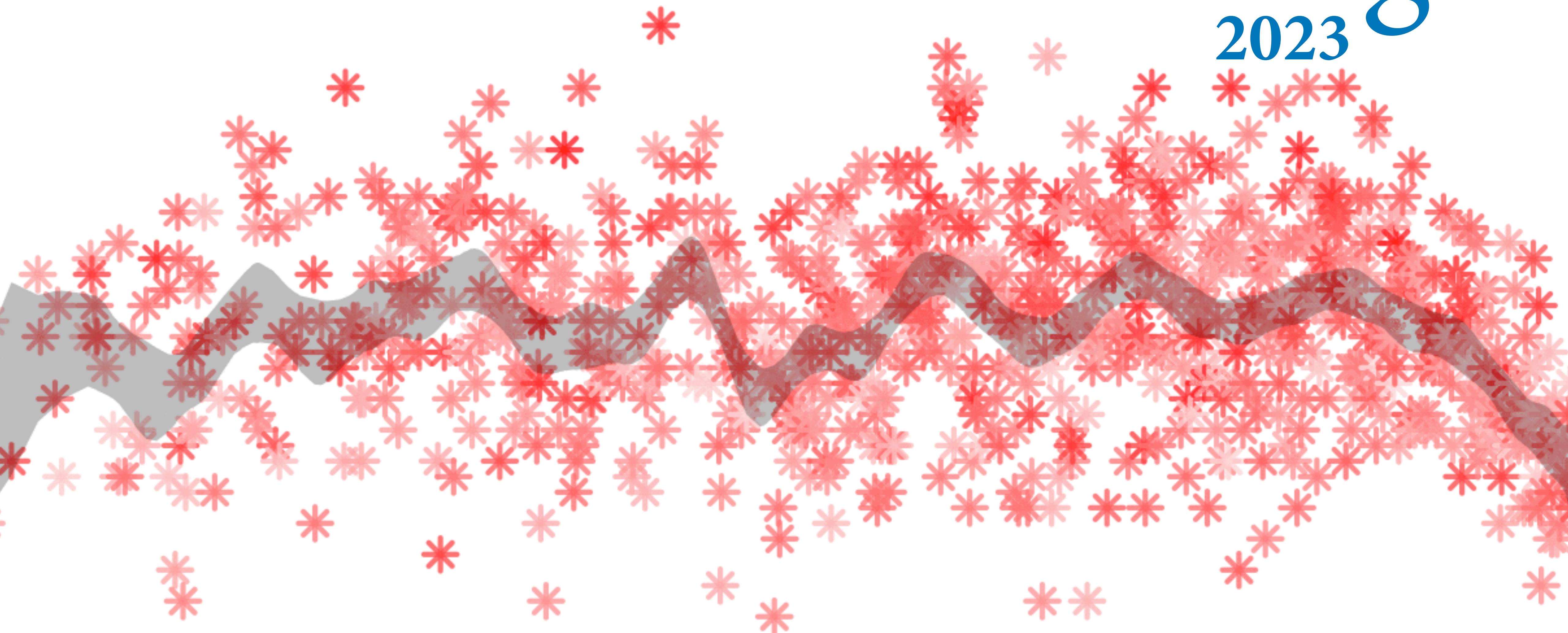


# Statistical Rethinking

2023



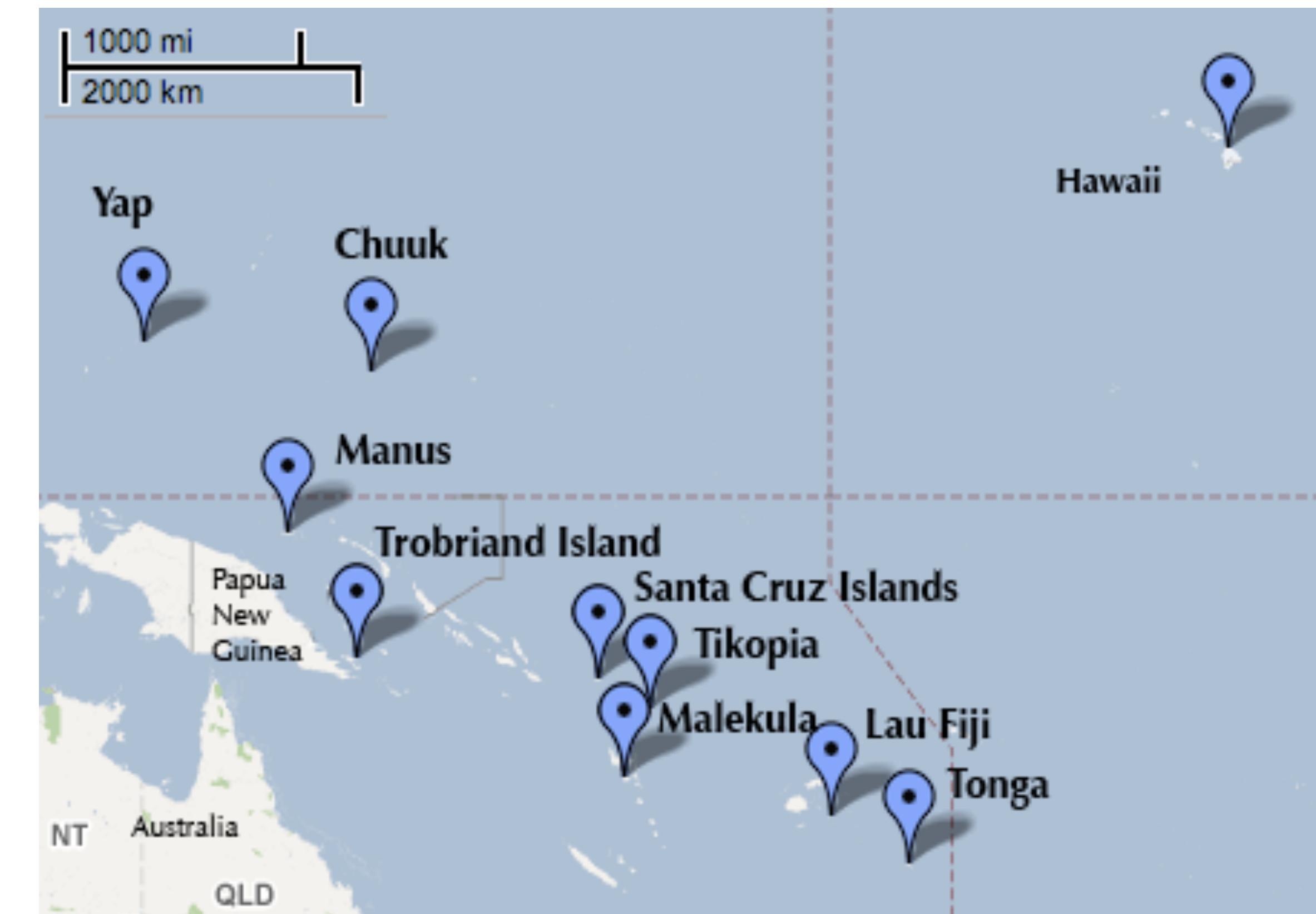
## 16. Gaussian Processes

# Oceanic Technology

data(Kline2)

Number of **tool types** associated with **population size**

Spatial covariation: Islands close together share **unobserved confounds** and innovations

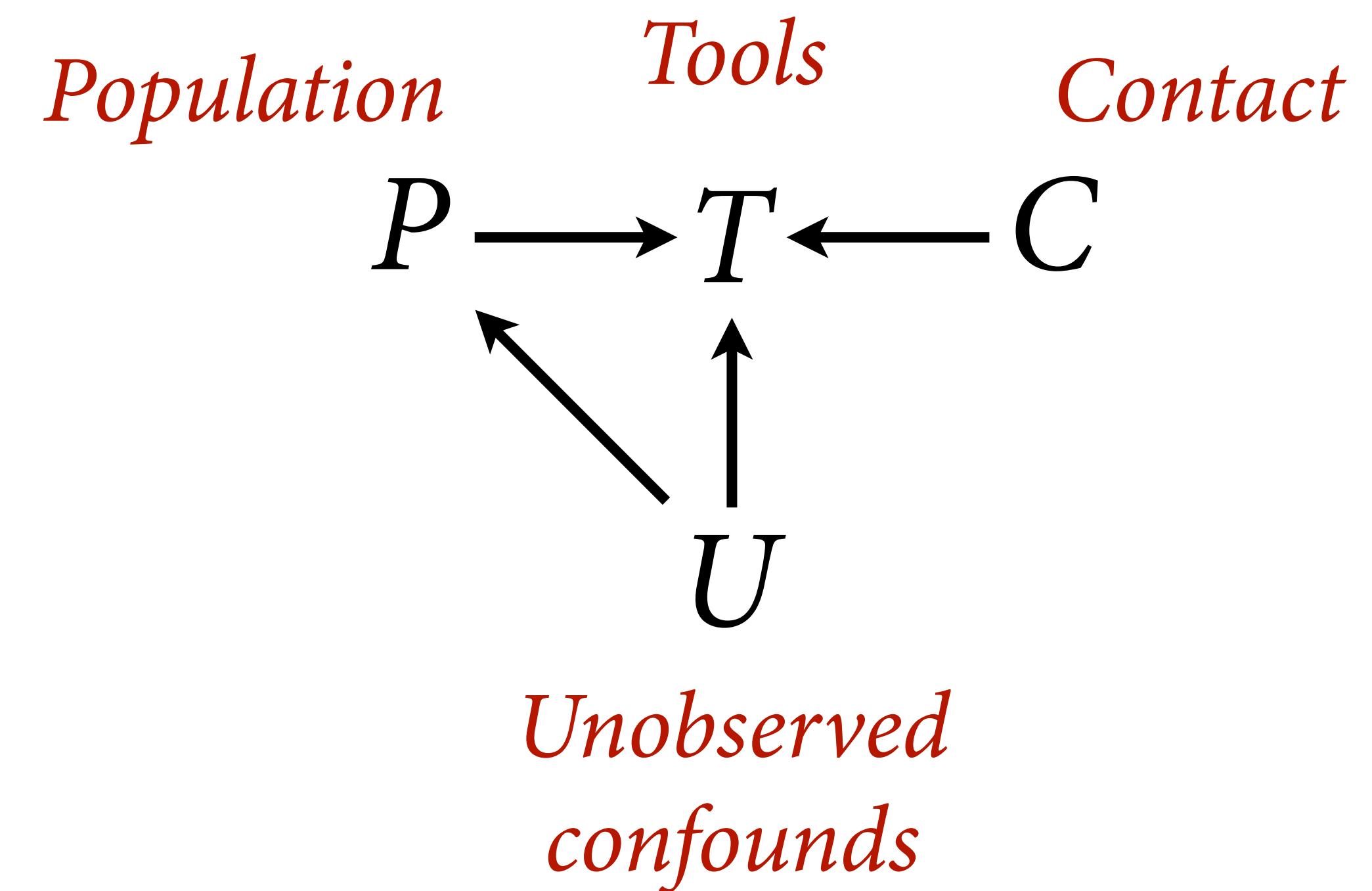


# Oceanic Technology

`data(Kline2)`

Number of **tool types** associated  
with **population** size

Spatial covariation: Islands close  
together share **unobserved**  
**confounds** and innovations



$$\Delta T = \alpha P^\beta - \gamma T$$

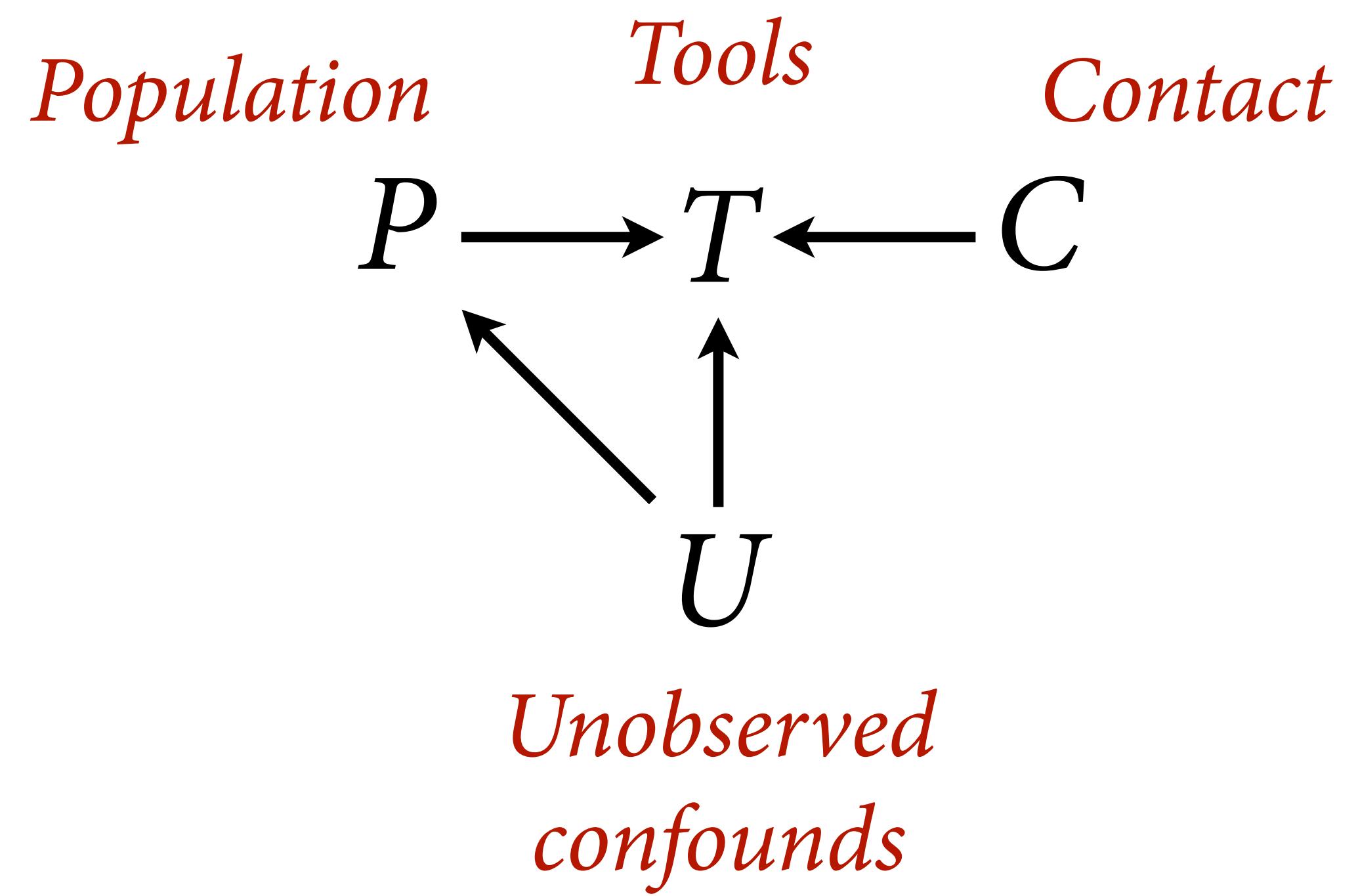
*change in tools*  
*innovation rate*  
*rate of loss*  
*diminishing returns (elasticity)*



$$T_i \sim \text{Poisson}(\lambda_i)$$

$$\lambda_i = \hat{T}$$

$$\hat{T} = \frac{\alpha P^\beta}{\gamma}$$



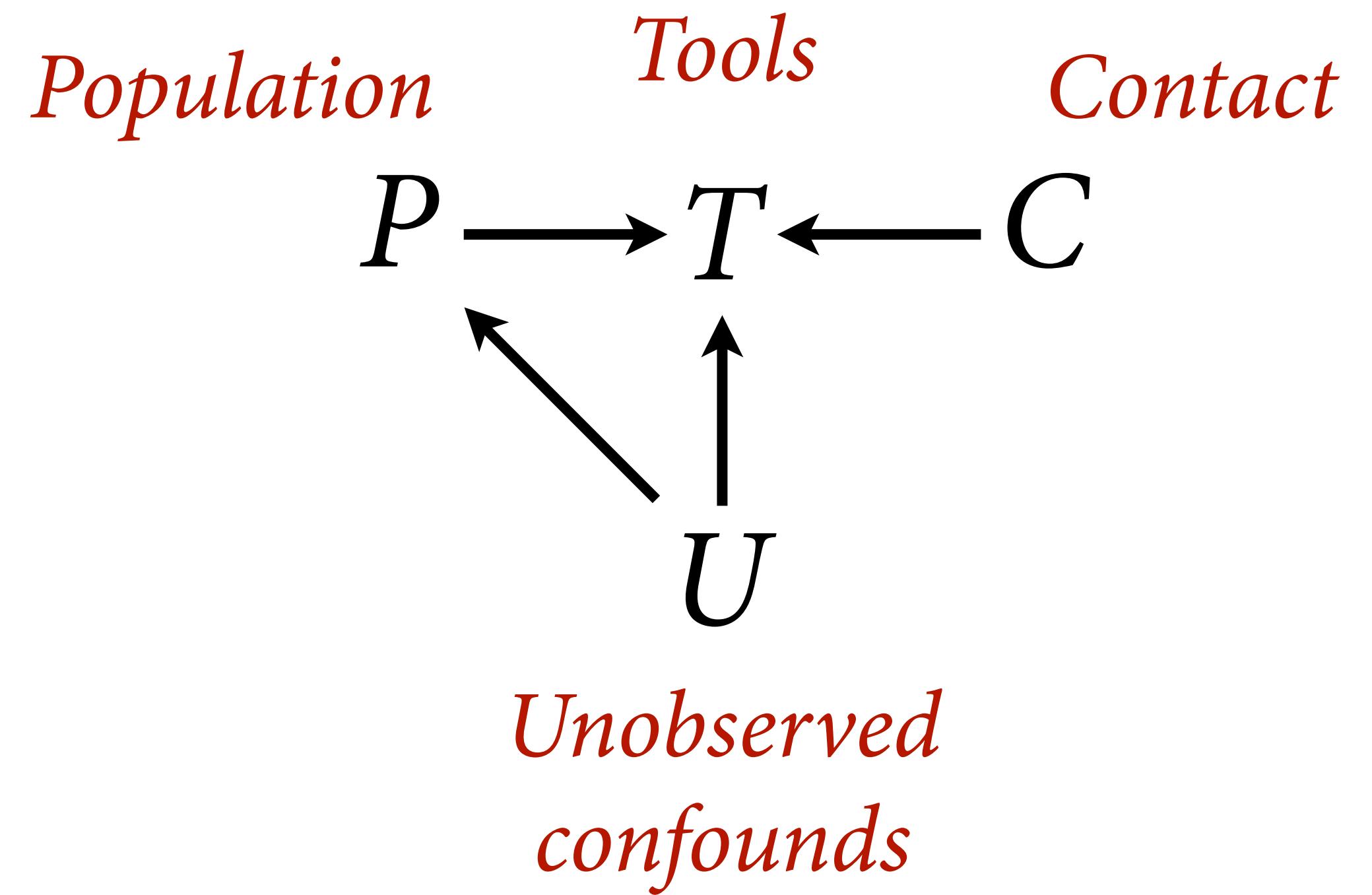
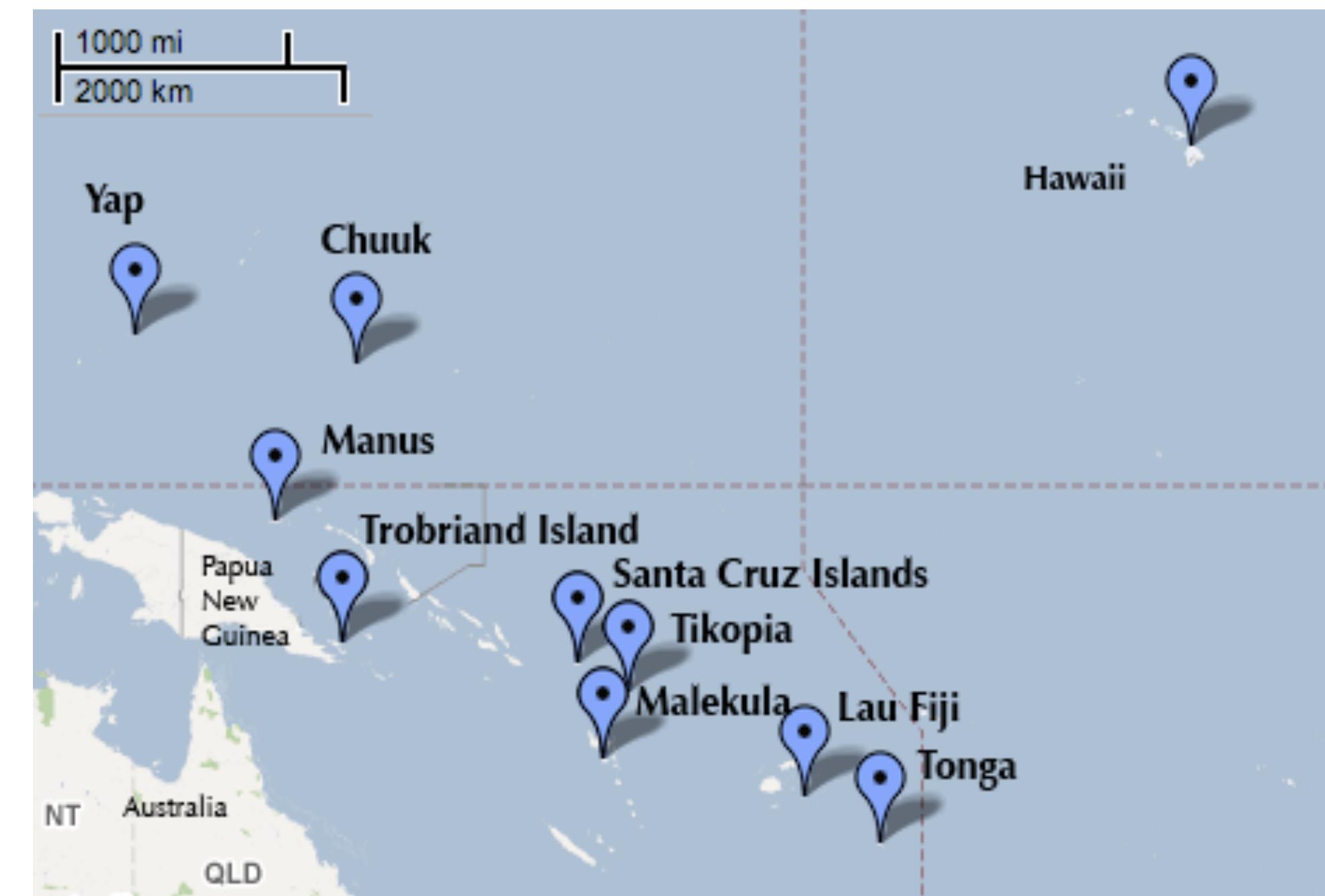
$$T_i \sim \text{Poisson}(\lambda_i)$$

$$\lambda_i = \hat{T}$$

$$\hat{T} = \frac{\alpha P^\beta}{\gamma}$$

Spatial covariation: Islands close together share **unobserved confounds** and **innovations**

Effect of  $U$  is to make closer islands have more similar  $\hat{T}$



$$T_i \sim \text{Poisson}(\lambda_i)$$

$$\log \lambda_i = \bar{\alpha} + \alpha_{S[i]}$$

*deviation log-tools  
in society  $i$*



$$T_i \sim \text{Poisson}(\lambda_i)$$

$$\log \lambda_i = \bar{\alpha} + \alpha_{S[i]}$$

$$\begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_{10} \end{bmatrix}$$

*vector of all  
varying effects*



$$T_i \sim \text{Poisson}(\lambda_i)$$

$$\log \lambda_i = \bar{\alpha} + \alpha_{S[i]}$$

$$\begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_{10} \end{bmatrix} \sim \text{MVNormal} \left( \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \mathbf{K} \right)$$

*vector of all  
varying effects*

*vector of zeros*



*covariance matrix,  
the “Kernel”*

$$T_i \sim \text{Poisson}(\lambda_i)$$

$$\log \lambda_i = \bar{\alpha} + \alpha_{S[i]}$$

$$\begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_{10} \end{bmatrix} \sim \text{MVNormal} \left( \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \mathbf{K} \right)$$

$$\mathbf{K} = \begin{bmatrix} \sigma^2 & k_{1,2} & k_{1,3} & k_{1,4} & k_{1,5} & k_{1,6} & k_{1,7} & k_{1,8} & k_{1,9} & k_{1,10} \\ \sigma^2 & k_{2,3} & k_{2,4} & k_{2,5} & k_{2,6} & k_{2,7} & k_{2,8} & k_{2,9} & k_{2,10} & \\ \sigma^2 & k_{3,4} & k_{3,5} & k_{3,6} & k_{3,7} & k_{3,8} & k_{3,9} & k_{3,10} & & \\ \sigma^2 & k_{4,5} & k_{4,6} & k_{4,7} & k_{4,8} & k_{4,9} & k_{4,10} & & & \\ \sigma^2 & k_{5,6} & k_{5,7} & k_{5,8} & k_{5,9} & k_{5,10} & & & & \\ \sigma^2 & k_{6,7} & k_{6,8} & k_{6,9} & k_{6,10} & & & & & \\ \sigma^2 & k_{7,8} & k_{7,9} & k_{7,10} & & & & & & \\ \sigma^2 & k_{8,9} & k_{8,10} & & & & & & & \\ \sigma^2 & k_{9,10} & & & & & & & & \\ \sigma^2 & & & & & & & & & \end{bmatrix}$$

$$\mathbf{K} = \begin{bmatrix}
& \text{Malekula} & & & & & & & & & \\
& \text{Tikopia} & \text{Santa Cruz} & & \text{Yap} & \text{Fiji} & \text{Trobriand} & \text{Chuuk} & \text{Manus} & \text{Tonga} & \text{Hawaii} \\
\sigma^2 & k_{1,2} & k_{1,3} & k_{1,4} & k_{1,5} & k_{1,6} & k_{1,7} & k_{1,8} & k_{1,9} & k_{1,10} & \text{Malekula} \\
\sigma^2 & k_{2,3} & k_{2,4} & k_{2,5} & k_{2,6} & k_{2,7} & k_{2,8} & k_{2,9} & k_{2,10} & \text{Tikopia} \\
\sigma^2 & k_{3,4} & k_{3,5} & k_{3,6} & k_{3,7} & k_{3,8} & k_{3,9} & k_{3,10} & & \text{Santa Cruz} \\
& \sigma^2 & k_{4,5} & k_{4,6} & k_{4,7} & k_{4,8} & k_{4,9} & k_{4,10} & & \text{Yap} \\
& & \sigma^2 & k_{5,6} & k_{5,7} & k_{5,8} & k_{5,9} & k_{5,10} & & \text{Fiji} \\
& & & \sigma^2 & k_{6,7} & k_{6,8} & k_{6,9} & k_{6,10} & & \text{Trobriand} \\
& & & & \sigma^2 & k_{7,8} & k_{7,9} & k_{7,10} & & \text{Chuuk} \\
& & & & & \sigma^2 & k_{8,9} & k_{8,10} & & \text{Manus} \\
& & & & & & \sigma^2 & k_{9,10} & & \text{Tonga} \\
& & & & & & & \sigma^2 & & \text{Hawaii}
\end{bmatrix}$$

45 covariances

# Gaussian Processes

A Gaussian Process is “*an infinite-dimensional generalization of multivariate normal distributions*”

What does this mean?

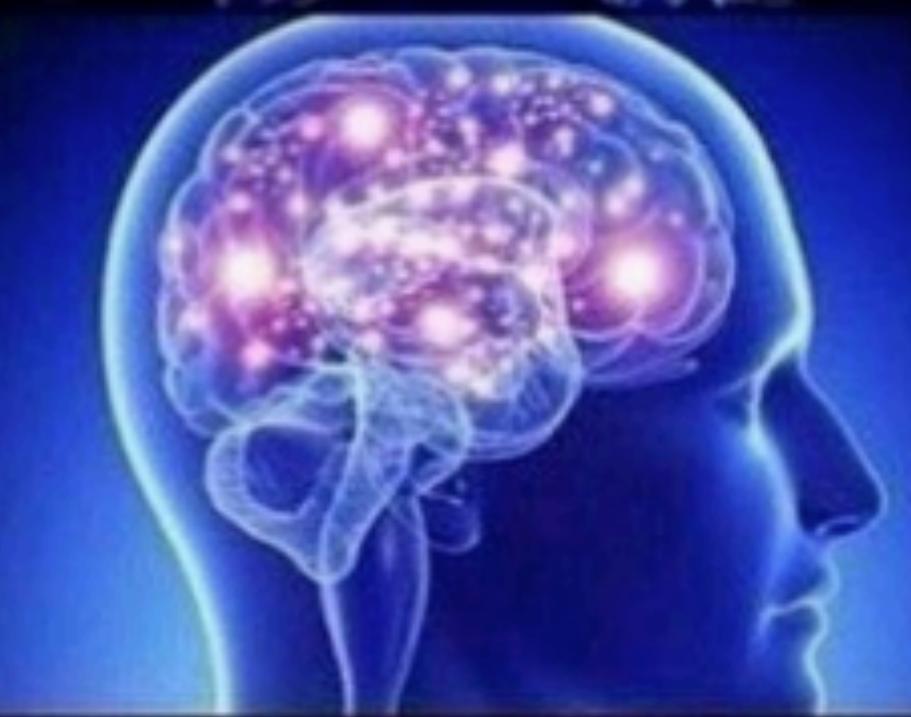
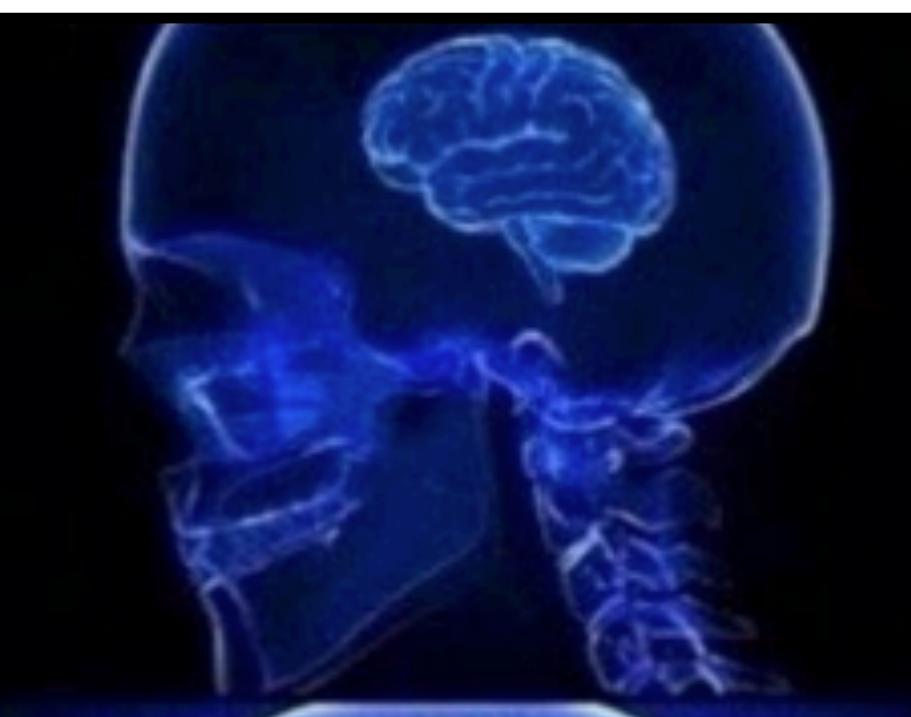
Instead of conventional covariance matrix, use a kernel function that generalizes to infinite dimensions/observations/predictions

**A NUMBER**

**A NORMAL  
DISTRIBUTION**

**A MULTIVARIATE  
NORMAL  
DISTRIBUTION**

**AN INFINITE  
DIMENSIONAL  
MULTIVARIATE  
NORMAL  
DISTRIBUTION**



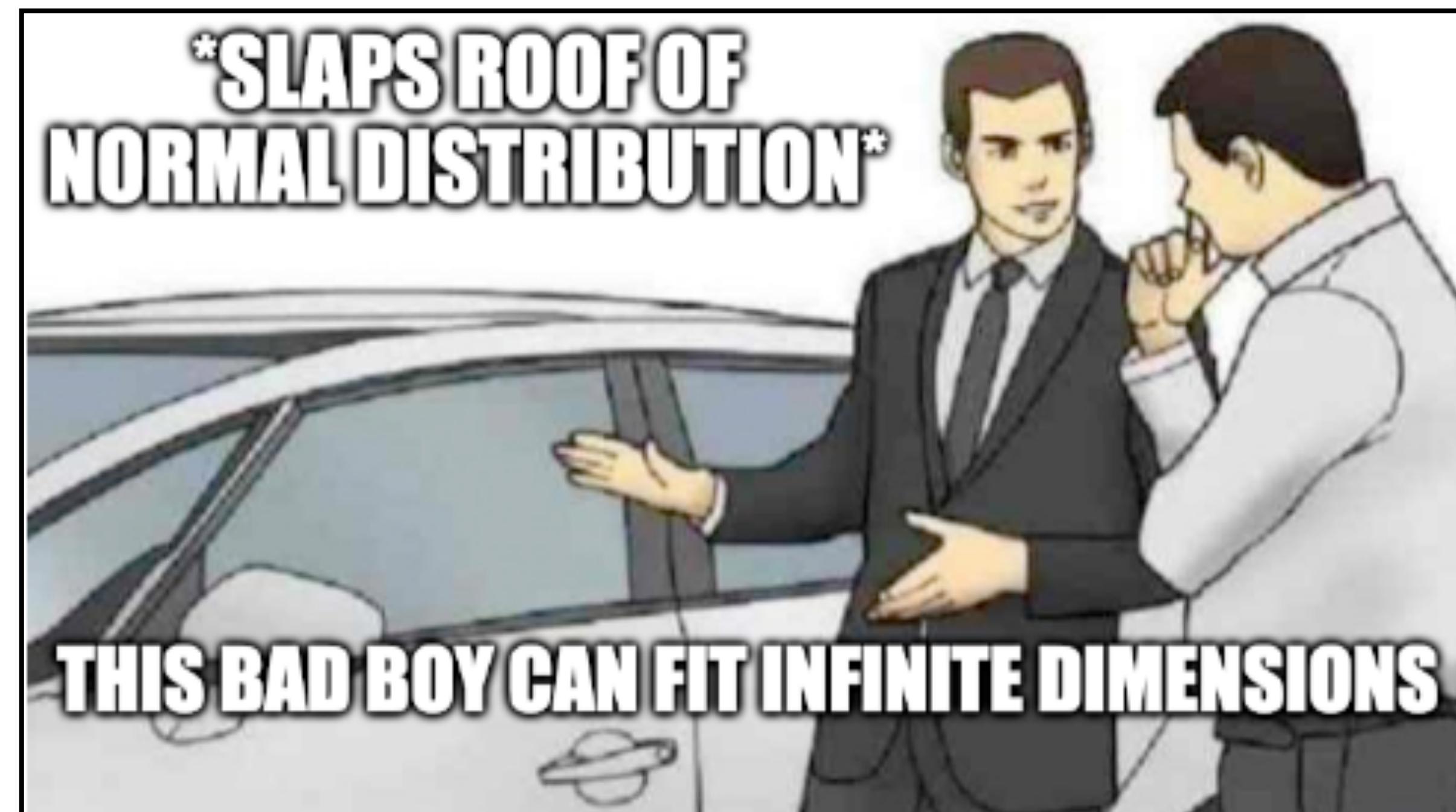
# Gaussian Processes

Instead of conventional covariance matrix, use a **kernel function**

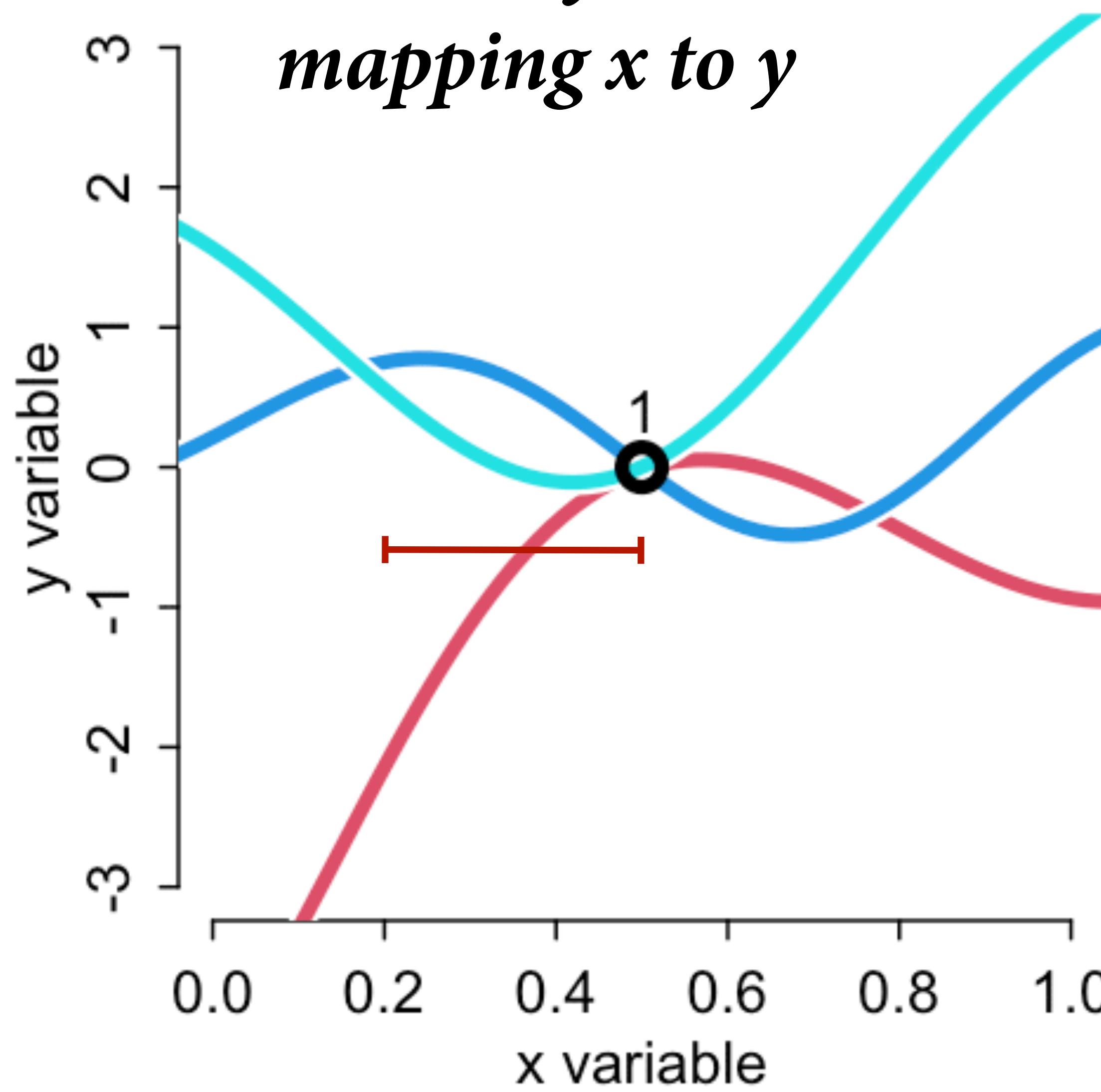
The kernel gives the covariance between any pair of points as a function of their **distance**

Distance can be difference, space, time, etc

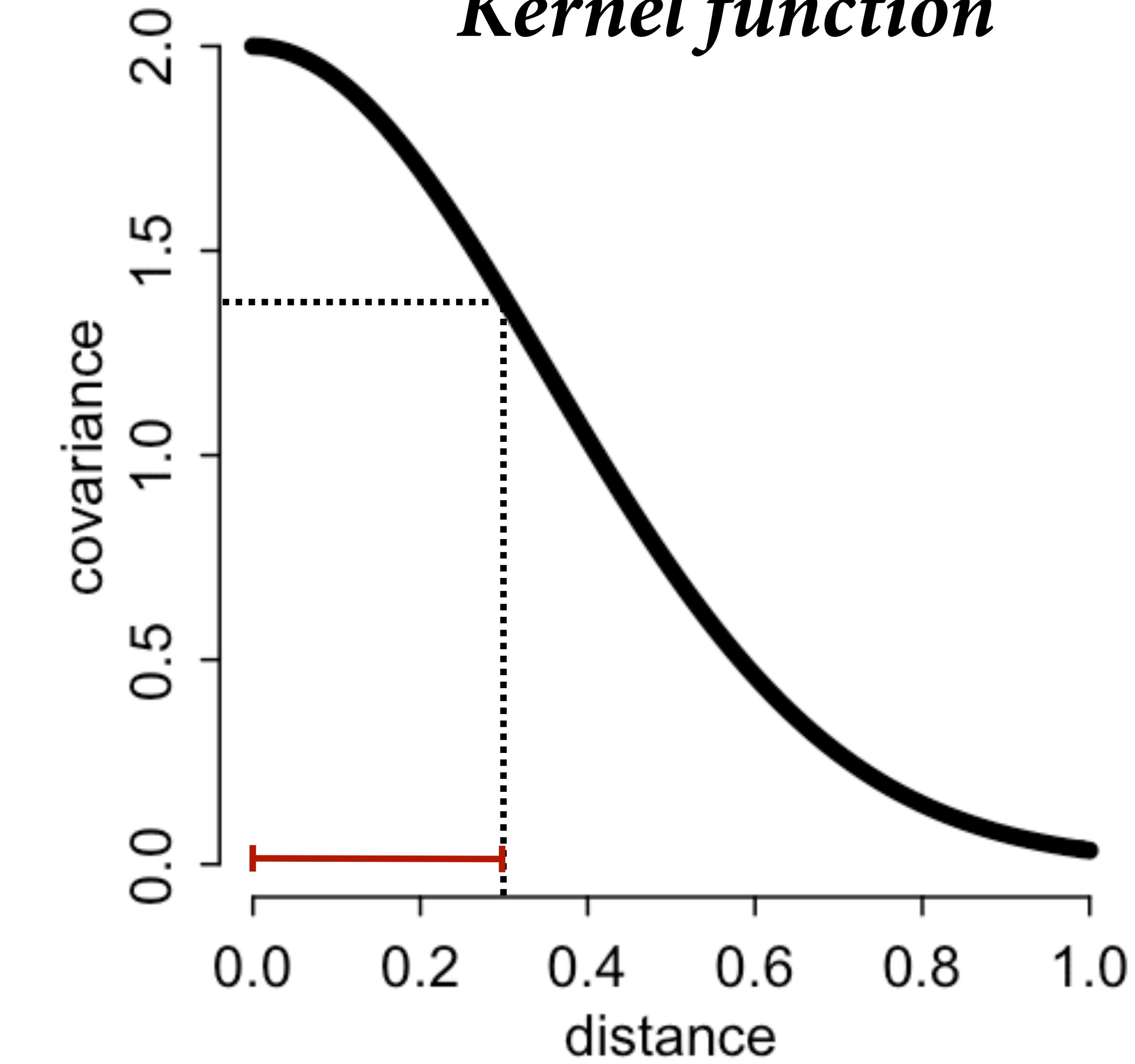
Continuous, ordered categories



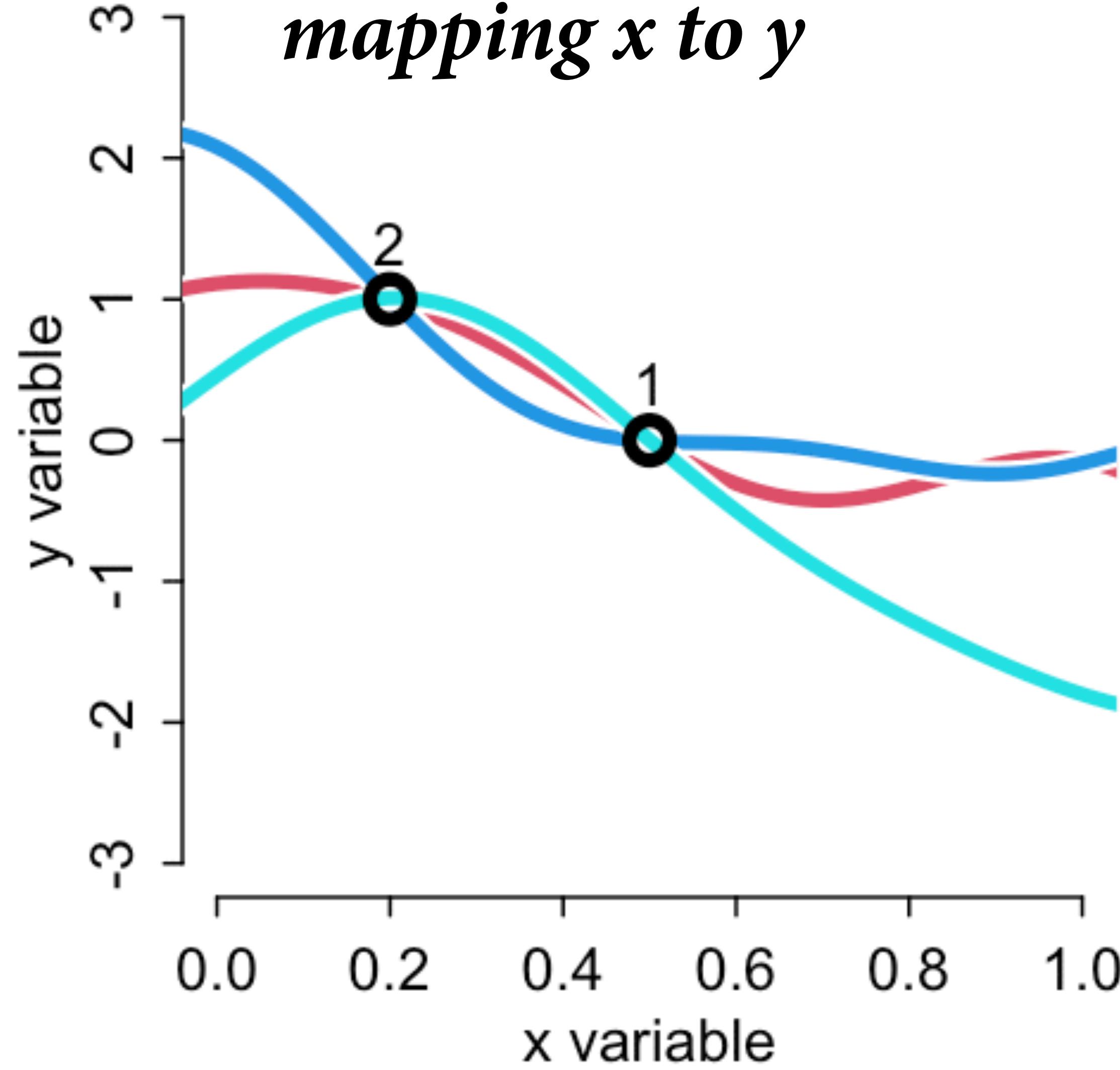
*Possible functions  
mapping  $x$  to  $y$*



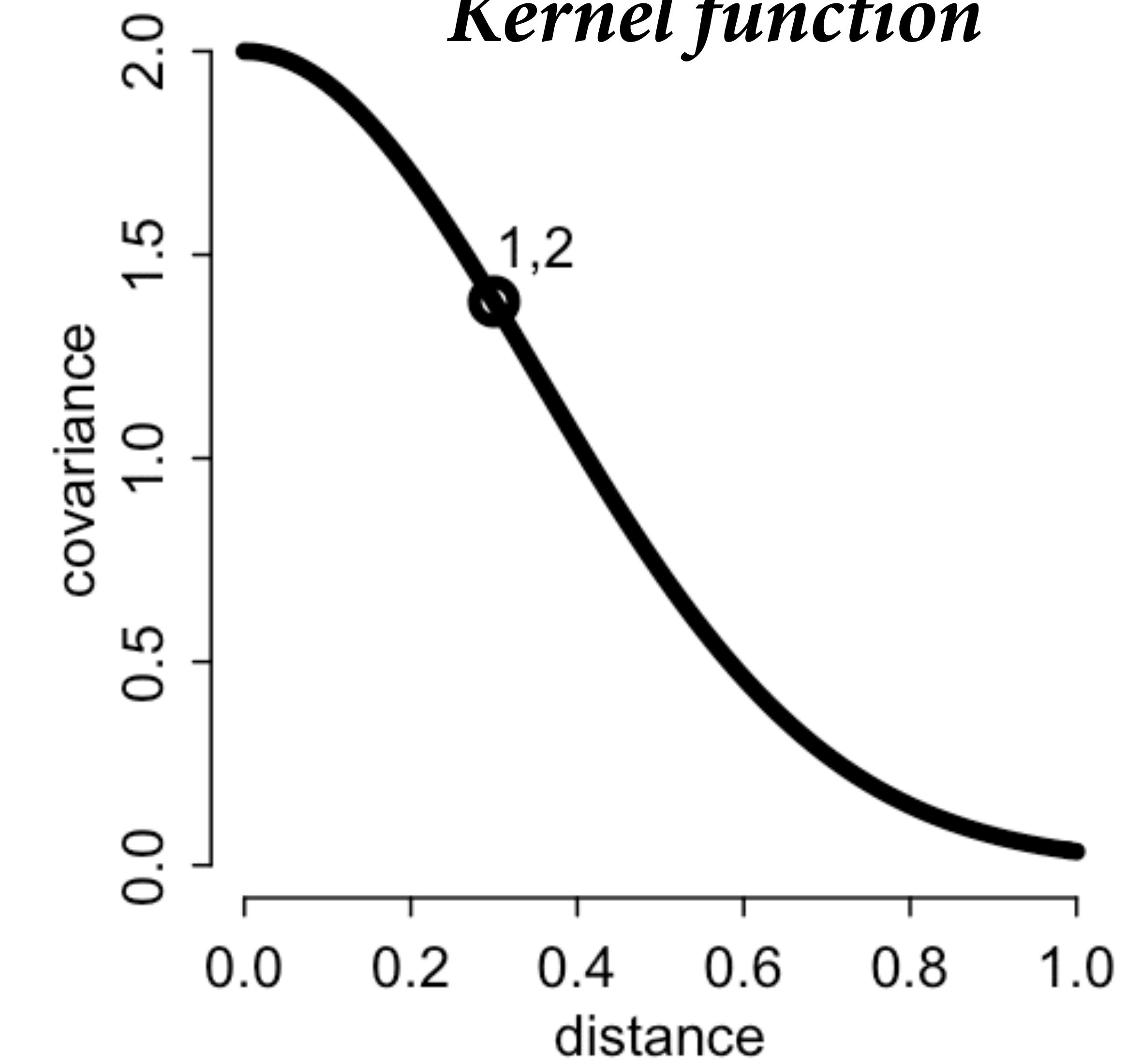
*Kernel function*



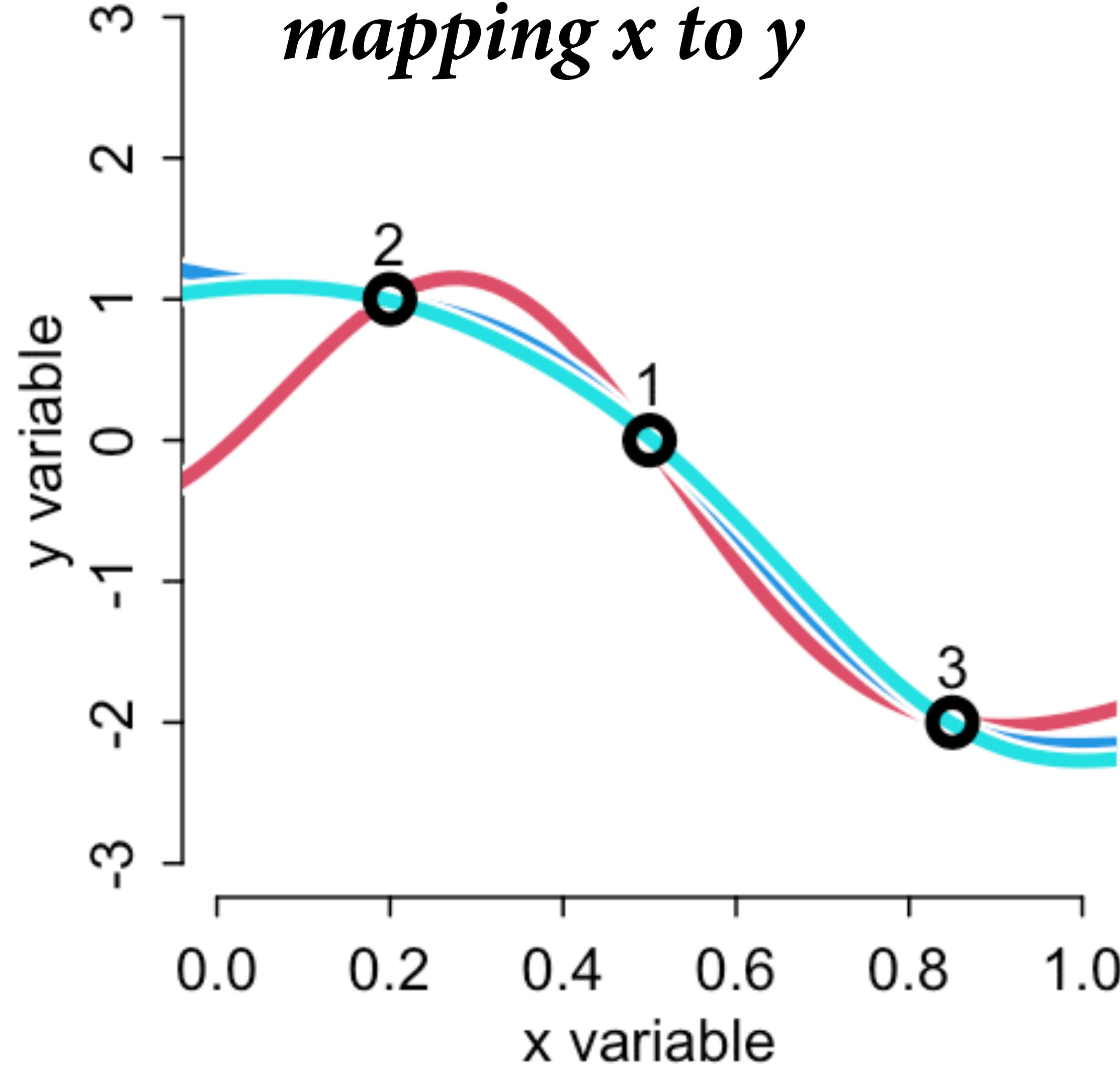
*Possible functions  
mapping  $x$  to  $y$*



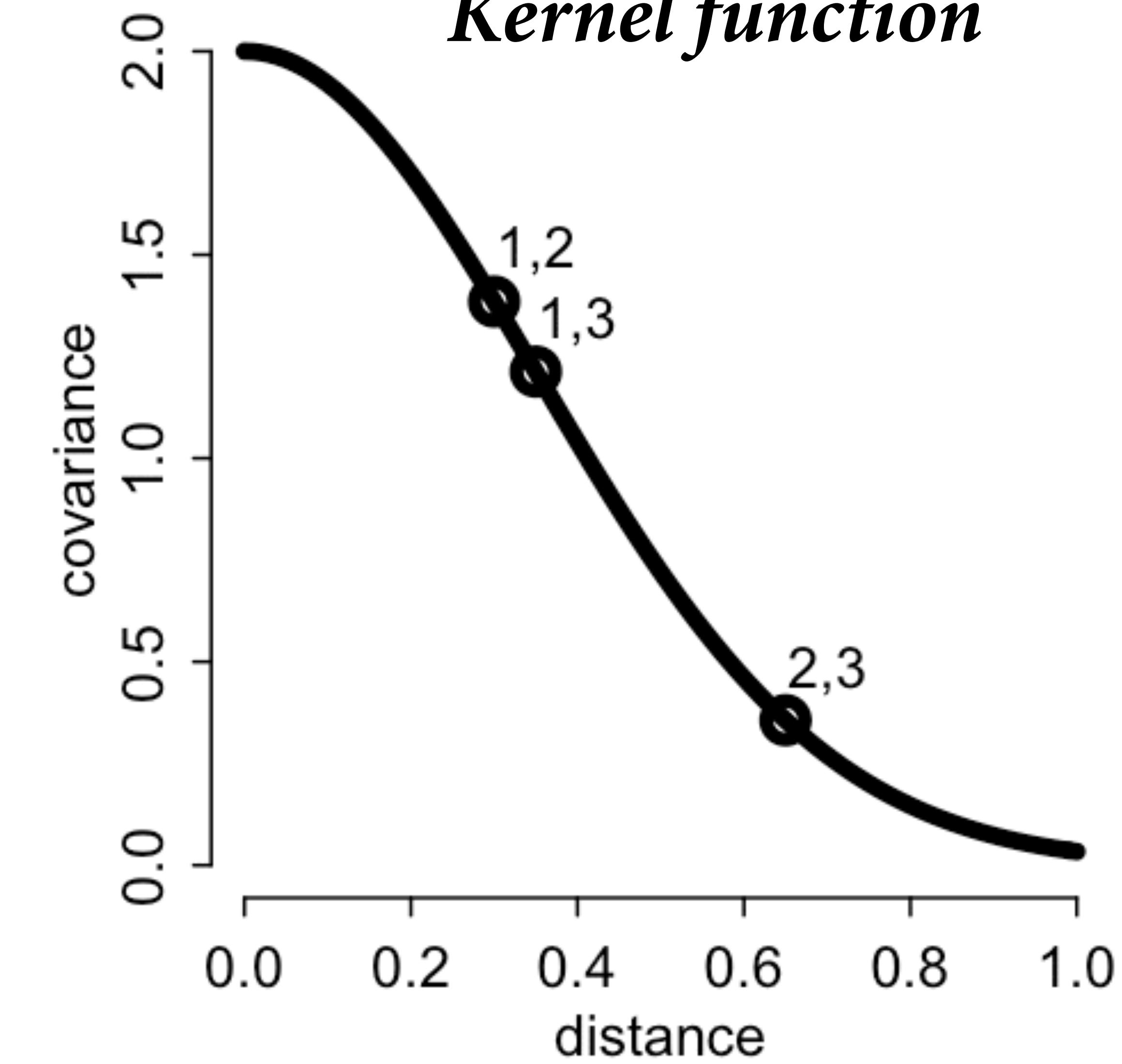
*Kernel function*



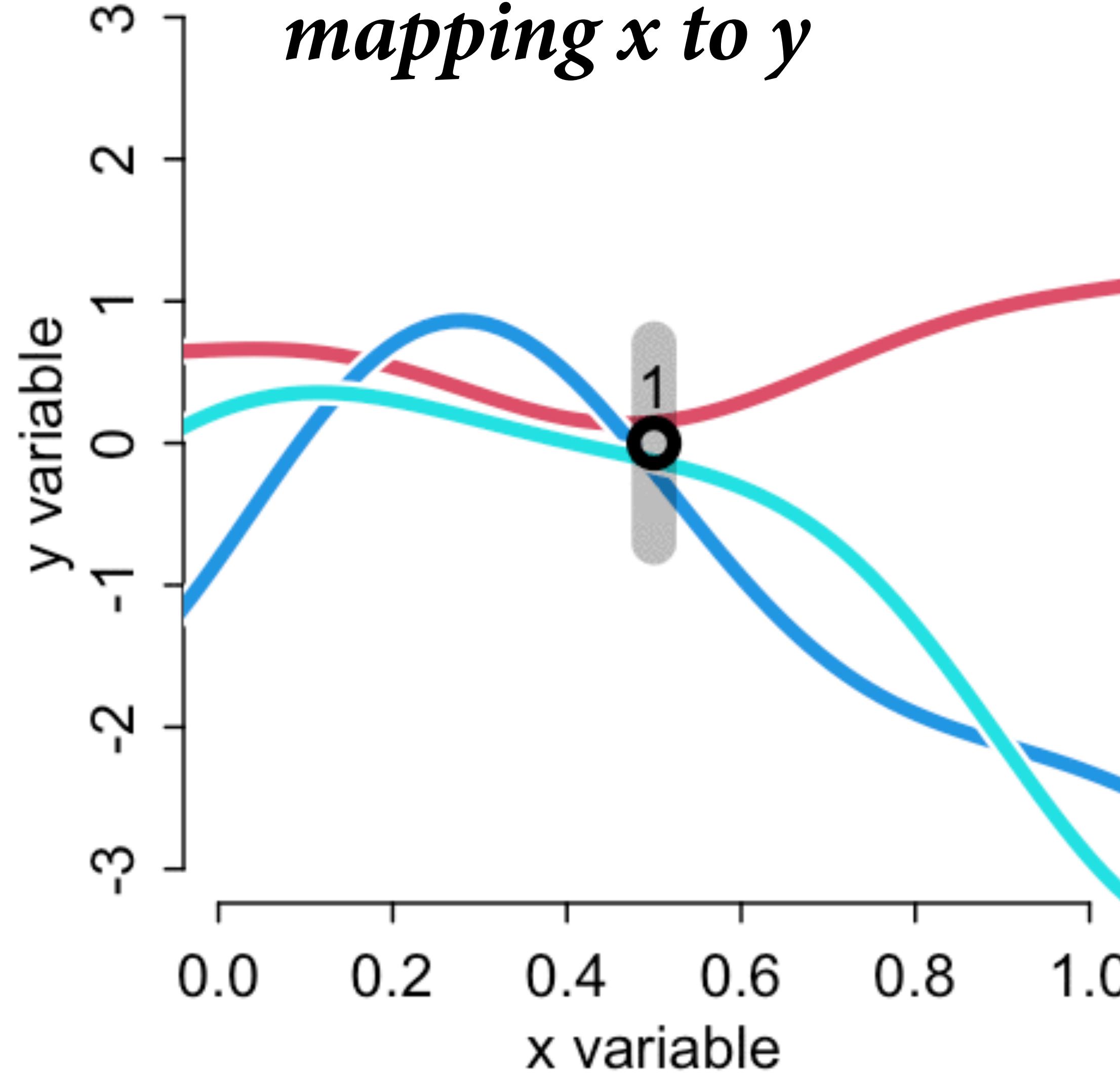
*Possible functions  
mapping  $x$  to  $y$*



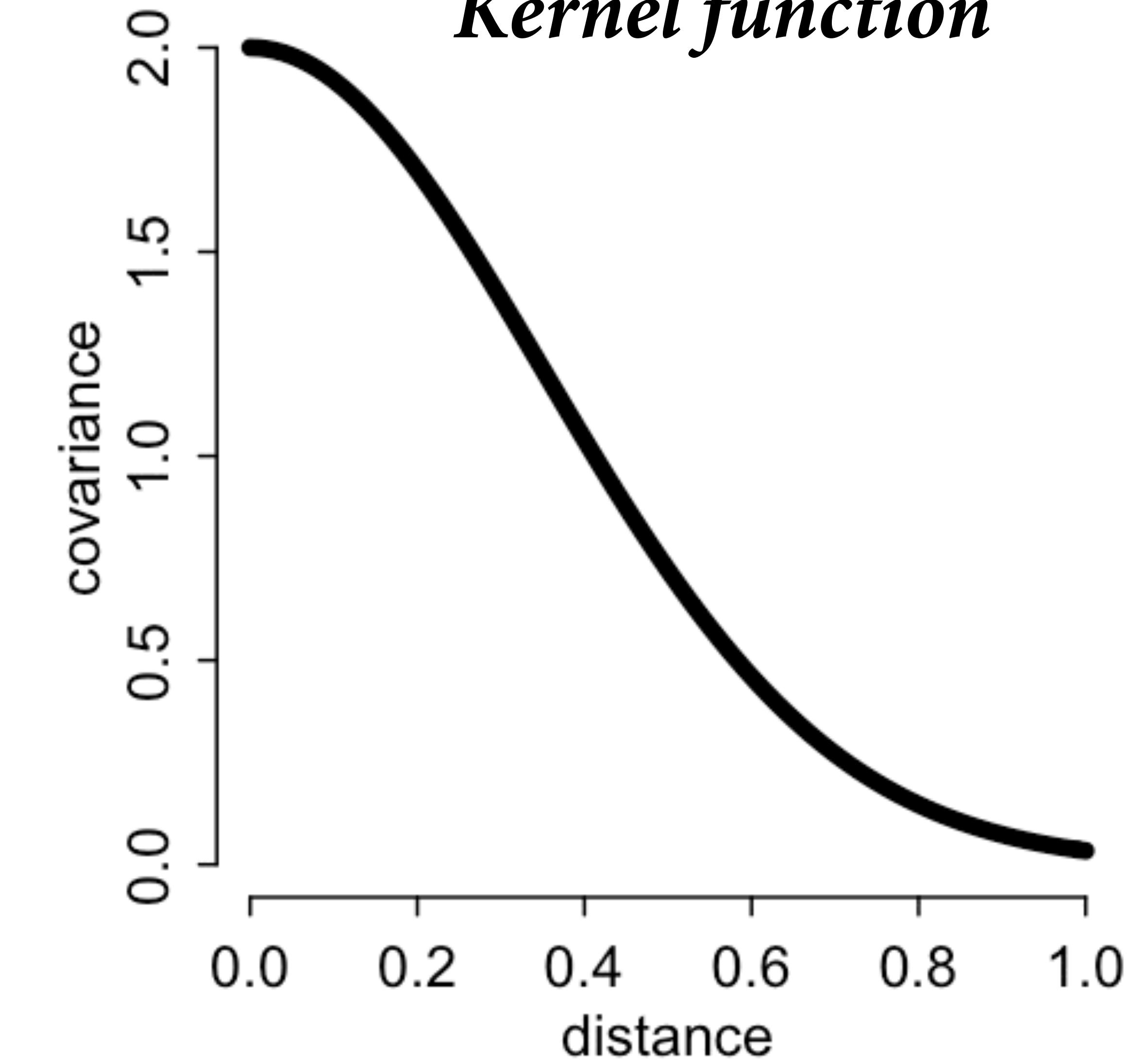
*Kernel function*

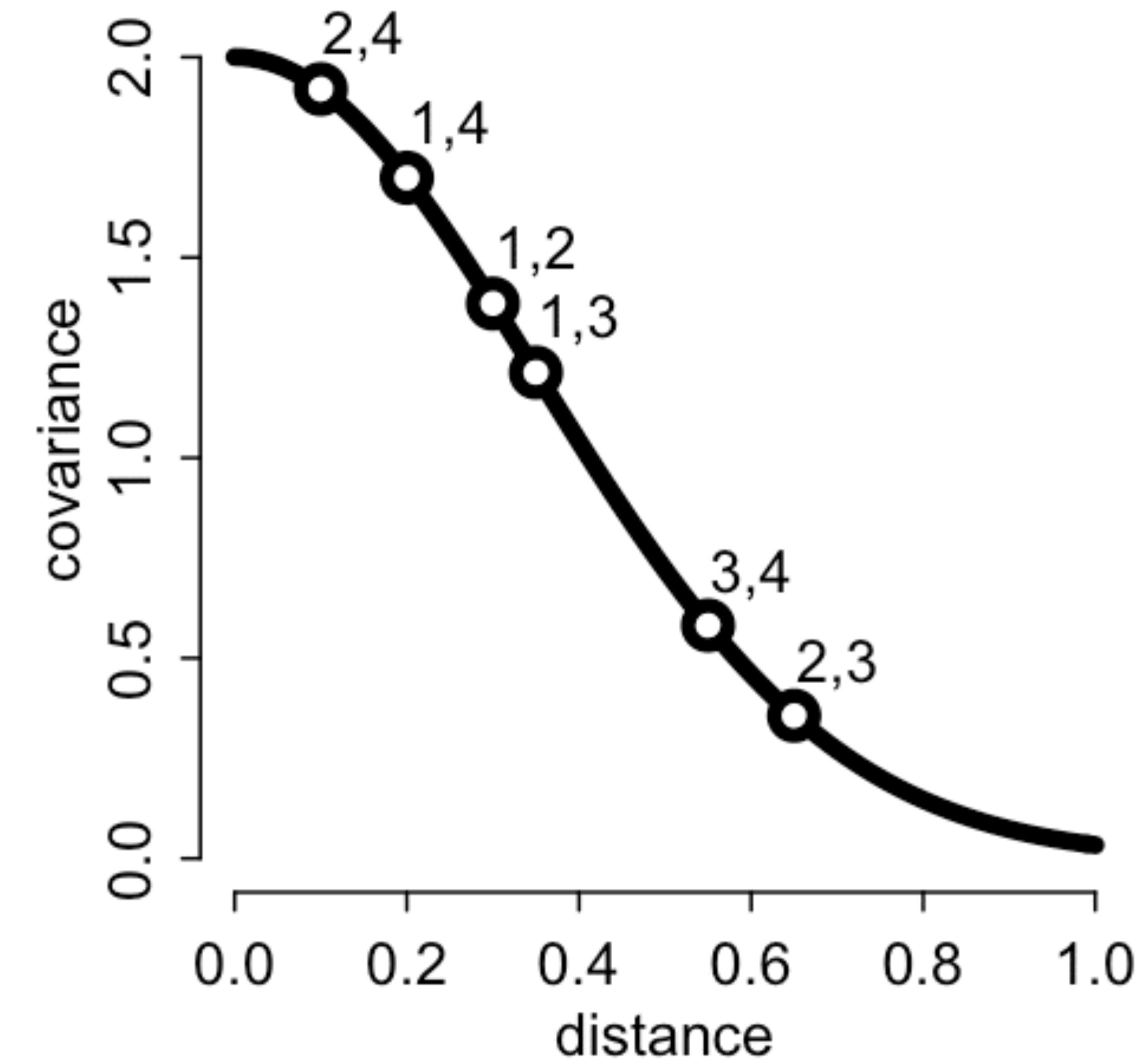
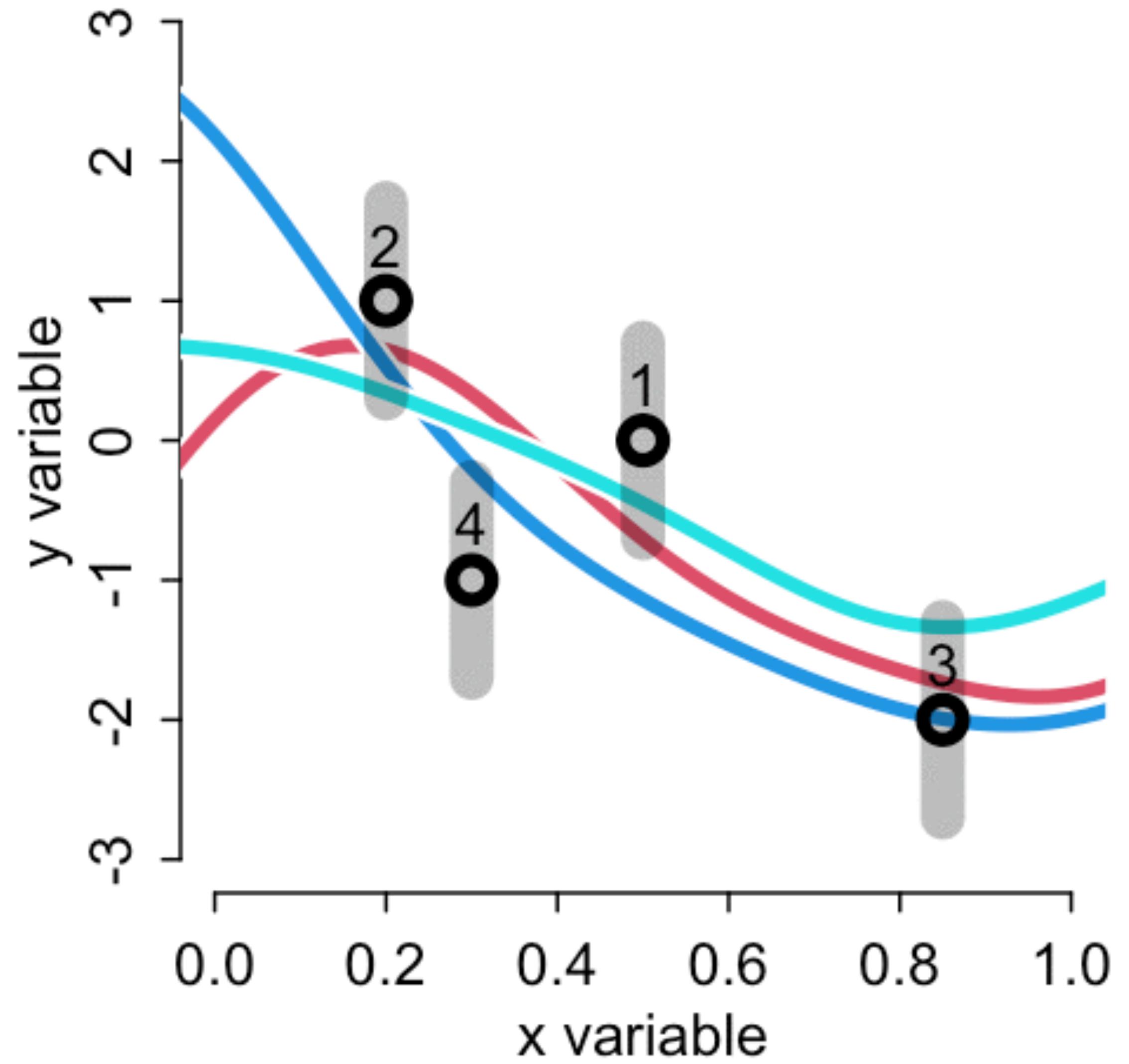


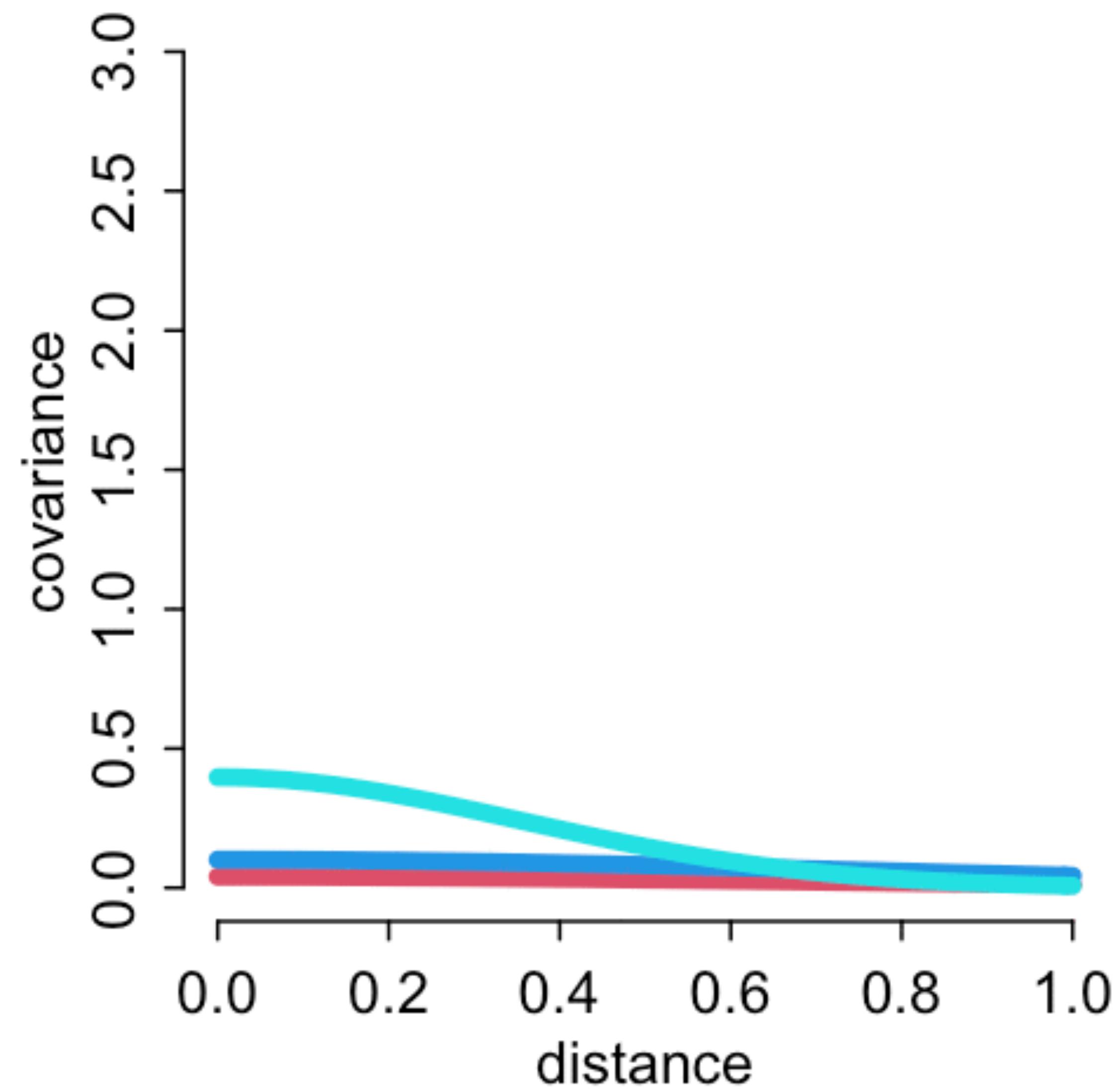
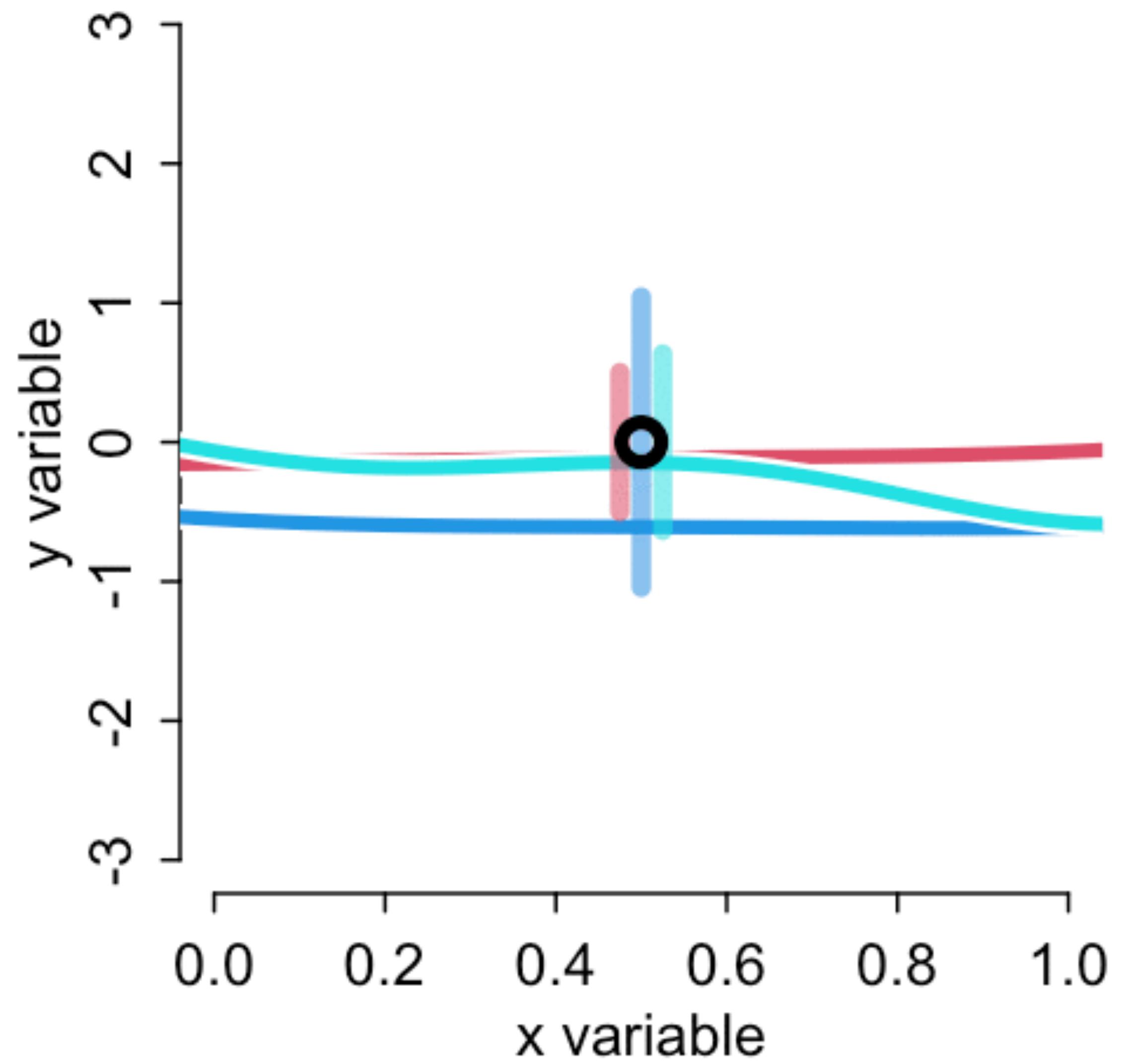
*Possible functions  
mapping  $x$  to  $y$*

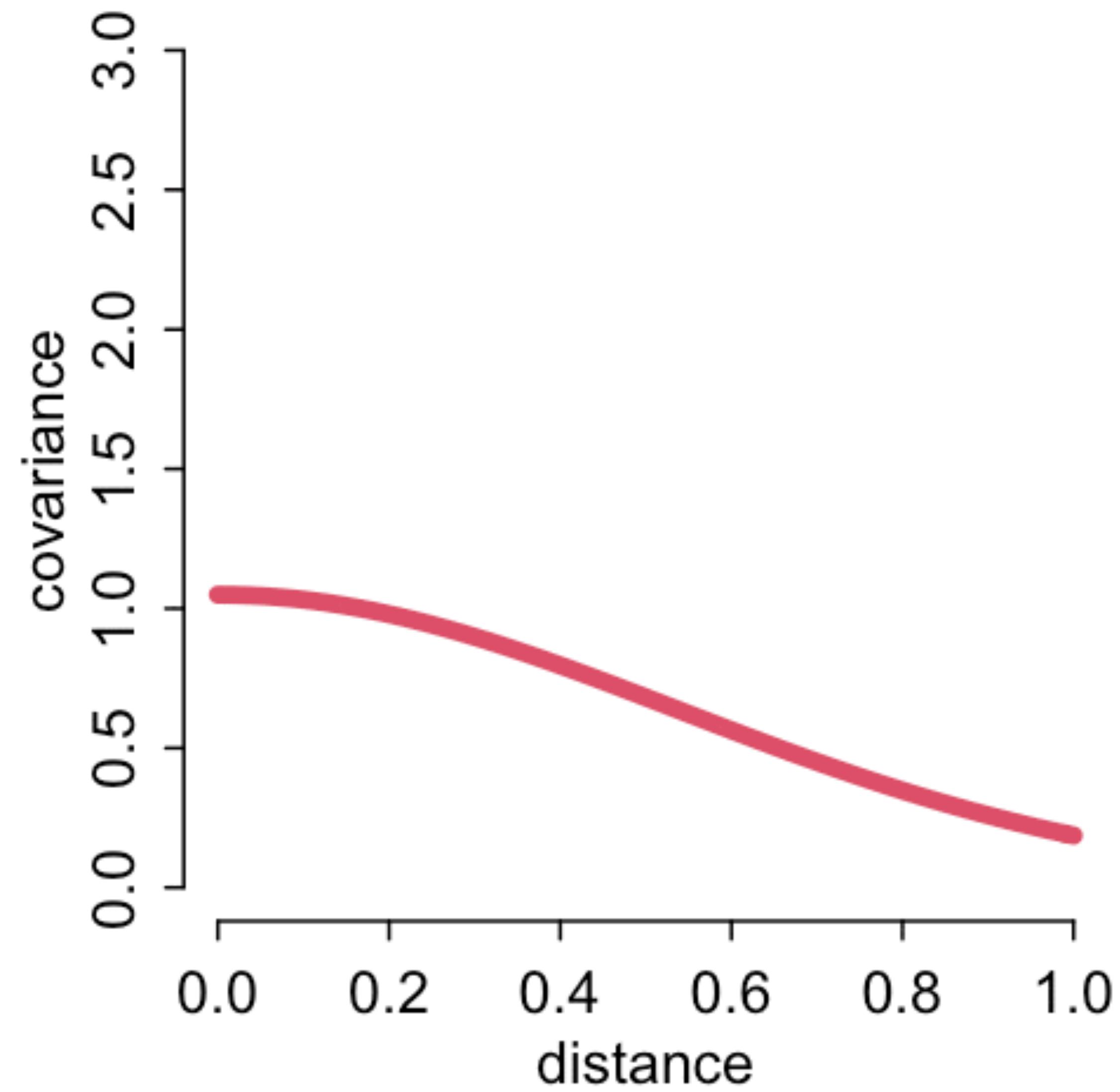
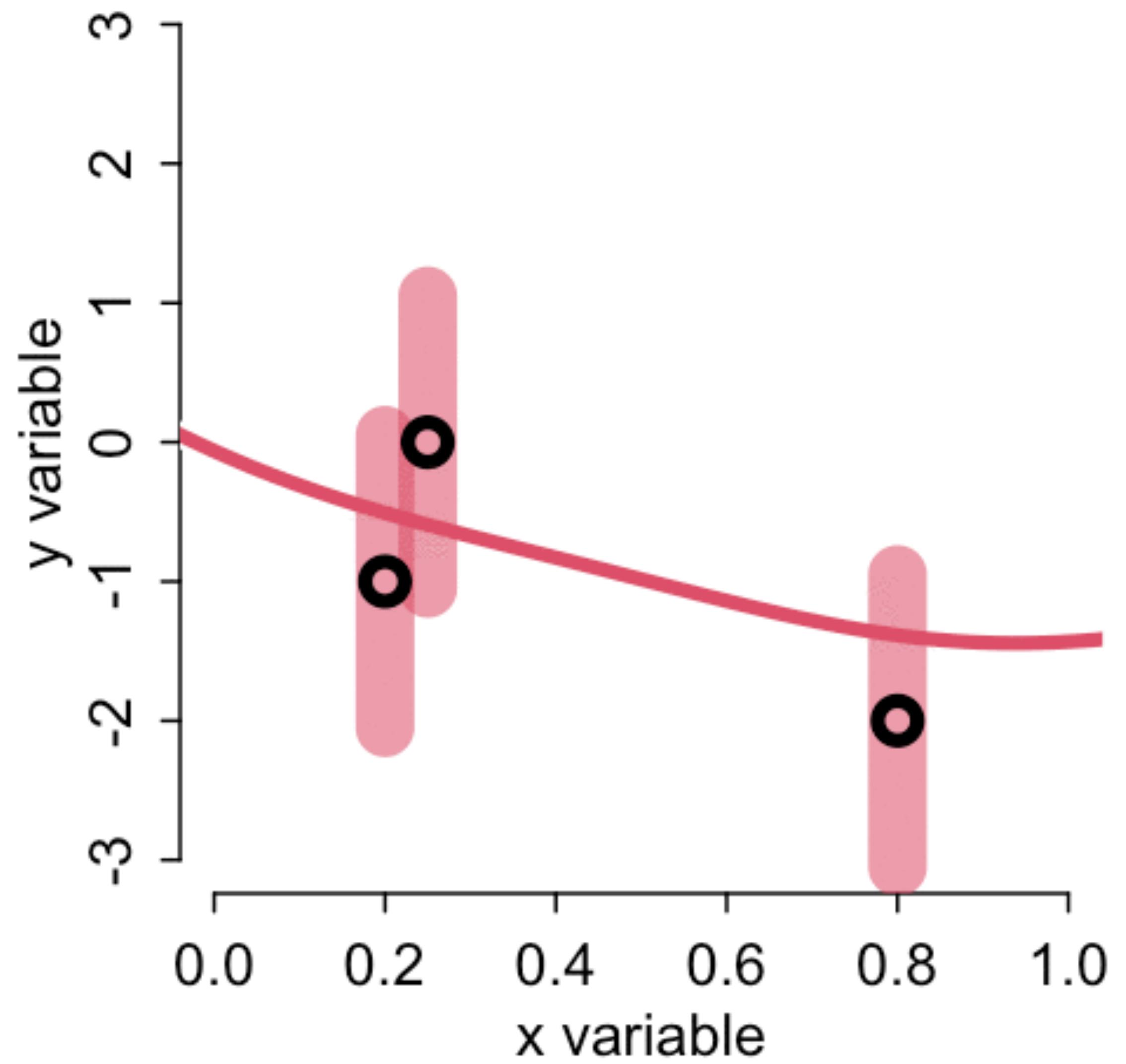


*Kernel function*



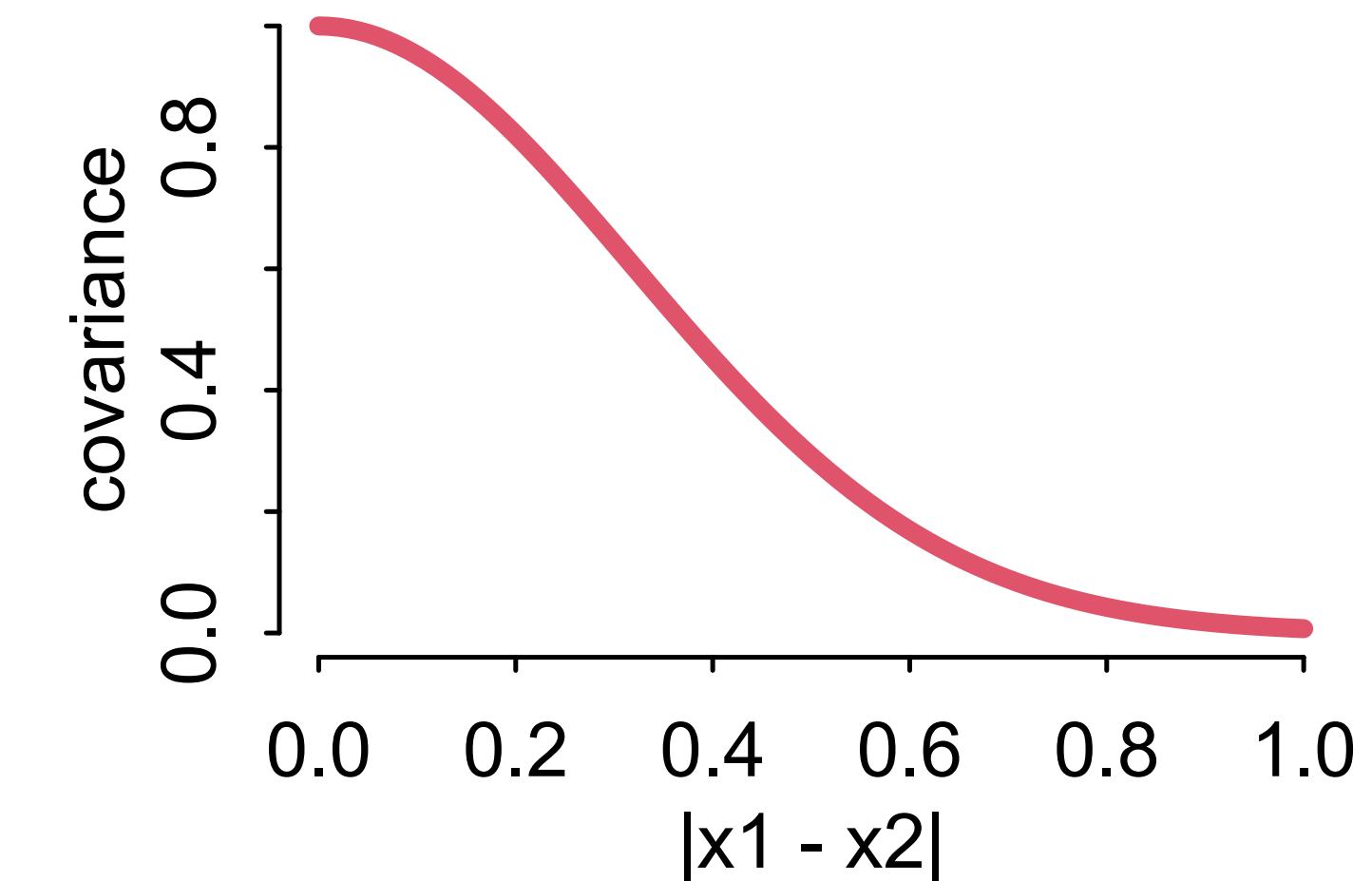






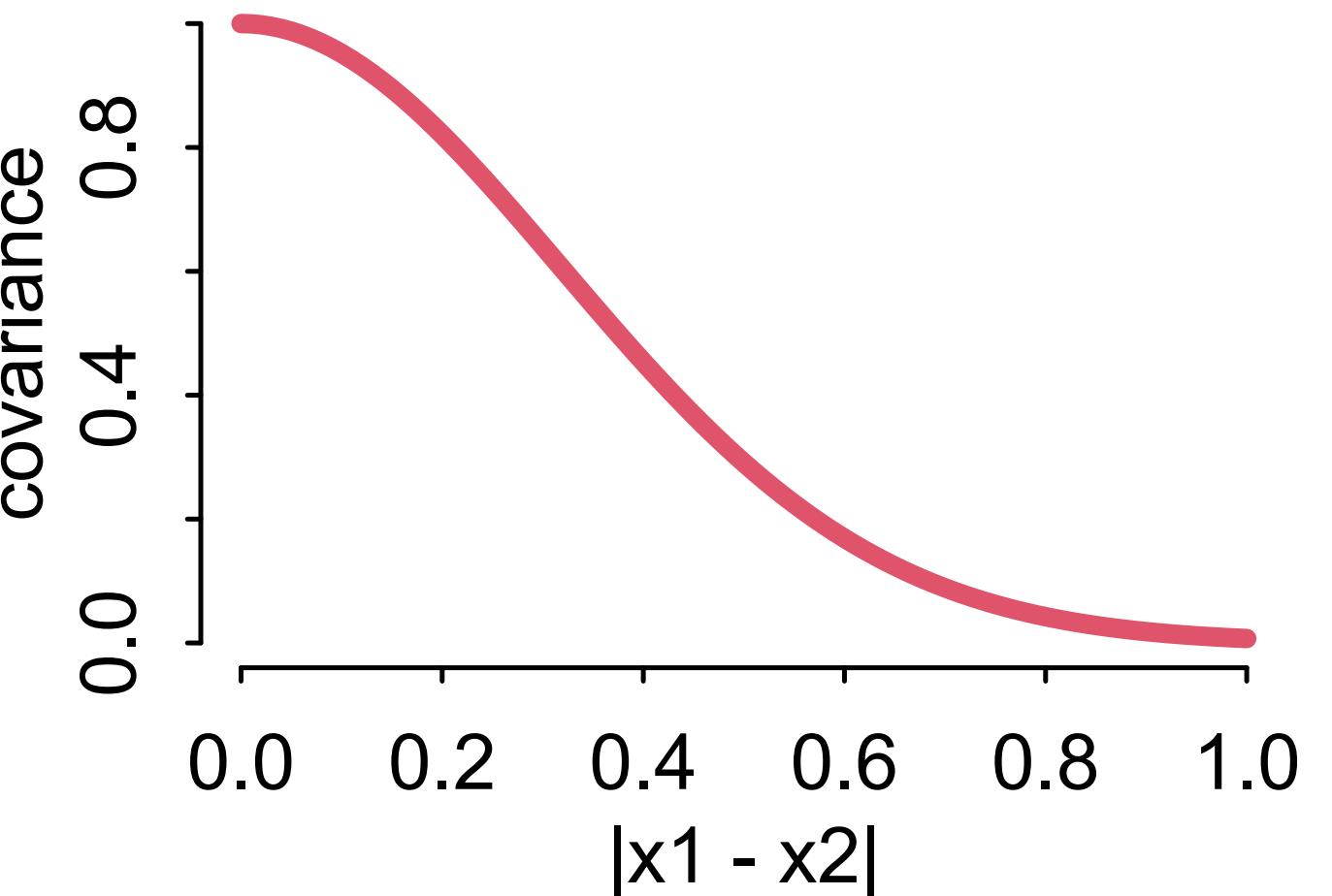
## Quadratic (L2)

$$k(x_1, x_2) = \alpha^2 \exp\left(-\frac{(x_1 - x_2)^2}{\sigma^2}\right)$$



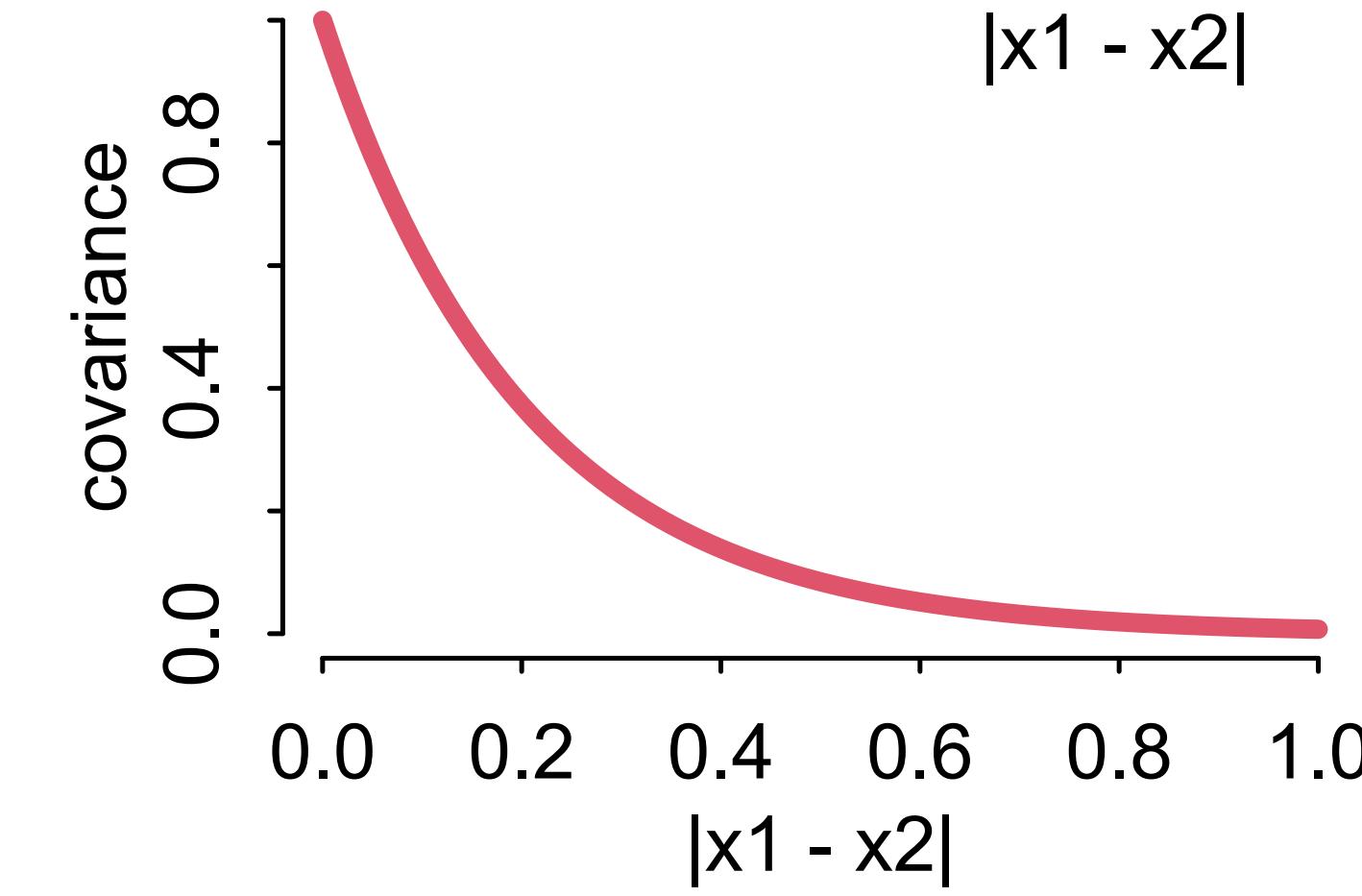
## Quadratic (L2)

$$k(x_1, x_2) = \alpha^2 \exp\left(-\frac{(x_1 - x_2)^2}{\sigma^2}\right)$$



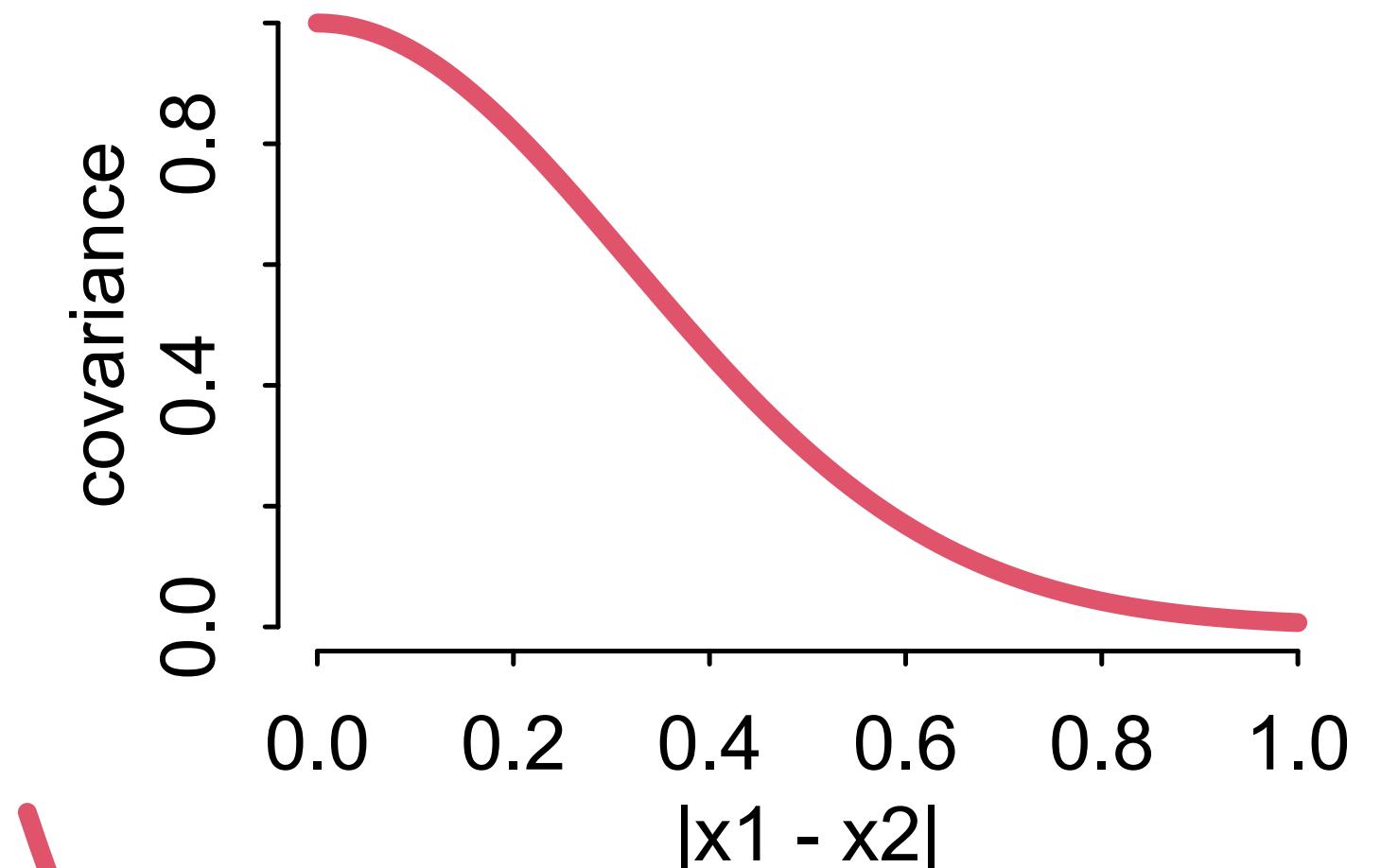
## Ornstein-Uhlenbeck

$$k(x_1, x_2) = \alpha^2 \exp\left(-\frac{|x_1 - x_2|}{\sigma}\right)$$



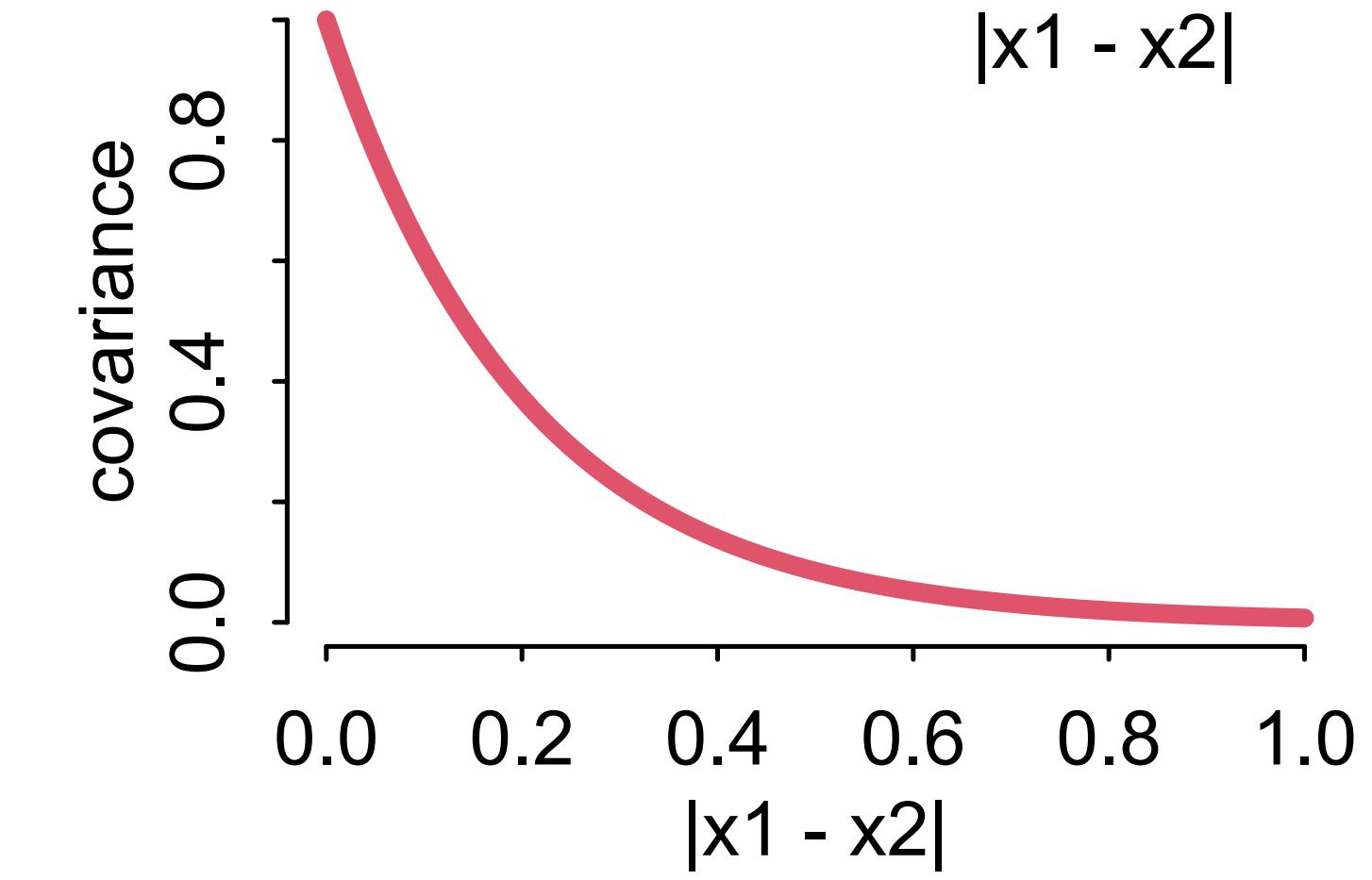
Quadratic (L2)

$$k(x_1, x_2) = \alpha^2 \exp\left(-\frac{(x_1 - x_2)^2}{\sigma^2}\right)$$



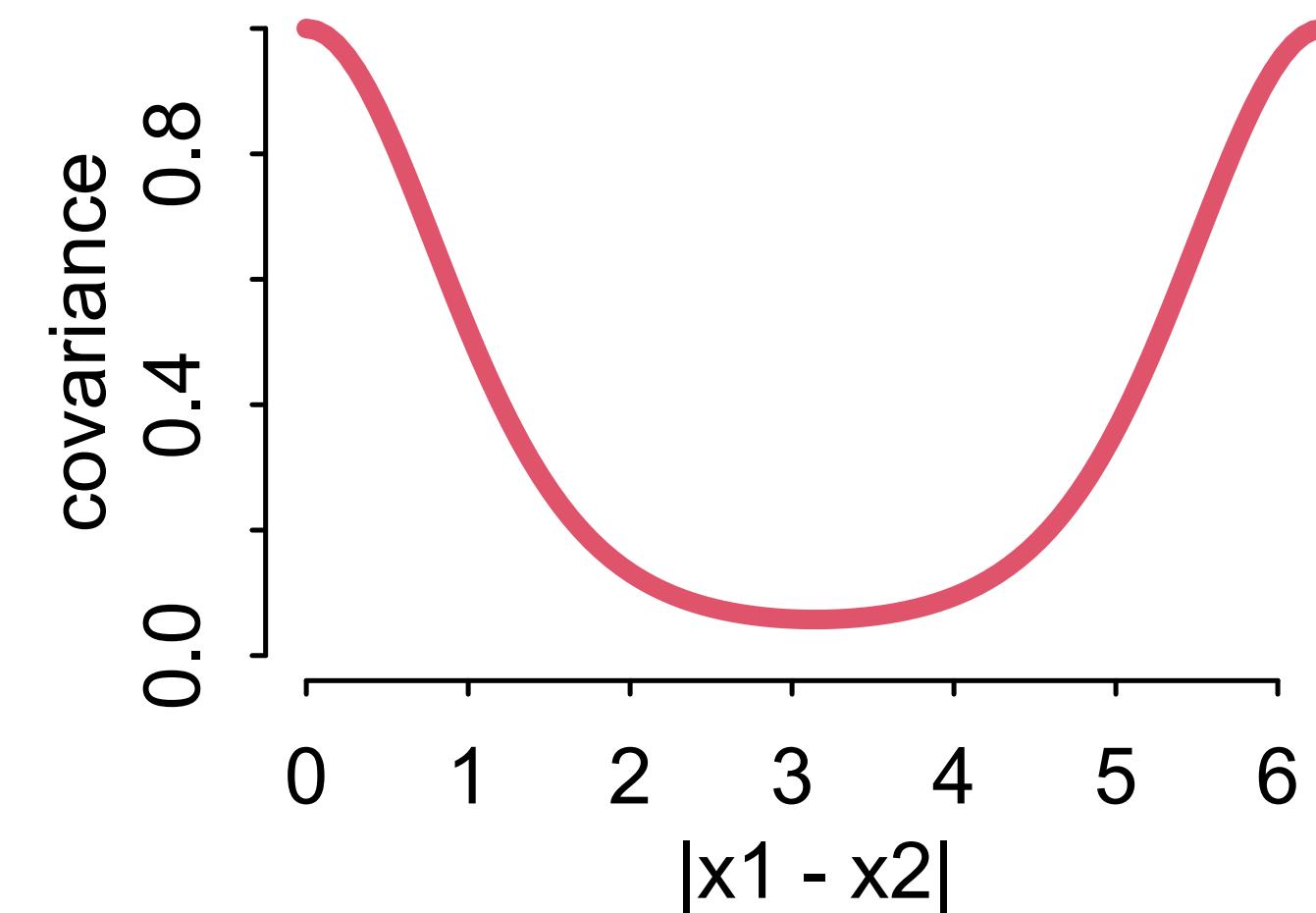
Ornstein-Uhlenbeck

$$k(x_1, x_2) = \alpha^2 \exp\left(-\frac{|x_1 - x_2|}{\sigma}\right)$$



Periodic

$$k(x_1, x_2) = \alpha^2 \exp\left(-\frac{2 \sin^2((x_1 - x_2)/2)}{\sigma^2}\right)$$



$$T_i \sim \text{Poisson}(\lambda_i)$$

$$\log \lambda_i = \bar{\alpha} + \alpha_{S[i]}$$

$$\begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_{10} \end{bmatrix} \sim \text{MVNormal} \left( \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \mathbf{K} \right)$$

$$k_{i,j} = \eta^2 \exp \left( -\rho^2 d_{i,j}^2 \right)$$

*covariance*      *maximum covariance*      *rate of decline*  
*distance  $i,j$*

$$T_i \sim \text{Poisson}(\lambda_i)$$

$$\log \lambda_i = \bar{\alpha} + \alpha_{S[i]}$$

$$\begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_{10} \end{bmatrix} \sim \text{MVNormal} \left( \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \mathbf{K} \right)$$

$$k_{i,j} = \eta^2 \exp\left(-\rho^2 d_{i,j}^2\right)$$

$$\bar{\alpha} \sim \text{Normal}(3, 0.5)$$

$$\eta^2 \sim \text{Exponential}(2)$$

$$\rho^2 \sim \text{Exponential}(0.5)$$

Distance matrix (thousand km)

	Ml	Ti	SC	Ya	Fi	Tr	Ch	Mn	To	Ha
Malekula	0.0	0.5	0.6	4.4	1.2	2.0	3.2	2.8	1.9	5.7
Tikopia	0.5	0.0	0.3	4.2	1.2	2.0	2.9	2.7	2.0	5.3
Santa Cruz	0.6	0.3	0.0	3.9	1.6	1.7	2.6	2.4	2.3	5.4
Yap	4.4	4.2	3.9	0.0	5.4	2.5	1.6	1.6	6.1	7.2
Lau Fiji	1.2	1.2	1.6	5.4	0.0	3.2	4.0	3.9	0.8	4.9
Trobriand	2.0	2.0	1.7	2.5	3.2	0.0	1.8	0.8	3.9	6.7
Chuuk	3.2	2.9	2.6	1.6	4.0	1.8	0.0	1.2	4.8	5.8
Manus	2.8	2.7	2.4	1.6	3.9	0.8	1.2	0.0	4.6	6.7
Tonga	1.9	2.0	2.3	6.1	0.8	3.9	4.8	4.6	0.0	5.0
Hawaii	5.7	5.3	5.4	7.2	4.9	6.7	5.8	6.7	5.0	0.0

*What do these priors imply?*

$$k_{i,j} = \eta^2 \exp\left(-\rho^2 d_{i,j}^2\right)$$

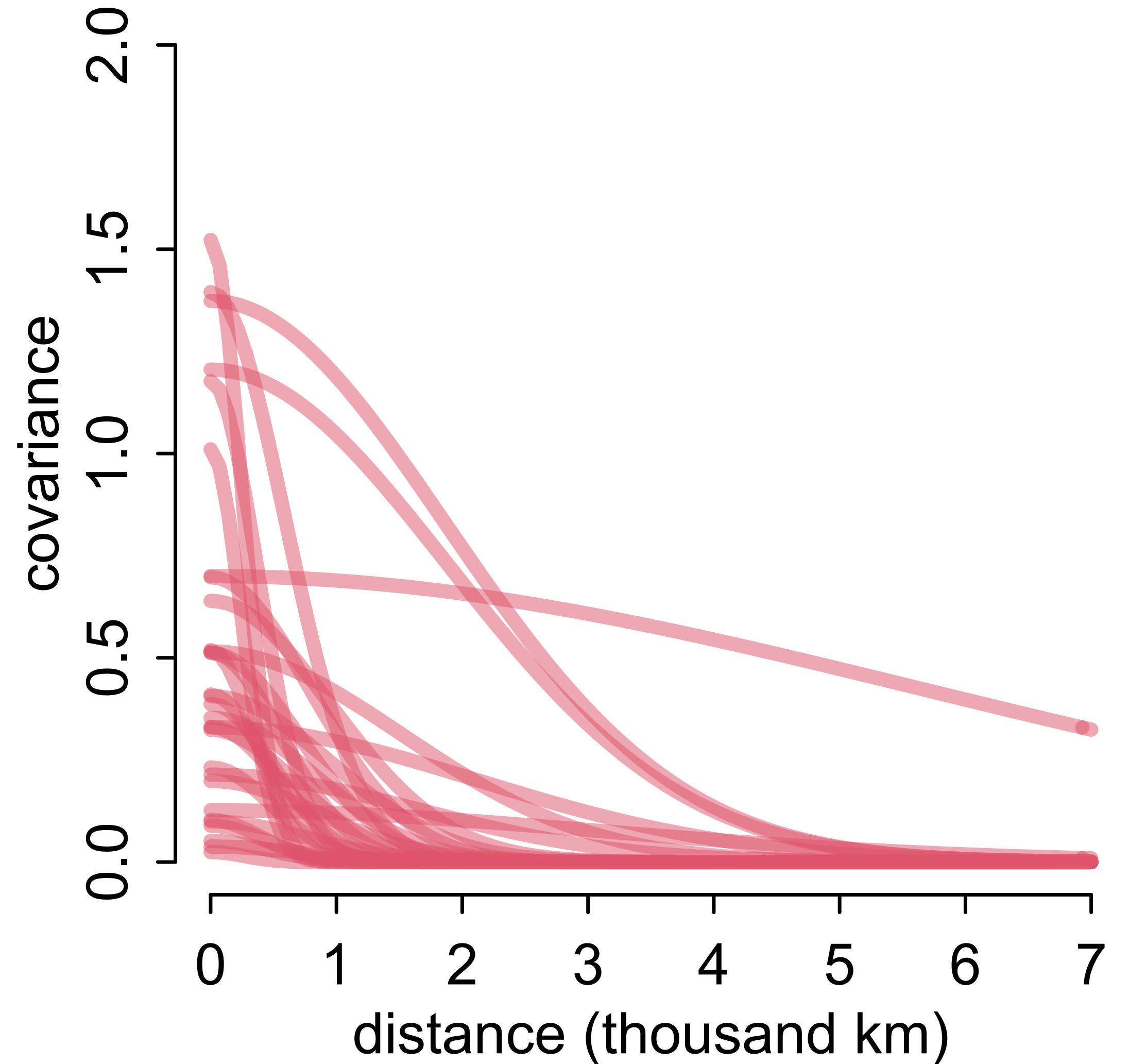
$$\eta^2 \sim \text{Exponential}(2)$$

$$\rho^2 \sim \text{Exponential}(0.5)$$

```
# sim priors for distance model
n <- 30
etasq <- rexp(n,2)
rhosq <- rexp(n,0.5)

plot( NULL , xlim=c(0,7) , ylim=c(0,2) ,
  xlab="distance (thousand km)" ,
  ylab="covariance" )

for ( i in 1:n )
  curve( etasq[i]*exp(-rhosq[i]*x^2) ,
    add=TRUE , lwd=4 ,
    col=col.alpha(2,0.5) )
```



## Distance matrix (thousand km)

$$T_i \sim \text{Poisson}(\lambda_i)$$

$$\log \lambda_i = \bar{\alpha} + \alpha_{S[i]}$$

$$\begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_{10} \end{bmatrix} \sim \text{MVNormal} \left( \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \mathbf{K} \right)$$

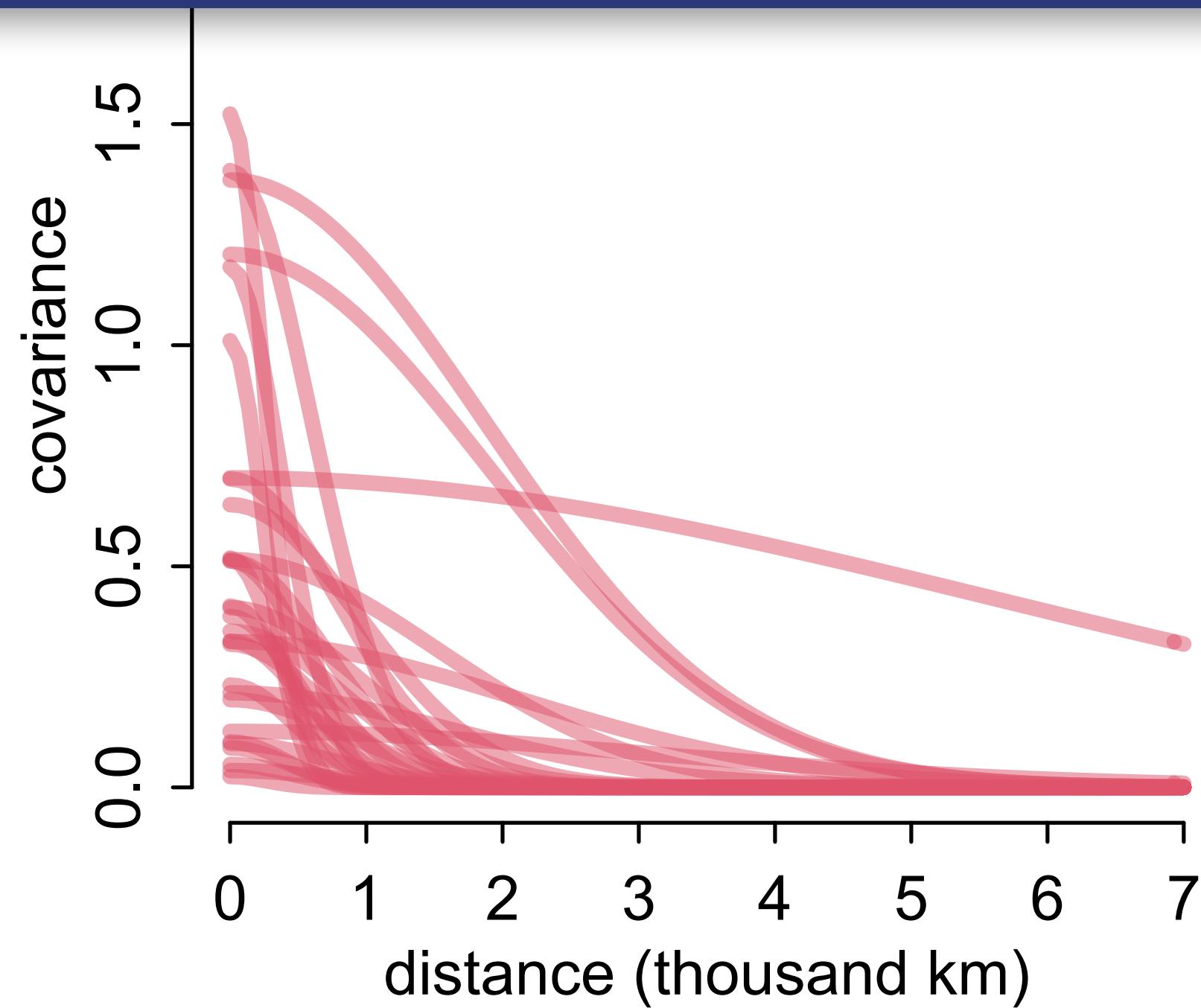
$$k_{i,j} = \eta^2 \exp \left( -\rho^2 d_{i,j}^2 \right)$$

$$\bar{\alpha} \sim \text{Normal}(3, 0.5)$$

$$\eta^2 \sim \text{Exponential}(2)$$

$$\rho^2 \sim \text{Exponential}(0.5)$$

	Ml	Ti	SC	Ya	Fi	Tr	Ch	Mn	To	Ha
Malekula	0.0	0.5	0.6	4.4	1.2	2.0	3.2	2.8	1.9	5.7
Tikopia	0.5	0.0	0.3	4.2	1.2	2.0	2.9	2.7	2.0	5.3
Santa Cruz	0.6	0.3	0.0	3.9	1.6	1.7	2.6	2.4	2.3	5.4
Yap	4.4	4.2	3.9	0.0	5.4	2.5	1.6	1.6	6.1	7.2
Lau Fiji	1.2	1.2	1.6	5.4	0.0	3.2	4.0	3.9	0.8	4.9
Trobriand	2.0	2.0	1.7	2.5	3.2	0.0	1.8	0.8	3.9	6.7
Chuuk	3.2	2.9	2.6	1.6	4.0	1.8	0.0	1.2	4.8	5.8
Manus	2.8	2.7	2.4	1.6	3.9	0.8	1.2	0.0	4.6	6.7
Tonga	1.9	2.0	2.3	6.1	0.8	3.9	4.8	4.6	0.0	5.0
Hawaii	5.7	5.3	5.4	7.2	4.9	6.7	5.8	6.7	5.0	0.0



```

data(Kline2)
d <- Kline2
data(islandsDistMatrix)

dat_list <- list(
  T = d$total_tools,
  S = 1:10,
  D = islandsDistMatrix )

mTdist <- ulam(
  alist(
    T ~ dpois(lambda),
    log(lambda) <- abar + a[S],
    vector[10]:a ~ multi_normal( 0 , K ),
    matrix[10,10]:K <- cov_GPL2(D,etasq,rhosq,0.01),
    abar ~ normal(3,0.5),
    etasq ~ dexp( 2 ),
    rhosq ~ dexp( 0.5 )
  ), data=dat_list , chains=4 , cores=4 , iter=4000 )

```

$$T_i \sim \text{Poisson}(\lambda_i)$$

$$\log \lambda_i = \bar{\alpha} + \alpha_{S[i]}$$

$$\begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_{10} \end{bmatrix} \sim \text{MVNormal} \left( \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \mathbf{K} \right)$$

$$k_{i,j} = \eta^2 \exp \left( -\rho^2 d_{i,j}^2 \right)$$

$$\bar{\alpha} \sim \text{Normal}(3,0.5)$$

$$\eta^2 \sim \text{Exponential}(2)$$

$$\rho^2 \sim \text{Exponential}(0.5)$$

$$T_i \sim \text{Poisson}(\lambda_i)$$

$$\log \lambda_i = \bar{\alpha} + \alpha_{S[i]}$$

```

data(Kline2)
d <- Kline2
data(islandsDistMatrix)

dat_list <- list(
  T = d$total_tools,
  S = 1:10,
  D = islandsDistMatrix )

mTdist <- ulam(
  alist(
    T ~ dpois(lambda),
    log(lambda) <- abar + a[S],
    vector[10]:a ~ multi_normal( 0 , K ),
    matrix[10,10]:K <- cov_GPL2(D,etasq,rhosq,0.01),
    abar ~ normal(3,0.5),
    etasq ~ dexp( 2 ),
    rhosq ~ dexp( 0.5 )
  ), data=dat_list , chains=4 , cores=4 , iter=4000 )

```

$$\begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_{10} \end{bmatrix} \sim \text{MVNormal} \left( \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \mathbf{K} \right)$$

$$k_{i,j} = \eta^2 \exp \left( -\rho^2 d_{i,j}^2 \right)$$

$$\bar{\alpha} \sim \text{Normal}(3,0.5)$$

$$\eta^2 \sim \text{Exponential}(2)$$

$$\rho^2 \sim \text{Exponential}(0.5)$$

$$T_i \sim \text{Poisson}(\lambda_i)$$

$$\log \lambda_i = \bar{\alpha} + \alpha_{S[i]}$$

```

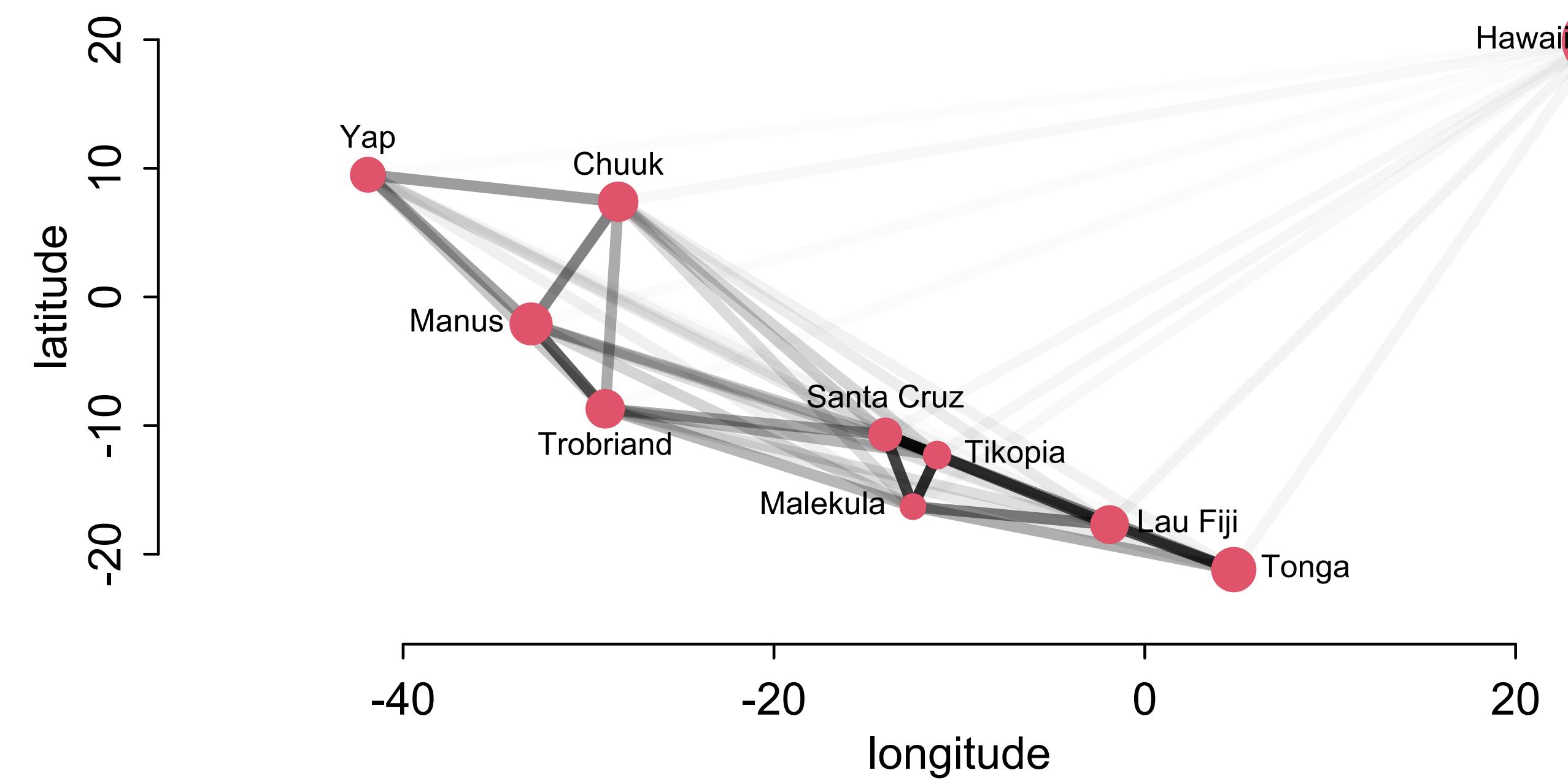
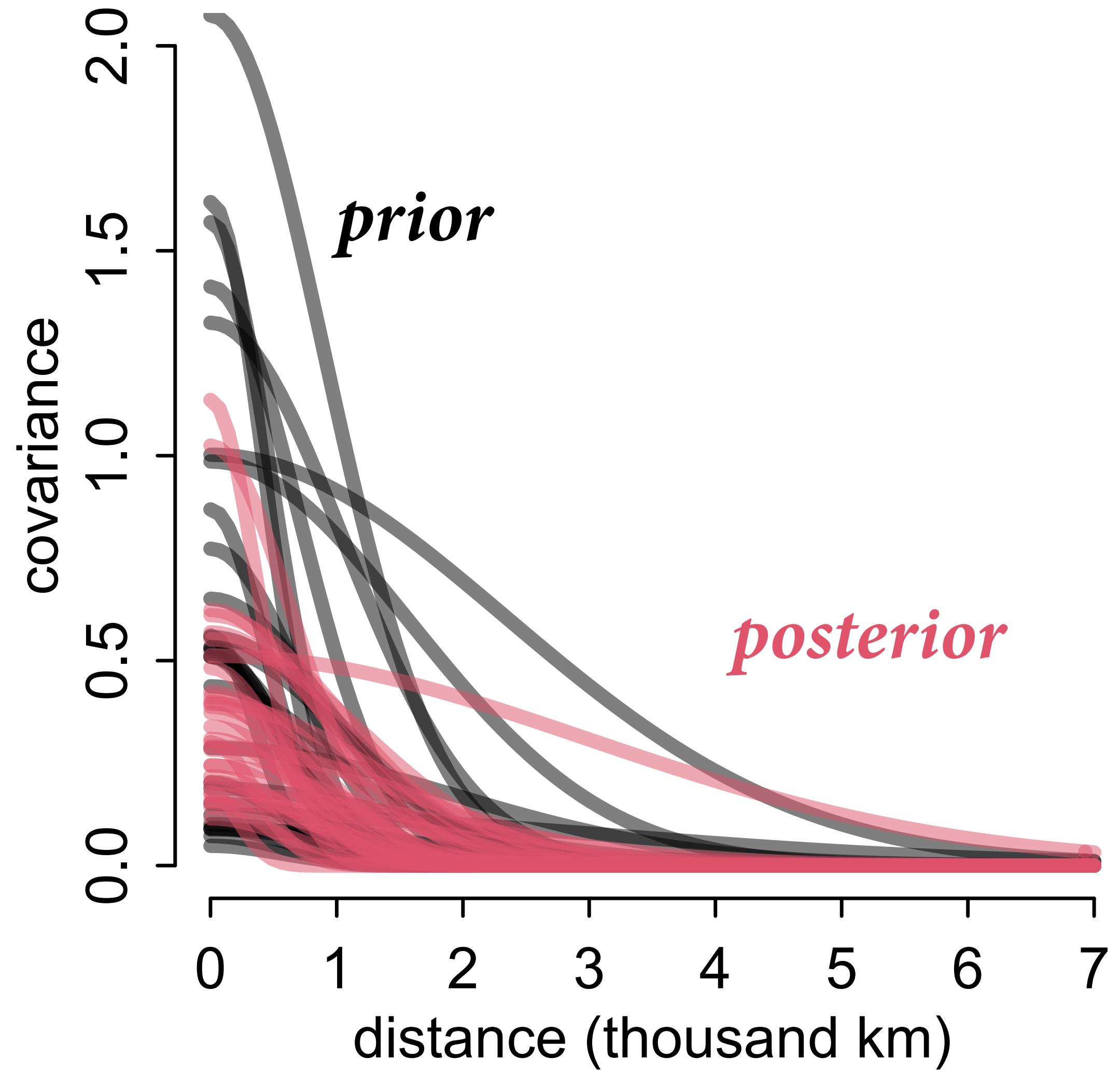
data(Kline2)
d <- Kline2
data(islandsDistMatrix)

dat_list <- list(
  T = d$total_tools,
  S = 1:10,
  D = islandsDistMatrix )

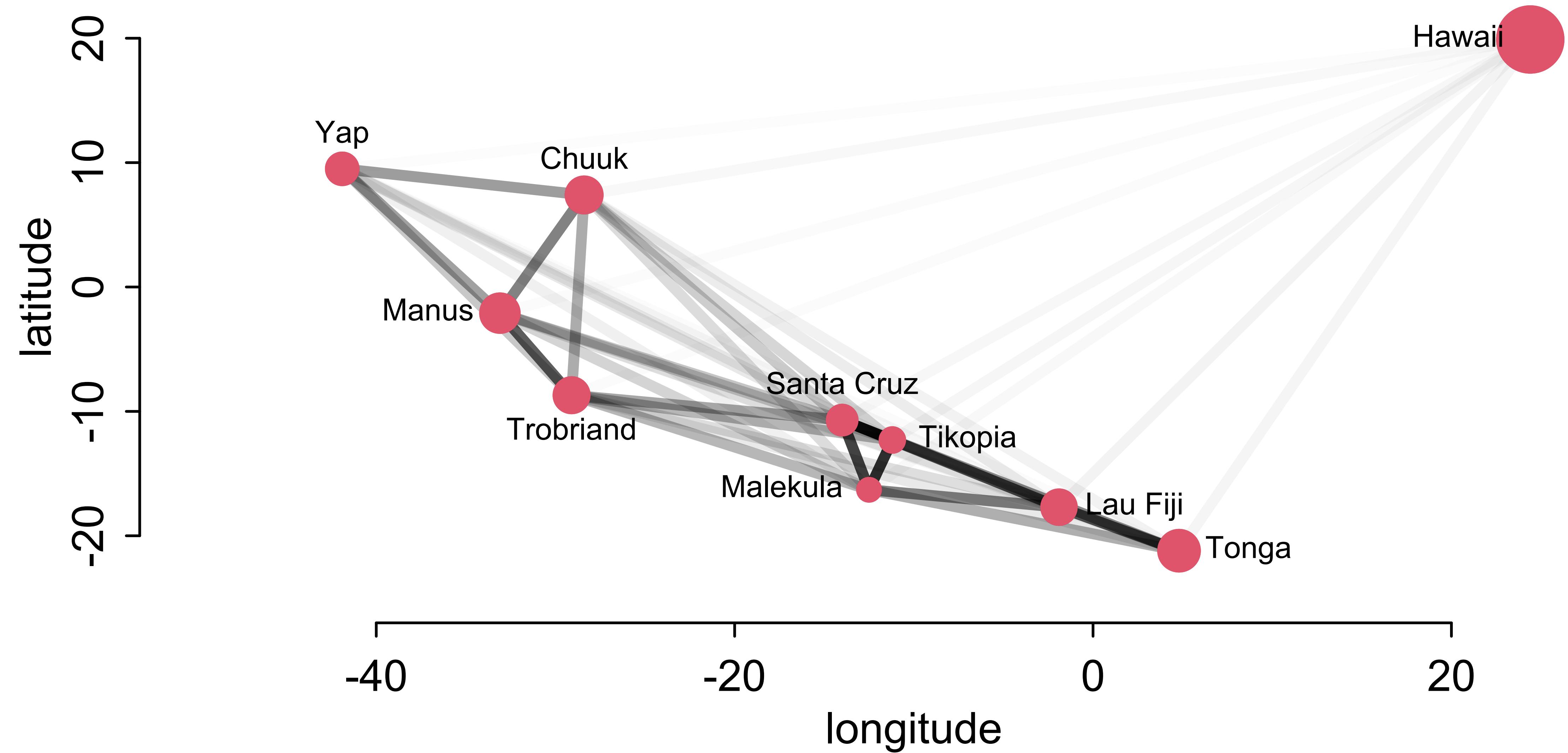
mTdist <- ulam(
  alist(
    T ~ dpois(lambda),
    log(lambda) <- abar + a[S],
    vector[10]:a ~ multi_normal( 0
      matrix[10,10]:K <- cov_GPL2(D,epsilon),
    abar ~ normal(3,0.5),
    etasq ~ dexp( 2 ),
    rhosq ~ dexp( 0.5 )
  ), data=dat_list , chains=4 , cores=4 )

```

	> precis(mTdist,2)					
	mean	sd	5.5%	94.5%	n_eff	Rhat4
a[1]	-0.67	0.31	-1.16	-0.18	1385	1
a[2]	-0.43	0.30	-0.89	0.06	1075	1
a[3]	-0.38	0.30	-0.87	0.10	1137	1
a[4]	0.24	0.28	-0.20	0.71	1133	1
a[5]	0.02	0.29	-0.44	0.49	1124	1
a[6]	-0.48	0.30	-0.96	-0.01	1303	1
a[7]	0.16	0.29	-0.28	0.63	1154	1
a[8]	-0.17	0.30	-0.65	0.29	1164	1
a[9]	0.45	0.28	0.01	0.90	1053	1
a[10]	0.73	0.27	0.30	1.18	1027	1
abar	3.49	0.25	3.08	3.88	896	1
etasq	0.38	0.27	0.12	0.87	1989	1
rhosq	1.09	1.39	0.08	3.68	3302	1



# Pure spatial covariance, nothing else



# Stratify by population size

```
dat_list <- list(  
  T = d$total_tools,  
  P = d$population,  
  S = 1:10,  
  D = islandsDistMatrix )  
  
mTDP <- ulam(  
  alist(  
    T ~ dpois(lambda),  
    lambda <- (abar*P^b/g)*exp(a[S]),  
    vector[10]:a ~ multi_normal( 0 , K ),  
    transpars> matrix[10,10]:K <-  
      cov_GPL2(D,etasq,rhosq,0.01),  
    c(abar,b,g) ~ dexp( 1 ),  
    etasq ~ dexp( 2 ),  
    rhosq ~ dexp( 0.5 )  
) , data=dat_list , chains=4 , cores=4 , iter=4000 )
```

$$T_i \sim \text{Poisson}(\lambda_i)$$

$$\lambda_i = \frac{\bar{\alpha} P^\beta}{\gamma} \exp(\alpha_{S[i]})$$

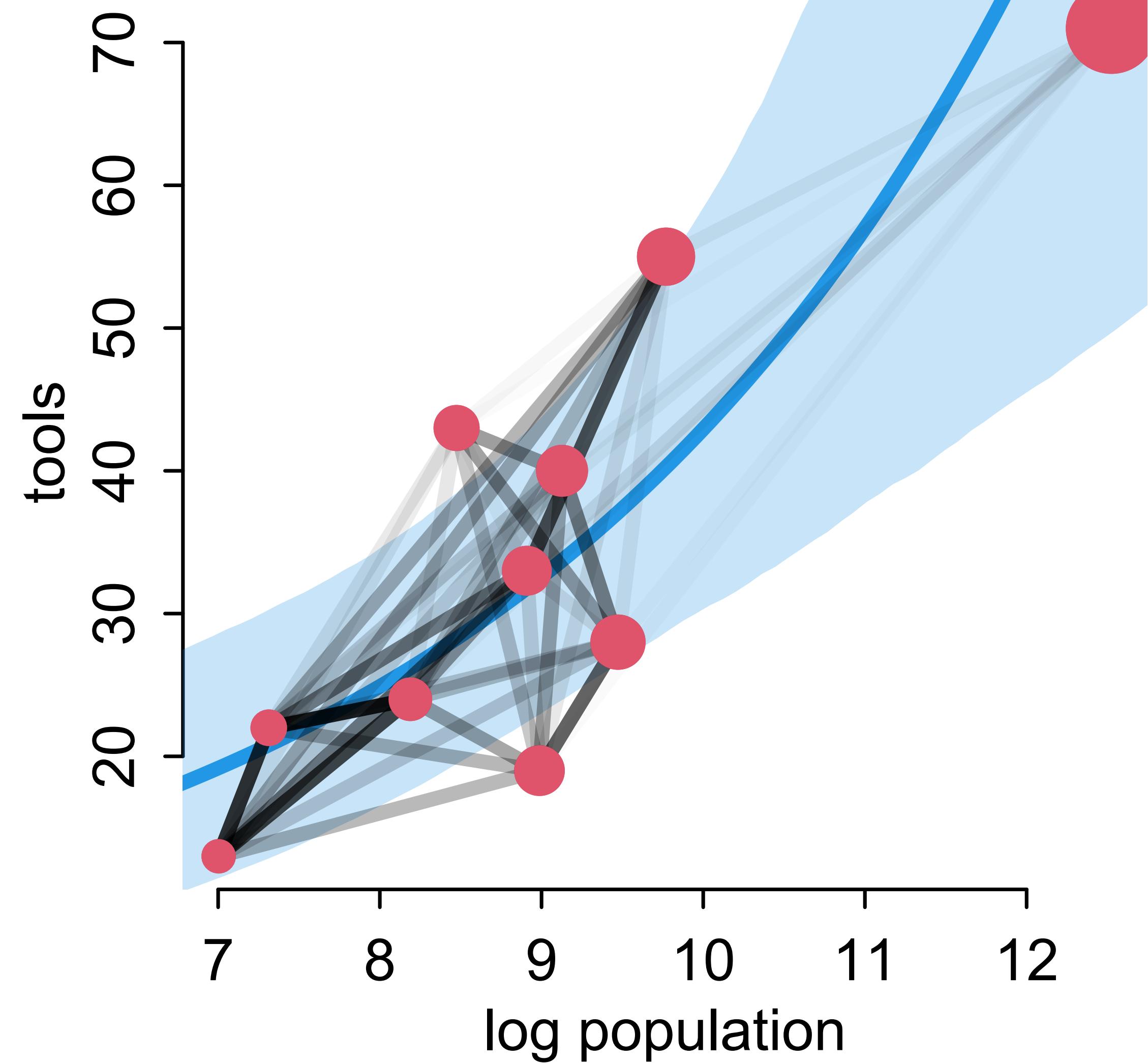
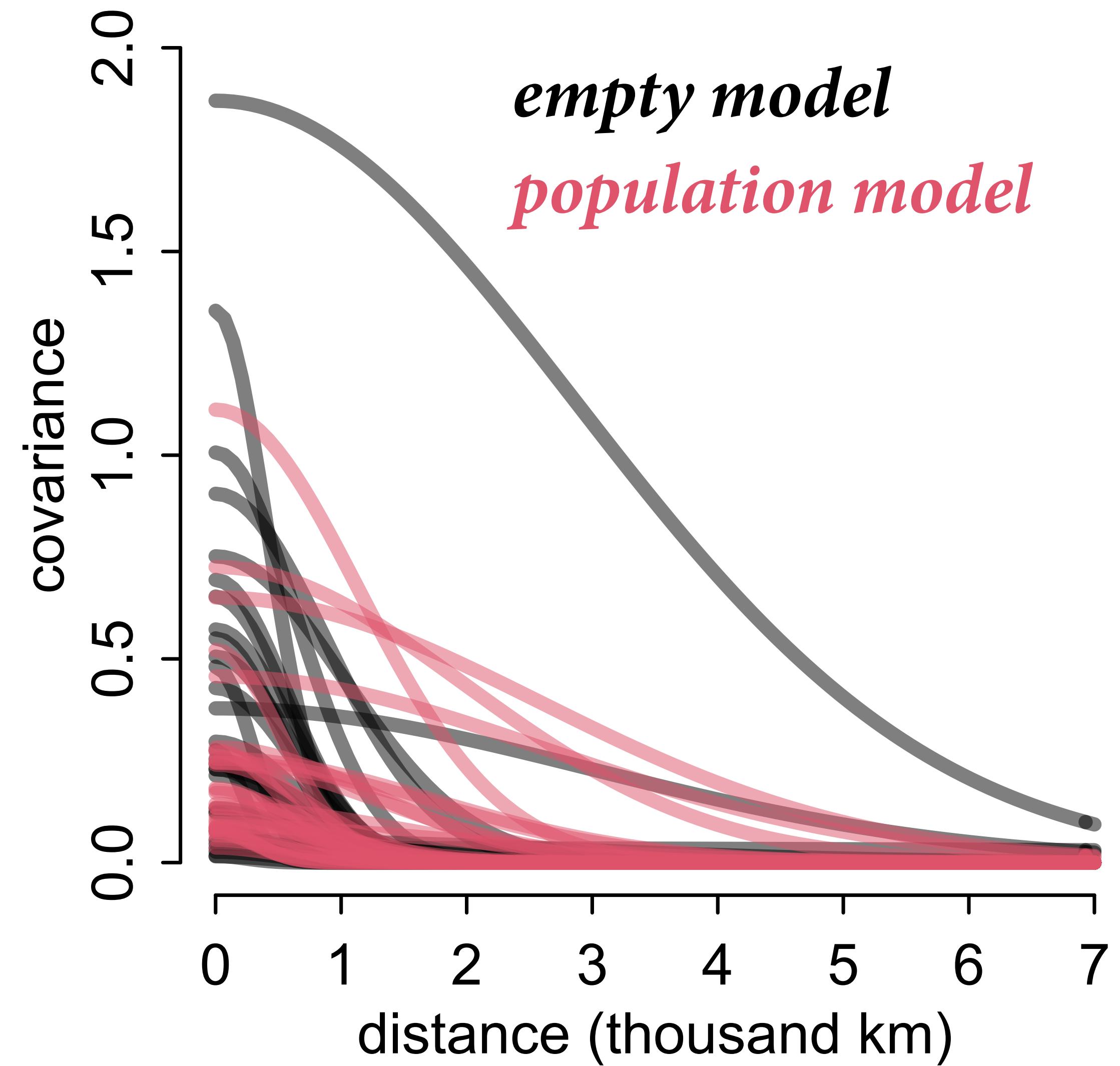
$$\begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_{10} \end{bmatrix} \sim \text{MVNormal} \left( \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \mathbf{K} \right)$$

$$k_{i,j} = \eta^2 \exp(-\rho^2 d_{i,j}^2)$$

$$\bar{\alpha}, \beta, \gamma \sim \text{Exponential}(1)$$

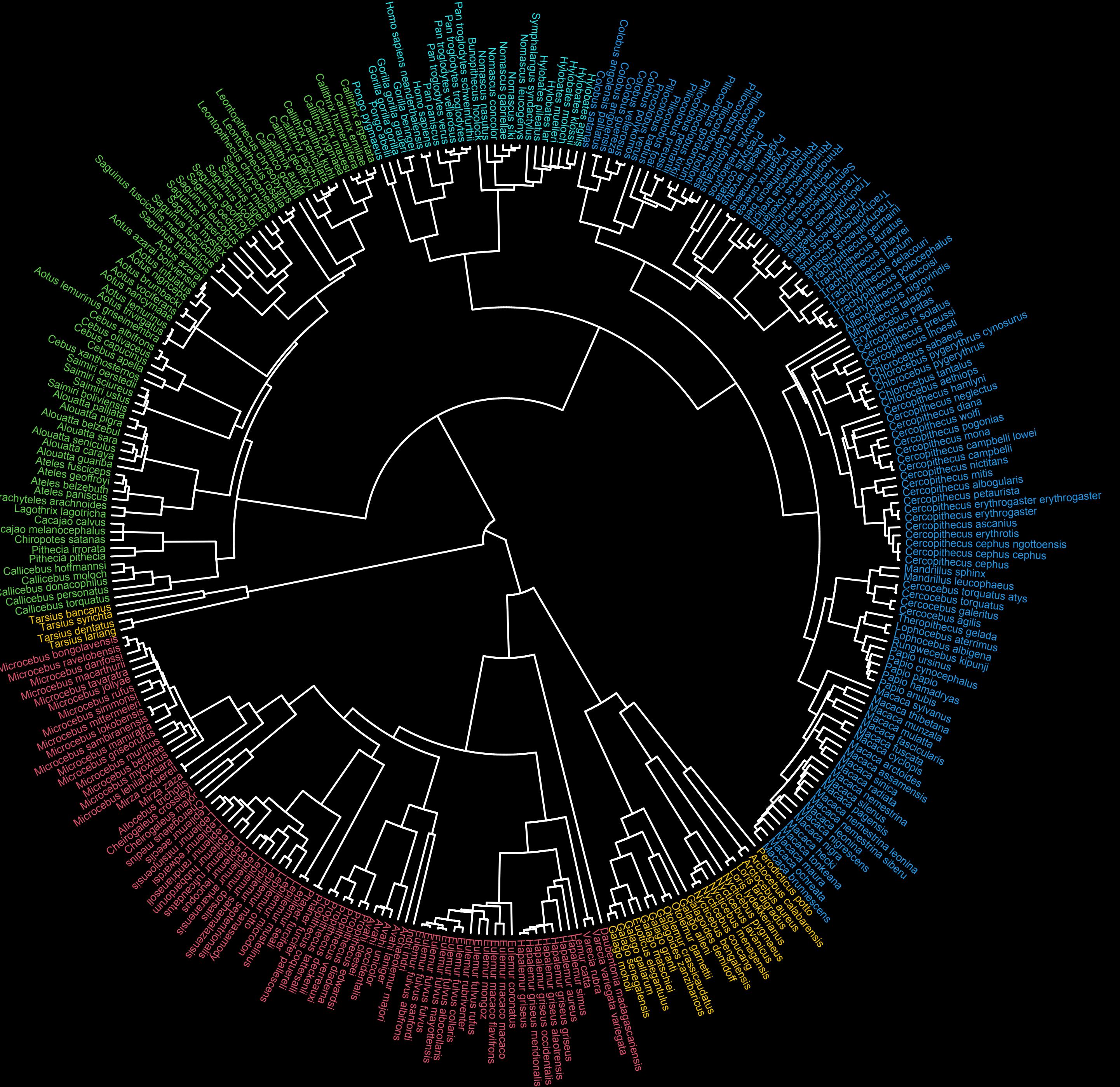
$$\eta^2 \sim \text{Exponential}(2)$$

$$\rho^2 \sim \text{Exponential}(0.5)$$



**PAUSE**

# Primates

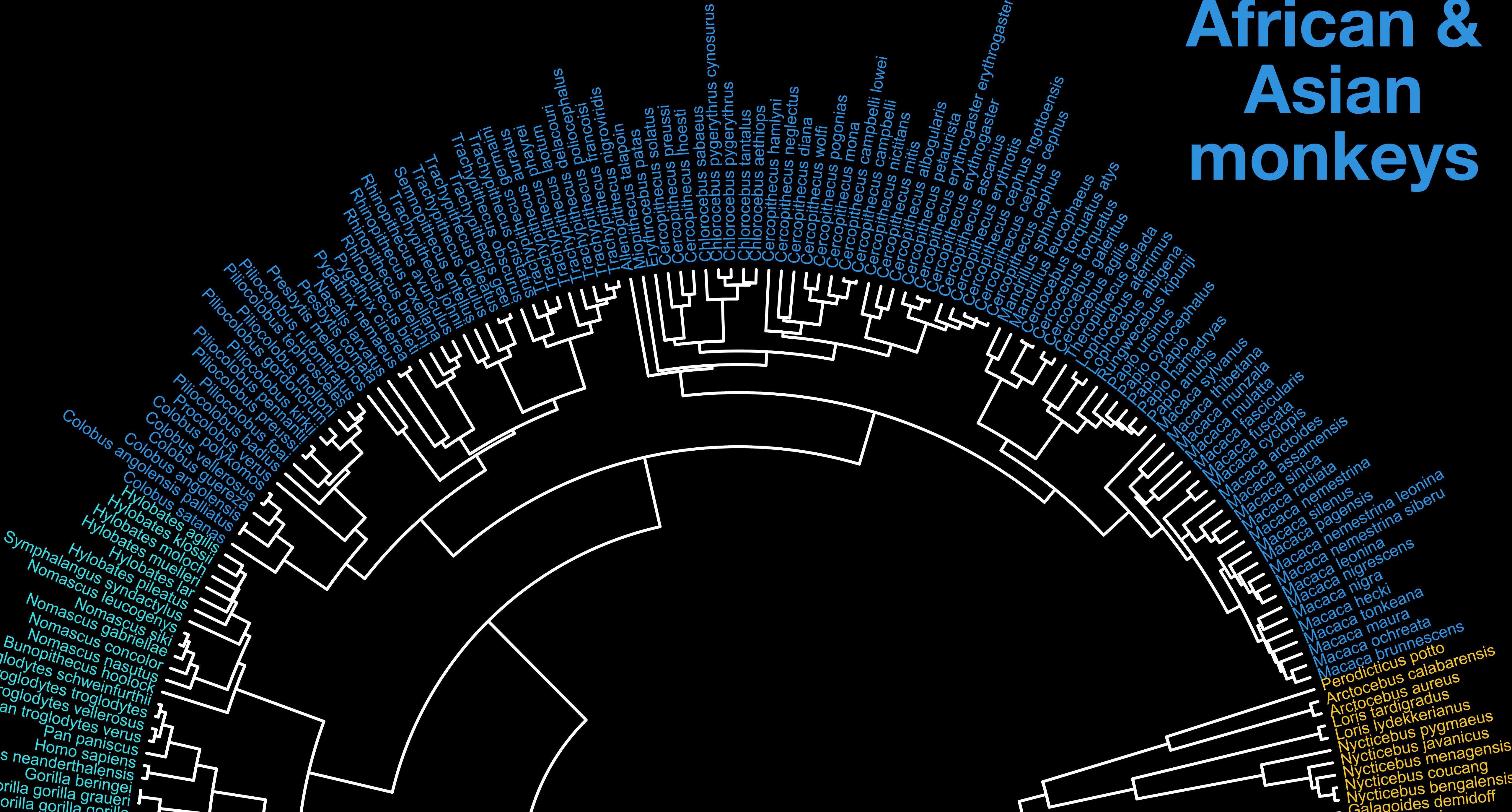




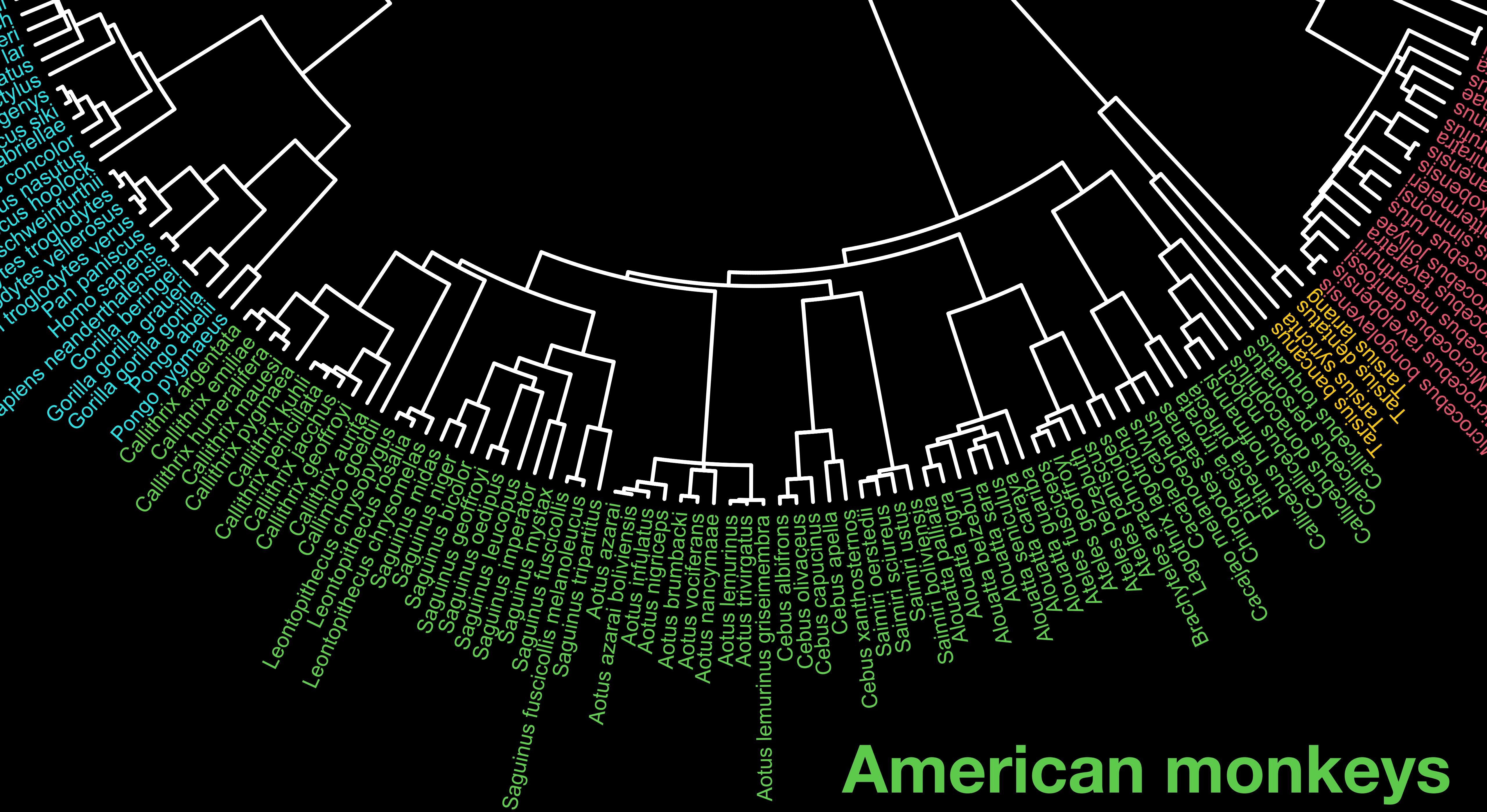
# Apes



# African & Asian monkeys



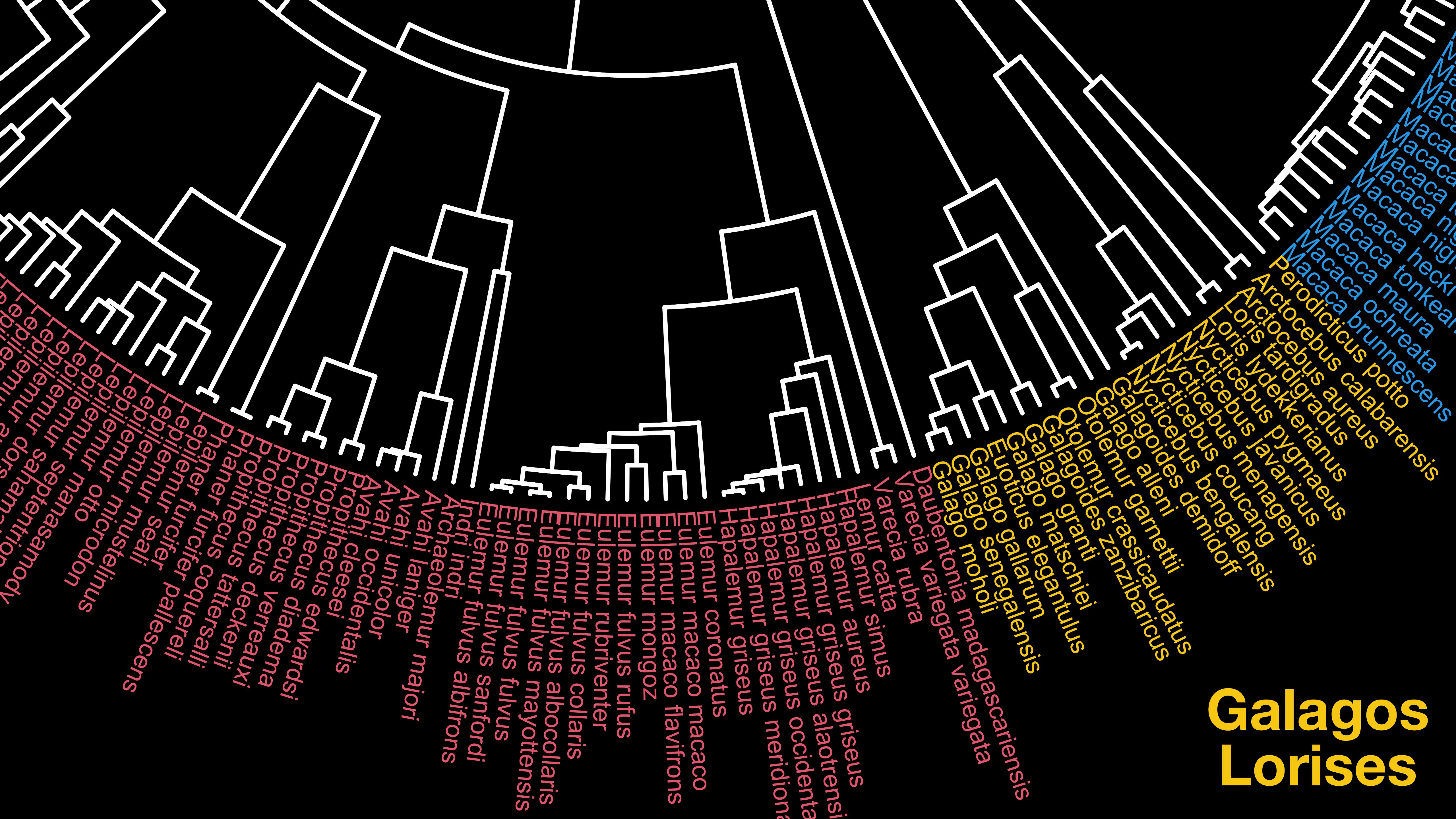
# American monkeys



# Tarsiers

# Lemurs etc

# Galagos Lorisés





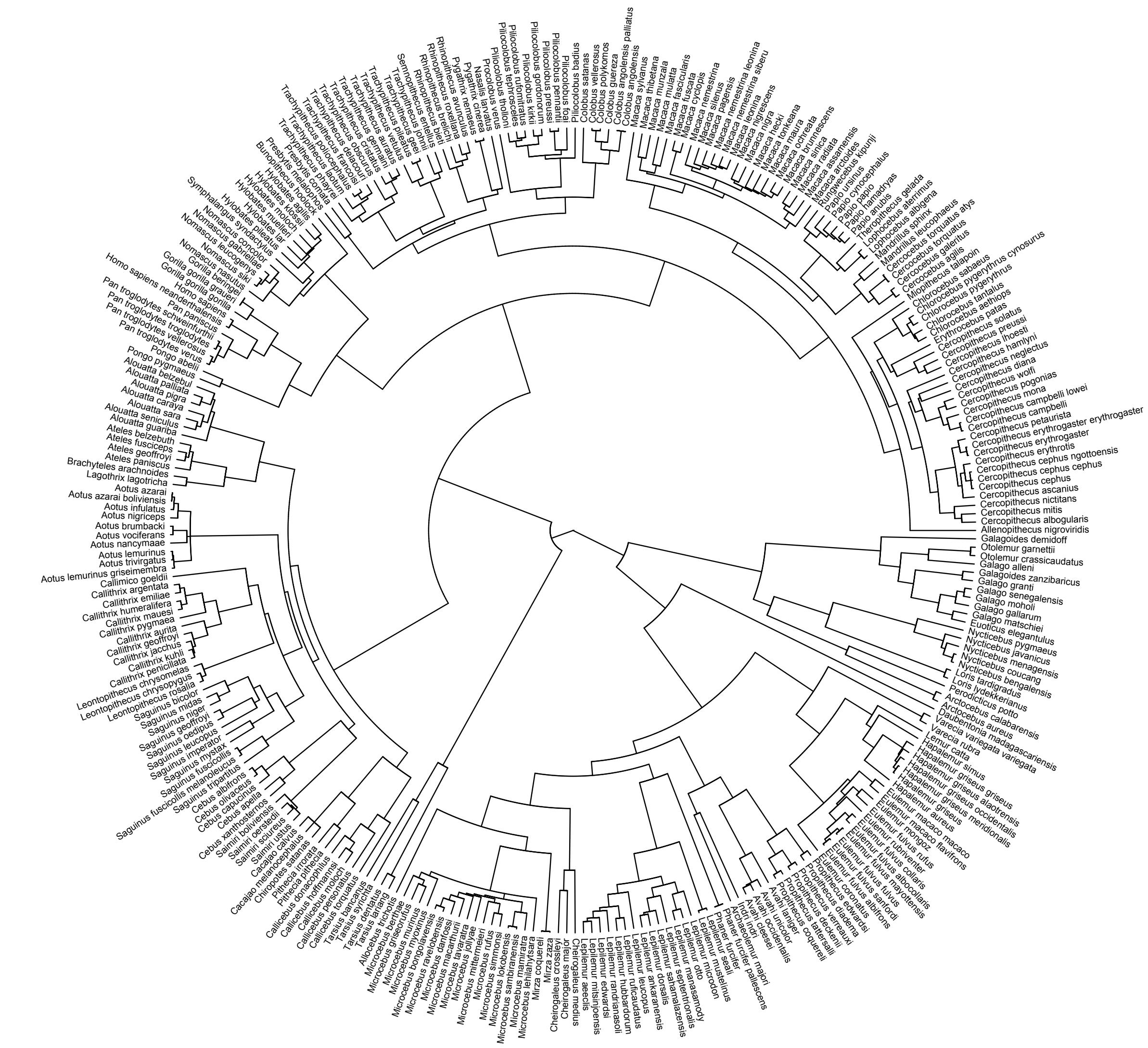
# Phylogenetic regression

```
data(Primates301)
```

# Life history traits

# Mass g, brain cc, group size

Much missing data,  
measurement error, unobserved  
confounding

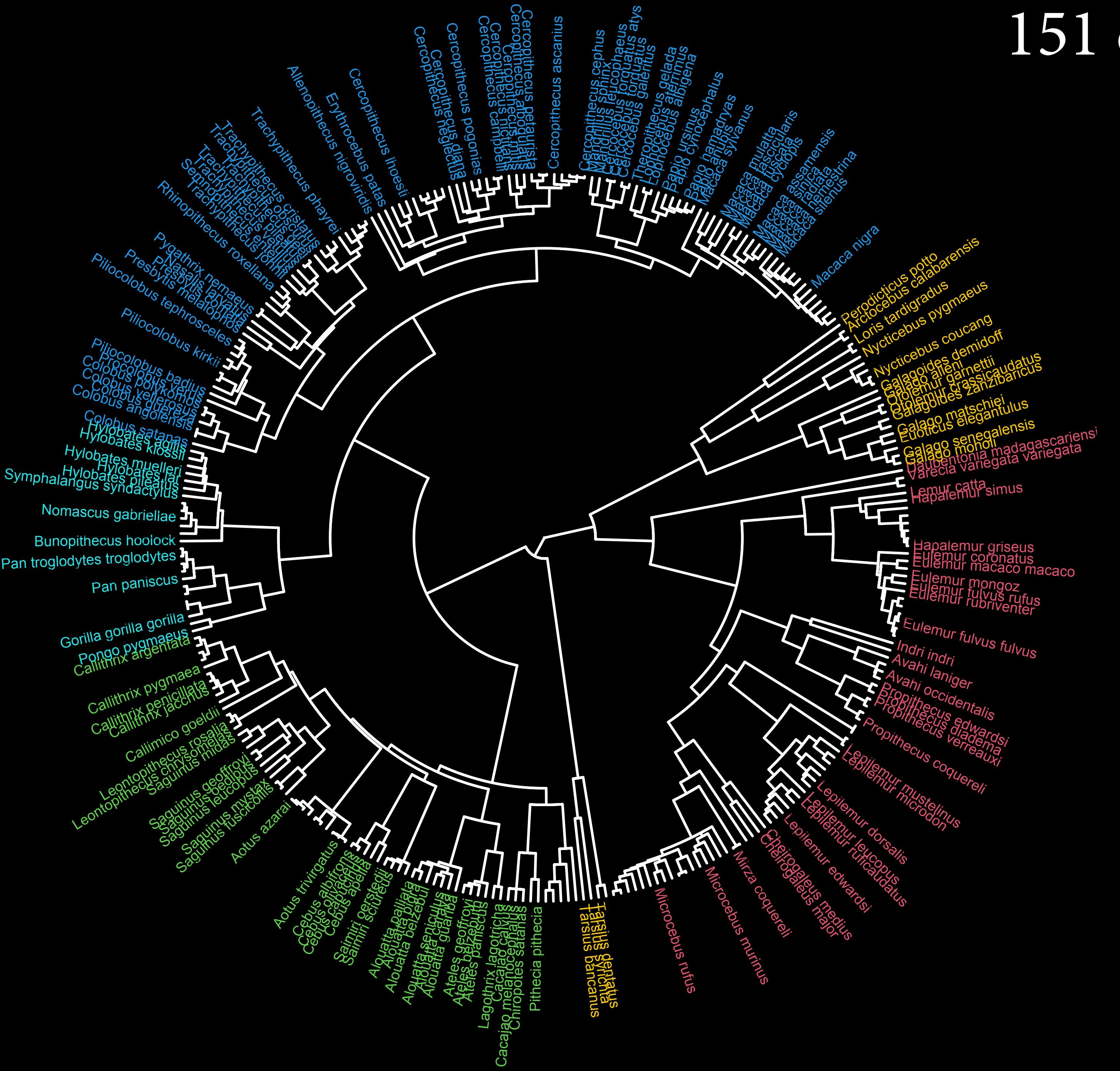


# 301 species

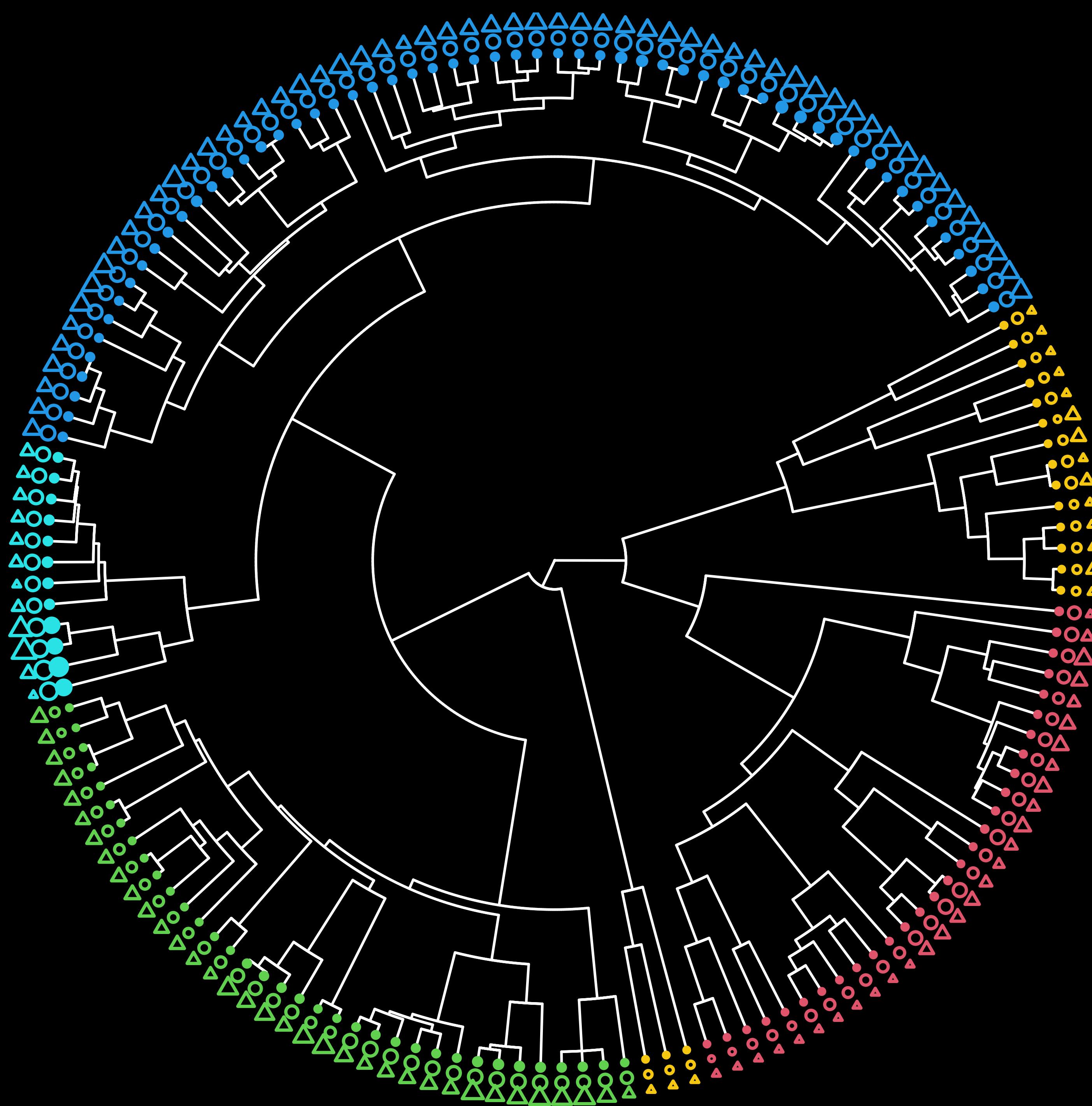


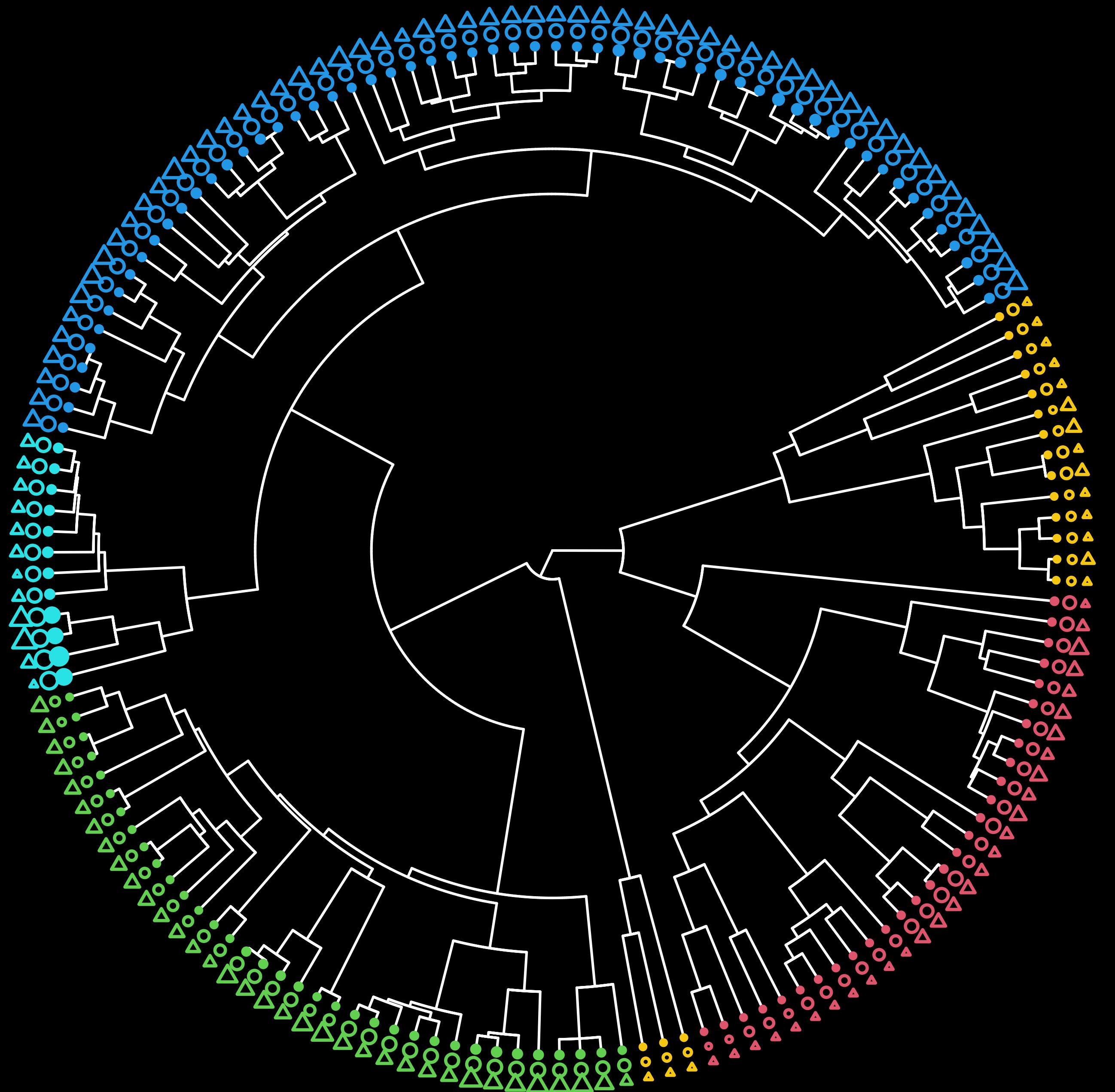
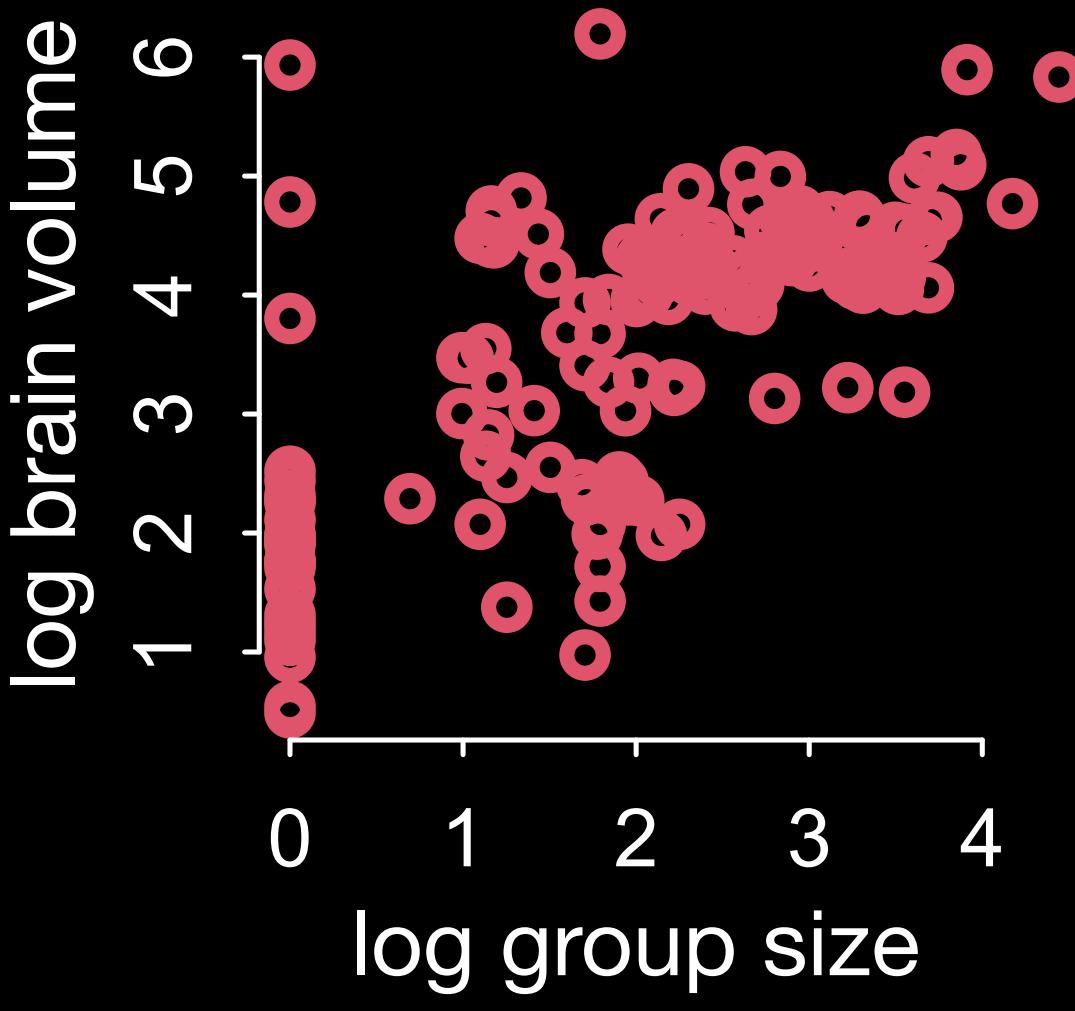
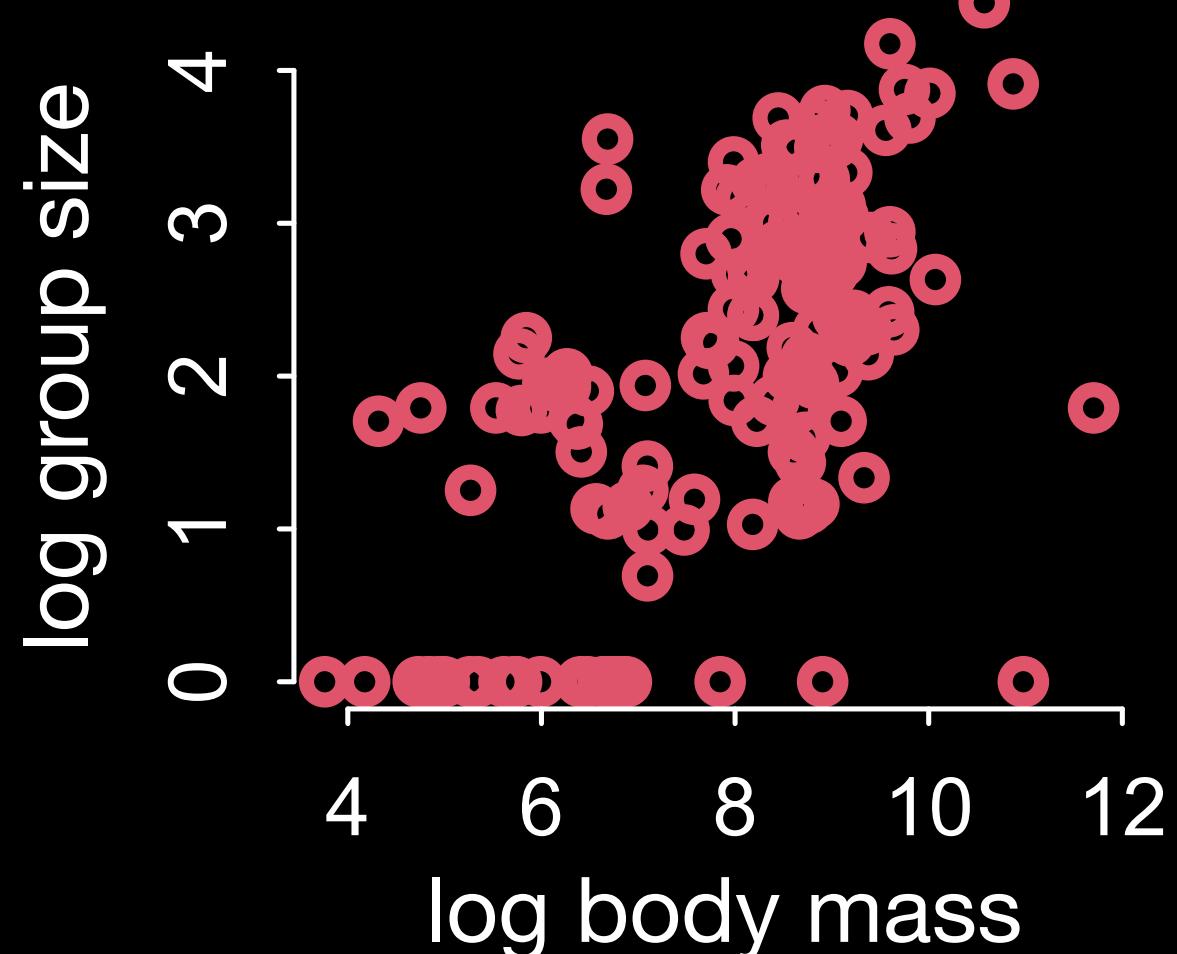
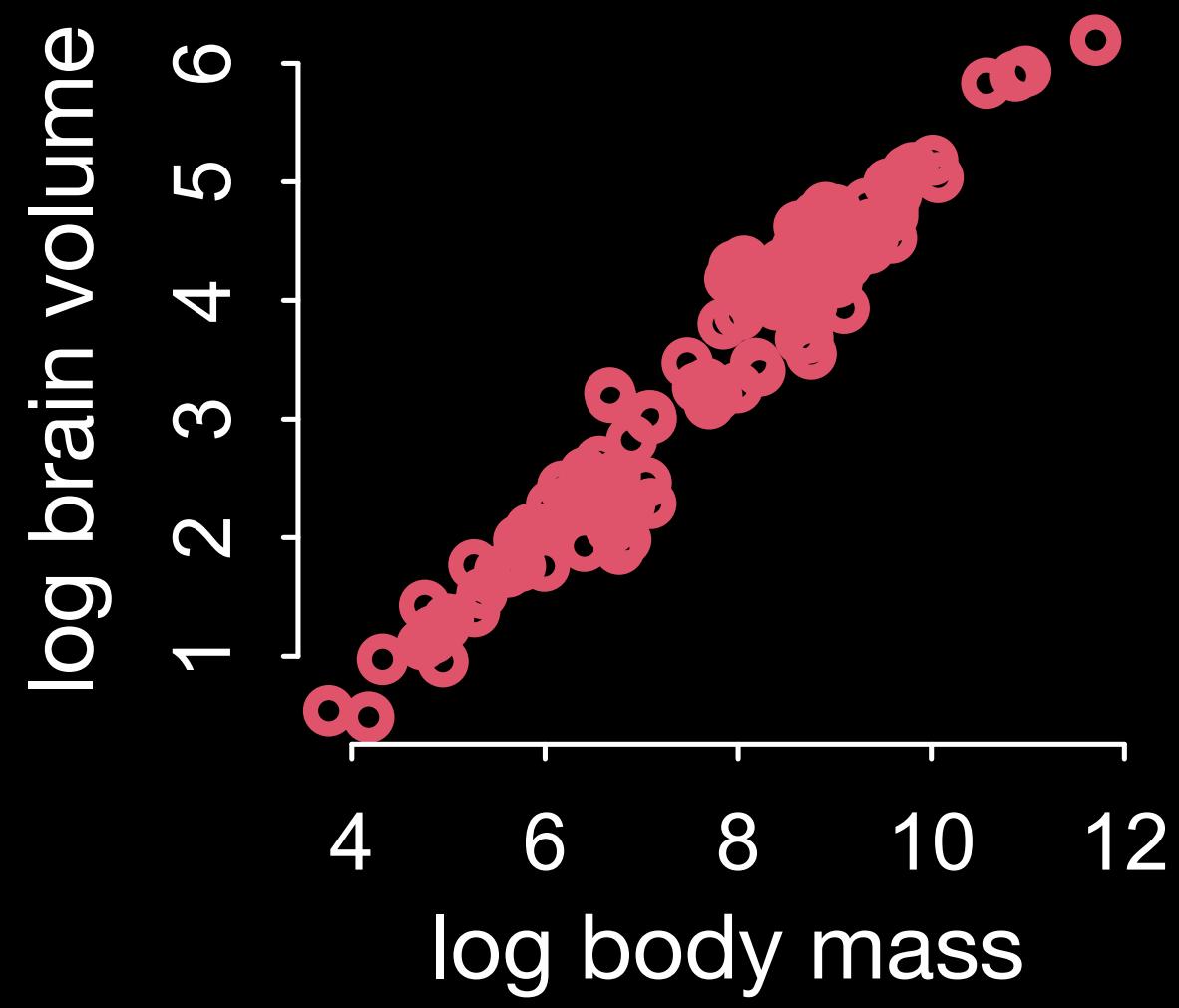
# 301 species

# 151 complete cases



- Brain vol (cc)
- Mass (log kg)
- △ Group size (log)





# Causal Salad in Evolutionary Ecology

Phylogenetic comparative methods  
dominated by causal salad

*Causal salad*: Tossing factors into  
regression and interpreting every  
coefficient as causal

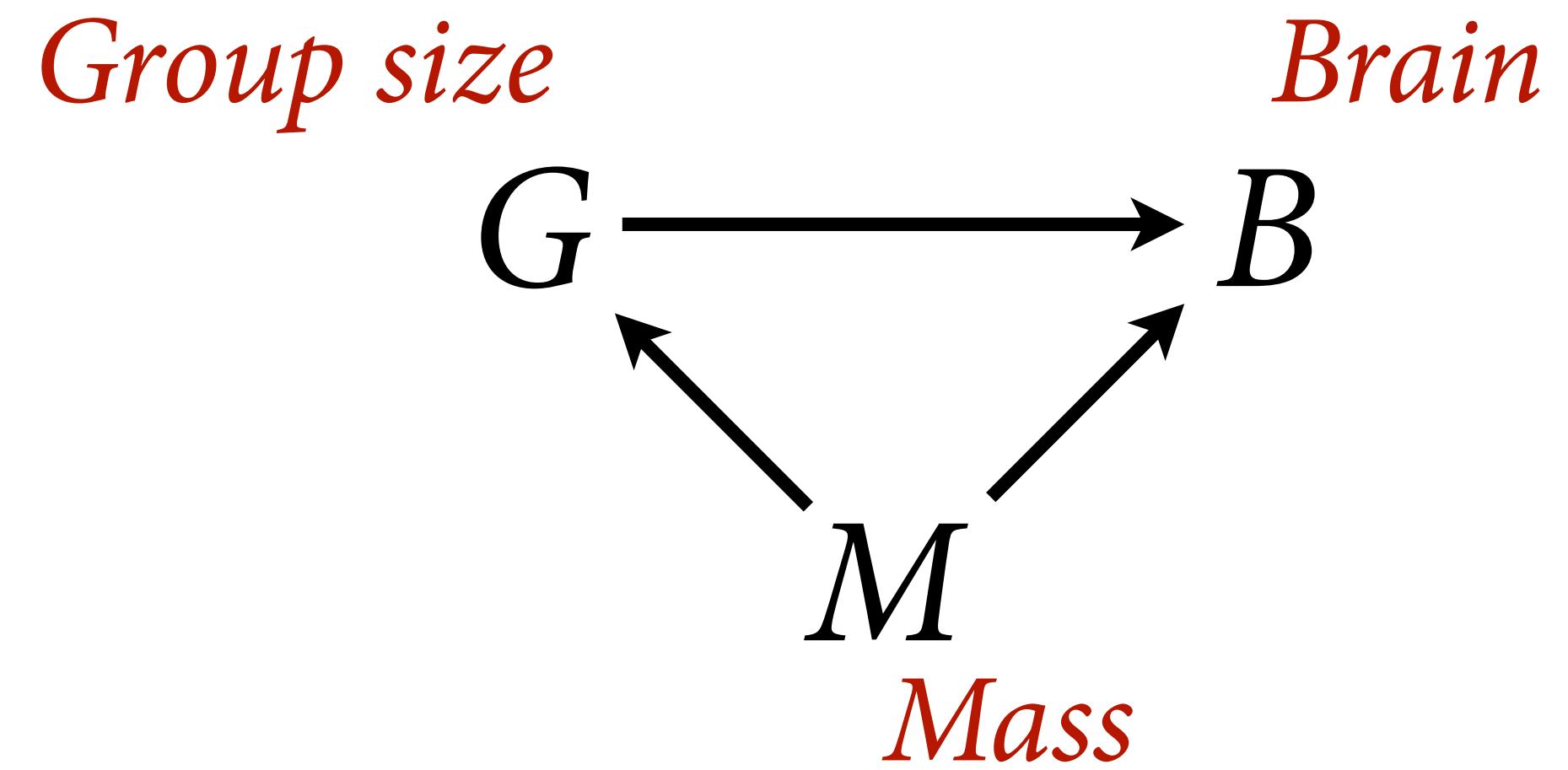
“Controlling for phylogeny”: Required  
but mindless

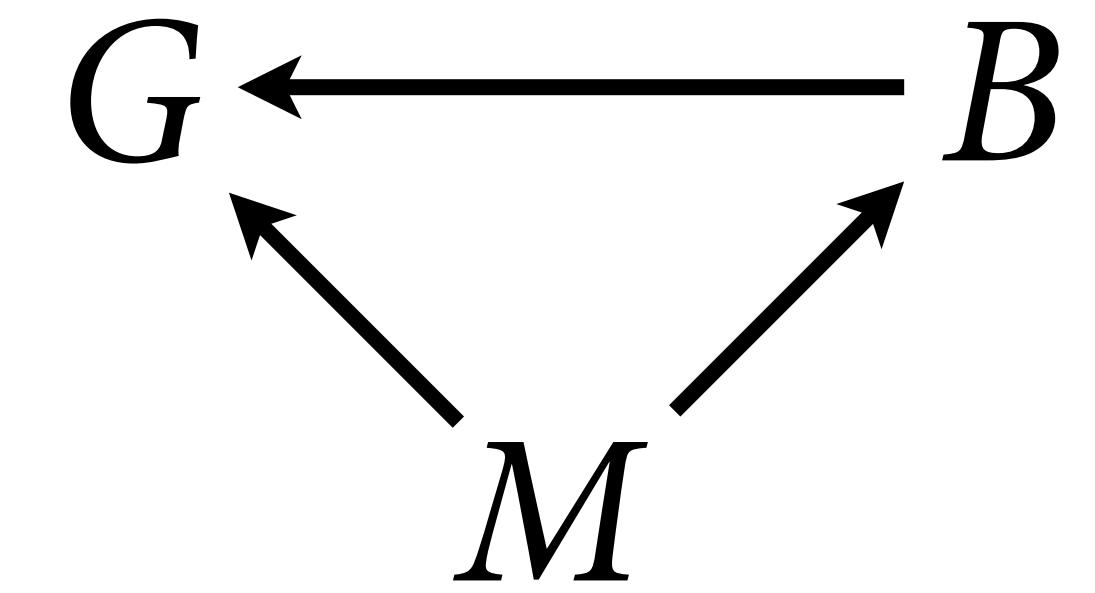
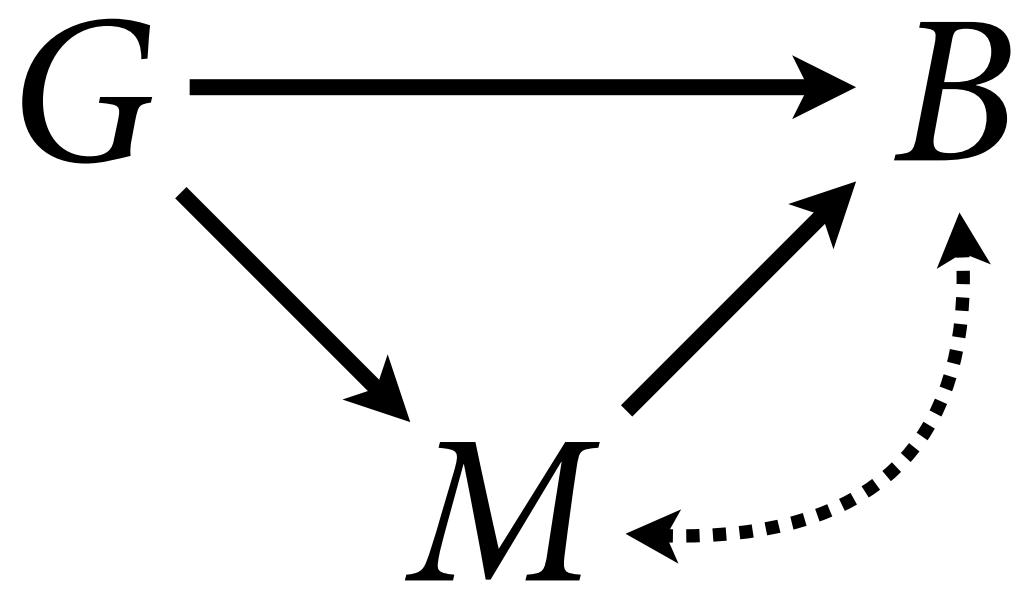
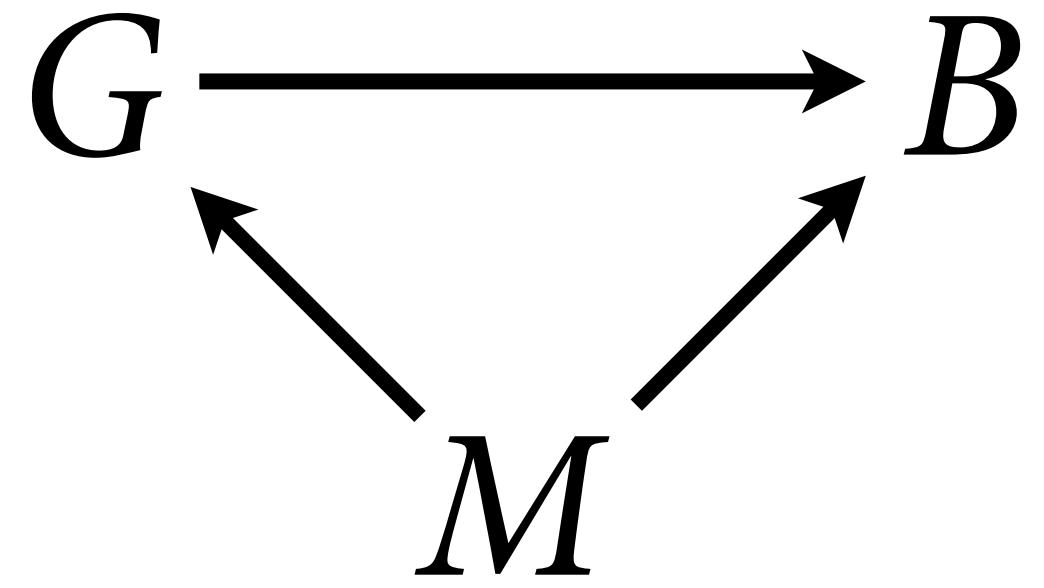
Regression + phylogeny still requires  
causal model



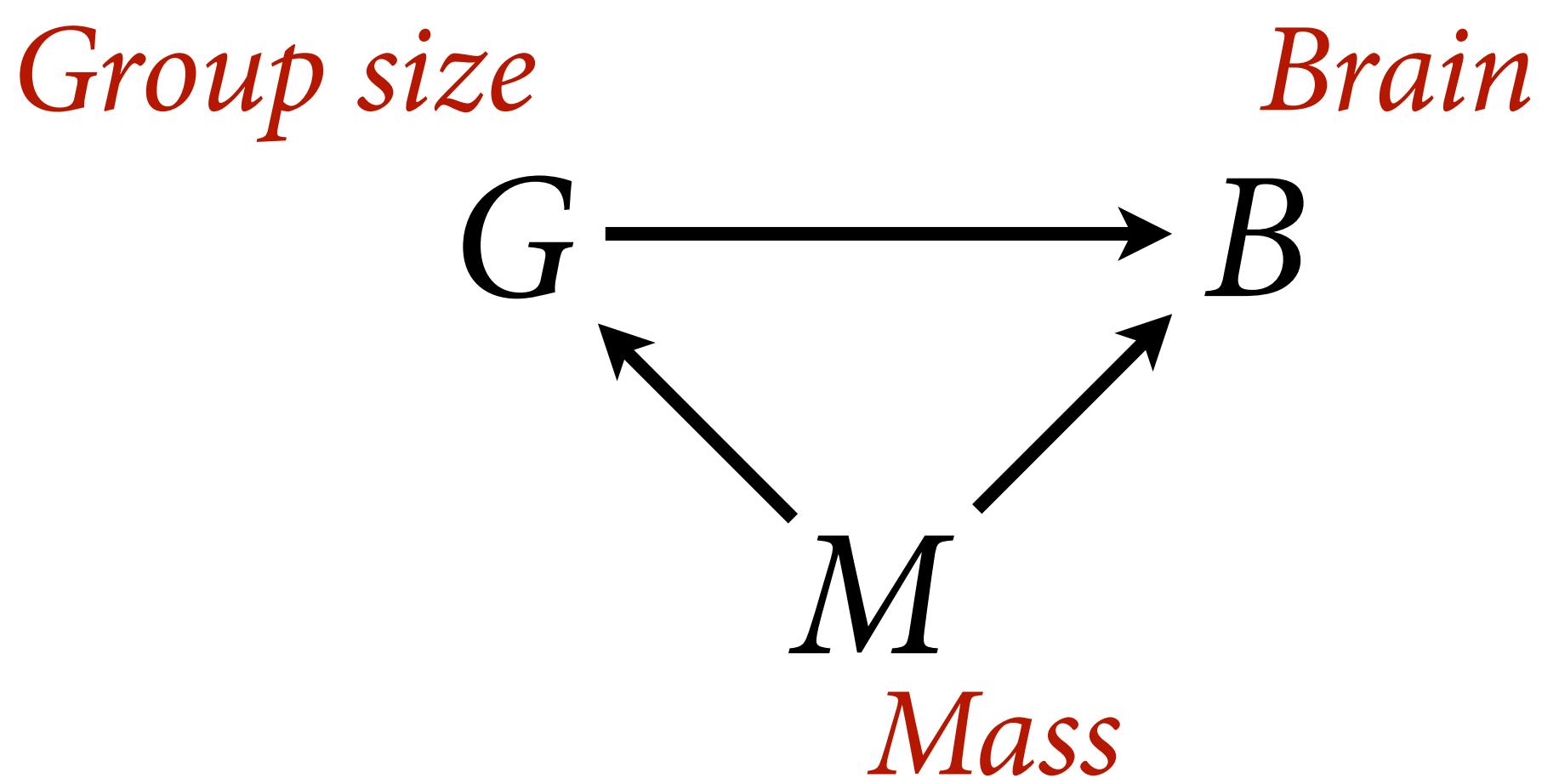
Illustration by Julia Suits

# Social brain hypothesis

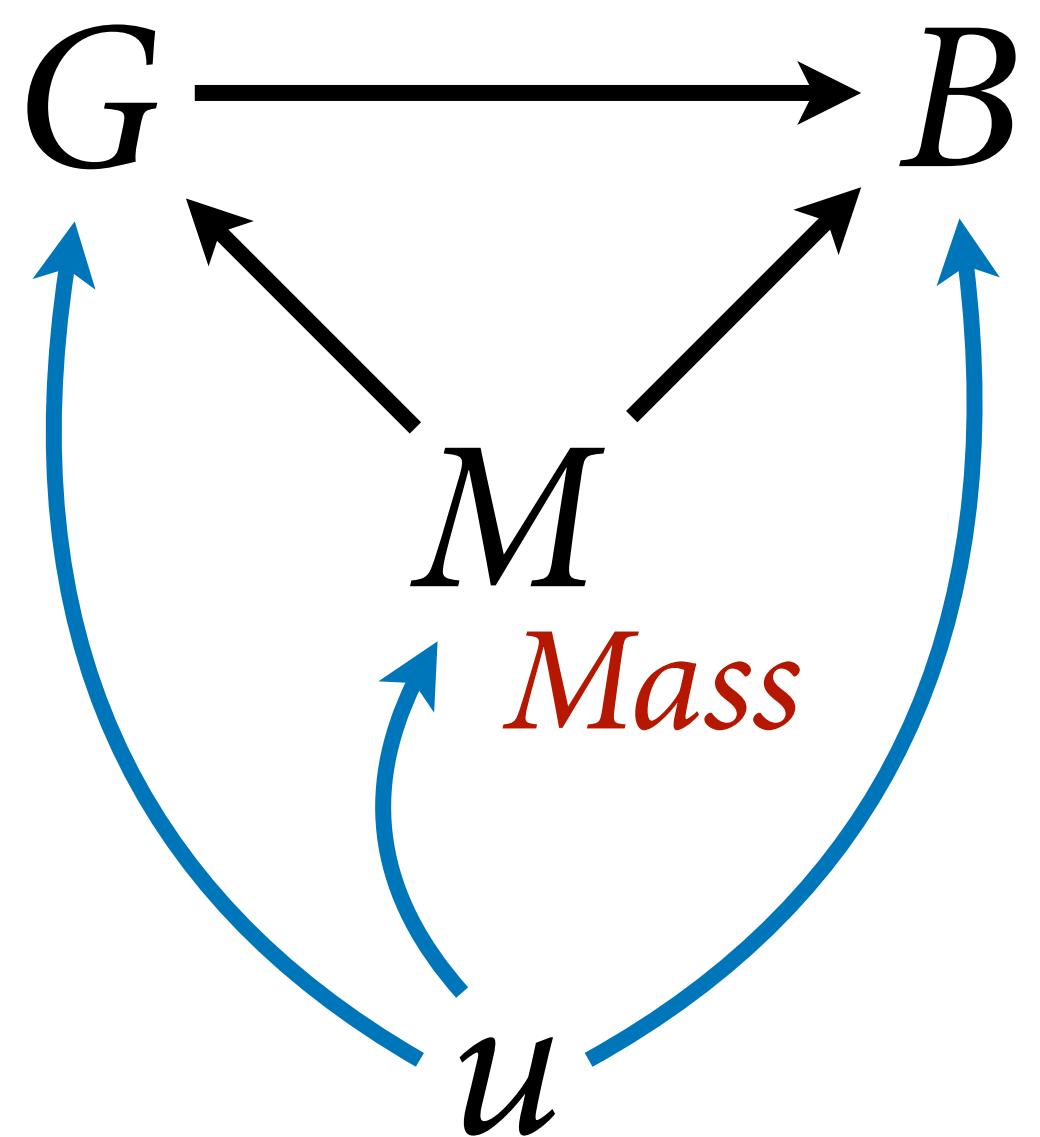


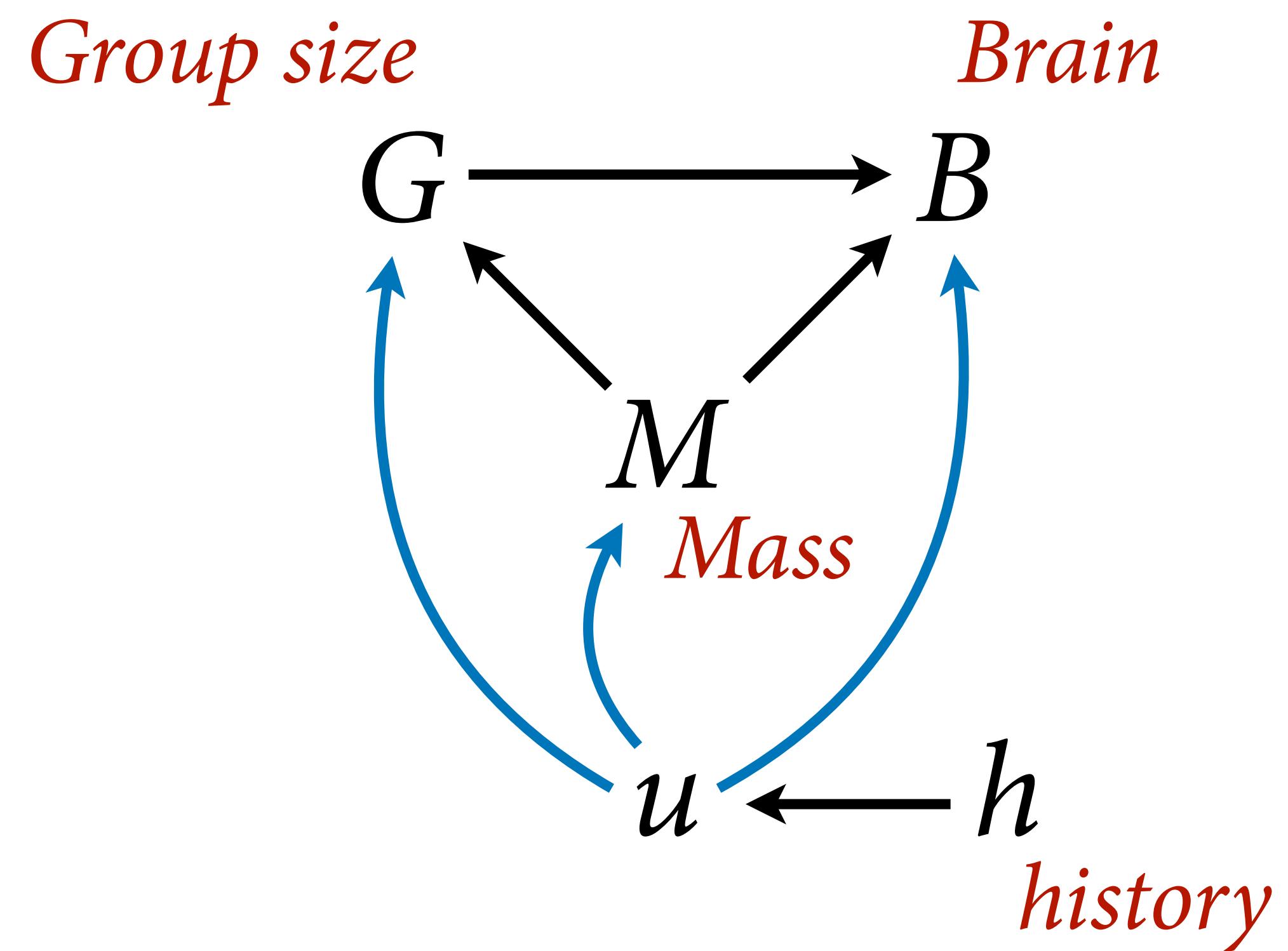


*No interpretation without causal representation*



*Group size*      *Brain*

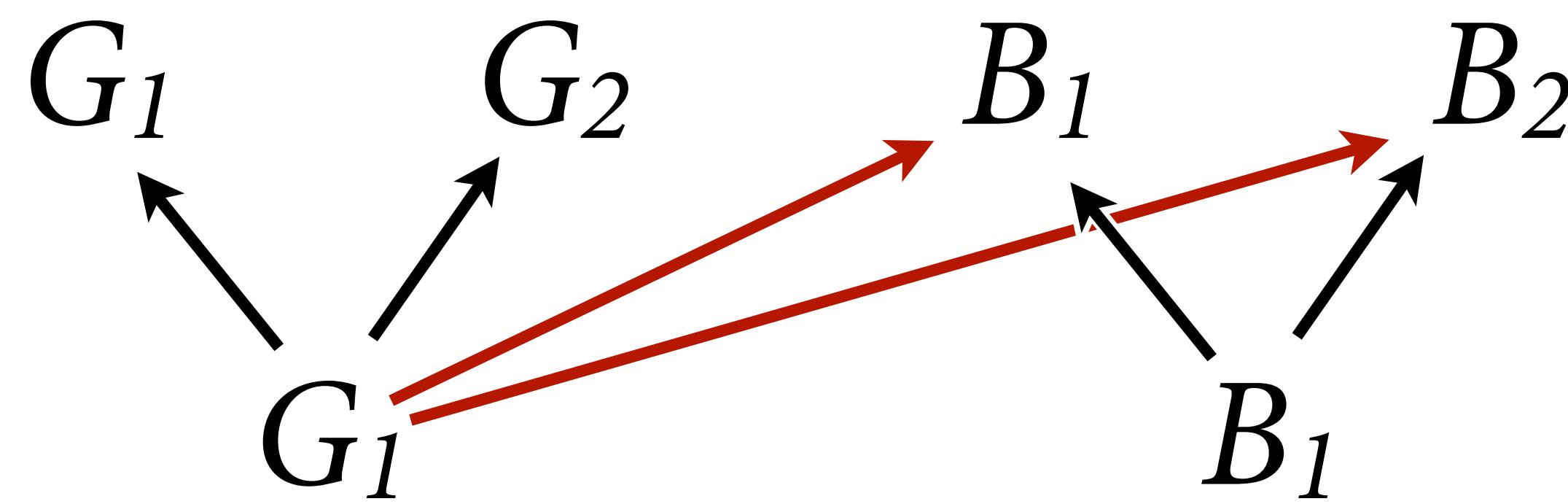


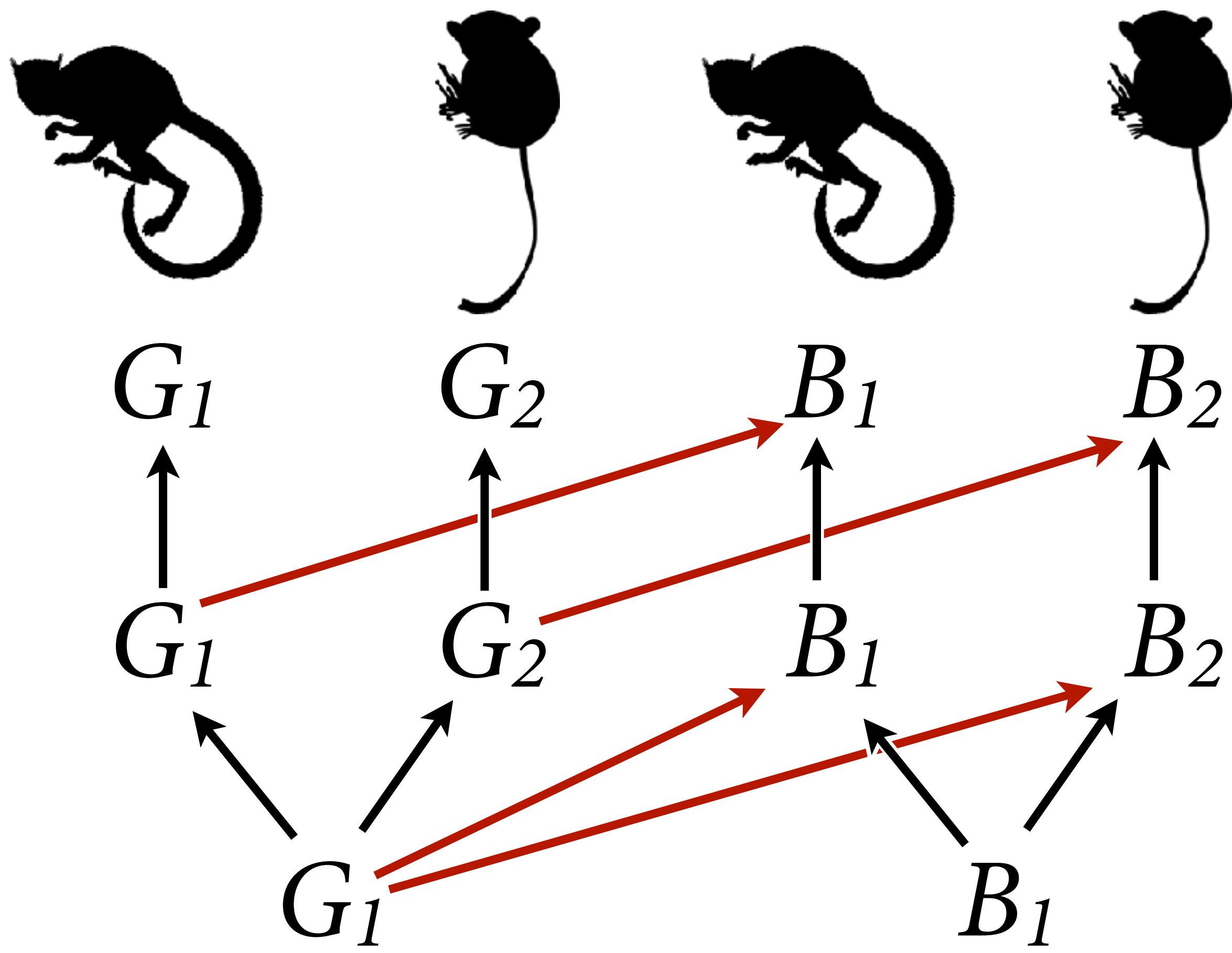


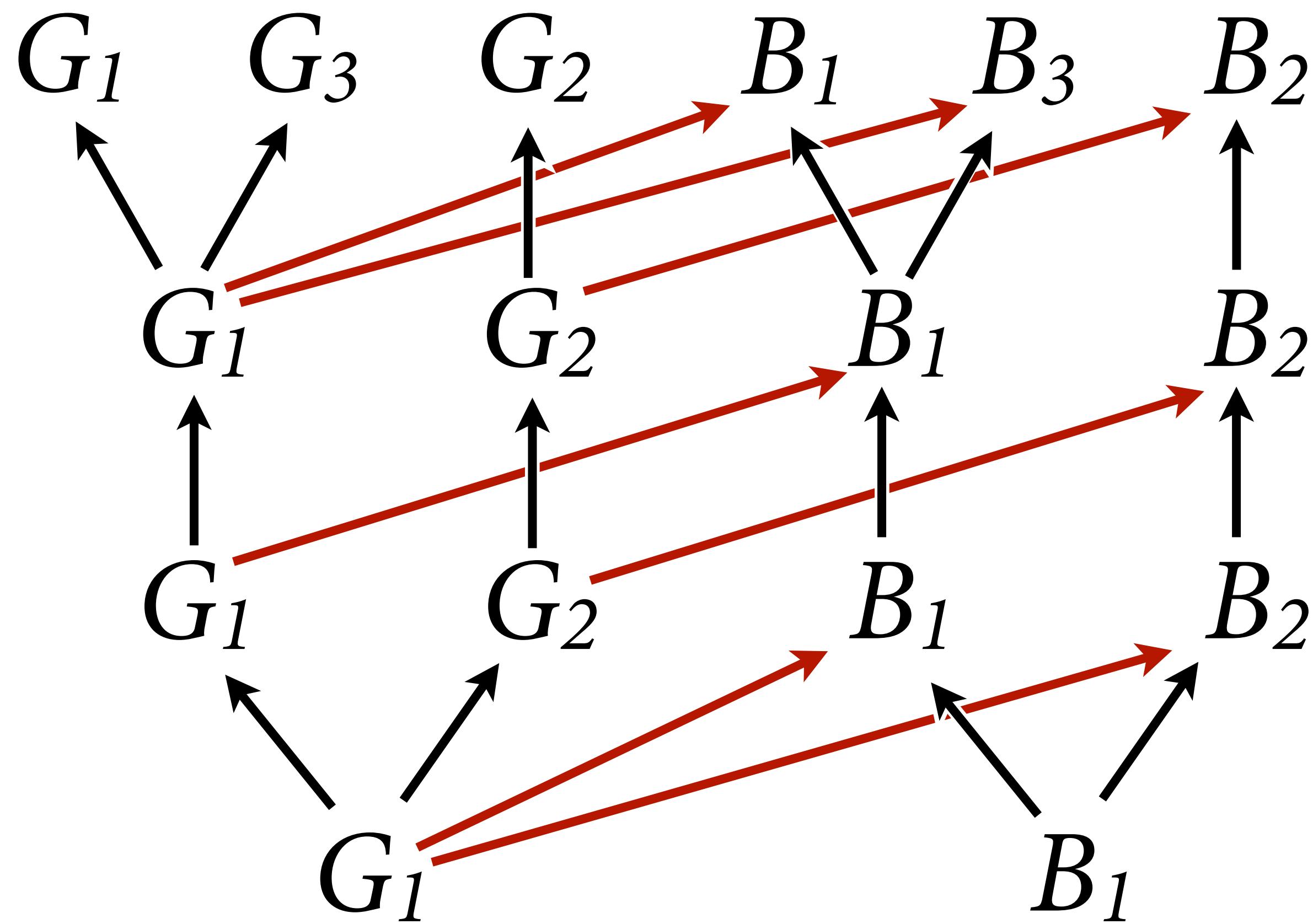
$G_1$

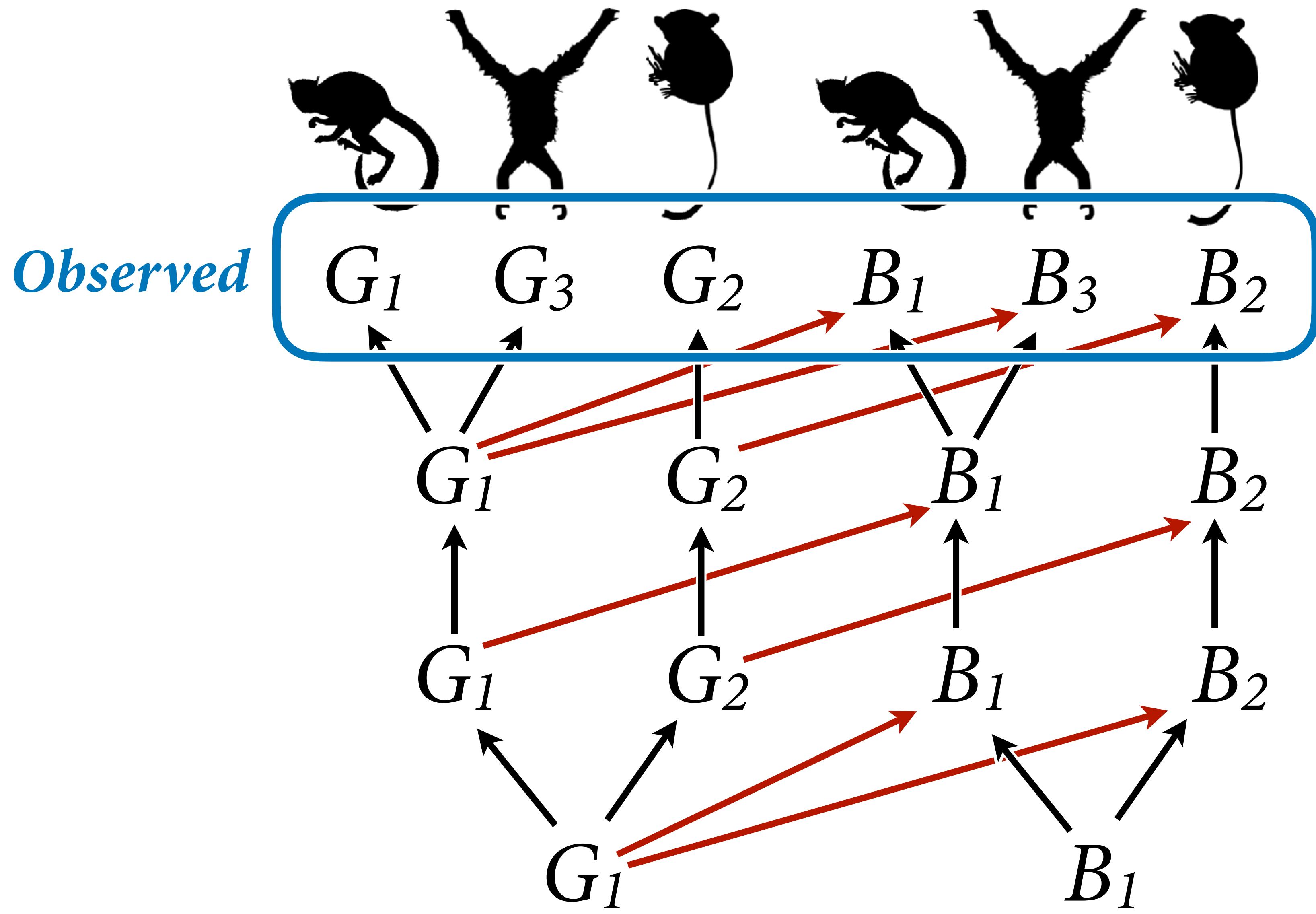


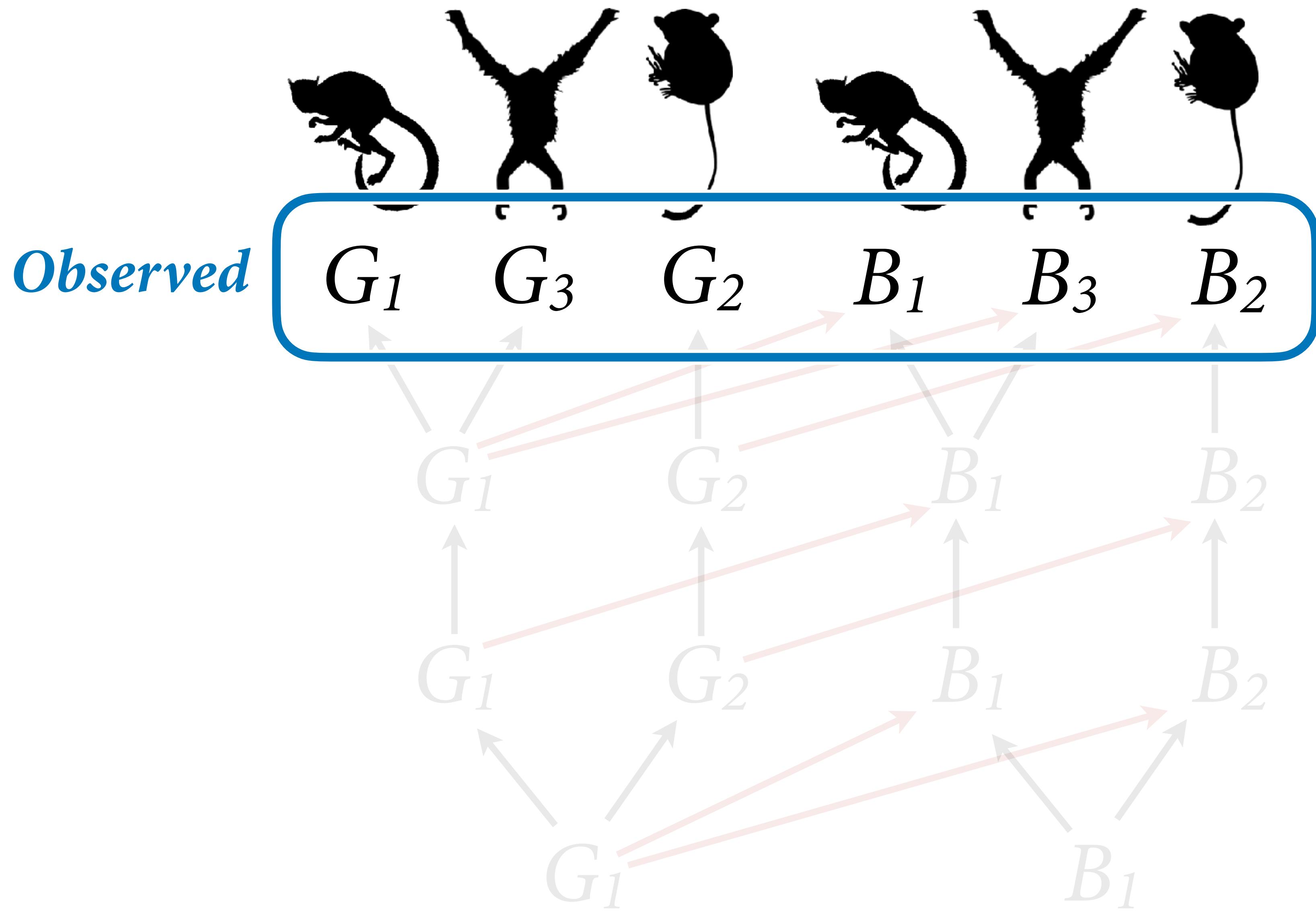
$B_1$







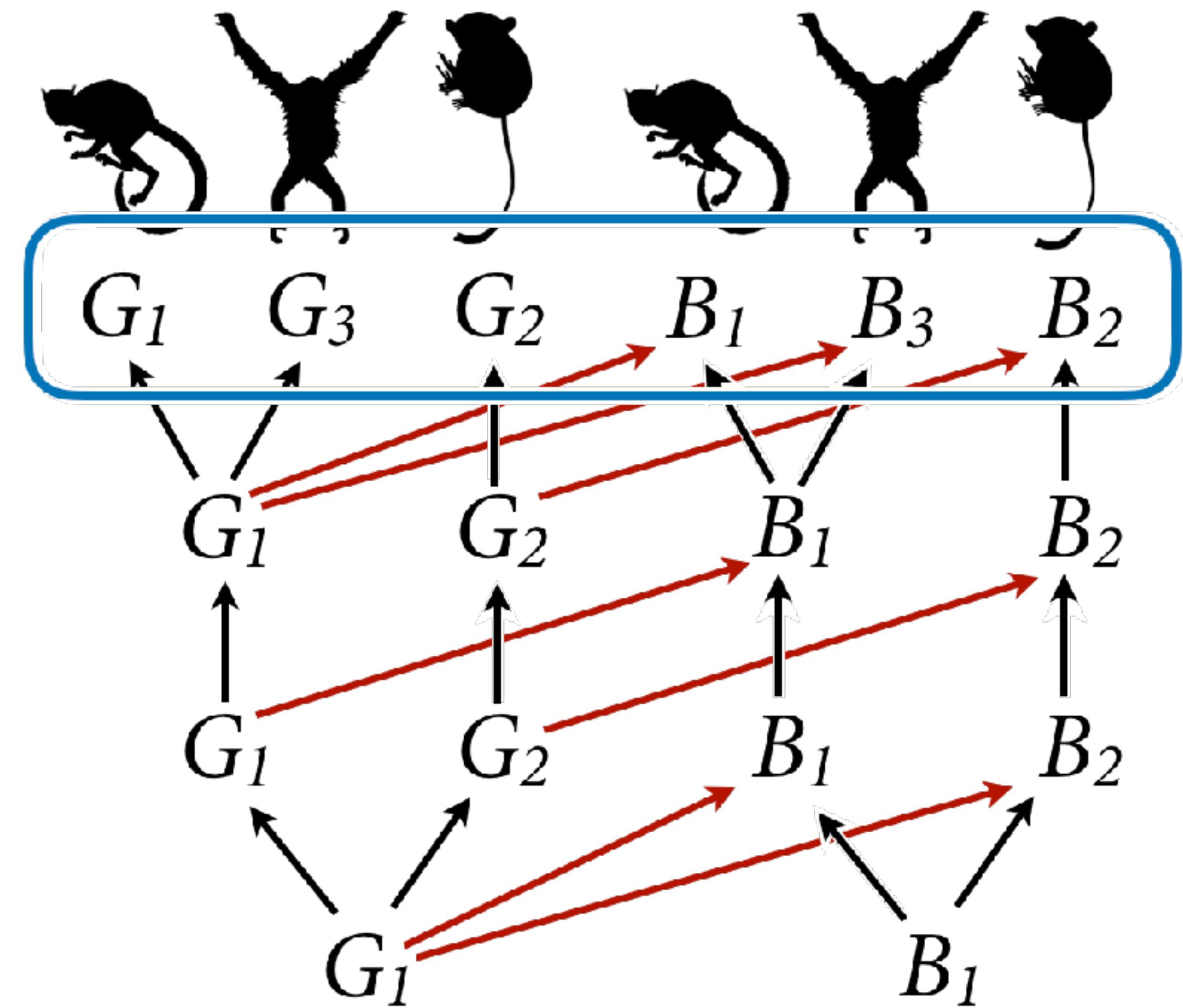




# Phylogenetic regression

Two conjoint problems

- (1) What is the history (phylogeny)?
- (2) How to use it to model causes?



# Phylogenetic regression

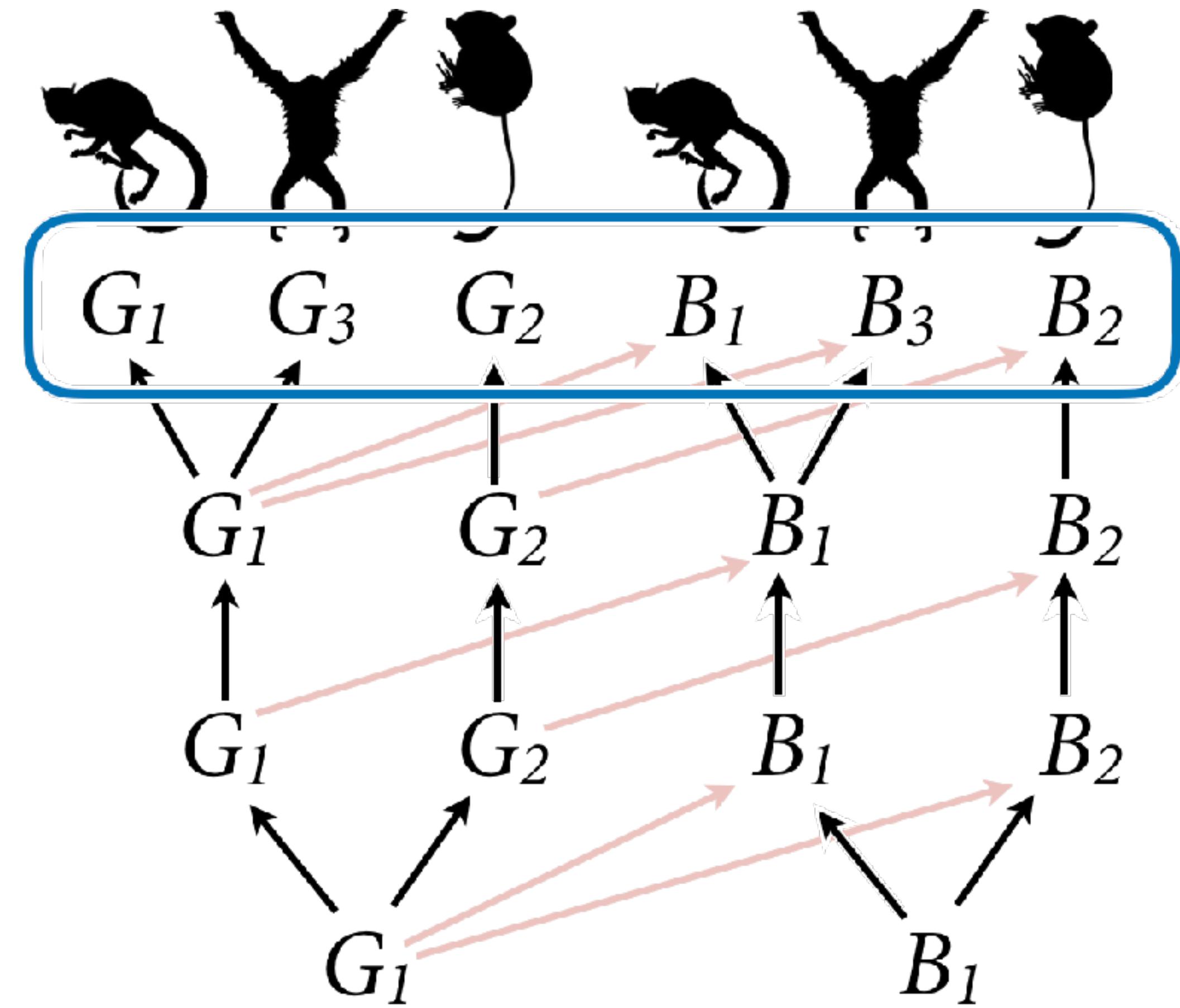
(1) What is the history (phylogeny)?

Gotten much better with genomics BUT

Problems: Huge **uncertainty** in best case,  
process **not stationary**, no one phylogeny  
correct for **all traits**

Cultural/linguistic phylogenies unconvincing,  
need new inference tools

Basic truth: Phylogenies do not exist



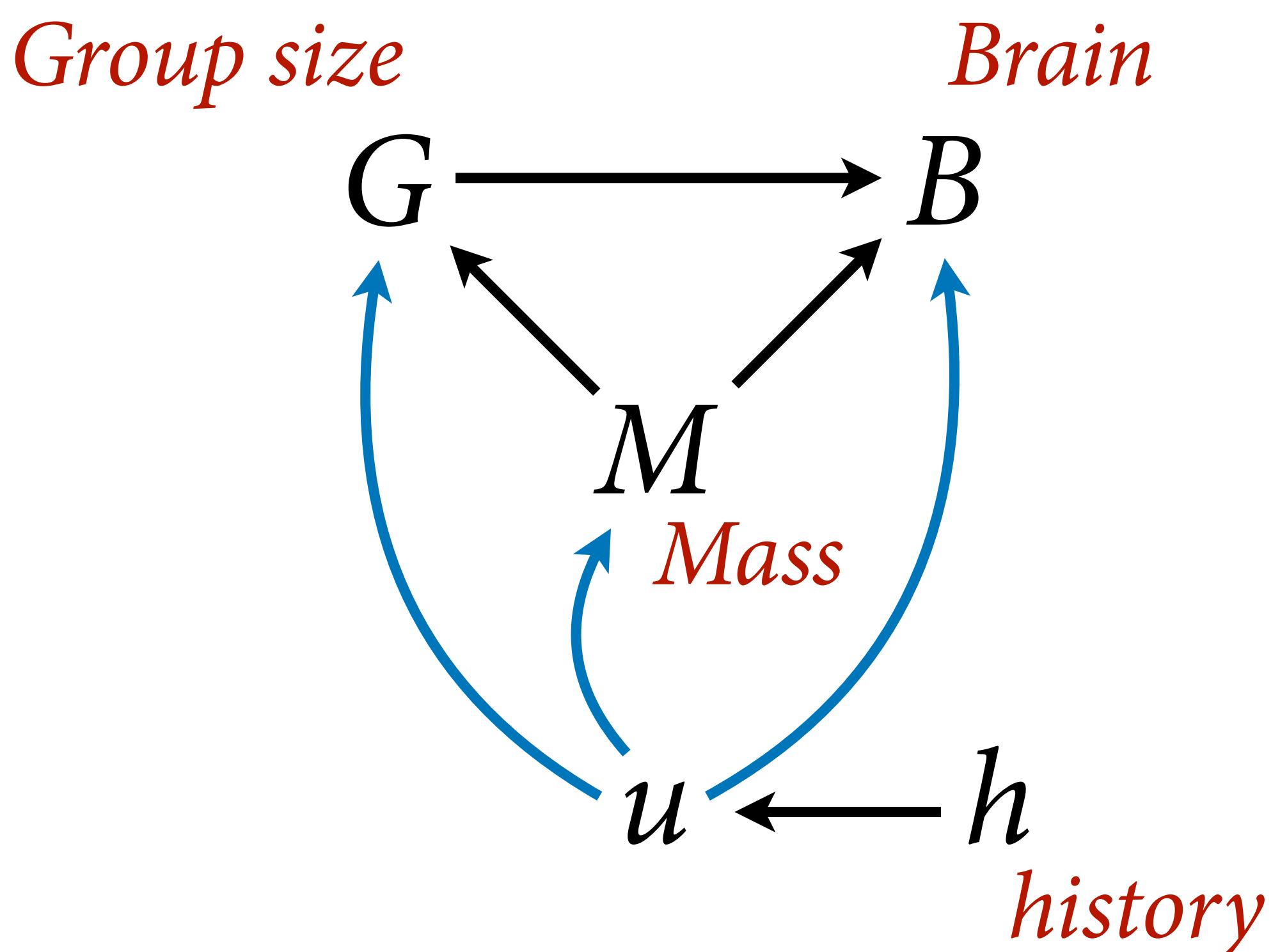
# Phylogenetic regression

(2) How to use it to model causes?

Suppose we have a phylogeny.  
Now what?

No universally correct approach

Default approach is a Gaussian  
process regression



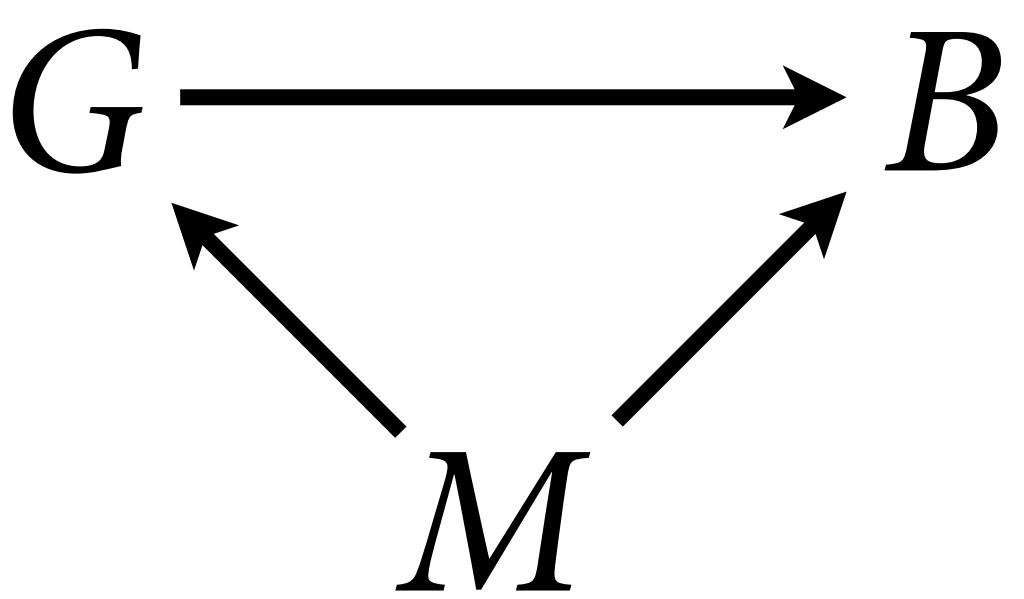
$$B_i \sim \text{Normal}(\mu_i, \sigma)$$

$$\mu_i = \alpha + \beta_G G_i + \beta_M M_i$$

$$\alpha \sim \text{Normal}(0,1)$$

$$\beta_G, \beta_M \sim \text{Normal}(0,0.5)$$

$$\sigma \sim \text{Exponential}(1)$$



$$B \sim \text{MVNormal}(\mu, \mathbf{K})$$

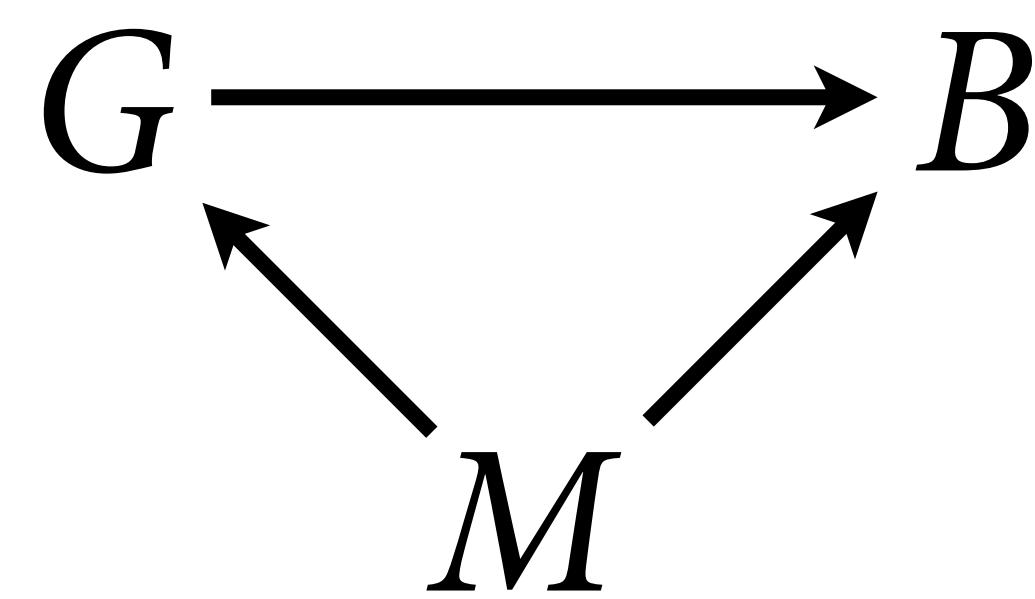
$$\mu_i = \alpha + \beta_G G_i + \beta_M M_i$$

$$\mathbf{K} = \mathbf{I}\sigma^2$$

$$\alpha \sim \text{Normal}(0,1)$$

$$\beta_G, \beta_M \sim \text{Normal}(0,0.5)$$

$$\sigma \sim \text{Exponential}(1)$$



$$B \sim \text{MVNormal}(\mu, \mathbf{K})$$

$$\mu_i = \alpha + \beta_G G_i + \beta_M M_i$$

$$\mathbf{K} = \mathbf{I}\sigma^2$$

$$\alpha \sim \text{Normal}(0,1)$$

$$\beta_G, \beta_M \sim \text{Normal}(0,0.5)$$

$$\sigma \sim \text{Exponential}(1)$$

$$\mathbf{I} = \begin{bmatrix} 1 & 0 & 0 & \cdots & 0 \\ 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & 0 \\ 0 & 0 & 0 & \cdots & 1 \end{bmatrix}$$

$$B \sim \text{MVNormal}(\mu, \mathbf{K})$$

$$\mu_i = \alpha + \beta_G G_i + \beta_M M_i$$

$$\mathbf{K} = \mathbf{I}\sigma^2$$

$$\alpha \sim \text{Normal}(0,1)$$

$$\beta_G, \beta_M \sim \text{Normal}(0,0.5)$$

$$\sigma \sim \text{Exponential}(1)$$

$$\mathbf{I} = \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & 0 \\ 0 & 0 & 0 & \dots & 1 \end{bmatrix}$$

$$\mathbf{K} = \begin{bmatrix} \sigma^2 & 0 & 0 & \dots & 0 \\ 0 & \sigma^2 & 0 & \dots & 0 \\ 0 & 0 & \sigma^2 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & 0 \\ 0 & 0 & 0 & \dots & \sigma^2 \end{bmatrix}$$

$$B_i \sim \text{Normal}(\mu_i, \sigma)$$

$$B \sim \text{MVNormal}(\mu, \mathbf{K})$$

```

dat_list <- list(
  N_spp = nrow(dstan) ,
  M = standardize(log(dstan$body)) ,
  B = standardize(log(dstan$brain)) ,
  G = standardize(log(dstan$group_size)) ,
  Imat = diag(nrow(dstan)) )

# classical regression form
mBMG0 <- ulam(
  alist(
    B ~ normal( mu , sigma ) ,
    mu <- a + bM*M + bG*G,
    a ~ normal( 0 , 1 ) ,
    c(bM,bG) ~ normal( 0 , 0.5 ) ,
    sigma ~ exponential( 1 )
  ), data=dat_list , chains=4 , cores=4 )

```

```

# multivariate form
mBMG <- ulam(
  alist(
    B ~ multi_normal( mu , K ) ,
    mu <- a + bM*M + bG*G,
    matrix[N_spp,N_spp]:K <- Imat*(sigma^2),
    a ~ normal( 0 , 1 ) ,
    c(bM,bG) ~ normal( 0 , 0.5 ) ,
    sigma ~ exponential( 1 )
  ), data=dat_list , chains=4 , cores=4 )

```

$$B_i \sim \text{Normal}(\mu_i, \sigma)$$

$$B \sim \text{MVNormal}(\mu, \mathbf{K})$$

```
dat_list <- list(
  N_spp = nrow(dstan),
  M = standardize(log(dstan$body)),
  B = standardize(log(dstan$brain)),
  G = standardize(log(dstan$group_size)),
  Imat = diag(nrow(dstan)) )
```

```
# classical regression form
mBMG0 <- ulam(
  alist(
    B ~ normal( mu , sigma ),
    mu <- a + bM*M + bG*G
```

> **precis( mBMG0 )**

	mean	sd	5.5%	94.5%	n_eff	Rhat4
a	0.00	0.02	-0.03	0.03	1740	1
bG	0.12	0.02	0.09	0.16	1491	1
bM	0.89	0.02	0.86	0.93	1439	1
sigma	0.22	0.01	0.20	0.24	1706	1

# multivariate form

```
mBMG <- ulam(
  alist(
    B ~ multi_normal( mu , K ),
    mu <- a + bM*M + bG*G,
    matrix[N spp N spp]•K <- Tmat*(sigma^2),
```

> **precis( mBMG )**

	mean	sd	5.5%	94.5%	n_eff	Rhat4
a	0.00	0.02	-0.03	0.03	1880	1
bG	0.12	0.02	0.09	0.16	1384	1
bM	0.89	0.02	0.86	0.93	1395	1
sigma	0.22	0.01	0.20	0.24	1433	1

$$B \sim \text{MVNormal}(\mu, \mathbf{K})$$

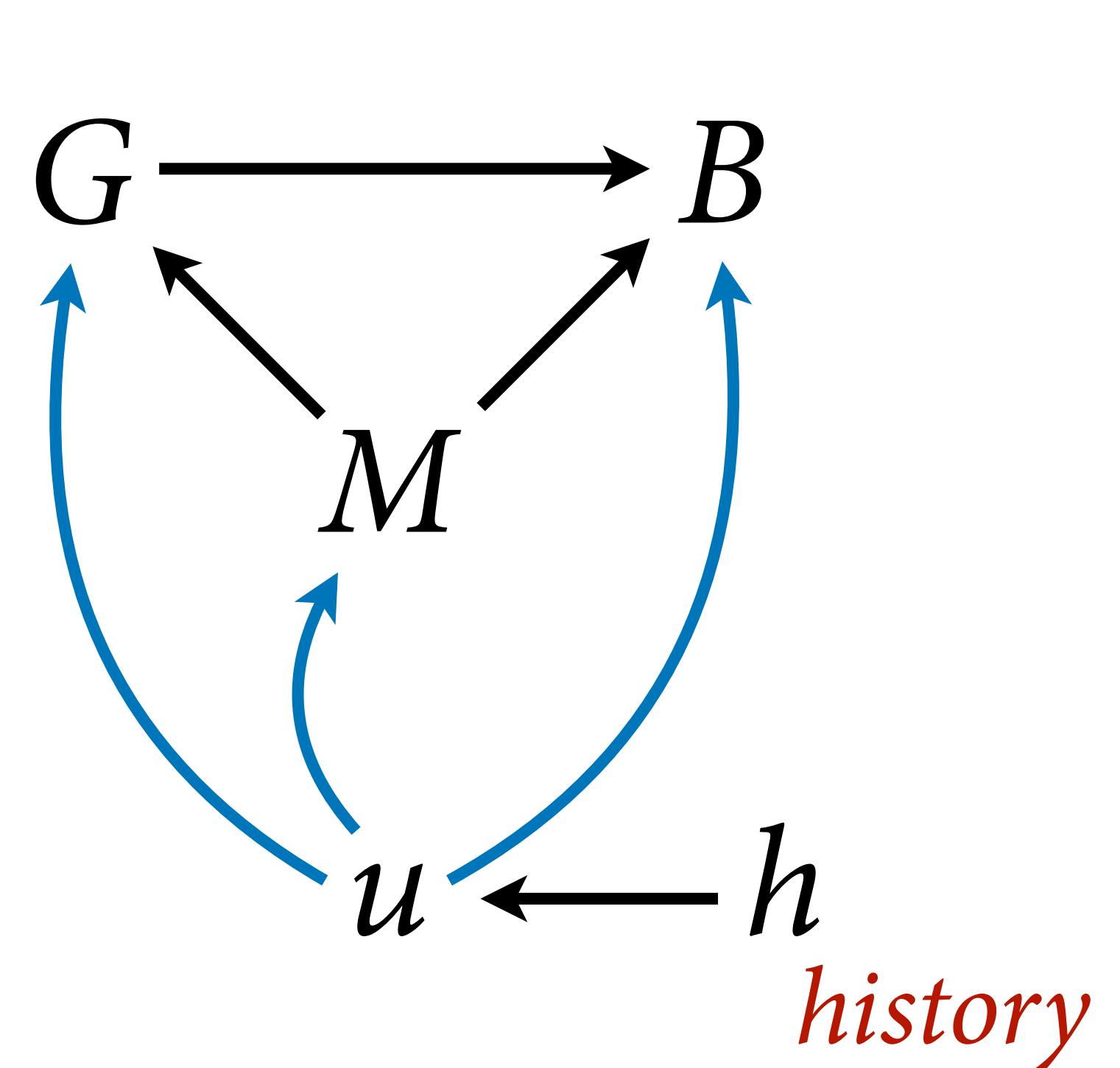
$$\mu_i = \alpha + \beta_G G_i + \beta_M M_i + u_i$$

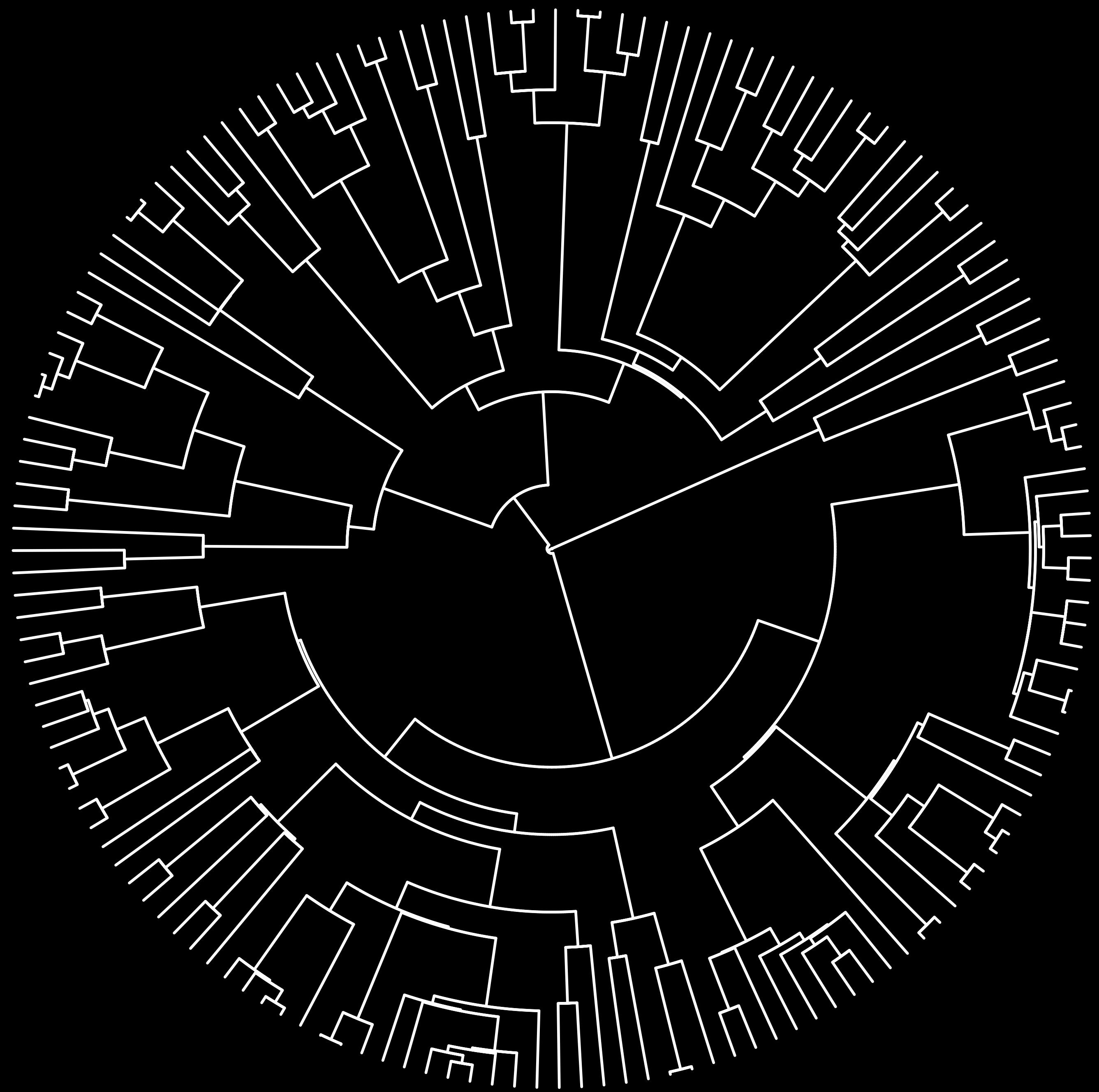
$$\mathbf{K} = \mathbf{I}\sigma^2$$

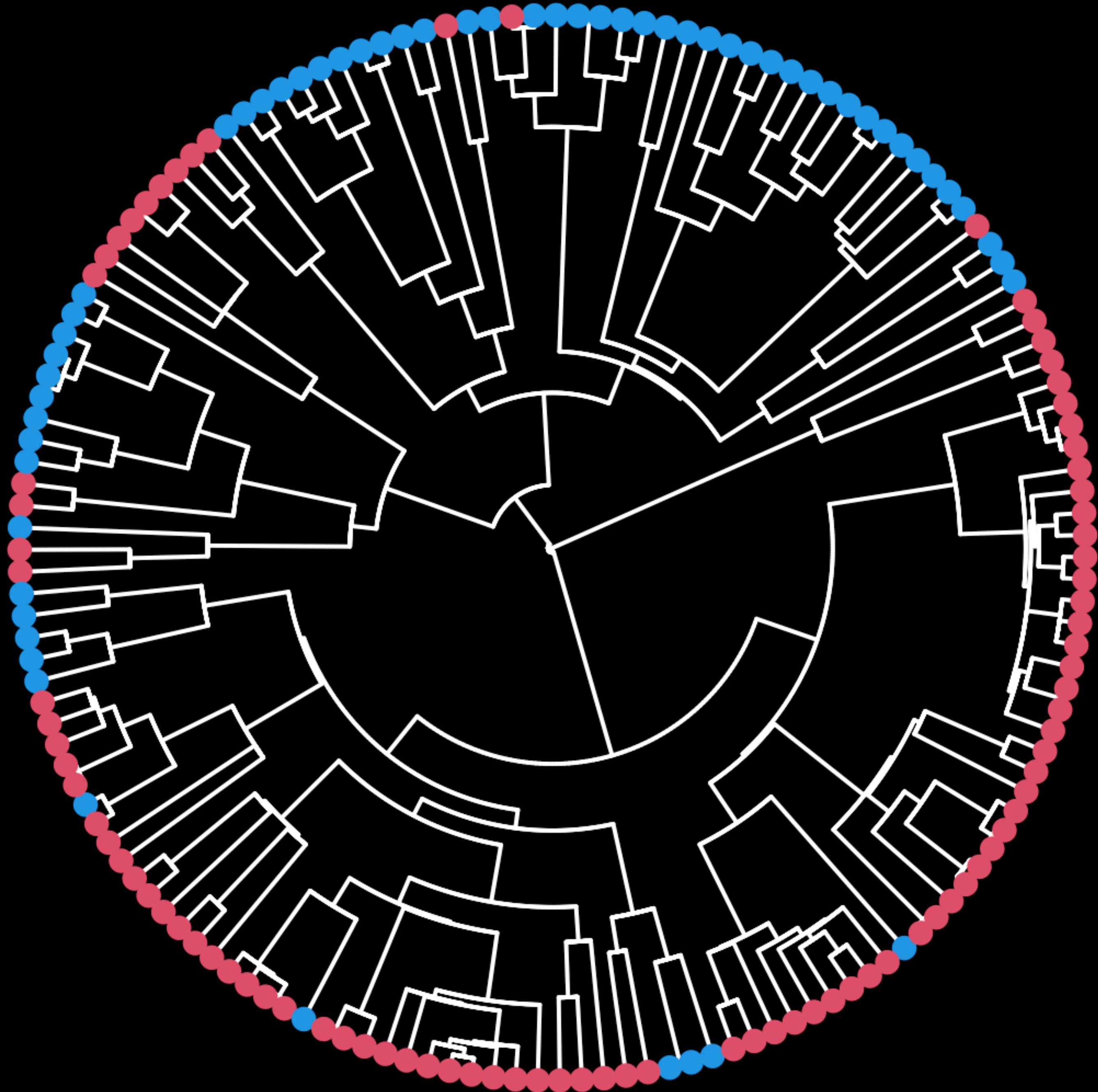
$$\alpha \sim \text{Normal}(0,1)$$

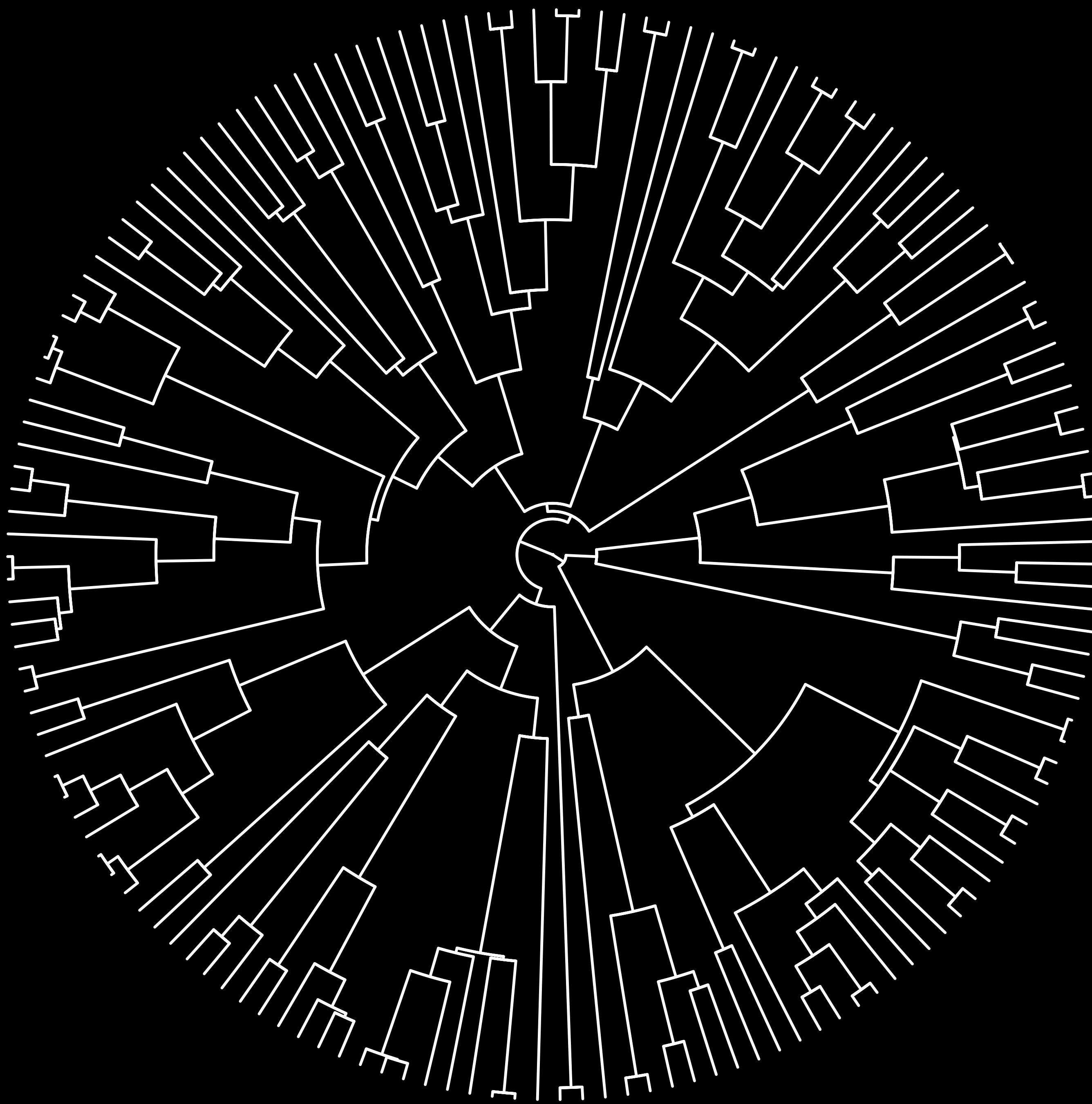
$$\beta_G, \beta_M \sim \text{Normal}(0,0.5)$$

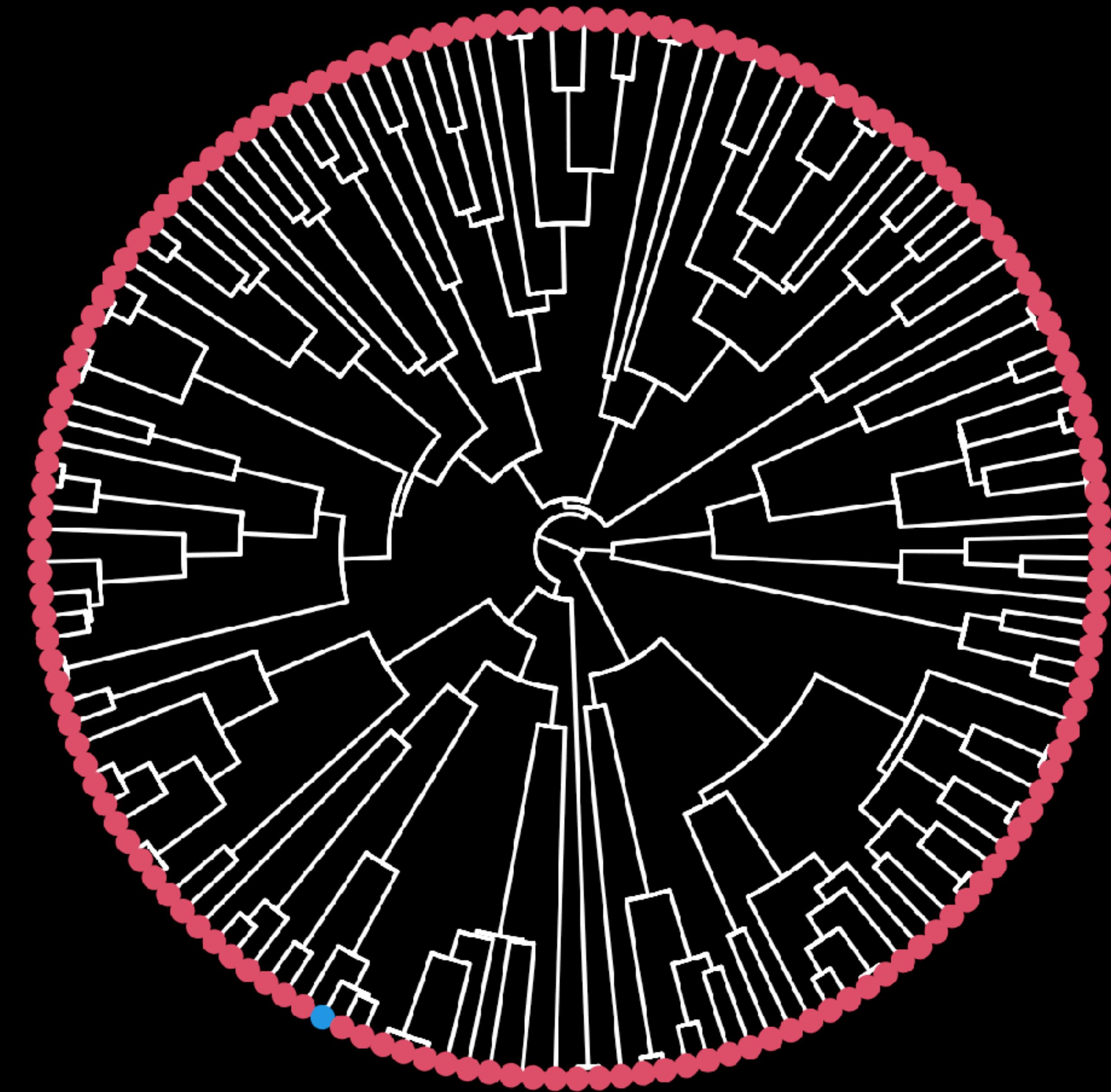
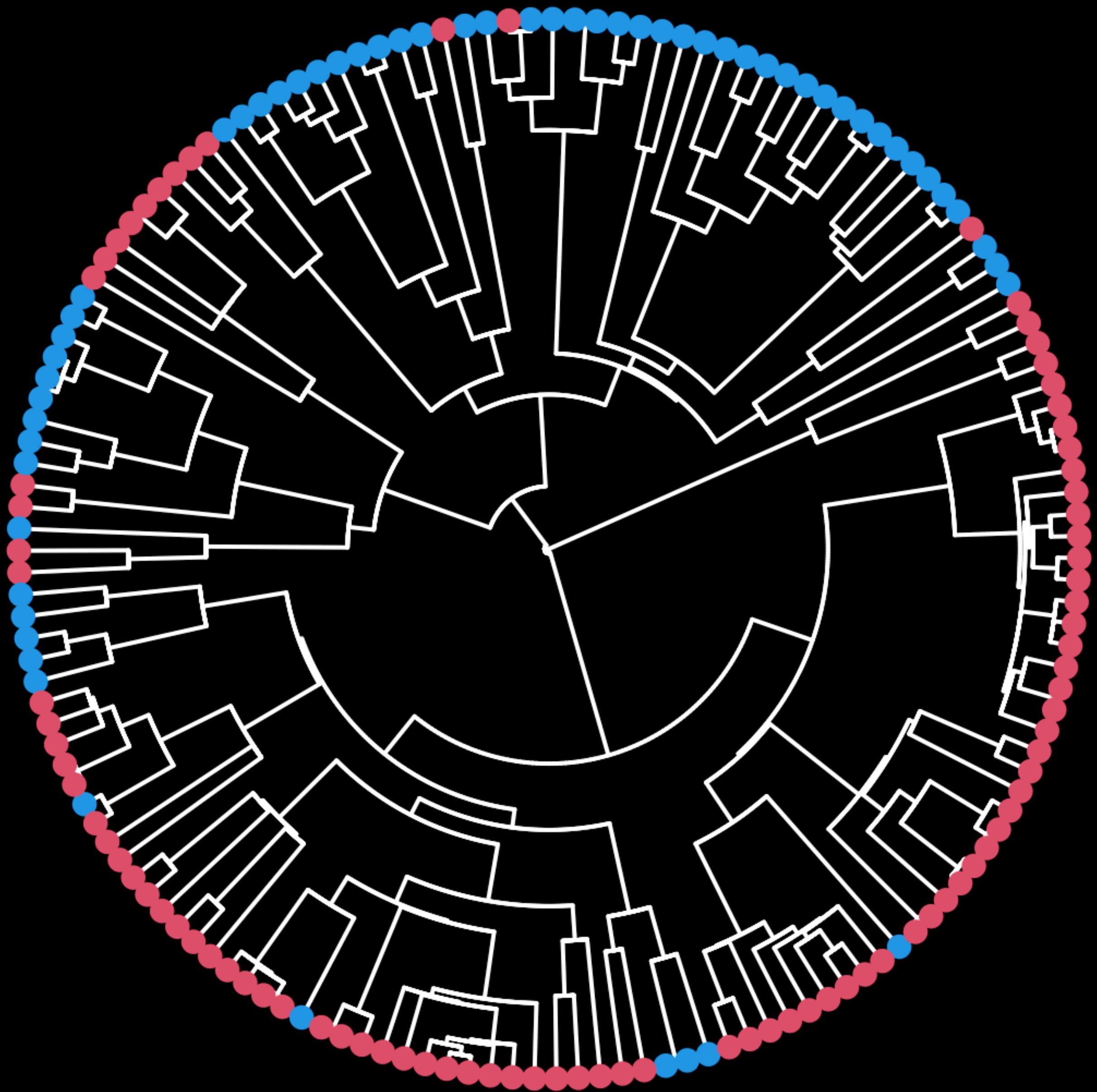
$$\sigma \sim \text{Exponential}(1)$$









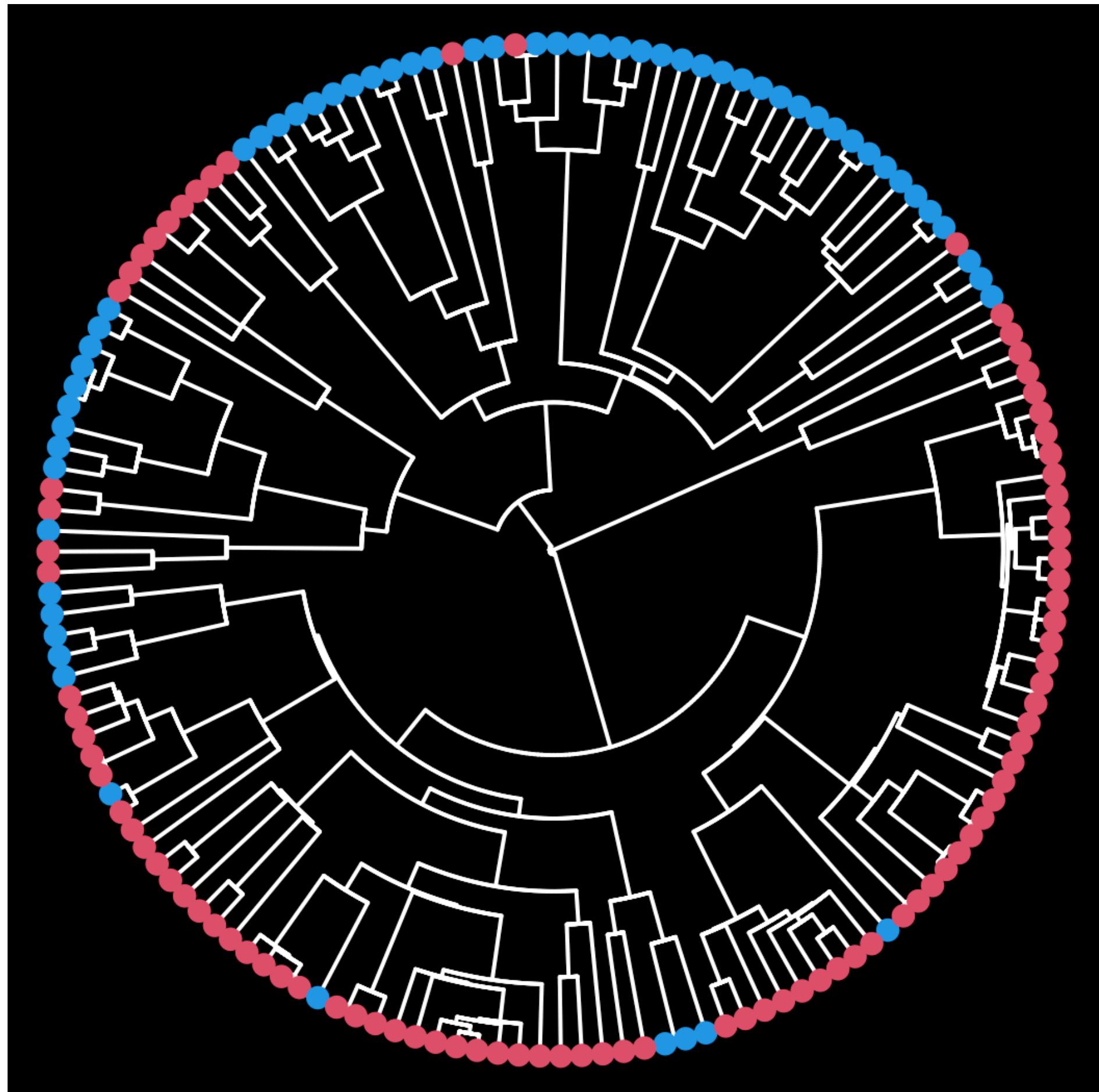


# From Model to Kernel

Evolutionary model + tree structure  
= pattern of covariation at tips

Covariance declines with  
**phylogenetic distance**

*Phylogenetic distance*: Branch length  
from one species to another



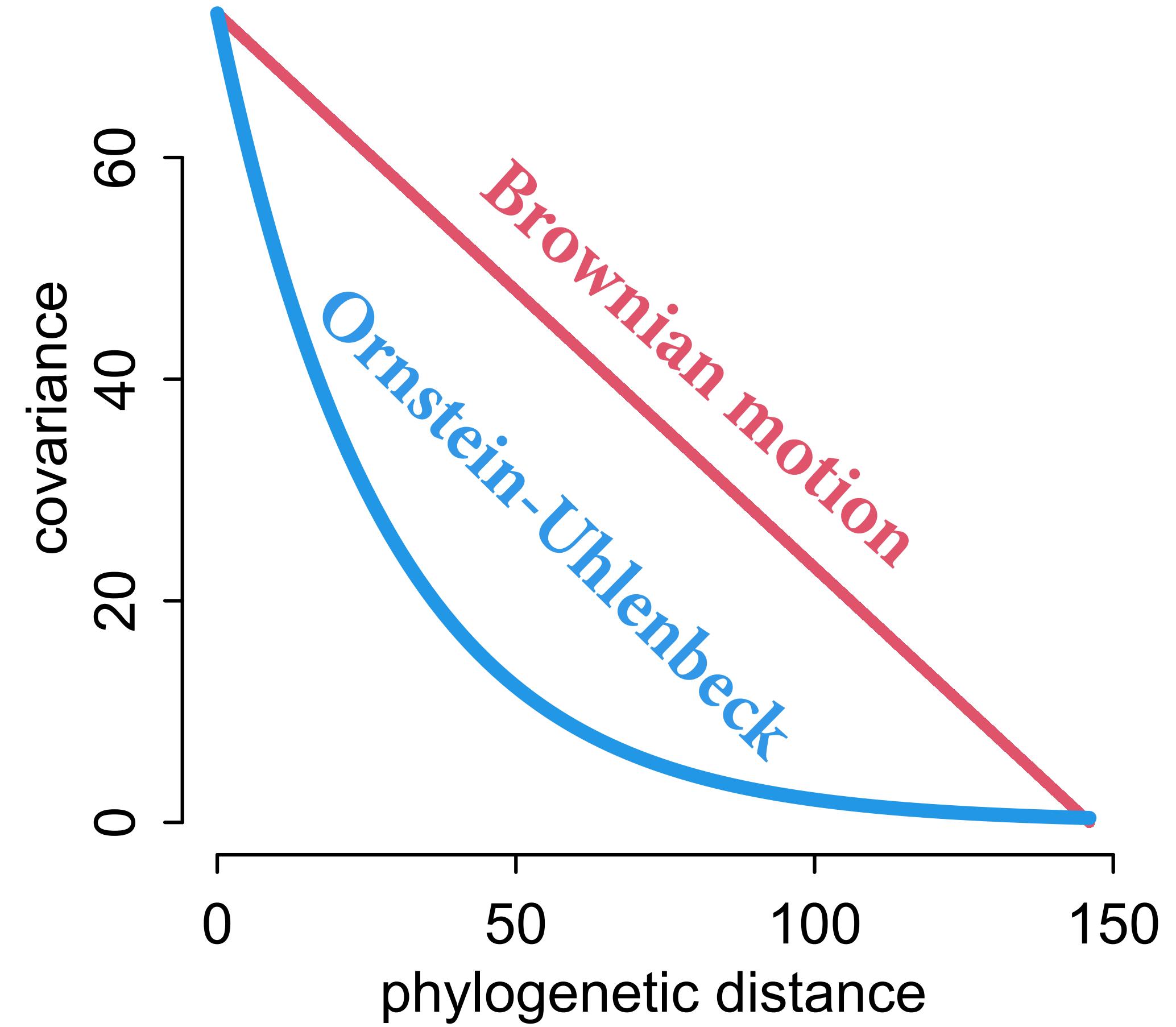
# From Model to Kernel

Evolutionary model + tree structure  
= pattern of covariation at tips

Common simple models:

**Brownian motion**

**Ornstein-Uhlenbeck** (damped Brownian motion)



$$B \sim \text{MVNormal}(\mu, \mathbf{K})$$

$$\mu_i = \alpha + \beta_G G_i + \beta_M M_i$$

$$\mathbf{K}=\mathbf{I}\sigma^2$$

$$\alpha \sim \text{Normal}(0,1)$$

$$\beta_G,\beta_M \sim \text{Normal}(0,0.5)$$

$$\sigma \sim \text{Exponential}(1)$$

$$B \sim \text{MVNormal}(\mu, \mathbf{K})$$

$$\mu_i = \alpha + \beta_G G_i + \beta_M M_i$$

$$\mathbf{K} = \eta^2 \exp(-\rho d_{i,j})$$

*Ornstein-Uhlenbeck kernel*

$$\alpha \sim \text{Normal}(0,1)$$

$$\beta_G, \beta_M \sim \text{Normal}(0,0.5)$$

$$\eta^2 \sim \text{HalfNormal}(1,0.25)$$

*Maximum covariance prior*

$$\rho \sim \text{HalfNormal}(3,0.25)$$

*Rate prior*

$$B \sim \text{MVNormal}(\mu, \mathbf{K})$$

$$\mu_i = \alpha + \beta_G G_i + \beta_M M_i$$

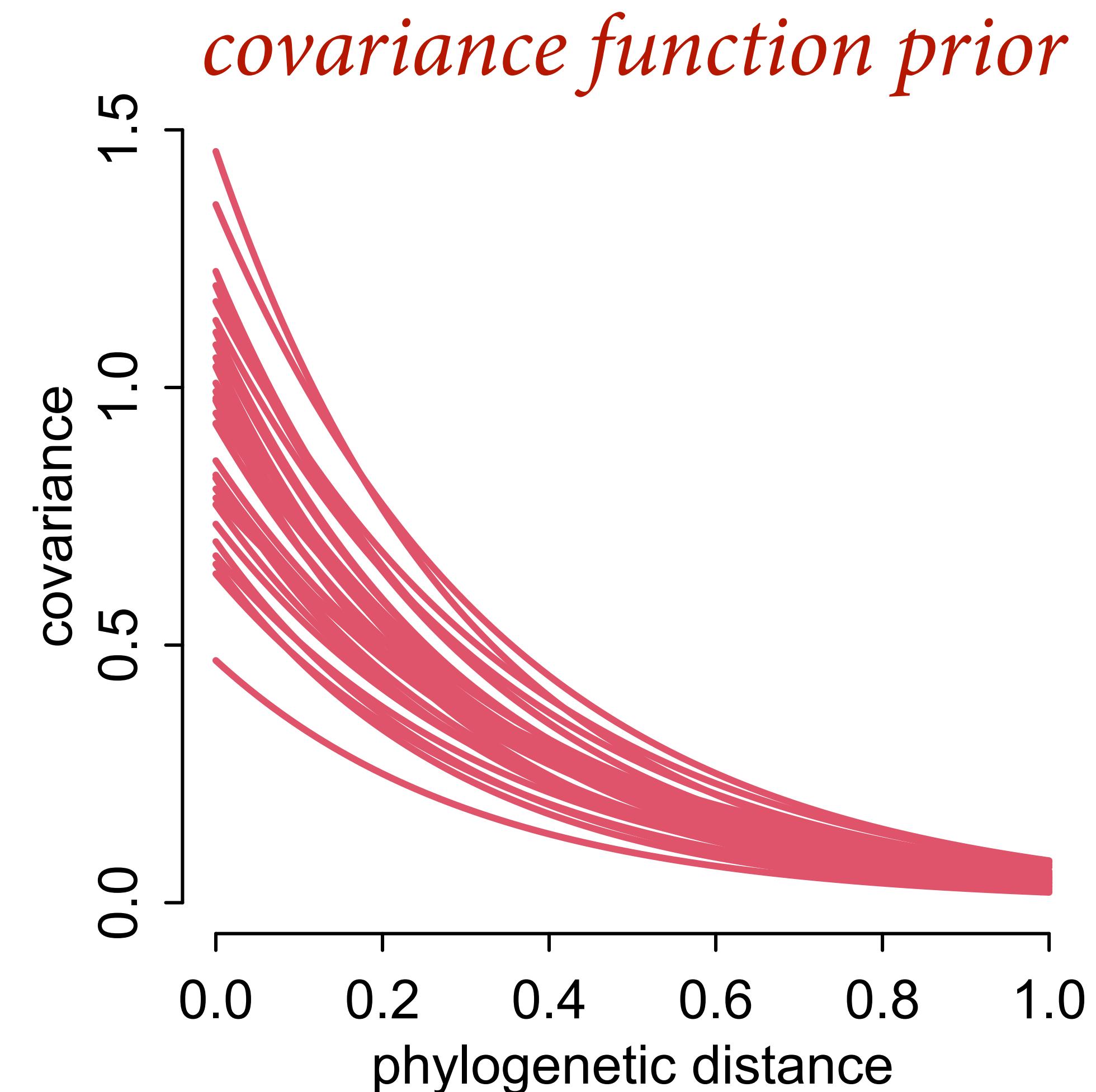
$$\mathbf{K} = \eta^2 \exp(-\rho d_{i,j})$$

$$\alpha \sim \text{Normal}(0,1)$$

$$\beta_G, \beta_M \sim \text{Normal}(0,0.5)$$

$$\eta^2 \sim \text{HalfNormal}(1,0.25)$$

$$\rho \sim \text{HalfNormal}(3,0.25)$$



$$B \sim \text{MVNormal}(\mu, \mathbf{K})$$

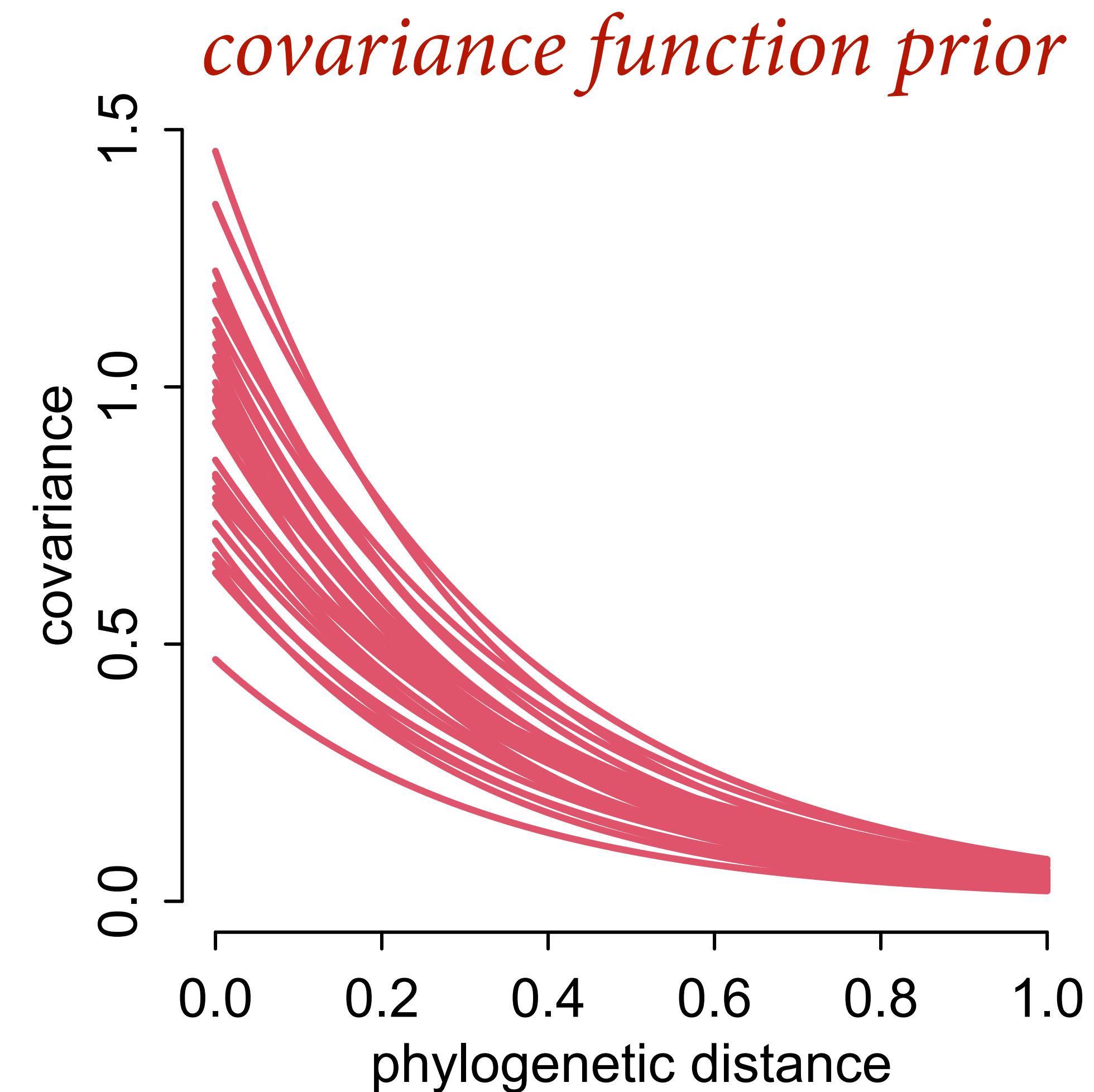
$$\mu_i = \alpha$$

$$\mathbf{K} = \eta^2 \exp(-\rho d_{i,j})$$

$$\alpha \sim \text{Normal}(0,1)$$

$$\eta^2 \sim \text{HalfNormal}(1,0.25)$$

$$\rho \sim \text{HalfNormal}(3,0.25)$$



```

# Ornstein-Uhlenbeck (L1 gaussian process)
# add scaled and reordered distance matrix
dat_list$Dmat <- Dmat[ spp_obs , spp_obs ] / max(Dmat)

mB_OU <- ulam(
  alist(
    B ~ multi_normal( mu , K ),
    mu <- a + 0*M,
    matrix[N_spp,N_spp]:K <- cov_GPL1(Dmat,etasq,rho,0.01),
    a ~ normal(0,1),
    etasq ~ half_normal(1,0.25),
    rho ~ half_normal(3,0.25)
  ), data=dat_list , chains=4 , cores=4 )

```

$$B \sim \text{MVNormal}(\mu, \mathbf{K})$$

$$\mu_i = \alpha$$

$$\mathbf{K} = \eta^2 \exp(-\rho d_{i,j})$$

$$\alpha \sim \text{Normal}(0,1)$$

$$\eta^2 \sim \text{HalfNormal}(1,0.25)$$

$$\rho \sim \text{HalfNormal}(3,0.25)$$

```

# Ornstein-Uhlenbeck (L1 gaussian process)
# add scaled and reordered distance matrix
dat_list$Dmat <- Dmat[ spp_obs , spp_obs ] / max(Dmat)

mB_OU <- ulam(
  alist(
    B ~ multi_normal( mu , K ),
    mu <- a + Υ * M,
    matrix[N_spp,N_spp]:K <- cov_GPL1(Dmat,etasq,rho,0.01),
    a ~ normal(0.1),
    etasq ~ half_normal(1,0.25),
    rho ~ half_normal(3,0.25)
  ), data=dat_list , chains=4 , cores=4 )

```

$$B \sim \text{MVNormal}(\mu, \mathbf{K})$$

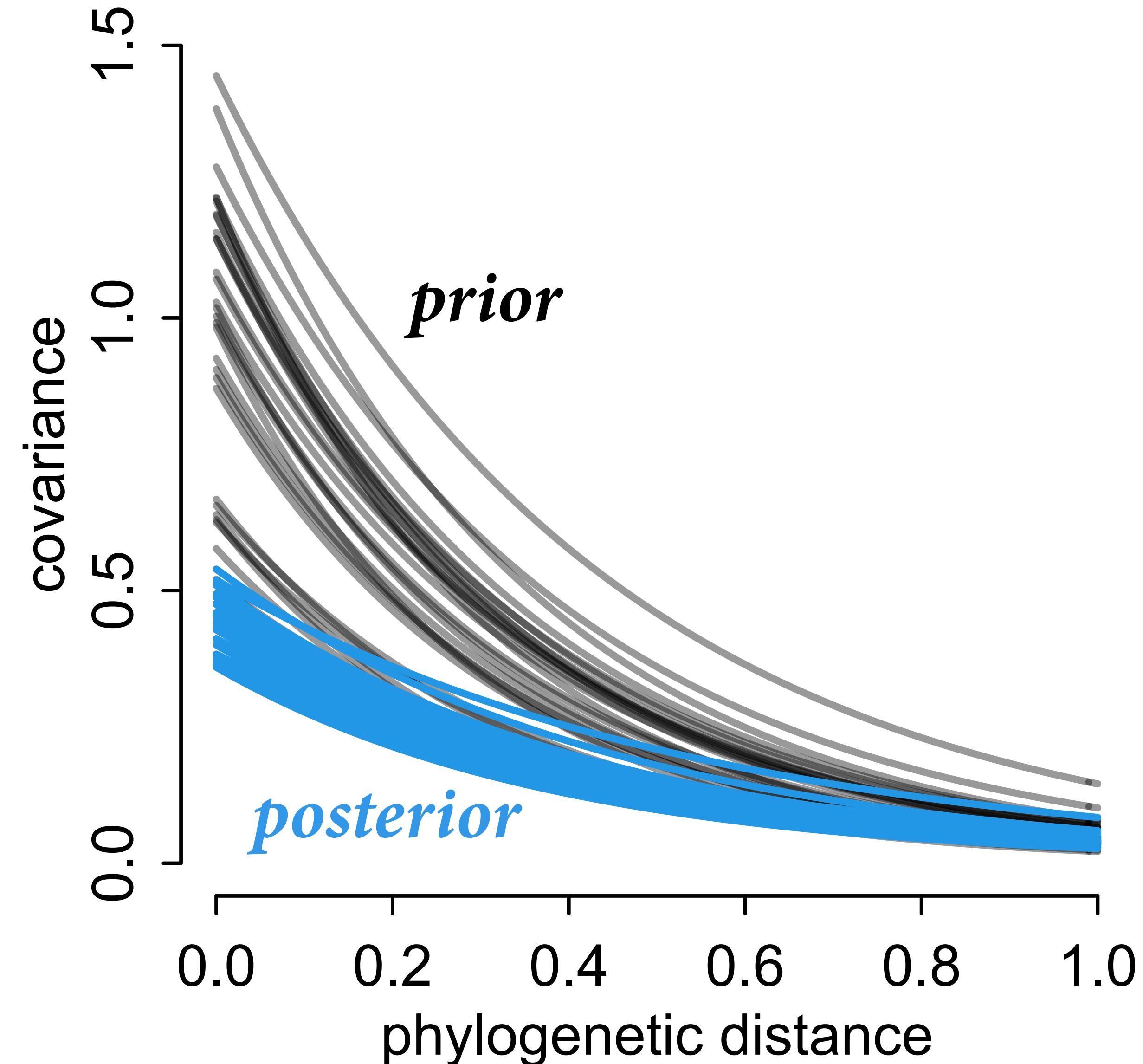
$$\mu_i = \alpha$$

$$\mathbf{K} = \eta^2 \exp(-\rho d_{i,j})$$

$$\alpha \sim \text{Normal}(0,1)$$

$$\eta^2 \sim \text{HalfNormal}(1,0.25)$$

$$\rho \sim \text{HalfNormal}(3,0.25)$$



$B \sim \text{MVNormal}(\mu, \mathbf{K})$   
 $\mu_i = \alpha$   
 $\mathbf{K} = \eta^2 \exp(-\rho d_{i,j})$   
 $\alpha \sim \text{Normal}(0, 1)$   
 $\eta^2 \sim \text{HalfNormal}(1, 0.25)$   
 $\rho \sim \text{HalfNormal}(3, 0.25)$

# Stratify by $M$ and $G$

```
mB MG_OU <- ulam(  
  alist(  
  
    B ~ multi_normal( mu , K ),  
    mu <- a + bM*M + bG*G,  
    matrix[N_spp,N_spp]:K <- cov_GPL1(Dmat,etasq,rho,0.01),  
    a ~ normal(0,1),  
    c(bM,bG) ~ normal(0,0.5),  
    etasq ~ half_normal(1,0.25),  
    rho ~ half_normal(3,0.25)  
  ), data=dat_list , chains=4 , cores=4 )
```

$$B \sim \text{MVNormal}(\mu, \mathbf{K})$$

$$\mu_i = \alpha + \beta_G G_i + \beta_M M_i$$

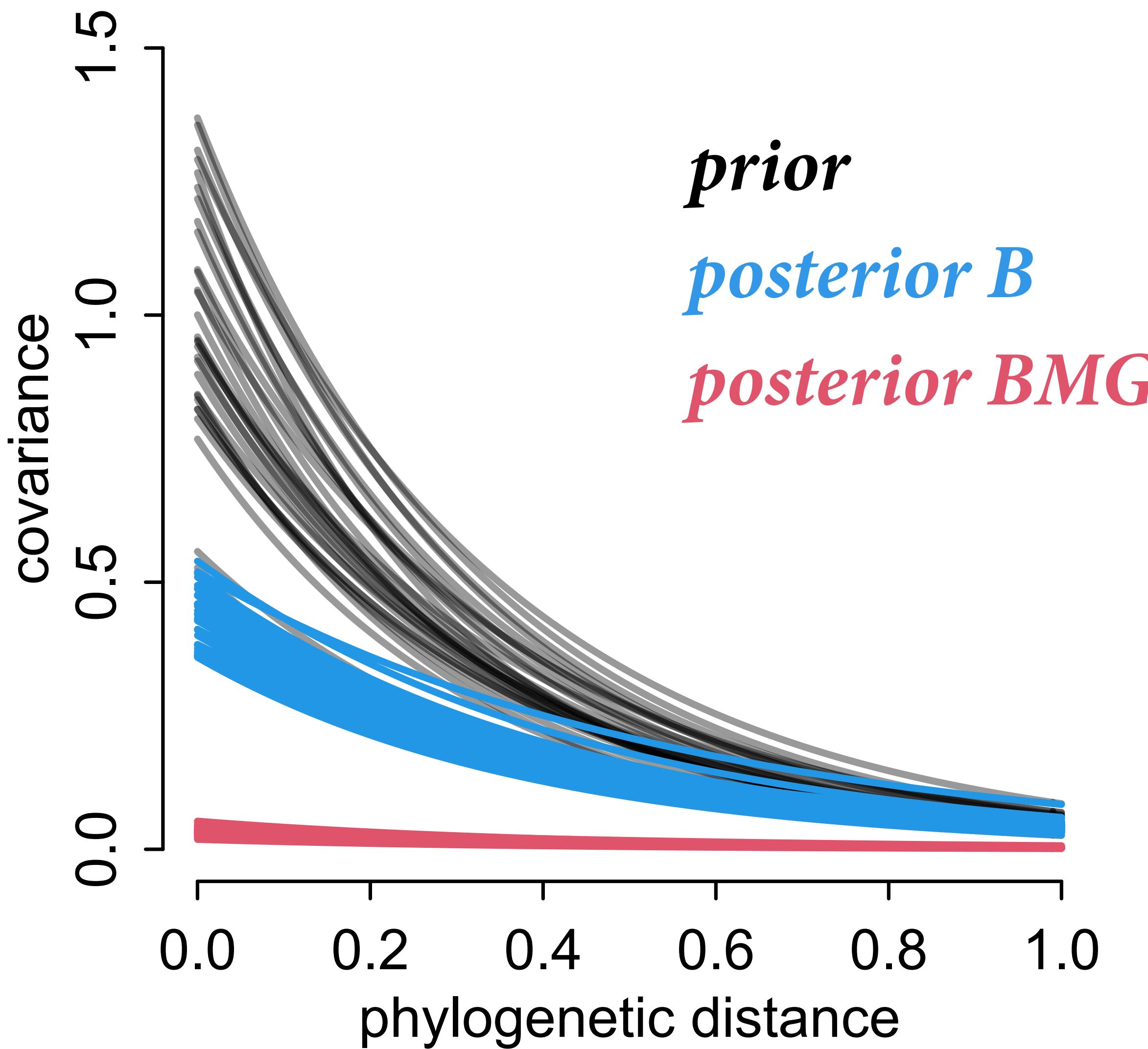
$$\mathbf{K} = \eta^2 \exp(-\rho d_{i,j})$$

$$\alpha \sim \text{Normal}(0,1)$$

$$\beta_G, \beta_M \sim \text{Normal}(0,0.5)$$

$$\eta^2 \sim \text{HalfNormal}(1,0.25)$$

$$\rho \sim \text{HalfNormal}(3,0.25)$$



$$B \sim \text{MVNormal}(\mu, \mathbf{K})$$

$$\mu_i = \alpha + \beta_G G_i + \beta_M M_i$$

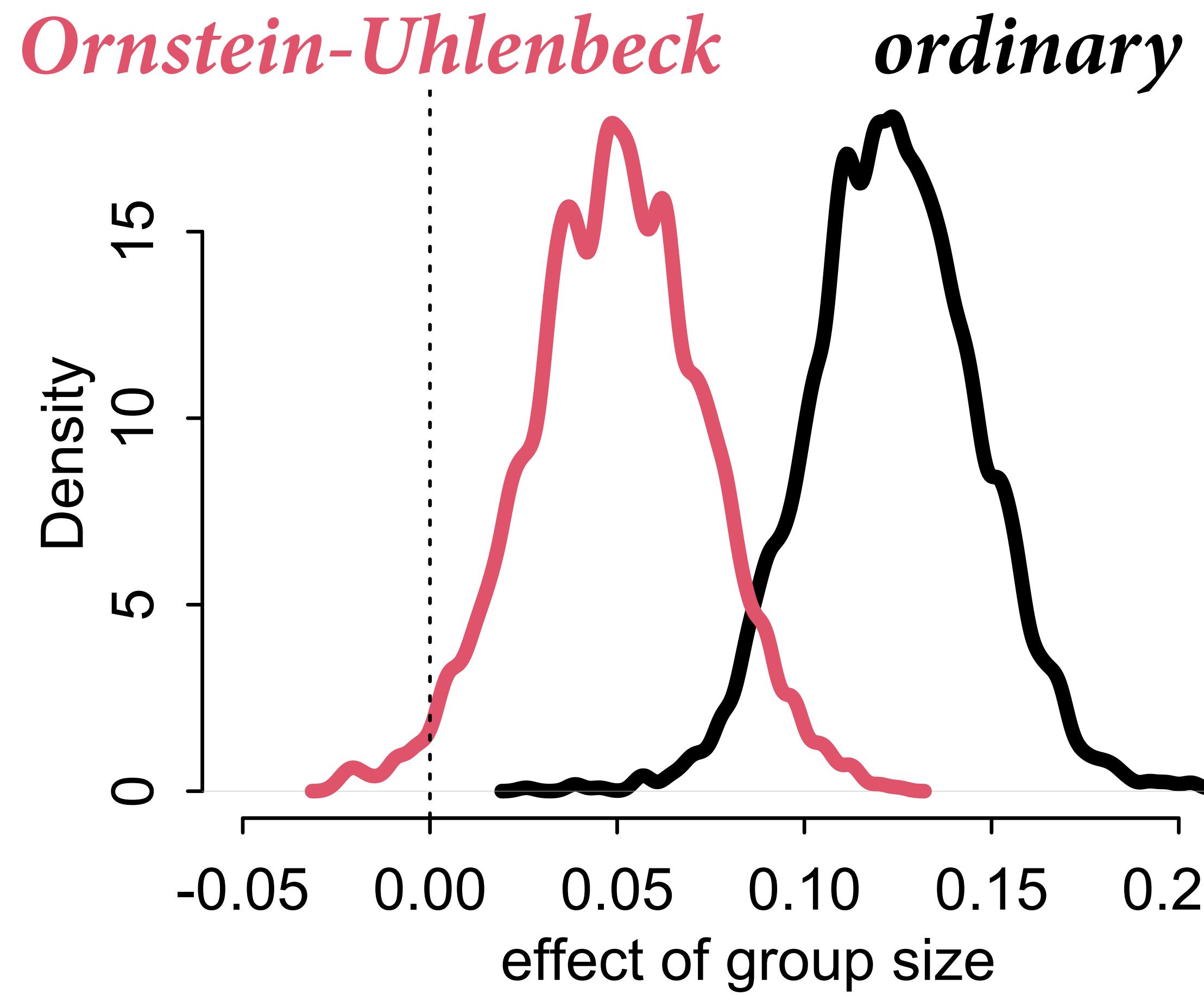
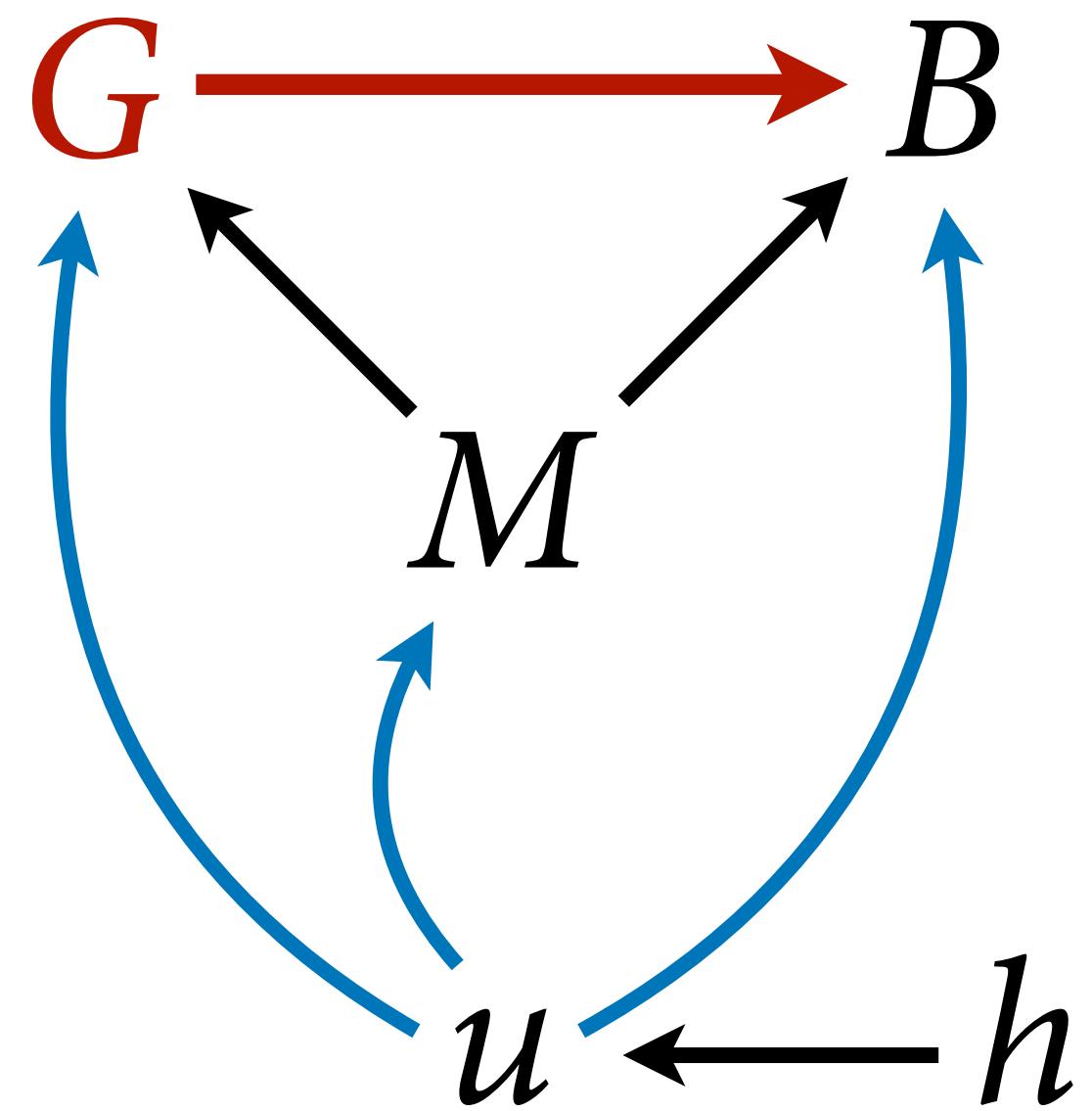
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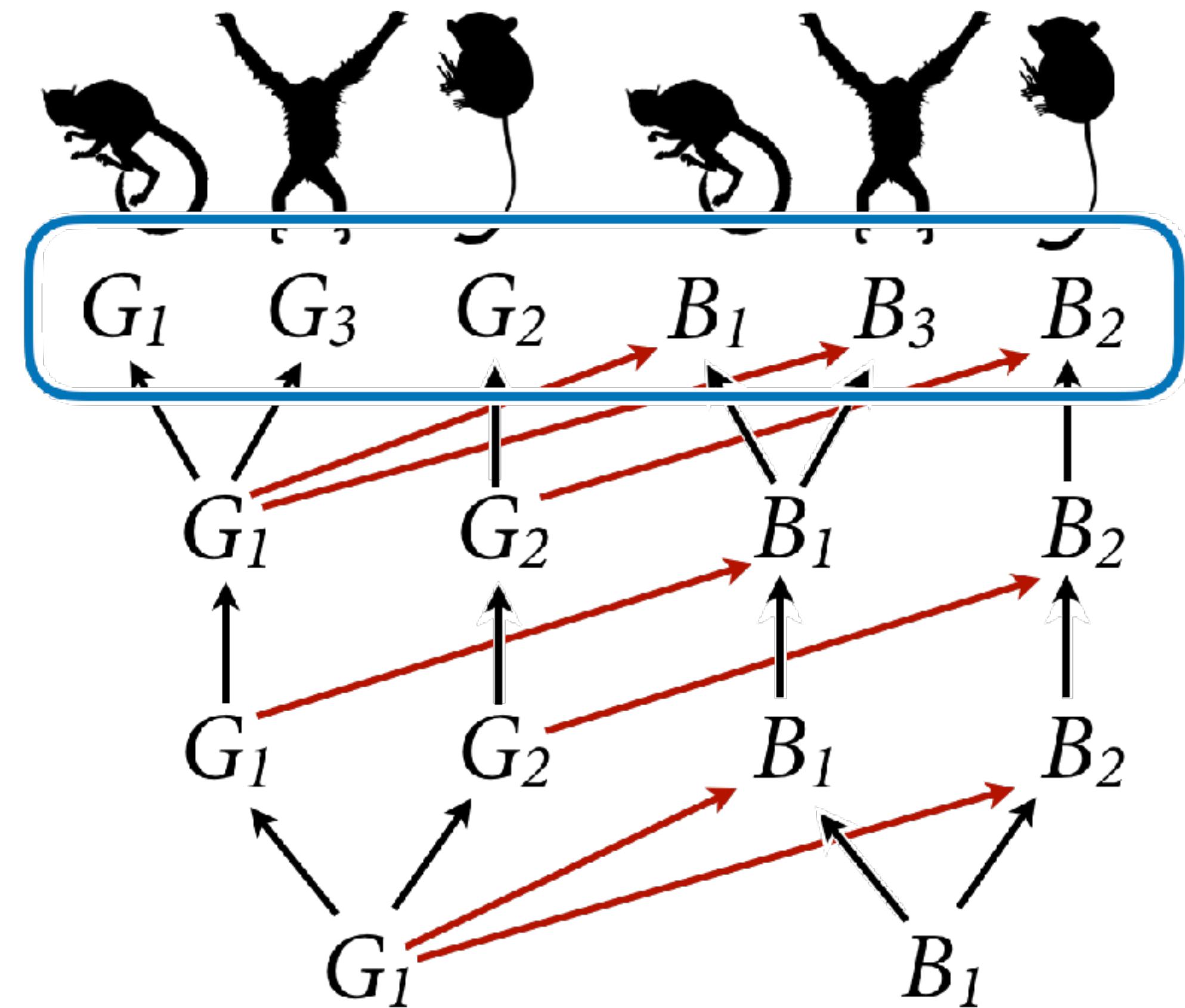


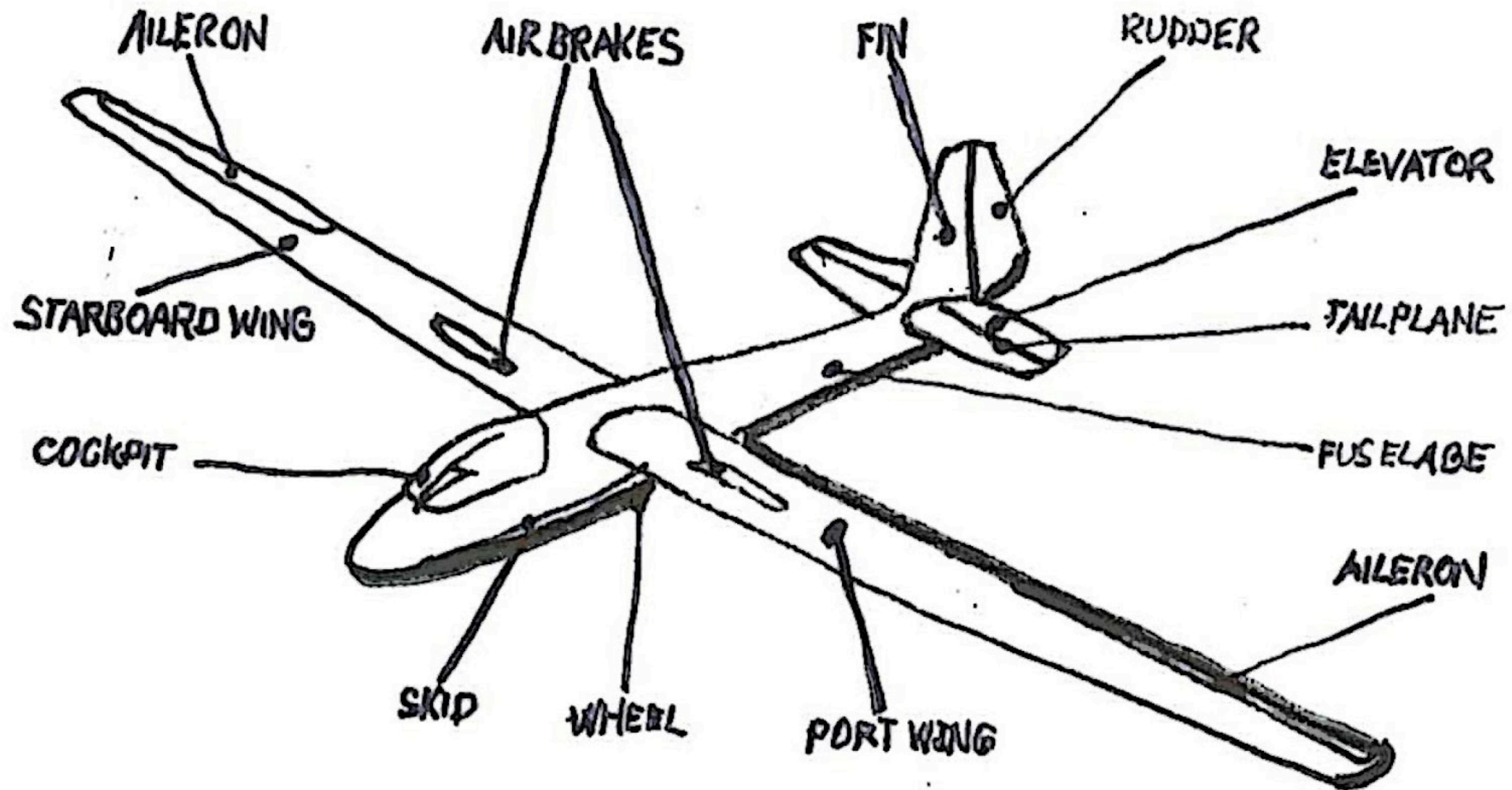
# Phylogenetic regression

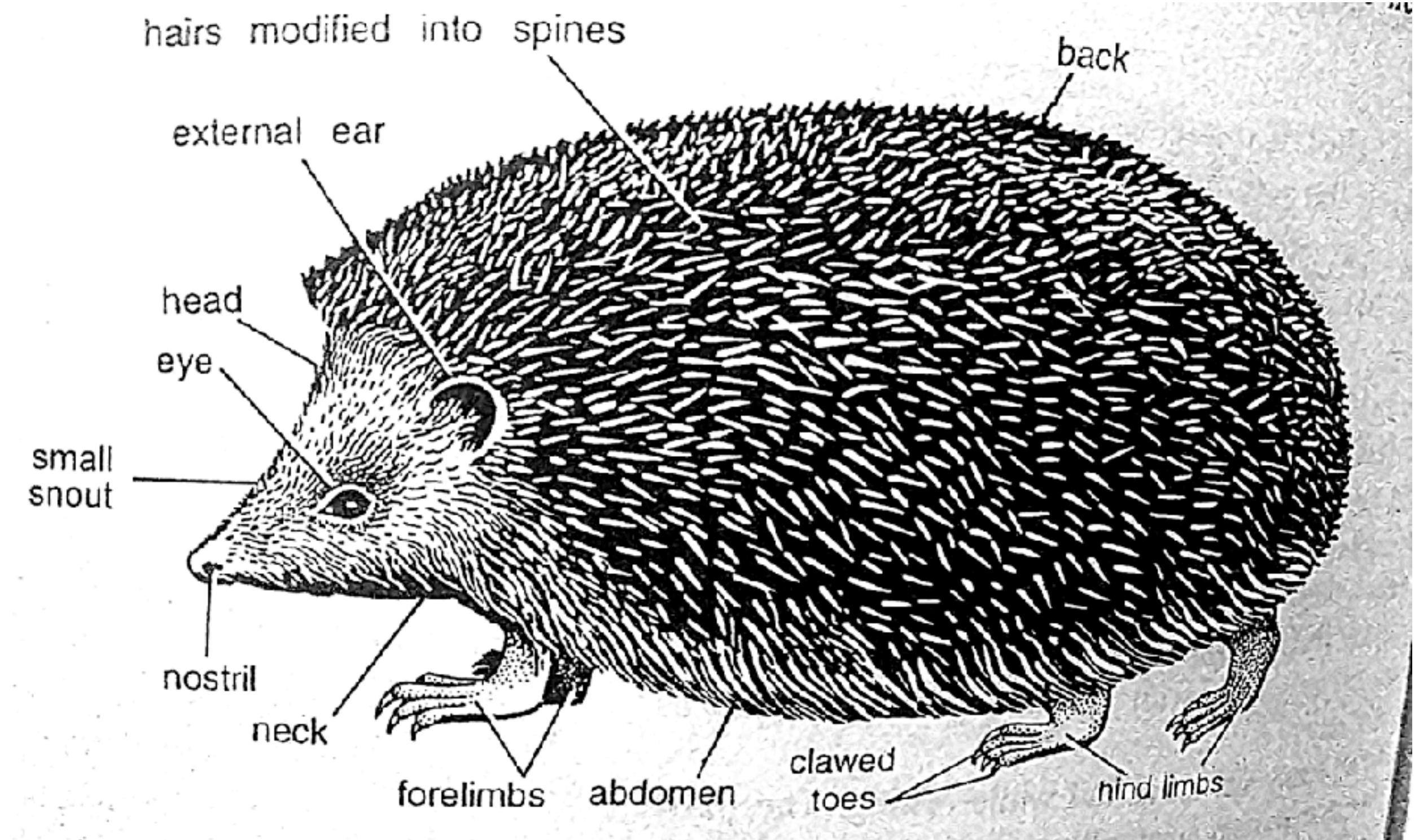
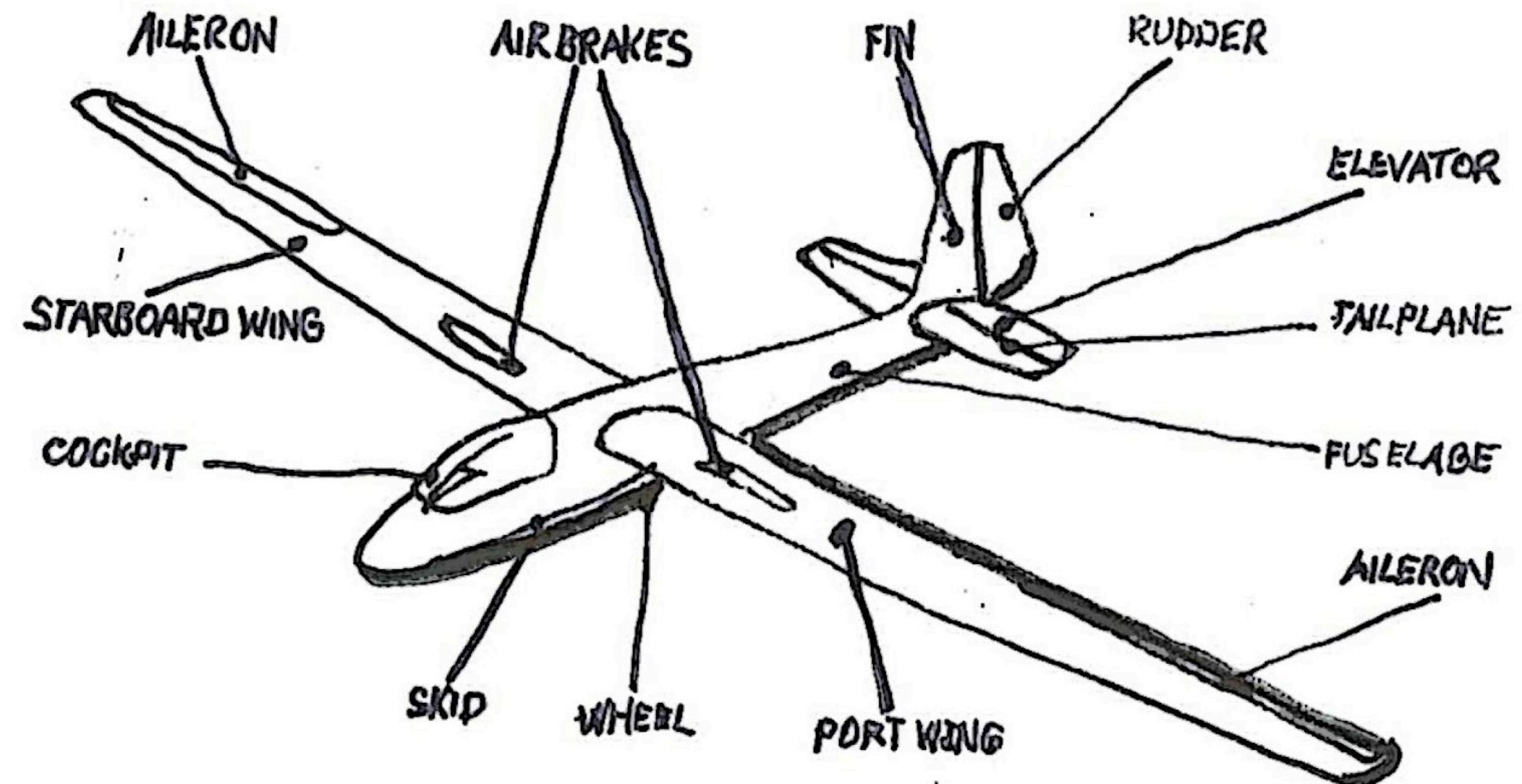
Lingering problems:

(1) What about phylogenetic uncertainty?

(2) Don't these traits influence one another reciprocally over time?



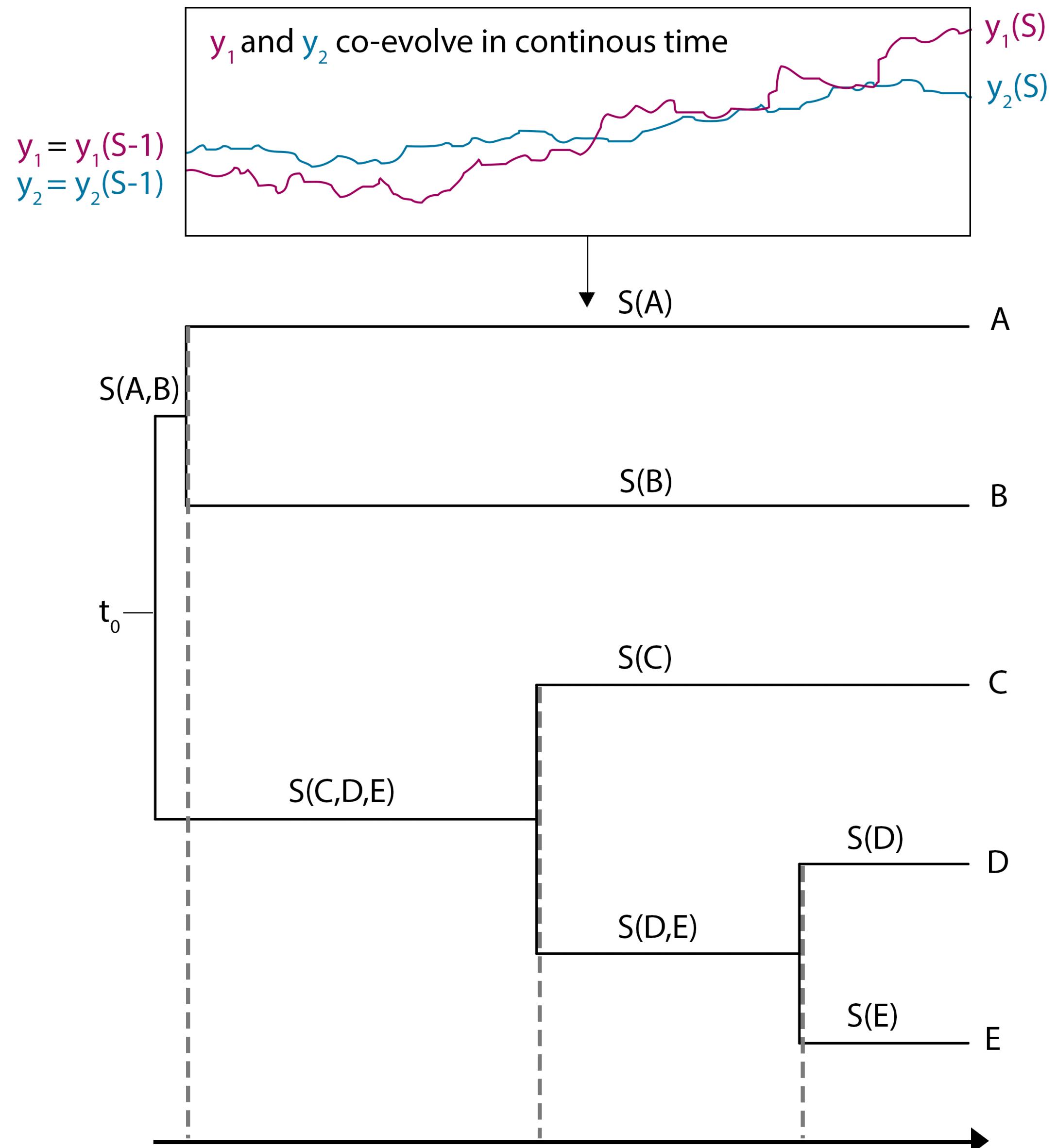




*A glider knows many things.* Gliders and hedgehogs are both complex machines with many mutually influencing parts. Causation in such machines involves powerful feedbacks.

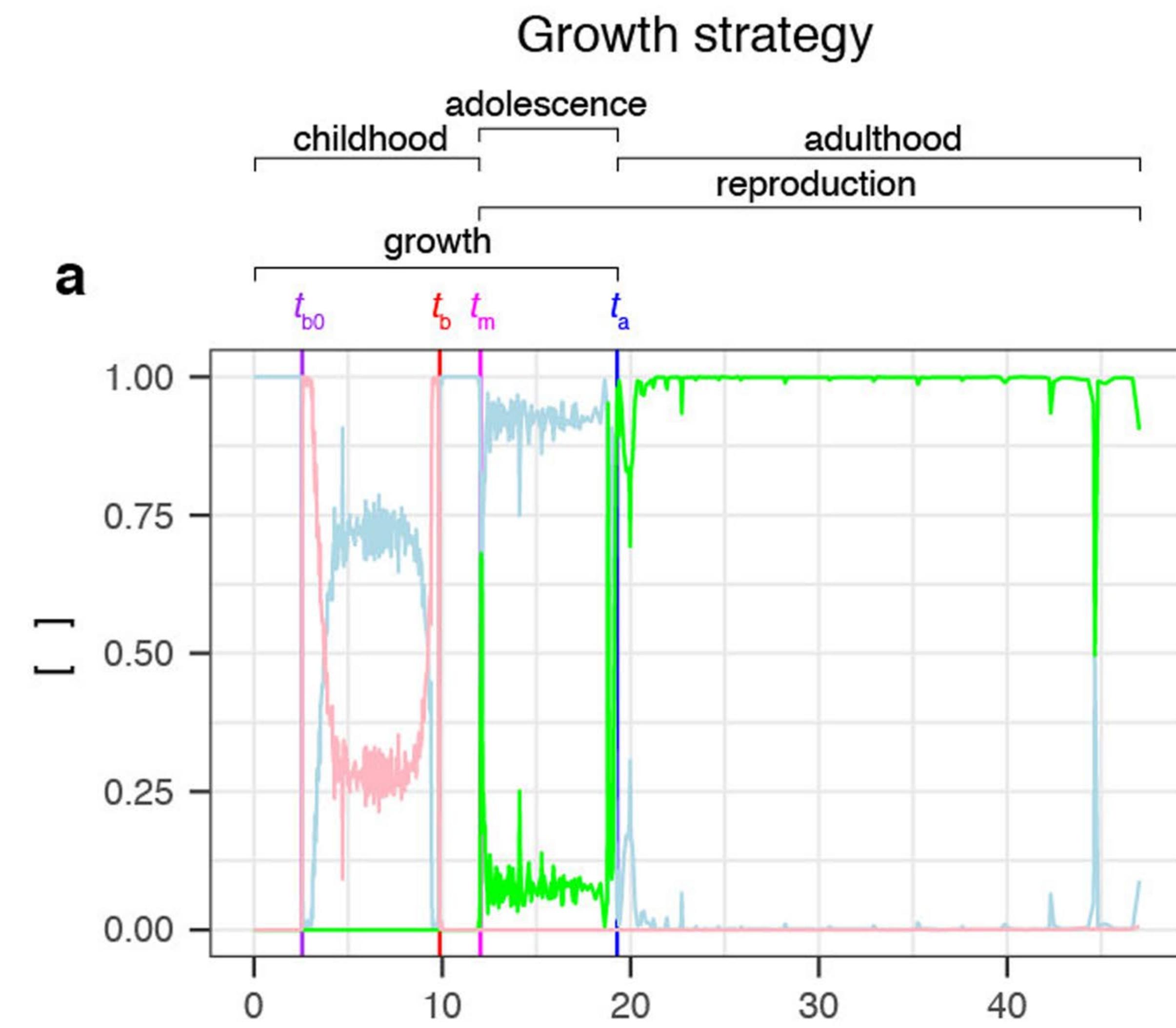
Ringen, Martin, Jaeggi 2021

*Drift-coevolution dynamics*



González-Forero & Gardner 2018

*Optimal life history approach*



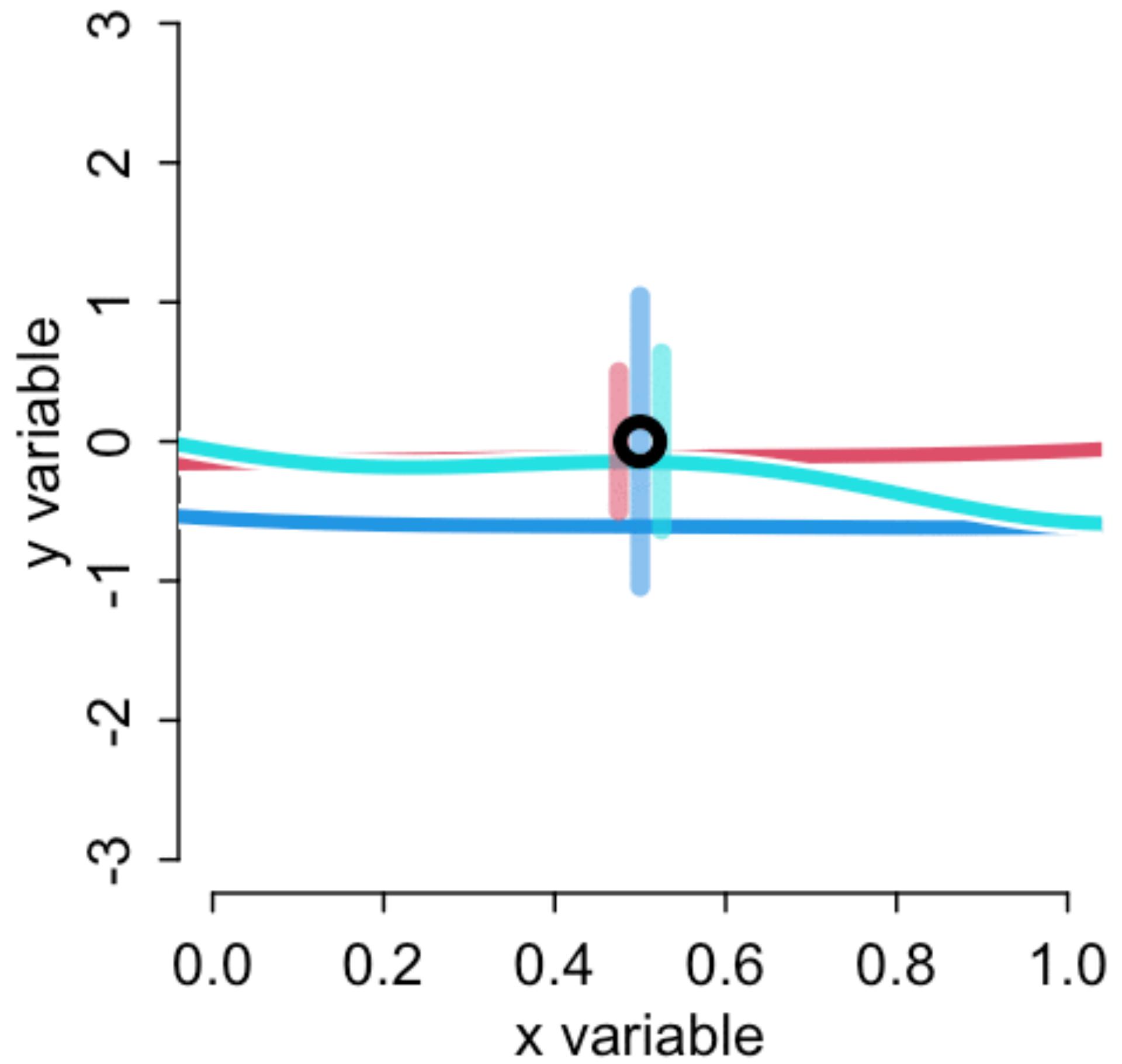
# Gaussian Processes

Partial pooling for continuous categories

Very general approximation engine

Causal theory => covariance kernel

Sensitivity to kernel priors — choose wisely

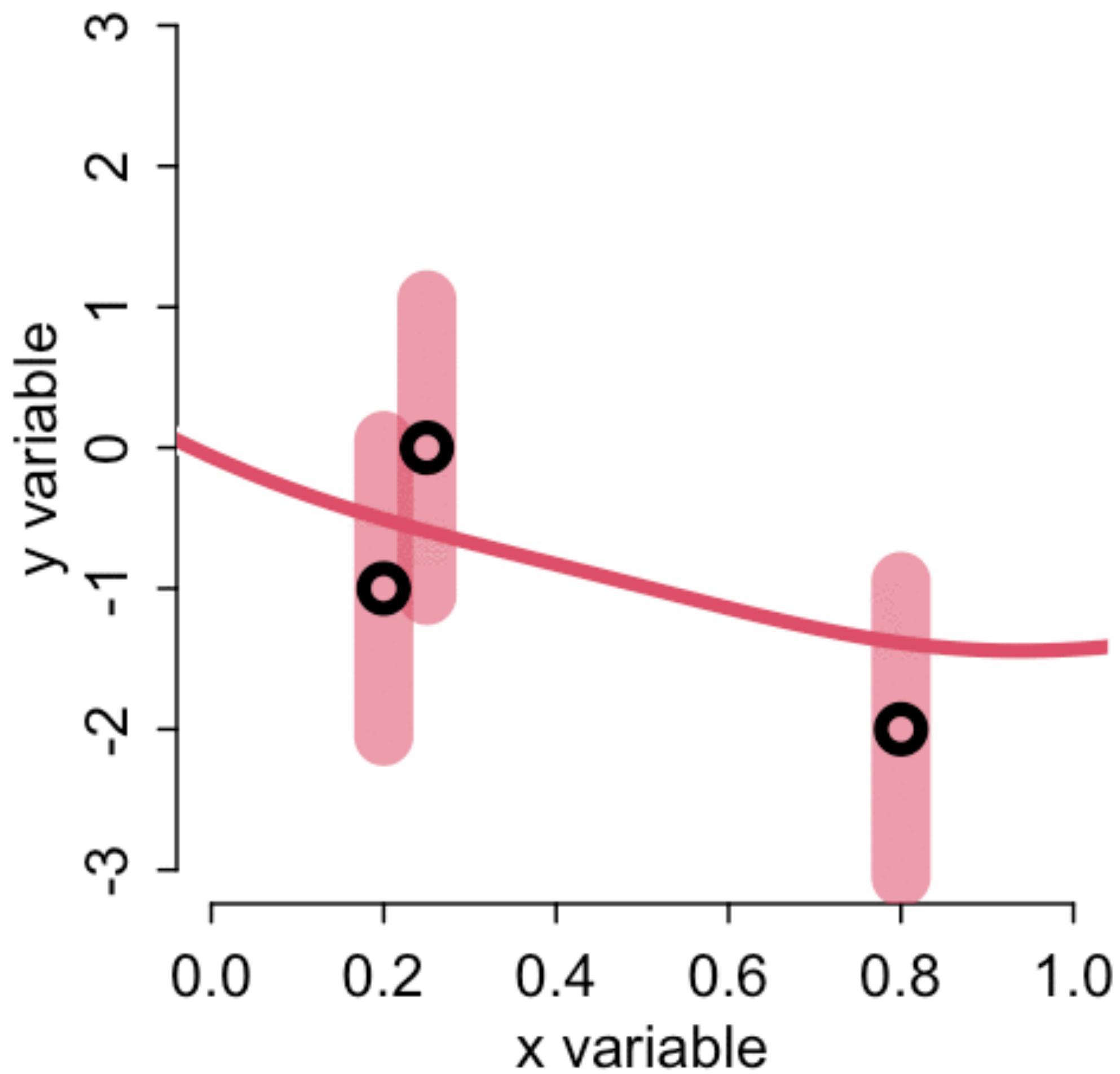


# Gaussian Possibilities

Automatic relevance determination  
(ARD): Multiple distance  
dimensions inside the kernel

Multi-output Gaussian processes:  
Draw vectors from kernel

Telemetry, navigation: Real-time  
tracking and error correction  
(*Kálmán filter*)



# Course Schedule

Week 1	Bayesian inference	Chapters 1, 2, 3
Week 2	Linear models & Causal Inference	Chapter 4
Week 3	Causes, Confounds & Colliders	Chapters 5 & 6
Week 4	Overfitting / MCMC	Chapters 7, 8, 9
Week 5	Generalized Linear Models	Chapters 10, 11
Week 6	Ordered categories & Multilevel models	Chapters 12 & 13
Week 7	More Multilevel models	Chapters 13 & 14
Week 8	Social Networks & Gaussian Processes	Chapter 14
Week 9	Measurement & Missingness	Chapter 15
Week 10	Generalized Linear Madness	Chapter 16

[https://github.com/rmcelreath/stat\\_rethinking\\_2023](https://github.com/rmcelreath/stat_rethinking_2023)

