# Project 2

## Due on Friday, May 5th, 2017 (Four weeks)

Consider the tridiagonal matrix  $\mathbf{A} = (a_{i,j})_{1 \leq i,j \leq n}$  given by

$$a_{i,j} = \begin{cases} -\frac{1}{h^2} & |i-j| = 1\\ \frac{2}{h^2} & i = j\\ 0 & Otherwise \end{cases}$$
 (1)

obtained when the following ODE

$$-u''(x) = f(x), \quad x \in [0, 1]$$
  
 
$$u(0) = u(1) = 0,$$
 (2)

is discretized using second order centered differences:

$$-\frac{u_{i+1} - 2u_i + u_{i-1}}{h^2} = f(x_i) \quad i = 1, 2, \dots, n,$$
 (3)

where h = 1/(n+1).

1. For each k = 1, 2, ..., n, show that the vector  $\mathbf{u}^{(k)}$  given by

$$u_i^{(k)} = \sin\left(\frac{\pi k i}{n+1}\right), \quad i = 1, 2, \dots, n$$
 (4)

is an eigenvector of the matrix A, and determine the corresponding eigenvalue  $\lambda_k$ .

- 2. Set up the Jacobi iteration for system (3), and show that the vectors (4) are also eigenvectors of the Jacobi iteration matrix,  $T_J$ .
- 3. Determine the spectral radius of  $T_J$ ,  $\rho(T_J)$ .
- 4. The Jacobi iteration can be written as

$$\mathbf{x}^{(k+1)} = \mathbf{T}_{\mathbf{J}}\mathbf{x}^{(k)} + \mathbf{c} \tag{5}$$

From the previous steps, we know that  $T_J$  is symmetric and diagonalizable. Use this fact to show that if  $\mathbf{x}^*$  is the (unique) fixed point of (5), then

$$\|\mathbf{x}^{(k)} - \mathbf{x}^*\|_2 \le \rho(\mathbf{T}_{\mathbf{J}})^k \|\mathbf{x}^{(0)} - \mathbf{x}^*\|_2 \tag{6}$$

- 5. Use formula (6) and the spectral radius obtained earlier to estimate the number of iterations necessary for the error to be less than a given  $\epsilon$  as a function of the number of grid points used, n. You should end up with a formula of the form  $Iter = O(n^{\alpha})$  for some  $\alpha$ .
- 6. Fix  $\epsilon = 10^{-4}$ . Consider the vector **u** such that

$$u_i = \sin\left(\frac{\pi i}{n+1}\right) \tag{7}$$

and construct the right hand side  $\mathbf{f} = \mathbf{A}\mathbf{u}$ . Solve the system of equations

$$\mathbf{A}\mathbf{x} = \mathbf{f} \tag{8}$$

using Jacobi's method. Use the values n=10,20,40,80,160,320. Do a log-log plot of the number of Jacobi iterations necessary for the error to satisfy

$$\|\mathbf{x}^{(k)} - \mathbf{u}\|_2 \le \epsilon \|\mathbf{u}\|. \tag{9}$$

Explain theoretically why this is the expected number of iterations.

7. Repeat the previous part with Gauss-Seidel's method. How much faster is it?

### Solution.

1. Consider the tridiagonal matrix  $\mathbf{A} = (a_{i,j})_{1 \leq i,j \leq n}$  given by

$$a_{i,j} = \begin{cases} -\frac{1}{h^2} & |i - j| = 1\\ \frac{2}{h^2} & i = j\\ 0 & Otherwise \end{cases}$$
 (10)

i.e.,

$$\mathbf{A} = \frac{1}{h^2} \begin{pmatrix} 2 & -1 & 0 & \cdots & 0 \\ -1 & 2 & -1 & \cdots & 0 \\ 0 & -1 & \cdots & \cdots & \cdots \\ \cdots & \cdots & \cdots & \cdots & -1 \\ 0 & 0 & \cdots & -1 & 2 \end{pmatrix}_{n \times n}$$

According to the definition of eigenvalue and eigenvector of the matrix, it is easy to check the vector  $\mathbf{u}^{(k)}$  given by

$$u_i^{(k)} = \sin\left(\frac{\pi ki}{n+1}\right), \quad i = 1, 2, \dots, n$$

is an eigenvector of the matrix  $\mathbf{A}$ , for each  $k=1,2,\ldots,n$ . When  $i\neq 1,n$ , we can take the i-th component of  $\mathbf{A}\mathbf{u}^{(k)}$ , i.e., we need to show that

$$(\mathbf{A}\mathbf{u}^{(k)})_i = \frac{1}{h^2} \left( -\sin\frac{\pi k(i-1)}{n+1} + 2\sin\frac{\pi ki}{n+1} - \sin\frac{\pi k(i+1)}{n+1} \right)$$

$$\stackrel{(?)}{=} \lambda_k \mathbf{u}_i^{(k)} = \lambda_k \sin\left(\frac{\pi ki}{n+1}\right), \tag{11}$$

note that

$$\sin(A \pm B) = \sin A \cos B \pm \cos A \sin B,$$
  
$$\sin(A + B) + \sin(A - B) = 2\sin A \cos B.$$

Then,

$$(\mathbf{A}\mathbf{u}^{(k)})_i = \frac{1}{h^2} \left( 2\sin\frac{\pi ki}{n+1} - 2\sin\frac{\pi ki}{n+1} \cdot \cos\frac{\pi k}{n+1} \right)$$
$$= \frac{1}{h^2} 2\sin\frac{\pi ki}{n+1} \left( 1 - \cos\frac{\pi k}{n+1} \right), \tag{12}$$

consequently,

$$\lambda_k = \frac{2}{h^2} \left( 1 - \cos \frac{\pi k}{n+1} \right), \quad k = 1, \dots, n.$$

Let us check the first and the last component, for i=1, we need to show

$$(\mathbf{A}\mathbf{u}^{(k)})_1 = \frac{1}{h^2} \left( 2\sin\frac{\pi k}{n+1} - \sin\frac{\pi 2k}{n+1} \right)$$

$$= \frac{1}{h^2} \left( 2\sin\frac{\pi k}{n+1} - 2\sin\frac{\pi k}{n+1}\cos\frac{\pi k}{n+1} \right)$$

$$= \frac{2}{h^2} \left( 1 - \cos\frac{\pi k}{n+1} \right) \sin\frac{\pi k}{n+1}$$

$$= \lambda_k \sin\frac{\pi k}{n+1}, \tag{13}$$

for i = n, we need to show

$$(\mathbf{A}\mathbf{u}^{(k)})_{n} = \frac{1}{h^{2}} \left( -\sin\frac{\pi k(n-1)}{n+1} + 2\sin\frac{\pi kn}{n+1} \right)$$

$$= \frac{1}{h^{2}} \left( 2\sin\frac{\pi kn}{n+1} - \sin\frac{\pi kn}{n+1}\cos\frac{\pi k}{n+1} + \cos\frac{\pi kn}{n+1}\sin\frac{\pi k}{n+1} \right)$$

$$\stackrel{(*)}{=} \frac{2}{h^{2}} \left( 1 - \cos\frac{\pi k}{n+1} \right) \sin\frac{\pi kn}{n+1}$$

$$= \lambda_{k} \sin\frac{\pi kn}{n+1}, \tag{14}$$

where the identity (\*) is true, if

$$-\sin\frac{\pi kn}{n+1}\cos\frac{\pi k}{n+1}+\cos\frac{\pi kn}{n+1}\sin\frac{\pi k}{n+1}=-2\cos\frac{\pi k}{n+1}\sin\frac{\pi kn}{n+1}$$
 i.e.,

$$\cos\frac{\pi k}{n+1}\sin\frac{\pi kn}{n+1} + \cos\frac{\pi kn}{n+1}\sin\frac{\pi k}{n+1} = \sin\left(\frac{\pi kn}{n+1} + \frac{\pi k}{n+1}\right)$$
$$= \sin\left(\frac{\pi k(n+1)}{n+1}\right)$$
$$= 0. \tag{15}$$

Therefore, the vectors  $\mathbf{u}^{(k)}$  with components

$$u_i^{(k)} = \sin\left(\frac{\pi ki}{n+1}\right), \quad i = 1, 2, \dots, n,$$

and the corresponding eigenvalue

$$\lambda_k = \frac{2}{h^2} \left( 1 - \cos \frac{\pi k}{n+1} \right), \quad k = 1, \dots, n.$$

2. Consider the Jacobi iteration is  $\mathbf{A} = \mathbf{D} - \mathbf{L} - \mathbf{U}$ , where  $\mathbf{U} = \mathbf{L}^T$ ,

$$\mathbf{L} = \frac{1}{h^2} \begin{pmatrix} 0 & 0 & 0 & \cdots & 0 \\ 1 & 0 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & \cdots & \cdots \\ \cdots & \cdots & \cdots & \cdots & 0 \\ 0 & 0 & \cdots & 1 & 0 \end{pmatrix}_{n \times n}$$

$$\mathbf{D} = \frac{1}{h^2} \begin{pmatrix} 2 & 0 & 0 & \cdots & 0 \\ 0 & 2 & 0 & \cdots & 0 \\ 0 & 0 & \cdots & \cdots & \cdots \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 0 & 2 \end{pmatrix}_{n \times n}$$

Set up the Jacobi iteration for system (3)

$$\mathbf{A}\mathbf{x} = \mathbf{f} \tag{16}$$

i.e.,

$$(\mathbf{D} - \mathbf{L} - \mathbf{U})\mathbf{x} = \mathbf{f}.$$

Then

$$\mathbf{D}\mathbf{x}^{(k+1)} = (\mathbf{L} + \mathbf{U})\mathbf{x}^{(k)} + \mathbf{f}.$$

We can obtain the Jacobi iteration as the following that

$$\mathbf{x}^{(k+1)} = \mathbf{D}^{-1}(\mathbf{L} + \mathbf{U})\mathbf{x}^{(k)} + \mathbf{D}^{-1}\mathbf{f}.$$

Introducing the notation

$$\mathbf{x}^{(k+1)} = \mathbf{T}_{\mathbf{J}}\mathbf{x}^{(k)} + \mathbf{c}$$

where  $T_J = D^{-1}(L + U)$ , and  $c = D^{-1}f$ . We rewrite the scheme in component,

$$\begin{cases} \mathbf{x}_{1}^{(k+1)} &= \frac{1}{2}\mathbf{x}_{2}^{(k)} + \frac{h^{2}}{2}f_{1} & i = 1, \\ \\ \mathbf{x}_{i}^{(k+1)} &= \frac{1}{2}\left(\mathbf{x}_{i-1}^{(k)} + \mathbf{x}_{i+1}^{(k)}\right) + \frac{h^{2}}{2}f_{i} & i = 2: n-1, \\ \\ \mathbf{x}_{n}^{(k+1)} &= \frac{1}{2}\mathbf{x}_{n-1}^{(k)} + \frac{h^{2}}{2}f_{n} & i = n. \end{cases}$$

the vectors (4) are also eigenvectors of the Jacobi iteration matrix,  $\mathbf{T}_{\mathbf{J}}$ . Indeed,

$$\mathbf{T}_{\mathbf{J}} = \mathbf{D}^{-1}(\mathbf{L} + \mathbf{U})$$

$$= \mathbf{D}^{-1}(\mathbf{D} - \mathbf{A})$$

$$= -\mathbf{D}^{-1}\mathbf{A} + \mathbf{I}$$

$$= -\frac{h^2}{2}\mathbf{A} + \mathbf{I},$$

the final equality is due to  $\mathbf{D} = \frac{2}{h^2}\mathbf{I}$ . Then,

$$\mathbf{T}_{\mathbf{J}}\mathbf{u}^{(k)} = \left(-\frac{h^2}{2}\mathbf{A} + \mathbf{I}\right)\mathbf{u}^{(k)}$$
$$= -\frac{h^2}{2}\lambda_k\mathbf{u}^{(k)} + \mathbf{u}^{(k)}$$
$$= \left(-\frac{h^2}{2}\lambda_k + 1\right)\mathbf{u}^{(k)}.$$

Note that

$$\lambda_k = \frac{2}{h^2} \left( 1 - \cos \frac{\pi k}{n+1} \right), \quad k = 1, \dots, n.$$

we get that the eigenvalue of  $T_J$  are

$$\mu_k = -\frac{h^2}{2}\lambda_k + 1$$

$$= -\frac{h^2}{2} \cdot \frac{2}{h^2} \left( (1 - \cos \frac{\pi k}{n+1}) + 1 \right)$$

$$= \cos \frac{\pi k}{n+1},$$

so 
$$\sigma(\mathbf{T}_{\mathbf{J}}) = \{\mu_k\}_{k=1}^n$$
.

3. Consider the spectral radius of  $T_J$ ,  $\rho(T_J)$ .

$$\rho(\mathbf{T}_{\mathbf{J}}) = \max_{k} |\mu_{k}|$$

$$= \max_{k} |\cos \frac{\pi k}{n+1}|$$

$$= \cos \frac{\pi}{n+1}$$

$$\approx 1 - \frac{1}{2} \left(\frac{\pi}{n+1}\right)^{2}$$

The approximation is due to  $\sin x \sim x$ , when  $x \to 0$ , from the last inequality, we know that the convergence of Jacobi iteration.

4. Consider The Jacobi iteration can be written as

$$\mathbf{x}^{(k+1)} = \mathbf{T}_{\mathbf{J}}\mathbf{x}^{(k)} + \mathbf{c},$$

where  $\mathbf{T}_{\mathbf{J}} = \mathbf{D}^{-1}(\mathbf{L} + \mathbf{U})$ , and  $\mathbf{c} = \mathbf{D}^{-1}\mathbf{f}$ . Then,

$$\mathbf{T_J}' = (\mathbf{L} + \mathbf{U})'(\mathbf{D}^{-1})' = (\mathbf{L} + \mathbf{U})\mathbf{D}^{-1} = \mathbf{D}^{-1}(\mathbf{L} + \mathbf{U}) = \mathbf{T_J},$$

it is easy to obtain  $T_J$  is symmetric and diagonalizable. If  $\mathbf{x}^*$  is the (unique) fixed point of (5), then

$$\|\mathbf{x}^{(k)} - \mathbf{x}^*\|_2 \le \rho(\mathbf{T}_{\mathbf{J}})^k \|\mathbf{x}^{(0)} - \mathbf{x}^*\|_2$$

Indeed, for a symmetric matrix  $\mathbf{T}_{\mathbf{J}}$ , it can be shown that  $\|\mathbf{T}_{\mathbf{J}}\|_2 = \sqrt{\lambda_{\max}(\mathbf{T}_{\mathbf{J}}'\mathbf{T}_{\mathbf{J}})} = \rho(\mathbf{T}_{\mathbf{J}})$ , so we need to show

$$\|\mathbf{x}^{(k)} - \mathbf{x}^*\|_2 \le \|\mathbf{T}_{\mathbf{J}}\|_2^k \|\mathbf{x}^{(0)} - \mathbf{x}^*\|_2.$$

Observe that  $\mathbf{x}^* = \mathbf{T}_{\mathbf{J}}\mathbf{x}^* + \mathbf{c}$  and  $\|\mathbf{A}\mathbf{x}\| \le \|\mathbf{A}\| \|\mathbf{x}\|$ , then

$$\begin{aligned} \|\mathbf{x}^{(k)} - \mathbf{x}^*\|_2 &= \|\mathbf{T}_{\mathbf{J}}\mathbf{x}^{(k-1)} + \mathbf{c} - (\mathbf{T}_{\mathbf{J}}\mathbf{x}^* + \mathbf{c})\|_2 \\ &= \|\mathbf{T}_{\mathbf{J}}(\mathbf{x}^{(k-1)} - \mathbf{x}^*)\|_2 \\ &\leq \|\mathbf{T}_{\mathbf{J}}\|_2 \|\mathbf{x}^{(k-1)} - \mathbf{x}^*\|_2 \\ &\leq \|\mathbf{T}_{\mathbf{J}}\|_2^2 \|\mathbf{x}^{(k-2)} - \mathbf{x}^*\|_2 \\ &\leq \cdots \\ &\leq \|\mathbf{T}_{\mathbf{J}}\|_2^k \|\mathbf{x}^{(0)} - \mathbf{x}^*\|_2, \end{aligned}$$

i.e.,

$$\|\mathbf{x}^{(k)} - \mathbf{x}^*\|_2 \le \rho(\mathbf{T}_{\mathbf{J}})^k \|\mathbf{x}^{(0)} - \mathbf{x}^*\|_2.$$

5. Consider the formula as above and the spectral radius  $\rho(\mathbf{T}_{\mathbf{J}})$ , we take  $\mathbf{x}^{(0)} = 0$ . Then, the relative error is

$$\frac{\|\mathbf{x}^{(k)} - \mathbf{x}^*\|_2}{\|\mathbf{x}^*\|_2} \le \rho(\mathbf{T}_{\mathbf{J}})^k.$$

We want  $\rho^k \leq \epsilon$ , we take logarithm on both side, it follows that  $k \log \rho \leq \log \epsilon$ , we note that  $\log \rho < 0$  due to  $\rho < 1$ , and also  $\log \epsilon < 0$ , therefore,

$$k|\log \rho| \ge |\log \epsilon|.$$

Then

$$k \ge \frac{|\log \epsilon|}{|\log \rho|},$$

we can set  $k = \frac{|\log \epsilon|}{|\log \rho|}$ , we need to show  $k = Cn^{\alpha}$ , i.e.,

$$\log k = \alpha \log n + \log C.$$

So, setting  $\epsilon = 10^{-r}$ , where r is a constant. We consider the relationship between

$$\log k = \log \frac{|\log \epsilon|}{|\log \rho|} = \log |r| - \log |\log \cos \frac{\pi}{n+1}|.$$

and  $\log n$ , we need to do a work of linear regression using LSM. We list as the following that

n	$\log n$	$\log  \log \cos \frac{\pi}{n+1} $
10	2.30258509	-3.1857
20	2.99573227	-4.4890
40	3.688879454	-5.8299
80	4.38202663	-7.1923
160	5.075173815	-8.5664
320	5.76832099579	-9.9466

We can draw the graph as follows

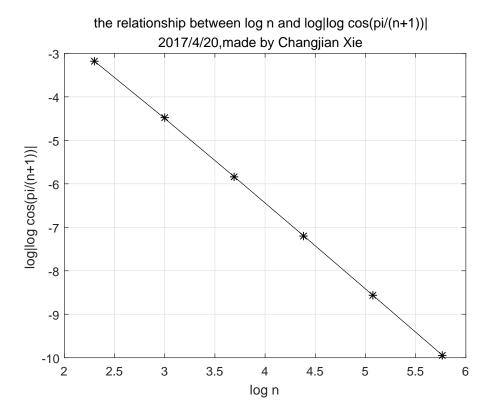


Figure 1: Using the values n = 10,20,40,80,160,320. Do a plot of log n and log | log cos  $\frac{\pi}{n+1}|$ 

The first problem transfers into

$$\log|\log\cos\frac{\pi}{n+1}| = \log C_1 + \alpha_1 \log n,$$

we have implied the method in Project 1, now, I omit the detail and only give the result as follows

$$\alpha_1$$
 -1.9537886863

Thus, we obtain that  $\alpha = -\alpha_1 = 1.9537886863$ ,  $Iterk = O(n^{\alpha})$  for some  $\alpha$ . In fact, we can also do the Taylor extension of the function, then, we deserve the same result.

6. Consider Fix  $\epsilon = 10^{-3}$  and note that  $\mathbf{f} = \mathbf{A}\mathbf{u}$ . Then, the vector  $\mathbf{u}$  is the exact solution. In the following, we solve the system of equations

$$Ax = f$$

using Jacobi's method with  $\mathbf{x}^{(0)} = 0$ .

## Jacobi iterative algorithm

To solve  $\mathbf{A}\mathbf{x} = \mathbf{f}$  given an initial approximation  $\mathbf{x}^{(0)}$ ,

- INPUT. The number of equations and unknowns n, the entries  $a_{ij}$ ,  $1 \le i, j \le n$  of the matrix  $\mathbf{A}$ , the entries  $f_i$  of  $\mathbf{f}$ , the entries  $XO_i$ ,  $1 \le i \le n$  of  $\mathbf{XO} = \mathbf{x}^{(0)}$ , tolerance TOL; maximum number of iterations N.
- OUTPUT. The approximate solution  $x_1, \ldots, x_n$  or a message that the number of iterations was exceeded.
  - Step 1. Set k = 1.
  - Step 2. While  $k \le N$  do Steps 3 6.
  - Step 3. For  $i = 1, \ldots, n$ , set

$$x_i = \frac{-\sum_{\substack{j=1\\j\neq i}}^{n} (a_{ij}XO_j) + f_i}{a_{ii}}$$

- Step 4. If  $\|\mathbf{x} \mathbf{XO}\| < TOL$ , then OUTPUT  $(x_1, \dots, x_n)$ ; (The procedure was successful). STOP.
- Step 5. Set k = k + 1.
- Step 6. For i = 1, ..., n, set  $XO_i = x_i$ .
- Step 7. OUTPUT (Maximum number of iterations exceeded); (The procedure was successful). STOP.

Using the values n=10,20,40,80,160,320. Do a log-log plot of the number of Jacobi iterations necessary for the error to satisfy

$$\|\mathbf{x}^{(k)} - \mathbf{u}\|_2 \le \epsilon \|\mathbf{u}\|.$$

We obtain that

n	iter k
10	223
20	821
40	3135
80	12243
160	48377
320	192314

The matlab code of Jacobi function file as following that

```
function [x, iter]=myjacobi(a,xexact,x0,tol)
```

```
b=a*xexact;
    n=length(x0);
    u0=x0;
    x=x0;
    iter = 0;
    error=1;
    while error > tol
        for i=1:n
            x(i) = a(i,1:i-1)*x0(1:i-1)+a(i,i+1:n)*x0(i+1:n);
            x(i)=(b(i)-x(i))/a(i,i);
        end
        error=norm(x-xexact)/norm(u0-xexact);
        x0=x;
        iter = iter + 1;
     end
end
```

The matlab code of Jacobi iteration as following that

```
%
% Project 2
% Jacobi method
%
```

```
clear
results=[];
for k=0:5,
    n=10*2^k;
    h=1./(n+1);
    % Define Grid
    x=zeros(n,1);
    for i=1:n,
        x(i) = i*h;
    end
    % Initialization
    sol = sin(pi*x);
    e=ones(n,1)/h^2;
    a=spdiags([-e 2*e -e], -1:1, n, n);
    f = a *sol;
    % Iteration starts here
    tol = 1.e-4;
    u0 = zeros(n,1);
    u1 = zeros(n,1);
    error=norm(u0-sol)/norm(sol);
    iter = 0;
    while error > tol
        u1(1) = (h^2*f(1)+u0(2))/2.;
        for i=2:n-1
            u1(i) = (h^2*f(i)+u0(i+1)+u0(i-1))/2.;
        end
        u1(n) = (h^2*f(n)+u0(n-1))/2.;
```

```
u0 = u1;
    error=norm(u0-sol)/norm(sol);
    iter = iter + 1;
    % fprintf('Iteration %d, Error: %16.10g\n', iter, norm(u1-sol));
    end
    results=[results; n error iter];
    fprintf('Iterations for n=%d: %d\n', n, iter);
end
%%
loglog(results(:,1),results(:,3),'o-'),hold on,grid on
title({['Log-Log plot of the number of Jacobis
iterations'];['Due on 2017/4/20, Changjian Xie']})
xlabel('n');
ylabel('#the number of Jacobi Iterations')
```

Do a log-log plot of the number of Jacobi iterations as follows

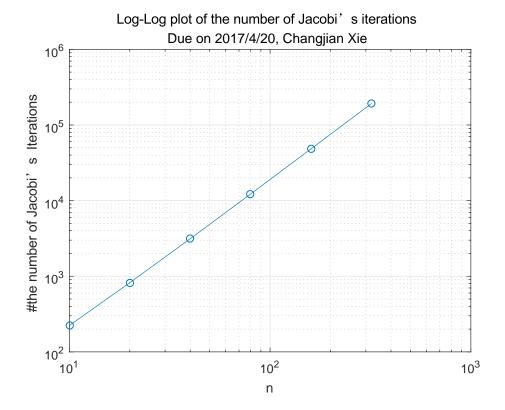


Figure 2: Using the values n = 10,20,40,80,160,320. Do a log-log plot of the number of Jacobi iterations necessary for the error to satisfy  $\|\mathbf{x}^{(k)} - \mathbf{u}\|_2 \le \epsilon \|\mathbf{u}\|$ .

Theoretically this is the expected number of iterations. Indeed, we know the result is linear of  $\log k$  and  $\log n$ . Then, Obviously,  $k = O(n^{\alpha})$ , from task (5), of course, it's true.

7. Repeat the previous part with Gauss-Seidel's method.

#### G-S iterative algorithm

To solve  $\mathbf{A}\mathbf{x} = \mathbf{f}$  given an initial approximation  $\mathbf{x}^{(0)}$ ,

INPUT. The number of equations and unknowns n, the entries  $a_{ij}$ ,  $1 \le i, j \le n$  of the matrix  $\mathbf{A}$ , the entries  $f_i$  of  $\mathbf{f}$ , the entries  $XO_i$ ,  $1 \le i \le n$  of  $\mathbf{XO} = \mathbf{x}^{(0)}$ , tolerance TOL; maximum number of iterations N.

- OUTPUT. The approximate solution  $x_1, \ldots, x_n$  or a message that the number of iterations was exceeded.
  - Step 1. Set k = 1.
  - Step 2. While  $k \leq N$  do Steps 3 6.
  - Step 3. For  $i = 1, \ldots, n$ , set

$$x_{i} = \frac{-\sum_{j=1}^{i-1} a_{ij} x_{j} - \sum_{j=i+1}^{n} a_{ij} X O_{j} + f_{i}}{a_{ii}}$$

- Step 4. If  $\|\mathbf{x} \mathbf{XO}\| < TOL$ , then OUTPUT  $(x_1, \dots, x_n)$ ; (The procedure was successful). STOP.
- Step 5. Set k = k + 1.
- Step 6. For  $i = 1, \ldots, n$ , set  $XO_i = x_i$ .
- Step 7. OUTPUT (Maximum number of iterations exceeded); (The procedure was successful). STOP. The matlab code of G-S function file as following that

function [x, iter]=mygs(a,xexact,x0,tol)

```
b=a*xexact;

n=length(x0);
x=x0;

iter = 0;
error=1;

while error > tol
    for i=1:n
        x(i) = a(i,1:i-1)*x(1:i-1)+a(i,i+1:n)*x(i+1:n);
        x(i)=(b(i)-x(i))/a(i,i);
    end
    error=norm(x-xexact)/norm(x0-xexact);
    iter = iter + 1;
```

```
end
end
```

The matlab code of G-S iteration as following that

```
%
% Project 2
% Gauss-Seidel method
%
clear
results=[];
for k=0:5,
    n=10*2^k;
    h=1./(n+1);
    % Define Grid
    x=zeros(n,1);
    for i=1:n,
        x(i) = i*h;
    end
    %
    % Initialization
    sol = sin(pi*x);
    e=ones(n,1)/h^2;
    a=spdiags([-e 2*e -e], -1:1, n, n);
    f = a *sol;
    % Iteration starts here
    tol = 1.e-4;
    u = zeros(n,1);
    error=norm(u-sol)/norm(sol);
```

```
iter = 0;
    while error > tol
        u(1) = (h^2*f(1)+u(2))/2.;
        for i=2:n-1
            u(i) = (h^2*f(i)+u(i+1)+u(i-1))/2.;
        end
        u(n) = (h^2*f(n)+u(n-1))/2.;
        error=norm(u-sol)/norm(sol);
        iter = iter + 1;
     %
         fprintf('Iteration %d, Error: %16.10g\n', iter, norm(u1-sol));
    end
   results=[results; n error iter];
    fprintf('Iterations for n=%d: %d\n', n, iter);
end
%%
loglog(results(:,1),results(:,3),'o-'),hold on,grid on
title({['Log-Log plot of the number of Gauss-Seidels
iterations'];['Due on 2017/4/20, Changjian Xie']})
xlabel('n');
ylabel('#the number of Gauss-Seidels Iterations')
%% The same graph
clf
loglog(results(:,1),results(:,3),'o-'),hold on,grid on
xlabel('n');
ylabel('#the number of Iterations'),
title({['Log-Log plot of the number of
iterations']; ['Due on 2017/4/20, Changjian Xie']}),
hold on
%% after the fisrt one
\% note that the output result of J and G-s is different
loglog(results(:,1),results(:,3),'s-.'),hold on,
legend('Jacobis Iterations', 'Gauss-Seidels Iterations')
```

We obtain that

Do a log-log plot of the number of G-S iterations as follows

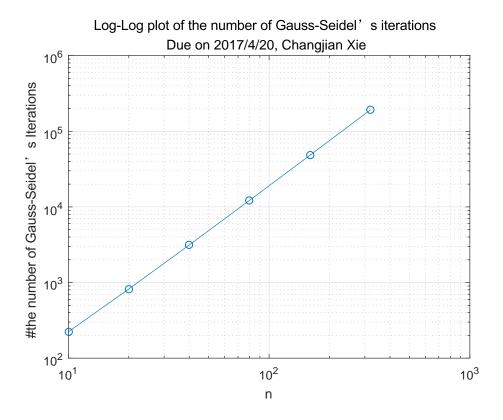


Figure 3: Using the values n=10,20,40,80,160,320. Do a log-log plot of the number of G-S iterations necessary for the error to satisfy  $\|\mathbf{x}^{(k)} - \mathbf{u}\|_2 \le \epsilon \|\mathbf{u}\|$ .

We can draw together as follows.

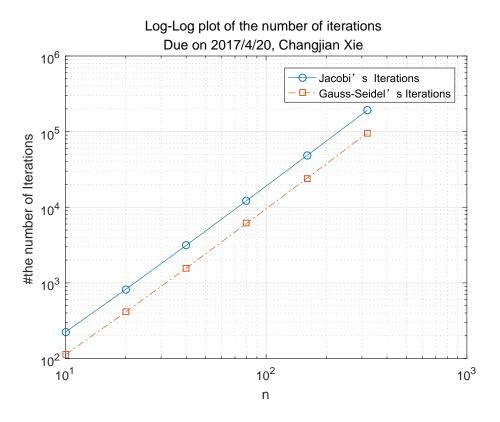


Figure 4: Using the values n=10,20,40,80,160,320. Do a log-log plot of the number of Jacobi and G-S iterations necessary for the error to satisfy  $\|\mathbf{x}^{(k)} - \mathbf{u}\|_2 \le \epsilon \|\mathbf{u}\|$ .

We can get the result from above graph that G-S iterations is a bit better than Jacobi iterations.