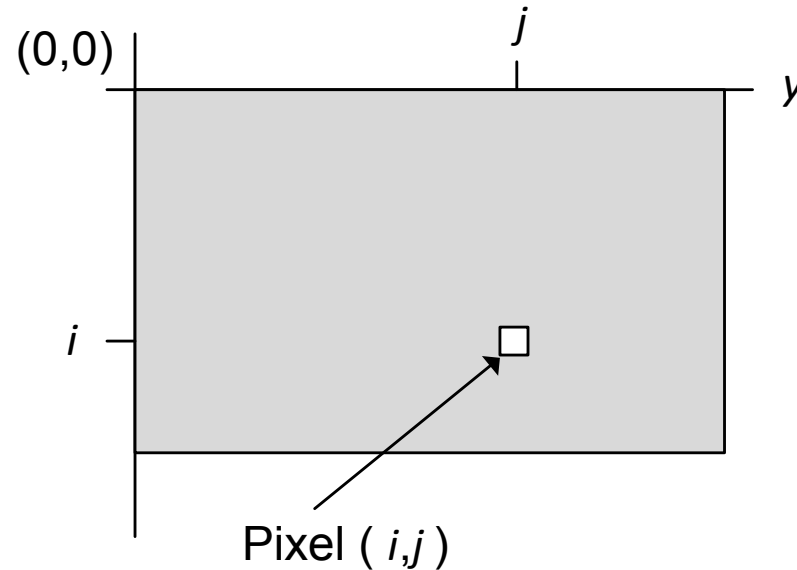
- It is very easy to read image files into MatLab and process them using signal processing technique(s).
- The function “imread()” supports the following file formats

BMP — Windows Bitmap	JPEG — Joint Photographic Experts Group	PNG — Portable Network Graphics
CUR — Cursor File	JPEG 2000 — Joint Photographic Experts Group 2000	PPM — Portable Pixmap
GIF — Graphics Interchange Format	PBM — Portable Bitmap	RAS — Sun Raster
HDF4 — Hierarchical Data Format	PCX — Windows Paintbrush	TIFF — Tagged Image File Format
ICO — Icon File	PGM — Portable Graymap	XWD — X Window Dump

- The function “imshow()” displays the image in MatLab.

7.2 Image signal processing

- An image in MatLab is treated as a matrix, i.e., every pixel is a matrix element.

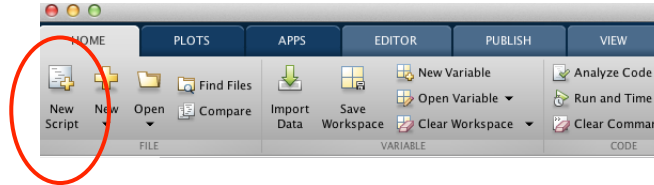


- Note that the $(0,0)$ position is located at the top-left corner of the image.

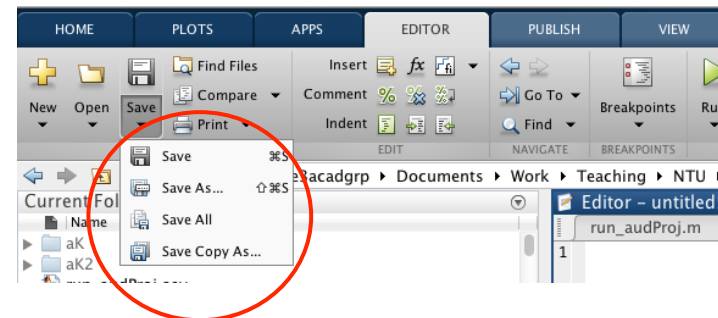
7.2 Image signal processing

- Example: We can generate a 500×500 matrix corresponding to greyscale (black-white) values via the following.

- Create the script



- Save this script as “*run_genGreyScale.m*” in the desktop folder you created



- Define the size of the matrix

```
>> size = 500;
```

- Generate a vector containing integers from 1 to 500^2 . The last element will hold the value 500^2 since, for a 500×500 matrix, there will be 500^2 pixels.

```
>> y = [1: size^2];
```

7.2 Image signal processing

- We next reshape the 1×500^2 vector into a 50×50 matrix
- `>> Y = reshape(y,size,size);`



1	501	...	249501
2	249502
...
500	500 ²

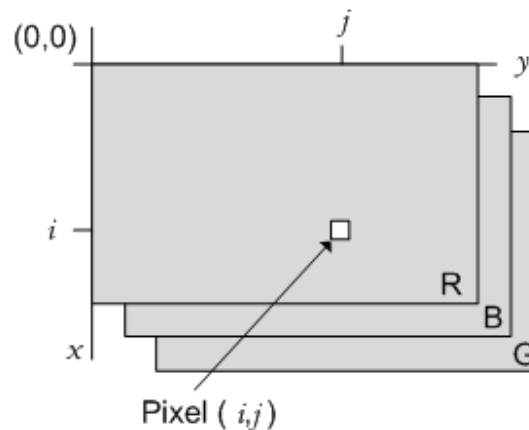
- Normalize each value by dividing all elements in the vector by the largest number, i.e., 5002. This is to ensure that the largest value in the matrix is 1.
- `>> Y = Y./Y(end);`

- We now show the image using
- `>> imshow(Y);`



7.2 Image signal processing

- Images, in general, are not greyscale, i.e., its values do not vary between 0 and 1.
- True color images comprise of RGB values.

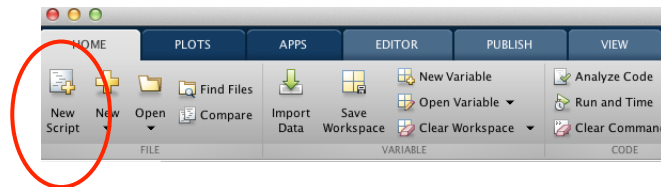


- The function “`imread()`” for true color image will therefore result in a 3D matrix with the 3rd dimension corresponding to the RGB values.
- <http://web.njit.edu/~kevin/rgb.txt.html>

7.2 Image signal processing

- In this example, we will
 - ✓ generate a script,
 - ✓ read in an image file
 - ✓ show the image on MatLab
 - ✓ adjust its RBG values
- Copy the jpg file “zoo.jpg” into a desktop folder.

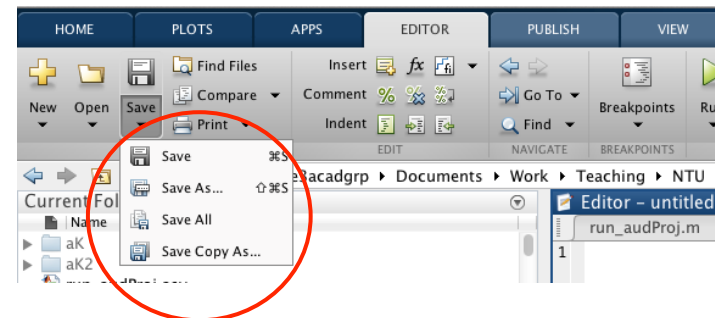
- Create the script using



- Save this script as “*run_imgProj.m*” in the desktop folder you created

- Read the image file

```
>> image = imread('zoo.jpg');
```





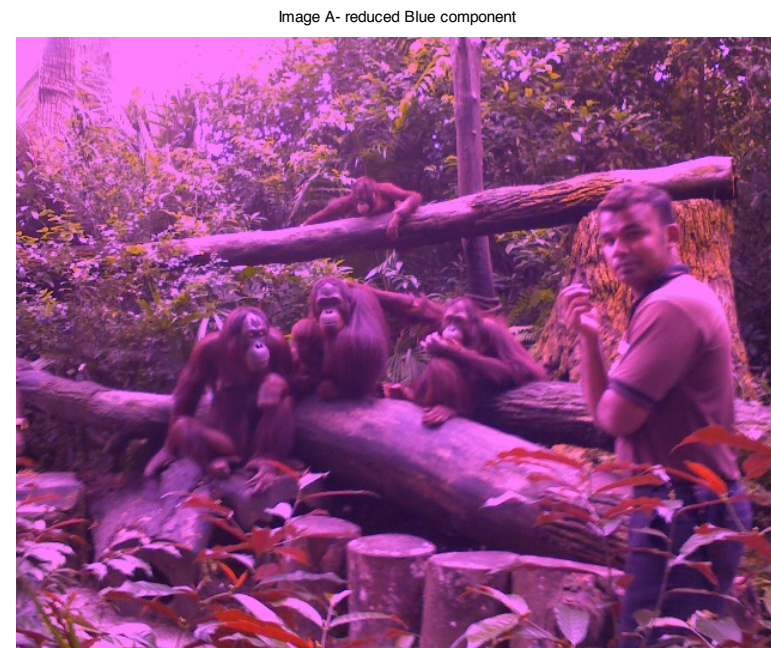
- Plot the image file

```
>> figure(32);  
>> imshow(image);  
>> title('original image');
```
- To reduce the blue component, we first create a dummy variable and equate it to the original image

```
>> imageA = image;
```
- Next we change the blue component by changing the 2nd component of “imageA”

```
>> imageA(:,:,2)= 0.5*imageA(:,:,2);  
>> figure(34)  
>> imshow(imageA);  
>> title('Image A- reduced Blue component');
```


7.1 Acoustic signal processing





धन्यवाद

Merci

谢谢



Gracias

Obrigado!

Ευχαριστώ

شكراً