

# An Introduction to Parallel Computing

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Short course on Parallel Computing  
Edgar Gabriel



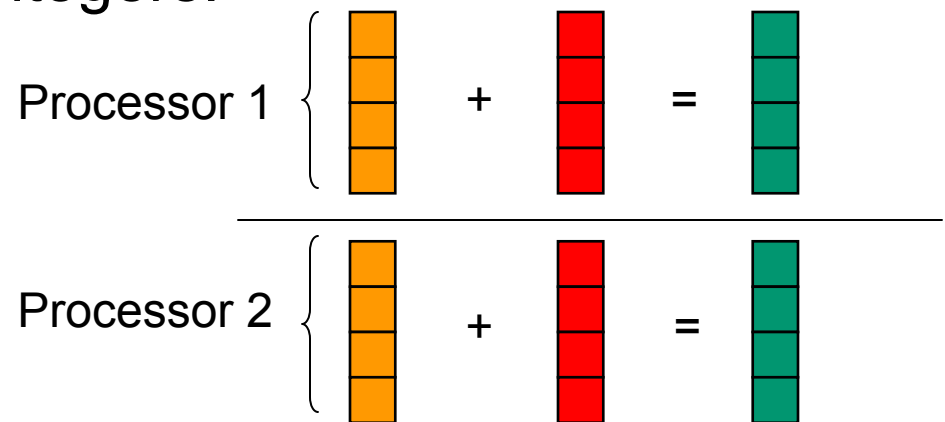
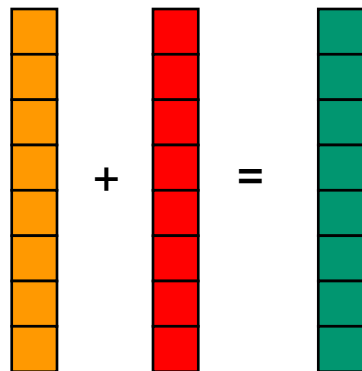
# Why Parallel Computing?

- To solve larger problems
  - many applications need significantly more memory than a regular PC can provide/handle
- To solve problems faster
  - despite of many advances in computer hardware technology, many applications are running slower and slower
    - e.g. databases having to handle more and more data
    - e.g. large simulations working on even more accurate solutions



# Parallel Programming

- Exploit concurrency
  - Internet: Client and server are independent, interacting applications
  - Searching an element: distribute the search database onto multiple processors
  - Adding two arrays of integers:



# Parallel Programming (II)

- Scalar product:

$$s = \sum_{i=0}^{N-1} a[i] * b[i]$$

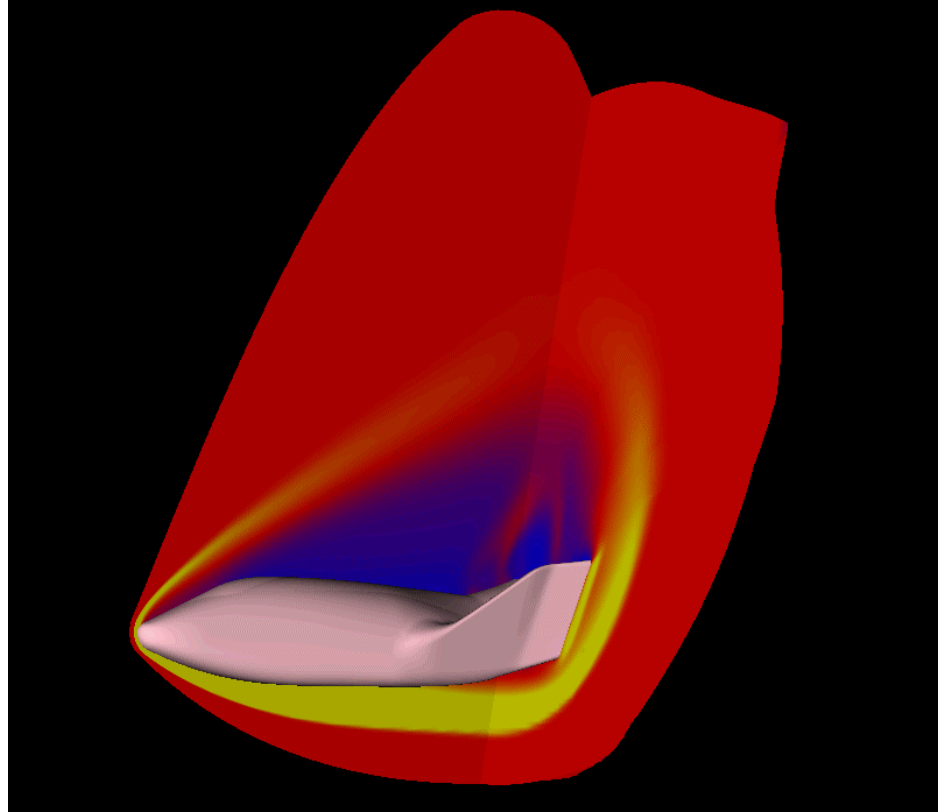
- Parallel algorithm

$$\begin{aligned} s &= \sum_{i=0}^{N/2-1} (a[i] * b[i]) + \sum_{i=N/2}^{N-1} (a[i] * b[i]) \\ &= \underbrace{\sum_{i=0}^{N/2-1} (a_{local}[i] * b_{local}[i])}_{rank=0} \quad + \quad \underbrace{\sum_{i=0}^{N/2-1} (a_{local}[i] * b_{local}[i])}_{rank=1} \end{aligned}$$

– requires communication between the processes



# Flow around a re-entry vehicle



# HPC in movies

- Special effects are highly compute intensive
- Example: Lord of the Rings
  - company: Weta Digitals
  - 3200 processor cluster
  - a single scene contains:
    - per second 24 frames
    - per frame: 4996 x 3112 points with 32- or 64 bit color encoding
    - each object means a separate compute cycle
- Number of computer-added special effects in movies:
  - Jurassic Park (I): 75
  - Lord of the Rings (I): 540
  - each of the following episodes of Lord of the Rings doubled the number of special effects
  - last episode of Star-Wars: 2000-2500



# What is a Parallel Computer?



# What is a Parallel Computer?



## PC cluster in 2000

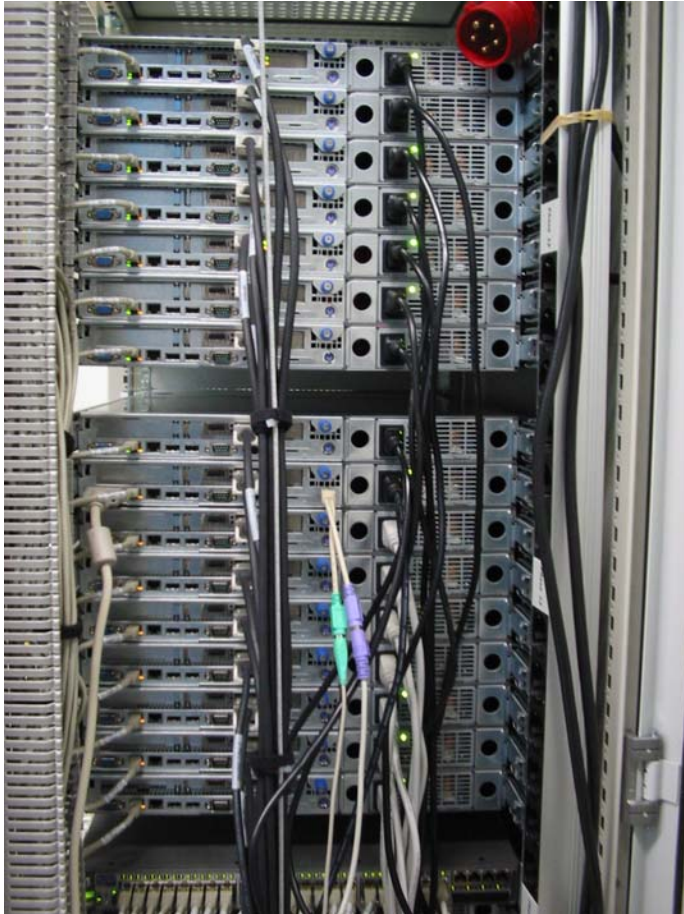
- 4U height per node
- Nodes:
  - 1-4 processors
  - 1-4 GB memory
- Network interconnects:
  - Myrinet (  $\sim 200\text{MB/s}$ ,  $7\mu\text{s}$  )
  - Fast Ethernet (  $\sim 12\text{MB/s}$ ,  $1\text{ms}$  )

(1U = 1.75" = 4.45 cm)





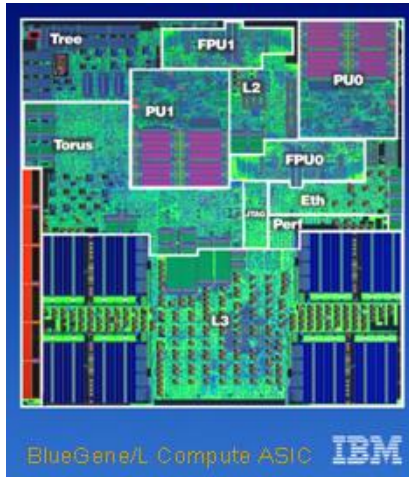
# What is a Parallel Computer?



## PC Cluster in 2005

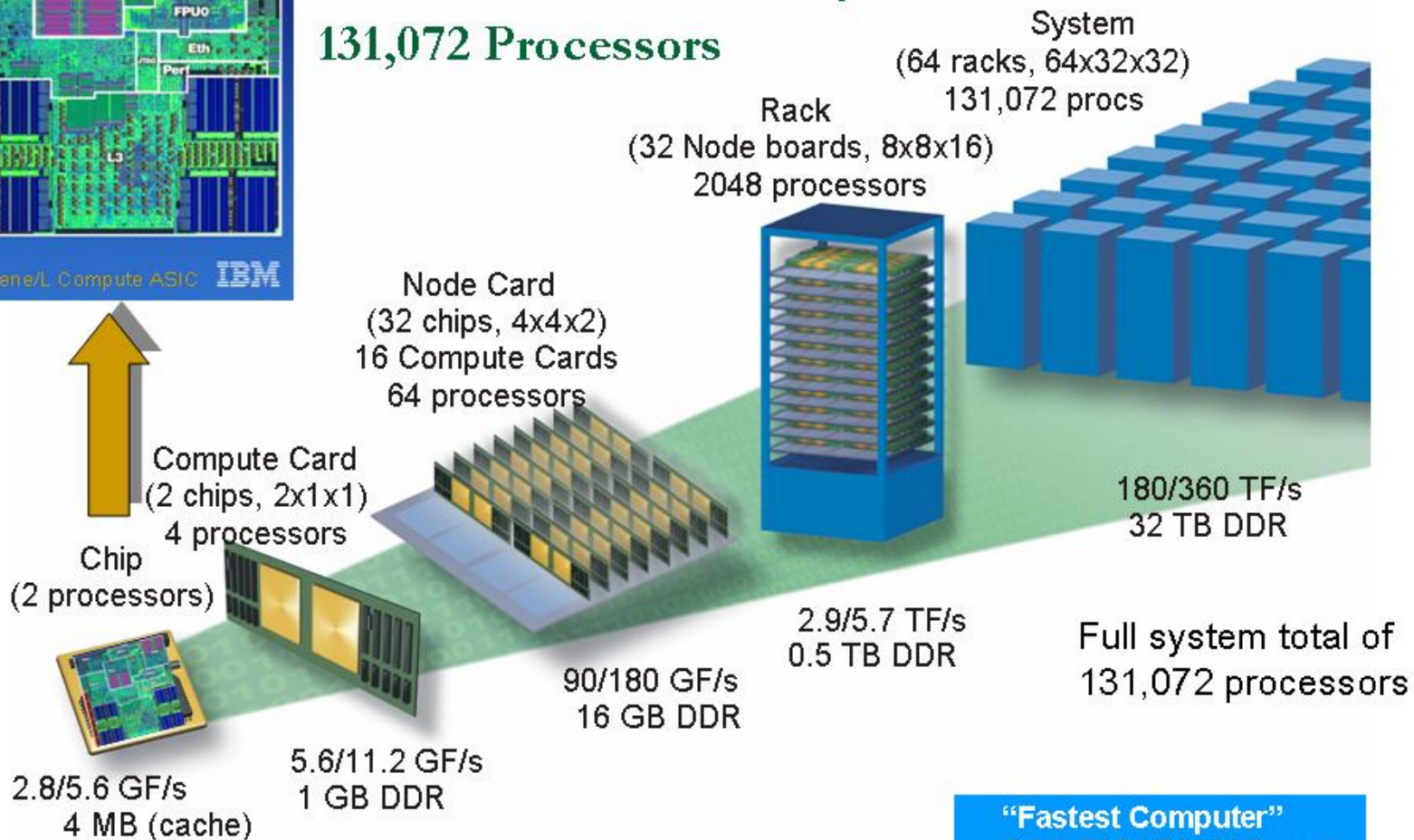
- 1U height
- Nodes:
  - 1-8 Processors
  - 1-32 GB main memory
- Network interconnects
  - Infiniband ( ~ 1 GB/s, 5  $\mu$ s )
  - Gigabit Ethernet ( ~80 MB/s, 50  $\mu$ s )





# IBM BlueGene/L

131,072 Processors

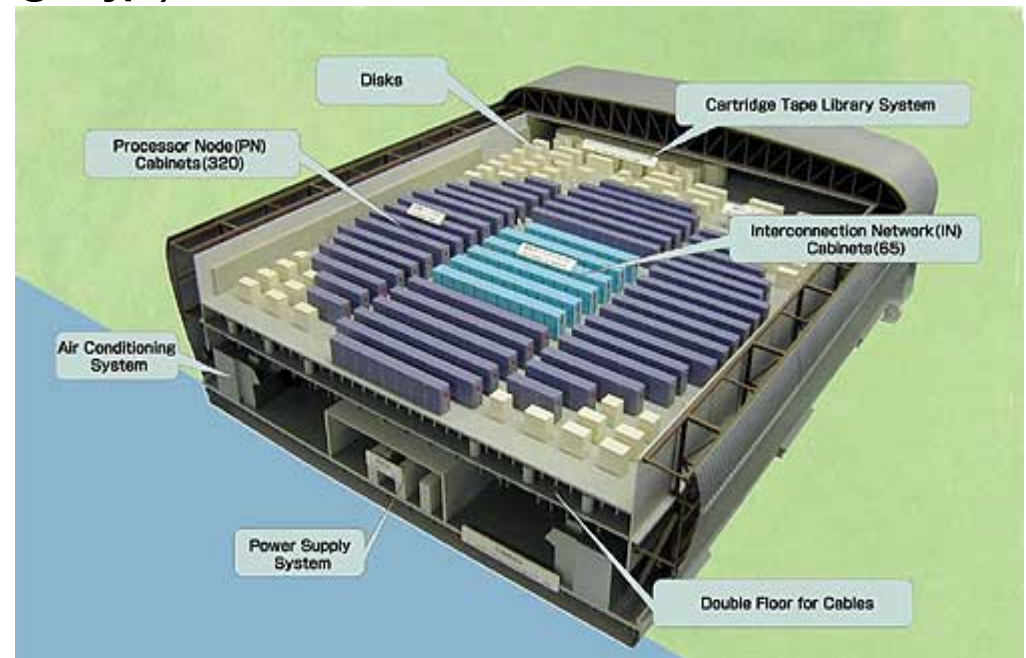


**"Fastest Computer"**  
BG/L 700 MHz 64K proc  
32 racks  
Peak: 184 Tflop/s  
Linpack: 135 Tflop/s  
73% of peak



# Earth Simulator

- Target: Achievement of high-speed numerical simulations with processing speed of 1000 times higher than that of the most frequently used supercomputers in 1996. ([www.es.jamstec.go.jp](http://www.es.jamstec.go.jp))
  - 640 nodes
  - 8 processors/node
  - 40 TFLOPS peak
  - 10 TByte memory



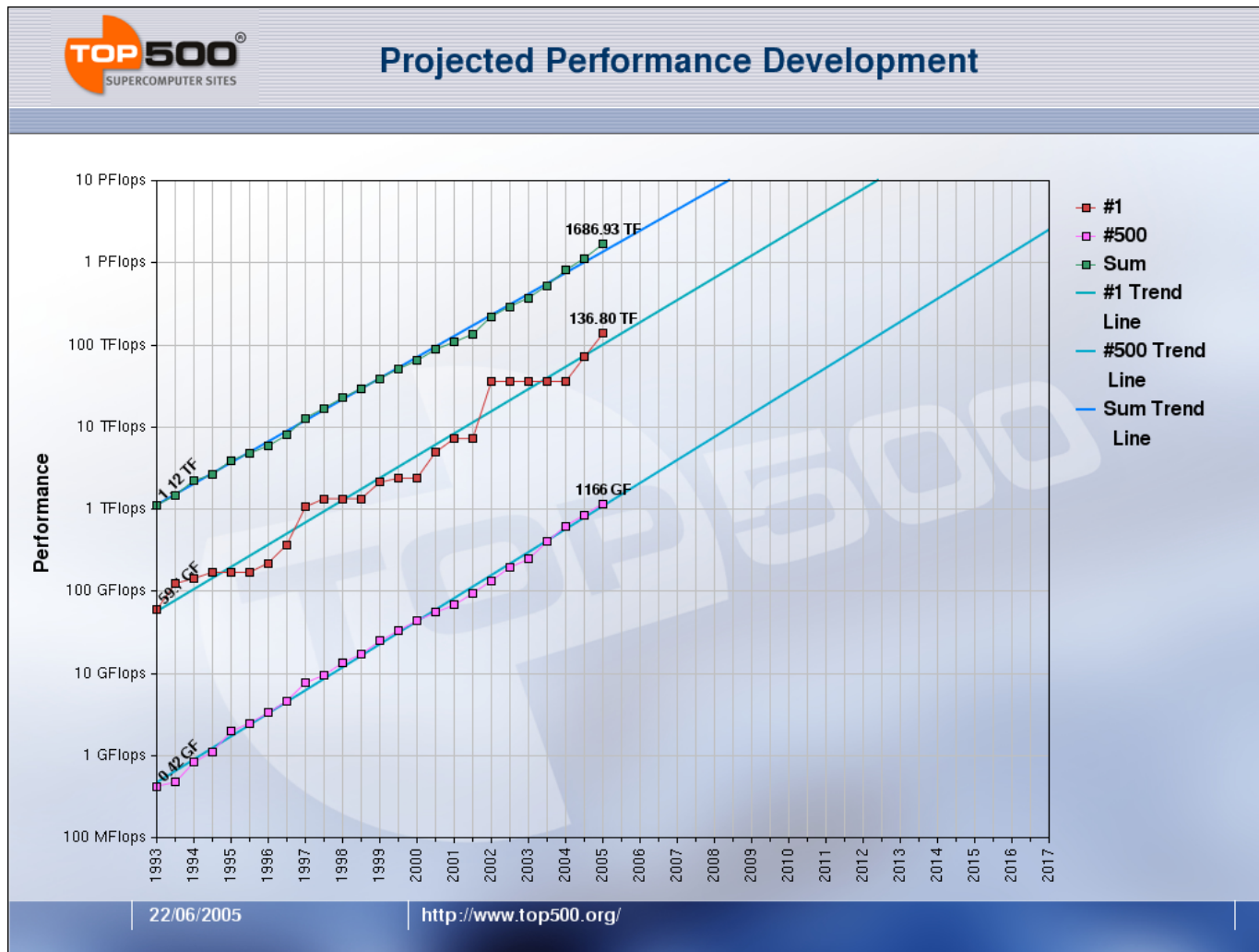


# Top 500 List (www.top500.org)

Rank	Site Country / Year	Computer / Processors Manufacturer	Computer Family Model	Inst. type Installation Area	R <sub>max</sub> R <sub>peak</sub>	N <sub>max</sub> n <sub>half</sub>
1	DOE/NNSA/LLNL United States/2005	BlueGene/L <u>eServer Blue Gene Solution</u> / 65536 IBM	IBM BlueGene/L eServer Blue Gene Solution	Research	136800 183500	1277951
2	IBM Thomas J. Watson Research Center United States/2005	BGW <u>eServer Blue Gene Solution</u> / 40960 IBM	IBM BlueGene/L eServer Blue Gene Solution	Research Information Processing Service	91290 114688	983039
3	NASA/Ames Research Center/NAS United States/2004	Columbia <u>SGI Altix 1.5 GHz, Voltaire</u> <u>Infiniband</u> / 10160 SGI	SGI Altix SGI Altix 3700	Research	51870 60960	1290240
4	The Earth Simulator Center Japan/2002	<u>Earth-Simulator</u> / 5120 NEC	NEC Vector SX6	Research	35860 40960	1075200 266240
5	Barcelona Supercomputer Center Spain/2005	MareNostrum <u>JS20 Cluster, PPC 970, 2.2 GHz,</u> <u>Myrinet</u> / 4800 IBM	IBM Cluster JS20 CCluster	Academic	27910 42144	977816
6	ASTRON/University Groningen Netherlands/2005	<u>eServer Blue Gene Solution</u> / 12288 IBM	IBM BlueGene/L eServer Blue Gene Solution	Academic	27450 34406.4	516095
7	Lawrence Livermore National Laboratory United States/2004	Thunder <u>Intel Itanium2 Tiger4 1.4GHz -</u> <u>Quadrics</u> / 4096 California Digital Corporation	NOW - Intel Itanium Itanium2 Tiger4 Cluster	Research	19940 22938	975000 110000
8	Computational Biology Research Center, AIST Japan/2005	Blue Protein <u>eServer Blue Gene Solution</u> / 8192 IBM	IBM BlueGene/L eServer Blue Gene Solution	Research	18200 22937.6	442367
9	Ecole Polytechnique Federale de Lausanne Switzerland/2005	<u>eServer Blue Gene Solution</u> / 8192 IBM	IBM BlueGene/L eServer Blue Gene Solution	Academic	18200 22937.6	442367
10	Sandia National Laboratories United States/2005	<u>Red Storm, Cray XT3, 2.0 GHz</u> / 5000 Cray Inc.	Cray XT3 Cray XT3	Research	15250 20000	
11	Oak Ridge National Laboratory United States/2005	<u>Cray XT3, 2.4 GHz</u> / 3748 Cray Inc.	Cray XT3 Cray XT3	Research	14170 17990	



# Top 500 List



# Recommended Literature

- Timothy G. Mattson, Beverly A. Sanders, Berna L. Massingill “*Patterns for Parallel Programming*” Software Pattern Series, Addison Wessley, 2005.
- Ananth Grama, Anshul Gupta, George Karypis, Vipin Kumar: “*Introduction to Parallel Computing*”, Pearson Education, 2003.
- Jack Dongarra, Ian Foster, Geoffrey Fox, William Gropp, Ken Kennedy, Linda Torczon, Andy White “*Sourcebook of Parallel Computing*”, Morgan Kaufmann Publishers, 2003.
- Michael J. Quinn: “*Parallel Programming in C with MPI and OpenMP*”, McGrawHill, 2004.
- L. Ridgeway Scott, Terry Clark, Babak Bagheri: “*Scientific Parallel Computing*”, Princeton University Press, 2005.



# Classification of Parallel Architectures

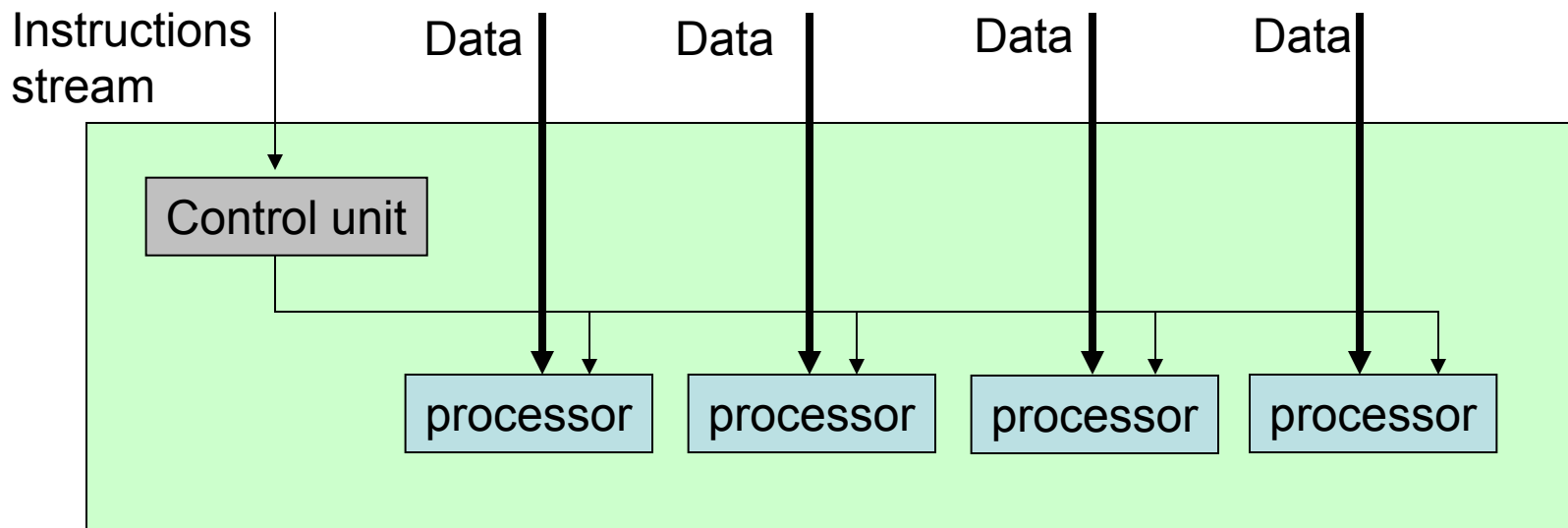
## Flynn's Taxonomy

- SISD: Single instruction single data
  - Classical von Neumann architecture
- SIMD: Single instruction multiple data
- MISD: Multiple instructions single data
  - Non existent, just listed for completeness
- MIMD: Multiple instructions multiple data
  - Most common and general parallel machine



# Single Instruction Multiple Data

- Also known as Array-processors
- A single instruction stream is broadcasted to multiple processors, each having its own data stream
  - Still used in graphics cards today





# Multiple Instructions Multiple Data (I)

- Each processor has its own instruction stream and input data
- Very general case
  - every other scenario can be mapped to MIMD
- Further breakdown of MIMD usually based on the memory organization
  - Shared memory systems
  - Distributed memory systems



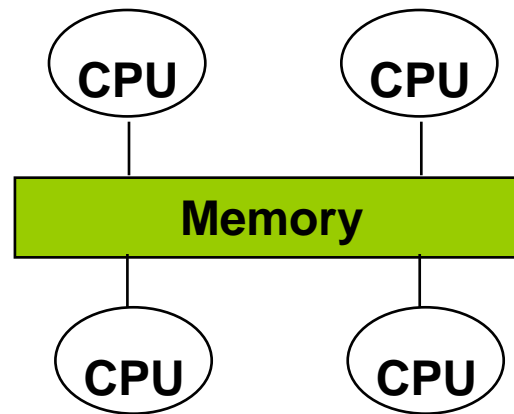
# Shared memory systems (I)

- All processes have access to the same address space
  - E.g. PC with more than one processor
- Data exchange between processes by writing/reading shared variables
  - Shared memory systems are easy to program
  - Current standard in scientific programming: OpenMP
- Two versions of shared memory systems available today
  - Symmetric multiprocessors (SMP)
  - Non-uniform memory access (NUMA) architectures



# Symmetric multi-processors (SMPs)

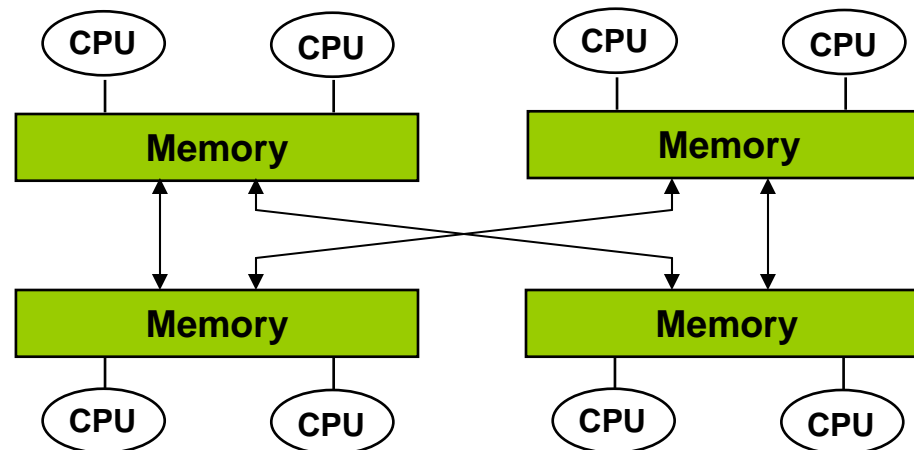
- All processors share the same physical main memory



- Memory bandwidth per processor is limiting factor for this type of architecture
- Typical size: 2-32 processors

# NUMA architectures (I)

- Some memory is closer to a certain processor than other memory
  - The whole memory is still addressable from all processors
  - Depending on what data item a processor retrieves, the access time might vary strongly



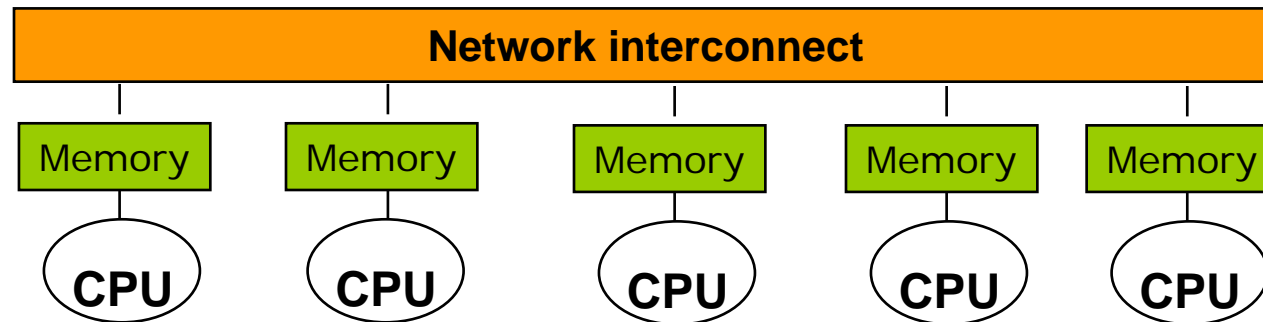
# NUMA architectures (II)

- Reduces the memory bottleneck compared to SMPs
- More difficult to program efficiently
  - E.g. first touch policy: data item will be located in the memory of the processor which uses a data item first
- To reduce effects of non-uniform memory access, caches are often used
  - ccNUMA: cache-coherent non-uniform memory access architectures
- Largest example as of today: SGI Origin with 512 processors



# Distributed memory machines (I)

- Each processor has its own address space
- Communication between processes by explicit data exchange
  - Sockets
  - Message passing
  - Remote procedure call / remote method invocation



# Distributed memory machines (II)

- Performance of a distributed memory machine strongly depends on the quality of the network interconnect and the topology of the network interconnect
  - Of-the-shelf technology: e.g. fast-Ethernet, gigabit-Ethernet
  - Specialized interconnects: Myrinet, Infiniband, Quadrics, 10G Ethernet ...



# Distributed memory machines (III)

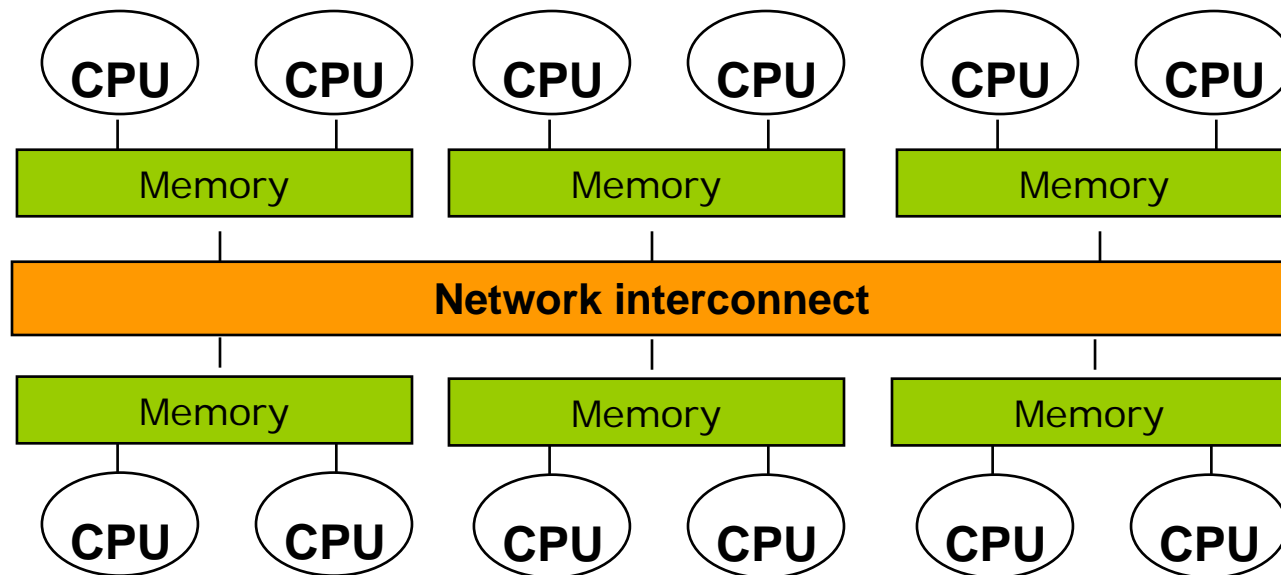
- Two classes of distributed memory machines:
  - Massively parallel processing systems (MPPs)
    - Tightly coupled environment
    - Single system image (specialized OS)
  - Clusters
    - Of-the-shelf hardware and software components such as
      - Intel P4, AMD Opteron etc.
      - Standard operating systems such as LINUX, Windows, BSD UNIX





# Hybrid systems

- E.g. clusters of multi-processor nodes



# Grids

- ‘Evaluation’ of distributed memory machines and distributed computing
- Several (parallel) machines connected by wide-area links (typically the internet)
  - Machines are in different administrative domains



# Network topologies (I)

- Important metrics:
  - Latency:
    - minimal time to send a very short message from one processor to another
    - Unit: ms,  $\mu$ s
  - Bandwidth:
    - amount of data which can be transferred from one processor to another in a certain time frame
    - Units: Bytes/sec, KB/s, MB/s, GB/s  
Bits/sec, Kb/s, Mb/s, Gb/s,  
baud



# Network topologies (II)

Metric	Description	Optimal parameter
Link	A direct connection between two processors	
Path	A route between two processors	As many as possible
Distance	Minimum length of a path between two processors	Small
Diameter	Maximum distance in a network	Small
Degree	Number of links that connect to a processor	Small (costs) / Large (redundancy)
Connectivity	Minimum number of links that have to be cut to separate the network	Large (reliability)
Increment	Number of procs to be added to keep the properties of a topology	Small (costs)
Complexity	Number of links required to create a network topology	Small (costs)

# Bus-Based Network

- All nodes are connected to the same (shared) communication medium
- Only one communication at a time possible
  - Does not scale

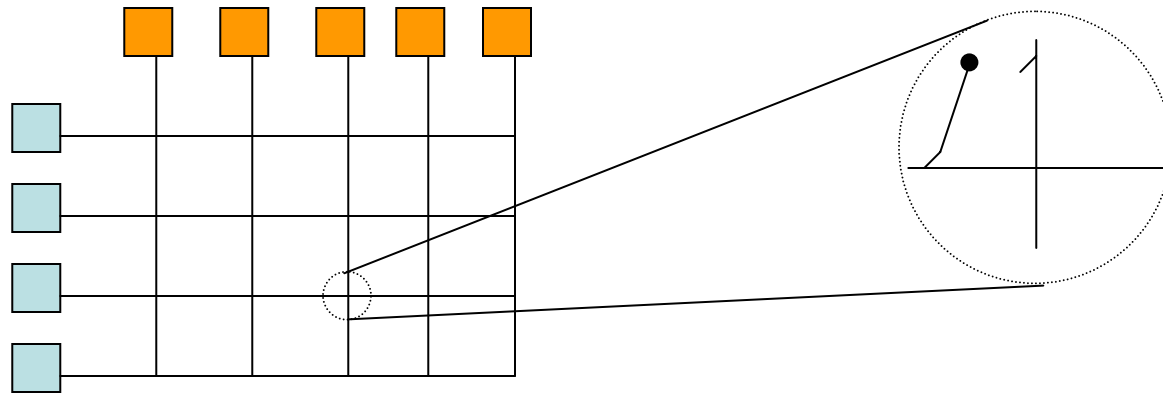


- Examples: Ethernet, SCSI, Token Ring, Memory bus
- Main advantages:
  - Cheap
  - Simple broadcast



# Crossbar Networks (I)

- A grid of switches connecting  $n \times m$  ports



- a connection from one process to another does not prevent communication between other process pairs
- Aggregated Bandwidth of a crossbar: sum of the bandwidth of all possible simultaneous connections

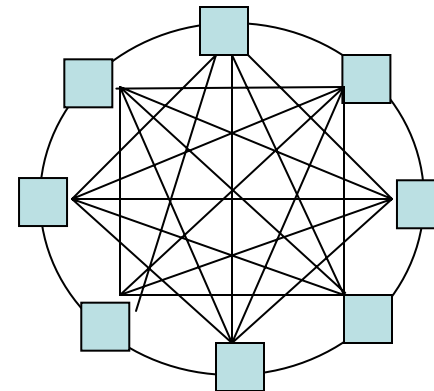
# Directly connected networks

- A direct connection between two processors exists
- Relevant topologies
  - Ring
  - Star
  - Fully connected
  - Meshes
  - Toruses
  - Tree based networks
  - Hypercubes



# fully connected network

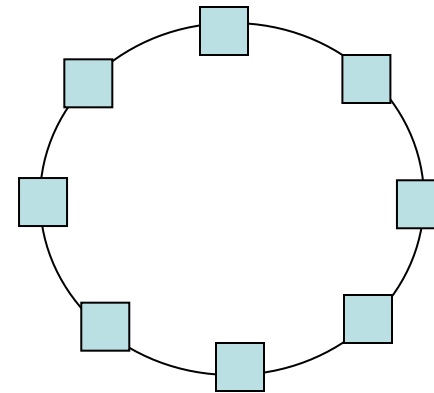
- Every node is connected directly with every other node
  - Distance: 1
  - Diameter: 1
  - Degree:  $N-1$
  - Connectivity:  $N-1$
  - Increment: 1
  - Complexity:  $N*(N-1)/2$
- Positive:
  - Fast: one *hop* to each node
  - Fault-tolerant
- Negative:
  - Does not scale / expensive
  - Technically difficult!





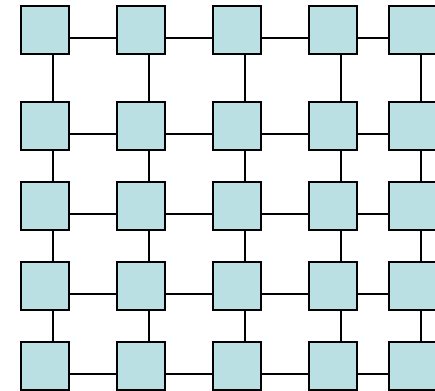
# Ring network

- N: Number of processor connected by the network
  - Distance: 1:  $N/2$
  - Diameter:  $N/2$
  - Degree: 2
  - Connectivity: 2
  - Increment: 1
  - Complexity:  $N-1$



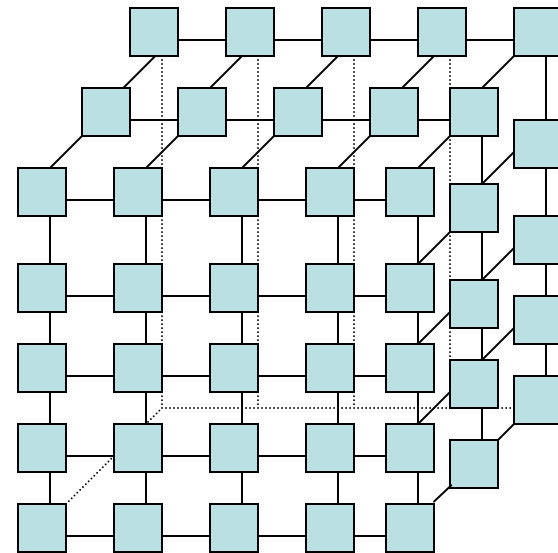
# Meshes (I)

- E.g. 2-D mesh
  - Distance:  $1: \sim 2\sqrt{N}$
  - Diameter:  $\sim 2\sqrt{N}$
  - Degree: 2-4
  - Connectivity: 2
  - Increment:  $\sim \sqrt{N}$
  - Complexity:  $\sim 2N$



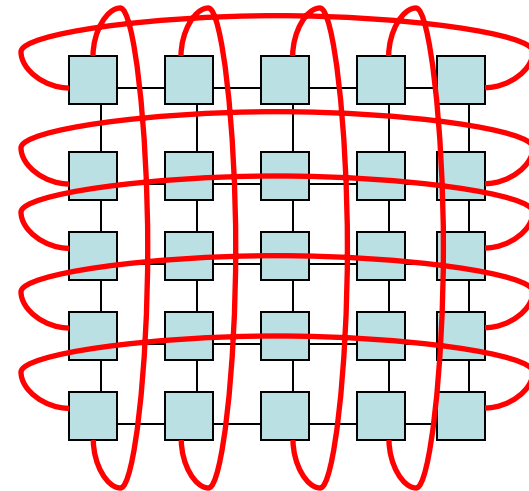
# Meshes (II)

- E.g. 3-D mesh
  - Distance:  $1: \sim \sqrt[3]{N}$
  - Diameter:  $\sim \sqrt[3]{N}$
  - Degree: 3-6
  - Connectivity: 3
  - Increment:  $\sim$
  - Complexity:  $\sim \sqrt[3]{N}$



# Toruses (I)

- E.g. 2-D Torus
  - Distance:  $1: \sim \sqrt{N}$
  - Diameter:  $\sim \sqrt{N}$
  - Degree: 4
  - Connectivity: 4
  - Increment:  $\sim \sqrt{N}$
  - Complexity:  $\sim 2N$



# Tree-based networks

- Leafs are computational nodes, Intermediate nodes in the tree are switches
- Fat tree: binary tree which increases the number of communication links between higher level switching elements to avoid contention
  - Distance:  $1:2\log_2(N)$
  - Diameter:  $2\log_2(N)$
  - Degree: 1
  - Connectivity: 1
  - Increment:  $N$
  - Complexity:  $\sim 2N$

