Computer Vision

CVI620

Session 2 01/2025

cameras



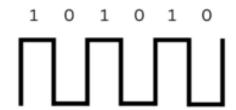
Digital vs Analog

- Continuous signals
- Infinite values in a range

- Discrete signals
- Finite values (0s and 1s)



Digital



Digital Images



Everything is signal



A representation of visual information stored digitally.



Humans are sensitive to light at wavelengths between 400 nm and 700 nm and hence most camera image sensors are



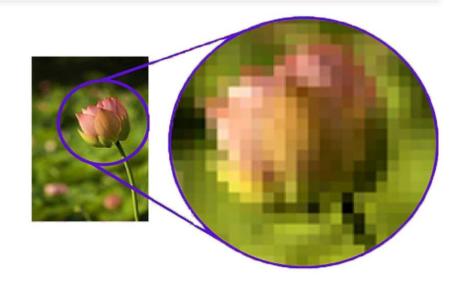
designed to be sensitive at those wavelengths.



Composed of pixels (picture elements).

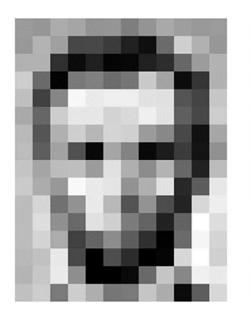
Pixels

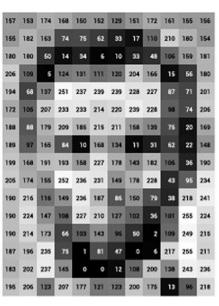
- Smallest unit of a digital image.
- Represents color or intensity information.
- Images are made of a grid of pixels.
- Higher resolution = more pixels = better detail.
- Pixels are typically organized in a 2D array (image matrix), with rows and columns corresponding to their position in the image.
- Size of the picture is the number of pixels in rows and columns (width*height)
- Resolution is number of pixels

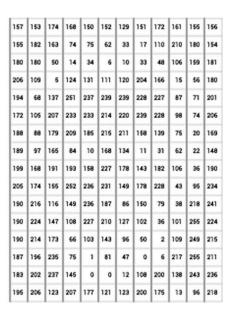


Pixel Values

Each pixel can have a value between 0 to 255 Reduced processing costs



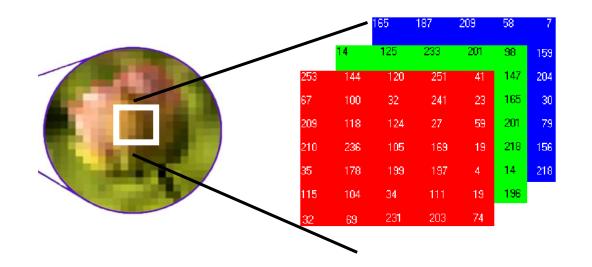






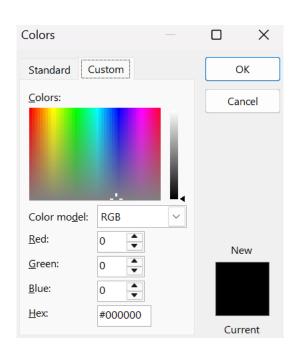
Channels

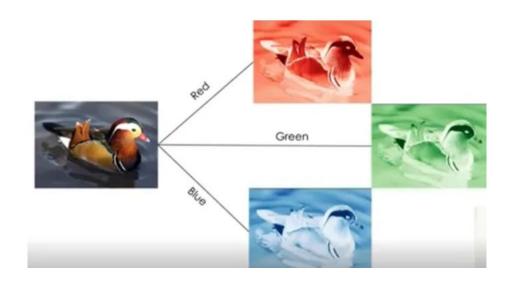
- 3 main pigmentation were introduced to represent color: Red, Green, Blue
- We call each one a channel
- 256*256*256 = 2^24 different possible colors

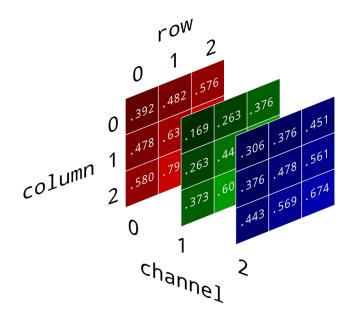




Channels





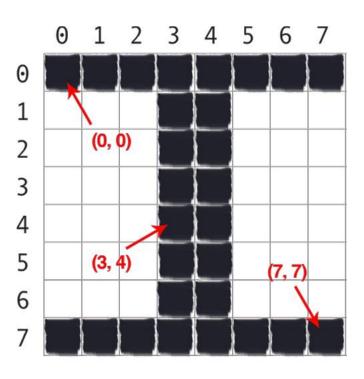


Binary Image

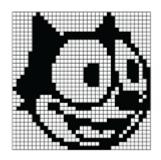
- 0 or 255
- 255 is represented with a logical 1
- 1 or no channels

1	1	1	1	1	1	1	1	1	1
1	0	0	0	1	1	0	0	0	1
1	1	0	1	1	1	1	0	1	1
1	1	0	1	1	1	1	0	1	1
1	1	0	1	1	1	1	0	1	1
1	1	0	0	0	0	0	0	1	1
1	1	0	1	1	٦	1	0	1	1
1	1	0	1	1	1	1	0	1	1
1	1	0	1	1	1	1	0	1	1
1	0	0		1	1	0	0	0	1
1	1	1	1	1	1	1	1	1	1

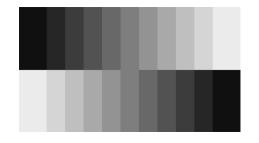
Image Coordinates



Color Models



Binary: 0 or 1 - black or white



Grayscale: 0 (black) to 255 (white)

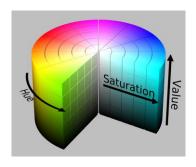


RGB: Combination of Red, Green, Blue (RGB)





CMYK: Cyan, Magenta, Yellow, and Key (Black)



HSV: Hue, Saturation, Value

Reading Image

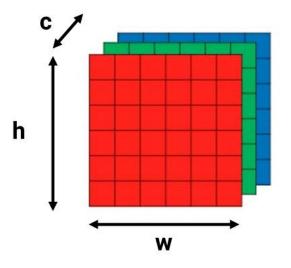
```
import cv2
import numpy as np

image_array = cv2.imread('Lucy.jpg')
print(f"Image shape: {image_array.shape}")
```

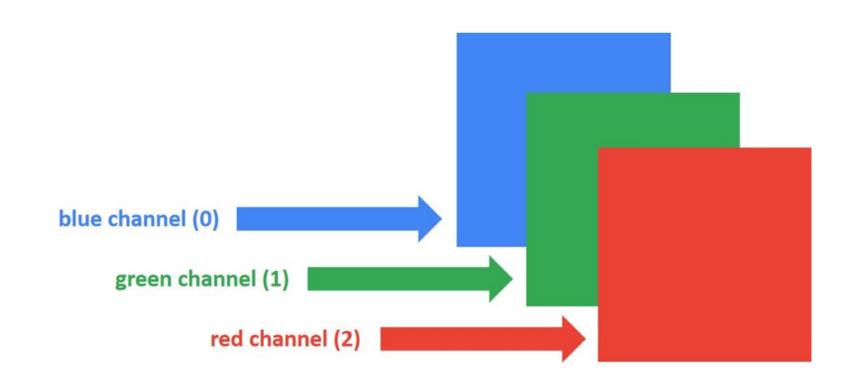
https://opencv24-python-tutorials.readthedocs.io/en/latest/index.html

Image Shape

h, w, c = img.shape



Channel Extraction



Saving Image

• Store processed images for later use or analysis

```
import cv2
image = cv2.imread("input.jpg")
gray_image = cv2.cvtColor(image, cv2.COLOR_BGR2GRAY)

cv2.imwrite("output.jpg", gray_image)
```

Saving Image

- Compresses image to specific format
- Writes compressed image to file

cv2.imwrite(filename, image[, params])

filename: The path and name of the file where the image will be saved.

Example: 'output.jpg'

image: The image array to be saved (e.g., a NumPy array).

params (optional): Format-specific save parameters, such as compression quality for .jpg or .png.

```
import cv2
image = 255 * np.ones((100, 100, 3), dtype=np.uint8)
cv2.imwrite('output.jpg', image)
```

Showing Image

```
1 cv2.imshow('img', image_array)
2 cv2.waitKey()
3 # cv2.destroyAllWindows(0)
```

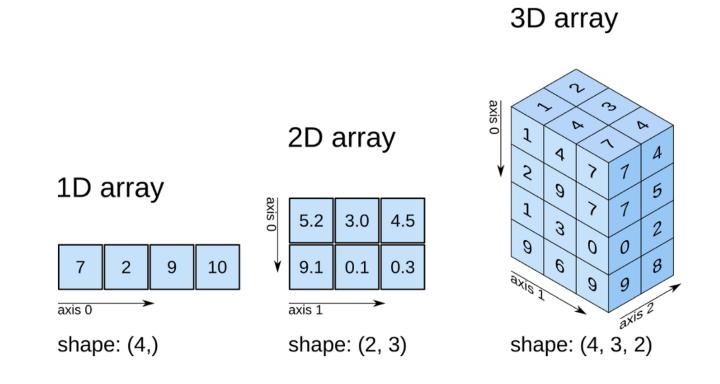
https://opencv24-python-tutorials.readthedocs.io/en/latest/py_tutorials/py_gui/py_image_display/py_image_display.html

Numpy Arrays

- Core data structure for images in OpenCV.
- Represent images as multi-dimensional arrays:
- Grayscale: 2D (Height x Width)
- Color: 3D (Height x Width x Channels).

```
1 pixel = image_array[60, 17] # (B, G, R) for color images
2 image_array[5, 80] = [255, 0, 0] # Set pixel to blue
3 roi = image_array[50:200, 100:300]
```

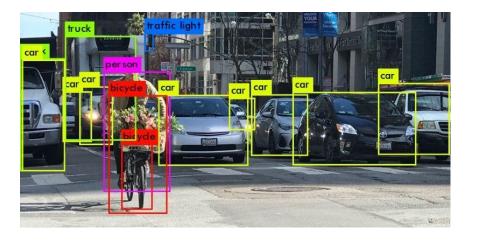
Numpy Coordinates



Region of Interest (ROI)

- A specific part of an image for focused processing
- Enhance efficiency by processing only the necessary area
- Common in object detection, image cropping, and analysis

• uint8



Slicing

• Extracting a portion of a NumPy array

```
array[start:stop:step]
```

```
1 import numpy as np
2
3 matrix = np.array([[1, 2, 3], [4, 5, 6], [7, 8, 9]])
4 slice = matrix[0:2, 1:3]
```

```
1 import cv2
2 image = cv2.imread("image.jpg")
3 roi = image[50:200, 100:300] #crop
4 cv2.imshow("ROI", roi)
5 cv2.waitKey(0)
6
```

Cropping

cropped = img[411:1560, 1700:3000]



Exercise

 Copy an ROI from your image, and paste it in another region

Convert Channels

Changing the color format or extracting individual color channels.

cv2.cvtColor(image, conversion_code)

cv2.COLOR_BGR2GRAY - Convert to grayscale

cv2.COLOR_BGR2RGB - Convert to RGB

cv2.COLOR_BGR2HSV - Convert to HSV

b, g, r = cv2.split(image) # Blue, Green, Red channels

merged_image = cv2.merge([b, g, r])

Image Formats

- File types that store visual information in various ways.
- For communicating with Hardware. Like a "protocol".
- They determine how images are saved, compressed, and displayed.
- To balance quality and file size for different use cases.
- Specific formats cater to unique needs like transparency, animation, or high-resolution printing
- Optimize images for web, print, or storage purposes
- Storage formats (e.g., BMP, JPEG, PNG) compress and encode pixel data for efficient use.



Format Examples

JPEG (JPG):

- Best for: Photographs and complex images.
- Features: Lossy compression (small size, lower quality at high compression).
- No transparency support.

PNG:

- Best for: Graphics, logos, and transparent images.
- Features: Lossless compression and transparency support.

TIFF:

- Best for: High-quality printing and professional imaging.
- Features: Lossless or lossy compression, supports layers, and large file sizes.

Padding

cv2.copyMakeBorder(src, top, bottom, left, right, borderType[, value])

```
src: Input image.
```

top, bottom, left, right: Pixels to add on each side.

borderType: Type of border:

cv2.BORDER_CONSTANT - Fixed color border.

cv2.BORDER_REFLECT - Mirrored border.

cv2.BORDER_REPLICATE - Extends edge pixels.

cv2.BORDER_WRAP - Wraps image around.

value (optional): Border color for BORDER_CONSTANT.

Video

- Videos are sequences of images
- A class to capture video streams from:
- Webcam
- Video files (e.g., .mp4, .avi)
- IP cameras or other sources.
- object being created

```
1 cap = cv2.VideoCapture(0)
2
3 # 0 for the default webcam
4 # Path to a video file for playback
5 # 1, 2, ... for external cameras
6 # IP
```

```
1 ret, frame = cap.read()
2 # ret: Boolean, True if frame is read successfully
3 # frame: Captured image array
4 cap.release()
5 cv2.destroyAllWindows()
```

```
cap = cv2.videoCapture("filename.mp4")

while True:
    ret, frame = cap.read()

if frame is None: break

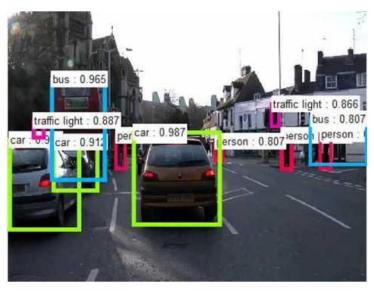
cv2.imshow("frame", frame)

if cv2.waitKey(30) == ord('q'):

heads
```

Drawing Shapes





Line

• draw a straight line on an image

cv2.line(image, pt1, pt2, color, thickness)

image: Input image where the line will be drawn pt1: starting point (x1, y1) (W, H) pt2: ending point (x2, y2) color: line color in BGR format (e.g., (255, 0, 0) for blue) thickness: line thickness (integer)

```
import cv2
import numpy as np

#blank image
image = np.zeros((400, 400, 3), dtype=np.uint8)

cv2.line(image, (50, 50), (350, 350), (255, 255, 255), thickness=3)

cv2.imshow("line example", image)

cv2.waitKey(0)

cv2.destroyAllWindows()
```

Rectangle

Draw rectangle on an image

cv2.rectangle(image, pt1, pt2, color, thickness)

image: Input image where the rectangle will be drawn.

pt1: Top-left corner (x1, y1).

pt2: Bottom-right corner (x2, y2).

color: Rectangle color in BGR format (e.g., (0, 255, 0) for

green).

thickness: Border thickness (integer). Use -1 to fill the

rectangle.

```
5  image = np.zeros((400, 400, 3), dtype=np.uint8)
6
7  cv2.rectangle(image, (50, 50), (350, 300), (0, 255, 0), thickness=5)
8
9  cv2.imshow("Rectangle Example", image)
10  cv2.waitKey(0)
11  cv2.destroyAllWindows()
```

Circle

• Draw circle

cv2.circle(image, center, radius, color, thickness)

image: input image where the circle will be drawn

center: center of the circle (x, y)

radius: radius of the circle (integer)

color: circle color in BGR format (e.g., (0, 0, 255) for red)

thickness: circle thickness (integer). Use -1 for a filled circle

Text

Add text on an image

cv2.putText(image, text, org, font, font_scale, color, thickness, line_type)

```
image: Input image where text will be added.
```

text: The string to display.

org: Bottom-left corner of the text (x, y).

font: Font type (e.g., cv2.FONT_HERSHEY_SIMPLEX).

font_scale: Scale factor for font size.

color: Text color in BGR format (e.g., (255, 255, 255) for

white).

thickness: Thickness of the text stroke.

line_type: Type of line for the text (e.g., cv2.LINE_AA).