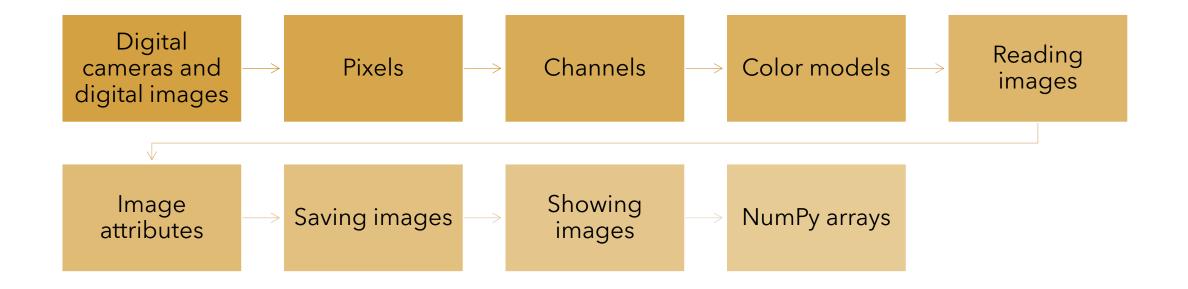
# Computer Vision

CVI620

Session 3 01/2025

### Overview



```
# reading image
image = cv2.imread("Lucy.jpg")
print(f"image array is: {image}")
# showing image
cv2.imshow("cat", image)
cv2.waitKey(0)
cv2.destroyAllWindows()
# saving image
cv2.imwrite("lucy_green.jpg", image)
# shape of the image
print(f"image shape is: {image.shape}")
```

### Q & A?

- Python questions
- NumPy questions
- OpenCV questions
- non configuration issues
- Don't have an idea!

#### Min and Max



Dynamic Range Adjustment: Normalizing pixel intensity for consistent brightness and contrast



Thresholding: Setting thresholds for binary segmentation or feature detection.



Error Detection: Identifying overexposed (max) or underexposed (min) areas in images.



Feature Extraction: Detecting edges or regions based on intensity differences.



Quality Control: Ensuring uniform intensity distribution in medical or industrial imaging.

# Finding Max Pixel Value

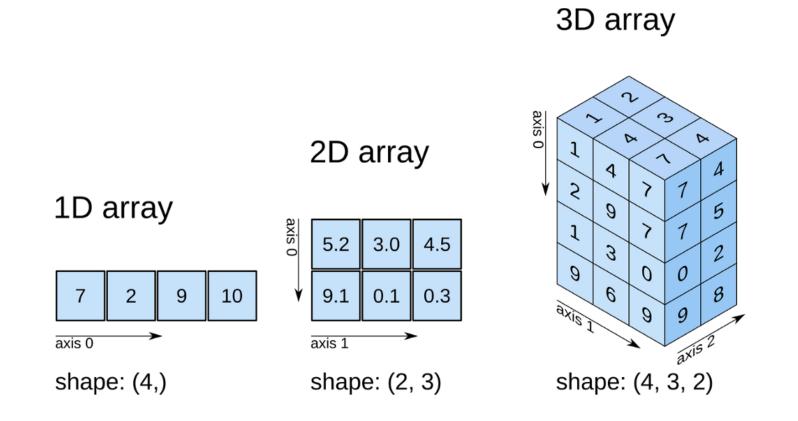
```
import cv2
img = cv2.imread("sample.png")
rows, cols, ncolor = img.shape
red = 2 # index of red values in (b,g,r)
max = 0
for i in range(rows):
    for j in range(cols):
        k = img.item(i, j, red)
        if k > max:
            max = k
            print("Maximum red value in image is ", max)
```

# Finding Max Red Value

• What is a more efficient code to find the maximum red channel value, as we did in the previous slide?

# Numpy Coordinates

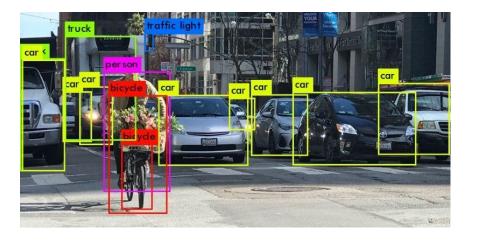
vector, matrix, tensor



#### Region of Interest (ROI)

- A specific part of an image for focused processing
- Enhance efficiency by processing only the necessary area
- Common in object detection, image cropping, and analysis

• uint8



# Slicing

• Extracting a portion of a NumPy array

```
array[start:stop:step]
```

```
1 import numpy as np
2
3 matrix = np.array([[1, 2, 3], [4, 5, 6], [7, 8, 9]])
4 slice = matrix[0:2, 1:3]
```

```
1 import cv2
2 image = cv2.imread("image.jpg")
3 roi = image[50:200, 100:300] #crop
4 cv2.imshow("ROI", roi)
5 cv2.waitKey(0)
```

# Cropping

cropped = img[411:1560, 1700:3000]



### Exercise

 Copy an ROI from your image, and paste it in another region

# Split and Merge

- Color Channel Processing: Isolating specific channels for analysis or filtering (enhancing the red channel in an image)
- Grayscale Conversion: Extracting a single channel to create a custom grayscale image
- Channel-Based Feature Extraction: Using specific channels to detect features like edges or color patterns
- Lustom Image Composition: Replacing or modifying one channel and merging back to create new images.
- Color Space Conversion: Manipulating individual channels in spaces like HSV, YUV, etc.
- Masking: Applying operations to specific channels and merging them back for the final result. ■

```
# Split into 3 channels
b,g,r = cv2.split(img)
# Merge 3 channels into one image
img = cv2.merge((b,g,r))
```

# Padding

Preserve Dimensions: Maintain spatial size during convolutions in CNNs

Data Augmentation: Enable cropping, shifting, or rotation without losing content

Standardization: Resize images to uniform dimensions

Object Detection: Keep bounding boxes within image boundaries

Edge Processing: Avoid truncation of features at image borders

Image Alignment: Align images of different sizes for stitching or other operations

# Padding

- src: It is the source image
- top: It is the border width in number of pixels in top direction
- bottom: It is the border width in number of pixels in bottom direction
- left: It is the border width in number of pixels in left direction
- right: It is the border width in number of pixels in right direction
- borderType: It depicts what kind of border to be added. It is defined by flags like cv2.BORDER\_CONSTANT, cv2.BORDER\_REFLECT, etc
- value: It is an optional parameter which depicts color of border if border type is cv2.BORDER\_CONSTANT.

# BorderType

cv2.BORDER\_CONSTANT: It adds a constant colored border. The value should be given as a keyword argument

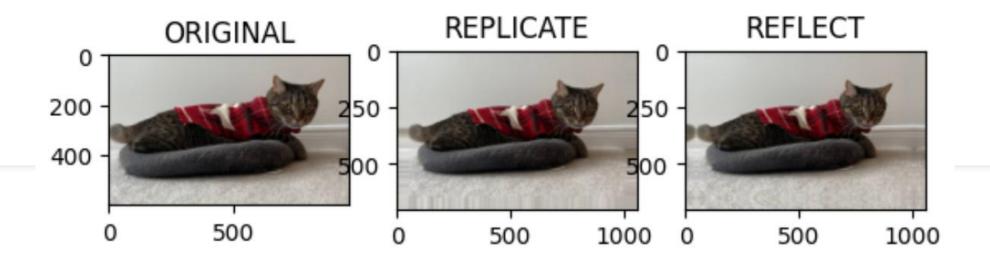
cv2.BORDER\_REFLECT: The border will be mirror reflection of the border elements. Suppose, if image contains letters "abcdefg" then output will be "gfedcba|abcdefg|gfedcba".

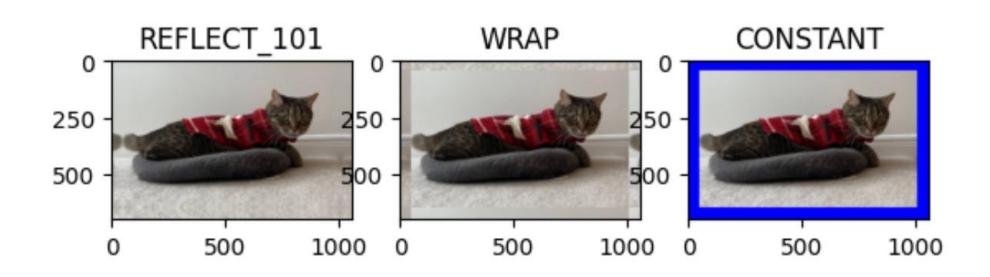
cv2.BORDER\_REFLECT\_101 or cv2.BORDER\_DEFAULT: It does the same works as reflect

cv2.BORDER\_REFLECT but with slight change. Suppose, if image contains letters "abcdefgh" then output will be "gfedcb|abcdefgh|gfedcba".

cv2.BORDER\_REPLICATE: It replicates the last element. Suppose, if image contains letters "abcdefgh" then output will be "aaaaa|abcdefgh|hhhhh".

```
import cv2
import matplotlib.pyplot as plt
BLUE = [255,0,0]
bsz = 50
img1 = cv2.imread('Lucy.jpg')
replicate = cv2.copyMakeBorder(img1,bsz,bsz,bsz,bsz,cv2.BORDER_REPLICATE)
reflect = cv2.copyMakeBorder(img1,bsz,bsz,bsz,bsz,cv2.BORDER_REFLECT)
reflect101 = cv2.copyMakeBorder(img1,bsz,bsz,bsz,bsz,cv2.BORDER_REFLECT_101)
wrap = cv2.copyMakeBorder(img1,bsz,bsz,bsz,bsz,cv2.BORDER_WRAP)
constant= cv2.copyMakeBorder(img1,bsz,bsz,bsz,bsz,cv2.BORDER_CONSTANT,value=BLUE)
plt.subplot(231), plt.imshow(cv2.cvtColor(img1,cv2.COLOR_BGR2RGB)), plt.title('ORIGIN
plt.subplot(232), plt.imshow(cv2.cvtColor(replicate,cv2.COLOR_BGR2RGB)), plt.title('
plt.subplot(233), plt.imshow(cv2.cvtColor(reflect,cv2.COLOR_BGR2RGB)), plt.title('REF
plt.subplot(234), plt.imshow(cv2.cvtColor(reflect101,cv2.COLOR_BGR2RGB)), plt.title(
plt.subplot(235), plt.imshow(cv2.cvtColor(wrap,cv2.COLOR_BGR2RGB)), plt.title('WRAP'
plt.subplot(236), plt.imshow(cv2.cvtColor(constant,cv2.COLOR_BGR2RGB)), plt.title('CO
plt.show()
```





#### Convert Channels

Changing the color format or extracting individual color channels.

cv2.cvtColor(image, conversion\_code)

cv2.COLOR\_BGR2GRAY - Convert to grayscale

cv2.COLOR\_BGR2RGB - Convert to RGB

cv2.COLOR\_BGR2HSV - Convert to HSV

b, g, r = cv2.split(image) # Blue, Green, Red channels

merged\_image = cv2.merge([b, g, r])

#### Image Formats

- File types that store visual information in various ways.
- For communicating with Hardware. Like a "protocol".
- They determine how images are saved, compressed, and displayed.
- To balance quality and file size for different use cases.
- Specific formats cater to unique needs like transparency, animation, or high-resolution printing
- Optimize images for web, print, or storage purposes
- Storage formats (e.g., BMP, JPEG, PNG) compress and encode pixel data for efficient use.



# Format Examples

#### JPEG (JPG):

- Best for: Photographs and complex images.
- Features: Lossy compression (small size, lower quality at high compression).
- No transparency support.

#### PNG:

- Best for: Graphics, logos, and transparent images.
- Features: Lossless compression and transparency support.

#### TIFF:

- Best for: High-quality printing and professional imaging.
- Features: Lossless or lossy compression, supports layers, and large file sizes.

#### Video

- Videos are sequences of images
- A class to capture video streams from:
- Webcam
- Video files (e.g., .mp4, .avi)
- IP cameras or other sources.
- object being created

```
1 cap = cv2.VideoCapture(0)
2
3 # 0 for the default webcam
4 # Path to a video file for playback
5 # 1, 2, ... for external cameras
6 # IP
```

```
1 ret, frame = cap.read()
2 # ret: Boolean, True if frame is read successfully
3 # frame: Captured image array
4 cap.release()
5 cv2.destroyAllWindows()
```

```
cap = cv2.videoCapture("filename.mp4")

while True:
    ret, frame = cap.read()

if frame is None: break

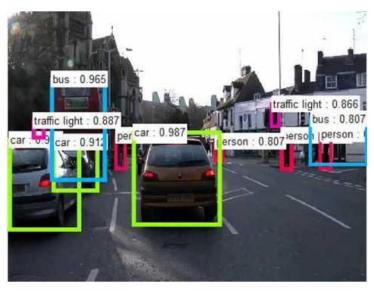
cv2.imshow("frame", frame)

if cv2.waitKey(30) == ord('q'):

heads
```

# Drawing Shapes





#### Line

• draw a straight line on an image

cv2.line(image, pt1, pt2, color, thickness)

image: Input image where the line will be drawn pt1: starting point (x1, y1) (W, H) pt2: ending point (x2, y2) color: line color in BGR format (e.g., (255, 0, 0) for blue) thickness: line thickness (integer)

```
import cv2
import numpy as np

#blank image
image = np.zeros((400, 400, 3), dtype=np.uint8)

cv2.line(image, (50, 50), (350, 350), (255, 255, 255), thickness=3)

cv2.imshow("line example", image)

cv2.waitKey(0)

cv2.destroyAllWindows()
```

# Rectangle

Draw rectangle on an image

cv2.rectangle(image, pt1, pt2, color, thickness)

image: Input image where the rectangle will be drawn.

pt1: Top-left corner (x1, y1).

pt2: Bottom-right corner (x2, y2).

color: Rectangle color in BGR format (e.g., (0, 255, 0) for

green).

thickness: Border thickness (integer). Use -1 to fill the

rectangle.

```
5  image = np.zeros((400, 400, 3), dtype=np.uint8)
6
7  cv2.rectangle(image, (50, 50), (350, 300), (0, 255, 0), thickness=5)
8
9  cv2.imshow("Rectangle Example", image)
10  cv2.waitKey(0)
11  cv2.destroyAllWindows()
```

#### Circle

#### • Draw circle

cv2.circle(image, center, radius, color, thickness)

image: input image where the circle will be drawn

center: center of the circle (x, y)

radius: radius of the circle (integer)

color: circle color in BGR format (e.g., (0, 0, 255) for red)

thickness: circle thickness (integer). Use -1 for a filled circle

#### **Text**

#### Add text on an image

cv2.putText(image, text, org, font, font\_scale, color, thickness, line\_type)

image: Input image where text will be added.

text: The string to display.

org: Bottom-left corner of the text (x, y).

font: Font type (e.g., cv2.FONT\_HERSHEY\_SIMPLEX).

font\_scale: Scale factor for font size.

color: Text color in BGR format (e.g., (255, 255, 255) for

white).

thickness: Thickness of the text stroke.

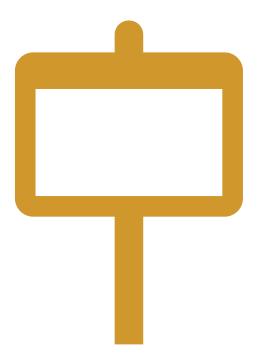
line\_type: Type of line for the text (e.g., cv2.LINE\_AA).

```
cv2.putText(image, "Hello OpenCV!", (50, 200), cv2.FONT_HERSHEY_SIMPLEX,

1, (255, 255, 255), thickness=2, lineType=cv2.LINE_AA)
```

### More shapes

- cv2.line()
- cv2.rectangle()
- cv2.circle()
- cv2.ellipse()
- cv2.polylines()
- cv2.fillPoly()
- cv2.putText()
- cv2.arrowedLine()
- cv2.drawMarker()



## PEP8 Standard

