

$$v_1 = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$$

$$v_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$v_3 = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}$$

$$w_1 = \frac{1}{\sqrt{5}} \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$$

$$w_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\begin{aligned} w_3 &= \text{normalised} \left(\begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} - \frac{3}{\sqrt{5}} \frac{1}{\sqrt{5}} \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} - 2 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right) \\ &= \text{normalised} \left(\begin{bmatrix} 1 \\ \frac{2}{5} \\ 0 \end{bmatrix} \right) = \frac{1}{\sqrt{5}} \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} \end{aligned}$$

$$\therefore Q = \begin{bmatrix} \frac{2}{\sqrt{5}} & 0 & -\frac{1}{\sqrt{5}} \\ \frac{1}{\sqrt{5}} & 0 & \frac{2}{\sqrt{5}} \\ 0 & 1 & 0 \end{bmatrix}$$

$$A = QR$$

$$\Rightarrow R = Q^{-1}A = Q^t A$$

$$\therefore R = \begin{bmatrix} \frac{2}{\sqrt{5}} & 0 & -\frac{1}{\sqrt{5}} \\ \frac{1}{\sqrt{5}} & 0 & \frac{2}{\sqrt{5}} \\ 0 & 1 & 0 \end{bmatrix}^T \begin{bmatrix} 2 & 0 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} & 0 \\ 0 & 0 & 1 \\ -\frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} & 0 \end{bmatrix} \begin{bmatrix} 2 & 0 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix}$$

$$= \begin{bmatrix} \sqrt{5} & 0 & \frac{3}{\sqrt{5}} \\ 0 & 1 & \frac{2}{\sqrt{5}} \\ 0 & 0 & \frac{1}{\sqrt{5}} \end{bmatrix}$$

$$1. \quad A x = b = [0 \ 3 \ -3]^t$$

$$\Rightarrow Q R x = b$$

$$\Rightarrow R x = Q^{-1} b = Q^t b$$

2 skipping

$$3 \quad A|_U = \text{id}_U, \quad A(U^\perp) \subset U^\perp,$$

$A|_{U^\perp}$ has 0 as the only fixed point

think of eigenvalues and eigenspace
is there an eigenspace that would
solve this?

let $u \in U^\perp$
show $A(u) \in U^\perp$

if $A(u) = u$, then $u = 0$

suppose another subspace V exists
 $\Rightarrow V \subseteq U$

$$V \subseteq U$$

$$4. \quad \langle f, g \rangle = \int_{-1}^1 f(x) g(x) dx$$

consider the functional, $\varphi : V \rightarrow \mathbb{R}$
 $f \sim f(0)$

show that $\exists g$ such that $\forall f$,
 $\varphi(f) = \langle f, g \rangle$

proof by contradiction. Assume g exists.

choose different functions f that give
 more ideas.

$$\begin{aligned} f &\equiv 1 \\ \Rightarrow \int_{-1}^1 g(x) dx &= \langle f, g \rangle = f(0) = 1 \end{aligned}$$

\exists some interval U_0 where $g(U_0) > 0$

you need another function h

shrink U_0 to some $U_1 \subseteq U_0$ such
that $0 \in U_1$

does this give you a hint of
what you can define as h .
drawing helps!

$$5. a \quad \delta : V \longrightarrow V^* \\ v \longmapsto \langle v, \cdot \rangle$$

δ is an isometry for the inner product $\langle \cdot, \cdot \rangle^*$ \Leftrightarrow

$$\forall v, w \in V, \quad \langle \delta(v), \delta(w) \rangle^* = \langle v, w \rangle$$

$$\langle \lambda, \mu \rangle^* = \langle \delta^{-1}(\lambda), \delta^{-1}(\mu) \rangle$$

why is this valid and unique

b) Digression : From last class, remember example

$$\begin{aligned} \langle f, g \rangle &= \int_0^\infty f(x) g(x) e^{-x} dx \\ &= c_f^t A c_g \end{aligned}$$

Let $\langle v_1, v_2, \dots, v_n \rangle$ be a basis for V .

$$\langle \delta(v_1), \delta(v_2), \dots, \delta(v_n) \rangle$$

- is this a basis for V^*

$$a_{ij} = \langle v_i, v_j \rangle \quad \text{where} \quad A = \{a_{ij}\}$$

$$a_{ij}^* = \langle \delta(v_i), \delta(v_j) \rangle^* \quad \text{where} \quad A^* = \{a_{ij}^*\}$$

Expand A^* in terms of A by
expanding δ and using
the definition of \langle, \rangle^*

Rough Notes

$$A \in GL_n(\mathbb{R})$$

$$A = QR, \quad Q \in O(n), \quad R \in M_{n \times n}(\mathbb{R})$$

upper triangular

$\langle v_1, v_2, \dots, v_n \rangle$ is a basis for A

$$v_1 = \text{proj}_{W_1}(v_1) = \langle w_1, v_1 \rangle w_1$$

$$v_2 = \text{proj}_{W_1}(v_2) + \text{proj}_{W_2}(v_2)$$

$$= \langle w_1, v_2 \rangle w_1 + \langle w_2, v_2 \rangle w_2$$

$$v_n = \sum_j \langle w_j, v_n \rangle w_j$$

$$v_2 = \begin{bmatrix} w_1 & w_2 \end{bmatrix} \begin{bmatrix} \langle w_1, v_2 \rangle \\ \langle w_2, v_2 \rangle \end{bmatrix}$$

$$Q = \begin{bmatrix} u_1 & u_2 & \dots & u_n \end{bmatrix}$$

$$R = \begin{bmatrix} \langle u_1, v_1 \rangle & \langle u_1, v_2 \rangle & \langle u_1, v_3 \rangle & \dots \\ & \langle u_2, v_2 \rangle & \langle u_2, v_3 \rangle & \dots \\ & & \langle u_3, v_3 \rangle & \dots \\ & & & \ddots \end{bmatrix}$$

$$A = QR$$

$$Q \in O(n)$$

$$Q^{-1} \in O(n)$$

$$V^* = \text{Hom}(V, K)$$

$$\phi_v(\cdot) = \langle \cdot, v \rangle$$

$$\text{Let } \phi \in V^*$$

$$\text{Then } \phi = \phi_v \text{ for some } v \in V$$

$$\phi_u(\cdot) + \phi_v(\cdot) = \phi_{u+v}(\cdot)$$

$$\alpha \phi_u(\cdot) = \phi_{\alpha u}(\cdot)$$

$$\langle e_1, e_2, \dots, e_n \rangle \text{ basis for } V$$

$$v = \sum_j \langle v, e_j \rangle e_j$$

$$\begin{aligned}
\phi(v) &= \phi\left(\sum_j \langle v, e_j \rangle e_j\right) \\
&= \sum_j \phi(e_j) \langle v, e_j \rangle \\
&= \langle v, \sum_j \phi(e_j) e_j \rangle \\
&= \phi_v(v)
\end{aligned}$$

$$\text{where } v = \sum_j \phi(e_j) e_j$$