

REPORT

LABORATORY OF EVOLUTIONARY ALGORITHMS



Genetic Algorithm for Traveling Salesman Problem

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1. Source code

1.1. Main source code:

```
%% GA main
clear all;

% Parameters:
P=100% 250; %100, 300, 500 % number of chromosomes
n=0.5% 0.8; % 0.5, 0.7, 0.9   percentage of the population that will
become parents
pm=0.1% 0.2; % 0.1, 0.7, 0.9  mutations rate
Tmax=1000; % number of iterations
N=10; % number of cities

% Initial population:
P0=[1 2 3 4 5 6 7 8 9 10];
Population=initPop(P0,P);
% Distance matrix for map number 1:
x = [0 3 6 7 15 12 14 9 7 0];
y = [1 4 5 3 0 4 10 6 9 10];
plot(x,y,'black','MarkerSize',4,'LineWidth',3);
title('Map of cities (number 1)'); hold on;
xlabel('Coord x');
ylabel('Coord y');
xlim([min(x)-2,max(x)+2]);
ylim([min(y)-2,max(y)+2]);
labels = string(1:10);
text(x-.1,y-.3, labels);
% adding connections between different points:
connect=nchoosek(1:length(x),2)';
plot(x(connect),y(connect),'Color','#FFC0CB');hold on;

% compute the distance matrix [10x10]:
Distance=zeros(length(P0)); %initialize distance matrix
for i=1:N
    for j=1:N
        Distance(i,j) = sqrt((x(i)-x(j))^2+(y(i)-y(j))^2);
    end
end

% main iteration:
for i=1:Tmax

    % Evaluation/ cost value:
    [fi,di]=evaluation(Population, Distance);
    mf=max(fi);
    ti=(mf-fi);
    ts=sum(ti);

    % select of parent population: n*P
    PPop=n*P ;% Quantity of parents chromosomes

    for i=1:PPop
        roulette=0;
        random=rand()*ts;
        dd=randperm(P);

    % first individual who exceed the random value is taken to the
    parents
```

```

for k=1:P
    roulette=roulette+ti(dd(k));
    if roulette>=random
        Parents(i,:)=Population(dd(k),:);
    end
end
half=length(Parents)/2;
P1=Parents(1:half,:);
P2=Parents(half+1:length(Parents),:);

%Cycle crossover
for i=1:length(P1)
    Offspring1(i,:)=cycle_cross(P1(i,:),P2(i,:));
    Offspring2(i,:)=cycle_cross(P2(i,:),P1(i,:));
end
Offspring=[Offspring1;Offspring2];

% Mutation
for j=1:length(Offspring)
    random_pm= rand();
    if random_pm<pm
        pos_mut=randperm(N,2); % random position of mutations
        temp=Offspring(j,pos_mut(1));
        Offspring(j,pos_mut(1))=Offspring(j,pos_mut(2));
        Offspring(j,pos_mut(2))=temp;
    end
end
% Evaluation of Offspring
[fi_O,di_O]=evaluation(Offspring, Distance);
% %Join offspring population with original population
Mixed=[Population;Offspring];

%Create new population (250 chromosomes) which have min. fi from
mixed population
Mixed_fi=[fi fi_O];
[values, index]=mink(Mixed_fi,P);
New_population=Mixed(index,:);
fi_new=Mixed_fi(index);
Population=New_population;
End

% Show the best distance and sequence:
[value1, index1]=min(fi_new);
Best_way=Population(index1,:);
Minimal_fi=value1
plot(x([Best_way,Best_way(1)]),y([Best_way,Best_way(1)]),'k.',
'MarkerSize',2,'LineWidth',1)

```

1.2. Initial population:

```

function Population = initPop(P0,P)
PP=perms(P0);
[x2 , ~]=size(PP);
Pop=[];
for i=1:P
    Pop1= PP(randi(x2),:);
    Pop=[Pop;Pop1];
end
Population=Pop;

```

1.3. Evaluation

```
function [fi,di]=evaluation(Pi,D)
% Pi = population of P chromosome
% D= matrix of distance between every cities
[xP, yP]=size(Pi);
di=zeros(xP,yP);
for j=1:xP
    tour=0;
    %Distance from the last city till first city:
    di(j,1)=D(Pi(j,1),Pi(j,yP));
    for k=1:(yP-1)
        di(j,k+1)=D(Pi(j,k),Pi(j,k+1)); % distance between every point
in given sequence
        tour=tour+di(j,k+1);
    end
    f(j)=di(j,1)+tour; % Total distance in a given sequence
end
fi=f;
di=di;
```

1.4. Cycle crossover

```
function O=cycle_cross(P1,P2)
O=[];
[~, y1]=size(P1);
O1 =zeros(1,y1);
O1(1)=P1(1); pos1=1;

for i=1:length(P1)
    pos1 = find(P1==P2(pos1));
    O1(pos1) = P1(pos1);
    if pos1==1
        empty=find(O1==0);
        O1(empty)=P2(empty);
    end

end
O=[O;O1];

OO=O;
```

2. Results

2.1. Task 1:

Parameters:

$P = 250 \rightarrow$ number of chromosomes

$n = 0.8 \rightarrow$ percentage of the population that will become parents

$p_m = 0.2 \rightarrow$ mutations rate

$T_{max} = 1000 \rightarrow$ maximum number of generations

Results:

Best_way =

7 9 10 1 2 3 4 8 6 5

Minimal_fi (minimum distance)=

55.0441

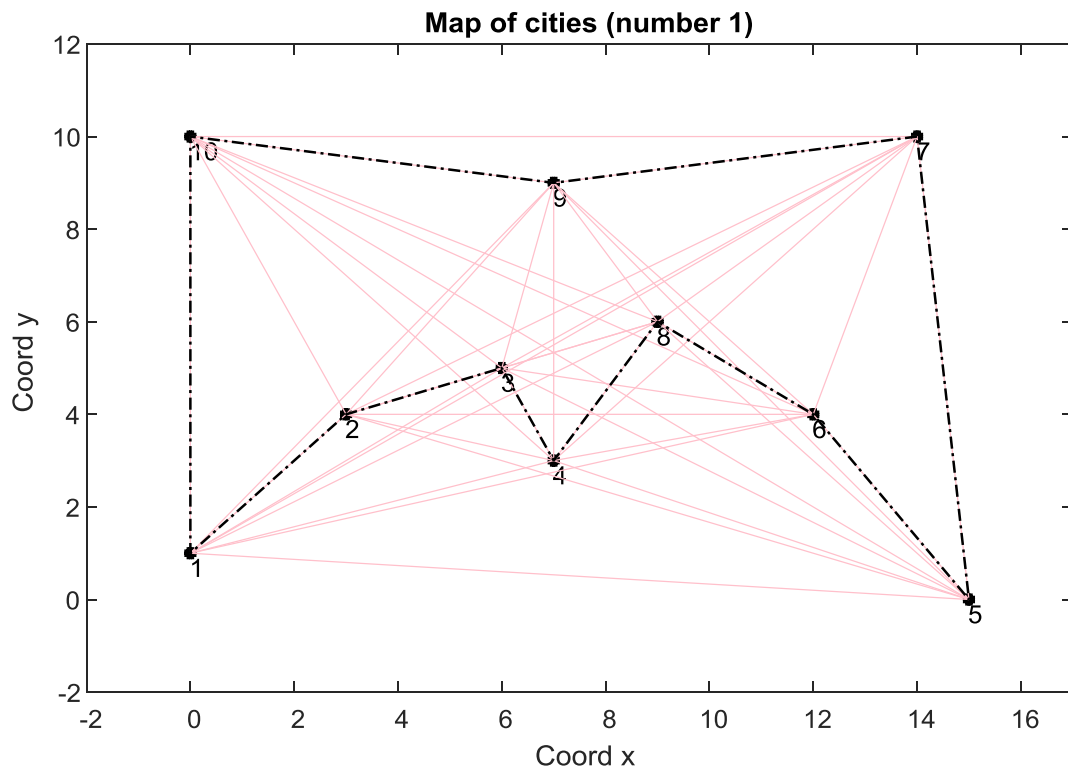


Figure 1. An example of a city network ($N=10$) with a TSP solution.

2.2. Results for task 2:

Table 1. Result table for task 2.

Minimal total distance for 10 trials			
Population size (P)	Crossover probability (n)	Mutation probability (p_m)	Mean of the minimal cost
100	0.5	0.1	55.5167
		0.3	55.15314
		0.5	55.3167
	0.7	0.1	55.15314
		0.3	55.09862
		0.5	55.20766
	0.9	0.1	55.26218
		0.3	55.51184
		0.5	55.09862
300	0.5	0.1	55.0441
		0.3	55.0441
		0.5	55.0441
	0.7	0.1	55.0441
		0.3	55.0441
		0.5	55.0441
	0.9	0.1	55.0441
		0.3	55.0441
		0.5	55.0441
500	0.5	0.1	55.0441
		0.3	55.0441
		0.5	55.0441
	0.7	0.1	55.0441
		0.3	55.0441
		0.5	55.0441
	0.9	0.1	55.0441
		0.3	55.0441
		0.5	55.0441

3. Conclusions

Genetic algorithms are very useful for solving optimization problems, image recognition and predicting stock market movements. In the traveling salesman problem, the main goal is to find the shortest distance between N different cities. In our algorithm, the number of cities that could be visited was 10, and the number of generations (iterations of the algorithm was 1000). The size of the population, the mutation rate and the percentage of the population included in the parental pool were variable parameters. The genetic algorithm in solving the traveling salesman problem

uses primarily randomness in the selection of the population, crossover and mutation to best reflect the populations present in nature.

Based on the obtained results, it can be concluded that the size of the population is of great importance in the case of solving the traveling salesman problem with the use of a genetic algorithm. In the case where the population size was 100, the algorithm failed to find the most optimal route each time. Since we have 10 cities, the number of possible permutations is $10!$ which gives over 3 million possible routes. In the case of a population of 100, we randomly choose only 100 out of these three million possible options, so it could happen that a randomly selected population would have less optimal routes, although sometimes it happens that crossing two weak individuals together gives offspring with a good genotype. If we select a larger population, it is more likely to encounter the most optimal route. It may also happen that a function stops at some local minimum and therefore may give worse results.

In the case when the population size was 300 and 500, the algorithm managed to find the shortest route for the first and each subsequent time. Even changing parameters such as the mutation rate (p_m) or the percentage of chromosomes selected for the parental pool (n) did not affect the algorithm's result. It follows that for the analyzed map of cities (number 1), the population of 100 individuals is insufficient to determine the optimal and shortest route.