Echoes and Delays: Time-to-Build in Production Networks

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Motivation

- Firms in a modern economy rely on a complex network of suppliers, whose time-to-build varies significantly
 - ► Ex.: < 1 month for furniture assembly, 1-2 years for container ships
- Most of the literature on production networks ignores time-to-build and possibilty of delays
 - ▶ Acemoglu et al. (2012), Baqaee and Farhi (2019, 2020),... essentially static
 - ▶ Roundabout production: disruptions are resolved within period
- How does the introduction of time-to-build or delivery lags affect dynamics of production networks?

What We Do

- We propose a simple model to introduce time-to-build (T2B) in production networks
 - ▶ Long and Plosser (1983) (one period delay) + heterogeneous T2B
- We analyze how T2B contributes to propagation of shocks:
 - 1. Persistence, delays and bottlenecks
 - 2. Echoes and endogenous fluctuations
 - 3. Dynamic sectoral comovements and aggregation
- Empirical evidence (in progress)

Related Literature

- Shock propagation in production networks
 - Acemoglu et al. (2012), Barrot and Sauvagnat (2016), Carvalho et al. (2016), Acemoglu et al. (2017), Baqaee and Farhi (2019), Ghassibe (2024),...
- Time-to-build
 - ► Kydland and Prescott (1982), Schwartzman (2014),...
 - ► In production networks:
 - Long and Plosser (1983), Liu and Tsyvinski (2023), Bizarri (2024), Carvalho and Reischer (2025), Bizarri, Pangallo and Queirós (2025), Leng, Liu, Ren and Tsyvinski (2025)
- Endogenous fluctuations in multi-sector economies:
 - ► Benhabib and Nishimura (1979, 1985, ...)
- Delays in supply chains:
 - ▶ Djankov et al. (2010), Hummels and Schaur (2013), Meier (2020), Alessandria et al. (2023), Carreras-Valle and Ferrari (2025)
- Sequential production in trade
 - Dixit and Grossman (1982), Antràs and Chor (2013), Costinot et al. (2013), etc.

Data

Input-Output

- IO-Use tables from BEA for 2017
 - ▶ 402 6-digit NAICS industries

Time-to-Build

Measure:

$$\mathsf{backlog\ ratio} = \frac{\mathsf{stock\ value\ of\ unfilled\ orders}}{\mathsf{flow\ value\ of\ goods\ delivered}}$$

- ▶ Includes production time + waiting and delivery times, some potential biases
- US Census M3 survey on "Shipments, Inventories and Orders" (monthly)
 - \blacktriangleright All manufacturing, aggregated to \sim 10 subsectors for 1992-2024
- Compustat "Order Backlog" variable (annual)
 - ▶ Publicly listed firms but firm level & broader sectoral coverage for 1970-2024



Backlog Distribution

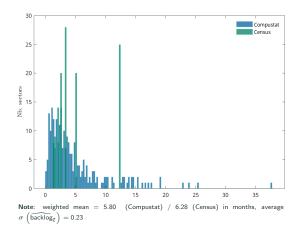


Figure 1: Distribution of backlog ratios (months) across 6-digit sectors

Model

Model

- Time is discrete
- Representative household with inelastic labor supply
- Sectors i = 1, ..., N with production

$$y_{it} = A_{it}F_i(I_{it}, x_{i1,t}, ..., x_{iN,t})$$

- Time-to-build modeled as delivery lags:
 - \blacktriangleright Goods in sector i take τ_i periods to be delivered
 - ▶ Denote $X_{i\tau} \equiv \text{agg. stock of } i$ scheduled for delivery in τ periods
- No capital, no storage between periods for now

$$V\left(\left\{A_{i}\right\},\left\{X_{1\tau}\right\}_{\tau=0}^{\tau_{1}-1},...,\left\{X_{N\tau}\right\}_{\tau=0}^{\tau_{N}-1}\right) = \max_{c_{i},l_{i},X_{ij},Y_{i}} U\left(c_{1},...,c_{N}\right) + \beta E\left[V\left(\left\{A_{i}^{\prime}\right\},\left\{X_{1\tau}^{\prime}\right\}_{\tau=0}^{\tau_{1}-1},...,\left\{X_{N\tau}^{\prime}\right\}_{\tau=0}^{\tau_{N}-1}\right)\right]$$

subject to:

$$1 \geq \sum_{i=1}^N I_i$$

and for all i = 1..N:

$$X'_{i\tau} = X_{i\tau+1} \text{ for } 0 \le \tau < \tau_i - 1$$
 $X'_{i\tau_i-1} = y_i$
 $X_{i0} \ge c_i + \sum_j x_{ji}$
 $y_i = A_i F_i (I_{it}, x_{i1}, ..., x_{iN})$

$$\begin{split} V\left(\left\{A_{i}\right\},\left\{X_{1\tau}\right\}_{t=0}^{\tau_{1}-1},...,\left\{X_{N\tau}\right\}_{\tau=0}^{\tau_{N}-1}\right) &= \max_{c_{i},l_{i},X_{ij},Y_{i}} U\left(c_{1},...,c_{N}\right) \\ &+ \beta E\left[V\left(\left\{A_{i}^{\prime}\right\},\left\{X_{1\tau}^{\prime}\right\}_{t=0}^{\tau_{1}-1},...,\left\{X_{N\tau}^{\prime}\right\}_{\tau=0}^{\tau_{N}-1}\right)\right] \end{split}$$

subject to:

$$1 \geq \sum_{i=1}^N I_i$$

and for all i = 1..N:

$$\begin{aligned} & \boldsymbol{X}_{i\tau}' = \boldsymbol{X}_{i\tau+1} \text{ for } 0 \leq \tau < \tau_i - 1 \\ & \boldsymbol{X}_{i\tau_i-1}' = y_i \\ & \boldsymbol{X}_{i0} \geq c_i + \sum_j x_{ji} \\ & y_i = A_i F_i \left(I_{it}, x_{i1}, ..., x_{iN} \right) \end{aligned}$$

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$$\begin{split} V\left(\left\{A_{i}\right\},\left\{X_{1\tau}\right\}_{t=0}^{\tau_{1}-1},...,\left\{X_{N\tau}\right\}_{\tau=0}^{\tau_{N}-1}\right) &= \max_{c_{i},l_{i},x_{ij},y_{i}} U\left(c_{1},...,c_{N}\right) \\ &+ \beta E\left[V\left(\left\{A_{i}^{\prime}\right\},\left\{X_{1\tau}^{\prime}\right\}_{t=0}^{\tau_{1}-1},...,\left\{X_{N\tau}^{\prime}\right\}_{\tau=0}^{\tau_{N}-1}\right)\right] \end{split}$$

subject to:

$$1 \geq \sum_{i=1}^{N} I_i$$

and for all i = 1..N:

$$\begin{aligned} X'_{i au} &= X_{i au+1} \text{ for } 0 \leq au < au_i - 1 \\ X'_{i au_i-1} &= y_i \\ X_{i0} &\geq c_i + \sum_j x_{ji} \\ y_i &= A_i F_i \left(I_{it}, x_{i1}, ..., x_{iN} \right) \end{aligned}$$

• High dimensional state space: 402 sectors × # lags !

Proposition

For
$$F_i\left(I,x_{i1},...,x_{iN}\right)=I^{\alpha_i}\prod_{j=1}^N x_{ij}^{\omega_{ij}}$$
 with $\alpha_i+\sum_j \omega_{ij}=1$ and $U\left(c_1,...,c_N\right)=\sum_1^N \gamma_i\log c_i$, the economy can be solved analytically and

$$c_{i} = \overline{c_{i}}X_{i0}$$

$$x_{ji} = \overline{x_{ji}}X_{i0}$$

$$I_{i} = \overline{I_{i}}$$

where $\overline{c_i}$, $\overline{x_{ij}}$ and $\overline{l_i}$ are constants, and

$$V\left(\mathbf{A}, \mathbf{X}_{1}, ...\right) = \sum_{i=1}^{N} \sum_{\tau=0}^{\tau_{i}} \beta^{\tau} \zeta_{i} \log X_{i\tau} + G\left(\mathbf{A}\right)$$

where

$$oldsymbol{\zeta} = \left(I - \left[\Omega \cdot eta^{ au}\right]'\right)^{-1} \gamma$$
 (time-adjusted Domar weights)
 $G\left(\mathbf{A}\right) = \sum_{i} eta^{ au_{i}} \zeta_{i} \log A_{i} + eta E\left[G\left(\mathbf{A}'\right)\right]$

Output

In log-deviation from steady state:

$$\hat{y}_{it} = \hat{A}_{it} + \sum_{j} \omega_{ij} \hat{y}_{jt-\tau_{j}}$$

• VAR(τ_{max}) representation:

$$\hat{\mathbf{y}}_t = \mathbf{\Omega}_1 \hat{\mathbf{y}}_{t-1} + \ldots + \mathbf{\Omega}_{ au_{\mathsf{max}}} \hat{\mathbf{y}}_{t- au_{\mathsf{max}}} + \hat{\mathbf{A}}_t$$

where
$$\Omega_{ au} = \Omega \cdot \mathbf{1} \left\{ au = au_i
ight\}$$

- Nested cases:
 - ► Roundabout production: no time-to-build

$$\begin{split} \hat{\mathbf{y}}_t &= \hat{\mathbf{A}}_t + \Omega \hat{\mathbf{y}}_t \Rightarrow \hat{\mathbf{y}}_t = &\hat{\mathbf{A}}_t + \Omega \hat{\mathbf{A}}_t + \Omega^2 \hat{\mathbf{A}}_t + \dots \\ &= \left[\mathbf{I} - \Omega\right]^{-1} \hat{\mathbf{A}}_t \quad \text{(Leontieff inverse)} \end{split}$$

▶ Long and Plosser (1983): one-period time-to-build

$$\hat{\mathbf{y}}_t = \hat{\mathbf{A}}_t + \Omega \hat{\mathbf{y}}_{t-1} \Rightarrow \hat{\mathbf{y}}_t = \hat{\mathbf{A}}_t + \Omega \hat{\mathbf{A}}_{t-1} + \Omega^2 \hat{\mathbf{A}}_{t-2} + \dots$$

Persistence and Delays

Additional results:

• Persistence statistics • Go

$$\mathcal{T}\left(\hat{\mathbf{A}}\right) = \frac{1}{\textit{CIR}\left(\hat{\mathbf{A}}\right)} \sum_{\tau=0}^{\infty} \sum_{i} \tau w_{i} \hat{y}_{i\tau}\left(\hat{\mathbf{A}}\right)$$

- ⇒ Substantial additional persistence even for iid shocks, highly heterogeneous
- Delay shocks Go
 - ▶ Delayed arrival of intermediate goods to later date
 - ⇒ Sizeable impact of delays, some leading to oscillations
- Bottlenecks Go
 - ▶ To which sectors do delay shocks contribute most to the persistence of shocks?
 - ⇒ Bottlenecks identified by (weighted) supplier × buyer centrality measures

Echoes and Endogenous Fluctuations

VAR(1) Representation

• The $VAR(\tau_{max})$ system can be put into VAR(1) form

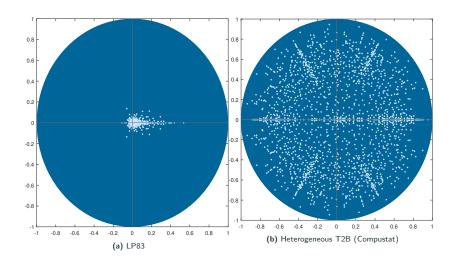
$$\underbrace{ \begin{pmatrix} \hat{\mathbf{y}}_t \\ \hat{\mathbf{y}}_{t-1} \\ \\ \hat{\mathbf{y}}_{t-\tau_{\max}+1} \end{pmatrix} }_{\equiv \mathbf{Y}_t} = \underbrace{ \begin{pmatrix} \Omega_1 & \Omega_2 & \dots & \Omega_{\tau_{\max}} \\ I_n & & & \\ & I_n & & \\ & & \ddots & \\ & & & I_n \end{pmatrix} }_{\equiv \mathbb{Q}} \underbrace{ \begin{pmatrix} \hat{\mathbf{y}}_{t-1} \\ \hat{\mathbf{y}}_{t-2} \\ \\ \hat{\mathbf{y}}_{t-\tau_{\max}} \end{pmatrix} }_{\equiv \mathbf{Y}_{t-1}} + \underbrace{ \begin{pmatrix} \hat{\mathbf{A}}_t \\ 0 \\ \vdots \\ 0 \end{pmatrix} }_{\equiv \mathbf{e}_t}$$

• VAR (1) representation:

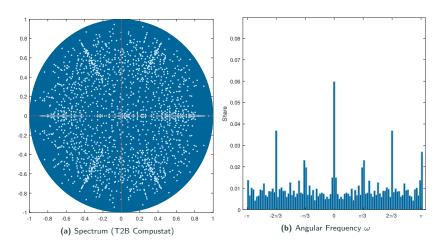
$$\mathbf{Y}_t = \mathbb{O}\mathbf{Y}_{t-1} + \mathbf{e}_t$$

- The system can oscillate if $\mathbb O$ has complex eigenvalues
 - Only true with time-to-build
 - ▶ In roundabout case, oscillations absent because collapsed within period

Spectrum



Frequencies with Heterogeneous T2B



- ⇒ Rich spectrum with peaks at periods of 2, 3 and 6 months
 - ▶ Period = $\frac{1}{f} = \frac{2\pi}{\omega}$

Oscillations and Network Cycles

- Oscillations are a consequence of cycles (loops) in the network
- A simple result:

Proposition

A vertical production network (i.e. acyclical) displays no oscillations.

Proof.

- \blacktriangleright There exists an ordering of sectors in which Ω is lower triangular with 0s on the diagonal
- ► All eigenvalues of ① are 0 (requires a few steps)
- ▶ Note: shocks vanish after a finite number of iterations (at most $N \times \tau_{max}$)
- Eigenvalues in the general case are too complicated
 - ► Algebraic graph theory: at most characterize 1st and 2nd largest eigenvalues...
 - ▶ ... but we can characterize the Fourier spectrum!

Refresher: Discrete-Time Fourier Transform (DTFT)

ullet Any discrete-time 0-mean stationary process x_t can be represented by

$$x_{t} = \int_{-\pi}^{\pi} \delta(\omega) e^{i\omega t} d\omega$$

where $E\left[\delta\left(\omega\right)\right]=0,\ E\left[\delta\left(\omega\right)\delta\left(\omega'\right)\right]=0$ for $\omega\neq\omega'$

• The Discrete Time Fourier Transform (DTFT) is

$$\delta(\omega) = \frac{1}{2\pi} \sum_{t=-\infty}^{\infty} x_t e^{-i\omega t}$$

• The spectral density is

$$f\left(\omega\right) \equiv E\left[\delta\left(\omega\right)\overline{\delta\left(\omega\right)}\right]$$

provides information about which frequencies ω are important for x_t .

DTFT and Autocorrelation Function

• Autocorrelation function (ACF)

$$\gamma_k = E\left[x_t x_{t-k}\right] \text{ for } k = -\infty, ..., \infty$$

• Key property: Fourier spectrum is the DTFT of the ACF

$$f(\omega) = \frac{1}{2\pi} \sum_{k=-\infty}^{\infty} \gamma_k e^{-i\omega k}$$

⇒ The ACF can be characterized analytically & using network topology

ACMF of a VAR(1)

• Recall the VAR(1) representation

$$\mathbf{Y}_t = \mathbb{O}\mathbf{Y}_{t-1} + \mathbf{e}_t$$

and $\Sigma = E[ee']$ and eiid

ullet The Autocovariance Matrix Function $oldsymbol{\Gamma}_k = E\left[oldsymbol{Y}_t oldsymbol{Y}_{t-k}'
ight]$ is

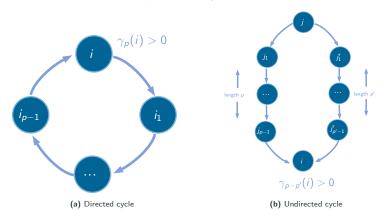
$$\Gamma_0 = \sum_{k=0}^{\infty} \mathbb{O}^k \mathbf{\Sigma} \left(\mathbb{O}' \right)^k$$

$$\Gamma_k = \mathbb{O}^k \Gamma_0$$

- ullet We can extract the relevant $\gamma_k\left(i
 ight)=E\left[\hat{y}_{it}\hat{y}_{it-k}
 ight]$ and construct spectrum
 - ▶ ... but provides little understanding

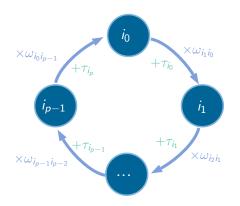
Sources of Serial Correlation

Serial correlation for sector *i* happens for only 2 reasons:



 \Rightarrow shocks echoe in the production network through cycles

Directed Cycles



$$p$$
-cycle $\varsigma = (i_0, i_1, ..., i_{p-1}, i_p = i_0)$

- Duration of cycle:
- Weight of cycle:

Cycles and Spectrum

Proposition

A p-cycle $\varsigma = (i_0, i_1, ..., i_{p-1}, i_p = i_0)$ contributes (at least) to the ACF

$$\gamma_{k\tau(\varsigma)}(i_0) = w(\varsigma)^k \sigma^2(\hat{y}_{i_0t})$$

for $k = 1, ..., \infty$ and to the Fourier spectrum

$$f_{i_0}\left(\omega\right) = \frac{\sigma^2\left(\hat{y}_{i_0t}\right)}{2\pi} \frac{1 - w\left(\varsigma\right)^2}{1 + w\left(\varsigma\right)^2 - 2w\left(\varsigma\right)\cos\left(\omega\tau\left(\varsigma\right)\right)}.$$

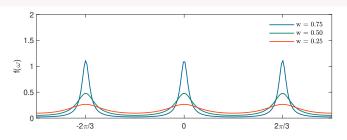


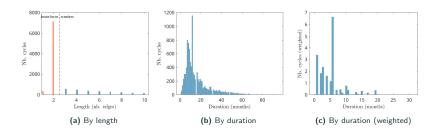
Figure 2: Spectrum of a cycle of duration au=3 for different weights



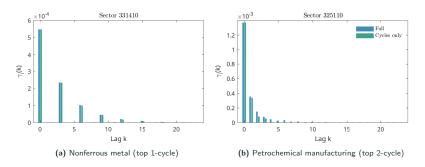
Identifying Cycles

- Finding cycles in a network is a highly combinatorial problem
 - ightharpoonup Cannot by brute force for length > 2-3
- We use a population of crawlers that travel the network randomly
 - ▶ Record cycles, their weights and durations whenever encountered
 - lacktriangle Not exhaustive, but cycles of length > 3 have low weights

Cycles (BEA I/O, Compustat)



ACF Full vs. Directed Cycles only



- Directed cycles account for virtually all the ACF
 - $R^2 = 0.9995$

Sectoral Comovements and Aggregation

Aggregation

- Oscillations survive aggregation
 - ► Large networks cycles appear in conditional GDP response
 - ▶ Depends how sectoral shocks spread to other sectors and involve other cycles/paths
- Real GDP $y_t = \sum \overline{p}_i \alpha_i y_{it}$ has ACF

$$E \left[\hat{y}_t \hat{y}_{t-k} \right] = E \left[\mu' \hat{\mathbf{y}}_t \hat{\mathbf{y}}'_{t-k} \mu \right]$$
$$= \mu' \Gamma_k \mu$$

where
$$\mu_i = \overline{p}_i \alpha_i \overline{y}_i / \sum_j \overline{p}_j \alpha_j \overline{y}_j$$

Spectrum of GDP

Proposition

The spectrum of real GDP is given by

$$f_{y}(\omega) = \sum_{i=1}^{N} \mu_{i}^{2} f_{i}(\omega) + \frac{1}{2\pi} \sum_{i \neq j} \sum_{k} \mu_{i} \mu_{j} \left[\mathbf{\Gamma}_{k} \right]_{ij} e^{-i\omega k}$$
sum of sectoral spectra

sectoral comovement term

- The spectrum of GDP is the sum of two terms:
 - ► Sum of individual sectoral spectra implied by dominant cycles
 - ► Sum of spectra implied by sectoral comovements due to dominant paths

Spectrum of GDP

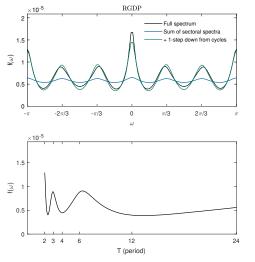


Figure 3: Spectrum of Real GDP

Dominant 2-cycles

- ▶ #298 Insurance carriers
- ▶ #225 Petroleum refineries
- ▶ #233 Organic chemical manuf.

Dominant 3-cycles

- ▶ #214 Leather and allied prod.
- ▶ #213 Apparel manuf.
- ▶ #43 Iron and steel mills

Dominant 6-cycles

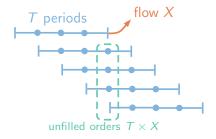
- ▶ #299 Insurance, brokerage
- ▶ #213 Hospitals
- ▶ #14 Oil and gas

Conclusion

- Heterogeneous T2B significantly affects the propagation of shocks in network
 - ► Adds substantial & heterogeneous persistence across sectors
 - ► Can study impact of delay shocks & bottlenecks in time
- The economy fluctuates at frequencies implied by dominant cycles
 - ► Rich Fourier spectrum for aggregate GDP
- Complex dynamic sectoral comovements
 - ▶ Role of dominant paths to be further explored
- Coming next:
 - ► Empirical evidence
 - ► Robustness to inventories & other modeling assumptions

Backlog Ratio

• In steady state, backlog $=\frac{T\times X}{X}=T$



◆ Back

Domar Weights and Hulten Theorem

A horizon-adjusted version of Hulten theorem applies:

$$\frac{\partial V}{\partial \log A_i} = \beta^{\tau_i} \zeta_i$$

- ▶ V is welfare, not real GDP
- $\triangleright \beta^{\tau_i}$ is time adjustment for delayed delivery
- ζ corresponds to the Domar weights: for $VA_t = \sum p_{it}c_{it}$,

$$\zeta_{i} = \frac{p_{it}X_{i0}(t)}{VA_{t}} = \frac{p_{it}y_{it-\tau_{i}}}{VA_{t}} = \frac{p_{it}\left(c_{it} + \sum_{j}X_{ji,t}\right)}{VA_{t}}$$
$$= \gamma_{i} + \sum_{j} \omega_{ji}\beta^{\tau_{j}}\zeta_{j}$$
$$\Rightarrow \boxed{\zeta = \left(I - \left[\Omega \cdot \beta^{\tau}\right]'\right)^{-1}\gamma}$$

▶ Back

Domar Weights

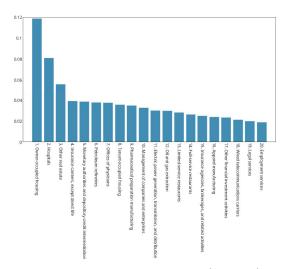
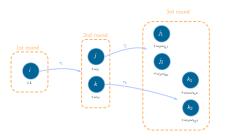


Figure 4: Top-20 sectors by Domar weight (Compustat)

Persistence Statistics

• Consider a shock to *i* at time *t*:



Define the average duration of a shock:

$$\mathcal{T}\left(\hat{\mathbf{A}}\right) = \frac{1}{CIR\left(\hat{\mathbf{A}}\right)} \sum_{\tau=0}^{\infty} \sum_{i} \tau w_{i} \hat{y}_{i\tau} \left(\hat{\mathbf{A}}\right)$$

where w_i a weighting vector and $\hat{y}_{i au}\left(\hat{\mathbf{A}}\right)$ the IRF to shock $\hat{\mathbf{A}}$ and

$$CIR\left(\hat{\mathbf{A}}\right) = \sum_{\tau=0}^{\infty} \sum_{i} w_{i} \hat{y}_{i\tau} \left(\hat{\mathbf{A}}\right)$$

◀ Back

Proposition

The average duration $\mathcal{T}\left(\hat{\mathbf{A}}\right)$ for weighting vector \mathbf{w} is equal to

$$\mathcal{T}\left(\hat{\mathbf{A}}\right) = \frac{1}{\textit{CIR}\left(\hat{\mathbf{A}}\right)} \mathbf{w}' \Omega \left[\mathbf{I} - \Omega\right]^{-1} \textit{diag}\left(\boldsymbol{\tau}\right) \left[\mathbf{I} - \Omega\right]^{-1} \hat{\mathbf{A}}$$

where $CIR(\hat{\mathbf{A}}) = \mathbf{w}'[\mathbf{I} - \mathbf{\Omega}]^{-1}\hat{\mathbf{A}}$.

Intuition: Consider single shock $\delta_i = \begin{pmatrix} 0 & \dots & 1 & \dots & 0 \end{pmatrix}'$ to sector i:

$$\mathcal{T}(\delta_i) = \frac{1}{CIR\left(\hat{\mathbf{A}}\right)} \mathbf{w}' \qquad \underbrace{\Omega}_{\text{duration } \tau \text{ only}}$$

contributes after 1 round

contribution of
$$\tau_j$$
 to later rounds of production

$$\left[\sum_{k=0}^{\infty} \Omega^{k}\right] \qquad \qquad \mathsf{diag}\left(\boldsymbol{\tau}\right) \qquad \left[\sum_{k=0}^{\infty} \Omega^{k}\right] \boldsymbol{\delta}_{\mathbf{i}}$$

of walks from sector i to other sectori of any length

The rest follows by linearity to any shock A.



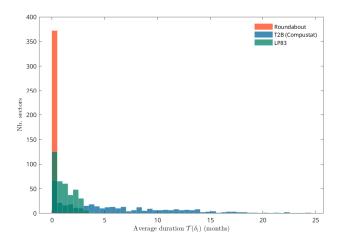


Figure 5: Comparison of average durations of iid sectoral shocks



Delay Shocks

• Consider a *T*-period delay shock in sector *i*

$$\hat{X}_{i au} = -arepsilon ext{ for } au = 0,...,T-1$$
 $\hat{X}_{i au} = +arepsilon ext{ for } au = T,...,2T-1$

- Plot the response of aggregate real GDP $y_t = \sum \overline{p}_i \alpha_i y_{it}$
 - ▶ -1% of deliveries for 1 and 3 months



Delay Shocks IRFs

Figure 6: Nonferrous metal smelting and refining (bottleneck #2, $\tau=3$ months)

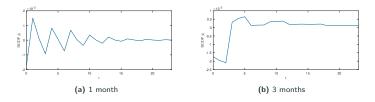
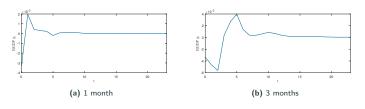


Figure 7: Plastics material and resin manuf. (bottleneck #3, au=5 months)





Bottlenecks

Which sector's T2B contributes the most to the persistence of shocks?

$$\frac{\partial \mathcal{T}\left(\hat{\mathbf{A}}\right)}{\partial \tau_{i}} = \frac{1}{\textit{CIR}\left(\hat{\mathbf{A}}\right)} \mathbf{w}' \Omega \left[\mathbf{I} - \Omega\right]^{-1} \frac{\partial \mathsf{diag}\left(\boldsymbol{\tau}\right)}{\partial \tau_{i}} \left[\mathbf{I} - \Omega\right]^{-1} \hat{\mathbf{A}}$$

Bottlenecks

Which sector's T2B contributes the most to the persistence of shocks?

$$\frac{\partial \mathcal{T}\left(\hat{\mathbf{A}}\right)}{\partial \tau_{i}} = \frac{1}{\textit{CIR}\left(\hat{\mathbf{A}}\right)} \mathbf{w}' \Omega \left[\mathbf{I} - \Omega\right]^{-1} \frac{\partial \mathsf{diag}\left(\boldsymbol{\tau}\right)}{\partial \tau_{i}} \left[\mathbf{I} - \Omega\right]^{-1} \hat{\mathbf{A}}$$

Proposition

The marginal impact of a delay $\partial \tau_n$ on the persistence of shock $\hat{\mathbf{A}}$ is given by

$$\frac{\partial \mathcal{T}\left(\hat{\mathbf{A}}\right)}{\partial \tau_{i}} = \frac{1}{CIR\left(\hat{\mathbf{A}}\right)} s_{i} \times b_{i}$$

where

$$s_i = \mathbf{w}' \Omega \left[\mathbf{I} - \Omega \right]^{-1} \delta_i = \sum_j \mathbf{w}' \Omega \left[\sum_{k=0}^{\infty} \Omega^k \right]_{ji}$$
 (supplier centrality)

of walks from i to all sectors of any length (weighted by $\Omega'w$)

$$b_i = \hat{\mathsf{A}}' \left(\mathsf{I} - \Omega' \right)^{-1} \delta_i = \qquad \hat{\mathsf{A}}' \sum_j \left[\sum_{k=0}^\infty (\Omega')^k \right]_{ij}$$
 (buyer centrality)

of walks from all sectors j hit by $\hat{\mathbf{A}}$ to i of any length

Bottlenecks

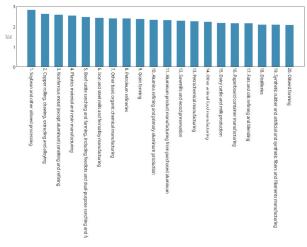
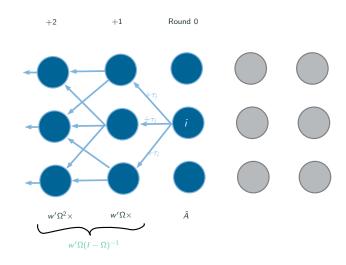
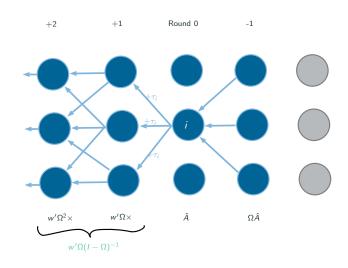
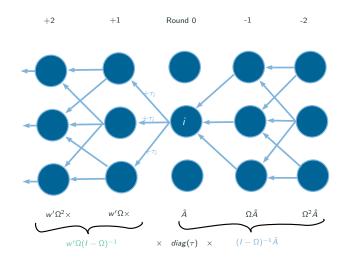


Figure 8: Top-20 bottleneck sectors









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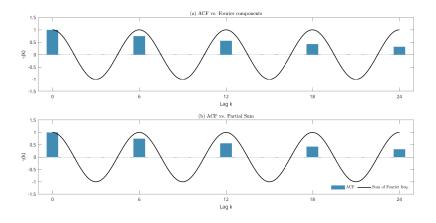


Figure: Fourier decomposition of ACF for $\tau=6$ and w=0.75

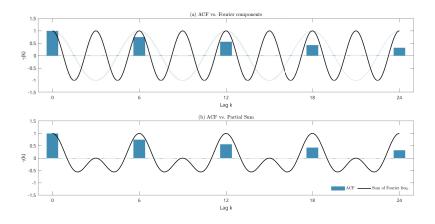


Figure: Fourier decomposition of ACF for $\tau=6$ and w=0.75

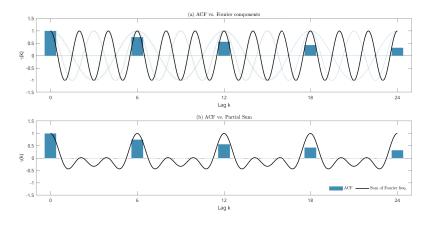


Figure: Fourier decomposition of ACF for $\tau=6$ and w=0.75

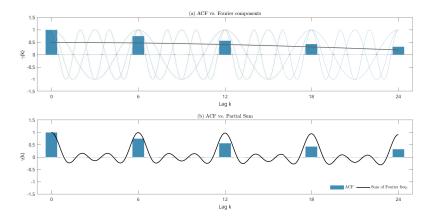


Figure: Fourier decomposition of ACF for $\tau=6$ and w=0.75

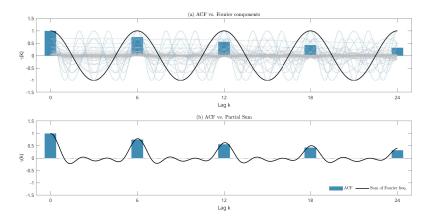


Figure: Fourier decomposition of ACF for $\tau = 6$ and w = 0.75



Poisson Model

- A common trick to model delays is to assume Poisson arrival:
 - For delivery lag τ , assume delivery with probability $1/\tau$ each period
- Example: suppose i_0 has a self-loop of weight w

$$\gamma_k\left(i_0
ight) = w\left(1 - rac{1}{ au}
ight)^{k-1}rac{1}{ au}\,\sigma^2\left(\hat{y}_{i_0t}
ight) + ext{further iterations}$$

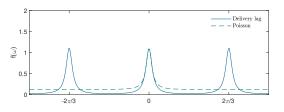


Figure 9: Spectrum of a Poisson model vs. delivery lag for $\tau=3$

⇒ Poisson arrival heavily distorts the spectrum

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