

Code Mobility

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Outline

- 1 Introduction
 - Code mobility overview
 - Level of abstraction
 - Requirements
- 2 System architecture
 - General overview
 - Agents
 - Platform
 - Scheduler
 - Execution Layer
 - Communication Protocol
- 3 Project management
- 4 Tools

Code mobility overview

Concept of code mobility

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Mobile agent

Strong and *weak* code mobility

Layered architecture

Advantages of code mobility

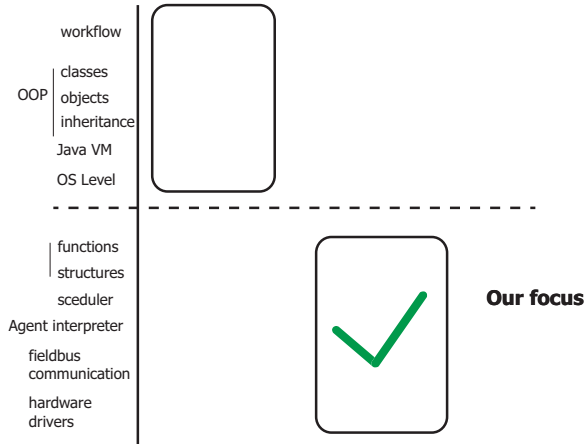
Move code close to resources

Enable client customization of remote resources

Performance gains

[FPV98, BCMV06]

Level of abstraction



Requirements

- Agents:
 - simple language
 - support mobility and message exchange
- Platform:
 - execute agents concurrently
 - provide hardware services to agents
- Communication:
 - transfer agents & state *strong mobility*
 - transfer messages between platforms
 - cross board communication via Zigbee

General overview

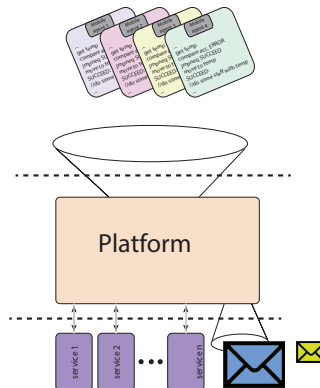
3 layered architecture:

- Agent level
- Platform level
- communication & drivers

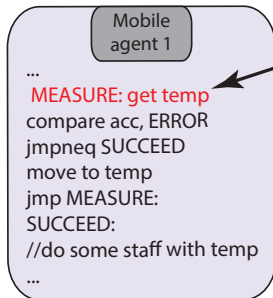
General overview

3 layered architecture:

- Agent level
- Platform level
- communication & drivers



Agents



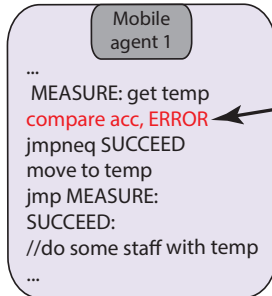
Get temperature value

Platform can provide this service?

yes: do stuff

no: move agent to another platform

Agents



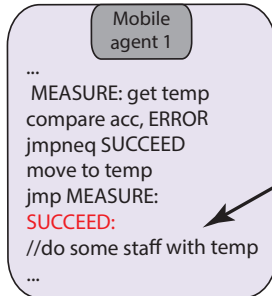
Get temperature value

Platform can provide this service?

yes: do staff

no: move agent to another platform

Agents



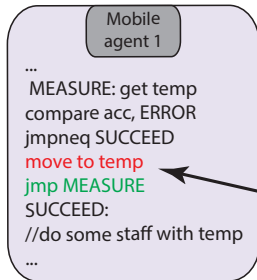
Get temperature value

Platform can provide this service?

yes: do staff

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Agents

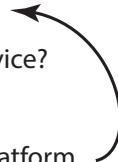


Get temperature value

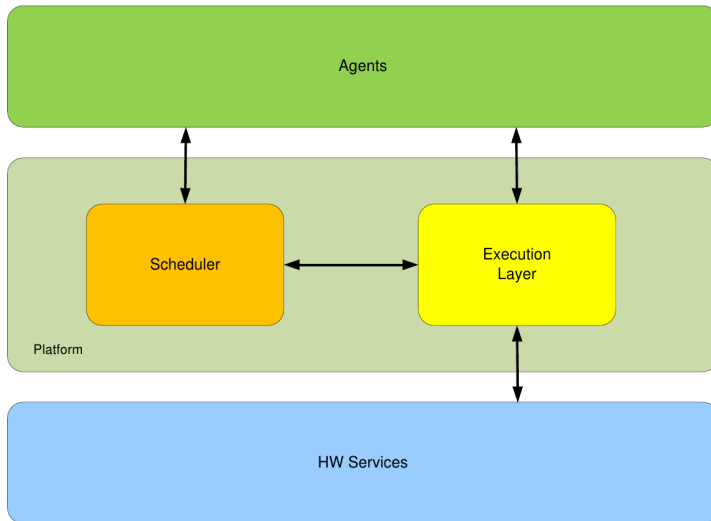
Platform can provide this service?

yes: do staff

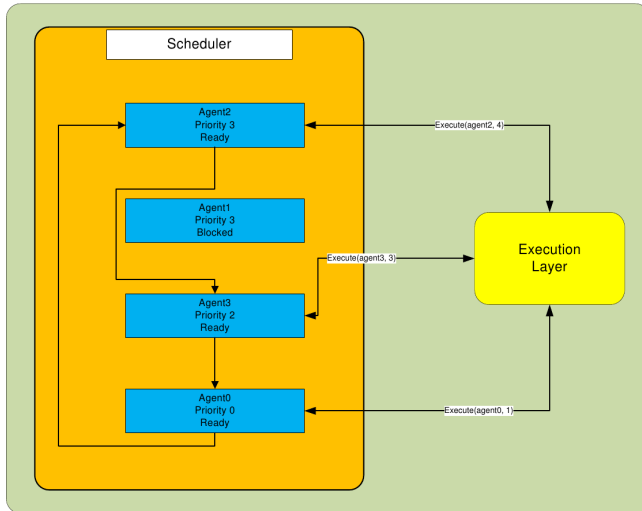
no: move agent to another platform



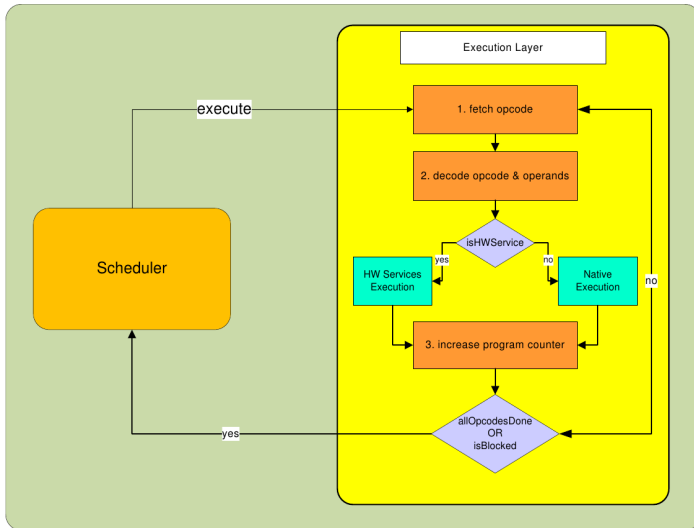
Platform



Scheduler

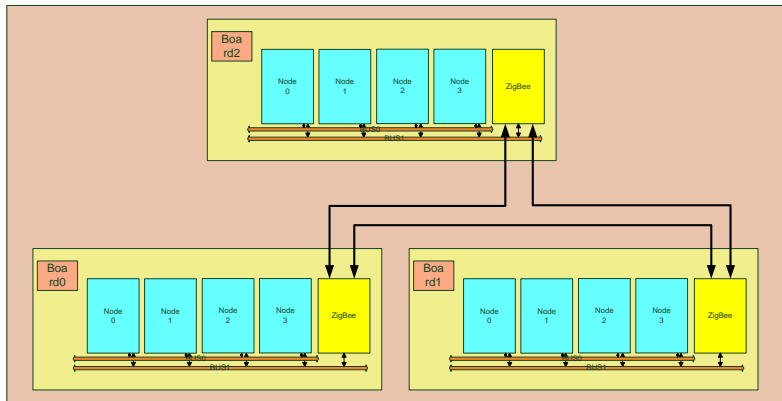


Execution Layer



Communication Protocol

Communication Participants



Protocol Design

Requirements

- Local *on-board* communication
- Remote communication
- Sending agent code
- Sending application data

Principles

- Layered design
- Fairness* in network access
- Composability with *Zigbee*
- Acknowledgement and retry

Transmission Layers

Byte	MSB	LSB
0	<i>destination node</i>	<i>payload length</i>
1	<i>data</i>	
1	...	
14	<i>data</i>	
15	<i>crc</i>	

Figure : Low Level Datagram

Byte	MSB	LSB
0	<i>destination node</i>	<i>payload length</i>
1	<i>source node</i>	<i>destination board</i>
2	<i>source board</i>	<i>packet type</i>
3	<i>frame id</i>	
4	<i>packet id high</i>	
5	<i>packet id low</i>	
6	<i>empty</i>	
7	<i>data</i>	
1	...	
14	<i>data</i>	
15	<i>crc</i>	

Figure : High Level Datagram

Network Configuration

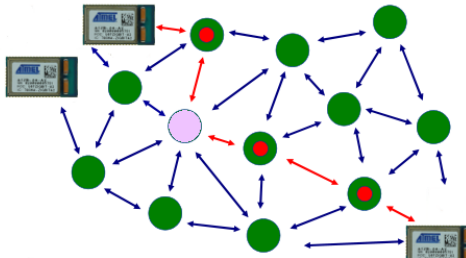


Figure : Zigbee Mesh Network

Zigbee Network Configuration

Rerouting Example

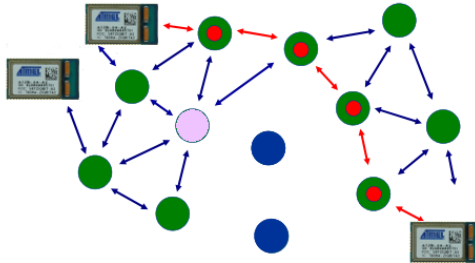


Figure : Network after rerouting

- Network Coordinator
- Failed Node
- Network Router
- Message Route

Milestones



Phase 1. Product outline and information gathering



Phase 2. Application requirements and specification



Phase 3. Implementation

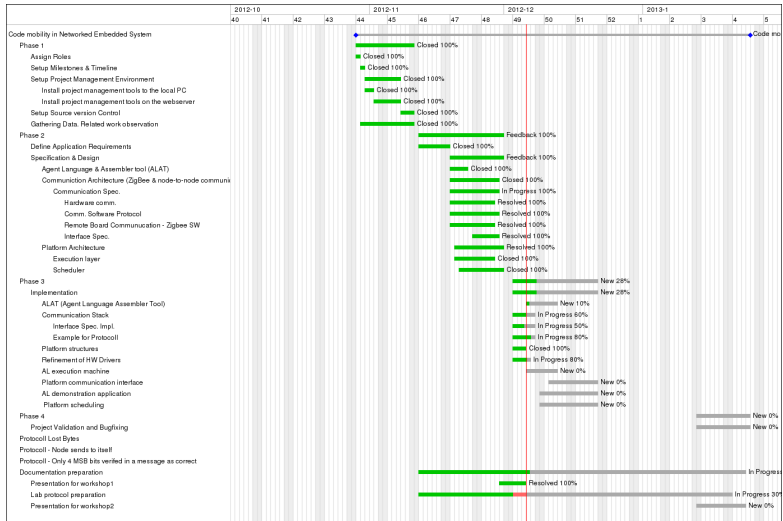


Phase 4. Validation and analysis

Workpackages

	Name	Dates	Interdependencies	Deliverables
WP1	Documentation	all	25.10.12 - 15.01.13	D1.1 Lab protocol
				D1.2 specification
				D1.3 workshop1
				D1.4 workshop2
WP2	Adaption of drivers		10.12 - 15.12	D2.1 hardware drivers
WP2	Agent language tool		6.12 - 10.12	D2.1 Agent language assembler tool
WP4	Communication	D2.1		Protocol
WP5	Platform	WP2, WP4	10.12 - 21.12	D3.1 Platform

Gantt diagram



Tools

Version control



git

Documentation & code repository



github

File sharing



amazon s3

Project management



redmine

<http://nes2012group4.herokuapp.com/>

Code generation



SCADE

Editors



Emacs

gedit

References



Ezio Bartocci, Flavio Corradini, Emanuela Merelli, and Leonardo Vito.

Model driven design and implementation of activity-based applications in hermes.

Proceedings of the 7th WOA 2006 Workshop, From Objects to Agents (Dagli Oggetti Agli Agenti), Catania, Italy, September 26-27, 2006, 2006.



Alfonso Fuggetta, Gian Pietro Picco, and Giovanni Vigna.

Understanding code mobility.

IEEE Transactions on Software Engineering, 24:342–361, 1998.

Questions

Roles

Konstantin Selyunin

Project manager

internal coordination

defining tasks

control meeting deadlines

Igor Pelesić

System architect

technical decisions

determine technical part of the project

Miljenko Jakovljević

Documentation responsible

Lab protocol

documentation decisions

Goals

Our goals:

- Design, implement and evaluate code mobility system on ESE Board
- Hardware drivers & mobile agents & communication
- Master project management skills

Use cases

Risk management

High-level agent language