Thomas R Groechel

GENERAL E-mail: groechel@usc.edu Website: https://tgroechel.github.io/

RESEARCH Interests Virtual and Augmented Reality for Human-Robot Interaction (VAM-HRI), Socially Assistive Robotics, Computer Science Education, Computational Modeling for HRI

TECHNICAL Languages: C#, C++, Python, Javascript, R, Bash

Tools: Unity, Robot Operating System (ROS), RosSharp (ROS#), Mixed Reality Toolkit (MRTK), Jupyterlab (pandas, seaborn, sklearn)

EDUCATION University of Southern California, Los Angeles, CA

July 2018 - Present

Ph.D. Computer Science: Expected Feb 2022
Master's Computer Science: Completed Aug 2021
Research Advisor: Professor Maja J. Matarić

University of Michigan, Ann Arbor, MI

Sep 2014 - May 2018

- B.S.E. Computer Science: Completed May 2018
- Undergraduate Research Advisor: Professor Odest C. Jenkins

EXPERIENCE

Ph.D. Researcher, USC Interaction Lab, Los Angeles, CA July 2018 - Present

- Created mixed reality robot tutor aiming to teach K-12 students coding through modeling student kinesthetic learning processes
- Developed and deployed telepresence robots in schools for home-bound students
- Supported month-long in-home deployments of robot tutor for students with Autism Spectrum Disorder

Robotics Software Intern, iRobot, Pasadena, CA May 2021 - Aug 2021

- Designed components for the robot behaviors framework
- Remotely collaborated on project

UG Researcher, UofM 4Progress Lab, Ann Arbor, MI May 2016 - May 2018

- Developed 2D SLAM algorithm using Iterative Closest Point visualization
- Implemented Stochastic Gradient Descent for loop closure based on Fast Iterative Alignment of Pose Graphs with Poor Initial Estimates (Olson et al.) using the Fetch

Staff Development Czar and TA, UofM, Ann Arbor, MI Sep 2016 - May 2018

- Created Staff Development program for teaching staff of 30 graduate and undergraduate TAs to improve teaching skills of new and returning staff members
- Structured 35-student lab session to review and teach concepts in a specialized alternative to traditional lecture, tailoring for active learning
- Produced class-specific help and tip videos to give students an extra resource to common issues in a newer format

Robotics Software Intern at TRACLabs, Houston, TX Summer 2017

- Adapted local mapping and navigation to move TRACBot, a mobile-manipulator, to maneuver dynamically through obstacles such as doors and people in order to reach/use items in Affordance Template library
- Refitted and rebuilt action server nodes into custom system to perform dynamic re-planning based on real time observations

STUDENT RESEARCH MENTORING

Current Students

– Ipek Göktan	Viterbi Fellow, USC SHINE Program, USC Computer Science
– Karen Ly	Merit Research Fellow, USC Computer Science
– Massimiliano Nigro	Politecnico di Milano Computer Science (MS)

Previous Students

i revious students	
- Rachel Channell	USC Computer Science
– Evelyn Miguel Vargas	USC Computer Science
- Charles Gary	USC Computer Science
- Dara Macareno	USC Computer Science
- Chloe Kuo	Merit Research Fellow, USC Computer Science
– Julia Cordero	Merit Research Fellow, USC Computer Science
– Nisha Chatwani	Merit Research Fellow, USC Computer Science
– Adam Wathieu	Northwestern University Computer Science
– Karen Berba	Cal State LA Computer Science (MS)
- Daniel Ramirez	Cal State LA Computer Science
- Jenny Haemin Lee	USC Computer Science
- Radhika Agrawal	Merit Research Fellow, USC Computer Science
– Kartik Mahajan	Merit Research Fellow, USC Computer Science
– Roddur Dasgupta	USC Computer Science
– Annika Modi	USC SHINE Program, High School Student
– Jacob Zhi	USC SHINE Program, High School Student
– Roxanna Pakkar	Merit Research Fellow, USC Electrical Engineering
– Zhonghao Shi	USC Computer Science
– Mena Hassan	USC SHINE Program, High School Student
– Adnan Karim	SURE Student, University of Calgary Computer Science
– Ryan Stevenson	USC Computer Science Games
- Ashley Perez	USC SHINE Program, High School Student
– Bryan Pyo	USC SHINE Program, High School Student

CONTRIBUTIONS TO AWARDED GRANT PROPOSALS

Amazon Research Awards - Learning User Preferences for In-Home Robots Through In Situ Augmented Reality

- Contributed significant ideas and content to proposal based upon ongoing Ph.D. work in learning SAR preferences using Mixed Reality
- Research grant awarded in Spring 2022

NSF NRI 2.0 - Communicate, Share, Adapt: A Mixed Reality Framework for Facilitating Robot Integration and Customization

- Contributed significant ideas and content to proposal based upon ongoing Ph.D. work in Mixed Reality SAR
- Research grant awarded in Fall 2019 $\,$

K-12 Educational Outreach

MoveToCode: Pair Programming a Robot in Augmented Reality

John Mack Elementary & Monterey Hills Elementary School 28 & 29 Apr 2022

From High School to Robotics Research at USC Panel

USC Robotics Ed Week via Zoom 6 Apr 2022

PoseToCode: Embodied Learning for Coding

USC CS Ed Week via Zoom 7 Dec 2021

Virtual, Augmented, and Mixed Reality for Human-Robot Interaction

USC Robotics Ed Week via Zoom

10 Apr 2021

What is a Socially Assistive Robotics Ph.D.?

Temple City High School Robotics Team Talk via Zoom

15 Nov 2020

Microsoft TEALS Teaching Volunteer

Los Angeles Center for Enriched Studies, Los Angeles, CA July 2019 - June 2020

Live Mixed Reality Demo and How it Applies to Socially Assistive Robotics USC Remote Robotics Open House via Zoom 19 May 2020 USC Robotics Academy Judge University of Southern California, Los Angeles, CA Dec 2018 & 2019, Apr 2019 Robotics Family Night Monterey Hills Elementary, Los Angeles, CA May 2019, Nov 2019 The Help Group STEM³ Academy Visit STEM³ Academy, Los Angeles, CA June 2019 Mixed Reality and the Kuri Robot USC Robotics Open House 10 Apr 2019 **VEX Robotics Team Leader** Oct 2018 - Feb 2019 Clifford Street Elementary, Los Angeles, CA

Honors and Awards

USC Computer Science Best Research Assistant	May 2022
ASEE PSW Section Graduate Student Award	$May\ 2022$
National Science Foundation Travel Fellowship	Nov~2021
USC Viterbi Undergraduate Research Mentoring Award	May~2021
USC Viterbi Undergraduate Research Mentoring Award	$May\ 2020$
USC Computer Science Best Research Assistant	$May\ 2020$
USC Robotics George Bekey Service Award	$May\ 2019$

PUBLICATIONS AND ABSTRACTS ** INDICATE CO. PROFES AUTHOR

- [1] **Thomas R. Groechel***, Allison O'Connell*, Massimiliano Nigro*, and Maja J. Matarić. "Reimagining RViz: Multidimensional Augmented Reality Robot Signal Design", In 2022 IEEE International Symposium on Robot and Human Interactive Communication (RO-MAN 2022), Aug-2022.
- [2] Julia Cordero*, Thomas R. Groechel* and Maja J. Matarić. "A Review and Recommendations on Reporting Recruitment and Compensation Information in HRI Research Papers", In 2022 IEEE International Symposium on Robot and Human Interactive Communication (RO-MAN 2022), Aug-2022. Best Paper Award Finalist (4 nominated out of 264)
- [3] Nisha Chatwani*, Chloe Kuo*, **Thomas R. Groechel*** and Maja J. Matarić. "PoseToCode: Exploring Design Considerations toward a Usable Block-Based Programming and Embodied Learning System", In the Fifteenth International Conference on Advances in Computer-Human Interactions (ACHI 2022), Porto, Portugal, Jun-2022.
- [4] Adam Wathieu*, Thomas R. Groechel*, Haemin Jenny Lee, Chloe Kuo, and Maja J. Matarić. "RE:BT-Espresso: Improving Interpretability and Expressivity ofBehavior Trees Learned from Robot Demonstrations", In 2022 IEEE International Conference on Robotics and Automation (ICRA 2022), Philadelphia, PA, May-2022.
- [5] İpek Göktan*, Karen Ly*, Thomas R. Groechel*, and Maja J. Matarić "Augmented Reality Appendages for Robots: Design Considerations and Recommendations for Maximizing Social and Functional Perception" In Refereed ACM/IEEE International Conference on Human Robot Interaction (HRI) Workshop on Virtual, Augmented, and Mixed Reality for Human-Robot Interaction (VAM-HRI 2022), Virtual, Mar-2022.
- [6] Julia R. Cordero*, Thomas R. Groechel*, and Maja J. Matarić "What and How Are We Reporting in HRI? A Review and Recommendations for Reporting Recruitment, Compensation, and Gender" In Refereed ACM/IEEE International Conference on Human Robot Interaction (HRI) Workshop on Fairness and Transparency in HRI: Algorithms, Methods, and Metrics, Jan 2022

- [7] Zhonghao Shi, **Thomas R. Groechel**, Shomik Jain, Kourtney Chima, Ognjen Rudovic, and Maja J. Matarić. "Toward Personalized Affect-Aware Socially Assistive Robot Tutors in Long-Term Interventions for Children with Autism." In *Transactions on Human-Robot Interaction* (THRI 2022).
- [8] Thomas R. Groechel*, Michael E. Walker*, Christine T. Chang, Eric Rosen, and Jessica Zosa Forde. "A Tool for Organizing Key Characteristics of Virtual, Augmented, and Mixed Reality for Human-Robot Interaction Systems: Synthesizing VAM-HRI Trends and Takeaways." In *IEEE Robotics and Automation Magazine* (2022).
- [9] Thomas R. Groechel and Maja J. Matarić "Abstract: Improving Bidirectional Communication in Human-Robot Interaction Through Mixed Reality Modalities", In Robotics Gordon Research Seminar (Jan 2022)
- [10] Christine T. Chang, Eric Rosen, **Thomas R. Groechel**, Michael Walker, Jessica Zosa Forde "Virtual, Augmented, and Mixed Reality for Human-Robot Interaction (VAM-HRI)", In *Companion of the 2022 ACM/IEEE International Conference on Human-Robot Interaction (Companion-HRI '21)*, Virtual, Mar-2022.
- [11] Matthew Rueben, Mohammad Syed, Emily London, Mark Camarena, Eunsook Shin, Yulun Zhang, Timothy S. Wang, **Thomas R. Groechel**, Rhianna Lee, and Maja J. Matarić. "Long-Term, In-the-Wild Study of Feedback About Speech Intelligibility for K-12 Students Attending Class via a Telepresence Robot", In 23rd International Conference on Multimodal Interaction (ICMI), Montreal, Canada, Oct-2021.
- [12] Zhonghao Shi, Manwei Cao, Sophia Pei, Xiaoyang Qiao, **Thomas R. Groechel** and Maja J. Matarić. "Personalized Affect-Aware Socially Assistive Robot Tutors Aimed at Fostering Social Grit in Children with Autism", In Refereed Workshop ACM/IEEE International Conference on Human Robot Interaction (HRI) Workshop on Child-Robot Interaction and Child's Fundamental Rights., Mar-2021.
- [13] **Thomas R. Groechel**, Roxanna Pakkar, Roddur Dasgupta, Chloe Kuo, Haemin Lee, Julia Cordero, Kartik Mahajan, and Maja J. Matarić "Kinesthetic Curiosity: Towards Personalized Embodied Learning with a Robot Tutor Teaching Programming in Mixed Reality", In 17th International Symposium on Experimental Robotics (ISER), Virtual, Mar-2021.
- [14] Eric Rosen, **Thomas R. Groechel**, Micahel Walker, Christine T. Chang, Jessica Zosa Forde "Virtual, Augmented, and Mixed Reality for Human-Robot Interaction (VAM-HRI)", In *Companion of the 2021 ACM/IEEE International Conference on Human-Robot Interaction (Companion-HRI '21)*, Virtual, Mar-2021.
- [15] Kartik Mahajan*, Thomas R. Groechel*, Roxanna Pakkar, Julia Cordero, Haemin Lee, Maja J. Matarić "Adapting Usability Metrics for a Socially Assistive, Kinesthetic, Mixed Reality Robot Tutoring Environment", In Proceedings of 2020 International Conference on Social Robotics (ICSR '20), Colorado, USA, Nov-2020. Best Paper Award Finalist (5 nominated out of 113)
- [16] Naomi T. Fitter, Luke M. Rush, Elizabeth Cha, Thomas R. Groechel, Maja J. Matarić, and Leila Takayama "Closeness is Key over Long Distances: Effects of Interpersonal Closeness on Telepresence Experience", In Proceedings of 2020 ACM/IEEE International Conference on Human Robot Interaction (HRI '20), Cambridge, UK, Mar-2020.

- [17] Tom Williams, Daniel Szafir, Tathagata Chakraborti, Ong Soh Khim, Eric Rosen, Serena Booth, Thomas R. Groechel, "Virtual, Augmented, and Mixed Reality for Human-Robot Interaction (VAM-HRI)", In Companion of the 2020 ACM/IEEE International Conference on Human-Robot Interaction (Companion-HRI '20), Cambridge, UK, Mar-2020.
- [18] Matthew Rueben, Thomas R. Groechel, Yulun Zhang, Gisele Ragusa, Maja J. Matarić "Increasing Telepresence Robot Operator Awareness of Speaking Volume Appropriateness: Initial Model Development", In Companion of the 2020 ACM/IEEE International Conference on Human-Robot Interaction (Companion-HRI '20), Cambridge, UK, Mar-2020.
- [19] Thomas R. Groechel, Zhonghao Shi, Roxanna Pakkar, and Maja J. Matarić "Using Socially Expressive Mixed Reality Arms for Enhancing Low-Expressivity Robots", In 2019 IEEE International Symposium on Robot and Human Interactactive Communication (RO-MAN '19), New Delhi, India, Oct-2019. Robotics Society of Japan and Korean Robotics Society Distinguished Interdisciplinary Research Award Finalist (3 nominated out of 206)

Talks, Demos, AND Presentations On Leveraging Virtual, Augmented, and Mixed Reality for Socially Assistive Robotics: Validation in a Kinesthetic K-12 Education Context

WS Keynote - AI for Business and Society: Opportunities and Challenges 3 June 2022 Overview of Computer Science Capstone Course: Design and Construction of Large Software Systems

USC Viterbi Corporate Advisory Board Meeting

3 May 2022

Communicate, Share, Adapt: A Mixed Reality Framework for Facilitation Robot Integration and Customization Virtual Poster Presentation

NSF NRI 2.0 PI Meeting via Hopin

Visualizing Robot Capabilities using Augmented Reality: Designing with Co-Dependent Factors Poster

USC Viterbi Ph.D. Visit Day

3 Mar 2022

Communicate, Share, Adapt: A Mixed Reality Framework for Facilitation Robot Integration and Customization Virtual Poster Presentation

NSF NRI 2.0 PI Meeting via Hopin

10 Mar 2021

Guest Lecture: Online Features and Measures for K-12 Robot Computer Science Tutoring Through Mixed Reality Modalities

CSCI 699: Computational Human-Robot Interaction via Zoom

8 Mar 2021

Robot Operating System (ROS) Tutorial and Demo

USC Makers Club via Zoom

4 Mar 2021

Planning A Successful Summer Research Experience

USC Summer Research Program Talks via Zoom

1 June 2020

Communicate, Share, Adapt: A Mixed Reality Framework for Facilitation Robot Integration and Customization Poster Presentation

NSF NRI 2.0 PI Meeting, Arlington, VA

27 Feb 2020

Human-Robot Interaction & Socially Assistive Robots

Laguna Woods Village, Laguna Woods, CA

19 Feb 2020

USC Robotics Visions & Voices: Emotionally Intelligent Robots Demo 24 Oct 2019

University of Southern California, Los Angeles, CA

SAR Through Augmented Reality Extensions Demo and Discussion

Public Affairs Council, Laguna Beach, CA

8-9 Jan 2019

Professional SERVICE

Workshop Organizer

- "The Fifth International Workshop on Virtual, Augmented, and Mixed Reality for Human-Robot Interaction (VAM-HRI)", In 2022 ACM/IEEE International Conference on Human Robot Interaction (HRI '22)

- "The Fourth International Workshop on Virtual, Augmented, and Mixed Reality for Human-Robot Interaction (VAM-HRI)", In 2021 ACM/IEEE International Conference on Human Robot Interaction (HRI '21)
- "The Third International Workshop on Virtual, Augmented, and Mixed Reality for Human-Robot Interaction (VAM-HRI)", In 2020 ACM/IEEE International Conference on Human Robot Interaction (HRI '20)

Reviewer

- International Conference on Computational Linguistics 2022
- International Conference on Robot & Human Interactive Communication 2022
- Robotics: Science and Systems 2022
- Virtual, Augmented, and Mixed Reality for Human-Robot Interaction Workshop at HRI 2020, 2021, & 2022
- Transactions on Human-Robot Interaction 2021 & 2022
- International Conference on Human Robot Interaction 2021 & 2022
- Frontiers in Robotics and AI 2021
- International Conference on Development and Learning 2021
- International Conference on Intelligent Robots and Systems 2021
- International Conference on Robotics and Automation 2021
- International Conference on Social Robotics 2020
- Applied Sciences 2020
- Science Robotics 2018

Women in US Academic Research in Robotics Website July 2019 - Present

- Designed and implemented, under Prof. Matarić's supervision, an actively curated and monitored list of current women in US academic robotics research
- Link: us-women-in-robotics-research.github.io

MEDIA COVERAGE Letting Robots Guide The Learning Experience

Spring 21

Daniel Druhora, Viterbi Magazine https://magazine.viterbi.usc.edu/spring-2021/

CERTIFICATION

USC Center for Excellence in Teaching's Future Faculty Teaching Institute USC, Los Angeles, CA

Jan 2020 - May 2020