Yeping Wang

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Education

University of Wisconsin-Madison, Madison, WI Ph.D. in Computer Sciences

Research Advisor: Prof. Michael Gleicher

Johns Hopkins University, Baltimore, MD August 2018 - May 2020 GPA: 3.97/4.0

August 2020 - present

GPA: 3.93/4.0

M.S.E. in Robotics Research Advisor: Prof. Chien-Ming Huang

South China University of Technology, Guangzhou, China September 2014-June 2018 GPA: 3.88/4.0

B.E. in Mechanical Engineering

Publications

Peer-Reviewed Conference Papers

Yeping Wang, Carter Sifferman, Michael Gleicher (2024) ICRA'24 IKLink: End-Effector Trajectory Tracking with Minimal Reconfigurations

IEEE International Conference on Robotics and Automation (ICRA). Acceptance Rate 43%

Yeping Wang, Pragathi Praveena, Daniel Rakita, Michael Gleicher (2023)

RangedIK: An Optimization-Based Robot Motion Generation Method for Ranged-Goal Tasks ICRA'23 IEEE International Conference on Robotics and Automation (ICRA). Acceptance Rate 43%

Yeping Wang, Carter Sifferman, Michael Gleicher (2023)

Exploiting Task Tolerances in Mimicry-based Telemanipulation IROS'23

IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS). Acceptance Rate 43%

Pragathi Praveena, Luis Molina, Yeping Wang, Emmanuel Senft, Bilge Mutlu, Michael Gleicher

Understanding Control Frames in Multi-Camera Robot Telemanipulation HRI'22

ACM/IEEE International Conference on Human-Robot Interaction (HRI). Acceptance Rate 25%

Yeping Wang, Gopika Ajaykumar, and Chien-Ming Huang (2020)

See What I See: Enabling User-Centric Robotic Assistance Using First-Person Demonstrations HRI'20

ACM/IEEE International Conference on Human-Robot Interaction (HRI). Acceptance Rate 24%

Peer-Reviewed Journal Articles

Yeping Wang, Alexander Peseckis, Zelong Jiang, Michael Gleicher (2024)

RAL'24 Motion Comparator: Visual Comparison of Robot Motions

IEEE Robotics and Automation Letters (RAL, ICRA'25)

Yeping Wang, Pragathi Praveena, Michael Gleicher (2024)

IA'24 A Design Space of Control Coordinate Systems in Telemanipulation

IEEE Access

Pragathi Praveena, Yeping Wang, Bilge Mutlu, Michael Gleicher (2023)

Periscope: A Robotic Camera System to Support Remote Physical Collaboration CSCW'23

Proceedings of the ACM on Human-Computer Interaction

Sifferman C., Yeping Wang, Mohit Gupta, Michael Gleicher (2023)

Unlocking the Performance of Proximity Sensors by Utilizing Transient Histograms RAL'23

IEEE Robotics and Automation Letters (RAL, ICRA'24)

Baltej Rupal, Khaled Mostafa, Yeping Wang, Ahmed Jawad Quresh (2019)

PM'19 A Reverse CAD Approach for Estimating Geometric and Mechanical Behavior of FDM Printed Parts Procedia Manufacturing *Equal Contribution

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Experiences

Research Intern

Mitsubishi Electric Research Laboratories (MERL)

January 2025-Present
Cambridge, MA

Mentor: Drs. Stefano Di Cairano and Alexander Schperberg

Teaching Assistant
August 2020–May 2021

CS559 Computer Graphics & CS400 Programming III, UW-Madison Madison, WI

Course Assistant January-May 2019 CS 482/682 Deep Learning, JHU Baltimore, MD

Summer Research Intern June-September 2016 University of Alberta Edmonton, Canada

Mentor: Prof. Ahmed Qureshi

Honors and Awards

CS Departmental Summer Fellowship, University of Wisconsin-Madison	2021
CS Departmental Scholarship, University of Wisconsin-Madison	2020
Annual 10 Merit Students, South China University of Technology	2017
China National Scholarship, Ministry of Education of the P.R. China	2016
China National Scholarship, Ministry of Education of the P.R. China	2015

Technical Skills

Programming C/C++, Python, Rust, JavaScript, MATLAB, HTML, CSS, Later View Programming C/C++, Python, Rust, JavaScript, MATLAB, HTML, CSS, Later View Programming C/C++, Python, Rust, JavaScript, MATLAB, HTML, CSS, Later View Programming C/C++, Python, Rust, JavaScript, MATLAB, HTML, CSS, Later View Programming C/C++, Python, Rust, JavaScript, MATLAB, HTML, CSS, Later View Programming C/C++, Python, Rust, JavaScript, MATLAB, HTML, CSS, Later View Programming C/C++, Python, Rust, JavaScript, MATLAB, HTML, CSS, Later View Programming C/C++, Python, Rust, JavaScript, MATLAB, HTML, CSS, Later View Programming C/C++, Python, Rust, JavaScript, MATLAB, HTML, CSS, Later View Programming C/C++, Python, Rust, JavaScript, MATLAB, HTML, CSS, Later View Programming C/C++, Python, Rust, Pyt

Frameworks/Libraries ROS 1/2, PyTorch, Isaac, Mujoco, MoveIt!, ACADO, Git, Docker, THREE.js, D3.js

Software Adobe Illustrator, SolidWorks, ANSYS, AutoCAD, and Inventor

Referee Service

IEEE International Conference on Robotics and Automation (ICRA)	2024, 2025
Workshop on the Algorithmic Foundations of Robotics (WAFR)	2024
IEEE/ACM International Conference on Human-Robot Interaction (HRI)	2025
IEEE Robotics and Automation Letters (RAL)	2024
IEEE Transactions on Visualization and Computer Graphics (TVCG)	2023

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