Title.class / content_amaze.xml

Responsibilities

- Displays welcome message
- Gets skill level from user and sends to Generating class
- Gets maze generator type from user and sends to Generating class
- Gets maze driver from user and sends to Generating class
- Gives option to revisit or explore
- Redirects to Generating screen if explore
- Checks if there are saved mazes when redirect button is pressed
- If there are saved mazes, redirect to Play_previous class
- If there are no saved mazes, redirect to Generating screen

Collaborators

None

Generating.class/generating_amaze.xml

- Generates maze accordingly to the user's input
- Redirects to Play_robot class if maze driver is wall follower
- Redirects to Play class if maze driver is manual
- Receives and displays the progress information in % form
- Display back button to go back to Title screen
- Sends the generated maze to Play/Play_robot classes when progress reaches 100%
- Saves the maze

- Receives skill level from Title class
- Receives maze driver from Title class
- Receives maze generation type from Title class
- Receives progress information from maze.java

Finish.class / finish_amaze.xml

- Displays congratulation message
- Redirects to the Title page if user chooses to play again
- Displays path length

• Knows pathlength from Play class

Play.class / play_amaze.xml

- Gives option to show walls
- Gives option to show full maze
- Gives option to show solutions
- Displays maze
- Displays navigation buttons
- Redirects to Finish class when the user reaches the exit
- Calculates path length
- Displays shortcut button (for proj 4) to Finish page
- Displays back button to Title page

• Receives maze from Generating class

Play_robot.class / play_robot_amaze.xml

- Gives option to show walls
- Gives option to show full maze
- Gives option to show solutions
- Displays maze
- Displays navigation buttons (no function)
- Redirects to Finish class when the robot reaches the exit
- Calculates path length
- Displays shortcut button (for proj 4) to Finish page
- Displays back button to Title page
- Gives option to pause
- Robot moves to the exit using wallfollower method

• Receives maze from Generating class

Play_previous.class / play_previous_amaze.xml

- Opens previously saved maze
- Gives option to show walls
- Gives option to show full maze
- Gives option to show solutions
- Displays maze
- Displays navigation buttons (no function)
- Redirects to Finish class when the robot reaches the exit
- Calculates path length
- Displays shortcut button (for proj 4) to Finish page
- Displays back button to Title page

 Requests and retrieves a previously saved maze from a Generating class

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