Given a linear map $A : \mathbb{R}^n \to \mathbb{R}^m$ and a vector in its range $b \in \mathbb{R}^m$, form the linear system $Ax = b$.

A basis $\{e_1 ... e_n\}$ in the domain of A now gives many ways to express b as a combination of the image of the basis $\{Ae_i\}_i$:

$$b = \sum_{i \in B} \lambda_i A e_i$$

for many choices of m-sized $B \subset \{1 ... n\}$ and $\lambda_i, i \in B$.

For each such choice of B, we can rewrite

$$b = A \sum_{i \in B} \lambda_i e_i$$

and denote

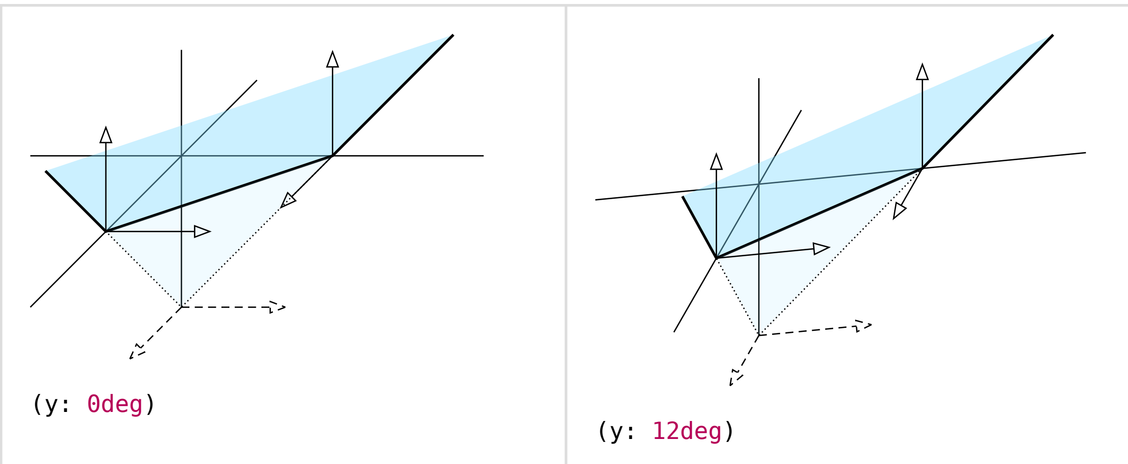
$$x_B := \sum_{i \in B} \lambda_i e_i.$$

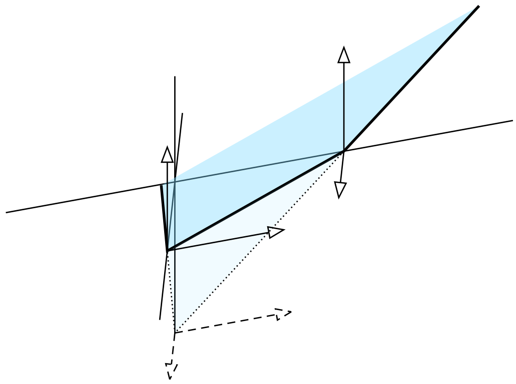
x_B is now well-defined for any choice of (a subset of) basis vectors in the domain of A whose images form a basis of A's range. Such x_B are *special* solutions to the system $Ax = b$ and are called *basic* solutions.

A general solution x can be decomposed as

$$x = x_B + x_N$$

which defines x_N. Put $N = \{1 ... n\} \setminus B$. Since x is a combination of $\{e_1 ... e_n\}$ and x_B is a (unique) combination of the B subset of the basis vectors, x_N is then a (unique) combination of the rest of the basis vectors.





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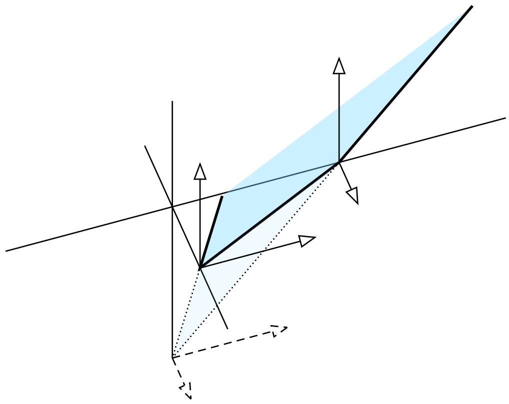

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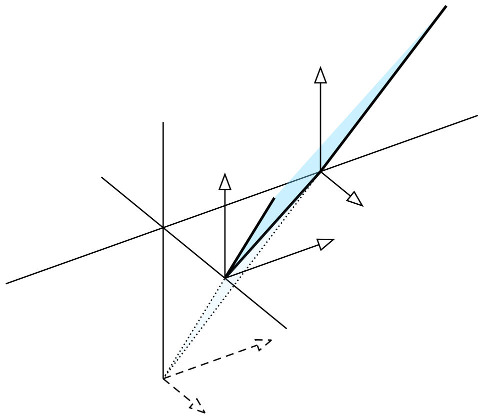

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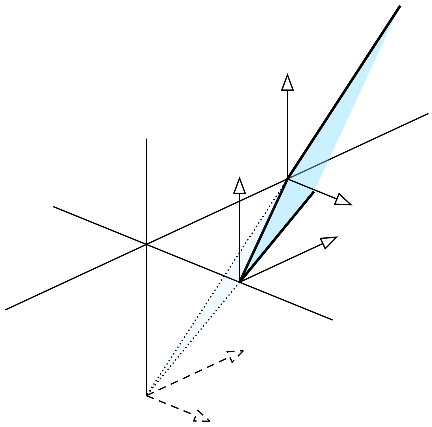

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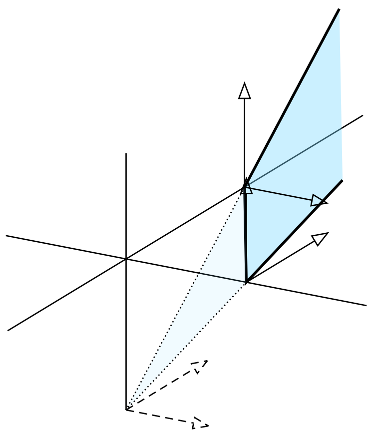

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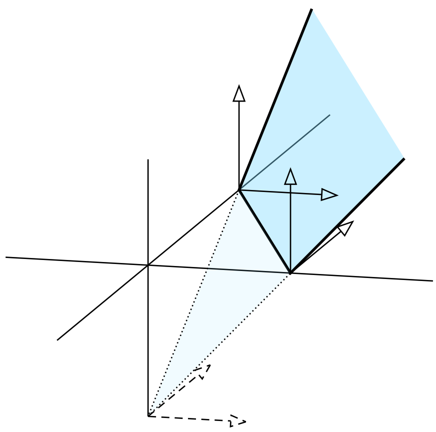

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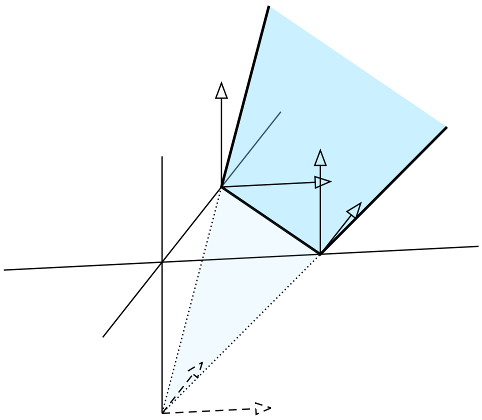

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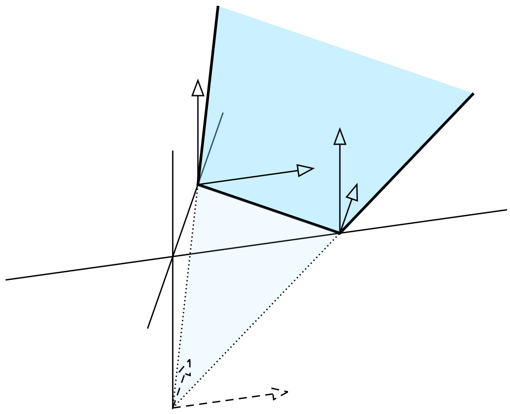

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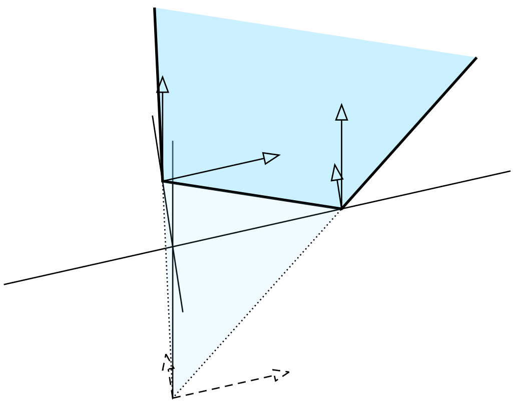

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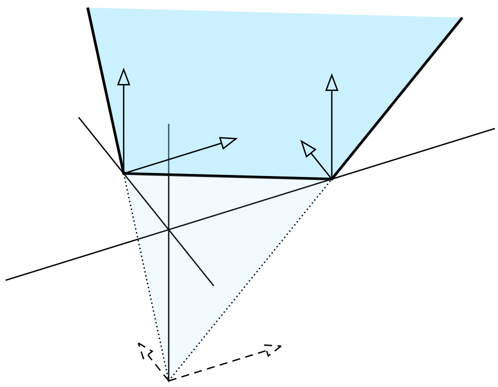

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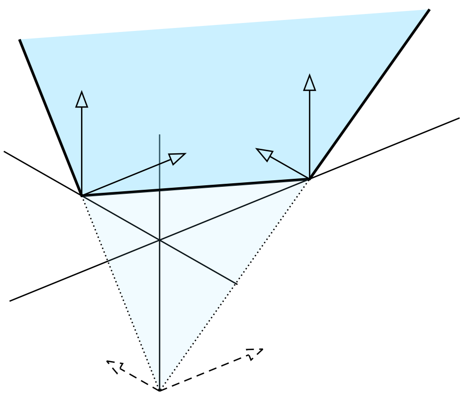

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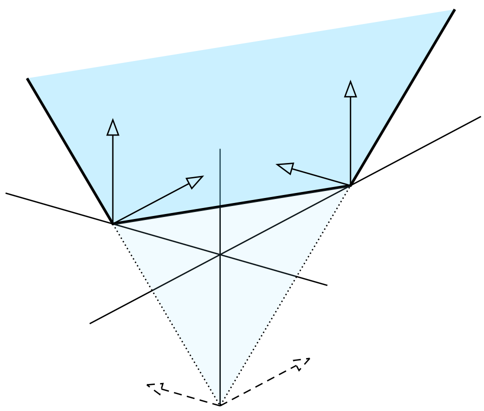

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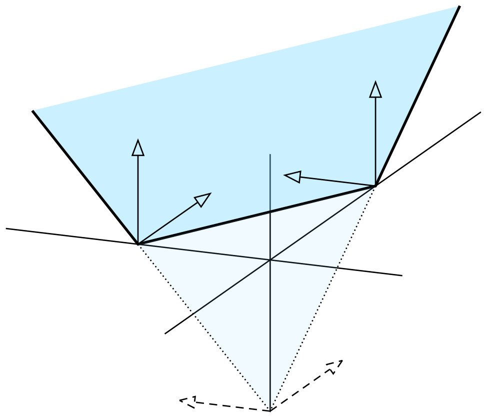

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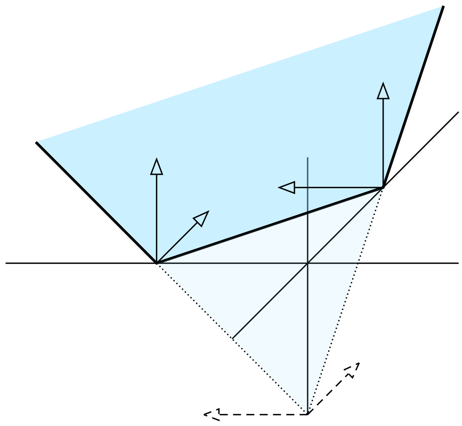

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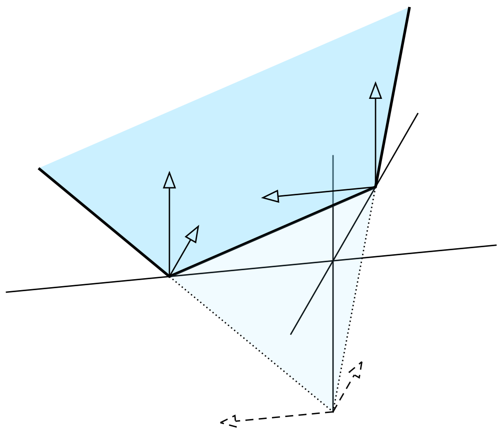

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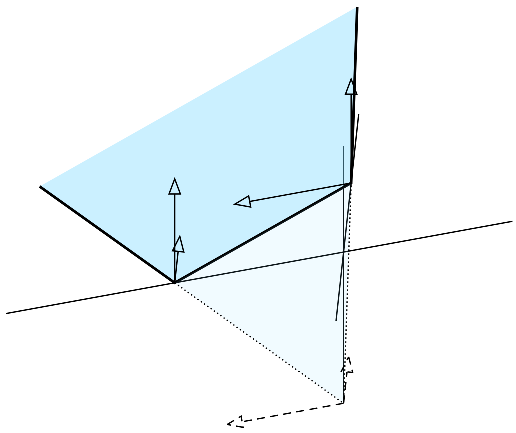

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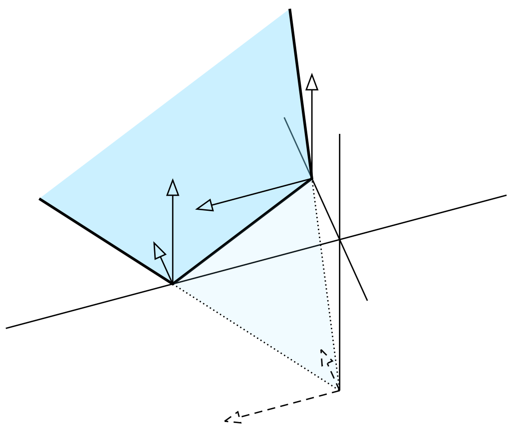

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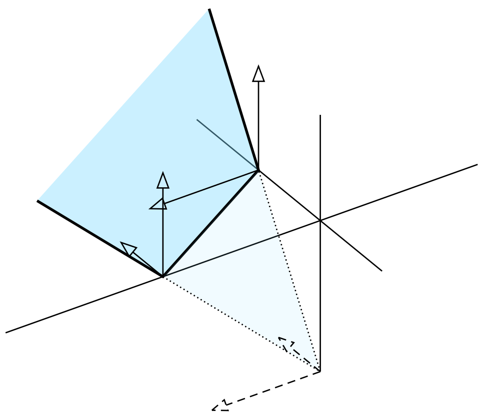

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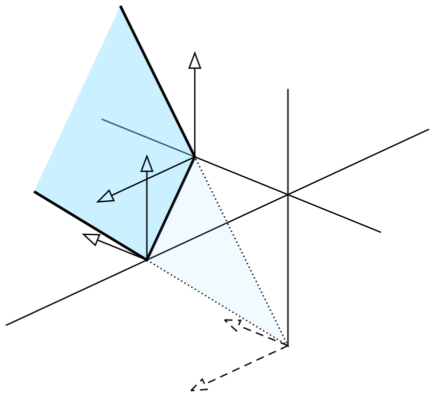

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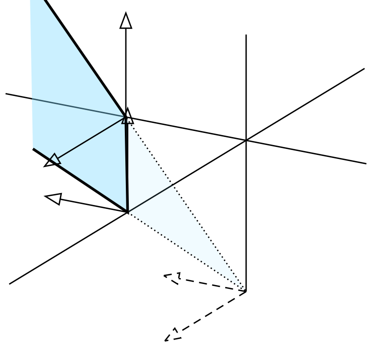

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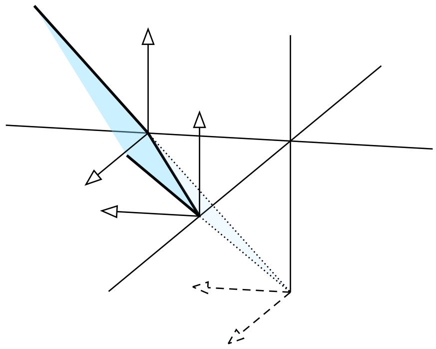

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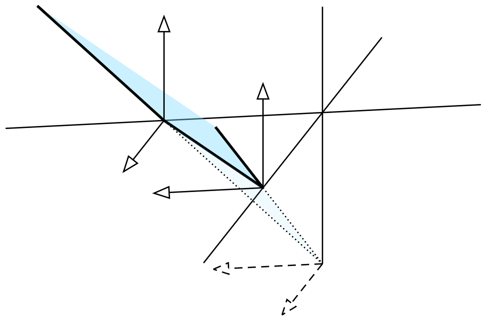

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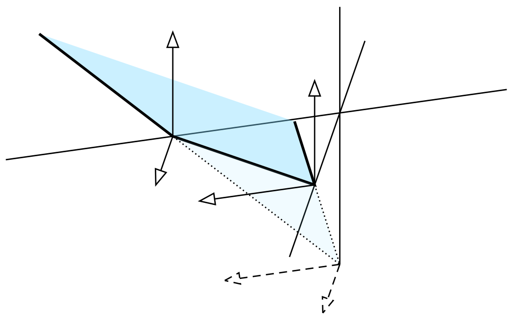

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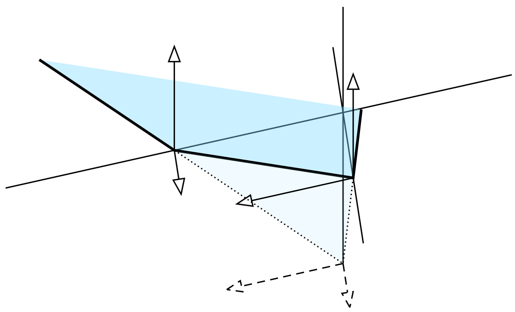

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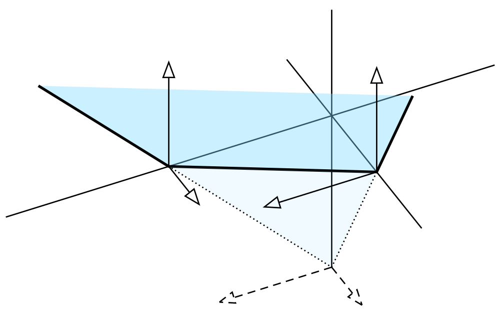

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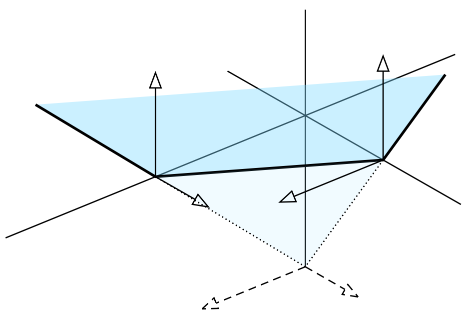

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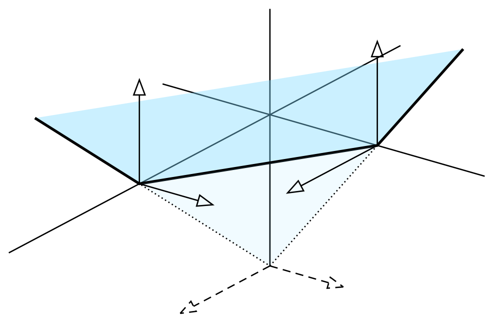

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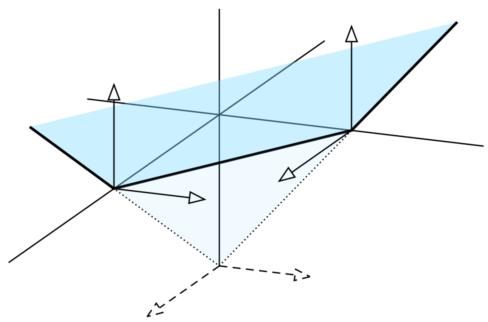

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