Code Mobility

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December 4, 2012



Outline

- Introduction
 - Code mobility overview
 - Level of abstraction
 - Requirements
- System architecture
 - General overview
 - Agents
 - Platform
 - Scheduler
 - Execution Layer
 - Communication Protocol
- Project management
- Tools



Code mobility overview

Concept of code mobility

Our goal:

- Design code mobility system on ESE Board
- Hardware drivers & mobile agents & communication
- Master project management skills

Concept of code mobility

Mobile agent

Strong and weak code mobility

Layered architecture

Advantages of code mobility

Move code close to resources

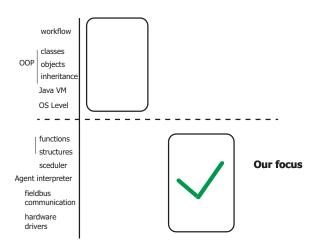
Enable client customization of remote resources

Performance gains

Jakovliević.Selvunin.Pelesić

Code Mobility

Level of abstraction



Requirements

- Agents:
 - simple language
 - support mobility and message exchange
- Platform:
 - execute agents concurrently
 - provide hardware services to agents
- Communication:
 - transfer agents & state strong mobility
 - transfer messages between platforms
 - cross board communication via Zigbee

General overview

3 layered architecture:

- Agent level
- Platform level
- communication & drivers

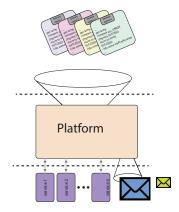
Mobile Agents Platform Hardware services & communication



General overview

3 layered architecture:

- Agent level
- Platform level
- communication & drivers



Mobile agent 1

...

MEASURE: get temp compare acc, ERROR jmpneq SUCCEED move to temp jmp MEASURE: SUCCEED: //do some staff with temp Get temperature value

Platform can provide this service?

yes: do staff

Mobile agent 1

MEASURE: get temp compare acc, ERROR impneg SUCCEED move to temp imp MEASURE:

SUCCEED: //do some staff with temp

Get temperature value

Platform can provide this service?

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Mobile agent 1

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Get temperature value

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Mobile agent 1

MEASURE: get temp compare acc, ERROR jmpneq SUCCEED move to temp jmp MEASURE SUCCEED:

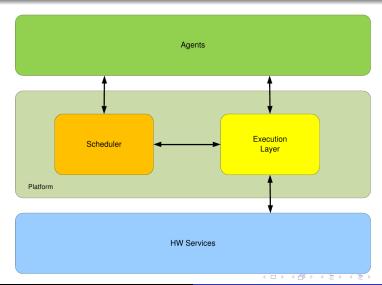
//do some staff with temp

Get temperature value

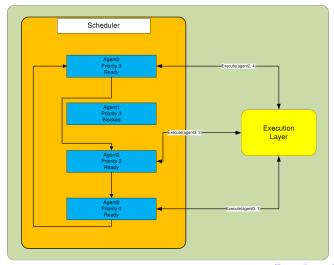
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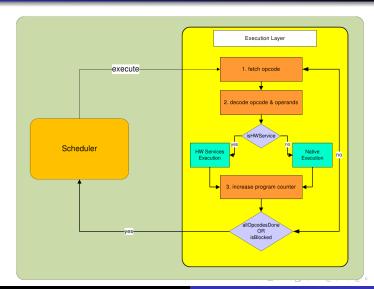
Platform



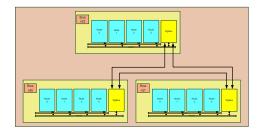
Scheduler



Execution Layer



Communication Requirements



- Inter-node and Inter-board communication
- Correct sending of large amounts of agent code
- Timely delivery of control messages
- Bridging between local and wireless network

Transmission Layers

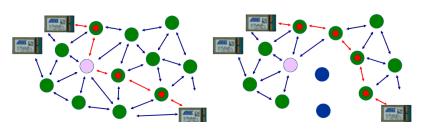
Byte	MSB	LSB		
0	destination node	payload length		
1	data			
14	data			
15	crc			

Byte	MSB	LSB			
0	destination node	payload length			
1[source node	destination board			
2[source board	packet type			
3[frame id				
4[packet id high				
5[packet id low				
6	empty				
7[data				
ı[***				
14	data				
15	crc				

Figure: Lower-and Upper Level Datagram

- Lower level: priority based CSMA/CA protocol
- Upper level: routing and frame composition
- Network bridge: Zigbee access on application layer

Network Topology Fault Tolerant Routing



- Zigbee Network Coordinator
- Zigbee Network Router
- Disabled Node



Milestones



Phase 1. Product outline and information gathering



Phase 2. Application requirements and specification



Phase 3. Implementation

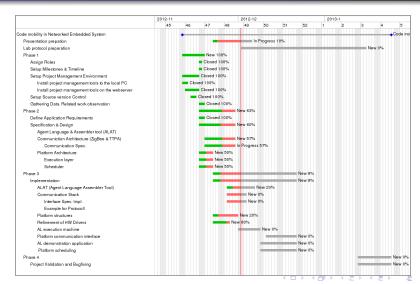


Phase 4. Validation and analysis

Workpackages

	Name	Dates	Interdependencies	Deliverables
WP1	Documentation	all	25.10.12 - 15.01.13	D1.1 Lab protocol
				D1.2 specification
				D1.3 workshop1
				D1.4 workshop2
WP2	Adaption of drivers		10.12 - 15.12	D2.1 hardware drivers
WP2	Agent language tool		6.12 - 10.12	D2.1 Agent language assembler tool
WP4	Communication	D2.1		Protocol
WP5	Platform	WP2, WP4	10.12 - 21.12	D3.1 Platform

Gantt diagram



Tools

Version control

Documentation & code repository

File sharing

Project management

Code generation

Editors



git



github



amazon s3



redmine

http://nes2012group4.herokuapp.com/



SCADE



Emacs

gedit

