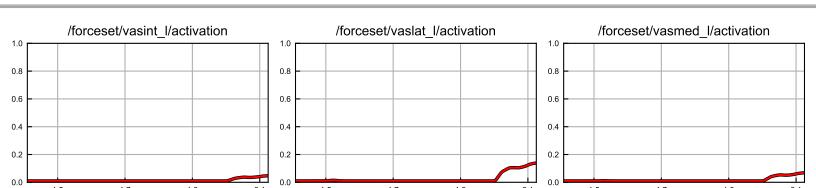


k\Repos\balance-exo-sim\results\perturbed\perturbed\_torque0\_time60\_rise10\_fall5\subject04\perturbed\_torque0\_time60\_rise10\_fall5\_exp k\Repos\balance-exo-sim\results\perturbed\perturbed\_torque0\_time60\_rise10\_fall5\subject04\unperturbed.sto k\Repos\balance-exo-sim\results\perturbed\perturbed\_torque0\_time60\_rise10\_fall5\subject04\perturbed\_torque0\_time60\_rise10\_fall5.sto



time (s)

time (s)

2.1

time (s)

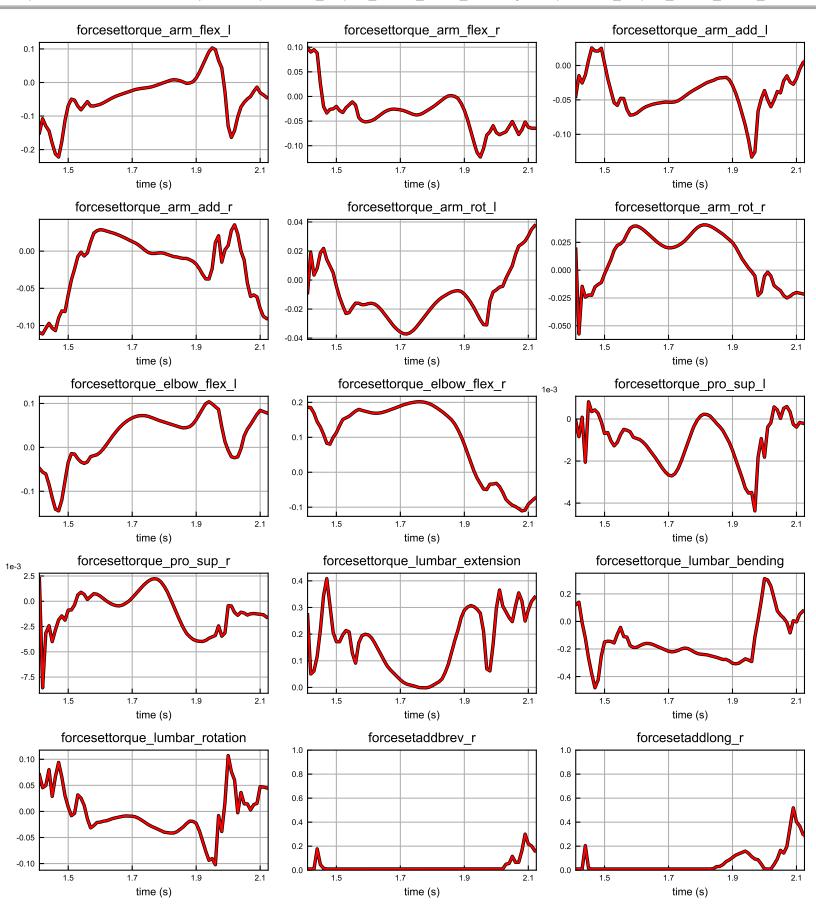
k\Repos\balance-exo-sim\results\perturbed\perturbed\_torque0\_time60\_rise10\_fall5\subject04\perturbed\_torque0\_time60\_rise10\_fall5\_exp k\Repos\balance-exo-sim\results\perturbed\perturbed\_torque0\_time60\_rise10\_fall5\subject04\unperturbed.sto k\Repos\balance-exo-sim\results\perturbed\perturbed\_torque0\_time60\_rise10\_fall5\subject04\perturbed\_torque0\_time60\_rise10\_fall5.sto

/forceset/gaslat\_r/...zed\_tendon\_force /forceset/gasmed\_r/...zed\_tendon\_force /forceset/soleus\_r/...zed\_tendon\_force 0.8 0.8 0.8 0.6 0.4 0.4 0.4 0.2 0.2 0.2 0.0 0.0 0.0 time (s) time (s) time (s) /forceset/gaslat\_l/...zed\_tendon\_force /forceset/gasmed\_I/...zed\_tendon\_force /forceset/soleus\_I/...zed\_tendon\_force 1.0 1.0 0.8 8.0 0.8 0.6 0.6 0.6 0.4 0.2 0.2

time (s)

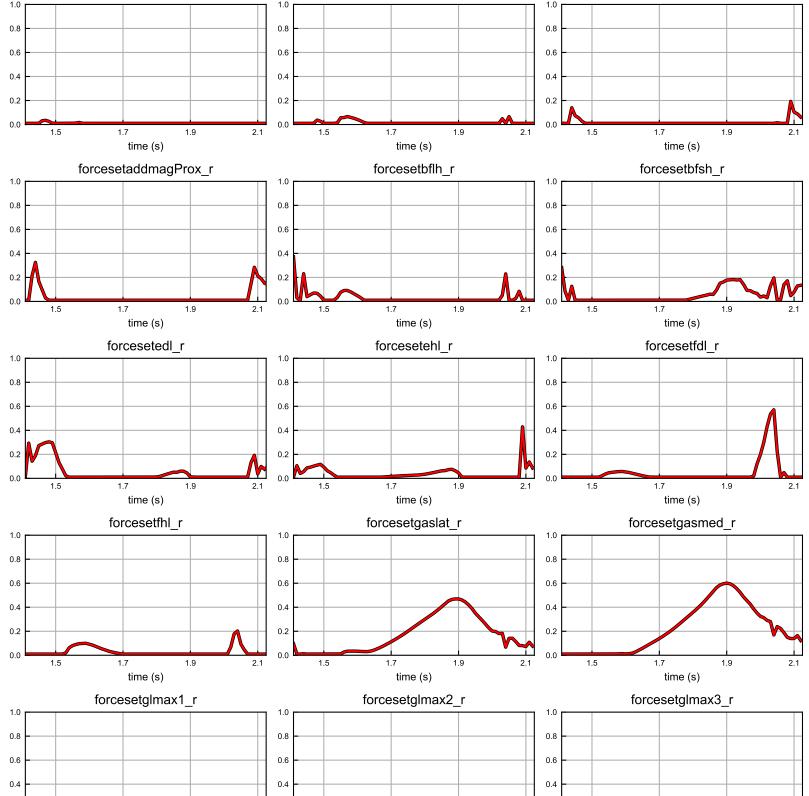
time (s)

time (s)



k\Repos\balance-exo-sim\results\perturbed\perturbed\_torque0\_time60\_rise10\_fall5\subject04\perturbed\_torque0\_time60\_rise10\_fall5\_exp

k\Repos\balance-exo-sim\results\perturbed\perturbed torque0 time60 rise10 fall5\subject04\unperturbed.sto k\Repos\balance-exo-sim\results\perturbed\perturbed\_torque0\_time60\_rise10\_fall5\subject04\perturbed\_torque0\_time60\_rise10\_fall5.sto forcesetaddmagDist\_r forcesetaddmaglsch\_r forcesetaddmagMid\_r 1.0 1.0 1.0 0.8 0.8 8.0



time (s)

0.2

time (s)

0.2

0.2

time (s)

