

COMP9418: Advanced Topics in Statistical Machine Learning

Variable Elimination

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Instructor: Gustavo Batista

University of New South Wales

Introduction

- This lecture introduces one of the simplest methods for inference
 - It is based on the principle of variable elimination
 - We successively remove variables from the Bayesian network, maintaining its ability to answer queries of interest
- In previous lectures we identified four types of queries
 - Probability of evidence, prior and posterior marginals, MPE and MAP
 - Variable elimination can be used to answer all these types of queries
 - But we will leave MPE and MAP to a future lecture on this topic
- We will discuss the algorithm of variable elimination
 - Its complexity and how to make it more efficient
 - How to implement it in the tutorials
 - Its variants such as bucket elimination

Process of Elimination

- Given this Bayesian network

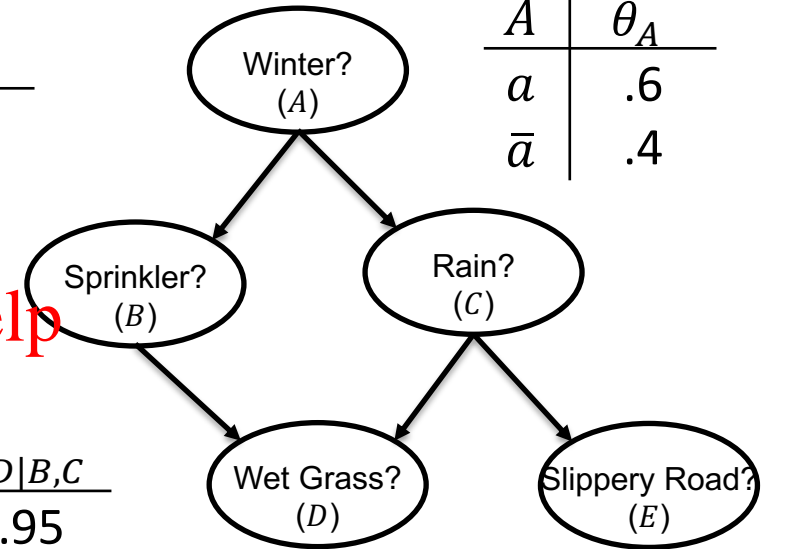
- We are interested in computing the marginal $P(D, E)$

D	E	$P(D, E)$
d	e	.30443
d	\bar{e}	.39507
\bar{d}	e	.05957
\bar{d}	\bar{e}	.24093

- The variable elimination (VE) algorithm,

- Sums out variable A , B and C to construct a marginal over D and E

A	B	$\theta_{B A}$
a	b	.2
a	\bar{b}	.8
\bar{a}	b	.75
\bar{a}	\bar{b}	.25



A	θ_A
a	.6
\bar{a}	.4

B	C	D	$\theta_{D B,C}$
b	c	d	.95
b	c	\bar{d}	.05
b	\bar{c}	d	.9
b	\bar{c}	\bar{d}	.1
\bar{b}	c	d	.8
\bar{b}	c	\bar{d}	.2
\bar{b}	\bar{c}	d	0
\bar{b}	\bar{c}	\bar{d}	1

C	E	$\theta_{E C}$
c	e	.7
c	\bar{e}	.3
\bar{c}	e	0
\bar{c}	\bar{e}	1

A	C	$\theta_{C A}$
a	c	.8
a	\bar{c}	.2
\bar{a}	c	.1
\bar{a}	\bar{c}	.9

Process of Elimination

- Consider the joint distribution over all variables. To sum out variable A

- Merge all rows that agree on values of B, C, D , and E

A	B	C	D	E	$P(.)$
a	b	c	d	e	.06384
\bar{a}	b	c	d	e	.01995

- Into a single row

B	C	D	E	$P(.)$
b	c	d	e	.08379 = .06384 + .01995

- Resulting in a table with 16 rows that do not mention variable A

A	B	C	D	E	$P(.)$
a	b	c	d	e	.06384
a	b	c	d	\bar{e}	.02736
a	b	c	\bar{d}	e	.00336
a	b	c	\bar{d}	\bar{e}	.00144
a	b	\bar{c}	d	e	0
a	b	\bar{c}	d	\bar{e}	.02160
a	b	\bar{c}	\bar{d}	e	0
a	b	\bar{c}	\bar{d}	\bar{e}	.00240
a	\bar{b}	c	d	e	.21504
a	\bar{b}	c	d	\bar{e}	.09216
a	\bar{b}	c	\bar{d}	e	.05376
a	\bar{b}	c	\bar{d}	\bar{e}	.02304
a	\bar{b}	\bar{c}	d	e	0
a	\bar{b}	\bar{c}	d	\bar{e}	0
a	\bar{b}	\bar{c}	\bar{d}	e	0
a	\bar{b}	\bar{c}	\bar{d}	\bar{e}	.09600

A	B	C	D	E	$P(.)$
\bar{a}	b	c	d	e	.01995
\bar{a}	b	c	d	\bar{e}	.00855
\bar{a}	b	c	\bar{d}	e	.00105
\bar{a}	b	c	\bar{d}	\bar{e}	.00045
\bar{a}	b	\bar{c}	d	e	0
\bar{a}	b	\bar{c}	d	\bar{e}	.24300
\bar{a}	b	\bar{c}	\bar{d}	e	0
\bar{a}	b	\bar{c}	\bar{d}	\bar{e}	.02700
\bar{a}	\bar{b}	c	d	e	.00560
\bar{a}	\bar{b}	c	d	\bar{e}	.00240
\bar{a}	\bar{b}	c	\bar{d}	e	.00140
\bar{a}	\bar{b}	c	\bar{d}	\bar{e}	.00060
\bar{a}	\bar{b}	\bar{c}	d	e	0
\bar{a}	\bar{b}	\bar{c}	d	\bar{e}	0
\bar{a}	\bar{b}	\bar{c}	\bar{d}	e	0
\bar{a}	\bar{b}	\bar{c}	\bar{d}	\bar{e}	.09000

Process of Elimination

- An important property of summing out variables
 - The new distribution is as good as the original one
 - As far as answering queries that do not mention A
 - That is $P'(\alpha) = P(\alpha)$ for any event α that does not involve A
- Therefore, if we want to compute a marginal distribution, say, over D and E
 - We just sum out variables A , B and C from the joint distribution
 - However, this procedure is exponential in the number of variables
- The key insight of VE is that we can sum out variables without constructing the joint probability
 - This allows to sometimes escape the exponential complexity

Factors

- A factor is a function over a set of variables
 - It maps each instantiation of these variables to a non-negative number
 - In some cases the number presents a probability. It may represent a distribution (e.g., f_2) or a conditional distribution (e.g., f_1)
- A factor over an empty set of variables is called trivial
 - It assigns a single number to the trivial instantiation 1
- There are two main operations over factors
 - Summing out a variable
 - Multiplying two factors
- These operations are building blocks of many inference algorithms

B	C	D	f_1
b	c	d	.95
b	c	\bar{d}	.05
b	\bar{c}	d	.9
b	\bar{c}	\bar{d}	.1
\bar{b}	c	d	.8
\bar{b}	c	\bar{d}	.2
\bar{b}	\bar{c}	d	0
\bar{b}	\bar{c}	\bar{d}	1

D	E	f_2
d	e	.448
d	\bar{e}	.192
\bar{d}	e	.112
\bar{d}	\bar{e}	.248

Summing Out

- Let f be a factor over variables X and let X be a variable in X .

$$\left(\sum_X f\right)(\mathbf{y}) \stackrel{\text{def}}{=} \sum_x f(x, \mathbf{y})$$

- The result of summing out variable X from the factor f is another factor over variables $Y = X \setminus \{X\}$ which we denote by $\sum_X f$

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- To illustrate this process consider the factor f_1
 - Summing out variable D results in a new factor $\sum_D f_1$
 - If we sum out all variables, we get a trivial factor

	$\sum_B \sum_C \sum_D f_1$
T	4

B	C	D	f_1	
b	c	d	.95	
b	c	\bar{d}	.05	
b	\bar{c}	d	.9	
b	\bar{c}	\bar{d}	.1	
\bar{b}	c	d	.8	
\bar{b}	c	\bar{d}	.2	
\bar{b}	\bar{c}	d	0	
\bar{b}	\bar{c}	\bar{d}	1	

B	C	$\sum_D f_1$
b	c	1
b	\bar{c}	1
\bar{b}	c	1
\bar{b}	\bar{c}	1

Summing Out

- The summing-out operation is commutative

- Therefore, we can sum out multiple variables without fixing an order

$$\sum_Y \sum_X f = \sum_X \sum_Y f$$

- This justifies the notation $\sum_X f$, where X is a set

- This algorithm provides the pseudocode for summing out any number of variables

- It is $O(\exp(w))$ time and space
 - w is the number of factor variables

- This operation is also known as *marginalization*

- $\sum_X f$ is also known as *projecting factor f on variables Y*

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Input: $f(X)$ and Z

Output: $\sum_Z f$

$Y \leftarrow X - Z$

$f' \leftarrow$ a factor over variables Y where $f'(y) = 0$ for all y

for each instantiation y **do**

for each instantiation z **do**

$f'(y) \leftarrow f'(y) + f(yz)$

return f'

Multiplication

- The second operation over factors is *multiplication*
 - If we multiply two factors, we construct a new factor over the union of their variables
 - Each instantiation on the new factor is compatible with exactly one instantiation on each original factor
- The result of multiplying two factors $f_1(X)$ and $f_2(Y)$ is another factor over variables $Z = X \cup Y$, denoted by $f_1 f_2$
 - $(f_1 f_2)(z) \stackrel{\text{def}}{=} f_1(x) f_2(y)$
 - Where x and y are compatible with z , that is $x \sim z$ and $y \sim z$

B	C	D	f_1			
b	c	d	.95			
b	c	\bar{d}	.05	D	E	f_2
b	\bar{c}	d	.9	d	e	.448
b	\bar{c}	\bar{d}	.1	d	\bar{e}	.192
\bar{b}	c	d	.8	\bar{d}	e	.112
\bar{b}	c	\bar{d}	.2	\bar{d}	\bar{e}	.248
\bar{b}	\bar{c}	d	0			
\bar{b}	\bar{c}	\bar{d}	1			

B	C	D	E	$f_1(B, C, D) f_2(D, E)$
b	c	d	e	.4256 = (.95).(.448)
b	c	d	\bar{e}	.1824 = (.95).(.192)
b	c	\bar{d}	e	.0056 = (.05)(.112)
\vdots	\vdots	\vdots	\vdots	\vdots
\bar{b}	\bar{c}	\bar{d}	\bar{e}	.2480 = (1)(.2480)

Multiplication

- Factor multiplication is commutative and associative

- We can multiply several factors without specifying the order of the multiplication

- This algorithm provides a pseudocode for multiplying m factors

- It is $O(m \exp(w))$ time and space
- w is the number of variables in the resulting factor

Input: $f_1(X_1), \dots, f_m(X_m)$

Output: $\prod_{i=1}^m f_i$

$Z \leftarrow \bigcup_{i=1}^m X_i$

$f \leftarrow$ a factor over variables Z where $f(z) = 1$ for all z

for each instantiation z do

for $i = 1$ to m do

$x_i \leftarrow$ instantiation of variables X_i consistent with z

$f(z) \leftarrow f(z)f_i(x_i)$

return f

Variable Elimination (VE)

- Suppose we want to compute the joint probability distribution for this network

- We can use the chain rule for Bayesian networks
- We can multiply the CPTs, viewing each CPT as a factor

$$P(a, b, c, d, e) = \theta_{e|c} \theta_{d|bc} \theta_{c|a} \theta_{b|a} \theta_a$$
$$\Theta_{E|C} \Theta_{D|BC} \Theta_{C|A} \Theta_{B|A} \Theta_A$$

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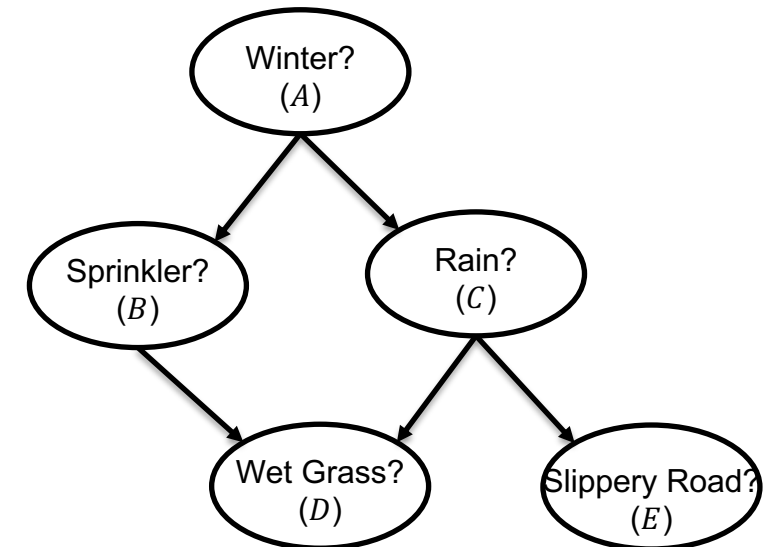
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- Suppose we want to compute the marginals for variables D and E

- We need to sum out variables A, B and C

$$P(D, E) = \sum_{A, B, C} \Theta_{E|C} \Theta_{D|BC} \Theta_{C|A} \Theta_{B|A} \Theta_A$$

- This is a combination of marginalization and multiplication
- However, it still has the problem of complexity



Variable Elimination (VE)

- If f_1 and f_2 are factors and if variable X appears only in f_2 , then
 - If f_1, \dots, f_n are the CPTs of a Bayesian network and if we want to sum out variable X
 - We may not need to multiply all these factors first

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- For instance,
 - If variable X appears only in factor f_n
 - But, if variable X appears in two factors f_{n-1} and f_n

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- In general, we need to multiply all factors f_k that include X and then sum out X from $\prod_k f_k$

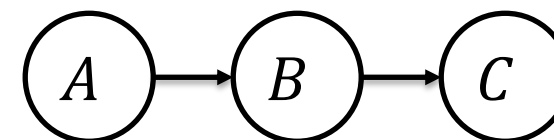
$$\sum_X f_1 f_2 = f_1 \sum_X f_2$$

$$\sum_X f_1 \dots f_n = f_1 \dots f_{n-1} \sum_X f_n$$

$$\sum_X f_1 \dots f_n = f_1 \dots f_{n-2} \sum_X f_{n-1} f_n$$

Variable Elimination (VE)

- Consider this network and assume the goal is to compute $P(C)$



- We will first eliminate A and then B
- There are two factors involving A : Θ_A and $\Theta_{B|A}$

A	B	Θ_A	$\Theta_{B A}$
a	b	.6	.9
a	\bar{b}	.4	.1
\bar{a}	b		.2
\bar{a}	\bar{b}		.8

A	Θ_A	A	B	$\Theta_{B A}$
a	.6	a	b	.9
\bar{a}	.4	a	\bar{b}	.1
		\bar{a}	b	.2
		\bar{a}	\bar{b}	.8

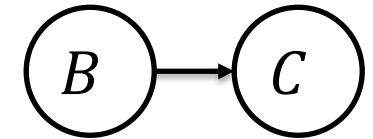
- Summing out variable A , we get

B	$\sum_A \Theta_A \Theta_{B A}$
b	.62 = .54 + .08
\bar{b}	.38 = .06 + .32

B	C	$\Theta_{C B}$
b	c	.3
b	\bar{c}	.7
\bar{b}	c	.5
\bar{b}	\bar{c}	.5

Variable Elimination (VE)

- Now, we have two factors, and we want to eliminate variable B



B	C	$\Theta_{C B}$	$\sum_A \Theta_A \Theta_{B A}$
b	c	.186	
b	\bar{c}	.434	
\bar{b}	c	.190	
\bar{b}	\bar{c}	.190	

B	$\sum_A \Theta_A \Theta_{B A}$
b	.62
\bar{b}	.38

- Summing out B

C	$\sum_B \Theta_{C B} \sum_A \Theta_A \Theta_{B A}$
c	.376
\bar{c}	.624

B	C	$\Theta_{C B}$
b	c	.3
b	\bar{c}	.7
\bar{b}	c	.5
\bar{b}	\bar{c}	.5

Computing Prior Marginals (VE_PR1)

- This algorithm provides the pseudocode for computing the marginal over some variables Q

- How much work does this algorithm do?
- Note that f and f_i differs only one variable $\pi(i)$

Input: Bayesian network N , query variables Q , variable ordering π

Output: prior marginal $P(Q)$

1: $S \leftarrow$ CPTs of network N

2: **for** $i = 1$ to length of order π **do**

3: $f \leftarrow \prod_k f_k$ where f_k belongs to S and mentions variable $\pi(i)$

4: $f_i \leftarrow \sum_{\pi(i)} f$

5: replace all factors f_k in S by factor f_i

6: **return** $\prod_{i \in S} f_i$

- For $\pi = \{A, B\}$

$$\underbrace{\sum_B \Theta_{C|B}}_1 \underbrace{\sum_A \Theta_{A|B} \Theta_{B|A}}_1$$

- For $\pi = \{B, A\}$

$$\underbrace{\sum_A \Theta_A \sum_B \Theta_{B|A} \Theta_{C|B}}_1$$

Computing Prior Marginals

- Therefore, although any order will work
 - Some orders are better than others
 - Since they lead to constructing smaller intermediate factors
- We need to find the best order
 - We will address this problem shortly
 - For now, let us try to formalize how to measure the quality of an elimination order
- If the largest factor has w variables, then the complexity of the lines 3-5 is $O(n \exp(w))$
 - This number is known as the *width* of the elimination order
 - We want to find the elimination order with the smallest width
 - The algorithm complexity is $O(n \exp(w) + n \exp(|Q|))$

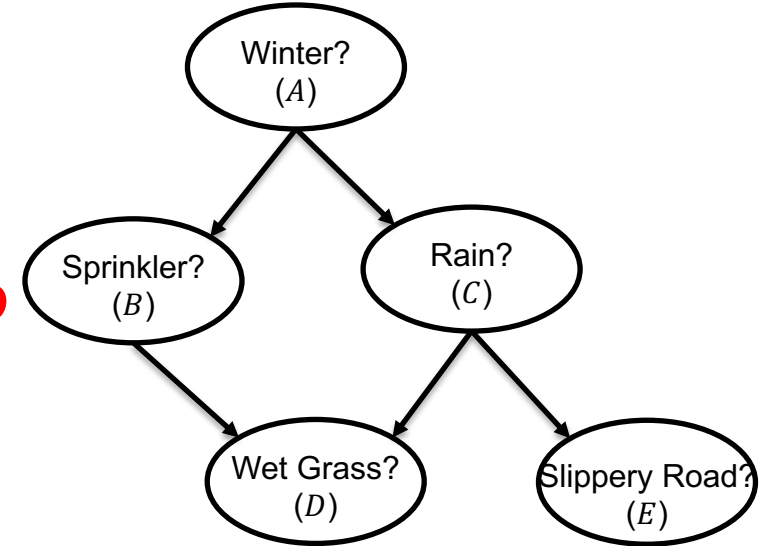
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Elimination Order

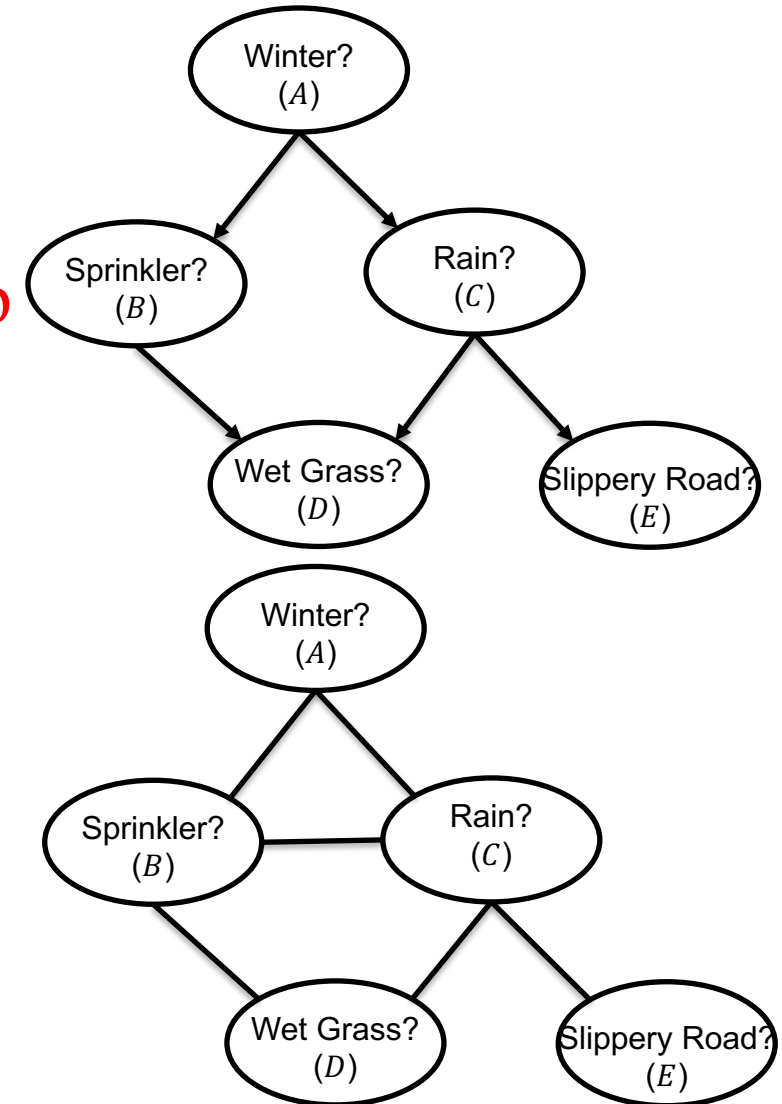
- Suppose we have two elimination orders π_1 and π_2
 - We want to choose the one with smallest width
 - We can modify the VE_PR1 to register the number of variables in line 4
 - The width is maximum number of variables any factor ever contained
- Let us suppose we want compute $P(C)$
 - With an elimination order B, C, A, D



i	$\pi(i)$	S	f_i	w
		$\Theta_A \Theta_{B A} \Theta_{C A} \Theta_{D BC} \Theta_{E C}$		
1	B	$\Theta_A \Theta_{C A} \Theta_{E C} f_1(A, C, D)$	$f_1 = \sum_B \Theta_{B A} \Theta_{D B,C}$	3
2	C	$\Theta_A f_2(A, D, E)$	$f_2 = \sum_C \Theta_{C A} \Theta_{E C} f_1(A, C, D)$	3
3	A	$f_3(D, E)$	$f_3 = \sum_A \Theta_A f_2(A, D, E)$	2
4	D	$f_4(E)$	$f_4 = \sum_D f_3(D, E)$	1

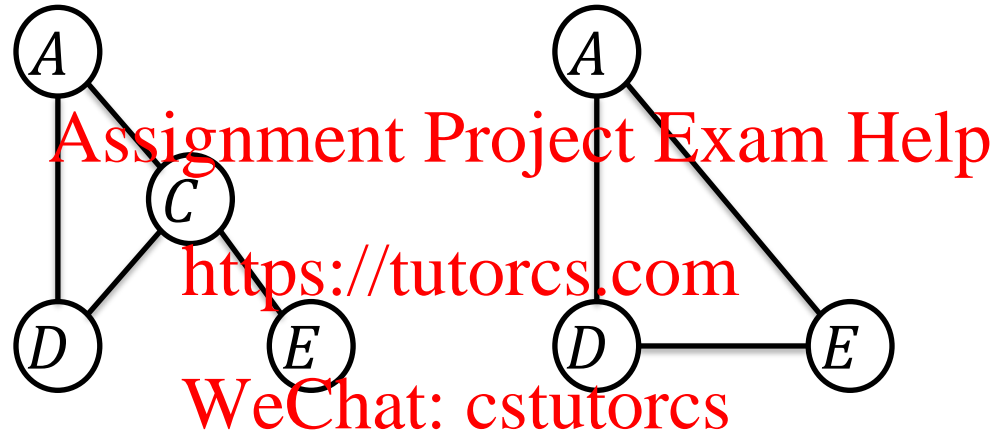
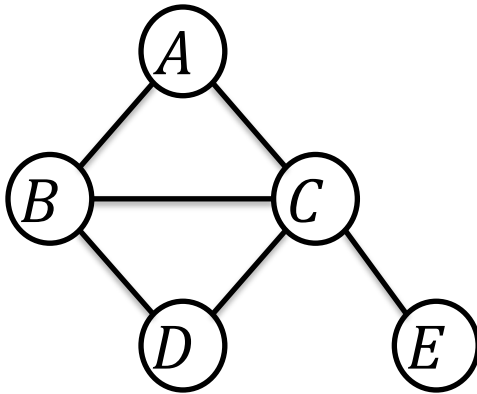
Interaction Graph

- We can compute the width of an order by simply operating on an undirected graph
 - Let f_1, \dots, f_n be a set of factors. The *interaction graph* G of these factors is an undirected graph constructed as follows
 - The nodes of G are the variables that appear in factors f_1, \dots, f_n
 - There is an edge between two variables in G iff those variables appear in the same factor
- Another way to visualise the interaction graph is to realise that the variables X_i of f_i form a clique in G
 - For example, $\Theta_A \Theta_{B|A} \Theta_{C|A} \Theta_{D|BC} \Theta_{E|C}$



Interaction Graph

Elimination order: B, C, A, D



$$S_1: \Theta_A \Theta_{B|A} \Theta_{C|A} \Theta_{D|BC} \Theta_{E|C}$$

$$S_2: \Theta_A \Theta_{C|A} \Theta_{E|C} f_1(A, C, D)$$

$$S_3: \Theta_A f_2(A, D, E)$$

$$S_4: f_3(D, E)$$

$$S_5: f_4(E)$$

Interaction Graph

- There are two key observations about interaction graphs
 - If G is the interaction graph of factors S , then elimination a variable $\pi(i)$ from S leads to constructing a factor over the neighbours of $\pi(i)$ in G
 - Let S' be the factors that result from eliminating variable $\pi(i)$ from factors S . If G' and G are the interaction graphs of S' and S , respectively, then G' can be obtained from G as follows
 - a) Add an edge to G between every pair of neighbours of variable $\pi(i)$ that are not already connected
 - b) Delete variable $\pi(i)$ from G

OrderWidth

Input: Bayesian network N , variable ordering π

Output: the width of π

$G \leftarrow$ interaction graph of the CPTs in network N

$w \leftarrow 0$

for $i = 1$ to length of order π **do**

$w \leftarrow \max(w, d)$, where d is the number of $\pi(i)$'s neighbours in G

 add an edge between every pair of non-adjacent neighbours of $\pi(i)$ in G

 delete variable $\pi(i)$ from G

return w

- This algorithm provides pseudocode for computing the width of an elimination order
 - One application of OrderWidth is to measure the quality of an ordering before using it
 - However, when the number of orderings is large, we need to do better

Interaction Graph

- Computing the optimal ordering is an NP-hard problem
 - But there are several heuristic approaches that provide good results
 - One of the most popular is also the simplest: *min-degree* heuristic
- The min-degree heuristic eliminates the variable that leads to constructing the smallest factor possible
 - It means we should eliminate the variable with the smallest number of neighbours in the current graph
 - Min-degree is optimal when applied to a network with some elimination order of width ≤ 2

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MinDegreeOrder

Input: Bayesian network N with variables X

Output: an ordering π of variables X

$G \leftarrow$ interaction graph of the CPTs in network N

for $i = 1$ to number of variables in X **do**

$\pi(i) \leftarrow$ a variable in X with smallest number of neighbours in G

add an edge between every pair of non-adjacent neighbours of $\pi(i)$ in G

delete variable $\pi(i)$ from G and from X

return π

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- There is another popular heuristic that is usually more effective than MinDegreeOrder
 - It consists in eliminating the variable that leads to adding the smallest number of edges in G , called *fill-in edges*
 - This heuristic is called *fill-in heuristic*

MinFillOrder

Input: Bayesian network N with variables X

Output: an ordering π of variables X

$G \leftarrow$ interaction graph of the CPTs in network N

for $i = 1$ to number of variables in X **do**

$\pi(i) \leftarrow$ a variable in X that adds the smallest number of edges in G

add an edge between every pair of non-adjacent neighbours of $\pi(i)$ in G

delete variable $\pi(i)$ from G and from X

return π

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Computing Posterior Marginals

- We now discuss an algorithm for computing the posterior marginal for a set of variables
 - For instance, $Q = \{D, E\}$ and $e: A = \text{true}, B = \text{false}$ we get the table on the right side

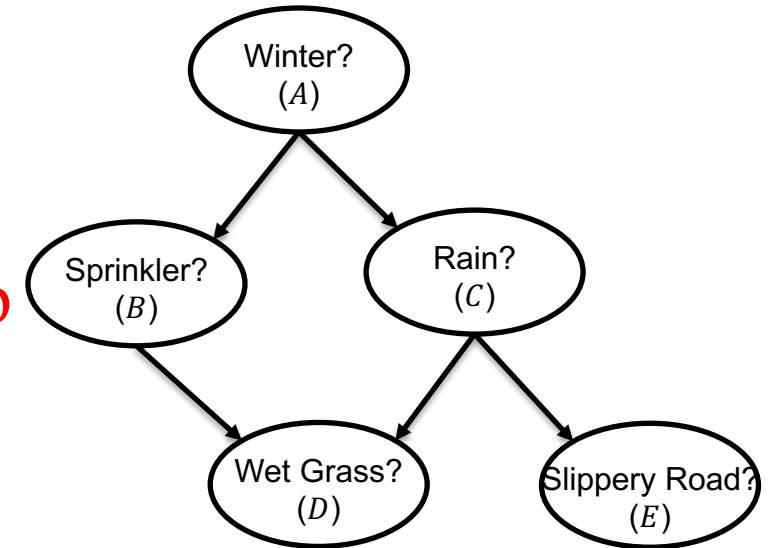
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- More generally, given a network N , query Q and evidence e

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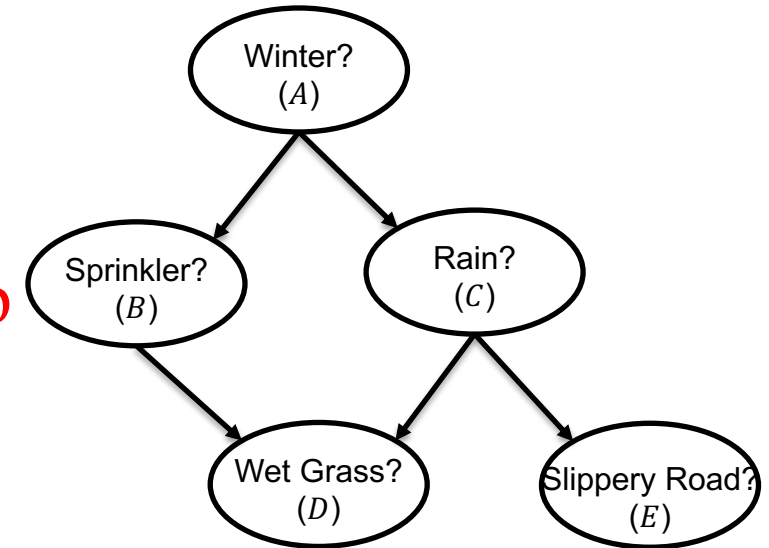
- We want to compute the posterior marginal $P(Q|e)$
- Prior marginals is a special case of posterior marginals when e is the trivial instantiation



D	E	$P(Q e)$
d	e	.448
d	\bar{e}	.192
\bar{d}	e	.112
\bar{d}	\bar{e}	.248

Computing Posterior Marginals

- It is more useful to construct a variation called *joint marginals*, $P(\mathbf{Q}, \mathbf{e})$
 - If we take $\mathbf{Q} = \{D, E\}$ and $\mathbf{e}: A = \text{true}, B = \text{false}$, we get the joint marginal on the right side
 - If we add the probabilities in this factor, we get .48
 - This is the probability of evidence \mathbf{e} , since $\sum_{\mathbf{q}} P(\mathbf{q}, \mathbf{e}) = P(\mathbf{e})$
- This means we can compute $P(\mathbf{Q} | \mathbf{e})$ by simply normalizing $P(\mathbf{Q}, \mathbf{e})$
 - We also get the probability of evidence \mathbf{e} for free
- VE can be extended to compute joint marginals
 - We need start by zeroing out those rows that are inconsistent with evidence \mathbf{e}



D	E	$P(\mathbf{Q}, \mathbf{e})$
d	e	.21504
d	\bar{e}	.09216
\bar{d}	e	.05376
\bar{d}	\bar{e}	.11904

Computing Posterior Marginals

- The reduction of factor $f(\mathbf{X})$ given evidence \mathbf{e} is another factor over variables \mathbf{X} , denoted by f^e

$$f^e(\mathbf{x}) \stackrel{\text{def}}{=} \begin{cases} f(\mathbf{x}), & \text{if } \mathbf{x} \sim \mathbf{e} \\ 0, & \text{otherwise} \end{cases}$$

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- For example, given the factor f and evidence $\mathbf{e}: E = \text{true}$, we obtain f^e

D	E	f
d	e	.448
d	\bar{e}	.192
\bar{d}	e	.112
\bar{d}	\bar{e}	.248

D	E	f^e
d	e	.448
d	\bar{e}	0
\bar{d}	e	.112
\bar{d}	\bar{e}	0

D	E	f^e
d	e	.448
\bar{d}	e	.112

Computing Posterior Marginals

- For this network, if $\mathbf{Q} = \{D, E\}$ and $\mathbf{e}: A = \text{true}, B = \text{false}$. The joint marginal $P(\mathbf{Q}, \mathbf{e})$ is

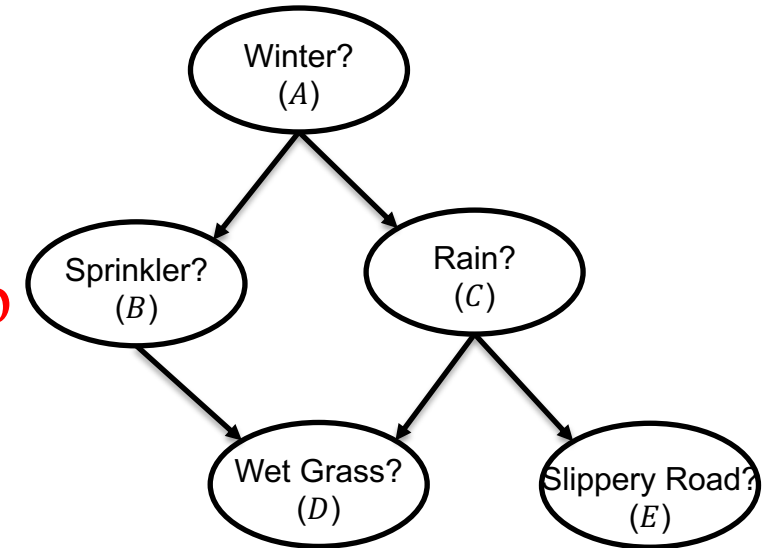
$$P(\mathbf{Q}, \mathbf{e}) = \sum_{A,B,C} (\theta_A \theta_{B|A} \theta_{C|A} \theta_{D|BC} \theta_{E|C})^{\mathbf{e}}$$

- We can use the following result

$$(f_1, f_2)^{\mathbf{e}} = f_1^{\mathbf{e}} f_2^{\mathbf{e}}$$

- Therefore

$$P(\mathbf{Q}, \mathbf{e}) = \sum_{A,B,C} \theta_A^{\mathbf{e}} \theta_{B|A}^{\mathbf{e}} \theta_{C|A}^{\mathbf{e}} \theta_{D|BC}^{\mathbf{e}} \theta_{E|C}^{\mathbf{e}}$$



Computing Posterior Marginals

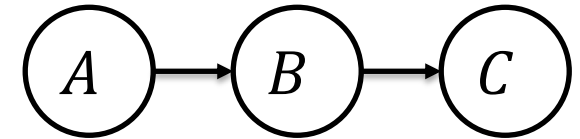
- Consider this network. Let $Q = \{C\}$, $e: A = \text{true}$
 - We want to compute $P(Q, e)$, by eliminating A then B

- We first reduce the network CPTs given evidence e

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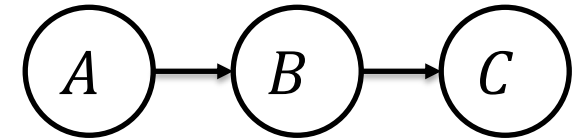
A	Θ_A	A	B	$\Theta_{B A}$
a	.6	a	b	.9
\bar{a}	.4	a	\bar{b}	.1
		\bar{a}	b	.2
		\bar{a}	\bar{b}	.8

B	C	$\Theta_{C B}$
b	c	.3
b	\bar{c}	.7
\bar{b}	c	.5
\bar{b}	\bar{c}	.5

Computing Posterior Marginals

- Consider this network. Let $\mathbf{Q} = \{C\}$, $e: A = \text{true}$
 - We want to compute $P(\mathbf{Q}, e)$, by eliminating A then B

- We first reduce the network CPTs given evidence e



A	Θ_A^e			A	B	$\Theta_{B A}^e$
a	.6	a	b	a	b	.9
		a	\bar{b}	a	\bar{b}	.1

- Then we need to evaluate

$$\begin{aligned}
 P(\mathbf{Q}, e) &= \sum_B \sum_A \Theta_A^e \Theta_{B|A}^e \Theta_{C|B}^e \\
 &= \sum_B \Theta_{C|B}^e \sum_A \Theta_A^e \Theta_{B|A}^e
 \end{aligned}$$

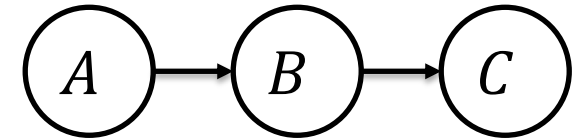
A	B	$\Theta_A^e \Theta_{B A}^e$	B	$\sum_A \Theta_A^e \Theta_{B A}^e$
a	b	.54	b	.54
a	\bar{b}	.06	\bar{b}	.06

B	C	$\Theta_{C B}^e$
b	c	.3
b	\bar{c}	.7
\bar{b}	c	.5
\bar{b}	\bar{c}	.5

Computing Posterior Marginals

- Consider this network. Let $\mathbf{Q} = \{C\}$, $e: A = \text{true}$
 - We want to compute $P(\mathbf{Q}, e)$, by eliminating A then B

- We first reduce the network CPTs given evidence e



- Then we need to evaluate

$$\begin{aligned}
 P(\mathbf{Q}, e) &= \sum_B \sum_A \Theta_A^e \Theta_{B|A}^e \Theta_{C|B}^e \\
 &= \sum_B \Theta_{C|B}^e \sum_A \Theta_A^e \Theta_{B|A}^e
 \end{aligned}$$

B	$\sum_A \Theta_A^e \Theta_{B A}^e$
b	.54
\bar{b}	.06

B	C	$\Theta_{C B}^e \sum_A \Theta_A^e \Theta_{B A}^e$
b	c	.162
b	\bar{c}	.378
\bar{b}	c	.030
\bar{b}	\bar{c}	.030

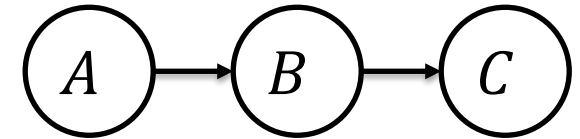
C	$\sum_B \Theta_{C B}^e \sum_A \Theta_A^e \Theta_{B A}^e$
c	.192
\bar{c}	.408

B	C	$\Theta_{C B}^e$
b	c	.3
b	\bar{c}	.7
\bar{b}	c	.5
\bar{b}	\bar{c}	.5

Computing Posterior Marginals

- Consider this network. Let $\mathbf{Q} = \{C\}$, $e: A = \text{true}$
 - We want to compute $P(\mathbf{Q}, e)$, by eliminating A then B

- We first reduce the network CPTs given evidence e



- Then we need to evaluate

$$\begin{aligned}
 P(\mathbf{Q}, e) &= \sum_B \sum_A \Theta_A^e \Theta_{B|A}^e \Theta_{C|B}^e \\
 &= \sum_B \Theta_{C|B}^e \sum_A \Theta_A^e \Theta_{B|A}^e
 \end{aligned}$$

- To compute $P(C|A = \text{true})$

- We need to normalize this factor, which gives

C	$\sum_B \Theta_{C B}^e \sum_A \Theta_A^e \Theta_{B A}^e$
c	.192
\bar{c}	.408

C	$P(C A = \text{true})$
c	.32
\bar{c}	.68

Computing Joint Marginals (VE_PR2)

Input: Bayesian network N , query variables Q , variable ordering π , evidence e

Output: joint marginal $P(Q, e)$

1: $S \leftarrow \{f^e : f \text{ is a CPTs of network } N\}$
2: **for** $i = 1$ to length of order π **do**
3: $f \leftarrow \prod_k f_k$ where f_k belongs to S and mentions variable $\pi(i)$
4: $f_i \leftarrow \sum_{\pi(i)} f$
5: replace all factors f_k in S by factor f_i
6: **return** $\prod_{f \in S} f$

- It is not uncommon to run VE_PR2 with empty Q
 - The algorithm will return a trivial factor with the probability of evidence e

Network Structure and Complexity

- Suppose we have two Bayesian networks with 100 variables
- We find the best elimination order for both
 - The first one has width 3, and therefore, good performance
 - The second one has width 25, and poor performance regardless of the elimination order
- Why is the second network more difficult given that both have the same number of variables?
 - The answer lies in the notion of *treewidth*
 - It is a number that quantifies the extent a network resembles a tree structure
 - No elimination order can have a width smaller than the network treewidth
 - There is an elimination order whose width equals the network treewidth. Yet determining such an order is NP-hard

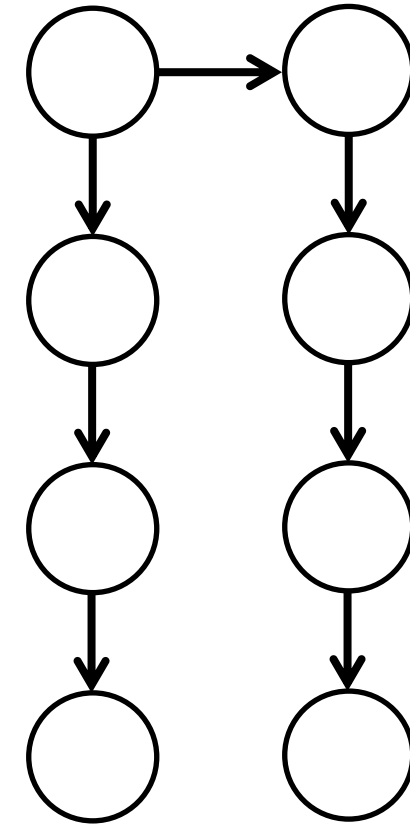
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Treewidth

- Intuitively, treewidth is a number that quantifies the extent a network resembles a tree structure
- The treewidth can be defined as the width of this best *complete elimination order*
- A complete elimination order has all network variables

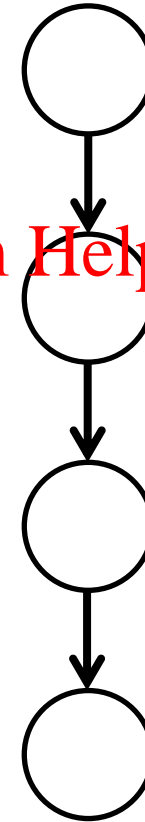


Network with treewidth = 1

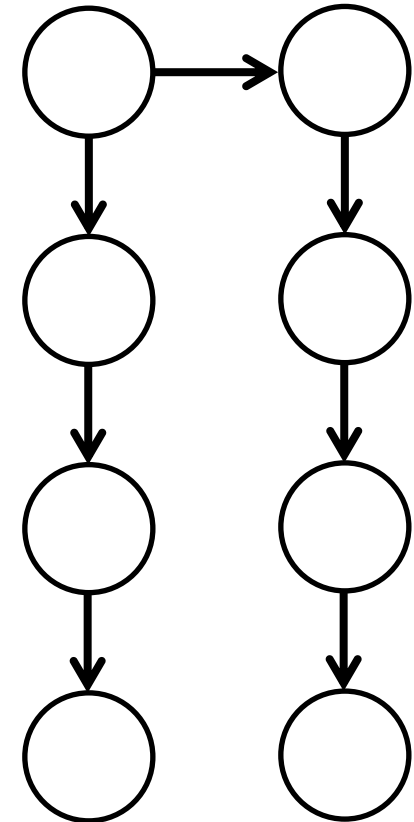
Treewidth: Intuition

- The number of nodes has no effect on treewidth

- For example, these two networks have treewidth = 1
- But the second one has the twice the number of nodes



Treewidth = 1



Treewidth = 1

Treewidth: Intuition

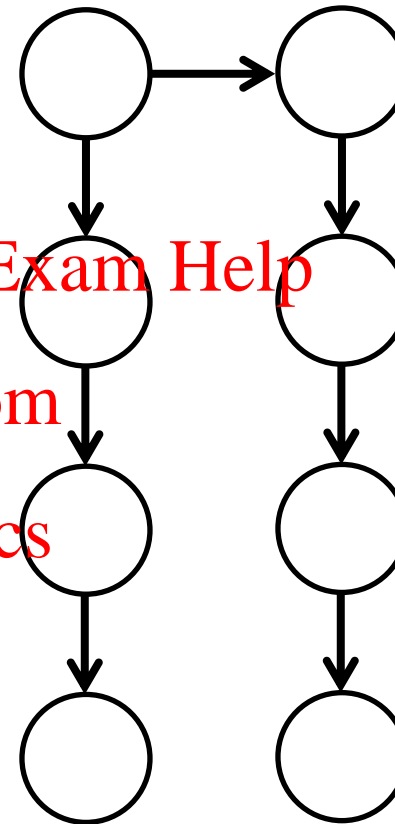
- The number of parents per node has a direct effect on treewidth

- If the number of parents can reach k , the treewidth is no less than k

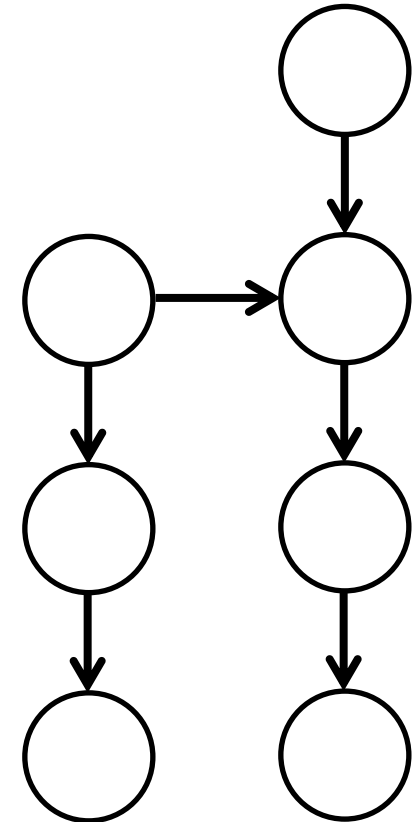
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Treewidth = 1

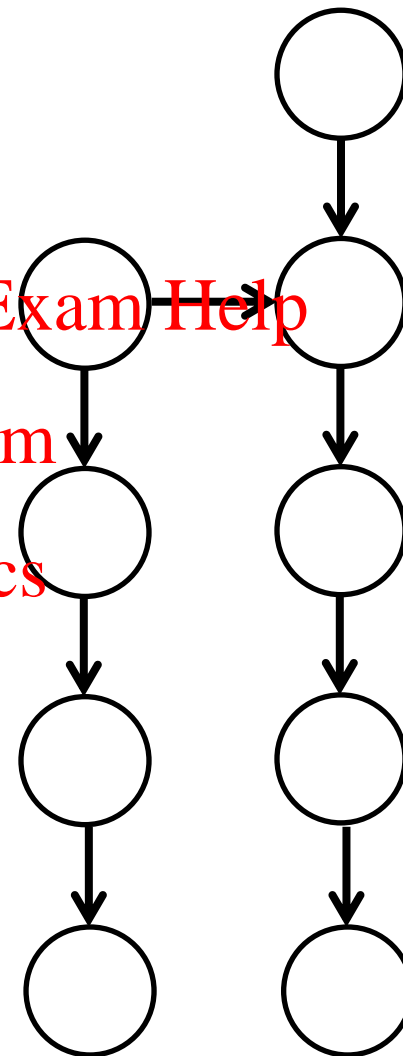


Treewidth = 2

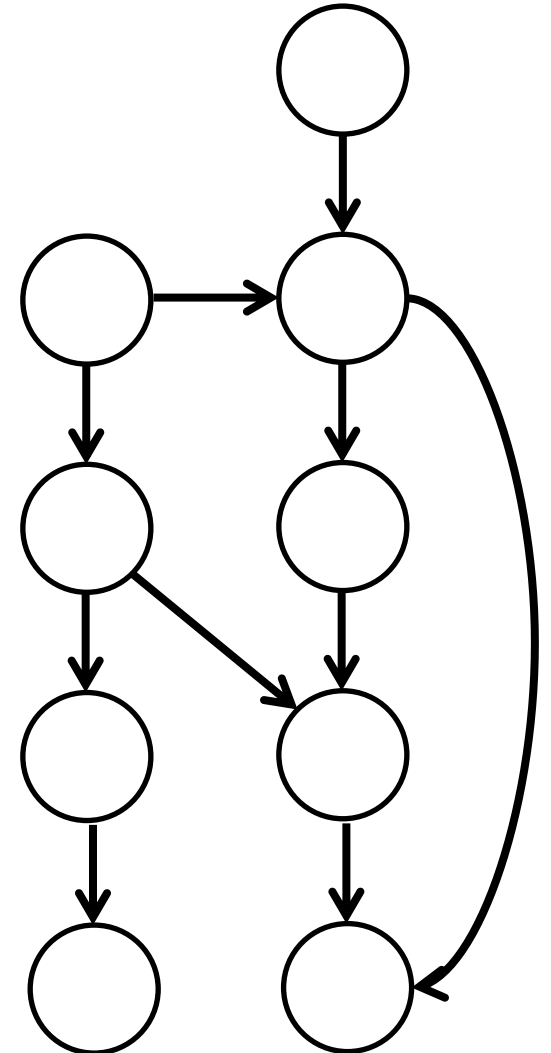
Treewidth: Intuition

- Loops tend to increase treewidth

- For example, the second network was obtained from the first by introducing some loops
- Notice the maximum number of parents per node did not increase



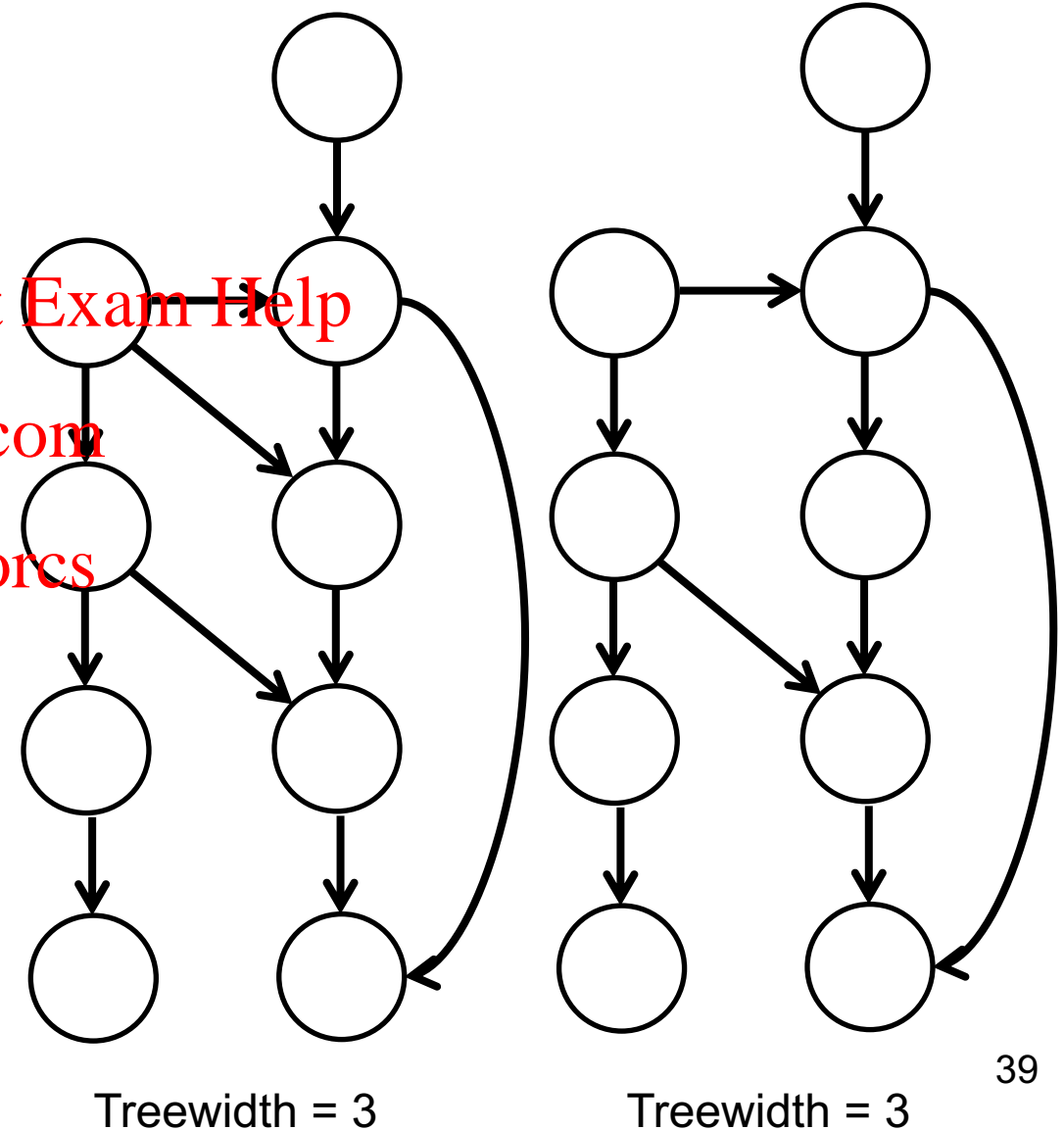
Treewidth = 2



Treewidth = 3

Treewidth: Intuition

- The number of loops per se does not have a genuine effect on treewidth
 - It is the nature of the loops which does
 - Their interaction in particular
 - These two networks have the same treewidth, although the first has more loops



Classes of Networks with Known Treewidth

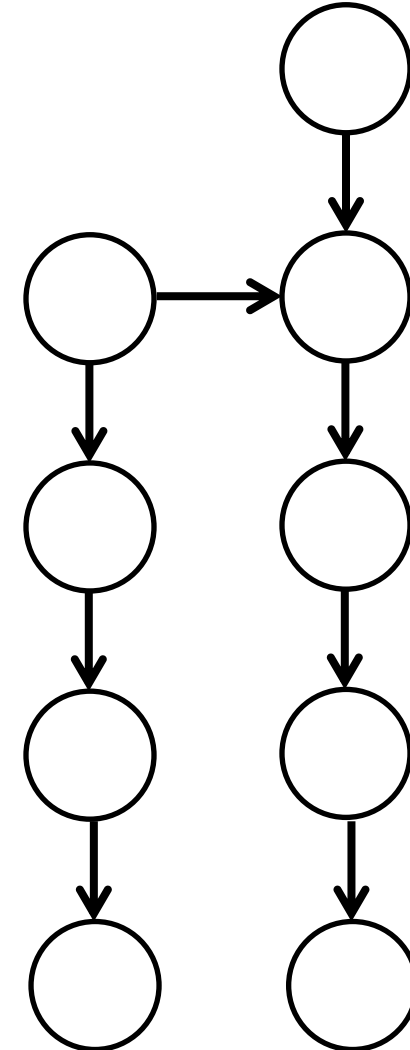
- *Polytrees networks* have at most one (undirected) path between two nodes

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- Also known as *singly connected networks*
- The treewidth of polytrees is k , where k is the maximum number of parents of any node.

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Treewidth = 2

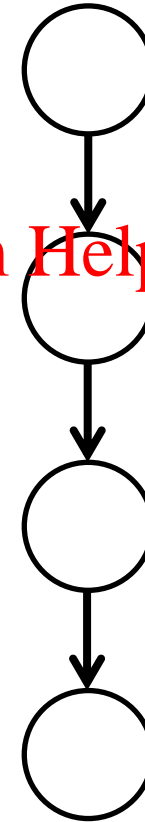
Classes of Networks with Known Treewidth

- *Tree networks* are polytrees where each node has at most one parent

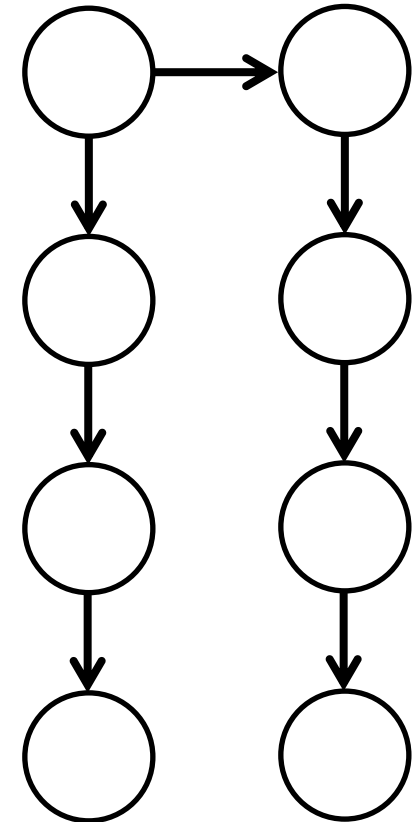
- Leading to a treewidth of at most 1

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Treewidth = 1



Treewidth = 1

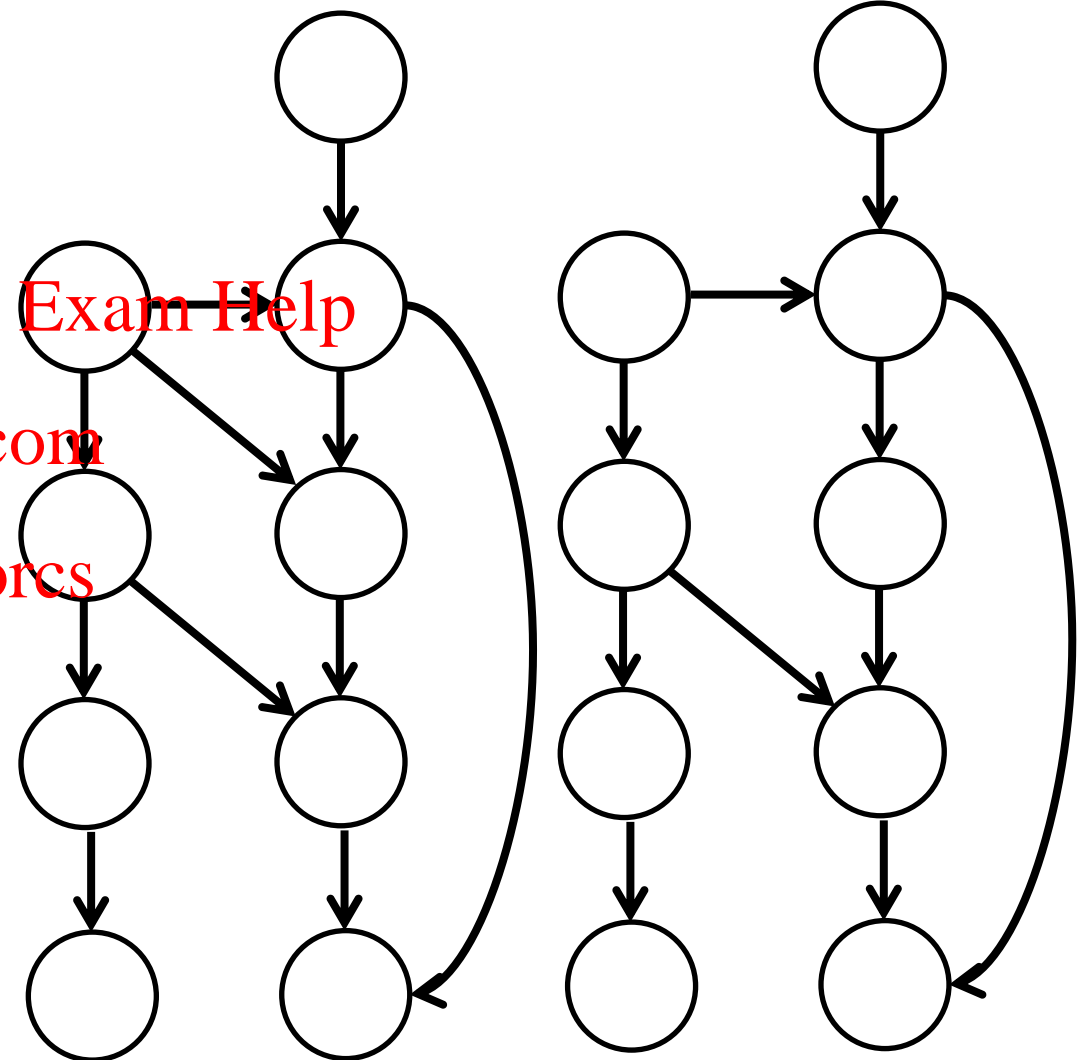
Classes of Networks with Known Treewidth

- *Multiply connected* are networks not singly connected (polytrees)

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Treewidth = 3

Treewidth = 3

Query Structure

- Treewidth indicates that network structure has a major impact on VE performance
 - Therefore, these algorithms are also known as *structure-based algorithms*
- Network structure can be simplified based on query structure
 - Query is a pair (Q, e)
- Goal is to compute $P(Q, e)$
 - If $E = \emptyset$ then we are interested in $P(Q)$
 - If $Q = \emptyset$ then we are interested in $P(e)$
- The complexity of inference can be affected by the number and location of variables in Q and e
 - For a given query, we provide two transformations that simplify the network, making it more amenable to inference
 - Yet preserving its ability to compute the joint marginal $P(Q, e)$

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Pruning Nodes

- Given a Bayesian network G and a query (Q, e) , we can remove any leaf node if it does not belong to $Q \cup E$

- This operation can be applied iteratively, possibly removing many nodes

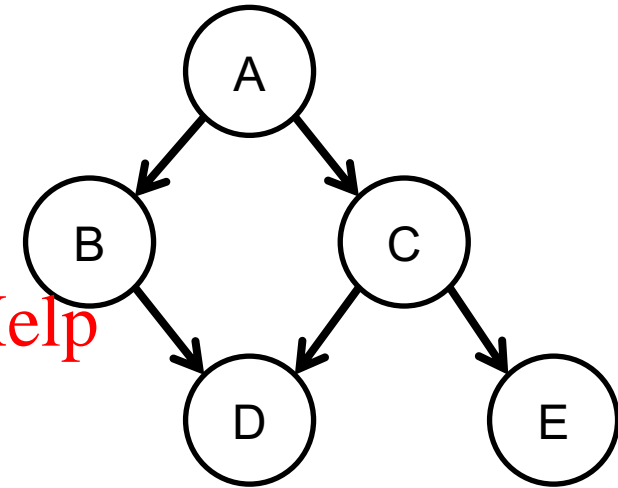
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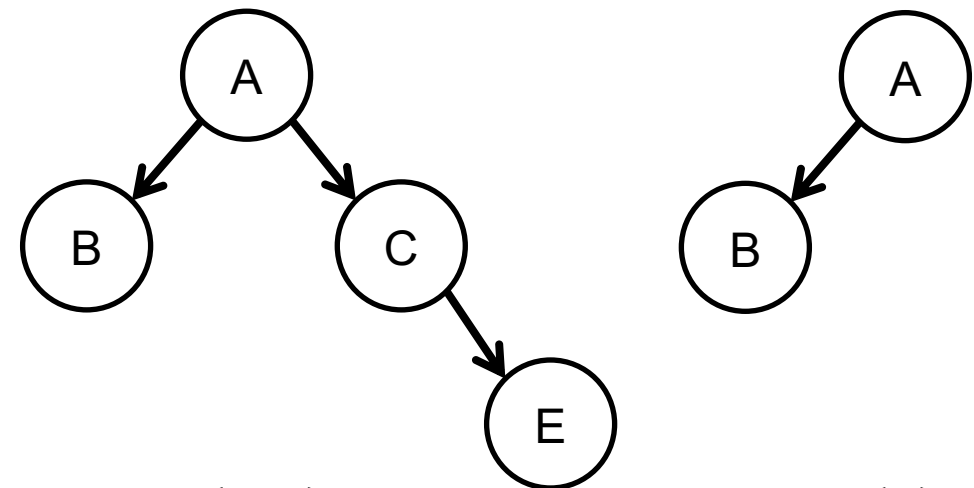
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- The network structure on the top has treewidth = 2

- After pruning, both networks have treewidth = 1



Network structure

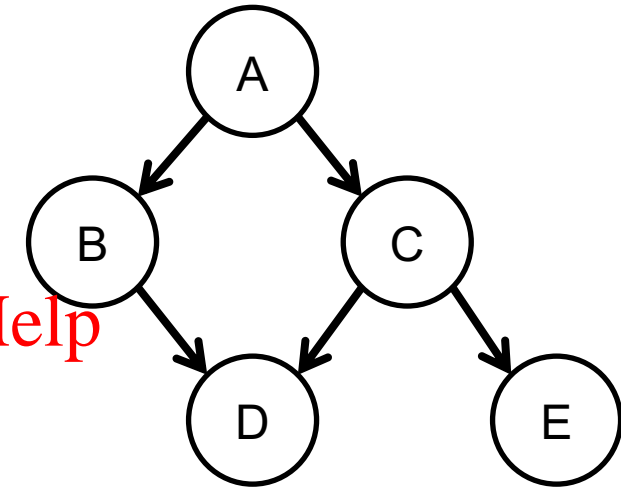


$P(B, E)$

$P(B)$

Pruning Nodes

- Why does pruning leaf nodes work?
 - For any CPT $P(X|U)$, the result of summing out variable X is a factor that assigns 1 to each instantiation
 - Multiplying this factor by any other factor f that includes variables U will give factor f back



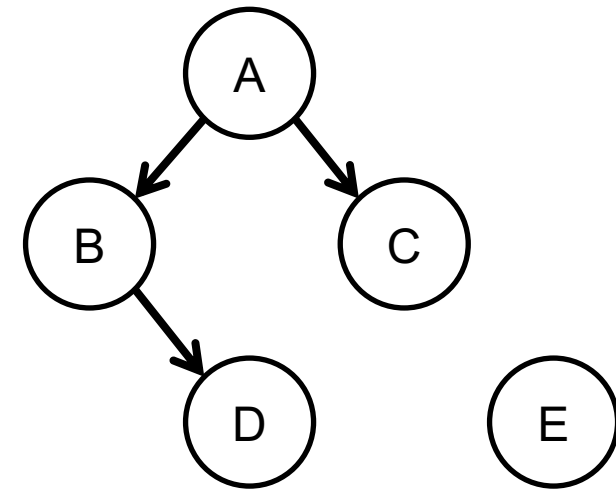
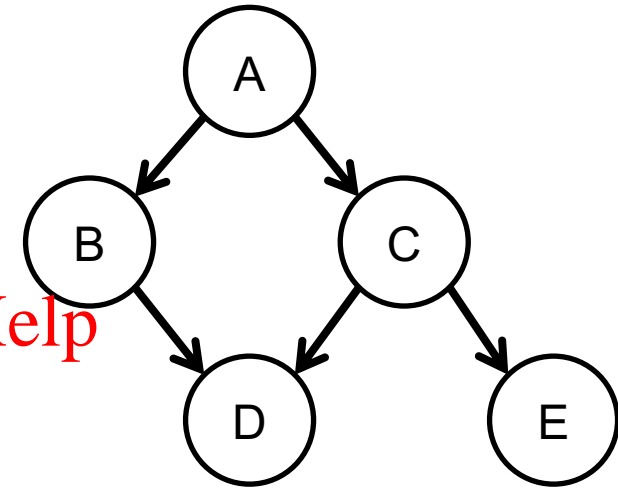
- The figure gives a numerical example

B	C	D	$\theta_{D B,C}$
b	c	d	.95
b	c	\bar{d}	.05
b	\bar{c}	d	.9
b	\bar{c}	\bar{d}	.1
\bar{b}	c	d	.8
\bar{b}	c	\bar{d}	.2
\bar{b}	\bar{c}	d	0
\bar{b}	\bar{c}	\bar{d}	1

B	C	$\sum_D \theta_{D B,C}$
b	c	1
b	\bar{c}	1
\bar{b}	c	1
\bar{b}	\bar{c}	1

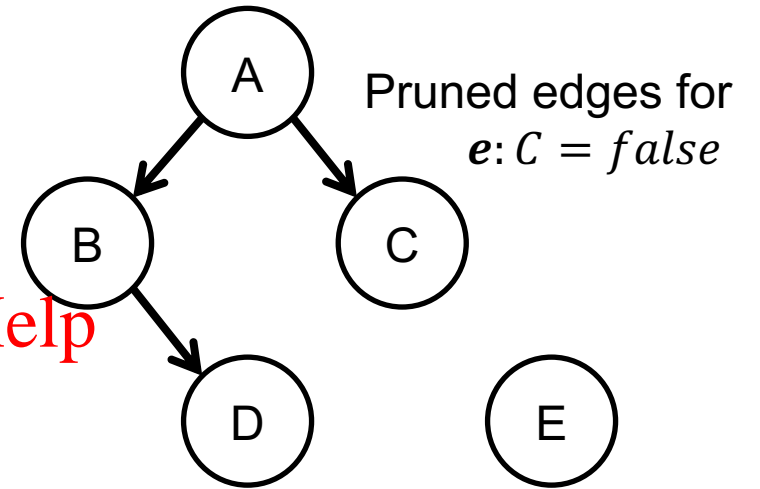
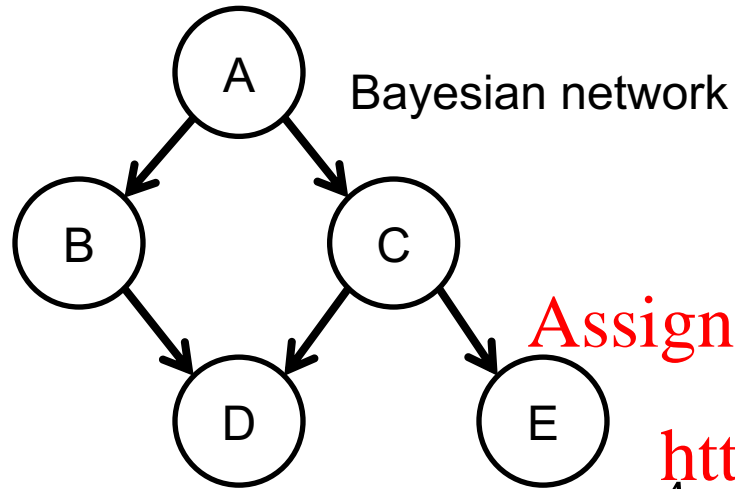
Pruning Edges

- Given a Bayesian network G and a query (Q, e) , we can remove each edge $U \rightarrow X$ that originates from a node $U \in E$
 - Remove the edge $U \rightarrow X$
 - Replace the CPT $\Theta_{X|U}$ by a smaller CPT which is obtained from $\Theta_{X|U}$ by assuming the value u of U given in evidence e



Pruned edges for $e: C = false$

Pruning Edges



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A	θ_A
a	.6
\bar{a}	.4

B	C	D	$\theta_{D B,C}$
b	c	d	.95
b	c	\bar{d}	.05
b	\bar{c}	d	.9
b	\bar{c}	\bar{d}	.1
\bar{b}	c	d	.8
\bar{b}	c	\bar{d}	.2
\bar{b}	\bar{c}	d	0
\bar{b}	\bar{c}	\bar{d}	1

A	B	$\theta_{B A}$
a	b	.2
a	\bar{b}	.8
\bar{a}	b	.75
\bar{a}	\bar{b}	.25

A	C	$\theta_{C A}$
a	c	.8
a	\bar{c}	.2
\bar{a}	c	.1
\bar{a}	\bar{c}	.9

C	E	$\theta_{E C}$
c	e	.7
c	\bar{e}	.3
\bar{c}	e	0
\bar{c}	\bar{e}	1

A	θ_A
a	.6
\bar{a}	.4

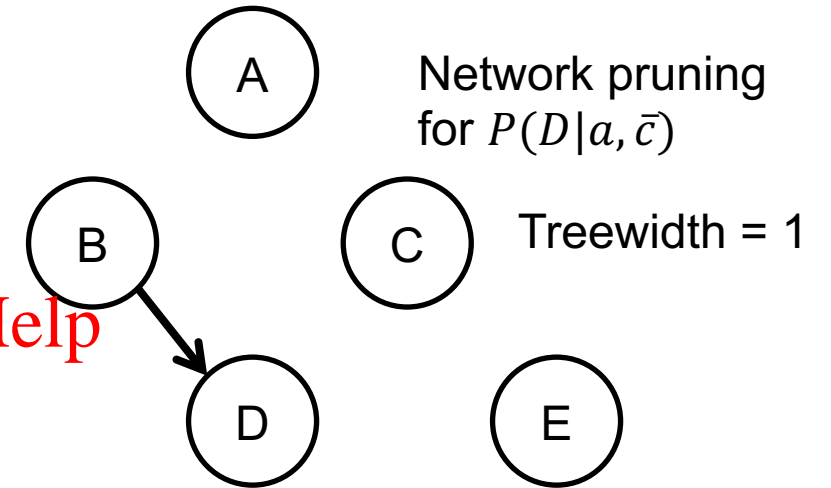
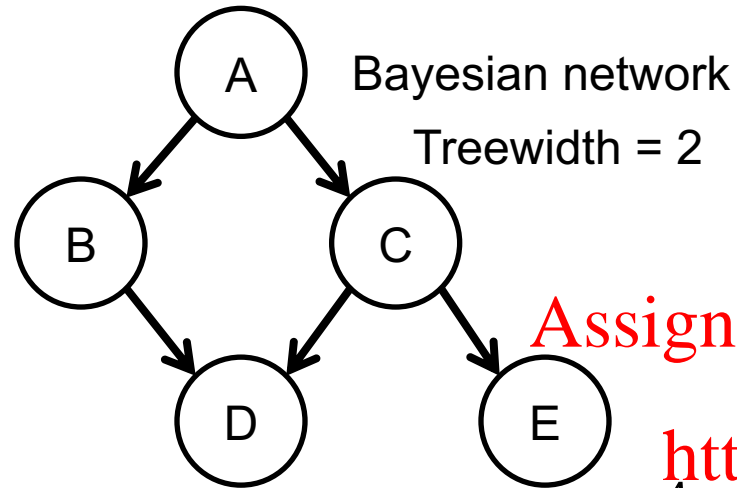
A	B	$\theta_{B A}$
a	b	.2
a	\bar{b}	.8
\bar{a}	b	.75
\bar{a}	\bar{b}	.25

B	D	$\sum_C \theta_{D B,C}^{\bar{c}}$
b	d	.9
b	\bar{d}	.1
\bar{b}	d	0
\bar{b}	\bar{d}	1

A	C	$\theta_{C A}$
a	c	.8
a	\bar{c}	.2
\bar{a}	c	.1
\bar{a}	\bar{c}	.9

E	$\sum_C \theta_{E C}^{\bar{c}}$
e	0
\bar{e}	1

Pruning Nodes + Edges = Network Pruning



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A	θ_A
a	.6
\bar{a}	.4

B	C	D	$\theta_{D B,C}$
b	c	d	.95
b	c	\bar{d}	.05
b	\bar{c}	d	.9
b	\bar{c}	\bar{d}	.1
\bar{b}	c	d	.8
\bar{b}	c	\bar{d}	.2
\bar{b}	\bar{c}	d	0
\bar{b}	\bar{c}	\bar{d}	1

A	B	$\theta_{B A}$
a	b	.2
a	\bar{b}	.8
\bar{a}	b	.75
\bar{a}	\bar{b}	.25

A	C	$\theta_{C A}$
a	c	.8
a	\bar{c}	.2
\bar{a}	c	.1
\bar{a}	\bar{c}	.9

C	E	$\theta_{E C}$
c	e	.7
c	\bar{e}	.3
\bar{c}	e	0
\bar{c}	\bar{e}	1

A	θ_A
a	.6
\bar{a}	.4

B	$\sum_A \theta_{B A}^a$
b	.2
\bar{b}	.8

B	D	$\sum_C \theta_{D B,C}^{\bar{c}}$
b	d	.9
b	\bar{d}	.1
\bar{b}	d	0
\bar{b}	\bar{d}	1

C	$\sum_A \theta_{C A}^a$
c	.8
\bar{c}	.2

Network Pruning (VE_PR)

Input: Bayesian network N , query variables Q , evidence e

Output: joint marginal $P(Q, e)$

$N' \leftarrow \text{pruneNetwork}(N, Q, e)$

$\pi \leftarrow$ an ordering of variables not in Q computed relative to N'

$S \leftarrow \{f^e: f \text{ is a CPTs of network } N\}$

for $i = 1$ to length of order π **do**

$f \leftarrow \prod_k f_k$ where f_k belongs to S and mentions variable $\pi(i)$

$f_i \leftarrow \sum_{\pi(i)} f$

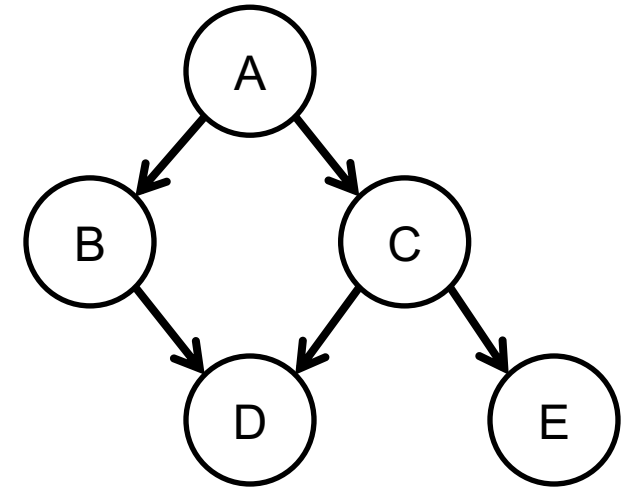
replace all factors f_k in S by factor f_i

return $\prod_{f \in S} f$

- The effective treewidth for a network N with respect to query (Q, e) is the treewidth of $\text{pruneNetwork}(N, Q, e)$
- Pruning is done in linear time in the size of the network. Therefore it is usually worthwhile to prune the network before answering the query

Bucket Elimination

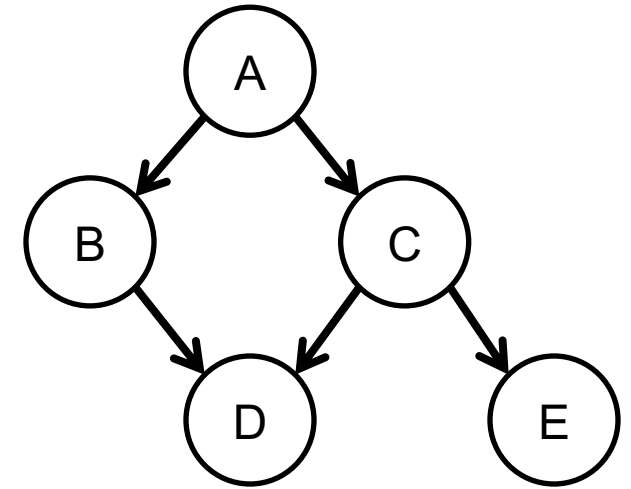
- VE requires to identify all factors that mention a particular variable
 - Best complexity if factors are found in linear time in the number of factors
- One method is to arrange the factors into *buckets*
 - One bucket for each network variable
- For instance, assume the elimination order: E, B, C, D, A



Bucket Label	Bucket Factors
E	$\Theta_{E C}$
B	$\Theta_{B A}, \Theta_{D BC}$
C	$\Theta_{C A}$
D	
A	Θ_A

Bucket Elimination

- Each factor is placed in the first bucket whose label appears in the factor
 - $\phi_C(C, A)$ goes to bucket C instead of A
- Given these buckets. We eliminate variables by processing the buckets from top to bottom
- When processing variable $\pi(i)$
 - Multiply all factors in the bucket $\pi(i)$
 - Sum out $\pi(i)$
 - Place the resulting factor f_i in the first next bucket whose label appears in f_i



Bucket Label	Bucket Factors
E	$\Theta_{E C}$
B	$\Theta_{B A}, \Theta_{D BC}$
C	$\Theta_{C A}$
D	
A	Θ_A

Bucket Elimination

- For instance, after processing bucket E , the resulting factor is placed in bucket C
- If our goal is to obtain marginals for variables D and A

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- We should process the first three buckets
- The buckets for D and A will contain a factored representation of the marginal
- We can multiply these factors or simply keep them in factored form

Bucket Label	Bucket Factors
E	$\Theta_{E C}$
B	$\Theta_{B A}, \Theta_{D BC}$
C	$\Theta_{C A}$
D	
A	Θ_A

Bucket Label	Bucket Factors
E	
B	$\Theta_{B A}, \Theta_{D BC}$
C	$\Theta_{C A}, \sum_E \Theta_{E C}$
D	
A	Θ_A

Bucket Elimination

- The original bucket elimination algorithm handles evidence differently

- It does not reduce the factors explicitly
 - Instead, it creates new factors

- For instance, given evidence e : $B = \text{true}$, $E = \text{false}$, it creates the factors

B	λ_B
b	1
\bar{b}	0

E	λ_E
e	0
\bar{e}	1

- λ_B and λ_E are called *evidence indicators*
 - They are added to their corresponding buckets

Bucket Label	Bucket Factors
E	$\Theta_{E C}$
B	$\Theta_{B A}, \Theta_{D BC}$
C	$\Theta_{C A}$
D	
A	Θ_A

Bucket Label	Bucket Factors
E	$\Theta_{E C}, \lambda_E$
B	$\Theta_{B A}, \Theta_{D BC}, \lambda_B$
C	$\Theta_{C A}$
D	
A	Θ_A

Conclusion

- Network pruning removes edges and nodes according to a query (Q, e)
 - Pruning may lead to significant reduction in treewidth
 - *Effective treewidth* is defined as the treewidth after pruning
- Bucket elimination
 - Algorithm that organizes the factors in buckets by variables
 - Quick access to all factors that references a variable