

## Thomas R Groechel

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CONTACT INFORMATION	3425 Motor Ave #310 Los Angeles, CA 90034	<i>E-mail:</i> groechel@usc.edu
RESEARCH INTERESTS	Computational Modeling for Human-Machine Interaction, Virtual and Augmented Reality, Socially Assistive Robotics, Computer Science Education	
TECHNICAL	<b>Languages:</b> C#, C++, Python, Javascript, R, Bash <b>Tools:</b> Unity, Robot Operating System (ROS), RosSharp (ROS#), Mixed Reality Toolkit (MRTK), Jupyterlab (pandas, seaborn, sklearn)	
EDUCATION	<b>University of Southern California</b> , Los Angeles, CA <i>July 2018 - Present</i> – Ph.D. Computer Science: <i>Expected Dec 2022</i> – Masters Computer Science: <i>Completed Aug 2021</i> – Research Advisor: Professor Maja J. Matarić  <b>University of Michigan</b> , Ann Arbor, MI <i>Sep 2014 - May 2018</i> – B.S.E. Computer Science: <i>Completed May 2018</i> – Undergraduate Research Advisor: Professor Odest C. Jenkins	
EXPERIENCE	<b>Ph.D. Researcher, USC Interaction Lab</b> , Los Angeles, CA <i>July 2018 - Present</i> – Created mixed reality robot tutor aiming to teach K-12 students coding through modeling student kinesthetic learning processes – Developed and deployed telepresence robots in schools for home-bound students – Supported month-long in-home deployments of robot tutor for students with Autism Spectrum Disorder  <b>Robotics Software Intern, iRobot</b> , Pasadena, CA <i>May 2021 - Aug 2021</i> – Worked on autonomous robot vacuum behaviors – Virtual internship  <b>UG Researcher, UofM 4Progress Lab</b> , Ann Arbor, MI <i>May 2016 - May 2018</i> – Developed 2D SLAM algorithm using Iterative Closest Point visualization – Implemented Stochastic Gradient Descent for loop closure based on <i>Fast Iterative Alignment of Pose Graphs with Poor Initial Estimates</i> (Olson et al.) using the Fetch  <b>Staff Development Czar and TA, UofM</b> , Ann Arbor, MI <i>Sep 2016 - May 2018</i> – Created Staff Development program for teaching staff of 30 graduate and undergraduate TAs to improve teaching skills of new and returning staff members – Structured 35-student lab session to review and teach concepts in a specialized alternative to traditional lecture, tailoring for active learning – Produced class-specific help and tip videos to give students an extra resource to common issues in a newer format  <b>Robotics Software Intern at TRAC Labs</b> , Houston, TX <i>Summer 2017</i> – Adapted local mapping and navigation to move TRACBot, a mobile-manipulator, to maneuver dynamically through obstacles such as doors and people in order to reach/use items in Affordance Template library	

- Refitted and rebuilt action server nodes into custom system to perform dynamic re-planning based on real time observations

STUDENT  
RESEARCH  
MENTORING

**Current Students**

- Chloe Kuo Merit Research Fellow, USC Computer Science
- Julia Cordero Merit Research Fellow, USC Computer Science
- Nisha Chatwani Merit Research Fellow, USC Computer Science
- Adam Wathieu Northwestern University Computer Science
- İpek Gökten Viterbi Fellow, USC SHINE Program, USC Computer Science
- Karen Ly Merit Research Fellow, USC Computer Science
- Karen Berba Cal State LA Computer Science (MS)
- Daniel Ramirez Cal State LA Computer Science
- Massimiliano Nigro Politecnico di Milano Computer Science (MS)

**Previous Students**

- Jenny Haemin Lee USC Computer Science
- Radhika Agrawal Merit Research Fellow, USC Computer Science
- Kartik Mahajan Merit Research Fellow, USC Computer Science
- Roddur Dasgupta USC Computer Science
- Annika Modi USC SHINE Program, High School Student
- Jacob Zhi USC SHINE Program, High School Student
- Roxanna Pakkar Merit Research Fellow, USC Electrical Engineering
- Zhonghao Shi USC Computer Science
- Mena Hassan USC SHINE Program, High School Student
- Adnan Karim SURE Student, University of Calgary Computer Science
- Ryan Stevenson USC Computer Science Games
- Ashley Perez USC SHINE Program, High School Student
- Bryan Pyo USC SHINE Program, High School Student

CONTRIBUTIONS  
TO GRANT  
PROPOSALS

**NSF NRI 2.0 - Communicate, Share, Adapt: A Mixed Reality Framework for Facilitating Robot Integration and Customization**

- Contributed significant ideas and content to proposal based upon ongoing Ph.D. work in Mixed Reality SAR
- Research grant awarded in Fall 2019

K-12  
EDUCATIONAL  
OUTREACH

**PoseToCode: Embodied Learning for Coding**

USC CS Ed Week via Zoom *7 Dec 2021*

**Virtual, Augmented, and Mixed Reality for Human-Robot Interaction**

USC Robotics Ed Week via Zoom *10 Apr 2021*

**What is a Socially Assistive Robotics Ph.D.?**

Temple City High School Robotics Team Talk via Zoom *15 Nov 2020*

**Microsoft TEALS Teaching Volunteer**

Los Angeles Center for Enriched Studies, Los Angeles, CA *July 2019 - June 2020*

**Live Mixed Reality Demo and How it Applies to Socially Assistive Robotics**

USC Remote Robotics Open House via Zoom *19 May 2020*

**USC Robotics Academy Judge**

University of Southern California, Los Angeles, CA *Dec 2018 & 2019, Apr 2019*

**Robotics Family Night**

Monterey Hills Elementary, Los Angeles, CA *May 2019, Nov 2019*

**The Help Group STEM<sup>3</sup> Academy Visit**

STEM<sup>3</sup> Academy, Los Angeles, CA *June 2019*

**Mixed Reality and the Kuri Robot**

USC Robotics Open House *10 Apr 2019*

**VEX Robotics Team Leader**  
Clifford Street Elementary, Los Angeles, CA

Oct 2018 - Feb 2019

HONORS AND  
AWARDS

<b>National Science Foundation Travel Fellowship</b>	Nov 2021
<b>USC Viterbi Undergraduate Research Mentoring Award</b>	May 2021
<b>USC Viterbi Undergraduate Research Mentoring Award</b>	May 2020
<b>USC CSCI Best Research Assistant</b>	May 2020
<b>USC Robotics George Bekey Service Award</b>	May 2019

PUBLICATIONS  
AND ABSTRACTS  
\* INDICATES CO-FIRST AUTHOR

- [1] Adam Wathieu\*, **Thomas R. Groechel\***, Haemin Jenny Lee, Chloe Kuo, and Maja J. Matarić. “RE:BT-Espresso: Improving Interpretability and Expressivity of Behavior Trees Learned from Robot Demonstrations”, Accepted in *2022 IEEE International Conference on Robotics and Automation (ICRA 2022)*, Philadelphia, PA, May-2022.
- [2] İpek Gökten\*, Karen Ly\*, **Thomas R. Groechel\***, and Maja J. Matarić “Augmented Reality Appendages for Robots: Design Considerations and Recommendations for Maximizing Social and Functional Perception” In *ACM/IEEE International Conference on Human Robot Interaction (HRI) Workshop on Virtual, Augmented, and Mixed Reality for Human-Robot Interaction (VAM-HRI 2022)*, Virtual, Mar-2022.
- [3] Julia R. Cordero\*, **Thomas R. Groechel\***, and Maja J. Matarić “What and How Are We Reporting in HRI? A Review and Recommendations for Reporting Recruitment, Compensation, and Gender” *arxiv:2201.09114 [cs.RO]*, Jan 2022
- [4] Zhonghao Shi, **Thomas R. Groechel**, Shomik Jain, Kourtney Chima, Ognjen Rudovic, and Maja J. Matarić. “Toward Personalized Affect-Aware Socially Assistive Robot Tutors in Long-Term Interventions for Children with Autism.” Accepted in *Transactions on Human-Robot Interaction (THRI 2022)*.
- [5] **Thomas R. Groechel\***, Michael E. Walker\*, Christine T. Chang, Eric Rosen, and Jessica Zosa Forde. “A Tool for Organizing Key Characteristics of Virtual, Augmented, and Mixed Reality for Human-Robot Interaction Systems: Synthesizing VAM-HRI Trends and Takeaways.” Accepted in *IEEE Robotics and Automation Magazine* (2022).
- [6] **Thomas R. Groechel** and Maja J. Matarić “Abstract: Improving Bidirectional Communication in Human-Robot Interaction Through Mixed Reality Modalities”, Accepted in Robotics Gordon Research Seminar (Jan 2022)
- [7] Christine T. Chang, Eric Rosen, **Thomas R. Groechel**, Michael Walker, Jessica Zosa Forde “Virtual, Augmented, and Mixed Reality for Human-Robot Interaction (VAM-HRI)”, Accepted in *Companion of the 2022 ACM/IEEE International Conference on Human-Robot Interaction (Companion-HRI '21)*, Virtual, Mar-2022.
- [8] Matthew Rueben, Mohammad Syed, Emily London, Mark Camarena, Eunsook Shin, Yulun Zhang, Timothy S. Wang, **Thomas R. Groechel**, Rhianna Lee, and Maja J. Matarić. “Long-Term, In-the-Wild Study of Feedback About Speech Intelligibility for K-12 Students Attending Class via a Telepresence Robot”, In *23rd International Conference on Multimodal Interaction (ICMI)*, Montreal, Canada, Oct-2021.
- [9] Zhonghao Shi, Manwei Cao, Sophia Pei, Xiaoyang Qiao, **Thomas R. Groechel** and Maja J. Matarić. “Personalized Affect-Aware Socially Assistive Robot Tu-

tors Aimed at Fostering Social Grit in Children with Autism”, In *Refereed Workshop ACM/IEEE International Conference on Human Robot Interaction (HRI) Workshop on Child-Robot Interaction and Child’s Fundamental Rights.*, Mar-2021.

- [10] **Thomas R. Groechel**, Roxanna Pakkar, Roddur Dasgupta, Chloe Kuo, Haemin Lee, Julia Cordero, Kartik Mahajan, and Maja J. Matarić “Kinesthetic Curiosity: Towards Personalized Embodied Learning with a Robot Tutor Teaching Programming in Mixed Reality”, In *17th International Symposium on Experimental Robotics (ISER)*, Virtual, Mar-2021.
- [11] Eric Rosen, **Thomas R. Groechel**, Micahel Walker, Christine T. Chang, Jessica Zosa Forde “Virtual, Augmented, and Mixed Reality for Human-Robot Interaction (VAM-HRI)”, In *Companion of the 2021 ACM/IEEE International Conference on Human-Robot Interaction (Companion-HRI ’21)*, Virtual, Mar-2021.
- [12] Kartik Mahajan\*, **Thomas R. Groechel\***, Roxanna Pakkar, Julia Cordero, Haemin Lee, Maja J. Matarić “Adapting Usability Metrics for a Socially Assistive, Kinesthetic, Mixed Reality Robot Tutoring Environment”, In *Proceedings of 2020 International Conference on Social Robotics (ICSR ’20)*, Colorado, USA, Nov-2020. *Best Paper Award Finalist (5 nominated out of 113)*
- [13] Naomi T. Fitter, Luke M. Rush, Elizabeth Cha, **Thomas R. Groechel**, Maja J. Matarić, and Leila Takayama “Closeness is Key over Long Distances: Effects of Interpersonal Closeness on Telepresence Experience”, In *Proceedings of 2020 ACM/IEEE International Conference on Human Robot Interaction (HRI ’20)*, Cambridge, UK, Mar-2020.
- [14] Tom Williams, Daniel Szafr, Tathagata Chakraborti, Ong Soh Khim, Eric Rosen, Serena Booth, **Thomas R. Groechel**, “Virtual, Augmented, and Mixed Reality for Human-Robot Interaction (VAM-HRI)”, In *Companion of the 2020 ACM/IEEE International Conference on Human-Robot Interaction (Companion-HRI ’20)*, Cambridge, UK, Mar-2020.
- [15] Matthew Rueben, **Thomas R. Groechel**, Yulun Zhang, Gisele Ragusa, Maja J. Matarić “Increasing Telepresence Robot Operator Awareness of Speaking Volume Appropriateness: Initial Model Development”, In *Companion of the 2020 ACM/IEEE International Conference on Human-Robot Interaction (Companion-HRI ’20)*, Cambridge, UK, Mar-2020.
- [16] **Thomas R. Groechel**, Zhonghao Shi, Roxanna Pakkar, and Maja J. Matarić “Using Socially Expressive Mixed Reality Arms for Enhancing Low-Expressivity Robots”, In *2019 IEEE International Symposium on Robot and Human Interactive Communication (RO-MAN ’19)*, New Delhi, India, Oct-2019. *Robotics Society of Japan and Korean Robotics Society Distinguished Interdisciplinary Research Award Finalist (3 nominated out of 206)*

TALKS, DEMOS,  
AND  
PRESENTATIONS

**Communicate, Share, Adapt: A Mixed Reality Framework for Facilitation Robot Integration and Customization Virtual Poster Presentation**  
NSF NRI 2.0 PI Meeting via Hopin 10 Mar 2021

**Guest Lecture: Online Features and Measures for K-12 Robot Computer Science Tutoring Through Mixed Reality Modalities**  
CSCI 699: Computational Human-Robot Interaction via Zoom 8 Mar 2021

**Robot Operating System (ROS) Tutorial and Demo**  
USC Makers Club via Zoom 4 Mar 2021

**Planning A Successful Summer Research Experience**  
USC Summer Research Program Talks via Zoom 1 June 2020

**Communicate, Share, Adapt: A Mixed Reality Framework for Facilitation  
Robot Integration and Customization Poster Presentation**

NSF NRI 2.0 PI Meeting, Arlington, VA

27 Feb 2020

**Human-Robot Interaction & Socially Assistive Robots**

Laguna Woods Village, Laguna Woods, CA

19 Feb 2020

**USC Robotics Visions & Voices: Emotionally Intelligent Robots Demo**

University of Southern California, Los Angeles, CA

24 Oct 2019

**SAR Through Augmented Reality Extensions Demo and Discussion**

Public Affairs Council, Laguna Beach, CA

8-9 Jan 2019

PROFESSIONAL  
SERVICE

**Workshop Organizer**

- “The Fifth International Workshop on Virtual, Augmented, and Mixed Reality for Human-Robot Interaction (VAM-HRI)”, In *2022 ACM/IEEE International Conference on Human Robot Interaction (HRI '22)*
- “The Fourth International Workshop on Virtual, Augmented, and Mixed Reality for Human-Robot Interaction (VAM-HRI)”, In *2021 ACM/IEEE International Conference on Human Robot Interaction (HRI '21)*
- “The Third International Workshop on Virtual, Augmented, and Mixed Reality for Human-Robot Interaction (VAM-HRI)”, In *2020 ACM/IEEE International Conference on Human Robot Interaction (HRI '20)*

**Reviewer**

- Virtual, Augmented, and Mixed Reality for Human-Robot Interaction Workshop at HRI 2020, 2021, & 2022
- Transactions on Human-Robot Interaction 2021 & 2022
- International Conference on Human Robot Interaction 2021 & 2022
- Frontiers in Robotics and AI 2021
- International Conference on Development and Learning 2021
- International Conference on Intelligent Robots and Systems 2021
- International Conference on Robotics and Automation 2021
- International Conference on Social Robotics 2020
- Applied Sciences 2020
- Science Robotics 2018

**Women in US Academic Research in Robotics Website** July 2019 - Present

- Designed and implemented, under Prof. Matarić’s supervision, an actively curated and monitored list of current women in US academic robotics research
- Link: [us-women-in-robotics-research.github.io](https://us-women-in-robotics-research.github.io)

MEDIA COVERAGE

**Letting Robots Guide The Learning Experience**

Spring 21

Daniel Druhora, Viterbi Magazine <https://magazine.viterbi.usc.edu/spring-2021/>

CERTIFICATION

**USC Center for Excellence in Teaching’s Future Faculty Teaching Institute**

USC, Los Angeles, CA

Jan 2020 - May 2020