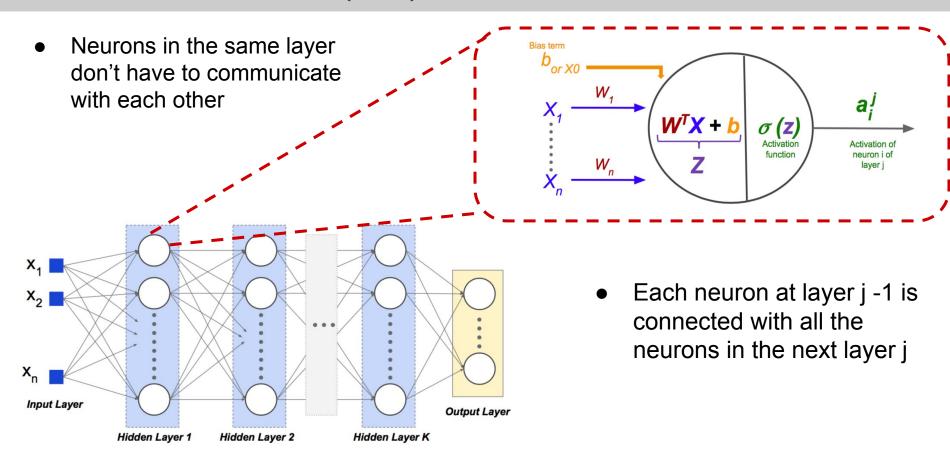


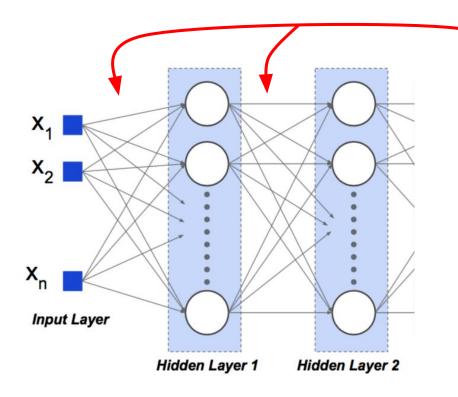
Neural Networks

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Artificial Neural Network (ANN)



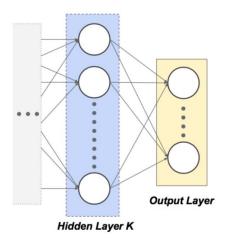
Artificial Neural Network (ANN)

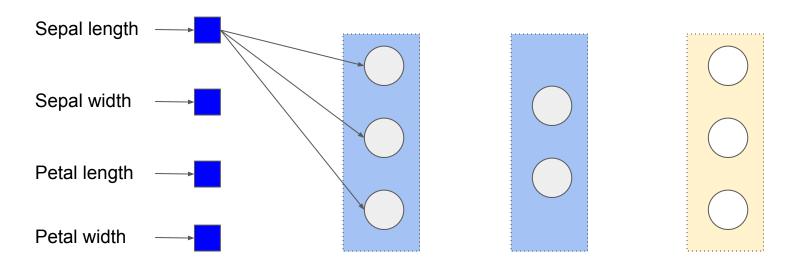


- Each connection between input and neurons, and between neurons and neurons has an associated weight w
- Weights are randomly initialized
- Our goal during the training step is to learn these weights
- All weights between two layers are organized in a matrix W

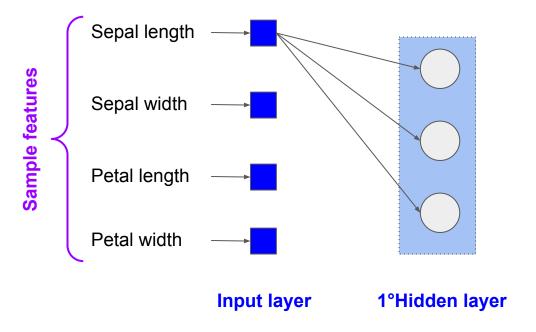
The output layer

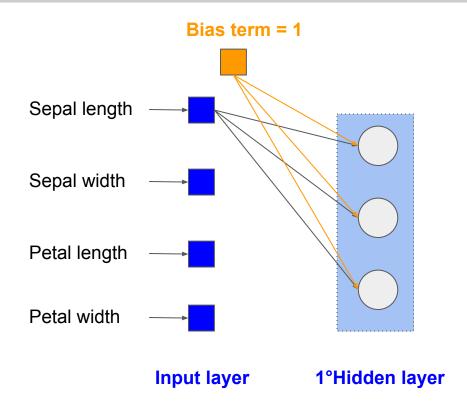
- We should say something more about the output layer.
- The structure of this last layer depends on the task you want to perform.
- y in our dataset has to be formatted depending on this layer
- Usually the number of neurons is equal to the number of expected possible outputs, but we should pay attention:
 - Regression: For example price prediction of a house, we need only one neuron with an activation function that is able to produce the value we need (for example a linear function)
 - Binary classification: We can have one neuron with a sigmoid activation function. But it is not the only possibility!
 - Multi-class or multi-label classification: We will have a number of neurons equal to the number of the possible classes.
 Each neuron is like a binary classifier.

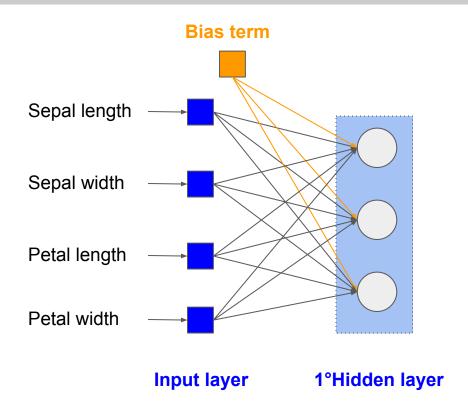


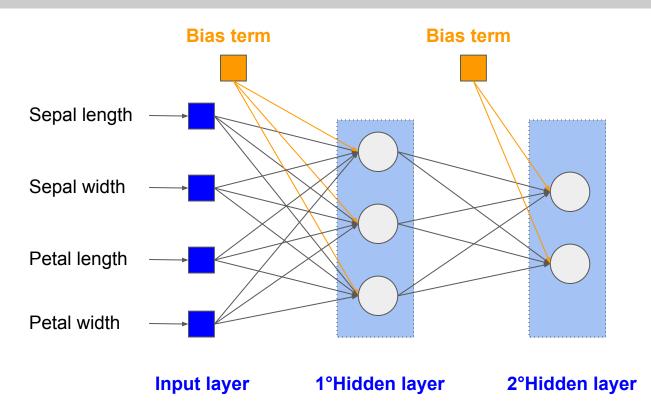


Input layer

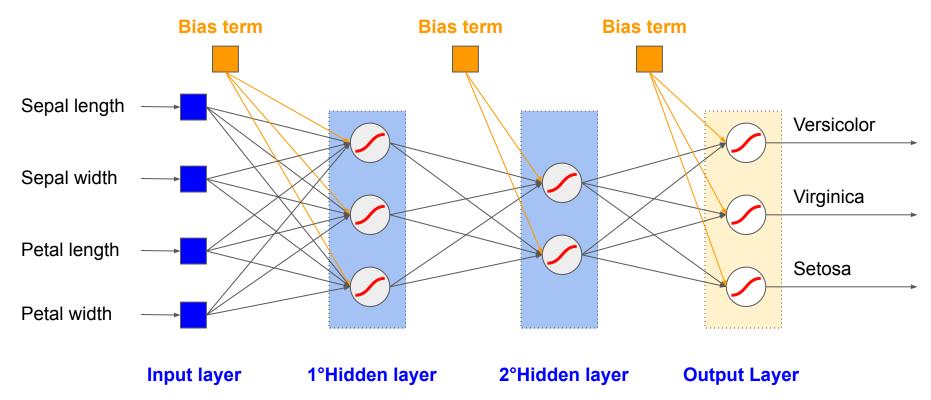








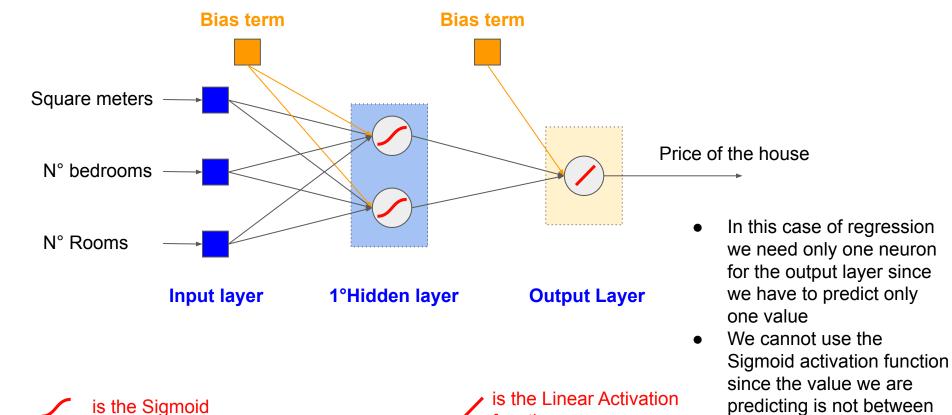
- Now we want to add the output layer to make predictions
- How many neurons we need?





Another example: House price prediction

Activation function

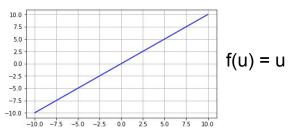


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0-1 but can be any value

Activation functions in Neural networks

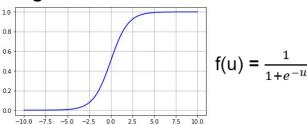
Linear Activation



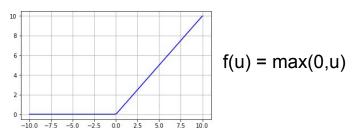
Tanh Activation



Sigmoid Activation

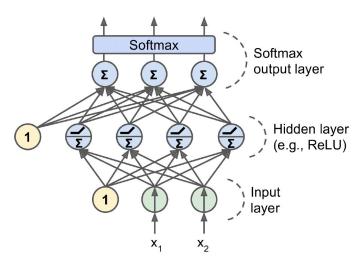


ReLU Activation



The Softmax output layer: Only for Classification!

- When the classes are exclusive (class 0 is a dog, class 1 is a cat, class 2 is a mouse) and the problem is not multi-label (to each sample we assign one and only one label, another type of neuron is used
- We can replace individual activation functions with a shared Softmax function
- The output of each neuron corresponds to the estimated probability of the corresponding class
- The Softmax function is a generalization of Logistic Regression in order to support multiple classes directly without having to train and combine multiple binary classifiers



The Softmax output layer

- The idea is the following:
 - Given an instance x or its representation in the penultimate layer of a neural network
 - The Softmax model compute a score s_k(x) for each class k
 - Then it estimates the probability of each class by applying the softmax function to these scores
- $s_k(x) = W^{(k) T} X$ (Remember logistic for binary classification?)
 - Each class has its own dedicated parameter vector W^(k)
- Now we can compute the probability p_k that the instance belongs to class k

$$\hat{p}_k = \sigma(s(\mathbf{x}))_k = \frac{\exp(s_k(\mathbf{x}))}{\sum_{i=1}^K \exp(s_i(\mathbf{x}))}$$

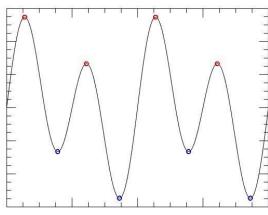
• It predicts the class with the highest probability (class with the highest score)

Neural networks: Optimization problem

- Our goal is to minimize an objective function, which measures the difference between the actual output t and the predicted output y.
 - In this case we will consider as the objective function the squared loss function.

Squared loss function

$$E = \frac{1}{2}(t - y)^2 = \frac{1}{2}(t - f(\mathbf{w}^T\mathbf{x}))^2$$



Loss functions

Squared loss function

$$E = \frac{1}{2}(t - y)^2$$

Mean squared error

$$E = \frac{1}{n} \sum_{i=1}^{n} (t_i - y_i)^2$$

Mean absolute error

$$E = \frac{\sum_{i=1}^{n} |t_i - y_i|}{n}$$

Cross entropy

$$E = -\sum_{i=1}^{n} t_i \log(y_i)$$

Kullback Leibler divergence

$$E = \sum_{i=1}^{n} t_i \log \left(\frac{t_i}{y_i} \right)$$

Cosine proximity

$$E = \frac{t \ y}{||t|| \ ||y||}$$

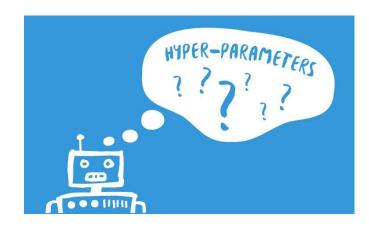
Loss functions

- For Regression task
 - Mean Squared Error Loss
 - Mean Absolute Error Loss
- For Binary Classification
 - Binary Cross-Entropy

- For Multi-Class Classification
 - Multi-Class Cross-Entropy Loss
 - Kullback Leibler Divergence Loss
- Note: This list is not exhaustive

Hyper-parameters

- Hyperparameters are the parameters which determine the network structure (e.g. Number of Hidden Units) and the parameters which determine how the network is trained (e.g. Learning Rate)
 - Number of neurons
 - Number of layers
 - Learning rate
 - Batch size
 - Number of epochs
 - others

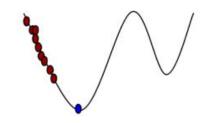


Learning rate

- Training parameter that controls the size of weight changes in the learning phase of the training algorithm.
- The learning rate determines how much an updating step influences the current value of the weights.

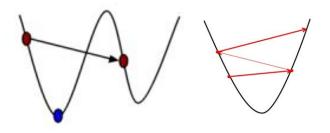
$$w_i^{new} = w_i^{old} - \frac{\partial E}{\partial w_i}$$

Very small learning rate



Many updates required before reaching the minimum.

Too big learning rate



Drastic updates can lead to divergent behaviors, missing the minimum.

Hyper-parameters

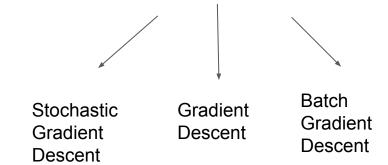
Number of epochs

 The number of epochs is the number of times the whole training data is shown to the network while training.

 Remember that at the beginning weights are randomly initialized. Our training is sensitive to this initialization

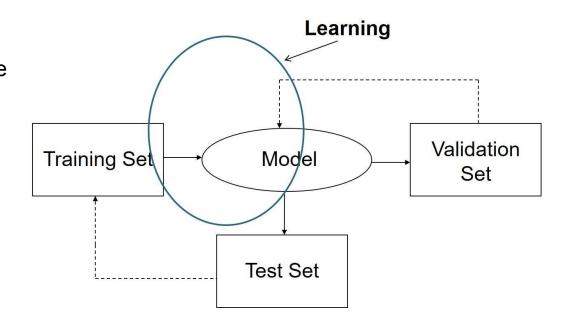
Batch size

 The number of samples shown to the network before the gradient computation and the parameter update.



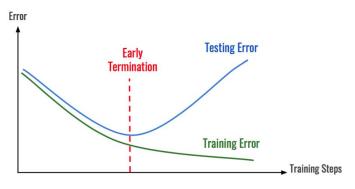
Validation set

- Data set with the 'same' goal of the test set (verifying the quality of the model which has been learnt), but not as a final evaluation, but as a way to fine-tune the model.
- Its aim is to provide a feedback which allows one to find the best settings for the learning algorithm (parameter tuning).



Early stopping

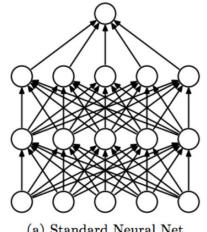
- Early stopping is a form of regularization used to avoid overfitting when training a learner with an iterative method, such as gradient descent
- Stop training as soon as the error on the validation set is higher than it was the last time it was checked
 - We can define a patient parameters: We accept that a patient number of times the validation error can be higher than the previous iteration. After this number is reached, training will be stopped.
- Use the weights the network had in that previous step as the result of the training run



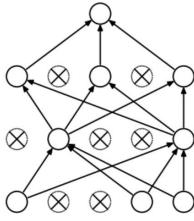
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Dropout

- It is another form of regularization for Neural Networks
- At each update during training time, randomly setting a fraction rate of input units to 0.
- It helps to prevent overfitting.



(a) Standard Neural Net



(b) After applying dropout.

Choosing the Loss function and the best optimizer

- To minimize the loss we don't have only Gradient Descent or Stochastic Gradient Descent (SGD).
- Other gradient-based optimizers are available, in particular in Keras such as:
 - RMSprop
 - Adam
- It is important to deeply understand the problem we are dealing with when we have to choose the loss function and the best optimizer for our task

Keras

- Keras is an open-source library that provides tools to develop artificial neural networks
- Keras acts as an interface for the TensorFlow library
- First install TensorFlow: pip install tensorflow
- Then pip install Keras (Optional with the latest version of Tensorflow)



```
from sklearn.datasets import load_breast_cancer
from sklearn.model_selection import train_test_split
import numpy as np
import matplotlib.pyplot as plt
```

import tensorflow as tf
from tensorflow.keras import models
from tensorflow.keras import layers

```
X, y = load_breast_cancer(return_X_y=True)
X_train, X_test, y_train, y_test = train_test_split(X, y,
test_size=0.20)

print("Training set dimensions (train_data):")
print(X train.shape)
```

```
model = models.Sequential()
#The first layer that you define is the input layer. This
layer needs to know the input dimensions of your data.
# Dense = fully connected layer (each neuron is fully
connected to all neurons in the previous layer)
model.add(layers.Dense(64, activation='relu',
input shape=(X train.shape[1],)))
# Add one hidden layer (after the first layer, you don't need
to specify the size of the input anymore)
model.add(layers.Dense(64, activation='relu'))
# If you don't specify anything, no activation is applied (ie.
"linear" activation: a(x) = x)
model.add(layers.Dense(1,activation='sigmoid'))
```

```
model.compile(loss='binary crossentropy', optimizer='adam',
metrics=[tf.keras.metrics.Precision()])
# Fit the model to the training data and record events into a
History object.
history = model.fit(X train, y train, epochs=10, batch size=1,
validation split=0.2, verbose=1)
 Model evaluation
test loss, test pr = model.evaluate(X test, y test)
print(test pr)
```

Breast cancer: Plot Loss VS Epochs

```
# Plot loss (y axis) and epochs (x axis) for training set and
validation set
plt.figure()
plt.xlabel('Epoch')
plt.ylabel('Loss')
plt.plot(history.epoch,
np.array(history.history['loss']), label='Train loss')
plt.plot(history.epoch,
np.array(history.history['val loss']), label = 'Val loss')
plt.legend()
plt.show()
```

Setting learning rate and optimizer

```
opt = keras.optimizers.Adam(lr=0.01)
model.compile(loss='binary_crossentropy',optimizer=opt, metrics=[...])
```

https://keras.io/api/optimizers/adam/

Available optimizers:

https://keras.io/api/optimizers/

Modifications to use Softmax (Suggested for Multi-class problems)

```
from tensorflow.keras.utils import to_categorical
y = to_categorical(y)
...
...
```

model.add(layers.Dense(2,activation='softmax'))

- Now our y is a matrix with a number of columns equal to the number of possible classes
- The column value is equal to 0 or 1 depending on the class associated to that example (row)

Example: Boston regression

```
from sklearn.datasets import load_boston
from sklearn.metrics import mean_squared_error
from sklearn.model_selection import train_test_split
import numpy as np
import matplotlib.pyplot as plt
```

from tensorflow.keras import models from tensorflow.keras import layers

Example: Boston regression

```
X, y = load_boston(return_X_y=True)
X_train, X_test, y_train, y_test = train_test_split(X, y,
test_size=0.20)

print("Training set dimensions (train_data):")
print(X train.shape)
```

Example: Boston regression

```
model = models.Sequential()
model.add(layers.Dense(64,
activation='relu', input shape=(X train.shape[1],)))
model.add(layers.Dense(64, activation='relu'))
model.add(layers.Dense(1,activation='relu'))
model.compile(optimizer='rmsprop', loss='mse', metrics=['mse'])
history = model.fit(X train, y train, epochs=10, batch size=1,
validation split=0.2, verbose=1)
test loss score, test mse score = model.evaluate(test data,
test targets)
# MSE
print(test mse score)
```

Possible metrics

https://keras.io/api/metrics/

Dropout, early stopping and validation data

- Dropout is a simple layer you should add
 - model.add(layers.Dropout(VALUE between 0 and 1))
- Early stopping is a callback

```
from keras.callbacks import EarlyStopping (for new version try tf.keras)
es = EarlyStopping(monitor='val_loss',mode='min', verbose=1, patience= 10)
....
model.fit(X_train, Y_train,epochs=300,validation_data=(X_val, Y_val),callbacks=[es])
```



Lab

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Exercise

- Starting from the breast cancer example try to report how precision and recall changes:
 - Increasing number of epochs
 - Increasing the batch size
 - Modify the network architecture: try to add more hidden layers and to build a funnel structure
 - First hidden layer should have 75% of input layer

■ Second: 50%

■ Third: 25%

■ Fourth: 12.5%

■ Five: 6% and so on

Cars sale prediction

- Cars dataset: the task is to predict the value of a potential car sale (i.e. how much a particular person will spend on buying a car) for a customer on the basis of the following attributes: age, gender, average miles driven per day, personal debt, monthly income
- Create a sequential model (loss='mse', optimizer='rmsprop', metrics=['mse'], epochs=150, batch_size=50) adding:
 - A ("Dense") layer with some nodes (input_dim=5, activation='relu')
 - A hidden ("Dense") layer with other nodes (activation='relu')
 - An output ("Dense") layer composed of 1 node
- Plot the mean squared error over the epochs for the training set and for the validation set (validation_spilt=0.2)
- Compute the root mean squared error on the test set

Sonar classification

- Sonar dataset: the task is to train a network to discriminate between sonar signals (60 features) bounced off a metal cylinder (class M) and those bounced off a roughly cylindrical rock (class R).
- Create a sequential model (loss='binary_crossentropy', optimizer='adam', metrics=['accuracy'], epochs=100, batch_size=5) adding:
 - An input ("Dense") layer composed of 60 nodes (input_dim=60, activation='relu')
 - An output ("Dense") layer composed of 1 node (activation='sigmoid')
- Make predictions for the labels of the test set and evaluate the model