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List of Abbreviations

EOS	E quation of S tate
GR	G eneral R elativity
LE	L ane- E mden
TOV	T olman O ppenheimer V olkoff

List of Symbols

Just a test

Units

This thesis uses the natural number system if not otherwise explicitly mentioned. This means $\hbar = c = G = k_B = 1$.

Abstract

This is not a good example for an abstract.

1 Contact Formulation of Thermodynamics

1.1 Motivation

Concepts and basic definitions can be read in the book [1] by Eschrig. The work in this chapter is mainly motivated by [2, 3, 4]. Throughout this section we will if not otherwise mentioned assume smoothness of manifolds and mappings. Also the Einstein summing convention will be used.

The theory of thermodynamics relates extensive quantities (eg. volume V , particle number N or entropy S) to a potential function Φ that resembles a form of energy of the thermodynamic system. In thermal equilibrium, the first law of thermodynamics states that

$$dU = \delta Q + \delta W \quad (1.1.1)$$

where U refers to the internal energy, Q to the heat of the system and W the work done. In physicists notation the δ -symbol is used to indicate that the 1-form considered here is not a exact differential. On the other hand, dU is postulated to be a exact differential of the internal energy U . In a thermodynamic system with variables (S, V, U, T, p) the first law can be expressed as

$$dU = TdS - pdV. \quad (1.1.2)$$

By writing down this equation, we see that $\partial U/\partial S = T$ and $\partial U/\partial V = -p$. This relates intensive parameters like p, T to extensive parameters V, S via derivatives. Considering the canonical ensemble, a potential function is given by the free energy

$$F = U - TS \quad (1.1.3)$$

from which all intensive parameters can be obtained by differentiating, for example

$$\frac{\partial F}{\partial V} = -p. \quad (1.1.4)$$

If we want to consider the intensive parameters as independent variables, we run into problems, since if U depends on X_n extensive and P_n intensive parameters, we have

$$dU = \frac{\partial U}{\partial X^i} dX^i + \frac{\partial U}{\partial P^i} dP^i = P_i dX^i + \frac{\partial U}{\partial P^i} dP^i. \quad (1.1.5)$$

But since the first law requires $dU = P_i dX^i \Rightarrow U = P_i X^i$, we obtain

$$0 = X_i dP^i \Rightarrow X_i = 0. \quad (1.1.6)$$

This poses the question on which space and in what manner these concepts can be defined rigidly. Clearly, since we are dealing with total derivatives, the aim is to consider a manifold on which the variables live. When considering variables $(U, X^1, \dots, X^n, P^1, \dots, P^n)$, one promptly notices that the system is overdefined since U is directly dependent on the other variables. However this only holds in thermal equilibrium and thus thermal equilibrium is a submanifold of the collection of these variables. Mathematical rigor of these statements is the aim of the next section.

1.2 Formal Definitions

Definition 1.1 - Distribution, Contact Element

A smooth distribution Δ of dimension m on a manifold M^n assigns at each point $p \in M$ a m -dimensional ($m \leq n$) subspace $\Delta_p \subseteq T_p M$ in such a way that for a neighborhood U of p there exist smooth vector fields X_1, \dots, X_m such that for every point $y \in U$ the subspace $\Delta_y = \text{span}(X_1(y), \dots, X_m(y))$. The set of smooth vector fields is called a local base of Δ . A tangent vector X is said to belong to Δ if $X(p) \in \Delta_p$ for all $p \in M$.

A smooth distribution of dimension $n - 1$ on a n -dimensional Manifold is called a contact element.

Definition 1.2 - Involutive Distribution, Integral Manifold

A distribution is called involutive if for two vector fields X, Y belonging to Δ , the Lie bracket $[X, Y]$ also belongs to Δ . A connected submanifold N with its natural embedding $\iota : N \hookrightarrow M$ is called integral manifold of a distribution Δ on N if $\iota_*^p(T_p N) = \Delta_{\iota(p)}$. That means that at any point $p \in N$, the tangent space $T_p N$ which is a subspace of $T_p M$ is given by $\Delta_{\iota(p)} = \Delta_p$ (since $\iota(p) = p$ for all $p \in N$).

Corollary 1.3

Every contact element can be given locally by the kernel of a 1-form ω . As a direct consequence every distribution of dimension $m < n$ can be given locally by the intersection of the kernels of m linear independent 1-forms. On the other hand a (global) 1-form defines a distribution at any point $p \in M$.

Example 1.4

In the space of thermodynamic variables M^{2n+1} that is locally given by the coordinates $(\Phi, X^1, \dots, X^n, P^1, \dots, P^n)$ the 1-form

$$\theta = d\Phi - P_i dX^i \quad (1.2.1)$$

defines a contact element via $\theta = 0$. The contact element is the subspace of $T_p M$ on which

$$d\Phi = P_i dX^i. \quad (1.2.2)$$

We see that the 1-form chosen satisfies the important relation $\theta \wedge (d\theta)^n \neq 0$ this will be used to define what a contact form is on a manifold.

The next statement will be the Frobenius theorem. It will be the justification why a geometric theory of thermodynamics must be formulated with contact manifolds.

Theorem 1.5 - Frobenius Theorem

Let Δ be a m -dimensional distribution on a manifold M^n with $1 \leq m \leq n$. There is a uniquely defined maximal connected integral manifold (N_p, ι_p) through every point $p \in M$ if and only if Δ is involutive.

Theorem 1.6 - "Dual" Frobenius Theorem

Given a m -dimensional distribution Δ in a sufficiently small neighborhood U of p there is an $(n - m)$ -dimensional annihilator subspace of $T_p^* M$ given by the dual of the orthogonal complement of Δ_p . This space D_p^\perp is spanned by $n - m$ linearly independent differential 1-forms $\omega_{m+1}, \dots, \omega_n$ which can be completed by addition of forms to form a complete basis of $T_p^* M$ for points $p \in U$. The set D_p^\perp can be characterised by the equation

$$\omega_j^i(p) dx^j = 0 \quad (1.2.3)$$

for all $i > m$ and $p \in U$. The statement of the theorem then says that this system of equations describes a submanifold $\iota : N \hookrightarrow M$ if and only if for $i > m$

$$d\omega^i \wedge \omega^{m+1} \wedge \cdots \wedge \omega^n = 0. \quad (1.2.4)$$

In this case the system is said to be completely integrable. A proof of both forms of this theorem can be found in [1, p. 78].

Example 1.7 - Adiabatic Submanifolds

The heat exchange 1-form of a thermodynamical system M^{2n+1} with local coordinates $(\Phi, S, X^2, \dots, X^n, T, P^2, \dots, P^n)$ for $n-1$ other (in principle here not relevant) extensive and intensive quantities X^i, P^i is given by

$$\delta Q = TdS. \quad (1.2.5)$$

Adiabaticity of a thermodynamic system means no exchange of heat $\delta Q = 0$. This characterises a distribution of dimension $2n$ and simultaneously states that the differential forms defining D_p^\perp are given by this equation and in this case is solely $TdS = 0$. To obtain a basis of $T_p M$ we take the canonical differential 1-forms dX^i, dT, dP^i . Then, it is clear that

$$d\delta Q \wedge dX^2 \wedge \cdots \wedge dX^n \wedge dT \wedge dP^2 \wedge \cdots \wedge dP^n = 0 \quad (1.2.6)$$

since $d\delta Q = dT \wedge dS$ and dT appears again in the \wedge -product, the whole term vanishes. Thus the requirements for the Frobenius theorem are satisfied and there exists a $2n$ -dimensional submanifold $N \subset M$ on which adiabatic processes take place.

Another important theorem is the Darboux Theorem [5] which gives us a standard coordinate representation for any contact structure later introduced.

Theorem 1.8 - Darboux's Theorem

To a 1-form ω on a n -dimensional manifold M^n that satisfies

$$\omega \wedge (d\omega)^p = \omega \wedge d\omega \wedge \cdots \wedge d\omega = 0 \quad (1.2.7)$$

there exist local coordinates $(x^1, \dots, x^{n-p}, y^1, \dots, y^p)$ such that ω can be written as

$$\omega = x^i dy^i = x^1 dy^1 + \cdots + x^p dy^p. \quad (1.2.8)$$

A 1-form that fulfills

$$\omega \wedge (d\omega)^p \neq 0 \quad (1.2.9)$$

can be equipped with local coordinates $(x^0, \dots, x^{n-p-1}, y^1, \dots, y^p)$ such that

$$\omega = dx^0 + x^i dy^i = dx^0 + x^1 dy^1 + \cdots + x^p dy^p. \quad (1.2.10)$$

Lemma 1.9

A 1-form on a $2n+1$ -dimensional manifold M that satisfies

$$\theta \wedge (d\theta)^n \neq 0 \quad (1.2.11)$$

does not define a submanifold via $\theta = 0$.

Proof. We choose local coordinates as given by the Darboux theorem above. Since $\theta = 0$ characterises a contact element, we only have one single defining equation and thus equation 1.2.4 can in our setting be expressed as

$$\theta \wedge (dx^1 \wedge \cdots \wedge dx^n \wedge dy^1 \wedge \cdots \wedge dy^n) = 0 \quad (1.2.12)$$

for a manifold to exist. Here we completed θ to the set $\{\theta, dx^i, dy^i\}$ which is linearly independent. But since $d\theta = dx_i \wedge dy^i$ and $(dx^i \wedge dy^i)$ and $(dx^j \wedge dy^j)$ commute, we also have

$$\theta \wedge (d\theta)^n = n\theta \wedge (dx^1 \wedge \cdots \wedge dy^n) \neq 0. \quad (1.2.13)$$

From this it can be already read of that equation 1.2.4 can not be fulfilled. \square

Remark

As we have already forewarned, it is not possible to find a suitable submanifold of M^{2n+1} such that the thermodynamic system in equilibrium can be treated globally. However as we have already seen this is still the case for other processes of such thermodynamic systems. In particular considering processes that involve only 1 coordinate (eg. isobaric $dp = 0$). In this case a distribution is always involutive since $d(dp) = 0$ and thus it is easily integrable.

Definition 1.10 - Contact Form and Manifold

A smooth 1-form θ that satisfies

$$\theta \wedge (d\theta)^n \neq 0 \quad (1.2.14)$$

(meaning the n th \wedge -product of $d\theta$) is called a contact form. A $2n+1$ -dimensional manifold with such a form (M, θ) is called a contact manifold. A contact form defines at any point $p \in M$ a contact element via $\theta = 0$. Such a contact element is also called contact structure. Note that a contact form is only defined up to a multiplicative constant $\lambda \neq 0$.

Definition 1.11 - Equilibrium (Legendre) Submanifold

A Legendre submanifold of a $2n+1$ -dimensional contact manifold (M, θ) is a n -dimensional submanifold $\iota : N \hookrightarrow M$ such that

$$\iota^*(\theta) = 0. \quad (1.2.15)$$

Since this corresponds to a thermodynamical system in equilibrium, we often refer to this as being a equilibrium (sub)manifold.

Corollary 1.12

Since locally, a contact form is always given by standard coordinates, a Legendre submanifold is specified by equations

$$x^0 = \Phi(y^1, \dots, y^n) \quad x^i = \frac{\partial \Phi}{\partial y^i}. \quad (1.2.16)$$

For a thermodynamical system with extensive variables X^i and intensive variables P^i and potential Φ this means

$$\Phi = \Phi(X^1, \dots, X^n) \quad P^i = \frac{\partial \Phi}{\partial X^i} \quad (1.2.17)$$

where we abused notation in the first equation to simultaneously label the function Φ and coordinate Φ with the same symbol. On this Legendre submanifold the usual thermodynamic equations for deriving expressions for intensive variables with respect to the potential hold.

Definition 1.13 - Contact transformations

Given two contact manifolds (M, θ) and (N, ω) , a diffeomorphism $\phi : N \rightarrow M$ is called a contact diffeomorphism if it preserves the contact structure, meaning

$$\phi^*(\omega) = f\theta \quad (1.2.18)$$

where f is a nonvanishing function on M . If $f = 1$, we call ϕ a strict contact transformation.

Corollary 1.14

Since pullback and exterior derivative commute, we have that given a contact form θ , a contact transformation implies

$$\begin{aligned} \phi^*(\omega \wedge (d\omega)^n) &= \phi^*(\omega) \wedge \phi^*((d\omega)^n) \\ &= \phi^*(\omega) \wedge (\phi^*(d\omega))^n \\ &= \phi^*(\omega) \wedge (d(\phi^*\omega))^n \\ &= f\theta \wedge (d(f\theta))^n \\ &= f\theta \wedge (df \wedge \theta + fd\theta)^n \end{aligned}$$

Now whenever the product of n forms contains the 1-form θ , the total product vanishes since $\theta \wedge \theta = 0$. Thus the only term that survives is

$$\phi^*(\omega \wedge (d\omega)^n) = f\theta \wedge (fd\theta)^n = f^{n+1}\theta \wedge (d\theta)^n \quad (1.2.19)$$

and for $f \neq 0$ and by injectivity of ϕ^* (since ϕ was a diffeomorphism), we immediately see that if ω (or resp. θ) is a contact form, so is the other.

The next section aims to rigorously define what the phase space of thermodynamic coordinates is and gives the definitions from this section a physical interpretation.

1.3 Thermodynamic Phase Space and Postulates

Postulate - Thermodynamic Phase Space

To every thermodynamic system corresponds a thermodynamic phase space (TPS) which is a $2n + 1$ -dimensional contact manifold (M, θ) with intensive and extensive variables as coordinates. A equilibrium state of such a thermodynamic system is represented by a Legendre submanifold of the contact manifold (M, θ) .

Example 1.15 - Canonical Ensemble

In the canonical ensemble, the Free Energy is the potential. We choose coordinates $(\mathcal{F}, -S, V, N, T, -p, \mu)$ and the contact form

$$\theta = d\mathcal{F} + SdT + pdV - \mu dN. \quad (1.3.1)$$

The heat exchange 1-form δQ is then given by $\delta Q = SdT$. For applications in Physics, the free energy in thermal equilibrium often times is given by a partition function \mathcal{Z} via the relation

$$\mathcal{F}(T, V, N) = -k_B T \log(\mathcal{Z}(T, V, N)). \quad (1.3.2)$$

This means on the Legendre submanifold where $\theta = 0$, we have

$$S = -\frac{\partial \mathcal{F}}{\partial T} = k_B \left(1 + T \frac{1}{\mathcal{Z}} \frac{\partial \mathcal{Z}}{\partial T} \right) \quad (1.3.3)$$

$$p = -\frac{\partial \mathcal{F}}{\partial V} = k_B T \frac{1}{\mathcal{Z}} \frac{\partial \mathcal{Z}}{\partial V} \quad (1.3.4)$$

$$\mu = \frac{\partial \mathcal{F}}{\partial N} = k_B T \frac{1}{\mathcal{Z}} \frac{\partial \mathcal{Z}}{\partial N}. \quad (1.3.5)$$

The partition function \mathcal{Z} can be calculated explicitly from the microscopic behaviour of the system given by the Hamilton Mechanics of the particles/fluids involved. Such a direct calculation is done in the next chapter. Often times the particle number N is assumed to be fixed and thus not be taken as a coordinate but simply as a whole number $N \in \mathbb{N}$.

Example 1.16 - Microcanonical Ensemble

In the microcanonical ensemble, the potential is given by the entropy S of the system. Thus we can choose coordinates $(S, E, V, N, 1/T, p/T, -\mu/T)$ and obtain the contact form

$$\theta = dS - \frac{1}{T}dE - \frac{p}{T}dV + \frac{\mu}{T}dN. \quad (1.3.6)$$

The transformation $\kappa : (x_0, x_1, x_2, x_3, p_1, p_2, p_3) \mapsto (x_1, x_0, x_2, x_3, 1/p_1, -p_2/p_1, -p_3/p_1)$ has the differential

$$D\kappa = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & -\frac{1}{p_1^2} & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{p_2}{p_1^2} & -\frac{1}{p_1} & 0 \\ 0 & 0 & 0 & 0 & \frac{p_3}{p_1^2} & 0 & -\frac{1}{p_1} \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & -T^2 & 0 & 0 \\ 0 & 0 & 0 & 0 & pT & -T & 0 \\ 0 & 0 & 0 & 0 & \mu T & 0 & -T \end{bmatrix}. \quad (1.3.7)$$

Clearly, the mapping is a diffeomorphism and since $\kappa^*(\theta) = dE - TdS + pdV - \mu dN$, the mapping is a contact transformation and on the Legendre submanifold, we have $dE = TdS - pdV + \mu dN$.

2 The Internal Energy calculated explicitly

The canonical ensemble was introduced in its mathematical form in the previous section. On the equilibrium submanifold of the TPS B , we can write the free energy as a function of the partition function \mathcal{Z} . The internal energy is then obtained by a change of coordinates or simply the equation $\mathcal{F} = \mathcal{U} + TS$. Microscopically the partition function is given by the behaviour of the N particles determined by the Hamiltonian H . Concepts and definitions of Hamilton Mechanics can be read in [1, 6, 7, 8, 9, 10]. In general we assume $H : TM^N \rightarrow \mathbb{R}$ to be a positive smooth function on the manifold of space-time M . This explicitly takes form in the well known equations

$$\mathcal{Z}(T, V, N) = \int_{TM^N} \exp\left(-\frac{H(x_1, \dots, x_N, p_1, \dots, p_N)}{k_B T}\right) \frac{dx_1 dp_1 \dots dx_N dp_N}{N! h^{3N}} \quad (2.0.1)$$

$$\mathcal{F}(T, V, N) = -k_B T \log(\mathcal{Z}(T, V, N)) \quad (2.0.2)$$

$$\mathcal{U}(T, V, N) = \mathcal{F} + TS \quad (2.0.3)$$

$$= \mathcal{F} - T \frac{\partial \mathcal{F}}{\partial T} \quad (2.0.4)$$

$$= k_B T^2 \frac{1}{\mathcal{Z}} \frac{\partial \mathcal{Z}}{\partial T}. \quad (2.0.5)$$

where $x_i \in M$ and $p_i \in T_{x_i} M$. The last equation shows that to fully calculate U it is necessary to obtain a readable output from \mathcal{Z} .

2.1 The Ultra-Relativistic Case

First we inspect the ultra-relativistic Hamiltonian given by

$$H(\vec{x}, \vec{p}) = ||\vec{p}||c. \quad (2.1.1)$$

The corresponding partition function for a N particle system then reads ($\beta = (k_B T)^{-1}$)

$$\mathcal{Z} = \frac{V^N}{N! h^{3N}} \left[\int_{\mathbb{R}^3} \exp(-\beta H(\vec{p})) d^3 p \right]^N \quad (2.1.2)$$

$$= \frac{V^N}{N! h^{3N}} \left[\int_0^\infty 4\pi p^2 \exp(-\beta pc) dp \right]^N \quad (2.1.3)$$

$$= \frac{V^N}{N! h^{3N}} \frac{(4\pi)^N (k_B T)^{3N}}{c^{3N}} \left[\int_0^\infty x^2 \exp(-x) dx \right]^N \quad (2.1.4)$$

$$\mathcal{Z} = \frac{1}{N!} \left(8\pi V \left(\frac{k_B T}{hc} \right)^3 \right)^N \quad (2.1.5)$$

where from the first to second line we used usual spherical coordinates and afterwards used the integral transformation $x = \beta cp$. The remaining integral \mathcal{U} can be solved to be exactly $= 2$ and the internal energy can now be written down and further approximated to subjective needs.

2.2 The Special-Relativistic Case

We will now turn our attention to the fully special-relativistic Hamiltonian given by

$$H = mc^2 \sqrt{1 + \frac{\vec{p}^2}{m^2 c^2}}. \quad (2.2.1)$$

In doing so, we keep in mind that the ultra relativistic limit can be obtained from this Hamiltonian by letting $m \rightarrow 0$. In this limiting case we should be able to recover the results from equation (2.1.5).

$$\mathcal{Z} = \frac{V^N}{N! h^{3N}} \left[\int_{\mathbb{R}^3} \exp \left(-\frac{mc^2 \sqrt{1 + \frac{\vec{p}^2}{m^2 c^2}}}{k_B T} \right) d^3 p \right]^N \quad (2.2.2)$$

$$= \frac{V^N}{N! h^{3N}} \left[\int_0^\infty 4\pi p^2 \exp \left(-\beta mc^2 \sqrt{1 + \frac{p^2}{m^2 c^2}} \right) dp \right]^N \quad (2.2.3)$$

$$= \frac{(4\pi V)^N}{N!} \left(\frac{mc}{h} \right)^{3N} \left[\int_0^\infty q^2 \exp \left(-\alpha \sqrt{1 + q^2} \right) dq \right]^N \quad (2.2.4)$$

$$= \frac{(4\pi V)^N}{N!} \left(\frac{mc}{h} \right)^{3N} \left(\int_0^\infty \sinh(x)^2 \cosh(x) \exp(-\alpha \cosh(x)) dx \right)^N \quad (2.2.5)$$

$$= \frac{(4\pi V)^N}{N!} \left(\frac{mc}{h} \right)^{3N} \left(\int_0^\infty \frac{\sinh(2x)}{2} \sinh(x) \exp(-\alpha \cosh(x)) dx \right)^N \quad (2.2.6)$$

$$= \frac{(4\pi V)^N}{N!} \left(\frac{mc}{h} \right)^{3N} \left(-\frac{\sinh(2x)}{2\alpha} \exp(-\alpha \cosh(x)) \Big|_0^\infty \right. \quad (2.2.7)$$

$$\left. + \frac{1}{\alpha} \int_0^\infty \cosh(2x) \exp(-\alpha \cosh(x)) dx \right)^N \quad (2.2.8)$$

$$= \frac{(4\pi V)^N}{N!} \left(\frac{mc}{h} \right)^{3N} \left(\frac{1}{\alpha} \int_0^\infty \cosh(2x) \exp(-\alpha \cosh(x)) dx \right)^N \quad (2.2.9)$$

$$= \frac{1}{N!} \left(8\pi V \left(\frac{k_B T}{hc} \right)^3 2\alpha^2 K_2(\alpha) \right)^N \quad (2.2.10)$$

In the first step we used spherical coordinates followed by the substitution $qmc = p$ and $\alpha = \beta mc^2 = mc^2/k_B T$. Afterwards we substituted $q = \sinh(x)$ and used the identity $\cosh(x) \sinh(x) = \sinh(2x)/2$. Partial integration then leads to the last integral which can be identified as the modified Bessel function of the 2nd kind $K_2(\alpha)$. The equation is then rewritten such that the ultra relativistic limit can be read off upon letting $\alpha \rightarrow 0$.

We can now calculate the internal energy \mathcal{U} from \mathcal{Z} via equation (2.0.5)

$$\mathcal{U} = 3Nk_B T - Nk_B T \left(\alpha \frac{\partial_\alpha K_2(\alpha)}{K_2(\alpha)} + 2 \right). \quad (2.2.11)$$

Again, it can be seen that the ultra relativistic limit can be obtained by letting $\alpha \rightarrow 0$ since the term written in brackets vanishes in this case.

From equation (2.2.10) and (2.0.2), we immediately derive the ideal gas equation via the definition of pressure in the canonical ensemble

$$p = \frac{\partial \mathcal{F}}{\partial V} = \frac{Nk_B T}{V}. \quad (2.2.12)$$

2.3 Deriving an equation of state

This section aims to develop an equation between the thermodynamic energy density $\rho = \mathcal{U}/V$ and the pressure p of the gas given by the ideal gas equation (2.2.12). This is done by assuming an additional constraint and thus further reducing the degrees of freedom of the thermodynamic system.

When assuming an adiabatic condition $\delta Q = 0$ and using the First Law of Thermodynamics $dU = \delta Q + \delta W$, where $\delta W = -pdV$ and $dU = C_V dT$, we can relate pressure and temperature. Using equation 2.2.11 and 2.2.12, we obtain

$$-pdV = C_V dT \quad (2.3.1)$$

$$-\frac{Nk_B T}{V} dV = Nk_B \left[1 + \alpha^2 \left(\left(\frac{\partial_\alpha K_2(\alpha)}{K_2(\alpha)} \right)^2 - \frac{\partial_\alpha^2 K_2(\alpha)}{K_2(\alpha)} \right) \right] dT \quad (2.3.2)$$

$$-\frac{dV}{V} = \left[1 - \alpha^2 \partial_\alpha \left(\frac{\partial_\alpha K_2(\alpha)}{K_2(\alpha)} \right) \right] \frac{dT}{T} \quad (2.3.3)$$

$$= \left[1 - \alpha^2 \partial_\alpha^2 (\log K_2(\alpha)) \right] \frac{dT}{T} \quad (2.3.4)$$

This equation also shows explicitly the T dependence of the specific heat C_V for the non-ultra-relativistic case. Again, taking the ultra-relativistic-limit by taking $\alpha \rightarrow 0$, one can calculate that the right hand term in the first equation converges to $-2Nk_B$. This agrees with the expected specific heat for an ultra-relativistic gas $C_{V,ur} = 3Nk_B$. With the identity $d\alpha/\alpha = -dT/T$ (using $\alpha = mc^2/k_B T$), we can transform the equation and integrate it. After applying partial integration, the result is

$$\frac{dV}{V} = (1 - \alpha^2 \partial_\alpha^2 \log K_2(\alpha)) \frac{d\alpha}{\alpha} \quad (2.3.5)$$

$$\log \left(\frac{V}{V_0} \right) = \log \left(\frac{\alpha}{\alpha_0} \right) - \int_{\alpha_0}^{\alpha} \alpha \frac{\partial^2}{\partial \alpha^2} \log(K_2(\alpha')) d\alpha' \quad (2.3.6)$$

$$= \log \left(\frac{\alpha}{\alpha_0} \right) + \log \left(\frac{K_2(\alpha)}{K_2(\alpha_0)} \right) - \left[\alpha \frac{\partial_\alpha K_2}{K_2} \right]_{\alpha_0}^{\alpha} \quad (2.3.7)$$

This equation enables us to write down a relation between volume and temperature (encapsulated in $\alpha = mc^2/k_B T$)

$$V(\alpha) = \frac{\alpha K_2(\alpha)}{C} \exp \left(\alpha \frac{K_3(\alpha) + K_1(\alpha)}{2K_2(\alpha)} \right) \quad (2.3.8)$$

where the constant C is defined by the equation beforehand and only depends on the integration boundaries α_0 and V_0 . It is given by

$$C = \frac{\alpha_0 K_2(\alpha_0)}{V_0} \exp \left(\alpha_0 \frac{K_1(\alpha_0) + K_3(\alpha_0)}{2K_2(\alpha_0)} \right). \quad (2.3.9)$$

Since the goal of this section is to obtain a readable output for an equation of state, it is necessary to construct a bijection relating p and T . This is made clear when writing down the energy density

$$\rho = \frac{\mathcal{U}}{V} = \frac{Nk_B T}{V} - \frac{Nk_B T}{V} \left(\alpha \frac{\partial_\alpha K_2(\alpha)}{K_2(\alpha)} \right) \quad (2.3.10)$$

where $p = Nk_B T/V$ can be easily identified but the T dependence through α is not solved yet.

The pressure p can be rewritten to take the form

$$p = \frac{Nk_B T}{V} = CNmc^2 \frac{1}{K_2(\alpha)\alpha^2} \exp \left(-\alpha \frac{K_1(\alpha) + K_3(\alpha)}{2K_2(\alpha)} \right). \quad (2.3.11)$$

At this point it is not reasonable to ask what happens in the ur-limit since C depends non-trivially on m and m is not fully substituted in α .

Interestingly, the pressure seems to be constant for very high temperatures. The limiting case is obtained when taking $T \rightarrow \infty$ (which corresponds to $\alpha \rightarrow 0$)

$$\lim_{\alpha \rightarrow 0} \left[\frac{1}{K_2(\alpha)\alpha^2} \exp \left(-\alpha \frac{K_1(\alpha) + K_3(\alpha)}{2K_2(\alpha)} \right) \right] = \frac{1}{2e^2} \approx 0.006767. \quad (2.3.12)$$

The same argument then holds true for the density given by equation 2.3.10 and since

$$\lim_{\alpha \rightarrow 0} \left[1 + \alpha \frac{K_1(\alpha) + K_3(\alpha)}{2K_2(\alpha)} \right] = 3 \quad (2.3.13)$$

we have

$$\lim_{\alpha \rightarrow 0} \left(\frac{\rho(\alpha)}{CNmc^2} \right) = \frac{3}{2e^2} \approx 0.203003. \quad (2.3.14)$$

Theorem 2.1

The mapping $p : \mathbb{R}_{>0} \rightarrow \mathbb{R}_{>0}, \alpha \mapsto p(\alpha)$ written down in equation (2.3.11) is a bijection for any $N, m, c, C \neq 0$.

$$p = \frac{Nk_B T}{V} = CNmc^2 \frac{1}{K_2(\alpha)\alpha^2} \exp \left(-\alpha \frac{K_1(\alpha) + K_3(\alpha)}{2K_2(\alpha)} \right) \quad (2.3.15)$$

Proof. For this proof it suffices to show that the function $p(\alpha)$ has a strictly monotonous¹ behaviour. Without loss of generality, we assume $N, m, c, C > 0$. Now it is obvious that the first two terms $Nmc^2/C K_2(\alpha)$ and α^{-2} are strictly decreasing. This is easy to see when using [11]

$$\frac{\partial K_n}{\partial \alpha} = \frac{n}{\alpha} K_n - K_{n+1} = -\frac{K_{n-1} + K_{n+1}}{2}. \quad (2.3.16)$$

¹We omit this word in this proof for readability.

We then calculate the derivative of the third term and divide by the exponential (since it is positive)

$$\frac{1}{\exp(\alpha \partial_\alpha \log(K_2))} \frac{\partial}{\partial \alpha} \exp(\alpha \partial_\alpha \log(K_2)) \quad (2.3.17)$$

$$= \partial_\alpha \log(K_2) + \alpha \partial_\alpha^2 \log(K_2) \quad (2.3.18)$$

$$= \frac{\partial_\alpha K_2}{K_2} + \alpha \frac{\partial_\alpha^2 K_2}{K_2} + \alpha \left(\frac{\partial_\alpha K_2}{K_2} \right)^2 \quad (2.3.19)$$

$$= \frac{K_1 - \frac{2}{\alpha} K_2}{K_2} + \alpha \frac{\frac{1}{\alpha} K_1 - K_2 - \frac{2}{\alpha} (K_1 - \frac{2}{\alpha} K_2) + \frac{2}{\alpha^2} K_2}{K_2^2} + \alpha \frac{K_1^2 - \frac{1}{\alpha} K_1 K_2 - \frac{4}{\alpha^2} K_2^2}{K_2^2} \quad (2.3.20)$$

$$= -\alpha + \alpha \frac{K_1^2}{K_2^2} - 4 \frac{K_1}{K_2} \quad (2.3.21)$$

thus it is sufficient to show that

$$\alpha \frac{K_1^2}{K_2^2} < \alpha + 4 \frac{K_1}{K_2}. \quad (2.3.22)$$

We quickly prove the more general result $K_\nu < K_{\nu+1}$. One possible definition[12] for the Bessel function K_ν is given by

$$K_\nu := \frac{\sqrt{\pi}}{(\nu - \frac{1}{2})!} \left(\frac{1}{2} z \right)^\nu \int_1^\infty e^{-tz} (t^2 - 1)^{\nu - \frac{1}{2}} dt \quad (2.3.23)$$

We inspect the ratio

$$\frac{K_\nu}{K_{\nu+1}} = \frac{1}{(\nu + \frac{1}{2}) (\frac{1}{2} z)} \frac{\int e^{-tz} (t^2 - 1)^{\nu - 1/2} dt}{\int e^{-tz} (t^2 - 1)^{\nu + 1/2} dt} \quad (2.3.24)$$

and rewrite the demoninator with partial integration

$$\frac{1}{2} z \int_1^\infty e^{-tz} (t^2 - 1)^{\nu + 1/2} dt = \left(\nu + \frac{1}{2} \right) \int_1^\infty e^{-tz} t (t^2 - 1)^{\nu - 1/2} dt. \quad (2.3.25)$$

Now it is obvious that $K_{\nu+1} > K_\nu$. Thus in total, the function given by equation 2.3.26 can be inverted. \square

With this mapping $p : \mathbb{R}_{>0} \rightarrow \mathbb{R}_{>0}, \alpha \mapsto p(\alpha)$ and its inverse $\alpha : \mathbb{R}_{>0} \rightarrow \mathbb{R}_{>0}, p \mapsto \alpha(p)$, we can use 2.3.10 and finally write down the equation of state

$$\rho = \frac{\mathcal{U}}{V} = p \left(1 + \alpha(p) \frac{K_1(\alpha(p)) + K_3(\alpha(p))}{2K_2(\alpha(p))} \right). \quad (2.3.26)$$

Figure 1 is obtained by choosing numerical values and then interpolating and inverting equation 2.3.11. The constant factor

$$A := CNmc^2/p_0 \quad (2.3.27)$$

is substituted to obtain independence of p_0^2 . Furthermore the graphs of the plotted EOS are normalised such that

$$\rho_i(p_0) = \rho_{0,i} \quad (2.3.28)$$

and can thus be compared with each other. Note that the ρ_0 of the plot is not a universal value but rather each function has been scaled individually and ρ_0 is a placeholder for the corresponding $\rho_{0,i}$. The polytropic EOS $\rho_{cla}(p) = Ap^{1/\gamma}$ when normalised as before the equation is independent of A and can be uniquely characterised by n . For further details, the interested reader is referred to [13].

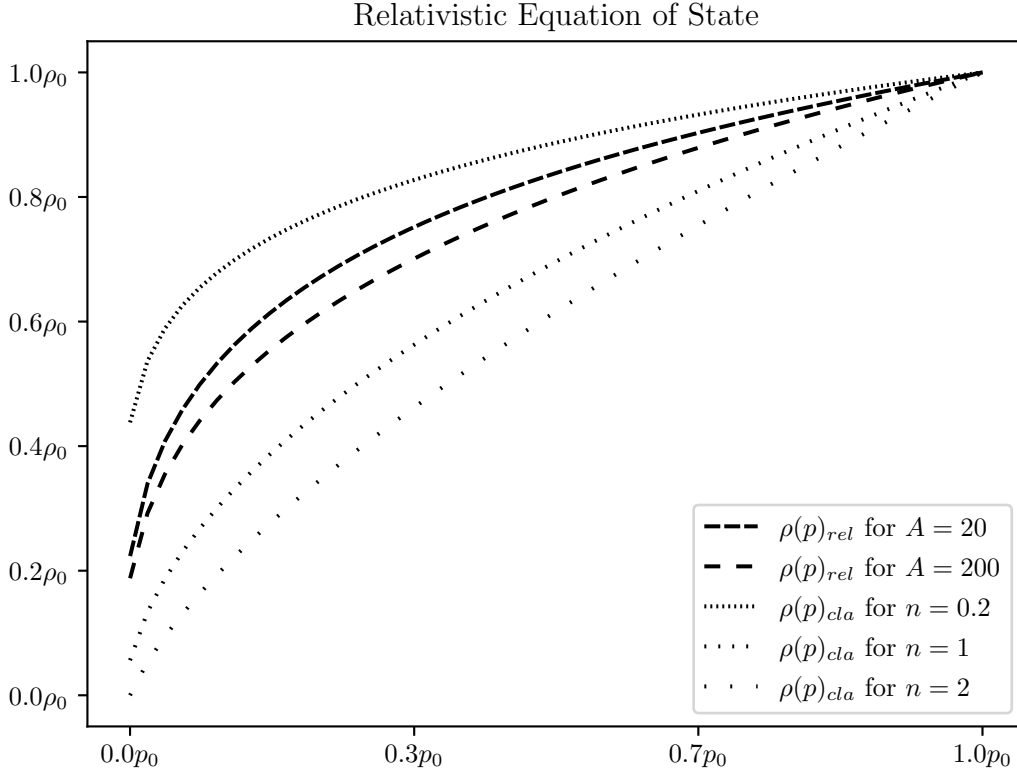


Figure 1: The plot shows the relativistic equation of state $\rho(p)$ normalised such that values can be compared with a polytropic EOS. Graphs for the relativistic version are independent of the exponent n which is a degree of freedom intrinsic to the polytropic equation of state. By normalisation, the graphs of the polytropic equation of state are independent of the factor A which is explained in equation 2.3.27.

²This will be the starting value for the pressure in the TOV equation. Since the pressure decreases from the inside of a star to the outside, this resembles our highest value of p .

3 Calculating the Mass of a Star with an EOS

3.1 Deriving the TOV-Equation

In this chapter, we consider a spherical-symmetric static Lorentz-Manifold (V, g) with charts such that the metric g can be written as

$$g = -e^\nu dt^2 + e^\lambda dr^2 + r^2(d\theta^2 + \sin^2 \theta d\phi^2). \quad (3.1.1)$$

The stress-energy tensor of an ideal fluid with density ρ and pressure p is given by

$$T_{\mu\nu} = \rho u_\mu u_\nu + p(g_{\mu\nu} + u_\mu u_\nu) \quad (3.1.2)$$

where u is the 4-velocity of the fluid. In the rest frame where $u^\mu = (-e^{-\nu/2}, 0, 0, 0)$, this equation simplifies to

$$T_\nu^\mu = \begin{bmatrix} -\rho & & & \\ & p & & \\ & & p & \\ & & & p \end{bmatrix}. \quad (3.1.3)$$

The Christoffel symbols for this metric are

$$\Gamma_{\mu\nu}^0 = \begin{bmatrix} 0 & \nu'/2 & & \\ \nu'/2 & 0 & & \\ & & 0 & \\ & & & 0 \end{bmatrix} \quad (3.1.4)$$

$$\Gamma_{\mu\nu}^1 = \begin{bmatrix} \nu' e^{\nu-\lambda}/2 & & & \\ & \lambda'/2 & & \\ & & -r e^{-\lambda} & \\ & & & -r \sin^2 \theta e^{-\lambda} \end{bmatrix} \quad (3.1.5)$$

$$\Gamma_{\mu\nu}^2 = \begin{bmatrix} 0 & & & \\ & 0 & 1/r & \\ & 1/r & 0 & \\ & & & -\sin \theta \cos \theta \end{bmatrix} \quad (3.1.6)$$

$$\Gamma_{\mu\nu}^3 = \begin{bmatrix} 0 & & & \\ & 0 & & \\ & 0 & 0 & 1/r \\ & 0 & 0 & \cos \theta / \sin \theta \\ & 1/r & \cos \theta / \sin \theta & 0 \end{bmatrix} \quad (3.1.7)$$

From these, the non-zero components of the Ricci-Tensor can be calculated

$$R_{11} = \frac{1}{4r} e^{-\lambda} [(2r\nu'' + r\nu'^2) + (4 - r\lambda') \nu'] \quad (3.1.8)$$

$$R_{22} = -\frac{1}{4r} e^{-\lambda} [(2r\nu'') + r\nu'^2 - r\lambda'\nu' - 4\lambda'] \quad (3.1.9)$$

$$R_{33} = -\frac{1}{2r^2} e^{-\lambda} (r\nu' - r\lambda' - 2e^\lambda + 2) \quad (3.1.10)$$

$$R_{33} = R_{44} \quad (3.1.11)$$

and with $R_{\mu\nu} - g_{\mu\nu}R/2 = G_{\mu\nu} = 8\pi T_{\mu\nu}$ ultimately yield the following field equations.

$$-8\pi T_0^0 = 8\pi\rho = \frac{\lambda' e^{-\lambda}}{r} + \frac{1 - e^{-\lambda}}{r^2} \quad (3.1.12)$$

$$8\pi T_1^1 = 8\pi p = \nu' \frac{e^{-\lambda}}{r} - \frac{1 - e^{-\lambda}}{r^2} \quad (3.1.13)$$

$$8\pi T_2^2 = 8\pi p = \frac{e^{-\lambda}}{2} \left[\nu'' + \left(\frac{\nu'}{2} + \frac{1}{r} \right) (\nu' - \lambda') \right] \quad (3.1.14)$$

Since $R_3^3 = R_2^2$, we omitted the last equation. From equation (3.1.12) we infer the relation.

$$e^{-\lambda} = 1 - \frac{2}{r} \int_0^r 4\pi\rho(r')r'^2 dr' = 1 - \frac{2m(r)}{r}. \quad (3.1.15)$$

The metric needs to be defined at every point in space and thus we can not have any additional integration constant in equation (3.1.15) since otherwise we would obtain a term a/r which is ill defined for $r \rightarrow 0$.

The property $m(r)$ can be recognized as the Newtonian Mass of the star (which is different to the proper mass). Since $e^{-\lambda} > 0$, we immediately see that $m(r) < r/2$.

In addition to the Field equations 3.1.12 to 3.1.14 the divergence of the Stress-Energy Tensor yields more information

$$\nabla_\mu T^{\mu\nu} = 0. \quad (3.1.16)$$

The following explicit calculation³ shows how to obtain this additional restriction on the pressure and density.

$$\nabla_\mu T_\nu^\mu = \partial_\mu T_1^\mu + \Gamma_{\mu\sigma}^\mu T_\nu^\sigma - \Gamma_{\mu\nu}^\sigma T_\sigma^\mu \quad (3.1.17)$$

$$\nabla_\mu T_1^\mu = \frac{\partial p}{\partial r} + p \left(\Gamma_{01}^0 + \Gamma_{11}^1 + \Gamma_{21}^2 + \Gamma_{31}^3 \right) - \Gamma_{\mu 1}^\sigma T_\sigma^\mu \quad (3.1.18)$$

$$= \frac{\partial p}{\partial r} + p \left(\frac{\nu' + \lambda'}{2} + \frac{2}{r} \right) + \rho \frac{\nu'}{2} - p \frac{\lambda'}{2} - p \frac{2}{r} \quad (3.1.19)$$

$$\frac{\partial p}{\partial r} = -\frac{p + \rho}{2} \nu' \quad (3.1.20)$$

Together with equation 3.1.13 and the definition 3.1.15, we can write

$$\frac{\partial p}{\partial r} = -\frac{p + \rho}{2} \left(\frac{8\pi p r + \frac{1 - e^{-\lambda}}{r}}{e^{-\lambda}} \right) \quad (3.1.21)$$

$$= -\frac{p + \rho}{2r} \left(\frac{8\pi p r + \frac{2m}{r^2}}{1 - \frac{2m}{r}} \right) \quad (3.1.22)$$

$$= -\frac{m\rho}{r^2} \left(1 + \frac{p}{\rho} \right) \left(\frac{4\pi r^3 p}{m} + 1 \right) \left(1 - \frac{2m}{r} \right)^{-1} \quad (3.1.23)$$

$$\frac{\partial p}{\partial r} = -\frac{Gm\rho}{r^2} \left(1 + \frac{p}{\rho c^2} \right) \left(\frac{4\pi r^3 p}{mc^2} + 1 \right) \left(1 - \frac{2Gm}{rc^2} \right)^{-1} \quad (3.1.24)$$

where in the last step the constants $c = G = 1$ were put back in.

³Again assuming spherical symmetry.

3.2 Newtonian Limit

This section follows [14] and [15, pp. 89 sqq.]. Together with a polytropic equation of state $p = K\rho^{1+1/n}$ and the definition $\rho = \lambda\theta^n$, we expect to obtain the Newtonian behavior in the non-relativistic limit in the form of the Lane-Emden equation

$$\frac{K(n+1)\lambda^{1/n-1}}{4\pi}\Delta\theta + \theta^n = 0. \quad (3.2.1)$$

The usual non-relativistic limit is obtained from a Taylor expansion of equation 3.1.24 around $1/c^2$ in lowest order. The resulting equation then reads

$$\frac{\partial p}{\partial r} = -\frac{Gm\rho}{r^2} + \mathcal{O}\left(\frac{1}{c^2}\right). \quad (3.2.2)$$

One could be tempted to make the assumption that $\frac{\partial p_{\text{TOV}}}{dr} \leq \frac{\partial p_{\text{LE}}}{dr}$. However this equation fails since the mass given in equation 3.1.24 is not the same as the one given in the LE equation. Using the previous relations for ρ and p and again setting $G = c = 1$, we can calculate

$$\frac{\partial p}{\partial r} = \frac{\partial}{\partial r}(K\rho^{1+1/n}) = K\lambda^{1+1/n}(n+1)\theta^n \frac{\partial \theta}{\partial r} = -\frac{m\lambda\theta^n}{r^2} \quad (3.2.3)$$

by using the definition of our polytropic equation of state and 3.2.2. Rearranging and taking the derivative of this equation and using $\partial m/\partial r = 4\pi\rho r^2$, we obtain

$$-\frac{\partial m}{\partial r} = K\lambda^{1/n}(n+1)\frac{\partial}{\partial r}\left(r^2\frac{\partial \theta}{\partial r}\right) = -4\pi r^2\lambda\theta^n \quad (3.2.4)$$

$$\frac{K\lambda^{1/n-1}(n+1)}{4\pi}\Delta\theta + \theta^n = 0. \quad (3.2.5)$$

Upon redefining $\xi = r/\alpha$ where $4\pi\alpha^2 = (n+1)K\lambda^{1/n-1}$, one can obtain the mathematically cleaner looking equation

$$\frac{1}{\xi^2}\frac{\partial}{\partial \xi}\left(\xi^2\frac{\partial \theta}{\partial \xi}\right) + \theta^n = 0 \quad (3.2.6)$$

Exact solutions are known for the cases $n = 0, 1, 5$. The derivation can be found in appendix A. Table 1 summarises them. Together with equation 3.2.6, it is immediate to see that for values $n \geq 5$, the equation does not yield solutions with a zero value.

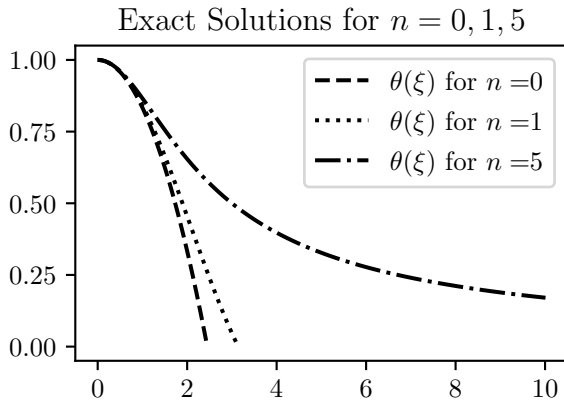


Figure 2: Graph of exact LE solutions.

n	Solution	ξ_0
$n = 0$	$1 - \frac{1}{6}\xi^2$	$\sqrt{6}$
$n = 1$	$\frac{\sin(\xi)}{\xi}$	π
$n = 5$	$\frac{1}{\sqrt{1 + \frac{1}{3}\xi^2}}$	∞

Table 1: Lane Emden exact Solutions and their zero value.

3.3 Upper Limits

We will first follow mainly the approach given in [16]. The first assumptions will be that $d\rho/dr < 0$ and $\rho \geq 0$. Also we again consider a compact star, meaning $\rho(r) = 0$ for all $r > R$. While we talk about the derivative of ρ it may not be differentiable at $r = R$. However differentiability of the metric demands at least continuity at every point. We first state a useful Lemma for the proof of our next theorem.

Lemma 3.1

The function $\rho_{av}(r) = m(r)/r^3$ has negative slope for $\partial_r \rho(r) \leq 0$.

Proof. Taking the derivative of ρ_{av} we obtain

$$\frac{\partial}{\partial r} \left(\frac{m(r)}{r^3} \right) = -\frac{m(r)}{r^4} + \frac{4\pi\rho(r)}{r}. \quad (3.3.1)$$

For this equation to be ≤ 0 , it is sufficient to have

$$\rho(r)r^3 \leq \frac{m(r)}{4\pi} = \int_0^r \rho(r')r'^2 dr'. \quad (3.3.2)$$

Since for $r = 0$ both sides of the equations match, we can take another derivative and obtain

$$\rho(r)r^2 \geq \partial_r \rho(r)r^3 + 3\rho(r)r^2 \Leftrightarrow -2\rho(r) \geq \partial_r \rho(r)r \quad (3.3.3)$$

which is always true since ρ has negative slope by definition. \square

Theorem 3.2 - Mass Bound

The Mass of a spherically symmetric star is bound from above by

$$M < \frac{4}{9}R. \quad (3.3.4)$$

Proof. In our attempt to obtain an upper limit for the mass of a spherically symmetric star, we start by taking the difference of equation (3.1.13) and (3.1.14), we obtain

$$0 = \nu' \frac{e^{-\lambda}}{r} - \frac{1 - e^{-\lambda}}{r^2} - \frac{e^{-\lambda}}{2} \left[\nu'' + \left(\frac{\nu'}{2} + \frac{1}{r} \right) (\nu' - \lambda') \right] \quad (3.3.5)$$

$$= -\frac{2m(r)}{r^3} + \frac{\lambda' e^{-\lambda}}{2r} - \frac{e^{-\lambda}}{2} \left[\nu'' + \frac{\nu'^2}{2} - \frac{\nu'}{r} - \frac{\lambda' \nu'}{2} \right] \quad (3.3.6)$$

$$= r \frac{\partial}{\partial r} \left(\frac{m(r)}{r^3} \right) - \frac{e^{-\lambda}}{2} \left[\nu'' + \frac{\nu'^2}{2} - \frac{\nu'}{r} - \frac{\lambda' \nu'}{2} \right] \quad (3.3.7)$$

$$0 = \frac{\partial}{\partial r} \left(\frac{m(r)}{r^3} \right) - \frac{e^{-\lambda}}{2} \left[\frac{\nu''}{r} + \frac{\nu'^2}{2r} - \frac{\nu'}{r^2} - \frac{\lambda' \nu'}{2r} \right] \quad (3.3.8)$$

$$= \frac{\partial}{\partial r} \left(\frac{m(r)}{r^3} \right) - \frac{1}{2} e^{-\frac{\lambda+\nu}{2}} \frac{\partial}{\partial r} \left[\frac{1}{r} \nu' e^{\frac{\nu-\lambda}{2}} \right]. \quad (3.3.9)$$

Since $\partial_r \rho \leq 0$, also the average density $m(r)/r^3$ decreases with r . Thus we obtain

$$\frac{\partial}{\partial r} \left[\frac{1}{r} \nu' \exp \left(\frac{\nu - \lambda}{2} \right) \right] \leq 0. \quad (3.3.10)$$

We integrate this equation from R to $r < R$

$$\frac{\nu'}{r} \exp\left(\frac{\nu - \lambda}{2}\right) \geq \frac{2\nu'(R)}{R} e^{-\frac{1}{2}\lambda(R)} \frac{\partial}{\partial r} e^{\frac{\nu}{2}} \Big|_R \quad (3.3.11)$$

and use the Schwarzschild solution at $r = R$ for e^λ and e^ν . This is justified since we assumed $\rho(r) = 0$ for $r > R$ and thus we need to recover the vacuum solution for a spherically symmetric object which is given by the Schwarzschild solution. By continuity of the metric on every point of space, we can match

$$e^{-\lambda(r)} \Big|_R = \left[1 - \frac{2M}{r}\right]_R = e^{\nu(r)} \Big|_R \quad (3.3.12)$$

and with the explicit solution for $e^{-\lambda}$, we obtain

$$\frac{2m(r)}{r} \Big|_R = \frac{2M}{R}. \quad (3.3.13)$$

When plugging this into equation (3.3.12), the result is

$$\frac{\nu'}{2r} \exp\left(\frac{\nu - \lambda}{2}\right) \geq \frac{(1 - 2M/R)^{1/2}}{R} \frac{\partial}{\partial r} \left(1 - \frac{2M}{r}\right)^{1/2} \Big|_{r=R} = \frac{M}{R^3}. \quad (3.3.14)$$

Now we multiply by $r \exp(\lambda/2)$ and use the explicit solution for e^λ

$$\frac{\partial}{\partial r} (e^{\frac{\nu}{2}}) \geq \frac{M}{R^3} r e^{\frac{\lambda}{2}} = \frac{M}{R^3} (r - 2m(r)) \quad (3.3.15)$$

and integrate again this time from 0 to R

$$e^{\nu(0)/2} \leq \left(1 - \frac{2M}{R}\right)^{1/2} - \frac{M}{R^3} \int_0^R \left[1 - \frac{2m(r)}{r}\right]^{-1/2} r dr. \quad (3.3.16)$$

As we have already noted, the average density $m(r)/r^3$ decreases, meaning explicitly $m(r)/r^3 \geq M/R^3$ and thus the integral with the previous equation can be written as

$$e^{\nu(0)/2} \leq \left(1 - \frac{2M}{R}\right)^{1/2} + \frac{1}{2} \left[1 - \frac{2Mr^2}{R^3}\right]^{1/2} \Big|_{r=0}^{r=R} = \frac{3}{2} \left(1 - \frac{2M}{R}\right)^{1/2} - \frac{1}{2}. \quad (3.3.17)$$

The simple fact that $e^{\nu(0)/2} > 0$ then implies

$$\left(1 - \frac{2M}{R}\right)^{1/2} > \frac{1}{3} \quad (3.3.18)$$

which is equivalent to

$$M < \frac{4R}{9}. \quad (3.3.19)$$

□

This shows that the mass of star has an upper limit under the assumptions $\rho \geq 0$, $\partial_r \rho \leq 0$ and $\rho(R) = 0$ for some $R \geq 0$. The case in which $M = 4R/9$ would be achieved by using a constant density of

$$\rho = \frac{1}{4\pi} \frac{M}{R^3} \quad (3.3.20)$$

from which the mass $m(r)$ can be obtained

$$m(r) = \frac{r^3}{R^3} M. \quad (3.3.21)$$

However this case is actually forbidden as was just shown. Physically, the assumption that $\rho(R) = 0$ defines a radius for the stellar object since it limits the physical dimension. In general stellar objects need not to fulfill this condition. Physically it is however necessary to have $p(R) = 0$ while the density may have discontinuities at this point.

4 Numerical Solutions

4.1 Comparing TOV and LE results with a polytropic EOS

In this section the numerical solutions of the TOV equation

$$\frac{\partial m}{\partial r} = 4\pi\rho r^2 \quad (4.1.1)$$

$$\frac{\partial p}{\partial r} = -\frac{m\rho}{r^2} \left(1 + \frac{p}{\rho}\right) \left(\frac{4\pi r^3 p}{m} + 1\right) \left(1 - \frac{2m}{r}\right)^{-1} \quad (4.1.2)$$

as derived previously in 3.1 will be discussed. To obtain numerical solvability a equation of state in the form $\rho(r, p)$ is supplied. In Figure 3 a plot of such a solution is presented. The density ρ is derived via the equation 4.1.1 and the integration is done with a 4th order Runge-Kutta Method. The integration is stopped once the pressure reaches values $p \leq 0$. The initial value of 4.1.1 is $\partial m/\partial r(r = 0) = 0$. For 4.1.2, the initial value can be calculated when applying L'Hôpital's rule and combining them to obtain

$$\lim_{r \rightarrow 0} \frac{m}{r} = \lim_{r \rightarrow 0} \frac{\partial m}{\partial r} = \lim_{r \rightarrow 0} \frac{4\pi\rho r^2}{1} = 0 \quad (4.1.3)$$

$$\lim_{r \rightarrow 0} \frac{m}{r^2} = \lim_{r \rightarrow 0} \frac{1}{2r} \frac{\partial m}{\partial r} = \lim_{r \rightarrow 0} \frac{4\pi\rho r^2}{2r} = 0 \quad (4.1.4)$$

$$\lim_{r \rightarrow 0} \frac{m}{r^3} = \lim_{r \rightarrow 0} \frac{1}{3r^2} \frac{\partial m}{\partial r} = \lim_{r \rightarrow 0} \frac{4\pi\rho r^2}{3r^2} = \frac{4\pi\rho_0}{3} \quad (4.1.5)$$

$$\lim_{r \rightarrow 0} \frac{\partial p}{\partial r} = 0 \quad (4.1.6)$$

Explicit code can be found in [13]. The Lane-Emden equation was obtained in section 3.2 as the non-relativistic limit of the TOV equation by neglecting terms of order $1/c^2$ and higher and setting $G = c = 1$. To obtain numerical results for the LE equation as given in equation 3.2.6, a substitution of the form $d\theta/d\xi = \chi$ was used.

$$\frac{d\theta}{d\xi} = \chi \quad \frac{d\theta}{d\xi} \Big|_{\xi=0} = 0 \quad (4.1.7)$$

$$\frac{d\chi}{d\xi} = -\frac{2}{\xi}\chi - \theta^n \quad \frac{d\chi}{d\xi} \Big|_{\xi=0} = -\theta^n \quad (4.1.8)$$

where the initial value for $d\chi/d\xi$ can be calculated with L'Hôpital's rule. With the conversion factor α derived in section 3.2, TOV and LE results can be compared. Figure 3 shows the solution of both equations for the parameters of table 2. Note that values in the last part are calculated instead of supplied to the solving routine. Additionally conversion equations to compare TOV and LE results are displayed.

Since the mass reads

$$m(r) = \int_0^r 4\pi s^2 \rho(s) ds, \quad (4.1.9)$$

we expect $\partial m/\partial r(R) = 0$ if $p(R) = 0$ when choosing a polytropic equation of state with $\gamma > 0$. The plot in figure 3 shows this expected behaviour for the Lane Emden equation at $r \approx 2.31$ and has the same behaviour for the TOV results at $r \approx 6.80$.⁴

⁴For the purpose of nicely displaying the calculated result, the plot only shows result up to $r = 2.5$

TOV		LE	
EOS	$\rho = Ap^{1/\gamma}$	EOS	$p = K\rho^\gamma$
A	2		
$\gamma = 1 + \frac{1}{n}$	4/3	$n = 1/(\gamma - 1)$	3
p_0	0.5	θ_0	1
m_0	0	$d\theta_0$	0
dr	0.01	$d\xi = dr/\alpha$	0.01/0.3355 \approx 0.0298
$\rho_0 = Ap_0^{1/\gamma}$	$2(2)^{\frac{4}{3}} \approx 1.1892$	$\lambda = \rho_0$	$2(2)^{\frac{4}{3}} \approx 1.1892$
		$K = A^{-1/\gamma}$	$2^{-3/4} \approx 0.5946$
		$\alpha^2 = ((n+1)K\lambda^{1/n-1})/(4\pi)$	≈ 0.1125

Table 2: Parameters for numerical solving of the TOV and Lane-Emden equation.

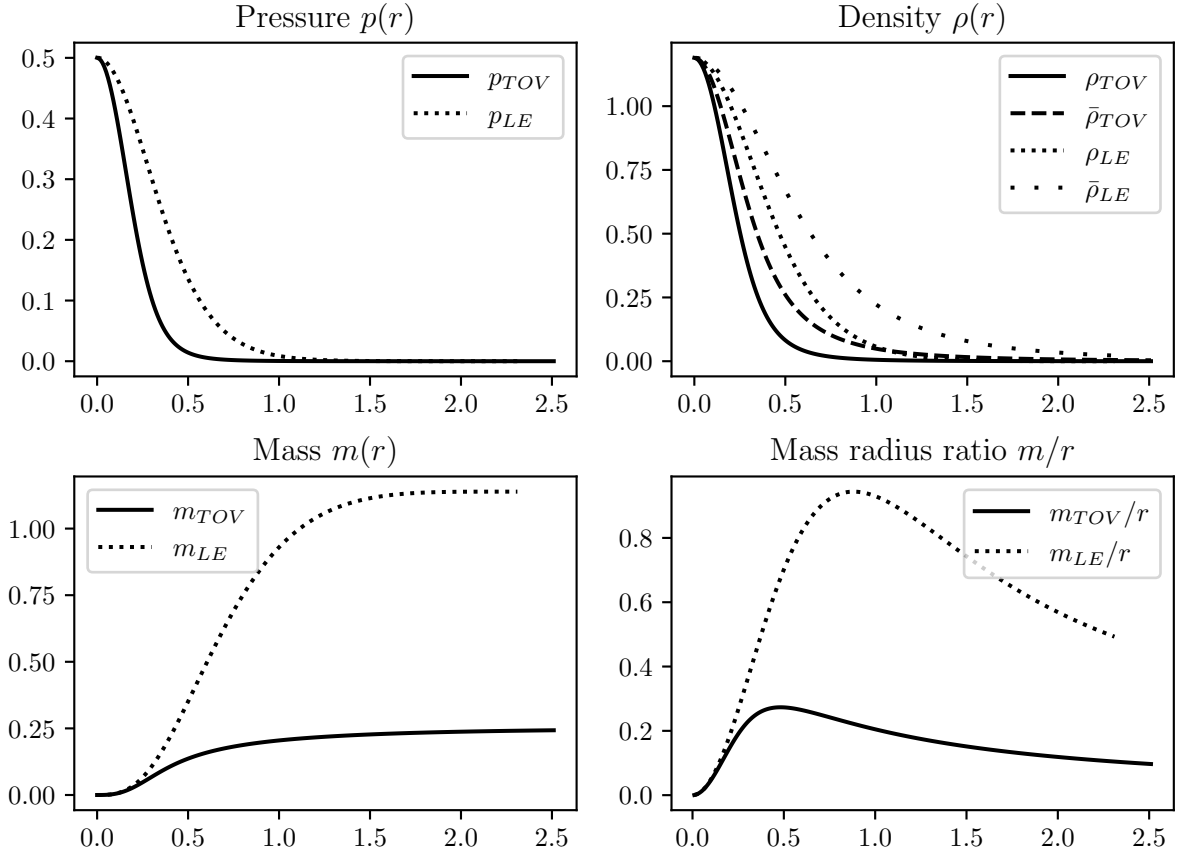


Figure 3: Comparison of the fully relativistic TOV result and the classical Lane-Emden solution. The images show the plots for the parameters of table 2. First the pressure is presented. Afterwards the density calculated with the given EOS and the average density $\bar{\rho}_i = (4\pi/3)^{-1}m_i/r^3$ for the two solutions are being compared. In the second row, the mass and the ratio m_i/r can be seen.

4.2 Verifying the results

Verification is done in different ways. First, one can compare calculated LE results with already known exact solutions for certain exponents as given in table 1. All calculations are carried out with a chosen step size of $d\xi = 0.03$.

The graphs overall show good numerical agreement. Initial values at $r = 0$ are identical since they were set to be. The spike occurring afterwards can be explained by equation 4.1.8. The initial value of all derivatives is identically 0 which means no change of value for θ or χ for the initial step. It is clear that the relative difference on the right hand side will spike again once smaller values for θ are reached if the absolute difference stays constant. This behaviour is best seen in the solution for $n = 5$ where a large range of $0 \leq r \leq 100$ for solving was chosen. The offset between the numerically calculated values and the exact result stays constant while the value of θ decreases inverse proportionally.

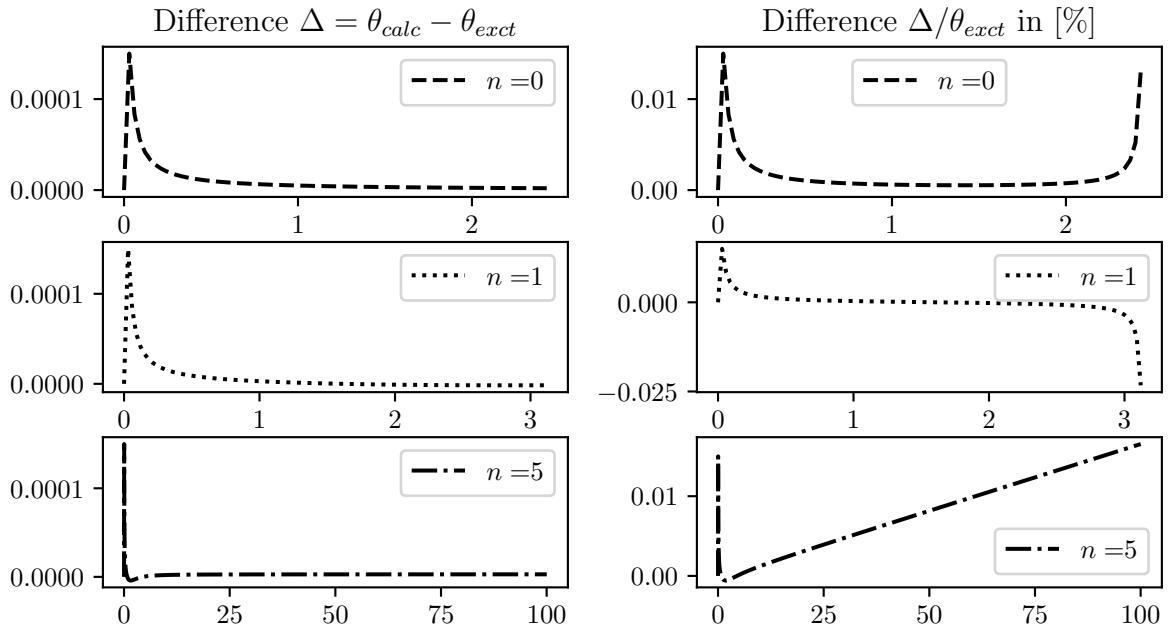


Figure 4: Validation of numerical LE results - The Plot shows absolute and relative difference of known exact and numerically calculated results.

Next, we wish to see how accurate numerical TOV results are. This is not an easy task since no explicit solutions are known for the TOV equation. However one way to at least get confident that solving was a success is by dropping terms from right to left in equation 4.1.2 and solving for these new differential equations. As we have seen in section 3.2, the last result should reproduce the LE equation. These intermediate differential equations have been numerically solved and results can be seen in figure 5.

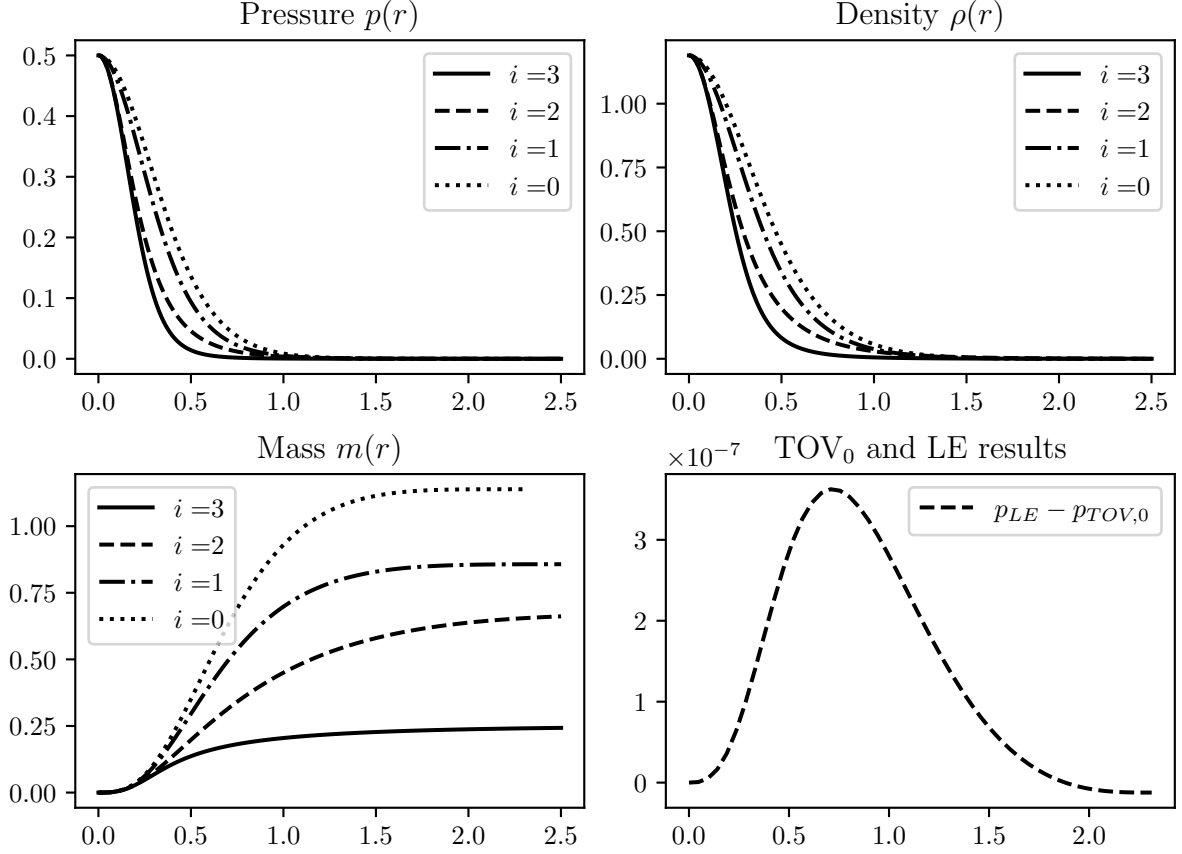


Figure 5: Comparison of LE and partial TOV solutions - The index i represents the number of terms still present in the equation where $i = 3$ means the complete TOV equation and $i = 0$ the LE equation. The last figure shows the difference between the TOV solution with 0 terms and the LE solution calculated via equation 4.1.8. The scale of the difference shows a maximum of $\approx 3.5 \times 10^{-7}$. In order to achieve such a comparison, a polynomial fit of both pressure solutions had to be done. This should however not alter the result in any noticeable way. For further details see [13].

4.3 Relativistic EOS

In the previous discussion, we relied on the EOS given by 3. This is a versatile assumption, but one could ask, what would happen to a star in which the particles have no interaction but are near relativistic speed. The resulting EOS was calculated in the beginning 2.3.26 although not written down explicitly. Since explicit inversion of the given function is hard, we rely on numerical methods for calculation.

5 More Exact Results

5.1 LE equation

One can derive another exact solution for the LE equation at the exponent $n = 2$ when considering a series expansion of θ around the point $\xi = 0$ with initial conditions

$$\theta = \sum_{m=0}^{\infty} a_m \xi^m \quad a_0 = \theta|_{\xi=0} = \theta_0 \quad a_1 = \left. \frac{d\theta}{d\xi} \right|_{\xi=0} = 0 \quad (5.1.1)$$

Since the series is absolut convergent, we can plug it into the LE equation 3.2.6 and use the Cauchy Product formula.

$$\sum_{m=2}^{\infty} m(m-1)a_m \xi^{m-2} + \sum_{m=1}^{\infty} (2m)a_m \xi^{m-2} + \sum_{m=0}^{\infty} \sum_{k=0}^m a_{m-k} a_k \xi^m = 0 \quad (5.1.2)$$

Theorem 5.1

The odd coefficients a_{2m+1} of this series expansion vanish.

Proof. We rewrite the summations of equation ?? to start at the same index $m = 0$ and combine them

$$\sum_{m=0}^{\infty} \left((m+2)(m+1)a_{m+2} \xi^m + (2m+2)a_{m+1} \xi^{m-1} + \sum_{k=0}^m a_{m-k} a_k \xi^m \right) = 0 \quad (5.1.3)$$

With equation ??, we can start the summation in the middle one index higher and separate the term ξ^m . This equation has to be true inside the radius of convergence of the series and thus needs to vanish for ambiguous ξ .

$$(m+2)(m+1)a_{m+2} + 2(m+2)a_{m+1} + \sum_{k=0}^m a_{m-k} a_k = 0 \quad (5.1.4)$$

and upon further manipulation results in the recursive description for the coefficients of the series

$$a_{m+2} = -\frac{1}{(m+2)(m+3)} \sum_{k=0}^m a_{m-k} a_k. \quad (5.1.5)$$

We show the statement by induction. For a_1 it is already true. Let the statement be true for all odd values $2k+1 \leq 2m+1$. Writing down a_{2m+3} gives us

$$a_{2m+3} = -\frac{1}{(2m+3)(2m+4)} (a_0 a_{2m+1} + a_1 a_{2m} + \dots + a_{2m} a_1 + a_{2m+1} a_0). \quad (5.1.6)$$

It is clear that in the summation odd and even coefficients get paired and will thus vanish completely. \square

This proof shows that we can restrict ourselves to the subsequence $b_m = a_{2m}$ and the subseries with initial values given by

$$\theta = \sum_{m=0}^{\infty} b_m \xi^{2m} \quad b_{m+1} = -\frac{1}{(2m+2)(2m+3)} \sum_{k=0}^m b_{m-k} b_k \quad b_0 = \theta_0 \quad (5.1.7)$$

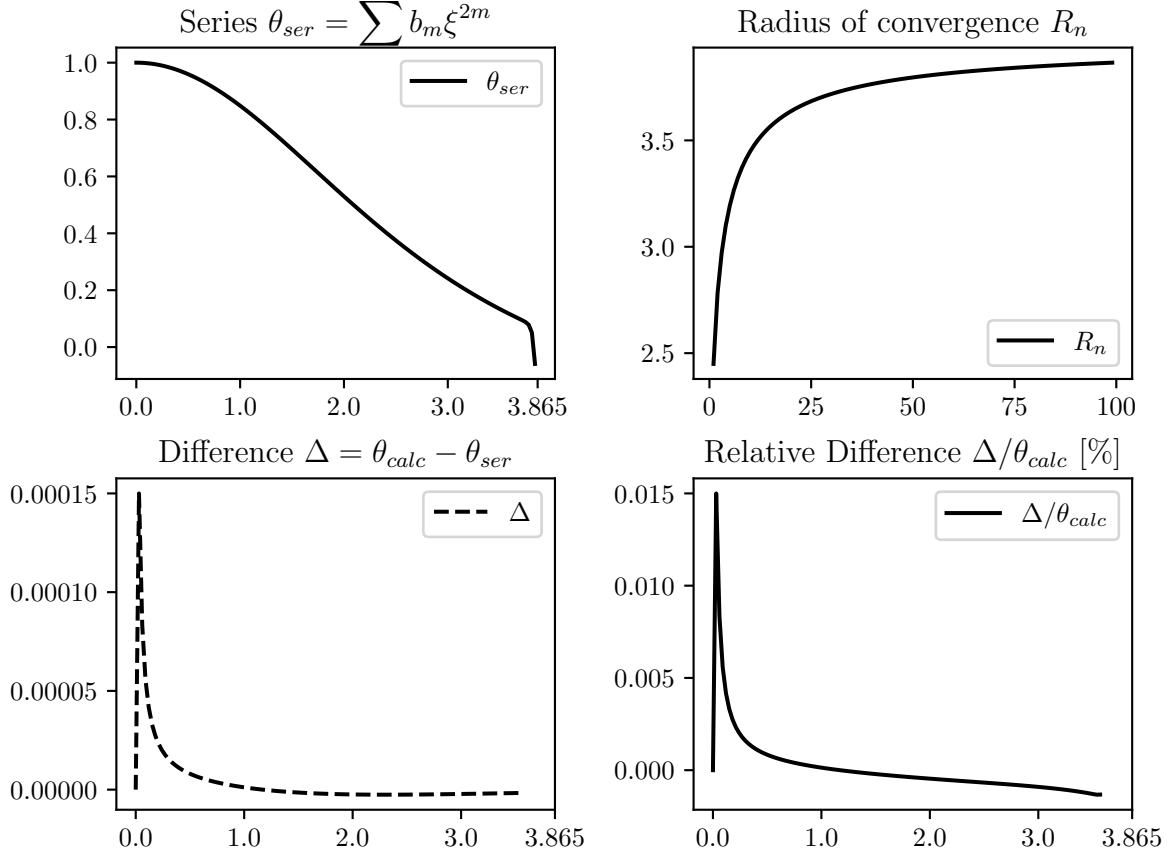


Figure 6: LE Solution for $n = 2$ - From top left to bottom right, the series calculated with the coefficients explained above, the sequence $R_n = (|b_n|)^{-1/n}$ which approaches the radius of convergence, the difference to the result obtained by solving the differential equation as in section ?? and the corresponding relative difference are shown.

These results can be used to calculate the series expansion of the LE equation numerically. Figure ?? shows those results. Good agreement is found between the two solutions. However in both plots at the bottom, the last few values where the solution reaches the radius of convergence have been omitted for better clarity. It is clear that in this regime both solutions do not agree. The third plot indicates that the radius of convergence might actually be larger than where the solutions deviate. However one important aspect is numerical uncertainty. In this procedure, the coefficients were calculated up to $a_{200} = b_{100}$

5.2 TOV equation

5.3 Existence of Solutions

6 Ideas

Theorem 6.1 - Lane-Emden Finite Boundary

For every $0 \leq n \leq 5$, the Lane-Emden equation

$$\frac{d^2\theta}{d\xi^2} + \theta^n = 0 \quad (6.0.1)$$

with $\theta(\xi = 0) = 1$ has a zero value for a finite ξ_0 . To prove this theorem, show the statements 6.2, 6.3 and 6.4.

Theorem 6.2 - Lane-Emden Finite Boundary 1

For every $n \geq 0$, the Lane-Emden equation 6.0.1 has a solution in a ϵ Ball around $r = 0$.

Theorem 6.3 - Lane-Emden Finite Boundary 2

For $n < 5$, the Lane-Emden equation 6.0.1 has no Solution defined on the total space $\mathbb{R}_{\geq 0}$.

Theorem 6.4 - Lane-Emden Finite Boundary 3

Let $n < 5$ and $\theta : [0, x) \rightarrow \mathbb{R}$ be a solution of 6.0.1. If $\theta(x) > 0$, then θ can be extended with Theorem 6.2 to $[0, x + \epsilon)$ where ϵ follows a growth condition $\epsilon(\xi) = \dots$ such that if θ would have no zero point, there would be a solution on total $\mathbb{R}_{\geq 0}$ and thus a contradiction with 6.3.

Theorem 6.5 - Lane-Emden Finite Boundary 4

The Lane Emden equation has a zero value if the exponent function $n(\xi)$ fullfills the growth condition XYZ.

Theorem 6.6 - TOV Exact Solution

The TOV equation 4.1.1 with a polytropic EOS $\rho = Ap^{1/\gamma}$ has a well defined limiting case where $A \rightarrow 0$ with $m = 0$ and

$$p = \frac{1}{r^2 + 1} \mod 4\pi. \quad (6.0.2)$$

Theorem 6.7 - TOV Finite Boundary

For each $A > 0$, the TOV equation 4.1.1 has a exponent $n > 0$ for which a solution p does not have any zero points.

Theorem 6.8 - TOV Finite Boundary 1

If p_1 and p_2 are two solutions of the TOV equation (for equal A) with p_i corresponding to n_i exponents, then if $n_1 < n_2$, the zero point (if it exists) of p_1 is smaller than that of p_2 (if it exists or is ∞).

Theorem 6.9 - TOV Finite Boundary 2

a

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Appendix

A Exact solutions of the LE equation

This section relies on information in [14] and [15]. The LE equation is

$$\frac{1}{\xi^2} \frac{d}{d\xi} \left(\xi^2 \frac{d\theta}{d\xi} \right) + \theta^n = 0 \quad (\text{A.1})$$

which for $n = 0$ transforms readily into

$$\int_0^\xi \frac{d}{d\xi} \left(\xi'^2 \frac{d\theta}{d\xi} \right) d\xi' = - \int_0^\xi \xi'^2 d\xi'. \quad (\text{A.2})$$

Both sides can be evaluated directly and then simplified further.

$$\xi^2 \frac{d\theta}{d\xi} = -\frac{\xi^3}{3} \quad (\text{A.3})$$

$$\theta(\xi) = \theta(0) - \frac{\xi^2}{6} \quad (\text{A.4})$$

With the initial condition $\theta(0) = 1$, we obtain the desired result. For $n = 1$, equation A.1 transforms into

$$\frac{d}{d\xi} \left(\xi^2 \frac{d\theta}{d\xi} \right) + \xi^2 \theta = 0 \quad (\text{A.5})$$

we start by substituting $U = \theta x$ and thus obtain (also multiplying by x^2)

$$0 = \frac{dU}{d\xi} + \xi \frac{d^2 U}{d\xi^2} - \frac{dU}{d\xi} + \xi U \quad (\text{A.6})$$

$$-U = \frac{d^2 U}{d\xi^2} \quad (\text{A.7})$$

and the last equation can be solved with a linear combination of $\cos(\xi)$ and $\sin(\xi)$. Transforming back to θ , we then have

$$\theta(\xi) = A \frac{\sin(\xi)}{\xi} - B \frac{\cos(k\xi)}{\xi}. \quad (\text{A.8})$$

The need for a well defined limit at $\xi \rightarrow 0$ implies that $B = 0$ and thus since $\sin(z)/z \rightarrow 1$ for $z \rightarrow 0$, we have $A = \theta(0) = 1$ and

$$\theta(\xi) = \frac{\sin(\xi)}{\xi}. \quad (\text{A.9})$$

For $n = 5$, we start by making the two substitutions $x = 1/\xi$ and $\theta = ax^\omega$ as done in [15, pp. 94 sqq.] and then transforming the LE equation into

$$x^4 \frac{d\theta}{d\xi} + \theta^n = 0 \quad (\text{A.10})$$

$$a\omega(\omega - 1)x^{\omega+2} + a^n x^{n\omega} = 0. \quad (\text{A.11})$$

From this we see that $\omega + 2 = n\omega$ and $a\omega(\omega - 1) = -a^n$ needs to be satisfied, since the equation needs to hold for all $x \in \mathbb{R}_{\geq 0}$. Rewriting these conditions, we obtain the singular solution for the LE equation

$$\theta(x) = \left(\frac{2(n-3)}{(n-1)^2} \right)^{1/(n-1)} x^{2/(n-1)} \quad (\text{A.12})$$

since with $x = 1/\xi$, we have $\theta(\xi) \rightarrow \infty$ for $\xi \rightarrow 0$. Notice that the solution is only valid if $n \geq 3$. We can use this solution to the LE equation and perturb it to make the more general ansatz

$$\theta(x) = ax^\omega z(x). \quad (\text{A.13})$$

If $n < 3$, the factor a has to be replaced with a more general one. The singular solution is obtained when taking $z = 1$. Using another transformation $1/x = \xi = \exp(-t)$, we obtain

$$\frac{1}{\xi^2} \frac{d}{d\xi} \left(\xi^2 \frac{d\theta}{d\xi} \right) + \theta^n = 0 \quad (\text{A.14})$$

$$x^4 \frac{d^2\theta}{dx^2} + \theta^n = 0 \quad (\text{A.15})$$

$$ax^{\omega+2} \left[x^2 \frac{d^2z}{dx^2} + 2\omega x \frac{dz}{dx} + \omega(\omega-1)z \right] + a^n x^{n\omega} z^n = 0 \quad (\text{A.16})$$

$$\frac{d^2z}{dt^2} + (2\omega-1) \frac{dz}{dt} + \omega(\omega-1)z + a^{n-1} z^n = 0 \quad (\text{A.17})$$

$$\frac{d^2z}{dt^2} + \frac{5-n}{n-1} \frac{dz}{dt} + 2 \frac{3-n}{(n-1)^2} z + 2 \frac{(n-3)}{(n-1)^2} z^n = 0. \quad (\text{A.18})$$

For $n = 5$, we obtain

$$\frac{d^2z}{dt^2} = \frac{1}{4} z(1 - z^4). \quad (\text{A.19})$$

we multiply both sides with dz/dt and integrate

$$\frac{1}{2} \left(\frac{d^2z}{dt^2} \right) = \frac{1}{8} z^2 - \frac{1}{24} z^6 + D \quad (\text{A.20})$$

where D is the integration constant. For $\xi \rightarrow 0$, we expect $\theta \rightarrow \theta_0$ and thus $z = \theta_0 e^{-\omega t} (1/a + \mathcal{O}(e^{-t}))$ as t approaches ∞ . We immediately see that dz/dt exhibits a similar behaviour and thus the integration constant D has to vanish.

The right hand side of equation A.20 cannot get negative since otherwise z would take complex values which enables us to take the square root with a minus sign⁵ and integrate again

$$\int \left(1 - \frac{1}{3} z^4 \right)^{-1/2} \frac{dz}{z} = -\frac{1}{2} \int dt. \quad (\text{A.21})$$

We change the integration by again substituting the variables $1/3z^4 = \sin^2(\alpha)$ and calculate $dz/z = 2 \cos(\alpha)/\sin(\alpha) d\alpha$ as well as $-dt = d\alpha/\sin(\alpha)$. Now we rewrite the integral

$$\int \frac{1}{\sqrt{1 - \sin^2(\alpha)}} \frac{2 \cos(\alpha)}{\sin(\alpha)} d\alpha = - \int dt \quad (\text{A.22})$$

$$\int \frac{2 d\alpha}{\sin(\alpha)} = - \int dt. \quad (\text{A.23})$$

⁵This only determines the direction in which t is defined, so it is arbitrary.

Evaluating those integrals leads us to

$$\log(\tan(\alpha/2)) + \log(1/C) = -t \quad (\text{A.24})$$

where the integration constant has been chosen in advance to simplify the next expressions. From here, we further manipulate equation A.24 and combine it with our previous substitution $1/3z^4 = \sin^2(\alpha)$ to obtain

$$\frac{1}{3}z^4 = \sin^2(\alpha) = \frac{4 \tan^2(\alpha/2)}{(1 + \tan^2(\alpha/2))^2} \quad (\text{A.25})$$

and with the solution for our integral before and plugging in the substitution from the beginning $\xi = e^{-t}$, we have

$$z = \pm \left(\frac{12C^2\xi^2}{1 + C^2\xi^2} \right)^{1/4}. \quad (\text{A.26})$$

For θ , we need to have $\theta \rightarrow \theta_0 = 1$ as $\xi \rightarrow 0$. This means that $C = 1$ and with $\theta = ax^\omega z$, we obtain

$$\theta = \frac{1}{(1 + \frac{1}{3}\xi^2)^{1/2}}. \quad (\text{A.27})$$

We see that this equation has no zero value and tends to 0 as $\xi \rightarrow \infty$.



Erklärung

Hiermit versichere ich, dass ich die eingereichte Masterarbeit selbständig verfasst habe. Ich habe keine anderen als die angegebenen Quellen und Hilfsmittel benutzt und alle wörtlich oder sinngemäß aus anderen Werken übernommenen Inhalte als solche kenntlich gemacht. Weiter versichere ich, dass die eingereichte Masterarbeit weder vollständig noch in wesentlichen Teilen Gegenstand eines anderen Prüfungsverfahrens war oder ist.

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