## dq0\_to\_abc\_2.xbe

## **Attributes**

xbe name=dq0\_to\_abc\_2 evaluate=yes

Jacobian: variable

input\_vars: xd xq x0 theta
output\_vars: xa xb xc

aux\_vars: c s

iparms:
sparms:
rparms:
stparms:
igparms:

outparms: xd xq x0 xa xb xc

## **Description**

dq0\_to\_abc\_2.xbe employs the following equations to relate xd, xq, x0, theta to xa, xb, xc:

$$\begin{bmatrix} x_a \\ x_b \\ x_c \end{bmatrix} = \begin{bmatrix} \cos\theta & \sin\theta & 1 \\ \cos(\theta - 2\pi/3) & \sin(\theta - 2\pi/3) & 1 \\ \cos(\theta + 2\pi/3) & \sin(\theta + 2\pi/3) & 1 \end{bmatrix} \begin{bmatrix} x_d \\ x_q \\ x_0 \end{bmatrix}.$$