Thomas R Groechel

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RESEARCH INTERESTS

Computational Modeling for Human-Machine Interaction, Virtual and Augmented Reality, Socially Assistive Robotics, Computer Science Education

TECHNICAL

Languages: C#, C++, Python, Javascript, R, Bash

Tools: Unity, Robot Operating System (ROS), RosSharp, Mixed Reality Toolkit (MRTK),

Jupyterlab (pandas, seaborn, sklearn)

EDUCATION

University of Southern California, Los Angeles, CA

July 2018 - Present

Ph.D. Computer Science: Expected May 2023
Masters Computer Science: Completed May 2020
Research Advisor: Professor Maja J. Matarić

University of Michigan, Ann Arbor, MI

Sep 2014 - May 2018

- B.S.E. Computer Science: Completed May 2018

- Undergraduate Research Advisor: Professor Odest C. Jenkins

EXPERIENCE

Ph.D. Researcher, USC Interaction Lab, Los Angeles, CA July 2018 - Present

- Created mixed reality robot tutor aiming to teach K-12 students coding through modeling student kinesthetic learning processes
- Developed and deployed telepresence robots in schools for home-bound students
- Supported month-long in-home deployments of robot tutor for students with Autism Spectrum Disorder

UG Researcher, UofM 4Progress Lab, Ann Arbor, MI May 2016 - May 2018

- Developed 2D SLAM algorithm using Iterative Closest Point visualization
- Implemented Stochastic Gradient Descent for loop closure based on Fast Iterative Alignment of Pose Graphs with Poor Initial Estimates (Olson et al.) using the Fetch

Staff Development Czar and TA, UofM, Ann Arbor, MI Sep 2016 - May 2018

- Created Staff Development program for teaching staff of 30 graduate and undergraduate TAs to improve teaching skills of new and returning staff members
- Structured 35-student lab session to review and teach concepts in a specialized alternative to traditional lecture, tailoring for active learning
- Produced class-specific help and tip videos to give students an extra resource to common issues in a newer format

Robotics Software Intern at TRACLabs, Houston, TX

Summer 2017

- Adapted local mapping and navigation to move TRACBot, a mobile-manipulator, to maneuver dynamically through obstacles such as doors and people in order to reach/use items in Affordance Template library
- Refitted and rebuilt action server nodes into custom system to perform dynamic re-planning based on real time observations

STUDENT RESEARCH MENTORING

Current Students

Chloe Kuo
 Julia Cordero
 Haemin Lee
 Merit Research Fellow, USC Computer Science
 Werit Research Fellow, USC Computer Science
 USC Computer Science

- Nisha Chatwani Merit Research Fellow, USC Computer Science - Adam Wathieu Northwestern University Computer Science İpek Göktan Viterbi Fellow, USC SHINE Program, USC Computer Science - Karen Ly Merit Research Fellow, USC Computer Science **Previous Students** Radhika Agrawal Merit Research Fellow, USC Computer Science - Kartik Mahajan Merit Research Fellow, USC Computer Science - Roddur Dasgupta USC Computer Science – Annika Modi USC SHINE Program, High School Student - Jacob Zhi USC SHINE Program, High School Student – Roxanna Pakkar Merit Research Fellow, USC Electrical Engineering Zhonghao Shi USC Computer Science - Mena Hassan USC SHINE Program, High School Student - Adnan Karim SURE Student, University of Calgary Computer Science - Ryan Stevenson USC Computer Science Games - Ashley Perez USC SHINE Program, High School Student - Brvan Pvo USC SHINE Program, High School Student Contributions NSF NRI 2.0 - Communicate, Share, Adapt: A Mixed Reality Framework for Facilitating Robot Integration and Customization - Contributed significant ideas and content to proposal based upon ongoing Ph.D. work in Mixed Reality SAR Research grant awarded in fall 2019 Virtual, Augmented, and Mixed Reality for Human-Robot Interaction USC Robotics Ed Week via Zoom 10 Apr 2020 What is a Socially Assistive Robotics Ph.D.? Temple City High School Robotics Team Talk via Zoom 15 Nov 2020 Microsoft TEALS Teaching Volunteer Los Angeles Center for Enriched Studies, Los Angeles, CA July 2019 - June 2020 Live Mixed Reality Demo and How it Applies to Socially Assistive Robotics USC Remote Robotics Open House via Zoom 19 May 2020 USC Robotics Academy Judge University of Southern California, Los Angeles, CA Dec 2018 & 2019, Apr 2019 Robotics Family Night Monterey Hills Elementary, Los Angeles, CA May 2019, Nov 2019 The Help Group STEM³ Academy Visit STEM³ Academy, Los Angeles, CA June 2019 Mixed Reality and the Kuri Robot USC Robotics Open House 10 Apr 2019 **VEX Robotics Team Leader** Clifford Street Elementary, Los Angeles, CA Oct 2018 - Feb 2019

Honors and AWARDS

TO GRANT

Proposals

EDUCATIONAL

OUTREACH

K-12

USC Viterbi Undergraduate Research Mentoring Award May 2020 & 2021 USC CSCI Best Research Assistant May 2020 USC Robotics George Bekey Service Award May 2019

Publications

[1] Zhonghao Shi, Manwei Cao, Sophia Pei, Xiaoyang Qiao, Thomas R. Groechel and Maja J. Matarić. "Personalized Affect-Aware Socially Assistive Robot Tutors Aimed at Fostering Social Grit in Children with Autism", Refereed Workshop ACM/IEEE International Conference on Human Robot Interaction (HRI) Workshop on Child-Robot Interaction and Child's Fundamental Rights., Mar-2021.

- [2] Thomas R. Groechel, Roxanna Pakkar, Roddur Dasgupta, Chloe Kuo, Haemin Lee, Julia Cordero, Kartik Mahajan, and Maja J. Matarić "Kinesthetic Curiosity: Towards Personalized Embodied Learning with a Robot Tutor Teaching Programming in Mixed Reality", In 17th International Symposium on Experimental Robotics (ISER), Virtual, Mar 2021.
- [3] Eric Rosen, **Thomas R. Groechel**, Micahel Walker, Christine T. Chang, Jessica Zosa Forde "Virtual, Augmented, and Mixed Reality for Human-Robot Interaction (VAM-HRI)", In *Companion of the 2021 ACM/IEEE International Conference on Human-Robot Interaction (Companion-HRI '21)*, Virtual, Mar-2021.
- [4] Kartik Mahajan*, Thomas R. Groechel*, Roxanna Pakkar, Julia Cordero, Haemin Lee, Maja J. Matarić "Adapting Usability Metrics for a Socially Assistive, Kinesthetic, Mixed Reality Robot Tutoring Environment", In Proceedings of 2020 International Conference on Social Robotics (ICSR '20), Colorado, USA, Nov 2020. Best Paper Award Finalist (5 nominated out of 113)
- [5] Naomi T. Fitter, Luke M. Rush, Elizabeth Cha, Thomas R. Groechel, Maja J. Matarić, and Leila Takayama "Closeness is Key over Long Distances: Effects of Interpersonal Closeness on Telepresence Experience", In Proceedings of 2020 ACM/IEEE International Conference on Human Robot Interaction (HRI '20), Cambridge, UK, Mar 2020.
- [6] Tom Williams, Daniel Szafir, Tathagata Chakraborti, Ong Soh Khim, Eric Rosen, Serena Booth, Thomas R. Groechel, "Virtual, Augmented, and Mixed Reality for Human-Robot Interaction (VAM-HRI)", In Companion of the 2020 ACM/IEEE International Conference on Human-Robot Interaction (Companion-HRI '20), Cambridge, UK, Mar 2020.
- [7] Matthew Rueben, Thomas R. Groechel, Yulun Zhang, Gisele Ragusa, Maja J. Matarić "Increasing Telepresence Robot Operator Awareness of Speaking Volume Appropriateness: Initial Model Development", In Companion of the 2020 ACM/IEEE International Conference on Human-Robot Interaction (Companion-HRI '20), Cambridge, UK, Mar 2020.
- [8] Thomas R. Groechel, Zhonghao Shi, Roxanna Pakkar, and Maja J. Matarić "Using Socially Expressive Mixed Reality Arms for Enhancing Low-Expressivity Robots", In 2019 IEEE International Symposium on Robot and Human Interactactive Communication (RO-MAN '19), New Delhi, India, Oct 2019. Robotics Society of Japan and Korean Robotics Society Distinguished Interdisciplinary Research Award Finalist (3 nominated out of 206)

Talks, Demos, and Presentations Communicate, Share, Adapt: A Mixed Reality Framework for Facilitation Robot Integration and Customization Virtual Poster Presentation

NSF NRI 2.0 PI Meeting via Hopin 10 Mar 2021

Guest Lecture: Online Features and Measures for K-12 Robot Computer Science Tutoring Through Mixed Reality Modalities

CSCI 699: Computational Human-Robot Interaction via Zoom 8 Mar 2021

Robot Operating System (ROS) Tutorial and Demo

USC Makers Club via Zoom 4 Mar 2021

Planning A Successful Summer Research Experience

USC Summer Research Program Talks via Zoom

1 June 2020

Communicate, Share, Adapt: A Mixed Reality Framework for Facilitation Robot Integration and Customization Poster Presentation

NSF NRI 2.0 PI Meeting, Arlington, VA 27 Feb 2020

Human-Robot Interaction & Socially Assistive Robots

Laguna Woods Village, Laguna Woods, CA 19 Feb 2020

USC Robotics Visions & Voices: Emotionally Intelligent Robots Demo
University of Southern California, Los Angeles, CA 24 Oct 2019
SAR Through Augmented Reality Extensions Demo and Discussion
Public Affairs Council, Laguna Beach, CA 8-9 Jan 2019

Professional Service

Workshop Organizer

- "The Fourth International Workshop on Virtual, Augmented, and Mixed Reality for Human-Robot Interaction (VAM-HRI)", In 2021 ACM/IEEE International Conference on Human Robot Interaction (HRI '21)
- "The Third International Workshop on Virtual, Augmented, and Mixed Reality for Human-Robot Interaction (VAM-HRI)", In 2020 ACM/IEEE International Conference on Human Robot Interaction (HRI '20)

Reviewer

- International Conference on Development and Learning 2021
- International Conference on Intelligent Robots and Systems 2021
- Transactions on Human-Robot Interaction 2021
- Virtual, Augmented, and Mixed Reality for Human-Robot Interaction Workshop at HRI 2020 &~2021
- International Conference on Robotics and Automation 2021
- International Conference on Human Robot Interaction 2021
- International Conference on Social Robotics 2020
- Applied Sciences 2020
- Science Robotics 2018

Women in US Academic Research in Robotics Website July 2019 - Present

- Designed and implemented, under Prof. Matarić's supervision, an actively curated and monitored list of current women in US academic robotics research
- Link: us-women-in-robotics-research.github.io

CERTIFICATION

USC Center for Excellence in Teaching's Future Faculty Teaching Institute USC, Los Angeles, CA

Jan 2020 - May 2020