

# Exact solution of statistical mechanical models via Dynamic Programming

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Dynamic Programming is a set of techniques for solving some class of mathematical problems in a computationally efficient way. This is typically achieved through a recursive strategy: the solution to a problem is given in the form of an algorithm, and it is found by solving smaller sub-problems similar in aspect to the original one. Here we see two examples where these techniques can be exploited to compute observables of (finite-size) statistical mechanical models. There will be no fancy math involved, just a wise use of the good old summations, multiplications, max/min, and sometimes derivatives.

As a measure of the running time of an algorithm we will be using the **big O notation**.

**Problem 1. Chain-factorized probability distributions** Given  $n$  discrete variables  $x_1, x_2, \dots, x_n$  each taking values in  $\mathcal{X} = \{1, 2, \dots, q\}$  and a function  $f : \mathcal{X}^n \rightarrow \mathbb{R}$

$$f(x_1, x_2, \dots, x_n) = \prod_{i=1}^{n-1} f_i(x_i, x_{i+1})$$

devise an algorithm running in polynomial time in  $n, q$  to compute:

1.  $Z = \sum_{x_1, x_2, \dots, x_n} f(x_1, x_2, \dots, x_n)$
2.  $p_i(\tilde{x}_i) = \sum_{x_1, x_2, \dots, x_n} \frac{1}{Z} f(x_1, x_2, \dots, x_n) \delta_{x_i, \tilde{x}_i}$
3.  $\max_{x_1, x_2, \dots, x_n} f(x_1, x_2, \dots, x_n)$

Bonus:

1. Can you compute all marginals  $p_i(\tilde{x}_i) \forall i$  in time  $\mathcal{O}(nq^2)$ ?
2. Find a polynomial strategy to draw samples from  $p(x_1, x_2, \dots, x_n) = \frac{1}{Z} f(x_1, x_2, \dots, x_n)$  (Hint: any multivariate distribution can be decomposed as the product of conditional distributions via repeated application of Bayes' formula, then...)
3. Repeat all of the above for a system with periodic boundary conditions:  $f(x_1, x_2, \dots, x_n) = \prod_{i=1}^n f_i(x_i, x_{i+1})$ , with  $x_{n+1} \equiv x_1$

**Observation** A one-dimensional Ising model is described by a distribution over binary spins  $\sigma_1, \sigma_2, \dots, \sigma_n$ ,  $\sigma_i \in \{1, -1\}$

$$p(\sigma_1, \sigma_2, \dots, \sigma_n) = \frac{1}{Z} \prod_{i=1}^n f_i(\sigma_i, \sigma_{i+1})$$

with  $f_i(\sigma_i, \sigma_{i+1}) = e^{J\sigma_i\sigma_{i+1} + h\frac{\sigma_i + \sigma_{i+1}}{2}}$  for some  $J, h \in \mathbb{R}$ . In case you have met the transfer matrix method for solving the one-dimensional Ising model, convince yourself that it is equivalent to the strategy we see here.

**Problem 2. Curie-Weiss model** Given  $n$  binary variables  $\sigma_1, \sigma_2, \dots, \sigma_n$  each taking values in  $\mathcal{X} = \{1, -1\}$  and the probability distribution  $p : \mathcal{X}^n \rightarrow \mathbb{R}$

$$p(\sigma_1, \sigma_2, \dots, \sigma_n) = \frac{1}{Z} e^{-\beta H(\sigma_1, \sigma_2, \dots, \sigma_n)}, \quad -H(\sigma_1, \sigma_2, \dots, \sigma_n) = \frac{J}{n} \left( \sum_{i=1}^n \sigma_i \right)^2 + \sum_{i=1}^n h_i \sigma_i$$

with  $J, \beta, h_1, h_2, \dots, h_n \in \mathbb{R}$ , devise an algorithm running in polynomial time in  $n$  to compute:

1. The partition function  $Z = \sum_{\sigma_1, \sigma_2, \dots, \sigma_n} e^{-\beta H(\sigma_1, \sigma_2, \dots, \sigma_n)}$
2. Marginals  $p_i(\tilde{\sigma}_i) = \sum_{\sigma_1, \sigma_2, \dots, \sigma_n} p(\sigma_1, \sigma_2, \dots, \sigma_n) \delta_{\sigma_i, \tilde{\sigma}_i}$
3. The average energy  $\langle H \rangle = \sum_{\sigma_1, \sigma_2, \dots, \sigma_n} p(\sigma_1, \sigma_2, \dots, \sigma_n) H(\sigma_1, \sigma_2, \dots, \sigma_n)$  (Hint: use linearity of expectation values)
4. Can you do 3., but faster than  $\mathcal{O}(n^3)$ ? (Hint:  $\langle H \rangle$  is related to the derivative of a quantity which you can compute in  $\mathcal{O}(n^2)$ )

Bonus

1. The entropy  $k = -\langle \log p \rangle = -\sum_{\sigma_1, \sigma_2, \dots, \sigma_n} p(\sigma_1, \sigma_2, \dots, \sigma_n) \log p(\sigma_1, \sigma_2, \dots, \sigma_n)$
2. A polynomial strategy to draw samples from  $p$
3. Do the same for a Potts model:  $\sigma_i \in \mathcal{X} = \{1, 2, \dots, q\}$  with energy

$$-H(\sigma_1, \sigma_2, \dots, \sigma_n) = \sum_{i=1}^n \sum_{j=1}^n f(\sigma_i, \sigma_j) + \sum_{i=1}^n h_i(\sigma_i) \quad (1)$$

with  $f : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ ,  $h_1, h_2, \dots, h_n : \mathcal{X} \rightarrow \mathbb{R}$ . The procedure must be polynomial in  $n, q$ . (Hint: observe that the first term only depends on how many variables are in each of the  $q$  states)

**Acknowledgement** These exercises are heavily inspired by Alfredo Braunstein's notes for the course "Algorithms for optimization, inference, and learning".