Phenotiki – How to setup the Phenotiki device

Author: Massimo Minervini* Software version: 1.1

June 6, 2016

Abstract

This document provides detailed instructions to setup and operate the Phenotiki device for affordable plant phenotyping. First, we provide a general overview of the RaspiCam image sensor and the web-based interface to operate the device using a browser. Next, we describe how to setup the device.

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^{*} E-mail: massimo.minervini@imtlucca.it
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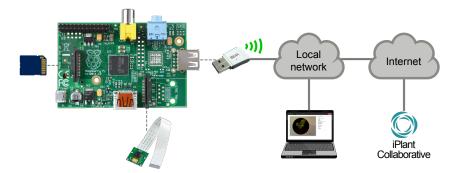


Figure 1: Schematic of our imaging solution based on the Raspberry Pi, showing the headless mode for image acquisition and transmission.

1 A smart sensing device based on the Raspberry Pi

The Raspberry Pi [1,2] is a credit-card sized single-board computer, designed and developed by the Raspberry Pi Foundation, ¹ UK, as an educational tool for teaching computer science and programming [3,4]. The Raspberry Pi is cheap (monetary cost is €40) and easy to use (it runs the Raspbian, a full-featured Linux operating system), therefore it is ideal to implement affordable systems.

As illustrated in Figure 1, we use a Raspberry Pi (Model B) single-board computer, shorthanded as RPi, equipped with a 5 megapixel 'RaspiCam' camera module, to capture static images (width×height: 2592×1944 pixels) of the scene. This solution offers great flexibility by having a complete yet small computer attached to the sensor. While the RaspiCam is capable of acquiring images of good quality that can satisfy a wide range of applications (the infrared camera module 'NoIR' is also available), in contexts where superior image quality is required, the Raspberry Pi can be used in combination with an SLR camera or other imaging sensors.

To control the camera and acquire images we adopt the *raspistill* application. The images acquired by the RPi setup are also automatically transmitted to the cloud for storage and analysis. Here we rely on the scientific cloud infrastructure offered by the iPlant Collaborative project [5], to deploy our plant image analysis software solution.

In a distributed sensing and analysis scenario, in which the acquired data needs to be transmitted via the Internet to centralized locations (e.g., a cloud service) for analysis, it becomes necessary to compress the images effectively [6]. In this context, a single-board computer such as the Raspberry Pi operating the sensor offers the possibility to: (a) perform (low-complexity) pre-processing operations on the acquired imagery (e.g., image enhancement, specialized compression, low level vision); and (b) autonomously transmit the images to a remote location.

To ease configuration and monitoring, we deploy a web-based interface to operate the sensor remotely (cf. Figure 1). In the following, we describe how to set up the hardware and software components of our affordable sensing solution based on the Raspberry Pi.

¹ http://www.raspberrypi.org



Figure 2: Screen captures of our web-based interface to operate the Raspberry Pi camera, based on the raspistillWeb project.

1.1 RaspiCam

The "RaspiCam" camera module is a fixed-focus 5 megapixel CMOS image sensor produced by OmniVision Technologies.²

raspistill:

Two command line utilities are available on the Raspberry Pi to operate the camera: raspistill, to capture still photos, and raspivid, to record HD video. For example, to acquire a picture and save it in the PNG format [7] we use the following command line options:

```
raspistill -n -e png -awb fluorescent -rot 180 -o filename
```

Notice that the camera module must be enabled in the Raspbian configuration (see Section 2.2).

The raspistill utility is easy to use and offers several options to configure image acquisition [8]. In particular, in our experimental setup we use neon lights for illumination, therefore we specify the option *fluorescent* to the automatic white balance algorithm embedded in raspistill.

Using a job scheduler (e.g., the Cron software utility), it is possible to run the raspistill periodically, to acquire a time-lapse sequence of images. However, any changes to the mode of operation require that the Raspberry Pi be connected to all input/output peripherals to provide the user with physical access. This procedure involves attaching and detaching cables, which may cause undesired displacements of the sensing device or the plants. Furthermore, in some scenarios, physical access to the device may not be possible or desirable after the initial setup, thus introducing the need for a solution that enables remote control.

1.2 Easy device configuration via web interface

After initial setup, the Phenotiki device offers a web-based interface for easy configuration and operation from another computer (e. g., a laptop or even a smartphone, cf. Figure 2).

We implement our interface as a fork of the *raspistillWeb*³ project (version 0.1), i.e. a web interface for the raspistill tool, implemented

 $^{^{2}\,\}text{http://www.ovt.com}$

³ https://github.com/TimJuni/raspistillWeb

using the Python programming language and the Pyramid⁴ web framework. We adapt the original software platform to the requirements of our application, adding the following key features:

- (a) the user can select among different image file formats, including lossy (JPEG [9], GIF [10]) and lossless (BMP [11], PNG [7]) encoding standards;
- (b) the user can start and interrupt time-lapse image acquisitions;
- (c) more detailed information and metadata are displayed about acquired images; and
- (d) acquired images can be transmitted to the iPlant Collaborative [5] cloud infrastructure for storage and analysis.

As shown in Figure 2, graphical control elements of the user interface are intuitive and self-explanatory, thus rendering the web application easy-to-use. The 'Settings' page allows to configure parameters regarding image acquisition, time-lapse photography, and transmission to the iPlant. 'Home' and 'Time Lapse' pages allow to capture single still images and initiate a time-lapse acquisition, respectively. Detailed information about acquired images is displayed in 'Home' and 'Archive' pages. In the 'Archive' page the user can browse previously acquired images and download time-lapse sequences as compressed archives. Our interface also adapts to small screens and can be displayed on mobile devices such as smartphones and tablets (cf. Figure 2).

Acquired images are transmitted to the iPlant using the Bisque Python APIs and the user's credentials (username and password) for iPlant. The user can also decide to delete the local copy of the image files after their transmission, to save storage space on the Raspberry Pi.

2 Setting up the Phenotiki device and software

2.1 Hardware requirements

To replicate the Phenotiki device you will need the following hardware equipment:

- Raspberry Pi version 1 model B (or higher);
- "RaspiCam" camera module;
- USB micro power supply (recent versions of the Raspberry Pi necessitate a specialized power supply);
- 8 GB (or larger) Secure Digital (SD) memory card;
- HDMI monitor and cable;
- USB keyboard and mouse;
- USB wireless dongle (not necessary for recent versions of the Raspberry Pi);
- self-powered USB hub (not necessary for recent versions of the Raspberry Pi).

This equipment can be easily purchased from one of the several distributors selling worldwide.

Setting up the Raspberry Pi requires only few simple steps, described in detail in the official documentation [8].⁵ In order to install the necessary software and perform initial configurations, the device must be attached

⁴ http://www.pylonsproject.org

⁵ http://www.raspberrypi.org/documentation/setup/

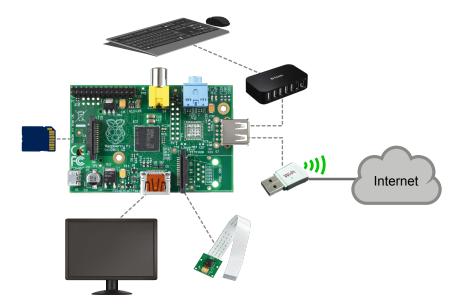


Figure 3: Schematic of our sensing solution at first configuration time, showing system setup and configuration. Note that after the initial setup, the system does not require input/output peripherals, and can be operated remotely (cf. Figure 1).

to input/output peripherals (monitor, keyboard, and mouse), as shown in Figure 3. To connect the camera module to the Raspberry Pi, proceed as shown in the instructional video available on YouTube. 6 Subsequently, the Raspberry Pi can be started headless and operated remotely from a computer connected to the same local network (cf. Figure 1).

2.2 Operating system and software setup

Operating system: Download and install the latest version of the Raspbian operating system, available at http://downloads.raspberrypi.org/raspbian latest. Extract the system image from the ZIP archive and install it on the SD card (also used for local storage on the Phenotiki device). The steps to write a Raspbian image to an SD card depend on the user's system, and instructions for several operating systems can be found in the official documentation [8].⁷ For example, on Linux, insert the SD card and run df-h to see the device name corresponding to the SD card, e.g., /dev/mmcblk0p1. Then, run the following commands with superuser privileges to first unmount the SD card and then install the Raspbian image 2016-03-18-raspbian-jessie.img:

```
umount /dev/mmcblk0p1
dd bs=4M if=2016-03-18-raspbian-jessie.img of=/dev/mmcblk0
sync
```

The dd command may take several minutes to write the image to the SD card. sync will ensure that all buffered data are written to the SD card. Upon completion, unmount and remove the SD card from the card reader.

With the peripherals connected as in Figure 3, start the Raspberry Pi, that will automatically boot to the desktop environment. From Menu,

 $^{^{6}\,\}texttt{http://www.youtube.com/watch?v=GImeVqHQzsE}$

⁷ http://www.raspberrypi.org/documentation/installation/

Preferences, launch Raspberry Pi Configuration to perform some system-level configuration tasks. In the System tab, click on Expand Filesystem. In the Interfaces tab, enable Camera and SSH. In the Localisation tab set Locale and Timezone. After completing configuration reboot the device.

Wi-Fi setup:

In the desktop environment, click on the network icon in the top menu bar. Select your local Internet connection and enter appropriate credentials if necessary. The device will remember network settings and connect on start-up.

Note that recent versions of the Raspberry Pi feature on board Wi-Fi, however, older versions require a USB wireless dongle.

Upon startup the Raspbian launches an SSH (secure shell) server, allowing remote access to the command line of the Raspberry Pi. For example, on a Linux system use the following command to connect to the device:

```
ssh -p 22 pi@<IP>
```

where <IP> is the local (or remote) IP address of the Raspberry Pi (e.g., 192.168.1.5). To find the IP address assigned to the Raspberry Pi in the local network, execute in a terminal on the device the command hostname -I. Default login user name and password are, respectively, 'pi' and 'raspberry'.

Packages upgrade:

Once a Wi-Fi connection is established, open a terminal on the Raspberry Pi (either directly on the device or remotely via SSH) and upgrade the device firmware and all installed packages to the latest available version:

```
sudo rpi-update
sudo apt-get update
sudo apt-get -y dist-upgrade
sudo apt-get -y autoremove
```

This operation may take some time, depending on network speed.

Software dependencies:

Install the software dependencies necessary to setup and run the Phenotiki software with BisQue support:

Install raspistillWeb:

Download the Phenotiki fork of the raspistillWeb software by cloning our GitHub repository and install it on the device:

```
mkdir ~/phenotiki
cd ~/phenotiki
virtualenv --python=python2.7 env
cd env
git clone https://github.com/phenotiki/raspistillWeb.git
cd raspistillWeb
../bin/python setup.py develop
../bin/initialize_raspistillweb_db development.ini
```

Note that the software and all dependencies will be installed in the virtual environment without affecting global Python options and libraries. This step guarantees that the software will work even if the Raspbian operating system and its packages are updated.

Install BisQue support:

Build and install the Python APIs for Bisque, running the following commands:

```
cd ~/phenotiki/env/
bin/pip install requests==2.7.0
bin/pip install BeautifulSoup4
bin/pip install lxml
hg clone http://biodev.ece.ucsb.edu/hg/bisque/
cd bisque/bqapi/
../../bin/python setup.py build_py
../../bin/python setup.py install
```

The hg command will download the BisQue code, thus this step may take some time depending on network speed.

Subsequently, when a new version of the BisQue API is available, to update the BisQue API from the official repository to the latest release, execute:

```
cd bisque/bqapi/
hg pull -u
```

You may check also the official BisQue installation instructions⁸ for a more extensive description of the installation process.

raspistillWeb:

Start raspistillWeb by launching the service that will run on the device and will generate the web interface upon request:

```
cd ~/phenotiki/env/raspistillWeb/
../bin/pserve development.ini
```

Afterwards, it is possible to access the raspistillWeb interface from a web browser on a computer connected to the same local network. For example, if the IP address of the Raspberry Pi is 192.168.1.5, in a browser on a laptop or a smartphone open http://192.168.1.5:6543. (By default the raspistillWeb service will be listening on port number 6543.)

By properly configuring the router of the local network, it is be possible to enable remote access to the raspistillWeb via the Internet. Notice however that this configuration step depends on the local network settings and you should seek support of your network administrator.

In order to start the raspistillWeb automatically on system boot, on the Raspberry Pi edit the /etc/rc.local file using a text editor with superuser privileges, for example:

```
sudo nano /etc/rc.local
```

Add the following lines at the bottom of the file before the line exit 0:

```
cd ~/phenotiki/env/raspistillWeb/
../bin/pserve development.ini
```

To save the changes and quit the editor, press Ctrl+X, then Y, and finally Enter.

Finally, if you are deploying multiple Phenotiki devices, you can assign different names by editing the /etc/hostname file:

```
sudo nano /etc/hostname
```

Change the default raspberrypi to a name of your choice, e.g., phenotiki-device-01. The name of a device is also displayed in Settings page of the web interface.

⁸https://biodev.ece.ucsb.edu/projects/bisque/wiki/ InstallationInstructions05

3 Operating the device

Coming soon!

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