

## Lecture 6 - 23

- Differential Equations  $\frac{dy}{dt} = Ay$

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- Exponential  $e^{At}$  of a matrix.

example 8  $\frac{du_1}{dt} = -u_1 + 2u_2$ ;  $\frac{du_2}{dt} = u_1 - 2u_2$

$$\rightarrow A = \begin{bmatrix} -1 & 2 \\ 1 & -2 \end{bmatrix}$$

$$u(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

suppose at time '0' everything is in  $u_1$

$$\Rightarrow A = \begin{bmatrix} -1 & 2 \\ 1 & -2 \end{bmatrix}; \text{ eigenvalues} = \{$$

$\hookrightarrow \therefore$  it's a singular matrix.  $\begin{pmatrix} 2^{\text{nd}} \text{ column is } (-2) \text{ times } \begin{pmatrix} 1^{\text{st}} \text{ column} \end{pmatrix} \end{pmatrix}$   
so one of the eigenvalue is  $\lambda = 0$

$\hookrightarrow$  from trace: other eigen value  $\therefore \lambda = -3$ ;

$$\Rightarrow |A - \lambda I| = \begin{vmatrix} -1-\lambda & 2 \\ 1 & -2-\lambda \end{vmatrix}$$

$$= -\lambda^2 + 3\lambda = 0$$

$$\lambda(\lambda + 3)$$

$$A = \begin{bmatrix} -1 & 2 \\ 1 & -2 \end{bmatrix}$$

eigen vector  $\therefore \lambda_1 = 0$ ;  $\lambda_2 = -3$

$$Ax_1 = 0x_1$$

$$x_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$x_2 =$  subtract ~~add~~ through the diagonal.

$$x_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix} \checkmark$$

$$A = \begin{bmatrix} 2 & 2 \\ 1 & 1 \end{bmatrix}$$

$(A + 3I) \rightarrow$  should be singular

$$(A - \lambda_k I) = 0$$

$$Ax_2 = -3x_2$$



Solution

sol<sup>n</sup> to diff. eq<sup>n</sup>

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$$u(t) = c_1 e^{\lambda_1 t} x_1 + c_2 e^{\lambda_2 t} x_2$$

two eigen value ; Hence two special sol<sup>n</sup>  
= Two pure exponential sol<sup>n</sup>

Check  $\frac{dy}{dt} = Ay$  ; Plug in  $e^{\lambda_1 t} x_1$

$$\lambda_1 e^{\lambda_1 t} x_1 = A e^{\lambda_1 t} x_1$$

$$= c_1 \cdot 1 \cdot \begin{bmatrix} 2 \\ 1 \end{bmatrix} + c_2 e^{-3t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

So how do we get  $c_1$  &  $c_2$ ?

$$\hookrightarrow u(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$Sc = u(0)$$

At  $t=0$ ;

$$\Rightarrow c_1 \begin{bmatrix} 2 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

Solution:  $c_1 = 1/3$  ;  $c_2 = 1/3$

$$\Rightarrow \frac{1}{3} \begin{bmatrix} 2 \\ 1 \end{bmatrix} + \frac{1}{3} e^{-3t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

steady state

if  $t$  goes to  $\infty$   
disappears

$$u(\infty) = \frac{1}{3} \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$



① So; when do we get stability?

$$u(t) \rightarrow 0$$

→ negative eigenvalues

suppose eigenvalues are complex numbers;

we need all these  $e^{\lambda t} \rightarrow 0$  & that asks us

to have lambda negative. ( $\lambda < 0$ );

suppose  $\lambda$  is complex number; then what's the test?

ex:  $\left| e^{(-3+bi)t} \right| \xrightarrow{\text{how big is it?}} = e^{-3t}$

because  $|e^{6it}| = 1$

then real part of  $\lambda$  has to be negative.

② Steady State: always in the same direction?

(when  $\lambda = 0$  & other eigenvalue = real part negative.)

③ Blow up: if any Real part of  $\lambda > 0$ ;

④ Suppose I change all the sign of matrix A what it will do to eigen values & vectors?   
 → change signs

⑤ 2x2 stability: looking for  $\text{Re } \lambda_1 < 0, \text{Re } \lambda_2 < 0$ ;

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

trace  $(a+d = \lambda_1 + \lambda_2 < 0)$  is it enough?   
 How can I tell by looking at matrix?   
 → to make stable

cond (I)



# so now i looking for an example where trace is negative; but still it will blow up. ?

ex:  $\begin{bmatrix} -2 & 0 \\ 0 & 1 \end{bmatrix}$

$\lambda_1 = 1, \lambda_2 = -2$

so  $e^{+t}$  & it will blow up if it has any second component at all.

# I need another condition

$\boxed{\det > 0}$  — cond-②  
↓  
( $\lambda_1 \lambda_2$ )

#  $\frac{du}{dt} = Au$  — coupled matrix. Set  $u = Sv$   
↓  
diagonalizing — decoupling — vector matrix

$S \frac{dv}{dt} = ASv$

$\frac{dv}{dt} = S^{-1}ASv$   
↓  
diagonal matrix ( $\Lambda$ )

$\boxed{\frac{dv}{dt} = \Lambda v}$

so if I'm using the eigen vectors as my basis, then my system of equations is just diagonal.

→ there's no coupling anymore

$\frac{dv_1}{dt} = \lambda_1 v_1$   
⋮  
} system of eqn but not connected

so they are easy to solve

→ solution  $v_1 = c_1 e^{\lambda_1 t}$

$\boxed{v(t) = e^{\Lambda t} v(0)}$



$$\underline{u(t) = S e^{At} S^{-1} u(0)}$$

$$= e^{At} u(0)$$

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$$e^{At} = S e^{\Lambda t} S^{-1}$$

what it mean?

exponential of a matrix ; why the formula correct?

## # Matrix exponential

converged by diry (n!)

$$e^{At} = I + At + \frac{(At)^2}{2} + \frac{(At)^3}{6} + \dots + \frac{(At)^n}{n!} + \dots$$

similar thing will be here :

$$(I - At)^{-1} = I + At + (At)^2 + (At)^3 + \dots$$

if + is small then  $(I + At)$

$$| \lambda(At) | < 1$$

eigenvalue < 1

Taylor series

$$e^x = \sum_{n=0}^{\infty} \frac{x^n}{n!}$$

another one

$$\frac{1}{1-x} = \sum_{n=0}^{\infty} x^n$$

geometric series

$$= I + S \Lambda S^{-1} t + \frac{S \Lambda^2 S^{-1} t^2}{2} + \dots$$

$$e^{A t} = S e^{\Lambda t} S^{-1}$$

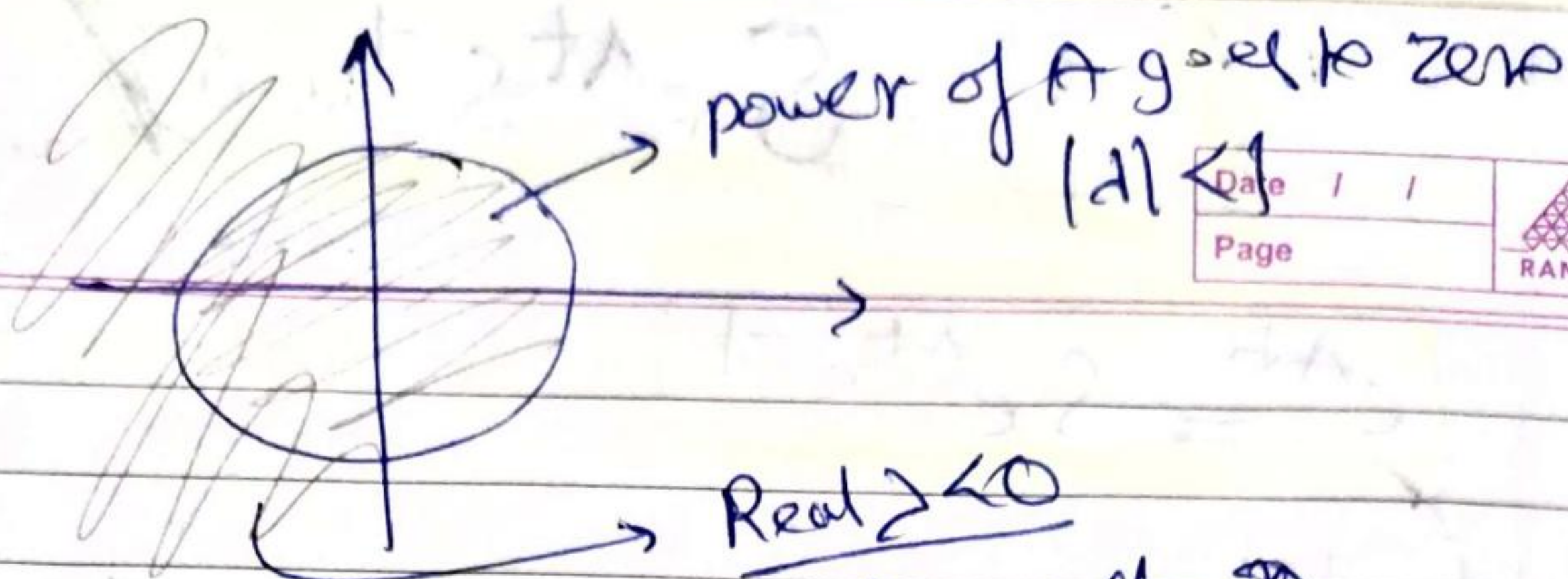
$$\Lambda t + \frac{\Lambda^2 t^2}{2} + \dots$$

Here, assumption are :- A can be diagonalized

$$e^{\Lambda t} = \begin{bmatrix} e^{\lambda_1 t} & & 0 \\ & \ddots & \\ 0 & & e^{\lambda_n t} \end{bmatrix}$$



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#

$$y'' + by' + ky = 0 \quad (1 \text{ eq}^n, 2^{\text{nd}} \text{ order})$$

$$u = \begin{bmatrix} y' \\ y \end{bmatrix} \rightarrow \text{vector unknown} \quad \rightarrow (2 \times 2) \text{ 1st order}$$

$$u' = \begin{bmatrix} y'' \\ y' \end{bmatrix} = \begin{bmatrix} -b & -k \\ 1 & 0 \end{bmatrix} \begin{bmatrix} y' \\ y \end{bmatrix} \quad (\text{just I did in fibonacci.})$$

for 5th order

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ & 1 & 1 & 1 & 1 \\ & & 1 & 1 & 1 \\ & & & 1 & 1 \\ & & & & 1 \end{bmatrix}$$

Problem & App: Higher order linear diff eq<sup>n</sup>

$$\text{eq}^n: - (y''' + 2y'' - y' - 2y = 0)$$

for the general solution. What is the matrix A?

find the first column of  $\exp(At)$  -

$$y''' = -2y'' + y' + 2y$$

Sol:

$$u'(t) = \begin{bmatrix} y''' \\ y'' \\ y' \end{bmatrix} = \begin{bmatrix} -2 & 1 & 2 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} y'' \\ y' \\ y \end{bmatrix} = A \cdot u(t)$$

transformed in 1st order of  $u(t)$   
 diff eq<sup>n</sup>



Although  $u(t)$  is vector, but if we can solve this equation for  $u$ , we have all the info we need for  $y$ .

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$$u'(t) = A u(t) \quad \text{Solve this eqn}$$

→ we need  $\lambda$ 's of  $A$

$$\det(A - \lambda I) = \det \begin{pmatrix} -2-\lambda & 1 & 2 \\ 1 & -\lambda & 0 \\ 0 & 1 & -\lambda \end{pmatrix}$$

$$= (1-\lambda)(1+\lambda)(2+\lambda)$$

three roots

$$\lambda_1 = 1; \lambda_2 = -1, \lambda_3 = -2;$$

↓  
 $x_1$

$$(A - I) \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} -3 & 1 & 2 \\ 0 & -1 & 0 \\ 0 & 1 & -1 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 0$$

$$a = b = c$$

$$x_1 = (1, 1, 1)^T$$

↓  
 $x_2$

$$x_2 = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$$

$$x_3 = \begin{pmatrix} 4 \\ -2 \\ 1 \end{pmatrix}$$

→ general sol<sup>n</sup> for  $u(t)$ :

$$u(t) = c_1 e^t x_1 + c_2 e^{-t} x_2 + c_3 e^{-2t} x_3$$

$y$  :- last item in  $x_1, x_2, x_3 = 1$  so

$$y(t) = c_1 e^t + c_2 e^{-t} + c_3 e^{-2t}$$



$$\exp(At) = S e^{\Lambda t} S^{-1}$$

$$S = \begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 4 \\ 1 & -1 & -2 \\ 1 & 1 & 1 \end{bmatrix}$$

$$e^{\Lambda t} = \begin{bmatrix} e^t & 0 & 0 \\ 0 & e^{-t} & 0 \\ 0 & 0 & e^{-2t} \end{bmatrix}$$

we want first column of result

$$\exp(At) = S e^{\Lambda t} S^{-1}$$

multiplying columns of  $S$  by diagonal of  $e^{\Lambda t}$

$$= \begin{bmatrix} e^t x_1 & e^{-t} x_2 & e^{-2t} x_3 \end{bmatrix} \begin{bmatrix} 1/6 & - & - \\ -1/2 & - & - \\ 1/2 & - & - \end{bmatrix}$$

inverse

⊕ first column of  $S^{-1} = \{$

$$= \frac{1}{\det(S)} C^T = \frac{1}{6} \begin{bmatrix} 1 & - & - \\ -3 & - & - \\ 2 & - & - \end{bmatrix}$$

$\swarrow$  cofactor of  $S_{11}$   $S_{12}$   
 $\uparrow$   $S_{13}$

$$\exp(At) = \begin{bmatrix} \frac{e^t}{6} x_1 - \frac{e^{-t}}{2} x_2 + \frac{e^{-2t}}{3} x_3 \\ \dots \end{bmatrix}$$