

Thomas R Groechel

CONTACT INFORMATION	3425 Motor Ave #310 Los Angeles, CA 90034	<i>Mobile:</i> 248-921-3254 <i>E-mail:</i> groechel@usc.edu
RESEARCH INTERESTS	Computational Modeling for Human-Machine Interaction, Virtual and Augmented Reality, Socially Assistive Robotics	
EDUCATION	University of Southern California , Los Angeles, CA <i>July 2018 - Present</i> – Ph.D. Computer Science: <i>Expected May 2023</i> – Masters Computer Science: <i>Completed Aug 2020</i> – Research Advisor: Professor Maja J. Matarić University of Michigan , Ann Arbor, MI <i>Sep 2014 - May 2018</i> – B.S.E. Computer Science: <i>Completed May 2018</i> – Undergraduate Research Advisor: Professor Odest C. Jenkins	
EXPERIENCE	Ph.D. Researcher, USC Interaction Lab , Los Angeles, CA <i>July 2018 - Present</i> – Created mixed reality robot tutor aiming to teach K-12 students coding through modeling student kinesthetic learning processes – Developed and deployed telepresence robots in schools for home-bound students – Supported month-long in-home deployments of robot tutor for students with Autism Spectrum Disorder UG Researcher, UofM 4Progress Lab , Ann Arbor, MI <i>May 2016 - May 2018</i> – Developed 2D SLAM algorithm using Iterative Closest Point visualization – Implemented Stochastic Gradient Descent for loop closure based on <i>Fast Iterative Alignment of Pose Graphs with Poor Initial Estimates</i> (Olson et al.) using the Fetch Staff Development Czar and TA, UofM , Ann Arbor, MI <i>Sep 2016 - May 2018</i> – Created Staff Development program for teaching staff of 30 graduate and undergraduate TAs to improve teaching skills of new and returning staff members – Structured 35-student lab session to review and teach concepts in a specialized alternative to traditional lecture, tailoring for active learning – Produced class-specific help and tip videos to give students an extra resource to common issues in a newer format Robotics Software Intern at TRAC Labs , Houston, TX <i>Summer 2017</i> – Adapted local mapping and navigation to move TRACBot, a mobile-manipulator, to maneuver dynamically through obstacles such as doors and people in order to reach/use items in Affordance Template library – Refitted and rebuilt action server nodes into custom system to perform dynamic re-planning based on real time observations	
STUDENT RESEARCH MENTORING	Current Students – Chloe Kuo Merit Research Fellow, USC Computer Science – Julia Cordero Merit Research Fellow, USC Computer Science – Roddur Dasgupta USC Computer Science – Haemin Lee USC Computer Science – Kartik Mahajan Merit Research Fellow, USC Computer Science – Radhika Agrawal Merit Research Fellow, USC Computer Science – Nisha Chatwani Merit Research Fellow, USC Computer Science – Adam Wathieu Georgetown University Computer Science	

- İpek Göktan Viterbi Fellow, USC SHINE Program, USC Computer Science
- Karen Ly Merit Research Fellow, USC Computer Science

Previous Students

- Annika Modi USC SHINE Program, High School Student
- Jacob Zhi USC SHINE Program, High School Student
- Roxanna Pakkar Merit Research Fellow, USC Electrical Engineering
- Zhonghao Shi USC Computer Science
- Mena Hassan USC SHINE Program, High School Student
- Adnan Karim SURE Student, University of Calgary Computer Science
- Ryan Stevenson USC Computer Science Games
- Ashley Perez USC SHINE Program, High School Student
- Bryan Pyo USC SHINE Program, High School Student

CONTRIBUTIONS TO GRANT PROPOSALS **NSF NRI 2.0 - Communicate, Share, Adapt: A Mixed Reality Framework for Facilitating Robot Integration and Customization**

- Contributed significant ideas and content to proposal based upon ongoing Ph.D. work in Mixed Reality SAR
- Research grant awarded in fall 2019

K-12 EDUCATIONAL OUTREACH **Microsoft TEALS Teaching Volunteer**
Los Angeles Center for Enriched Studies, Los Angeles, CA *July 2019 - Jan 2020*
USC Robotics Academy Judge
University of Southern California, Los Angeles, CA *Dec 2018/19, Apr 2019*
Robotics Family Night
Monterey Hills Elementary, Los Angeles, CA *May 2019, Nov 2019*
The Help Group STEM³ Academy Visit
STEM³ Academy, Los Angeles, CA *June 2019*
VEX Robotics Team Leader
Clifford Street Elementary, Los Angeles, CA *Oct 2018 - Feb 2019*

HONORS AND AWARDS **USC CSCI Best Research Assistant** *May 2020*
USC Viterbi Undergraduate Research Mentoring Award *May 2020*
USC Robotics George Bekey Service Award *May 2019*

PEER-REVIEWED PUBLICATIONS [1] **Thomas R. Groechel**, Roxanna Pakkar, Roddur Dasgupta, Chloe Kuo, Haemin Lee, Julia Cordero, Kartik Mahajan, and Maja J. Matarić “Kinesthetic Curiosity: Towards Personalized Embodied Learning with a Robot Tutor Teaching Programming in Mixed Reality”, To appear in *International Symposium on Experimental Robotics (ISER)*, 2020.

[2] Kartik Mahajan, **Thomas R. Groechel**, Roxanna Pakkar, Julia Cordero, Haemin Lee, Maja J. Matarić “Adapting Usability Metrics for a Socially Assistive, Kinesthetic, Mixed Reality Robot Tutoring Environment”, To appear in *Proceedings of 2020 International Conference on Social Robotics (ICSR '20)*, Colorado, USA, Nov 2020.

[3] Naomi T. Fitter, Luke M. Rush, Elizabeth Cha, **Thomas R. Groechel**, Maja J. Matarić, and Leila Takayama “Closeness is Key over Long Distances: Effects of Interpersonal Closeness on Telepresence Experience”, In *Proceedings of 2020 ACM/IEEE International Conference on Human Robot Interaction (HRI '20)*, Cambridge, UK, Mar 2020.

- [4] Tom Williams, Daniel Szafir, Tathagata Chakraborti, Ong Soh Khim, Eric Rosen, Serena Booth, **Thomas R. Groechel**, “Virtual, Augmented, and Mixed Reality for Human-Robot Interaction (VAM-HRI)”, In *Companion of the 2020 ACM/IEEE International Conference on Human-Robot Interaction (Companion-HRI ’20)*, Cambridge, UK, Mar 2020.
- [5] Matthew Rueben, **Thomas R. Groechel**, Yulun Zhang, Gisele Ragusa, Maja J. Matarić “Increasing Telepresence Robot Operator Awareness of Speaking Volume Appropriateness: Initial Model Development”, In *Companion of the 2020 ACM/IEEE International Conference on Human-Robot Interaction (Companion-HRI ’20)*, Cambridge, UK, Mar 2020.
- [6] **Thomas R. Groechel**, Zhonghao Shi, Roxanna Pakkar, and Maja J. Matarić “Using Socially Expressive Mixed Reality Arms for Enhancing Low-Expressivity Robots”, In *2019 IEEE International Symposium on Robot and Human Interactive Communication (RO-MAN ’19)*, New Delhi, India, Oct 2019.
Robotics Society of Japan and Korean Robotics Society Distinguished Interdisciplinary Research Award Finalist (3 nominated out of 206)

TALKS, DEMOS, AND PRESENTATIONS	Planning A Successful Summer Research Experience	
	USC Summer Research Program Talks via Zoom	1 June 2020
	Live Mixed Reality Demo and How it Applies to Socially Assistive Robotics	
	USC Remote Robotics Open House via Zoom	19 May 2020
	Communicate, Share, Adapt: A Mixed Reality Framework for Facilitation	
	Robot Integration and Customization Poster Presentation	
	NSF NRI 2.0 PI Meeting, Arlington, VA	27 Feb 2020
	Human-Robot Interaction & Socially Assistive Robots	
	Laguna Woods Village, Laguna Woods, CA	19 Feb 2020
	USC Robotics Visions & Voices: Emotionally Intelligent Robots Demo	
PROFESSIONAL SERVICE	University of Southern California, Los Angeles, CA	24 Oct 2019
	SAR Through Augmented Reality Extensions Demo and Discussion	
	Public Affairs Council, Laguna Beach, CA	8-9 Jan 2019
	Workshop Organizer	
	– “The Third International Workshop on Virtual, Augmented, and Mixed Reality for Human-Robot Interaction (VAM-HRI)”, In <i>2020 ACM/IEEE International Conference on Human Robot Interaction (HRI ’20)</i>	
	Reviewer	
	– International Conference on Social Robotics 2020	
	– Applied Sciences 2020	
	– Virtual, Augmented, and Mixed Reality for Human-Robot Interaction Workshop at HRI 2020	
	– Science Robotics 2018	
CERTIFICATION	Women in US Academic Research in Robotics Website	July 2019 - Present
	– Designed and implemented, under Prof. Matarić’s supervision, an actively curated and monitored list of current women in US academic robotics research	
	– Link: us-women-in-robotics-research.github.io	
	USC Center for Excellence in Teaching’s Future Faculty Teaching Institute	
	USC, Los Angeles, CA	Jan 2020 - May 2020