

# Thomas R. Groechel

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## TECHNICAL

**Languages:** Proficient {C++, C#, Python} Working Knowledge {Javascript, R, Bash}

**Tools:** ROS 2 / ROS, Unity, Docker, Git, Jupyterlab, Pandas, Scikit-learn, Firebase, Mixed Reality Toolkit (MRTK)

## RELEVANT WORK EXPERIENCE

- Robotics Software PhD Intern**, iRobot, Pasadena, CA & Remote *May 2021 - Aug 2021, March 2023-Present*
- (C++) Designed and implemented ROS 2 asynchronous services for user flexibility within lifecycle nodes
  - (C++) ROS-ified backend robot actuators with more robust service calls
  - (C++) Developed key components for the new robot behaviors framework, reducing multithreaded programming errors
  - (C++) Improved behavior framework engine for reduced latency and enhanced sequential and fallback behaviors
  - Pitched new behaviors framework to external teams for wider adoption
- Software Developer**, Interaction Lab - University of Southern California, Los Angeles CA *July 2018-February 2023*
- (C#) Built MoveToCode, a custom visual programming language for embodied autonomous agents
  - (Python) Built RE:BT-Espresso, a multi-threaded learning from demonstration pipeline for real-time agent control
  - (C#/Python) Built NRI-SVTE, a system for robot capability visualization and user-robot proxemic preference learning
  - (Javascript) Built PoseToCode, a real-time system mapping user pose landmarks to coding blocks with a neural network
- Researcher**, Interaction Lab - University of Southern California, Los Angeles CA *July 2018-February 2023*
- Planned and executed end-to-end research projects including question ideation/background research, system design, technical implementation, system testing, user studies, data analysis, and paper writing
  - Implemented branching and review system to manage code across multiple teams consisting of a diverse mixture of Ph.D., Undergraduate (UG), Master's (MS), and high school (HS) students
  - Managed 26 UG, MS, and HS first-time research students - 7 total UG/MS first author papers and 7 UG research awards
  - Designed, conducted, and analyzed data of user studies across a variety of target populations/clients
  - Created both technical and non-technical documentation along with handoff documentation for new and current students
  - Co-authored awarded grant proposals (~\$1.55m total) - NSF IIS-1925083, Amazon Research Award, ITE-2236320
  - Co-organized VAM-HRI workshop (3 years total with 60-110 attendees, website: <https://vam-hri.github.io/>)
  - First authored or co-authored 2 journal, 9 conference, and 9 workshop peer-reviewed papers
- Undergraduate Research Assistant**, Laboratory for Progress, Ann Arbor, MI *May 2016 - May 2018*
- (C++/Javascript) Developed 2D SLAM algorithm using Iterative Closest Point visualization
  - (C++/Javascript) Implemented Stochastic Gradient Descent for loop closure based on Fast Iterative Alignment of Pose Graphs with Poor Initial Estimates (Olson et al.) using the Fetch robot
- Robotics Software Intern**, TRACLabs, Houston, TX *May 2017 - August 2017*
- (C++) Adapted local mapping and navigation to move TRACBot, a mobile-manipulator, to maneuver dynamically through obstacles such as doors and people in order to reach/use items in Affordance Template library
  - (C++) Rebuilt action server nodes into custom system to perform dynamic re-planning based on real time observations

## HONORS AND AWARDS

- USC Computer Science Best Research Assistant (2x)** *May 2020 & May 2022*  
Awarded to top research assistant out of all of USC Computer Science graduate students
- USC Viterbi Undergraduate Research Mentoring Award (2x)** *May 2020 & May 2021*  
Awarded to top research mentor out of all of USC Viterbi (Engineering) graduate students

## EDUCATION

- University of Southern California** **Los Angeles, CA**  
Ph.D. Computer Science (GPA: 4.0) Advisor: Prof. Maja Matarić *July 2018-February 2023*  
M.S. Computer Science (GPA: 4.0) *July 2018-August 2021*
- University of Michigan** **Ann Arbor, MI**  
B.S.E. Computer Science (GPA: 3.57) Advisor: Prof. Chad Jenkins *August 2014-May 2018*