# EECS 545: Machine Learning Lecture 3. Linear Regression (part 2)

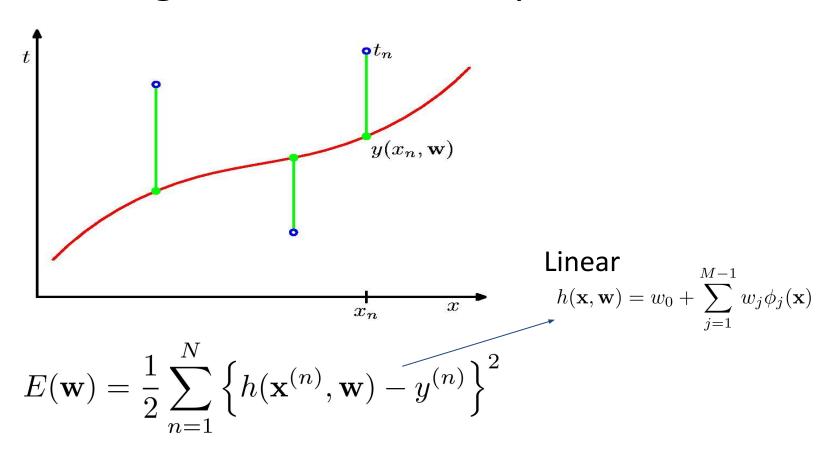
Honglak Lee



#### Outline

- Linear regression review
- Regularized linear regression
- Review on probability
- Maximum likelihood interpretation of linear regression
- Locally-weighted linear regression

#### Regression, sum of square error



We want to find w that minimizes  $E(\mathbf{w})$  over the training data.

#### Least squares problem

Objective function

$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^{N} \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right)^2$$

M: dimension of feature, N: number of data

 $\phi_j(\mathbf{x}^{(n)})$ : j-th feature of data

- Two ways to find w that minimizes E(w)
  - 1. Gradient descent
  - 2. Closed-form solution

### Least squares problem

#### Objective function

$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^{N} (\sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)})^2$$

#### 1. Gradient Descent

$$\frac{\partial E(w)}{\partial w_k} = \sum_{n=1}^N \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right) \phi_k(\mathbf{x}^{(n)})$$

$$\nabla_{\mathbf{w}} E(\mathbf{w}) = \sum_{n=1}^N \left( \mathbf{w}^\top \phi(\mathbf{x}^{(n)}) - y^{(n)} \right) \phi(\mathbf{x}^{(n)})$$

$$\mathbf{w} := \mathbf{w} - \eta \nabla_{\mathbf{w}} E(\mathbf{w})$$

#### 2. Closed-form solution

$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^{N} \left( \sum_{j=0}^{M-1} w_j \phi_j \left( \mathbf{x}^{(n)} \right) - y^{(n)} \right)^2$$
$$= \frac{1}{2} \mathbf{w}^{\top} \Phi^{\top} \Phi \mathbf{w} - \mathbf{w}^{\top} \Phi^{\top} \mathbf{y} + \frac{1}{2} \mathbf{y}^{\top} \mathbf{y}$$

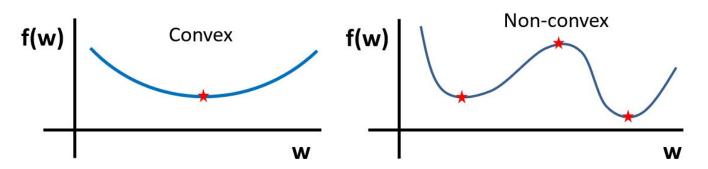
$$\begin{array}{lll} \text{Recap} & \mathbf{w} \colon \mathsf{M} \; \mathsf{by} \; \mathbf{1} & \mathbf{w} = [w_0, w_1, \cdots, w_{M-1}]^\top \\ & \mathbf{y} \colon \mathsf{N} \; \mathsf{by} \; \mathbf{1} & \mathbf{y} = [y^{(1)}, y^{(2)}, \cdots, y^{(N)}]^\top \\ & \Phi \colon \mathsf{N} \; \mathsf{by} \; \mathsf{M} & \begin{pmatrix} \phi_0(\mathbf{x}^{(1)}) & \phi_1(\mathbf{x}^{(1)}) & \dots & \phi_{M-1}(\mathbf{x}^{(1)}) \\ \phi_0(\mathbf{x}^{(2)}) & \phi_1(\mathbf{x}^{(2)}) & \dots & \phi_{M-1}(\mathbf{x}^{(2)}) \\ \vdots & \vdots & \ddots & \vdots \\ \phi_0(\mathbf{x}^{(N)}) & \phi_1(\mathbf{x}^{(N)}) & \dots & \phi_{M-1}(\mathbf{x}^{(N)}) \end{pmatrix} \end{array}$$

#### Useful trick: Matrix Calculus

 Compute gradient and set gradient to 0 (condition for optimal solution)

Note: Least squared is a convex problem.

$$\nabla_{\mathbf{w}} E(\mathbf{w}) = 0$$



Need to compute the first derivative in matrix form

#### Gradient via matrix calculus

Compute gradient and set to zero

$$\nabla_{\mathbf{w}} E(\mathbf{w}) = \nabla_{\mathbf{w}} \left( \frac{1}{2} \mathbf{w}^{\top} \Phi^{\top} \Phi \mathbf{w} - \mathbf{w}^{\top} \Phi^{\top} \mathbf{y} + \frac{1}{2} \mathbf{y}^{\top} \mathbf{y} \right)$$
$$= \Phi^{\top} \Phi \mathbf{w} - \Phi^{\top} \mathbf{y}$$
$$= \mathbf{0}$$

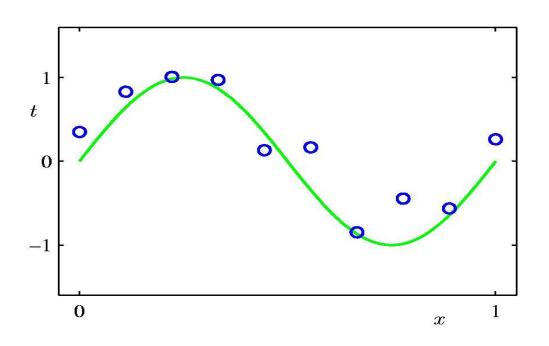
Solve the resulting equation (normal equation)

$$\Phi^{\top}\Phi\mathbf{w} = \Phi^{\top}\mathbf{y}$$
 $\mathbf{w}_{\mathrm{ML}} = (\Phi^{\top}\Phi)^{-1}\Phi^{\top}\mathbf{y}$ 

This is the Moore-Penrose pseudo-inverse:  $\Phi^\dagger = (\Phi^\top \Phi)^{-1} \Phi^\top$  applied to:  $\Phi \mathbf{w} \approx \mathbf{y}$ 

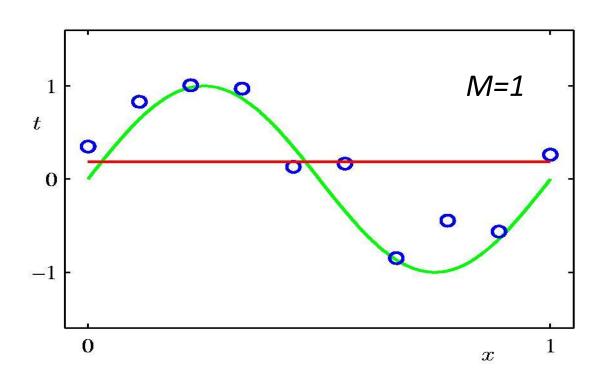
## Back to curve-fitting examples

## Polynomial Curve Fitting

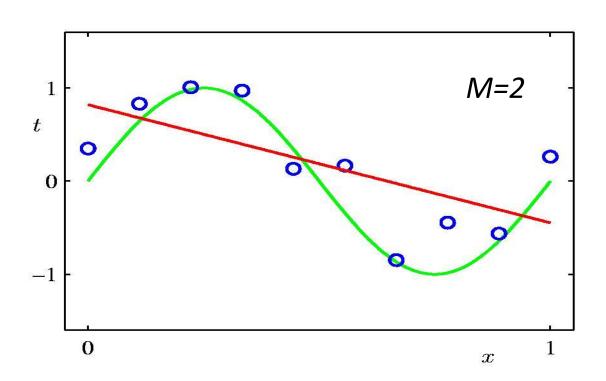


$$h(x, \mathbf{w}) = w_0 + w_1 x + w_2 x^2 + \ldots + w_{M-1} x^{M-1} = \sum_{j=0}^{M-1} w_j x^j$$

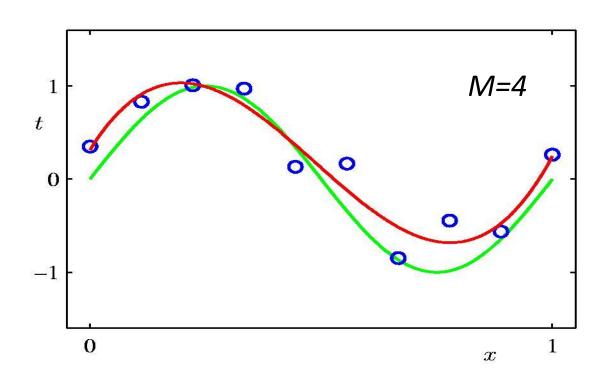
# Oth Order Polynomial



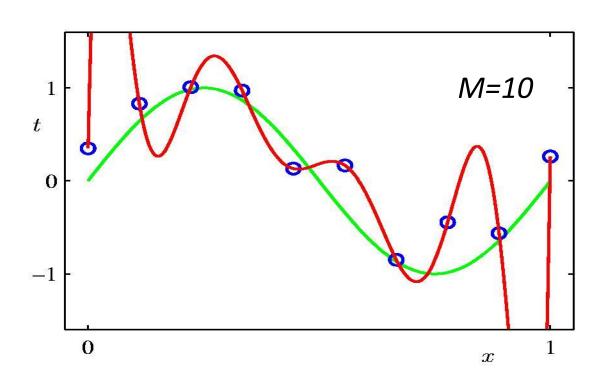
# 1<sup>st</sup> Order Polynomial



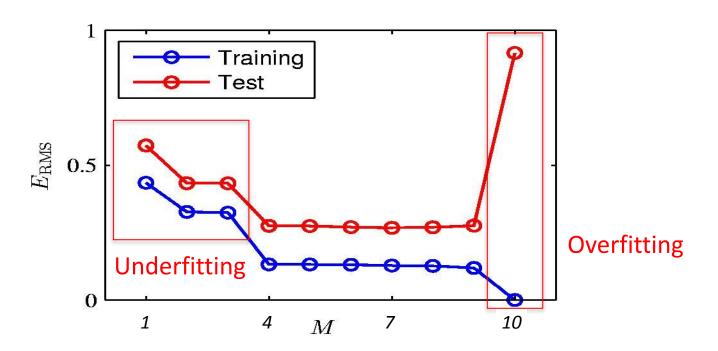
# 3<sup>rd</sup> Order Polynomial



# 9<sup>th</sup> Order Polynomial



### Over-fitting



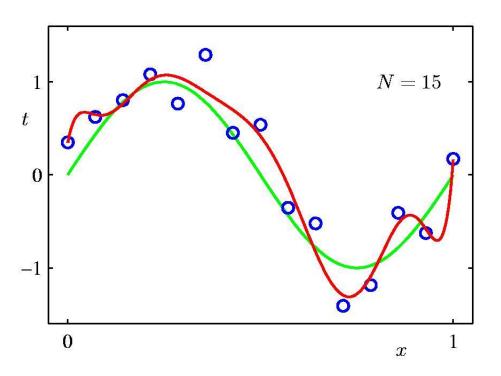
Root-Mean-Square (RMS) Error:

$$E_{\rm RMS} = \sqrt{2E(\mathbf{w}^{\star})/N}$$

Q: How do we resolve the over-fitting problem?

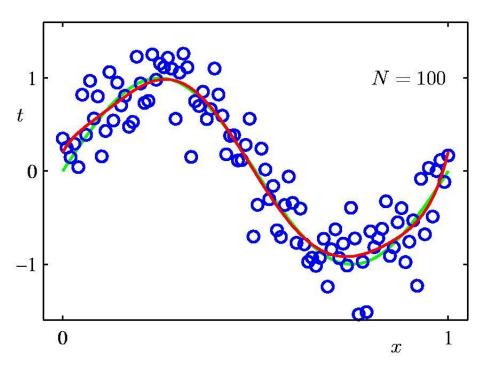
#### Data Set Size: N = 15

#### 9<sup>th</sup> Order Polynomial



#### Data Set Size: N = 100

#### 9<sup>th</sup> Order Polynomial



Increasing data set size can help

# Q. How do we choose the degree of polynomial?

#### Rule of thumb

- If you have a small number of data, then use low order polynomial (small number of features).
  - Otherwise, your model will overfit
- As you obtain more data, you can gradually increase the order of the polynomial (more features).
  - However, your model is still limited by the finite amount of the data available (i.e., the optimal model for finite data cannot be infinite dimensional polynomial).
- Controlling model complexity: regularization

## Regularized Linear Regression

#### Back to Polynomial Coefficients

M=0 $M=1$ $M=3$ $M=9$
$w_0^{\star} \mid 0.19  0.82 \mid 0.31  0.38$
$w_1^{\star}$   -1.27   7.99   232.3
$w_2^{\star}$   -25.43 -5321.83
$w_3^{\star}$ Underfitting 17.37 48568.3
$w_3^{\star}$ Underfitting 17.37 48568.38 $w_4^{\star}$ Good -231639.30 $w_5^{\star}$ 640042.20
$w_5^{\star}$ 640042.20
$\begin{bmatrix} w_6^{\star} \\ w_7^{\star} \end{bmatrix}$ -1061800.53
$w_7^{\star}$ 1042400.13
$w_8^{\star}$ -557682.99
$w_9^{\star}$   125201.43

 $h(x, \mathbf{w}) = w_0 + w_1 x + w_2 x^2 + \ldots + w_{M-1} x^{M-1}$  Coefficients are large!

## Regularized Least Squares (1)

• Consider the error function:

$$E_D(\mathbf{w}) + \lambda E_W(\mathbf{w})$$

Data term + Regularization term

 $\lambda$  is called the regularization coefficient.

With the sum-of-squares error function and a

quadratic regularizer, we get

Penalize large coefficient values

$$\widetilde{E}(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^{N} \left( \mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}) - y^{(n)} \right)^{2} + \frac{\lambda}{2} ||\mathbf{w}||_{2}^{2}$$

New objective function

Definition (L2): 
$$\|\mathbf{w}\|_{2}^{2} = \sum_{j=0}^{M-1} w_{j}^{2}$$

Effect of λ

#### L2 Regularization: $\ln \lambda = 0$

$$M = 9$$
  $\widetilde{E}(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^{N} \left( \mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}) - y^{(n)} \right)^2 + \frac{\lambda}{2} \|\mathbf{w}\|_2^2$ 

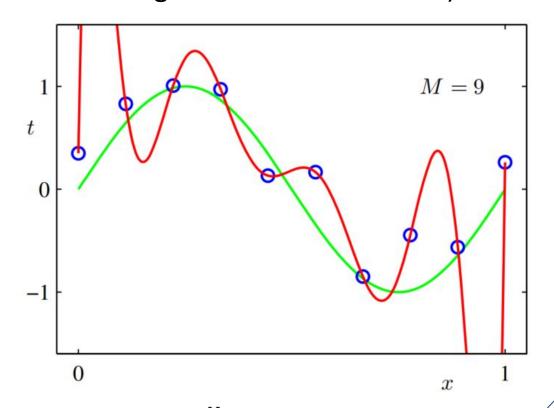
#### **L2** Regularization: $\ln \lambda = -18$

$$M = 9$$
  $\widetilde{E}(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^{N} \left( \mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}) - y^{(n)} \right)^2 + \frac{\lambda}{2} \|\mathbf{w}\|_2^2$ 

## "No" L2 Regularization:

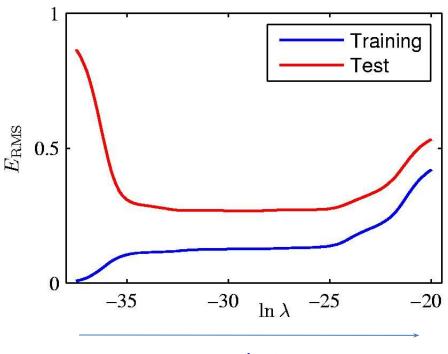
(or when L2 regularization is too small)

$$\lambda = 0$$
(or  $\ln \lambda \to -\infty$ )



$$\boldsymbol{M} = \boldsymbol{9} \qquad \widetilde{E}(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^{N} \left( \mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}) - y^{(n)} \right)^{2} + \frac{\lambda}{2} \| \mathbf{w} \|_{2}^{2}$$

#### L2 Regularization: $E_{\rm RMS}$ vs. $\ln \lambda$



$$E_{\rm RMS} = \sqrt{2E(\mathbf{w}^{\star})/N}$$

Larger regularization

NOTE: For simplicity of presentation, we divided the data into training set and test set. However, it's **not** legitimate to find the optimal hyperparameter based on the test set. We will talk about legitimate ways of doing this when we cover model selection and cross-validation.

## **Polynomial Coefficients**

(i.e.,  $\lambda = 0$ )

	$\ln \lambda = -\infty$	$\ln \lambda = -18$	$\ln \lambda = 0$
$\overline{w_0^{\star}}$	0.35	0.35	0.13
$w_1^{\star}$	232.37	4.74	-0.05
$w_2^\star$	-5321.83	-0.77	-0.06
$w_3^\star$	48568.31	-31.97	-0.05
$w_4^\star$	-231639.30	-3.89	-0.03
$w_5^{\star}$	640042.26	55.28	-0.02
$w_6^{\star}$	-1061800.52	41.32	-0.01
$w_7^\star$	1042400.18	-45.95	-0.00
$w_8^\star$	-557682.99	-91.53	0.00
$w_9^\star$	125201.43	72.68	0.01

Good

Overfitting; Coefficients are large!

Underfitting

## Regularized Least Squares (1)

Consider the error function:

$$E_D(\mathbf{w}) + \lambda E_W(\mathbf{w})$$

Data term + Regularization term

 $\lambda$  is called the regularization coefficient.

 With the sum-of-squares error function and a quadratic regularizer, we get

Penalize large coefficient values

$$\widetilde{E}(\mathbf{w}) = \frac{1}{2} \sum_{1}^{N} \left( \mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}) - y^{(n)} \right)^{2} + \frac{\lambda}{2} \|\mathbf{w}\|_{2}^{2}$$

Closed-form solution:

$$\mathbf{w}_{\mathrm{ML}} = (\lambda \mathbf{I} + \Phi^{\top} \Phi)^{-1} \Phi^{\top} \mathbf{y}$$

#### Derivation

#### Objective function

$$\widetilde{E}(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^{N} \left( \mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}) - y^{(n)} \right)^{2} + \frac{\lambda}{2} \|\mathbf{w}\|_{2}^{2}$$
$$= \frac{1}{2} \mathbf{w}^{\top} \Phi^{\top} \Phi \mathbf{w} - \mathbf{w}^{\top} \Phi^{\top} \mathbf{y} + \frac{1}{2} \mathbf{y}^{\top} \mathbf{y} + \frac{\lambda}{2} \mathbf{w}^{\top} \mathbf{w}$$

#### Compute the gradient and set it zero:

$$\nabla_{\mathbf{w}} \widetilde{E}(\mathbf{w}) = \nabla_{\mathbf{w}} \left[ \frac{1}{2} \mathbf{w}^{\top} \Phi^{\top} \Phi \mathbf{w} - \mathbf{w}^{\top} \Phi^{\top} \mathbf{y} + \frac{1}{2} \mathbf{y}^{\top} \mathbf{y} + \frac{\lambda}{2} \mathbf{w}^{\top} \mathbf{w} \right]$$

$$= \Phi^{\top} \Phi \mathbf{w} - \Phi^{\top} \mathbf{y} + \lambda \mathbf{w}$$

$$= (\lambda \mathbf{I} + \Phi^{\top} \Phi) \mathbf{w} - \Phi^{\top} \mathbf{y}$$

$$= 0$$

$$\mathbf{w}_{\mathrm{ML}} = (\Phi^{\top} \Phi)^{-1} \Phi^{\top} \mathbf{y}$$
v.s. Ordinary Least Square

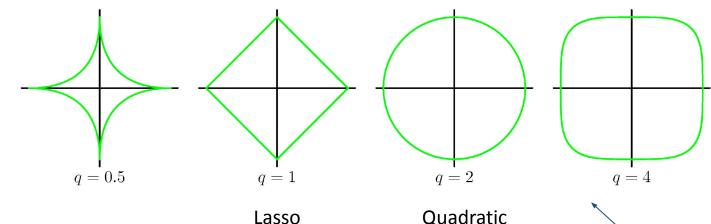
Therefore, we get:  $\mathbf{w}_{\mathrm{ML}} = (\boldsymbol{\lambda}\mathbf{I} + \boldsymbol{\Phi}^{\top}\boldsymbol{\Phi})^{-1}\boldsymbol{\Phi}^{\top}\mathbf{y}$ 

## Regularized Least Squares (2)

• With a more general regularizer, we have

$$\frac{1}{2} \sum_{n=1}^{N} \left( \mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}) - y^{(n)} \right)^{2} + \frac{\lambda}{2} \sum_{j=1}^{M} |w_{j}|^{q}$$

Note: In this lecture, we focus on q=2 (L2 regularization), but other values of q>0 can be used.



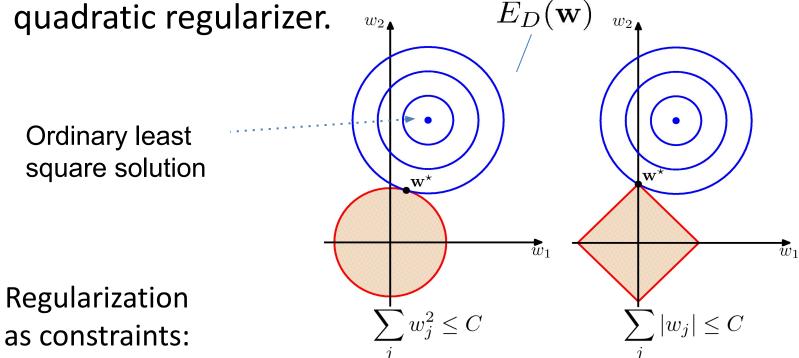
"L1 regularization"

Quadratic "L2 regularization"

plotting curves of  $(w_1, w_2)$  where  $\sum_{j=1}^{M} |w_j|^q$  is a constant. (M=2)

## Regularized Least Squares (3)

• Lasso tends to generate sparser solutions than a



Assuming a simple scenario of isotropic data covariance, the optimal solution to L2/L1 regularization is closest point to the original solution (center of the concentric circles) that touches the boundary of the L2/L1 constraint.

#### Summary: Regularized Linear Regression

- Simple modification of linear regression
- Regularization controls the tradeoff between "fitting error" and "complexity"
  - Small regularization results in complex models (but with risk of overfitting)
  - Large regularization results in simple models (but with risk of underfitting)

 It is important to find an optimal regularization that balances between the two.

# Maximum Likelihood interpretation of least squares regression

## Review on probability

### **Probability: Terminology**

- Experiment: Procedure that yields an outcome
  - E.g., Tossing a coin three times:
    - Outcome: HHH in one trial, HTH in another trial, etc.
- Sample space: Set of all possible outcomes in the experiment, denoted as  $\Omega$  (or S)
  - E.g., for the above example:
    - $\Omega = \{HHH, HHT, HTH, HTT, THH, THT, THT, TTH, TTT\}$
- Event: subset of the sample space  $\Omega$  (i.e., an event is a set consisting of individual outcomes)
  - Event space: Collection of all events, called  $\mathcal{F}$  (aka  $\sigma$ -algebra)
  - E.g., Event that # of heads is an even number.
    - E = {HHT, HTH, THH, TTT}
- **Probability measure**: function (mapping) from events to probability levels. I.e.,  $P: \mathcal{F} \to [0, 1]$  (see next slide)
  - Probability that # of heads is an even number: 4/8 = 1/2.
- Probability space:  $(\Omega, \mathcal{F}, P)$

## Law of Total Probability

$$P(A) \ge 0, \forall A \in \mathcal{F}$$
  
 $P(\Omega) \ge 1$ 

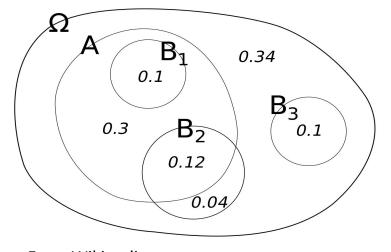
Law of total probability

$$P(A) = P(A \cap B) + P(A \cap B^C)$$
  $P(A) = \sum_i P(A \cap B_i)$  Discrete  $B_i$   $P(A) = \int P(A \cap B_i) dB_i$  Continuous  $B_i$ 

#### **Conditional Probability**

For events  $A, B \in \mathcal{F}$  with P(B) > 0, we may write the **conditional probability** of A given B:

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$



From Wikipedia

#### Bayes' Rule

Using the chain rule we may see:

$$P(A|B)P(B) = P(A \cap B) = P(B|A)P(A)$$

Rearranging this yields Bayes' rule:

$$P(B|A) = \frac{P(A|B)P(B)}{P(A)}$$

Often this is written as:

$$P(B_i|A) = \frac{P(A|B_i)P(B_i)}{\sum_i P(A|B_i)P(B_i)}$$

Where  $B_i$  are a partition of  $\Omega$  (note the bottom is just the law of total probability).

#### Likelihood Functions

Why is Bayes' so useful in learning? Allows us to compute the posterior of **w** given data *D*:

$$p(\mathbf{w}|D) = \frac{p(D|\mathbf{w})p(\mathbf{w})}{p(D)} - Prior$$
 Prior

Bayes' rule in words: posterior 
$$\infty$$
 likelihood  $\times$  prior  $p(\mathbf{w}|D) \propto p(D|\mathbf{w})p(\mathbf{w})$ 

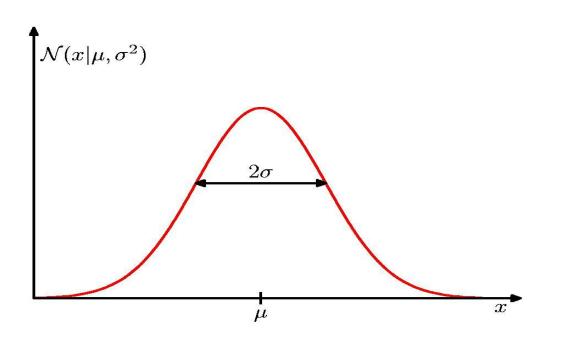
The likelihood function,  $p(\mathbf{w} \mid D)$ , is evaluated for observed data D as a function of  $\mathbf{w}$ . It expresses how parameter settings  $\mathbf{w}$ .

#### Maximum Likelihood Estimation (MLE)

- Maximum likelihood:
  - choose parameter setting **w** that maximizes likelihood function  $p(D \mid \mathbf{w})$ .
  - choose the value of w that maximizes the probability of observed data.
- Cf. MAP (Maximum a posteriori) estimation
  - Equivalent to maximizing  $p(\mathbf{w}|D) \propto p(D|\mathbf{w})p(\mathbf{w})$
  - Can compute this using Bayes rule!
  - This will be covered in later lectures

#### The Gaussian Distribution

$$\mathcal{N}(x|\mu,\sigma^2) = \frac{1}{(2\pi\sigma^2)^{1/2}} \exp\left\{-\frac{1}{2\sigma^2}(x-\mu)^2\right\}$$



$$\mathcal{N}(x|\mu,\sigma^2) > 0$$

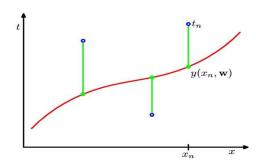
$$\int_{-\infty}^{\infty} \mathcal{N}\left(x|\mu,\sigma^2\right) \, \mathrm{d}x = 1$$

# Maximum Likelihood interpretation of least squares regression

#### MLE for Linear Regression

Assume a stochastic model:

$$y^{(n)} = \mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}) + \epsilon$$
 where  $\epsilon \sim \mathcal{N}(0, \beta^{-1})$ 



This gives a likelihood function:

$$p(y^{(n)} \mid \phi(\mathbf{x}^{(n)}), \mathbf{w}, \beta) = \mathcal{N}(y^{(n)} \mid \mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}), \beta^{-1})$$

• With input matrix  $\Phi$  and output matrix y, the data likelihood is:

$$p(\mathbf{y} \mid \mathbf{\Phi}, \mathbf{w}, \beta) = \prod_{n=1}^{N} \mathcal{N}(y^{(n)} \mid \mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}), \beta^{-1})$$

#### Log-likelihood

Given data likelihood (prev. slide)

$$p(\mathbf{y} \mid \mathbf{\Phi}, \mathbf{w}, \beta) = \prod_{n=1}^{N} \mathcal{N}(y^{(n)} \mid \mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}), \beta^{-1})$$

Log likelihood:

$$\log p(\mathbf{y}|\mathbf{\Phi}, \mathbf{w}, \beta) = \frac{N}{2} \log \beta - \frac{N}{2} \log 2\pi - \beta E_D(\mathbf{w})$$

where 
$$E_D(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^{N} \left( \mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}) - y^{(n)} \right)^2$$

Derivation?

### Derivation of log-likelihood of p

From 
$$p(y^{(n)} \mid \phi(\mathbf{x}^{(n)}), \mathbf{w}, \beta) = \mathcal{N}(y^{(n)} \mid \mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}), \beta^{-1})$$
  
$$= \sqrt{\frac{\beta}{2\pi}} \exp\left(-\frac{\beta}{2} \left\| y^{(n)} - \mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}) \right\|^{2}\right)$$

Derive: 
$$\log p(y^{(1)}, y^{(2)}, \dots, y^{(N)} \mid \Phi, \mathbf{w}, \beta)$$

$$= \log \prod_{n=1}^{N} \mathcal{N} \left( y^{(n)} \mid \mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}), \beta^{-1} \right)$$

$$= \sum_{n=1}^{N} \log \left( \sqrt{\frac{\beta}{2\pi}} \exp \left( -\frac{\beta}{2} \left\| y^{(n)} - \mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}) \right\|^{2} \right) \right)$$

$$= \sum_{n=1}^{N} \left( \frac{1}{2} \log \beta - \frac{1}{2} \log 2\pi - \frac{\beta}{2} \left\| y^{(n)} - \mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}) \right\|^{2} \right)$$

$$= \frac{N}{2} \log \beta - \frac{N}{2} \log 2\pi - \sum_{n=1}^{N} \frac{\beta}{2} \left\| y^{(n)} - \mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}) \right\|^{2}$$

#### Maximum likelihood estimation (MLE)

- Let's maximize the log-likelihood!
- Set the gradient of log-likelihood = 0 (Why?)

$$\nabla_{\mathbf{w}} \log p(y|\mathbf{\Phi}, \mathbf{w}, \beta) = \nabla_{\mathbf{w}} \left( \frac{N}{2} \log \beta - \frac{N}{2} \log 2\pi - \sum_{n=1}^{N} \frac{\beta}{2} \left\| y^{(n)} - \mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}) \right\|^{2} \right)$$
Constant

$$= \beta \sum_{n=1}^{N} \left( y^{(n)} - \underline{\mathbf{w}}^{\top} \phi(\mathbf{x}^{(n)}) \phi(\mathbf{x}^{(n)}) \right)$$

$$= \beta \left( \sum_{n=1}^{N} y^{(n)} \phi(\mathbf{x}^{(n)}) - \phi(\mathbf{x}^{(n)}) \phi(\mathbf{x}^{(n)})^{\top} \mathbf{w} \right) = 0$$

• In matrix form,  $\beta(\Phi^{\top}\mathbf{y} - \Phi^{\top}\Phi\mathbf{w}) = 0$ 

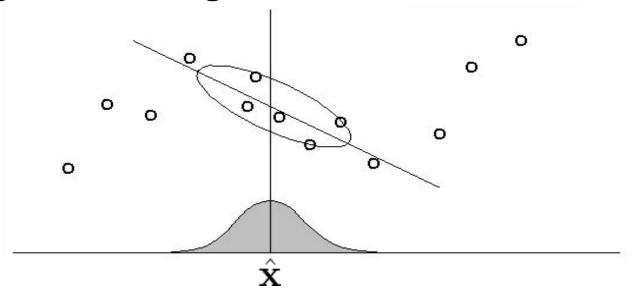
$$\mathbf{w}_{\mathrm{ML}} = (\Phi^{\top}\Phi)^{-1}\Phi^{\top}\mathbf{y}$$

MLE solution is equivalent to OLS solution!

## Locally-weighted Linear Regression

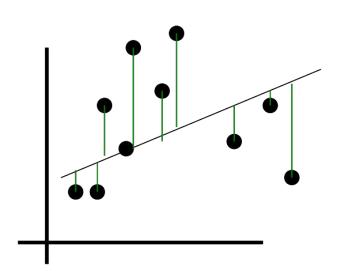
#### Locally weighted linear regression

• Main idea: When predicting  $f(\hat{\mathbf{x}})$ , give high weights for "neighbors" of  $\hat{\mathbf{x}}$ .



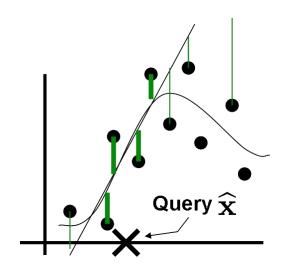
In locally weighted regression, points are weighted by proximity to the current  $\hat{\mathbf{x}}$  in question using a kernel. A regression is then computed using the weighted points.

## Regular linear regression vs. locally weighted linear regression



Regular linear regression

$$\sum_{n=1}^{N} \left( \mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}) - y^{(n)} \right)^{2}$$



Locally weighted linear regression

$$\sum_{n=1}^{N} r^{(n)}(\widehat{\mathbf{x}}) \left( \mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}) - y^{(n)} \right)^{2}$$

### Linear regression vs. Locally-weighted Linear Regression

- A query point  $\widehat{\mathbf{x}}$ , training set  $\left\{\left(\mathbf{x}^{(n)},y^{(n)}\right)\right\}_{n=1}^N$
- Linear regression
  - 1. Fit w to minimize  $\sum_{n=1}^{N} (\mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}) y^{(n)})^2$
  - 2. Predict  $\mathbf{w}^{\top} \phi(\widehat{\mathbf{x}})$
- Locally-weighted linear regression
  - 1. Fit w to minimize  $\sum_{n=1}^{N} r^{(n)}(\widehat{\mathbf{x}}) \left( \mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}) y^{(n)} \right)^2$ 
    - 2. Predict  $\mathbf{w}^{\top} \phi(\widehat{\mathbf{x}})$

weights are dependent on the query  $\,\widehat{\mathbf{x}}\,$  (i.e., need to solve the optimization for each query value)

# Linear regression vs. Locally-weighted Linear Regression

- Locally-weighted linear regression
  - 1. Fit w to minimize  $\sum_{n=1}^{N} r^{(n)}(\widehat{\mathbf{x}}) \left( \mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}) y^{(n)} \right)^{2}$
  - 2. Predict  $\mathbf{w}^{\top} \phi(\widehat{\mathbf{x}})$
- Remarks:

1. Standard choice: 
$$r^{(n)}(\widehat{\mathbf{x}}) = \exp\left(-\frac{\left\|\phi(\mathbf{x}^{(n)}) - \phi(\widehat{\mathbf{x}})\right\|^2}{2\tau^2}\right)$$

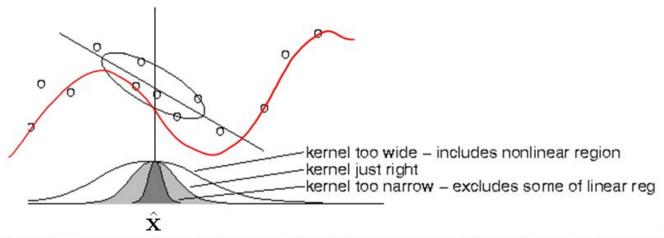
2. Note that  $r^{(n)}(\widehat{\mathbf{x}})$  depends on  $\widehat{\mathbf{x}}$  (query point), and you solve linear regression for each query point  $\widehat{\mathbf{x}}$ 

Gaussian kernel with kernel width au

3. The problem can be formulated as a modified version of least squares problem (HW#1)

### Locally weighted linear regression

- Choice of kernel width  $\tau$  matters
  - Requires hyper-parameter tuning



The estimator is minimized when kernel includes as many training points as can be accommodated by the model. Too large a kernel includes points that degrade the fit; too small a kernel neglects points that increase confidence in the fit.

#### Summary

- $L_2$  Regularized linear regression  $\widetilde{E}(\mathbf{w}) = \frac{1}{2} \sum_{i=1}^{N} (\mathbf{w}^{\top} \phi(\mathbf{x}^{(n)}) y^{(n)})^2 + \frac{\lambda}{2} ||\mathbf{w}||_2^2$ 
  - Adding L<sub>2</sub> regularizer
  - Can be solved via closed form (simple modification of the original linear regression)
  - penalizes complex solutions (with high weights)
- Maximum likelihood interpretation of linear regression
  - Linear regression can be interpreted as performing MLE assuming the Gaussian noise distribution for targets
- Locally-weighted linear regression

#### Any feedback (about lecture, slide, homework, project, etc.)?

(via anonymous google form: <a href="https://forms.gle/99jeftYTaozJvCEF8">https://forms.gle/99jeftYTaozJvCEF8</a>)



#### Change Log of lecture slides:

https://docs.google.com/document/d/e/2PACX-1vRKx40eOJKACqrKWraio0AmlFS1\_xBMINuWcc-jzpfo-ySj\_gBuqTVdf Hy8v4HDmqDJ3b3TvAW1FVuH/pub