

In the previous lecture, we were trying to show the following.

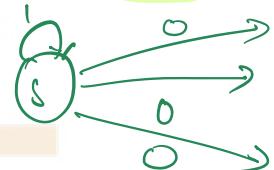
Theorem 1.26: Regular languages are closed under the concatenation operation.

We needed a new ingredient.

Non-deterministic Finite Automata (NFA)

let us see the major differences between DFA and NFA.

1. DFA has exactly one outgoing arrow / transition for each state $s \in Q$ and symbol $a \in \Sigma$.



NFA can have 0, 1 or more than 1.

2. DFA has all the arrows labelled with symbols in the alphabet.

NFA can have arrows marked with ϵ .

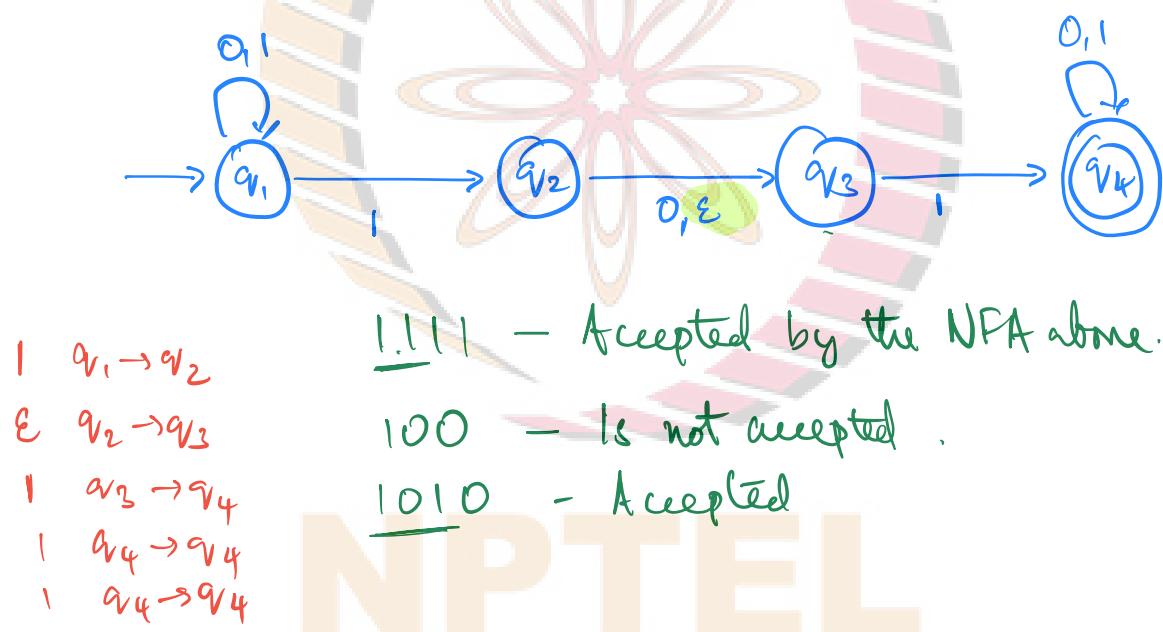
empty string
q₁

Can have 0, 1 or many such arrows.

3. NFA can have multiple choices to be made

at each state, possibly. It could have **many possible computation paths**.

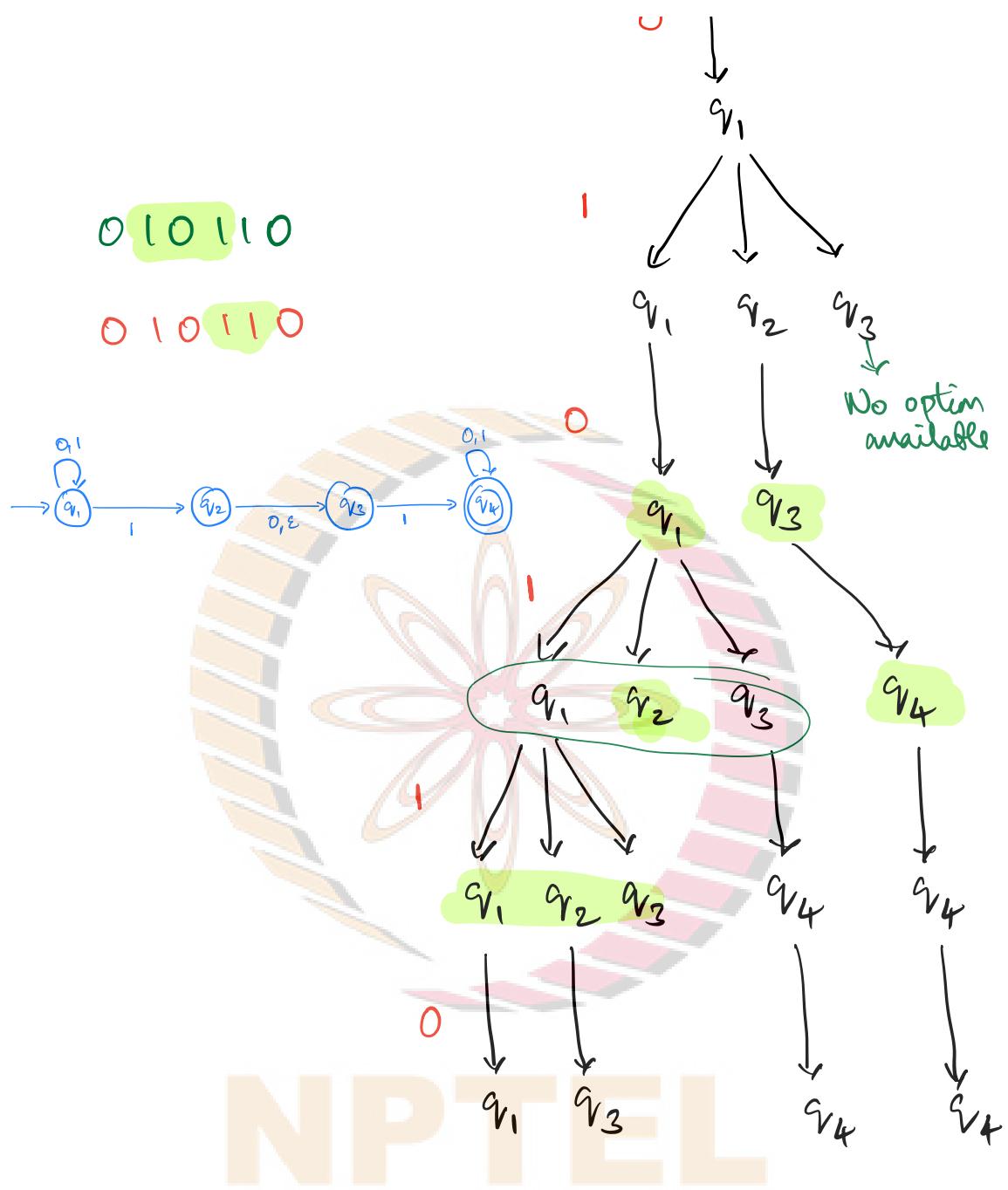
4. NFA accepts a string if there is at least one accepting computation path.



$$L = \{ \omega \in \{0,1\}^* \mid \omega \text{ contains } 101 \text{ or } 11 \text{ as a substring} \}$$

5. Nondeterminism can be viewed as guessing.



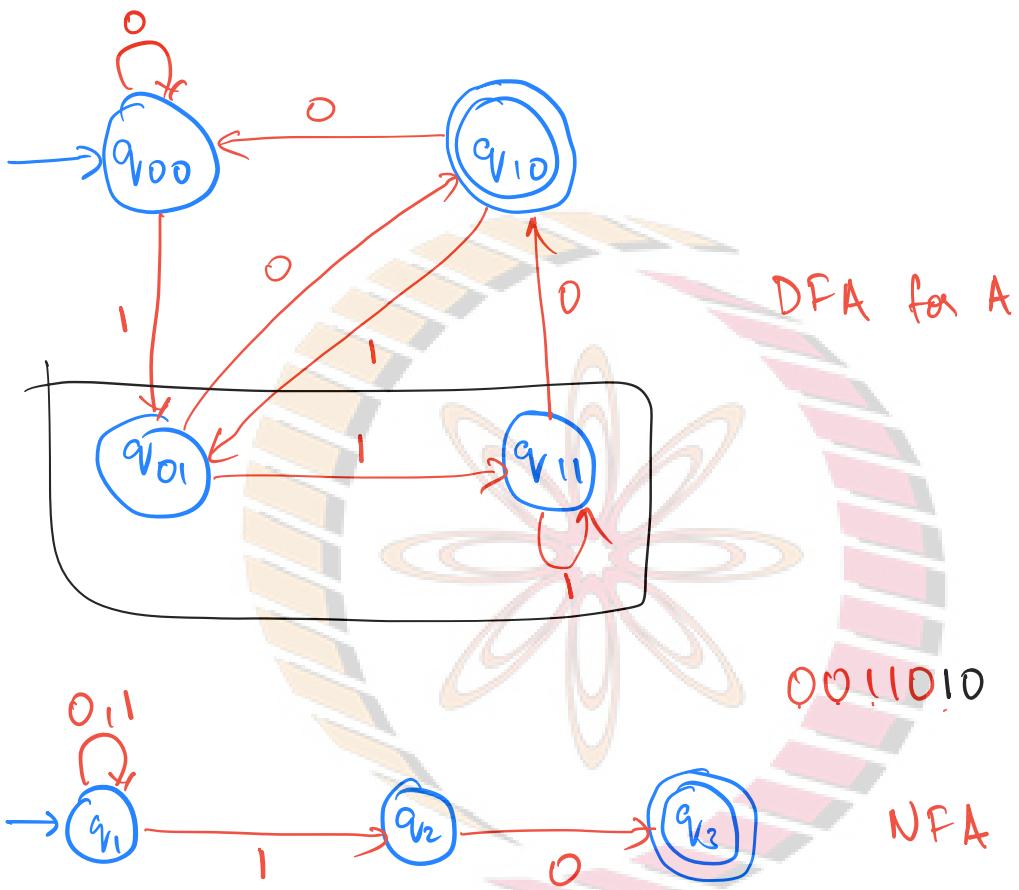


NFA's are at least as powerful as DFA's.

But we may be able to do the computation using a smaller no. of states.

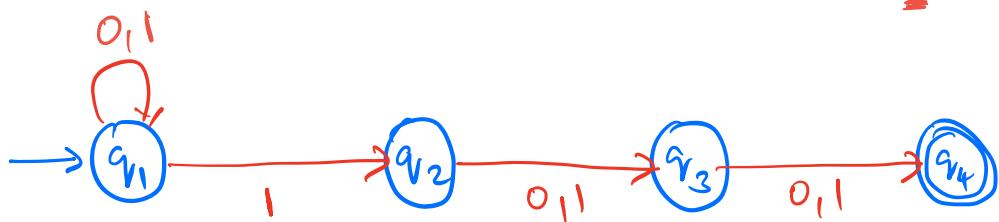
Examples

$$A = \{ \omega \mid \omega \text{ ends in } 10 \}$$



Example 1.30: language of strings where the third last symbol is a 1.

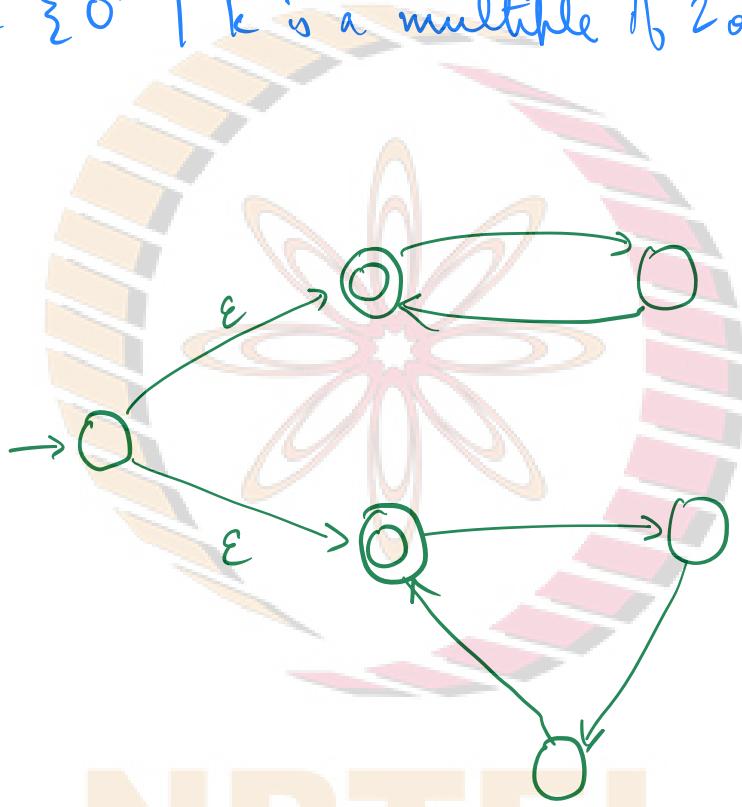
$\underline{\underline{xxxx\ 1\ 0}}$



Read the book to see the DFA. (has 8 states!)

Example 1.33: Unary language.

$$A = \{0^k \mid k \text{ is a multiple of } 2 \text{ or } 3\}$$



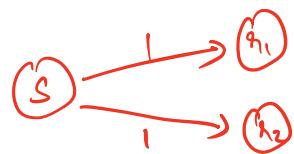
Def 1.37: A non-deterministic finite automaton

(NFA) is a 5-tuple $(Q, \Sigma, \delta, q_0, F)$

I) Q is a finite set of states

$$\delta(s, i) = \{s_1, s_2\}$$

2) Σ is a finite alphabet



3) $f : Q \times \Sigma_E \rightarrow \overline{P(Q)}$ is the transition function

$[f : Q \times \Sigma \rightarrow Q]$
in DFA

$$\Sigma_E = \Sigma \cup \{\epsilon\}$$

$$f(s, \epsilon) = \{q_1\}$$

Power set of Q .

"

Set of all subsets of Q .

4) $q_0 \in Q$ is the start state

5) $F \subseteq Q$ is the set of accepting states.

NFA computation : NFA N accepts w if we

can write $w = y_1, y_2, \dots, y_m$ where $y_i \in \Sigma_E$ and

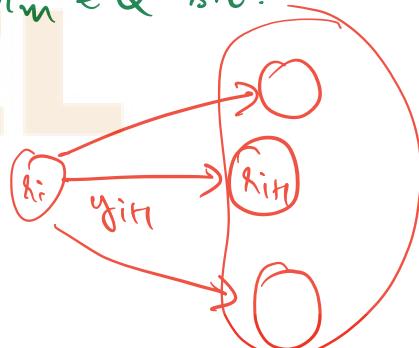
a sequence of states $q_0, r_1, \dots, q_m \in Q$ s.t.

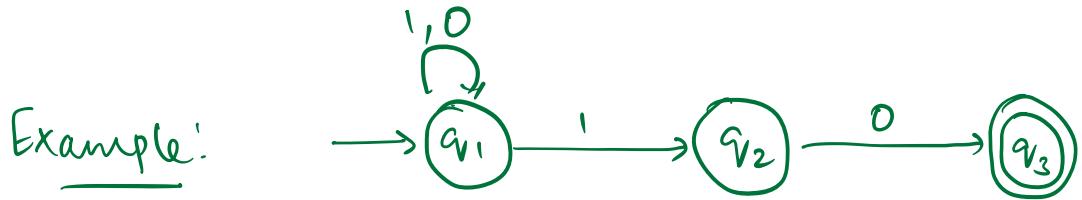
$$(1) \quad r_0 = q_0$$

$$(2) \quad r_{i+1} \in f(r_i, y_{i+1})$$

for $0 \leq i \leq m-1$

$$(3) \quad q_m \in F.$$





$$Q = \{q_1, q_2, q_3\}$$

$$\Sigma = \{0, 1\}$$

$$F = \{q_3\}$$

Start State = q_1

$$\delta(q_1, 0) = \{q_1\}$$

$$\delta(q_1, 1) = \{q_1, q_2\}$$

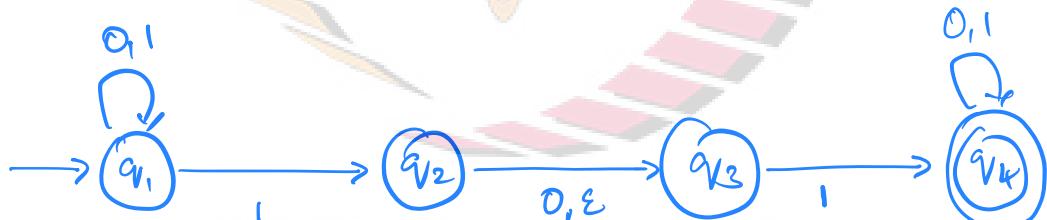
$$\delta(q_1, \epsilon) = \emptyset$$

$$\delta(q_2, 0) = \{q_3\}$$

$$\delta(q_2, 1) = \emptyset$$

$$\delta(q_3, 0) = \delta(q_3, 1) = \emptyset.$$

Read Example 1.38 in the book.



NPTEL