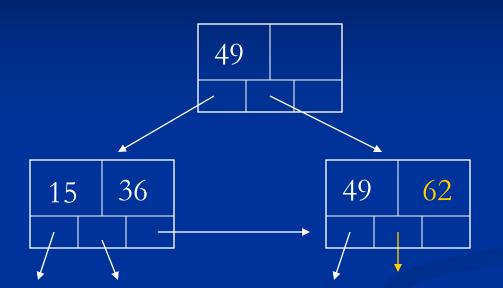
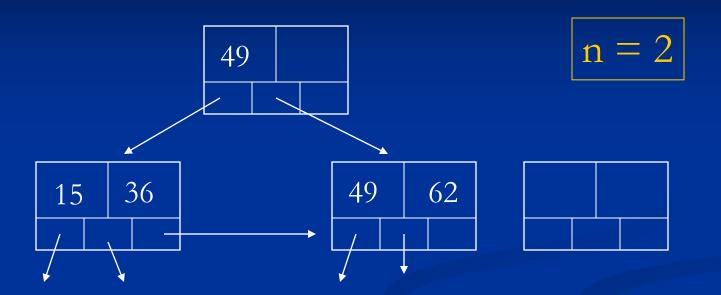
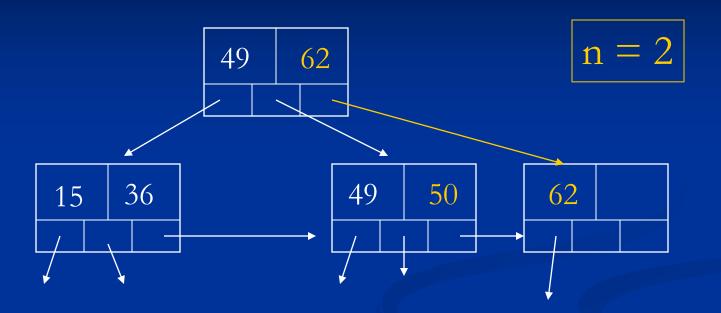


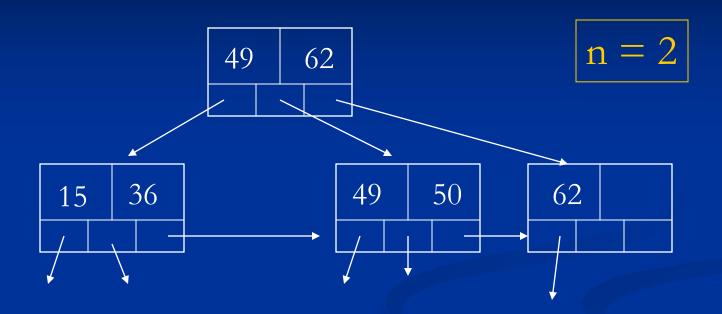
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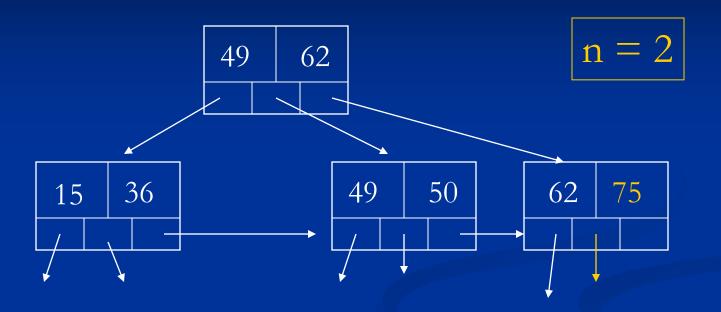


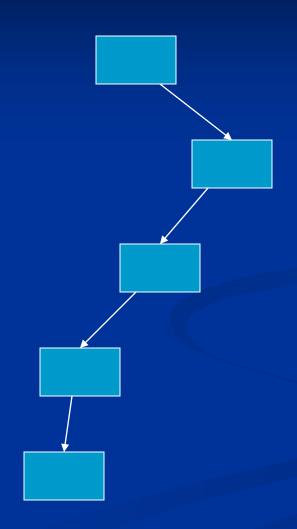
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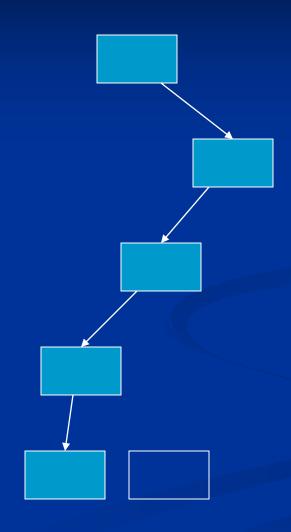


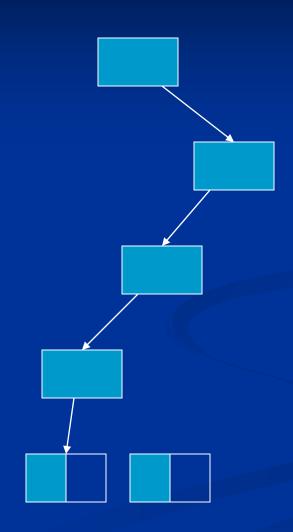


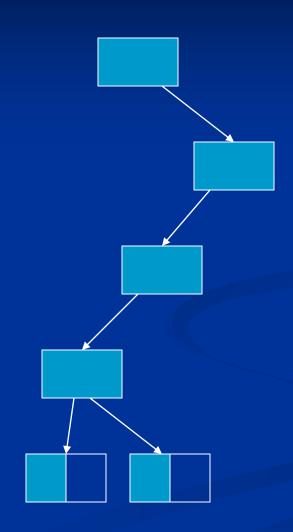


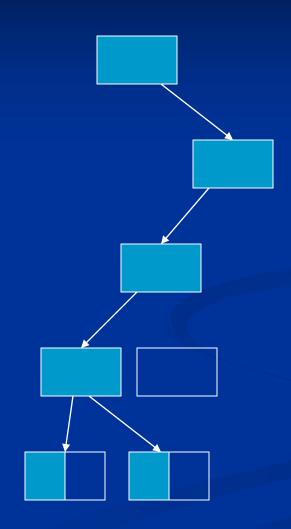


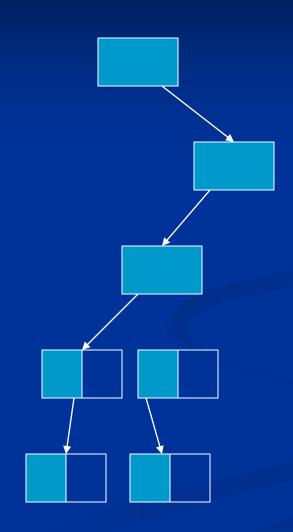


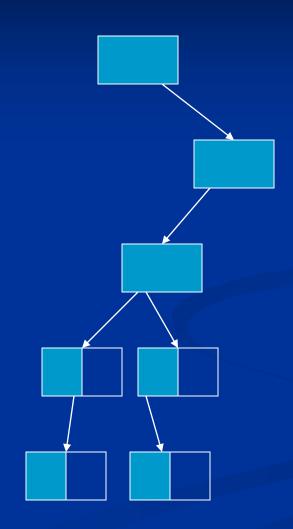


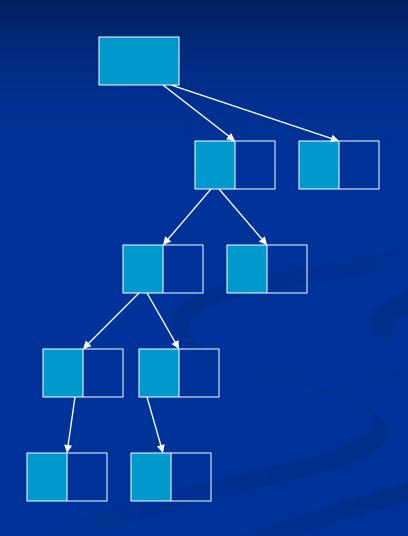


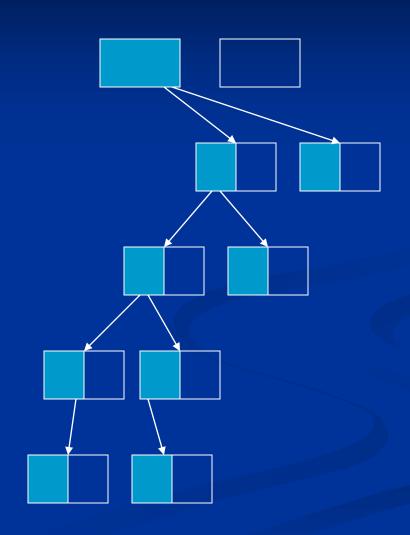


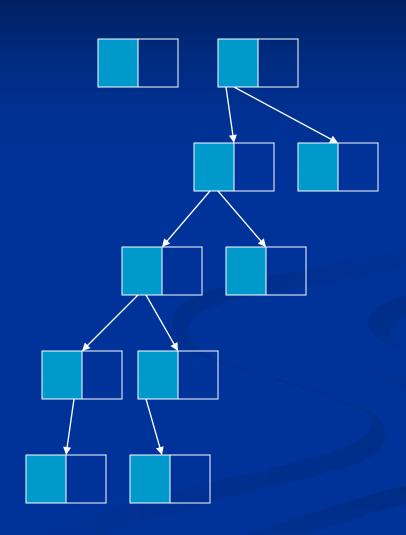


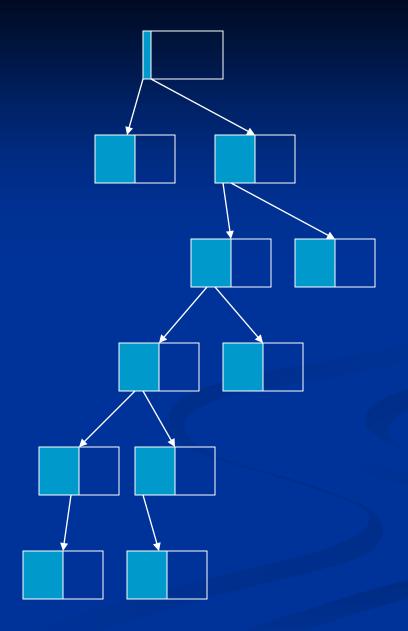








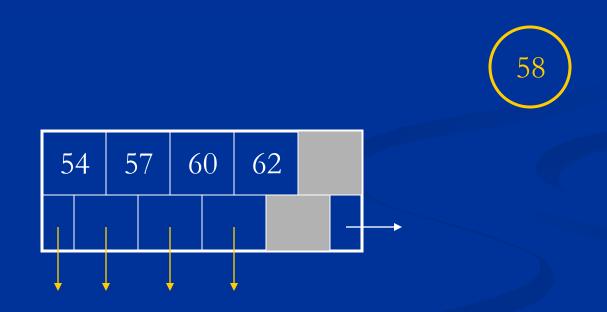




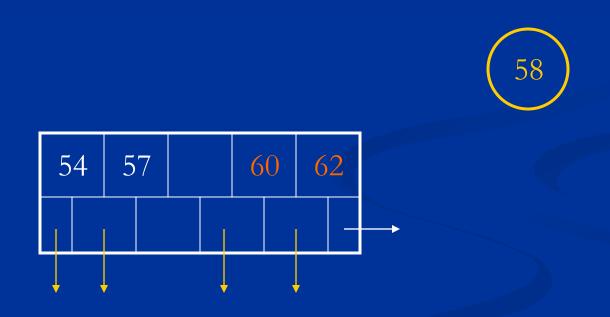
Insertion: Primitives

- Inserting into a leaf node
- Splitting a leaf node
- Splitting an internal node
- Splitting root node

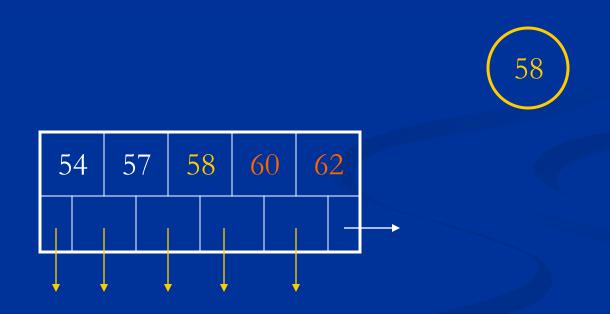
Inserting into a Leaf Node

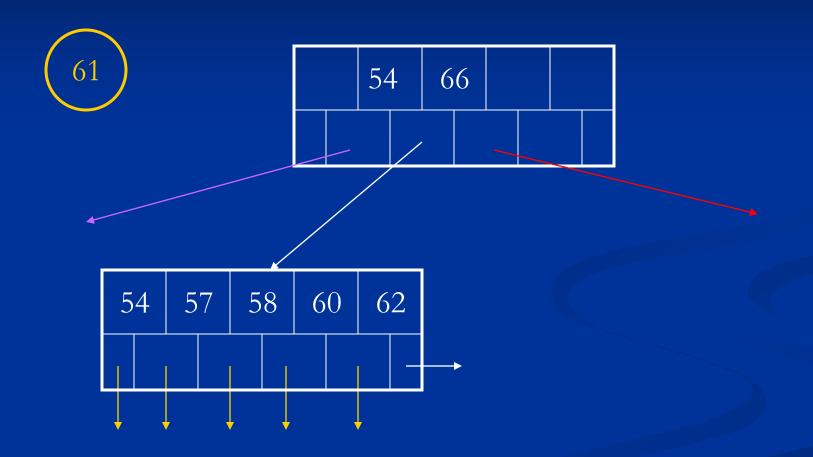


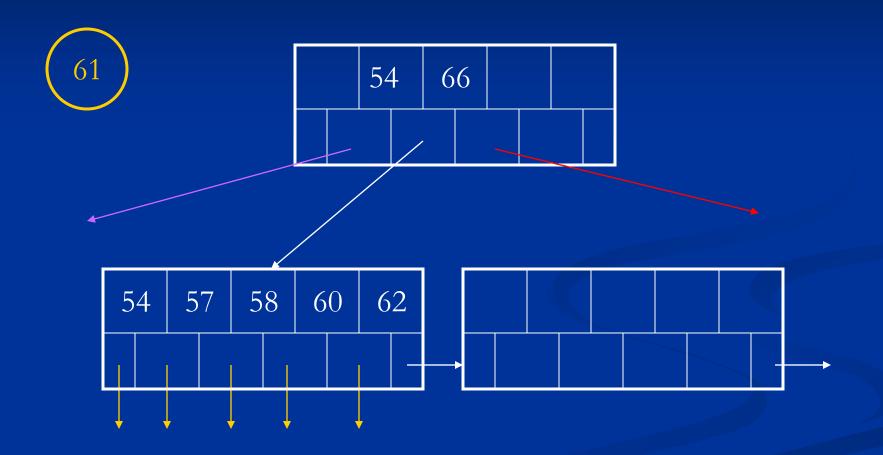
Inserting into a Leaf Node

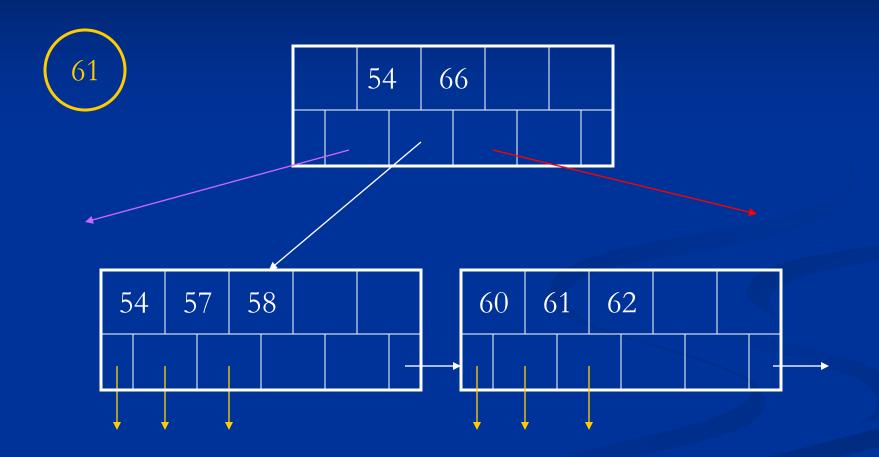


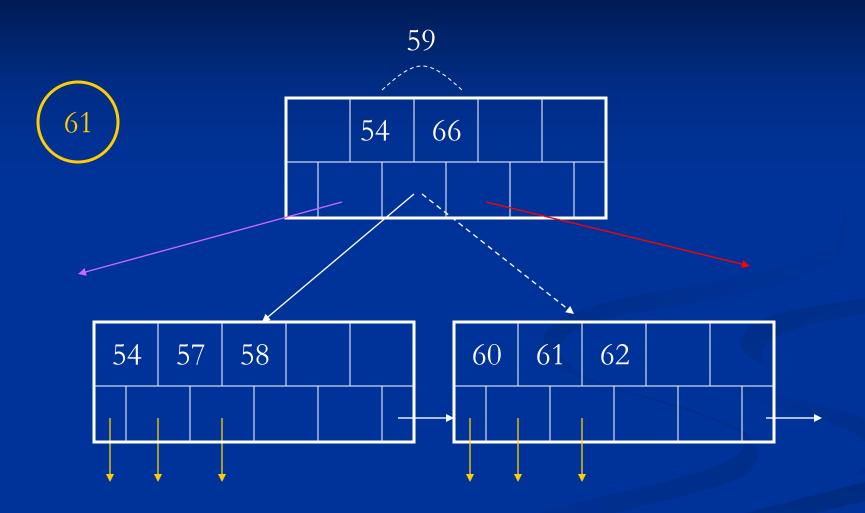
Inserting into a Leaf Node

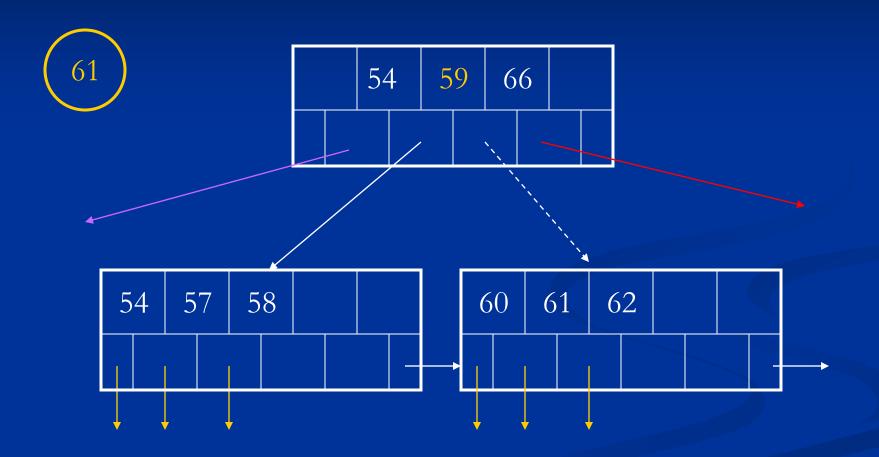




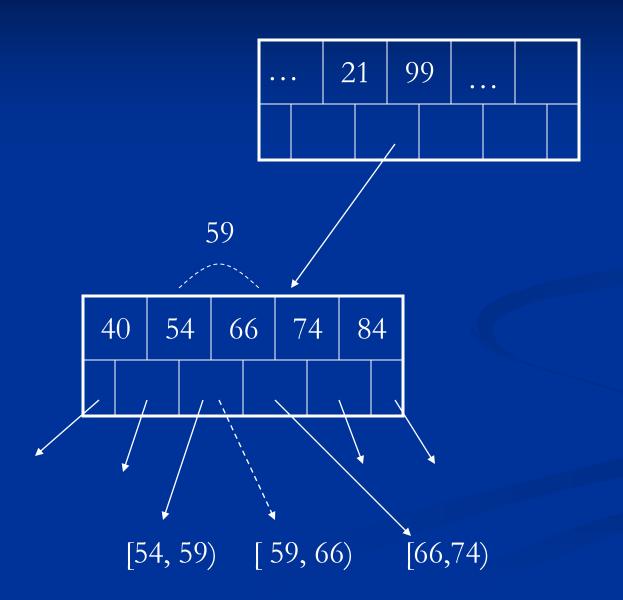




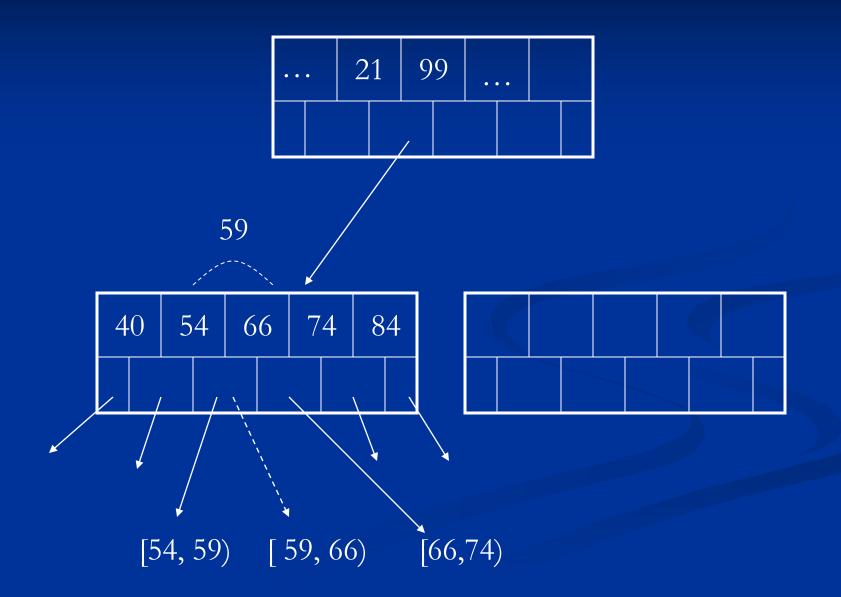




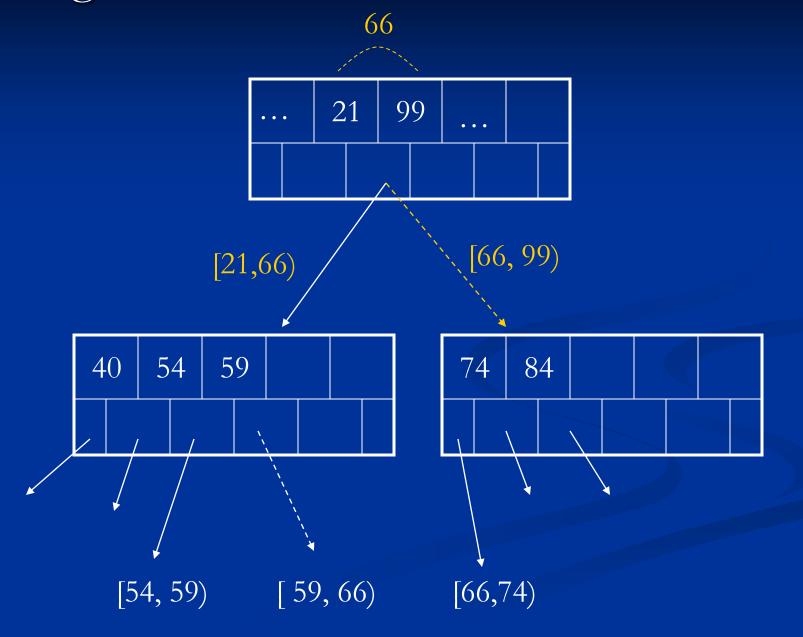
Splitting an Internal Node



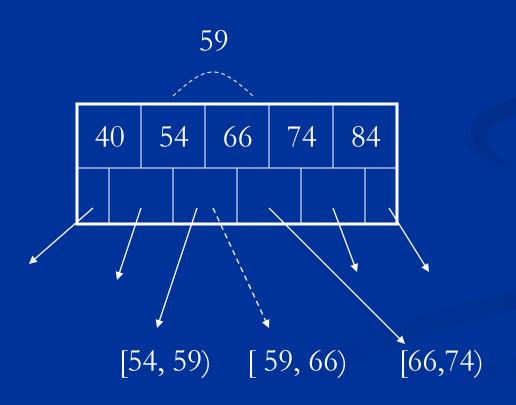
Splitting an Internal Node



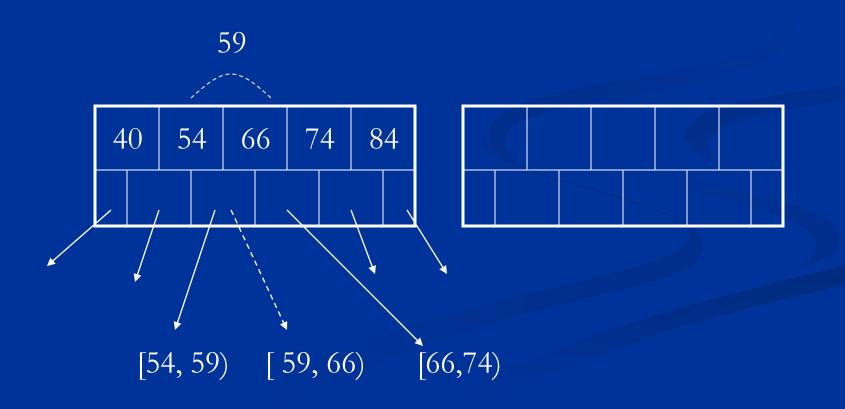
Splitting an Internal Node



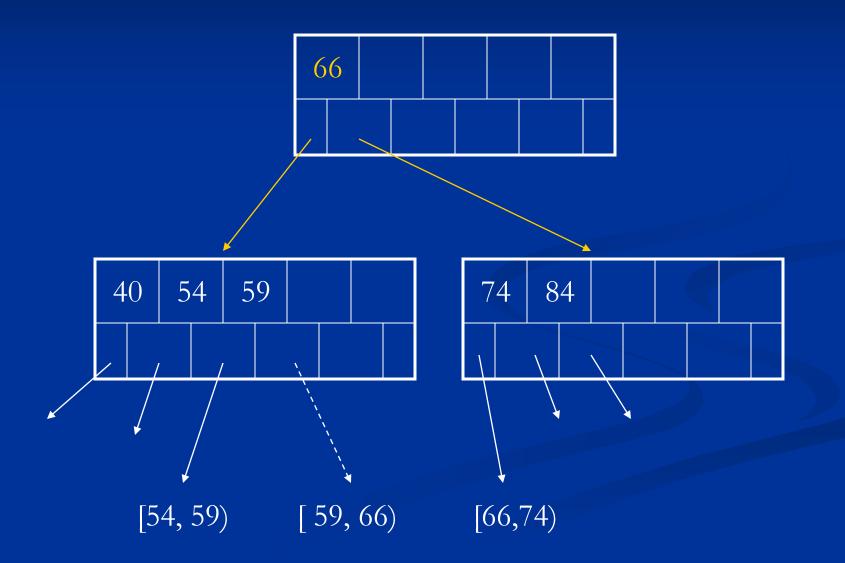
Splitting the Root



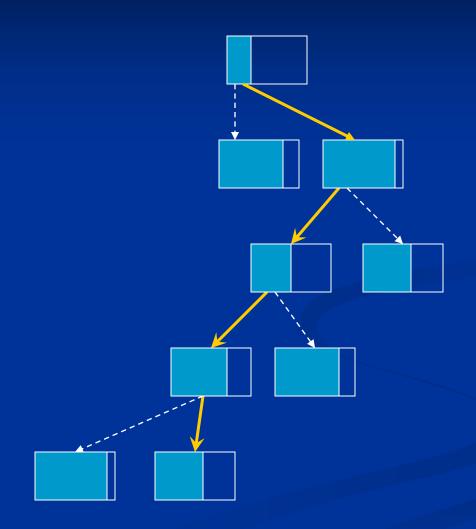
Splitting the Root



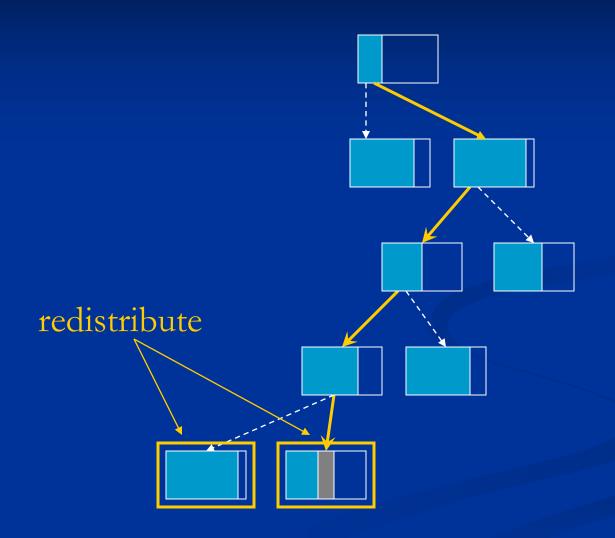
Splitting the Root



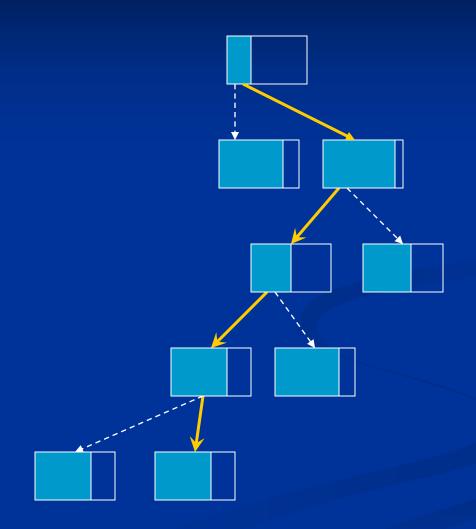
Deletion



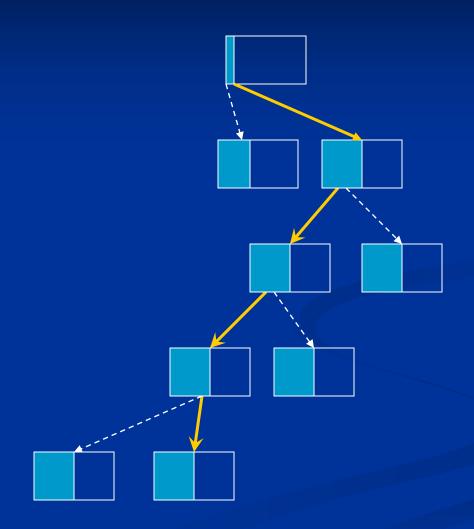
Deletion

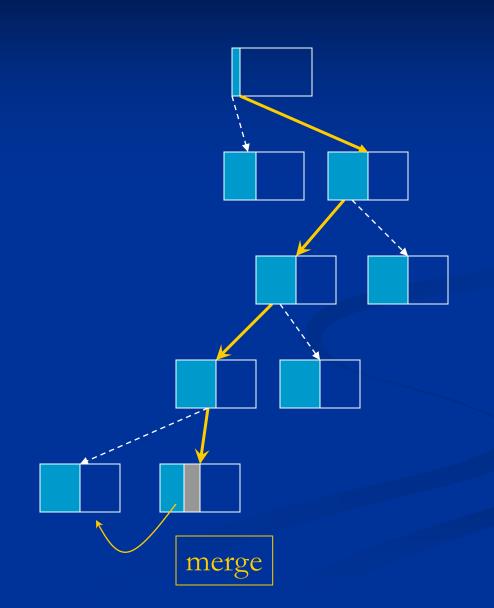


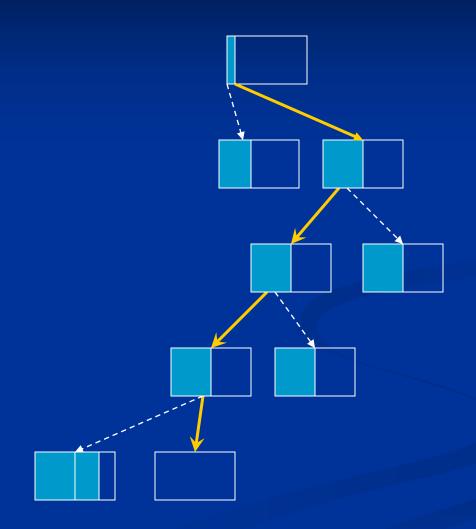
Deletion

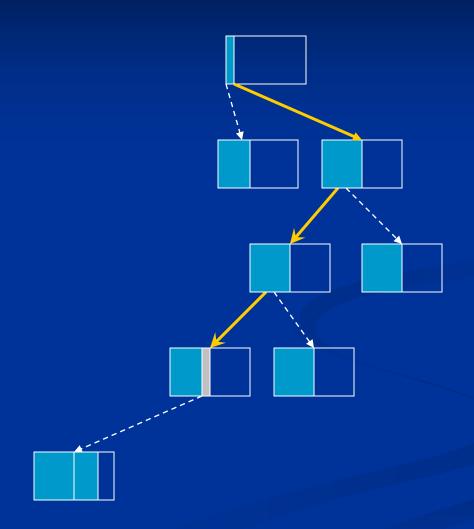


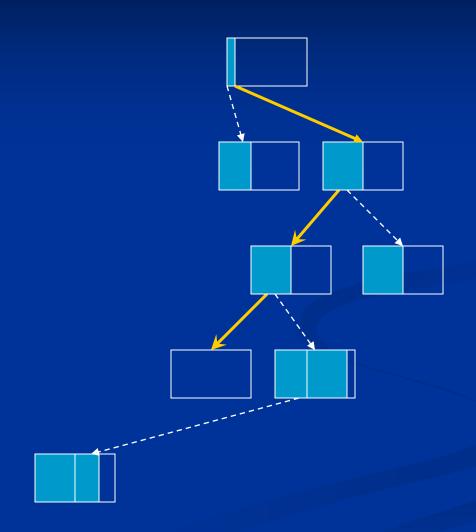
Deletion - II

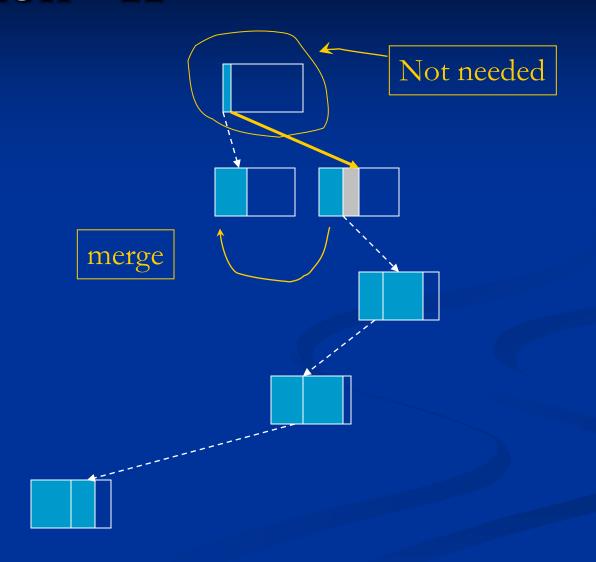


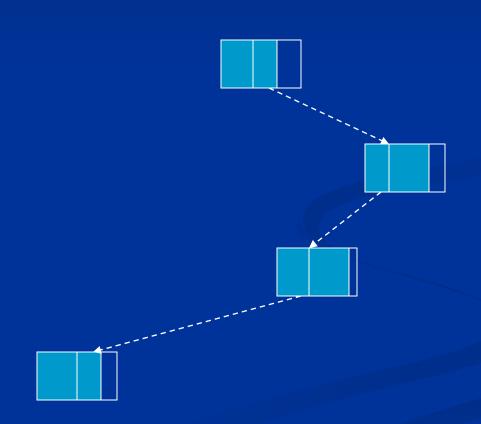






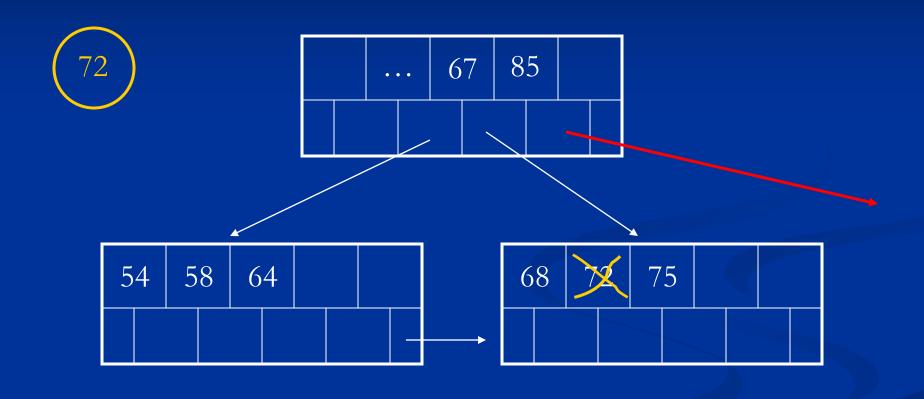


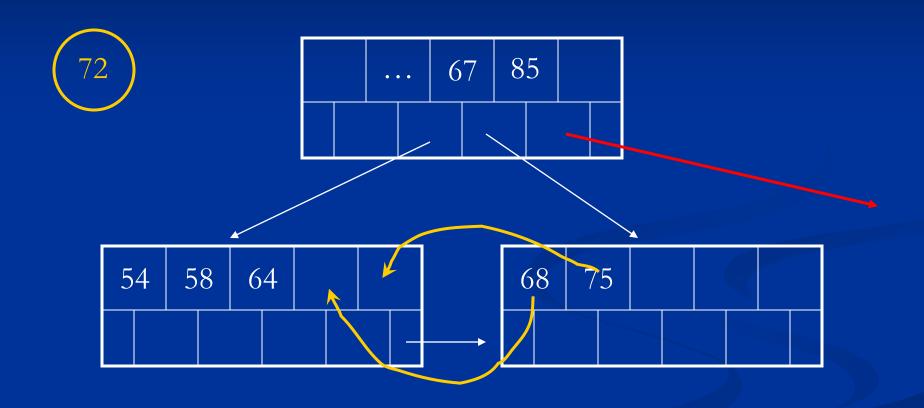


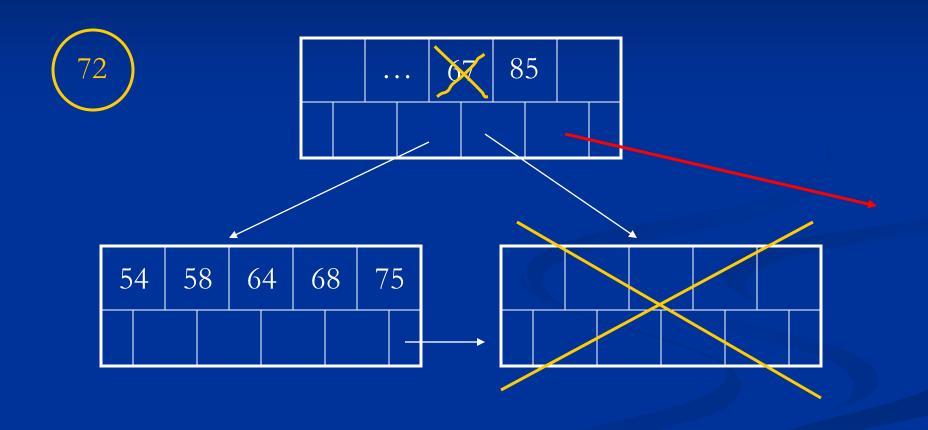


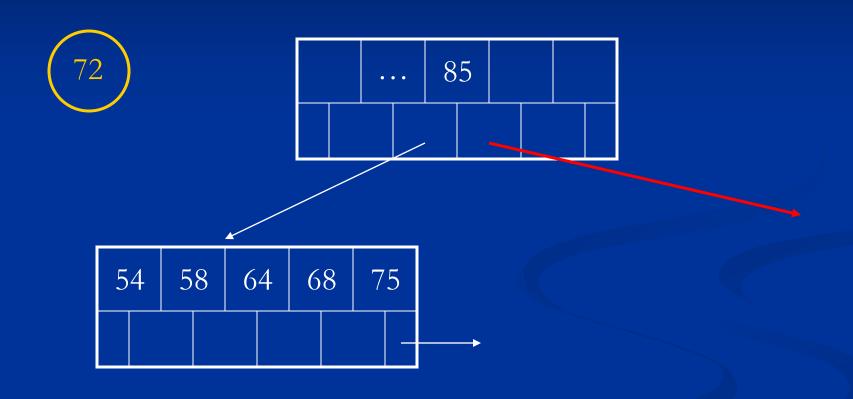
Deletion: Primitives

- Delete key from a leaf
- Redistribute keys between sibling leaves
- → Merge a leaf into its sibling
 - Redistribute keys between two sibling internal nodes
- → Merge an internal node into its sibling

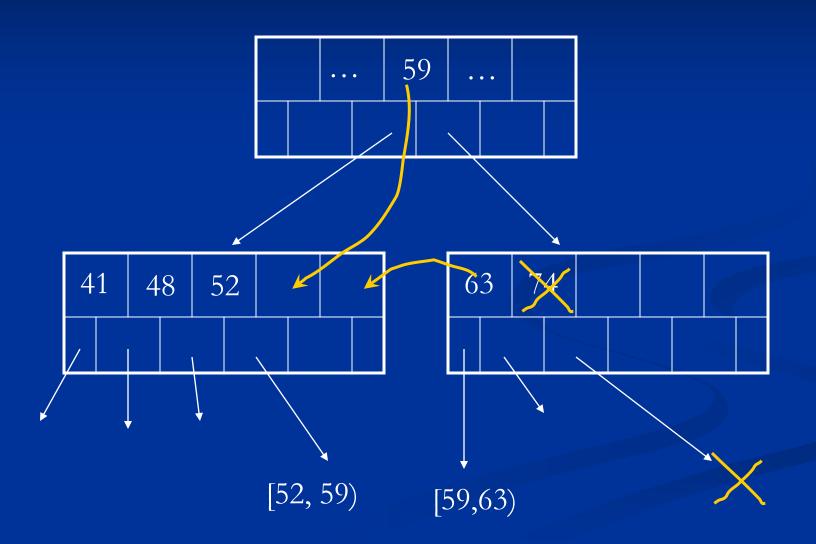




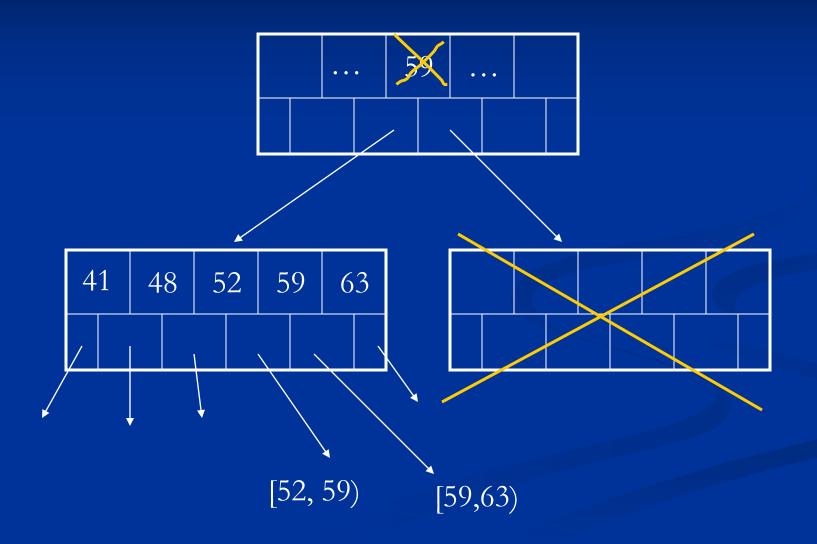




Merge Internal Node into Sibling



Merge Internal Node into Sibling

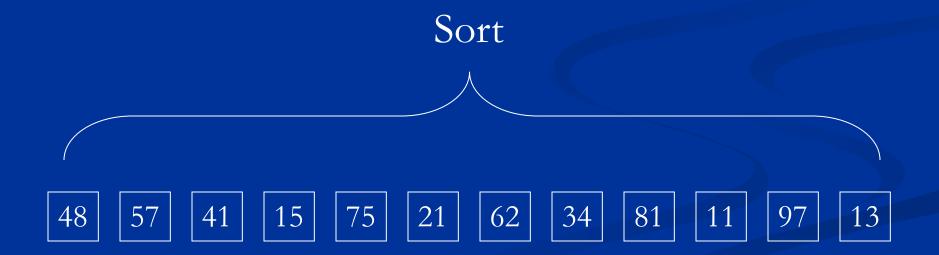


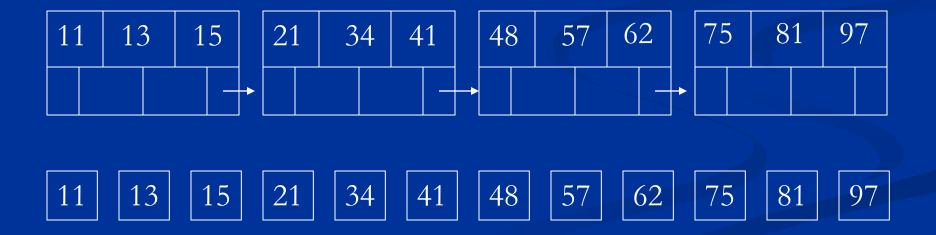
B-Tree Roadmap

- B-Tree
 - Recap
 - Insertion (recap)
 - Deletion
- Construction
 - Efficiency
 - B-Tree variants
 - Hash-based Indexes

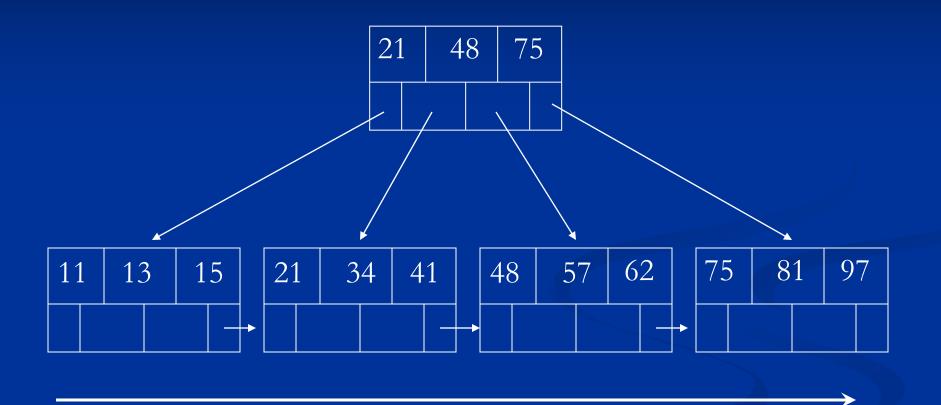
Question

How does insertion-based construction perform?





Scan



Scan

Why is sort-based construction better than insertion-based one?

Cost of B-Tree Operations

- Height of B-Tree: H
- Assume no duplicates
- Question: what is the random I/O cost of:
 - Insertion:
 - Deletion:
 - Equality search:
 - Range Search:

Height of B-Tree

- Number of keys: N
- B-Tree parameter: n

Height
$$\approx \log_n N = \frac{\log N}{\log n}$$

In practice: 2-3 levels

Question: How do you pick parameter n?

- 1. Ignore inserts and deletes
- 2. Optimize for equality searches
- 3. Assume no duplicates

Roadmap

- B-Tree
- B-Tree variants
 - Sparse Index
 - Duplicate Keys
- Hash-based Indexes

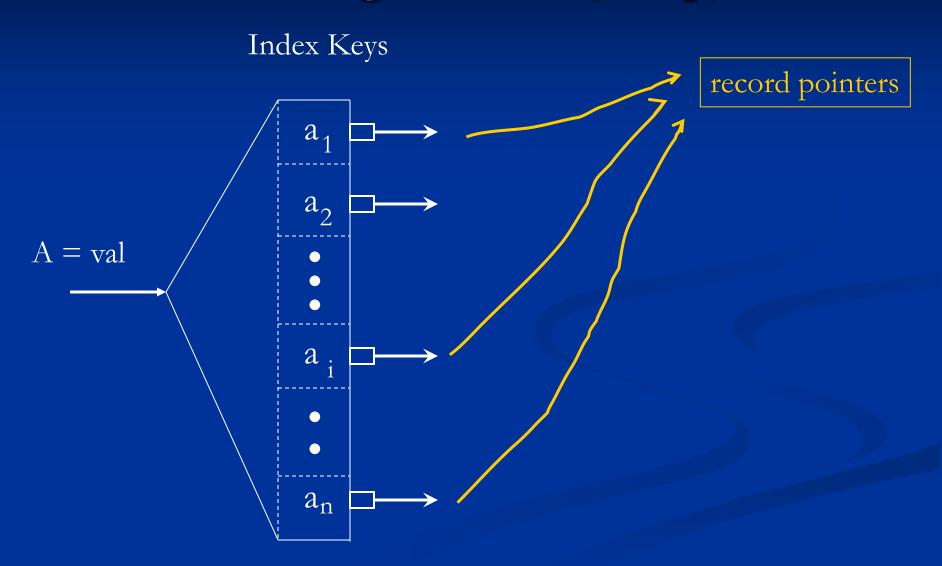
Roadmap

- B-Tree
- B-Tree variants
- Hash-based Indexes
- Static Hash Table
- Extensible Hash Table
- Linear Hash Table

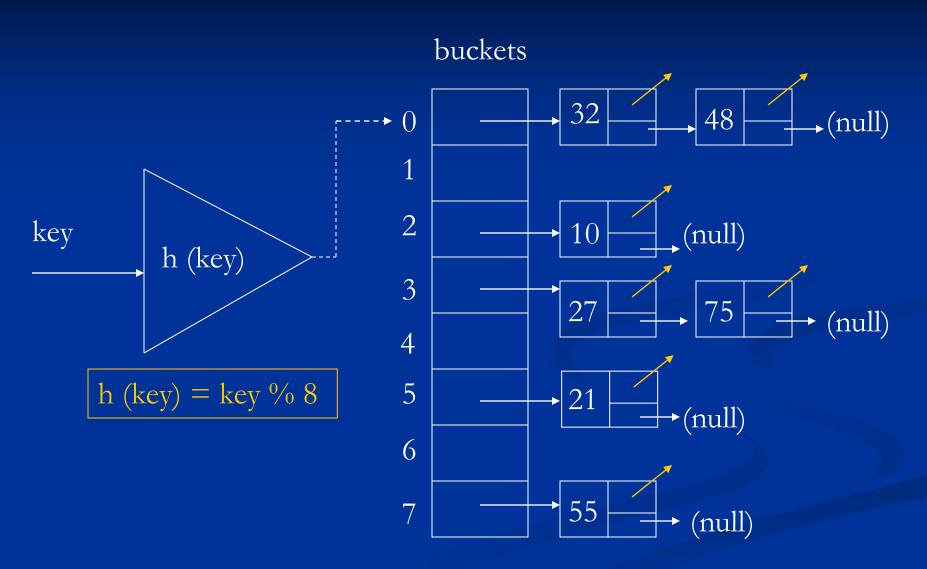
Hash-Based Indexes

- Adaptations of main memory hash tables
- Support equality searches
- No range searches

Indexing Problem (recap)



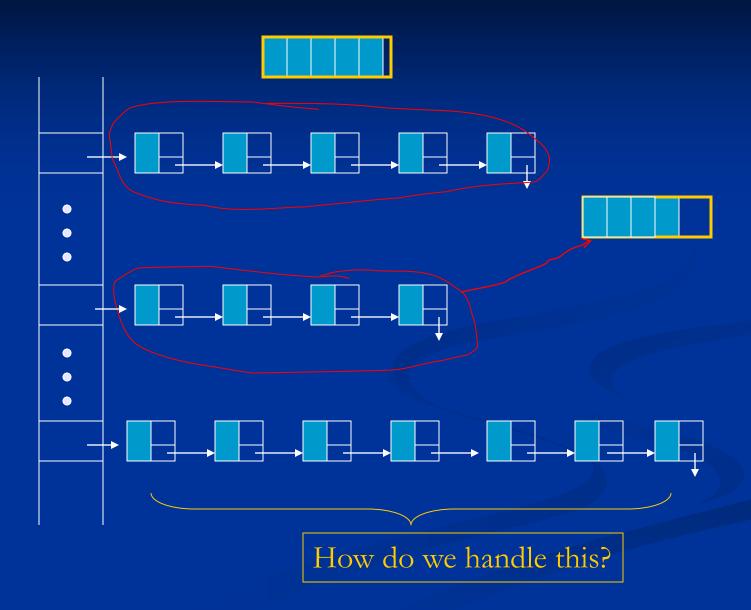
Main Memory Hash Table



Adapting to disk

- 1 Hash Bucket = 1 Block
 - All keys that hash to bucket stored in the block
 - Intuition: keys in a bucket usually accessed together
 - No need for linked lists of keys ...

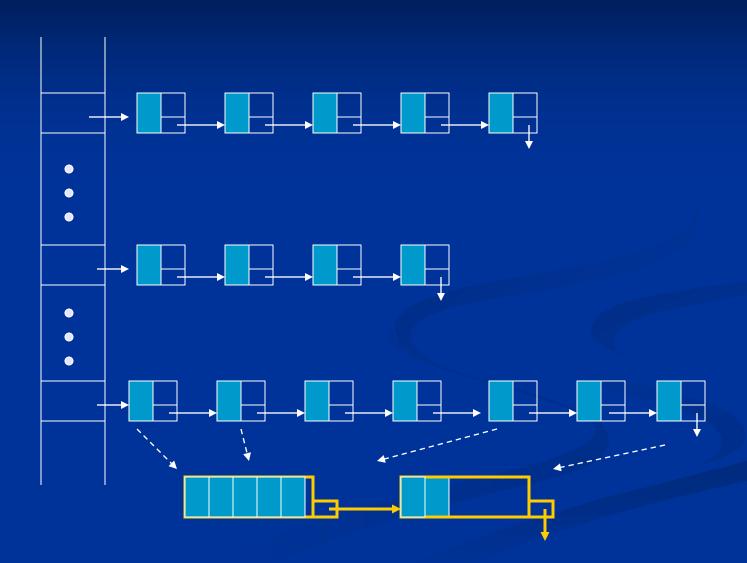
Adapting to Disk



Adapting to disk

- 1 Hash Bucket = 1 Block
 - All keys that hash to bucket stored in the block
 - Intuition: keys in a bucket usually accessed together
 - No need for linked lists of keys ...
 - ... but need linked list of blocks (overflow blocks)

Adapting to Disk



Adapting to disk

- Bucket Id → Disk Address mapping
 - Contiguous blocks
 - Store mapping in main memory
 - ■Too large?
 - Dynamic → Linear and Extensible hash tables

Beware of claims that assume 1 I/O for hash tables and 3 I/Os for B-Tree!!