Machine Learning Theory Lecture 5: PAC Bayesian Learning

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October 12, 2021

1 Warm-up: PAC Learning

1.1 Big picture

let size of data to be |S| = m:

$$\mathbf{Pr}(\exists_{h \in \mathcal{H}} : (\hat{R}_S(h) = 0) \cap (R(h) > \epsilon)) \leq |\mathcal{H}| \exp^{-\epsilon m} \leq \delta$$

$$\implies m \geq \frac{\log(|\mathcal{H}|)}{\epsilon} + \frac{\log(1/\delta)}{\epsilon}$$
(1)

1.2 Some definition from usual PAC learning text

Firstly, instead of writing $\left\{x_i, y_i\right\}_{i=1}^m$, we can write it as:

$$\left\{x_i, c(x_i)\right\}_{i=1}^m \tag{2}$$

$$\begin{cases} y = c(x) & \in \mathcal{C} \quad \text{concept set} \\ \hat{y} = h(x) & \in \mathcal{H} \quad \text{hypothesis set} \end{cases} \tag{3}$$

Concept set is all set of "latent" functions that maps each x_i perfectly with y_i . I used $(x,y) \sim \mathcal{D}$ in all writings.

Of course, we cannot observe $\mathcal C$ and c may not be a member of $\mathcal H$.

Think $\mathcal C$ may be some polynomial function, but $\mathcal H$ is what the model we propose to apply, say linear.

1.2.1 bound amount of over-fitting

We are interested to compute:

$$\Pr(\underbrace{R(h) - \hat{R}_S(h)}_{\text{amount of over-fitting}} > \epsilon) \le \delta(\epsilon)$$
(4)

1.2.2 Version space

1. definition: Version space (VS)

$$VS_{\mathcal{H},S} \equiv \{ \forall h \in \mathcal{H} \mid \hat{R}_S(h) = 0 \}$$
 (5)

2. definition: ϵ -exhausted version space

 $VS_{\mathcal{H},S}$ is ϵ -exhausted iff:

$$\{\forall h \in VS_{\mathcal{H},S} \mid R(h) \le \epsilon\} \tag{6}$$

meaning that for all hypothesis h in version space (zero training error), h has less than ϵ testing error (low error)

Theorem 1 If hypothesis space \mathcal{H} is finite and S is a sequence of $m \geq 1$ i.i.d random examples of target concept c, then for any $0 \leq \epsilon \leq 1$:

Probability that version space $VS_{\mathcal{H},S}$ *is* **not** ϵ -exhausted is at most:

$$|\mathcal{H}| \exp^{-\epsilon m}$$
 (7)

1.2.3 **proof**

Start from just one $h_{\text{bad}} \in \mathcal{H}$ that assumes to be a bad classifier with error rate $\geq \epsilon$, i.e., $R(h_{\text{bad}}) \equiv \mathbb{E}_{(x,y) \sim \mathcal{D}}[R(h_1)] > \epsilon$. In order for h_1 to be element of the version space $\text{VS}_{\mathcal{H},S}$ (clearly, by including h_{bad} , $\text{VS}_{\mathcal{H},S}$ is **not** ϵ -exhausted), then, it must classify all m data in S correctly:

$$\mathbf{Pr}(\hat{R}_{S}(h_{\text{bad}}) = 0) = \mathbf{Pr}(h_{\text{bad}}(x_{1}) = y_{1} \cap \dots \cap h_{\text{bad}}(x_{m}) = y_{m})$$

$$= \mathbf{Pr}(\hat{R}_{x_{1},y_{1}}(h_{\text{bad}}) = 0 \cap \dots \cap \hat{R}_{x_{m},y_{m}}(h_{\text{bad}}) = 0)$$

$$\leq (1 - \epsilon)^{m}$$

$$\leq \exp^{-\epsilon m}$$
(8)

using well known fact: $1+x \le \left(1+\frac{x}{2}\right)^2 \le \cdots \le \left(1+\frac{x}{n}\right)^n \xrightarrow[n\to\infty]{} \exp^x$

$$\Longrightarrow \mathbf{Pr}\Big(\exists_{h\in\mathcal{H}}: (\hat{R}_S(h) = 0)\Big) \le |\mathcal{H}| \exp^{-\epsilon m}$$
 (9)

union bound, since any h_i makes it **not** ϵ -exhausted

1.2.4 what does tell you about m?

let
$$|\mathcal{H}| \exp^{-\epsilon m} \le \delta$$

 $\implies -\epsilon m \le \log(\delta) - \log(|\mathcal{H}|)$
 $\implies m \ge \frac{\log(|\mathcal{H}|)}{\epsilon} - \frac{\log(\delta)}{\epsilon}$
 $= \frac{\log(|\mathcal{H}|)}{\epsilon} + \frac{\log(1/\delta)}{\epsilon}$
(10)

let |S| = m:

$$\mathbf{Pr}\big(\exists_{h\in\mathcal{H}}: (\hat{R}_S(h)=0)\cap (R(h)>\epsilon)\big) \le |\mathcal{H}| \exp^{-\epsilon m} \le \delta \tag{11}$$

Say we fix ϵ , then if one desires to have a very small chance (i.e., set δ to be very small) that the $VS_{\mathcal{H},S}$ is **not** ϵ -exhausted, i.e., the set has good generalization (zero training error, test error to be less than ϵ), then one must feed in a very large m

1.3 Outside of version space

Hoeffding Inequality (mean version):

$$\mathbf{Pr}\left(\overline{X} - \mu \ge \epsilon\right) \le \exp\left(-\frac{2n^2 \epsilon^2}{\sum_{i=1}^n (b_i - a_i)^2}\right)$$

$$\mathbf{Pr}\left(\mu - \overline{X} \ge \epsilon\right) \le \exp\left(-\frac{2n^2 \epsilon^2}{\sum_{i=1}^n (b_i - a_i)^2}\right)$$
(12)

using the second definition for Bernoulli random variable:

$$\mathbf{Pr}(R(h) - \hat{R}_{S}(h) \ge \epsilon) \le \exp\left(-\frac{2m^{2}\epsilon^{2}}{\sum_{i=1}^{m} 1^{2}}\right)$$

$$= \exp(-2m\epsilon^{2})$$

$$\implies \mathbf{Pr}(\exists_{h \in \mathcal{H}} : R(h) - \hat{R}_{S}(h) \ge \epsilon) \le |\mathcal{H}| \exp(-2m\epsilon^{2})$$
(13)

Let
$$|\mathcal{H}| \exp(-2m\epsilon^2) \le \delta$$

 $\implies -2m\epsilon^2 \le \log(\delta) - \log(|\mathcal{H}|)$
 $\implies m \ge \frac{\log(|\mathcal{H}|)}{2\epsilon^2} - \frac{\log(\delta)}{2\epsilon^2}$
 $= \frac{\log(|\mathcal{H}|)}{2\epsilon^2} + \frac{\log(1/\delta)}{2\epsilon^2}$ (14)

2 PAC Bayes

2.1 Big picture

$$C(\hat{R}_{S}(Q)||R(Q)) \le \frac{\mathrm{KL}(Q||P) + \log\left[\frac{1}{\delta}\mathbb{E}_{S \sim \mathcal{D}}\mathbb{E}_{h \sim P}\left[\exp^{mC\left(\hat{R}_{S}(h), R(h)\right)}\right]\right]}{m}$$
(15)

The generalization error bound:

$$R(Q) \le \hat{R}_S(Q) + \sqrt{\frac{\text{KL}(Q||Q^0) + \log\left(\frac{2\sqrt{n}}{\delta}\right)}{2n}}$$
(16)

2.2 definition

- 1. \mathcal{X} input space
- 2. $\mathcal{Y} \in \{+1, -1\}$
- 3. \mathcal{D} be "true distribution" of input-output pair defined on $\mathcal{X} \times \mathcal{Y}$, such that one may

$$(x,y) \sim \mathcal{D}$$
 (17)

4. $S^m \sim \mathcal{D}$ be the sampled data pair $\in \mathcal{X} \times \mathcal{Y}$, i.e., training data

2.2.1 Q(h)

let Q be a distribution defined over \mathcal{H} :

1. Expected risk over Q:

$$R(Q) = \mathbb{E}_{(x,y) \sim \mathcal{D}} \mathbb{E}_{h \sim Q}[l(h;(x,y))]$$
(18)

2. Empirical Risk over Q:

$$\hat{R}_{S}(Q) = \frac{1}{m} \sum_{(x,y) \in S} \mathbb{E}_{h \sim Q}[l(h;(x,y))]$$
(19)

- 3. in classification, typical $l(h;(x,y)) = \mathbb{1}_{h(x)\neq y}$
- 4. without the red bits, they are just ordinary empirical and expected risks
- 5. probability distributions occur in two places:
 - (a) Q encodes hypotheses
 - (b) \mathcal{D} describes randomness in the real-world

2.3 Theorem to bound PAC-Bayes

Theorem 2 with probability at least $1 - \delta$ over $S \sim \mathcal{D}$:

$$\underbrace{\mathcal{C}(\hat{R}_{S}(Q)||R(Q))}_{consistency for Q} \leq \underbrace{\frac{KL(Q||P)}{KL(Q||P)} + \log\left[\frac{1}{\delta}\mathbb{E}_{S \sim \mathcal{D}}\mathbb{E}_{h \sim P}\left[\exp^{m\mathcal{C}\left(\hat{R}_{S}(h), R(h)\right)}\right]\right]}_{consistency for Q}$$

$$(20)$$

 $\mathcal{C}(\hat{R}_S(Q)||R(Q))$ can be thought of how consistent is the performance between hypothesis from Q on both training($\hat{R}_S(Q)$) and testing(R(Q)) data-set

2.3.1 notes on Theorem 2

- 1. **difference** between loss distribution using *sampled data* and *population/test data* is (i.e., consistency for $h \in Q$) is bounded by:
 - (a) consistency for $h \in P$
 - (b) similarity between P and Q,

the bound is true $\forall Q$ defined over \mathcal{H} , i.e., posterior distribution on \mathcal{H}

- 2. for example, when consistency for $h \in P$ is good, and P and posterior Q are similar, then the consistency for $h \in Q$ is also good
- 3. when large amount of data is used, i.e., $m \to \infty$ the difference between $\hat{R}_S(Q)$ and R(Q) is negligible
- 4. that Q need not be a Bayesian posterior, it can be any distribution

2.4 Proof

we use intermediate term:

$$f(S) = \mathbb{E}_{h \sim P} \exp^{m\mathcal{C}\left(\hat{R}_S(h), R(h)\right)}$$
(21)

since f(S) is a non-negative random variable (function of S), as $\exp(\cdot) > 0$, using Markov's inequality:

2.4.1 Markov's inequality

If X is a non-negative random variable and a > 0, then:

$$\mathbf{Pr}(X \ge a) \le \frac{\mathbb{E}[X]}{a}$$

$$\mathbf{Pr}(f(S) \ge a) \le \frac{\mathbb{E}[f(S)]}{a} \quad \text{let } f(S) \equiv X$$
(22)

letting:

$$\delta = \frac{\mathbb{E}[f(S)]}{a} \implies a = \frac{\mathbb{E}[f(S)]}{\delta}$$

$$\implies \mathbf{Pr}\left(f(S) \ge \frac{\mathbb{E}[f(S)]}{\delta}\right) \le \delta$$
(23)

substitute:

$$f(S) \equiv \mathbb{E}_{h \sim P} \left[\exp^{m\mathcal{C} \left(\hat{R}_{S}(h), R(h) \right)} \right]$$

$$\mathbb{E}[f(S)] \equiv \mathbb{E}_{S \sim \mathcal{D}} \mathbb{E}_{h \sim P} \left[\exp^{m\mathcal{C} \left(\hat{R}_{S}(h), R(h) \right)} \right]$$
(24)

$$\mathbf{Pr}\Big(\mathbb{E}_{h\sim P}\big[\exp^{m\mathcal{C}\big(\hat{R}_{S}(h),R(h)\big)}\big] > \frac{1}{\delta}\mathbb{E}_{S\sim \mathcal{D}}\mathbb{E}_{h\sim P}\big[\exp^{m\mathcal{C}\big(\hat{R}_{S}(h),R(h)\big)}\big]\Big) \le \delta \quad (25)$$

since log(.) is monotonically increasing, it won't change inquality sign:

$$\mathbf{Pr}\Big(\log\left(\mathbb{E}_{h\sim P}\left[\exp^{m\mathcal{C}\left(\hat{R}_{S}(h),R(h)\right)}\right]\right) \leq \log\left(\frac{1}{\delta}\mathbb{E}_{S\sim \mathcal{D}}\mathbb{E}_{h\sim P}\left[\exp^{m\mathcal{C}\left(\hat{R}_{S}(h),R(h)\right)}\right]\right)\Big) \geq 1 - \delta$$
(26)

2.5 find the lower bound of $\log(\mathbb{E}_{h\sim P}[f(h)])$

let \mathcal{H}_Q be support of Q i.e.,

$$h \in \mathcal{H}_Q \implies Q(h) > 0$$
 (27)

For any $g: \mathcal{H} \to \mathbb{R}$ and Q and P, we have:

$$\mathbb{E}_{h\sim P}[g(h)] = \int_{\mathcal{H}} g(h)P(h)\mathrm{d}h$$

$$= \underbrace{\int_{\mathcal{H}_Q} g(h)P(h)\mathrm{d}h}_{Q\text{support}} + \underbrace{\int_{\mathcal{H}\backslash\mathcal{H}_Q} g(h)P(h)\mathrm{d}h}_{\text{no }Q\text{ support}}$$

$$= \int_{\mathcal{H}_Q} g(h)\frac{P(h)}{Q(h)}Q(h)\mathrm{d}h + \int_{\mathcal{H}\backslash\mathcal{H}_Q} g(h)P(h)\mathrm{d}h \quad \text{introduce } Q(h) \text{ to where it has support}$$

$$\geq \mathbb{E}_{h\sim Q}\left[\frac{P(h)}{Q(h)}g(h)\right]$$

$$\Rightarrow \log \mathbb{E}_{h\sim P}[g(h)] \geq \log\left[\mathbb{E}_{h\sim Q}\left[\frac{p(h)}{Q(h)}g(h)\right]\right]$$

$$\geq \mathbb{E}_{h\sim Q}\left[\log\left[\frac{P(h)}{Q(h)}g(h)\right]\right]$$

$$= \mathbb{E}_{h\sim Q}\left[\log\left[\frac{P(h)}{Q(h)}\right]\right] + \mathbb{E}_{h\sim Q}\left[\log\left[g(h)\right]\right]$$

$$= -\mathrm{KL}(Q\|P) + \mathbb{E}_{h\sim Q}\left[\log\left[g(h)\right]\right]$$
(28)

note that the above is just standard variational Bayes, if we have:

$$P(h) \to p(z) \quad Q(h) \to q(z|x) \quad g(h) \to p(x|z)$$

$$\implies \log \mathbb{E}_{z \sim p(z)}[p(x|z)] \ge -\text{KL}(q(z|x)||p(z)) + \mathbb{E}_{z \sim q(z|x)}[\log(p(x|z)]$$
(29)

2.5.1 back to proof

substitute $g(h) = \exp^{m\mathcal{C}(\hat{R}_S(h), R(h))}$:

$$\log \left(\mathbb{E}_{h \sim P}[g(h)] \right) \ge -\text{KL}(Q \| P) + \mathbb{E}_{h \sim Q} \left[\log \left[g(h) \right] \right]$$

$$\implies \log \left(\mathbb{E}_{h \sim P} \left[\exp^{m\mathcal{C} \left(\hat{R}_{S}(h), R(h) \right)} \right] \right) \ge -\text{KL}(Q \| P) + \mathbb{E}_{h \sim Q} \left[\log \left[\exp^{m\mathcal{C} \left(\hat{R}_{S}(h), R(h) \right)} \right] \right]$$

$$= -\text{KL}(Q \| P) + m\mathbb{E}_{h \sim Q} \left[\mathcal{C} \left(\hat{R}_{S}(h), R(h) \right) \right]$$
(30)

inequality automatically applies to the lower bound with higher probability:

$$\mathbf{Pr}\Big(\log\left(\mathbb{E}_{h\sim P}\left[\exp^{m\mathcal{C}\left(\hat{R}_{S}(h),R(h)\right)}\right]\right) \leq \log\left(\frac{1}{\delta}\mathbb{E}_{S\sim \mathcal{D}}\mathbb{E}_{h\sim P}\left[\exp^{m\mathcal{C}\left(\hat{R}_{S}(h),R(h)\right)}\right]\right)\Big) \geq 1-\delta$$

$$\Longrightarrow \mathbf{Pr}\Big(-\mathsf{KL}(Q\|P) + m\mathbb{E}_{h\sim Q}\left[\mathcal{C}\left(\hat{R}_{S}(h),R(h)\right)\right]\right] \leq \log\left(\frac{1}{\delta}\mathbb{E}_{S\sim \mathcal{D}}\mathbb{E}_{h\sim P}\left[\exp^{m\mathcal{C}\left(\hat{R}_{S}(h),R(h)\right)}\right]\right)\Big) \geq 1-\delta$$

$$\Longrightarrow \mathbf{Pr}\Big(\mathbb{E}_{h\sim Q}\left[\mathcal{C}\left(\hat{R}_{S}(h),R(h)\right)\right]\right] \leq \frac{1}{m}\Big\{\mathsf{KL}(Q\|P) + \log\left[\frac{1}{\delta}\mathbb{E}_{S\sim \mathcal{D}}\mathbb{E}_{h\sim P}\left[\exp^{m\mathcal{C}\left(\hat{R}_{S}(h),R(h)\right)}\right]\right]\Big\}\Big) \geq 1-\delta$$
(31)

therefore, with probability of at least $1 - \delta$ and $\forall Q$ on \mathcal{H} :

$$C(\hat{R}_{S}(Q), R(Q)) \leq \frac{\mathrm{KL}(Q||P) + \log\left[\frac{1}{\delta}\mathbb{E}_{S \sim \mathcal{D}}\mathbb{E}_{h \sim P}\left[\exp^{mC\left(\hat{R}_{S}(h), R(h)\right)}\right]\right]}{m}$$
(32)

2.6 example of: $C(\hat{R}_S(h), R(h))$

The term $\mathcal{C}(\hat{R}_S(h), R(h))$ is measuring the consistency between $R(h) = \mathbb{E}_{(x,y) \sim \mathcal{D}}[h(x,y)]$ and its discrete sample approximation $\hat{R}_S = \frac{1}{n} \sum_{i=1}^n h(x_i, y_i)$ one of the most used choice of:

$$\mathcal{C}(\hat{R}_{S}(h), R(h)) \equiv \text{KL}\left(\text{Bernoulli}(\hat{R}_{S}(h)), \text{Bernoulli}(R(h))\right) \\
= \sum_{x \in \{0,1\}} \left(p(\hat{R}_{S}(h) = x)\right) \log \left(\frac{p(\hat{R}_{S}(h) = x)}{p(R(h) = x)}\right) \\
= \left(p(\hat{R}_{S}(h) = 1)\right) \log \left(\frac{p(\hat{R}_{S}(h) = 1)}{p(R(h) = 1)}\right) + \left(p(\hat{R}_{S}(h) = 0)\right) \log \left(\frac{p(\hat{R}_{S}(h)) = 0}{p(R(h) = 0)}\right) \\
= \hat{R}_{S}(h)\right) \log \left(\frac{\hat{R}_{S}(h)}{R(h)}\right) + \left(1 - \hat{R}_{S}(h)\right) \log \left(\frac{1 - \hat{R}_{S}(h)}{1 - R(h)}\right) \tag{33}$$

which say, instead of measure directly the difference between $\hat{R}_S(h)$, R(h), we measure the KL between Bernoulli distribution using $\hat{R}_S(h)$, R(h) as parameters. By substitution:

$$\mathbb{E}_{S \sim \mathcal{D}} \mathbb{E}_{h \sim P} \left[\exp^{m\mathcal{C}\left(\hat{R}_{S}(h), R(h)\right)} \right]$$

$$= \mathbb{E}_{S \sim \mathcal{D}} \mathbb{E}_{h \sim P} \left[\exp^{m\left[\hat{R}_{S}(h)\right) \log\left(\frac{\hat{R}_{S}(h)}{\hat{R}(h)}\right) + \left(1 - \hat{R}_{S}(h)\right) \log\left(\frac{1 - \hat{R}_{S}(h)}{1 - R(h)}\right)} \right] \right]$$

$$= \mathbb{E}_{S \sim \mathcal{D}} \mathbb{E}_{h \sim P} \left[\left(\frac{\hat{R}_{S}(h)}{R(h)}\right)^{m\hat{R}_{S}(h)} \left(\frac{1 - \hat{R}_{S}(h)}{1 - R(h)}\right)^{m(1 - \hat{R}_{S}(h))} \right]$$

$$= \mathbb{E}_{h \sim P} \mathbb{E}_{S \sim \mathcal{D}} \left[\left(\frac{\hat{R}_{S}(h)}{R(h)}\right)^{m\hat{R}_{S}(h)} + \left(\frac{1 - \hat{R}_{S}(h)}{1 - R(h)}\right)^{m(1 - \hat{R}_{S}(h))} \right] \quad \text{swap two expectations}$$

$$(34)$$

the term
$$\hat{R}_S(h) = \frac{1}{m} \sum_{(x,y) \in S} l(h;(x,y))$$
 here, sample S is given/fixed
$$= \frac{\text{number of times } l(h;(x,y)) = 1}{m}$$

$$\in \left\{0, \frac{1}{m}, \frac{2}{m}, \dots, 1\right\} \quad \text{of course, each of their probabilities is different}$$

$$(35)$$

2.6.1 consider only:
$$\mathbb{E}_{S \sim \mathcal{D}} \left[\left(\frac{\hat{R}_S(h)}{R(h)} \right)^{m\hat{R}_S(h)} + \left(\frac{1 - \hat{R}_S(h)}{1 - R(h)} \right)^{m(1 - \hat{R}_S(h))} \right]$$

instead of summing all combination of $\sum_{S \sim \mathcal{D}}$, we change the expectation variables to be $\hat{R}_S(h)$, i.e., $\mathbb{E}_{\hat{R}_S(h) \sim \text{Binomial}(m,R(h))}[\cdot]$. Instead of taking expectation over $S \sim \mathcal{D}$, we only have finite number of different $\hat{R}_S(h)$ values:

$$= \sum_{k=0}^{m} \underbrace{\binom{m}{k} R(h)^{k} (1 - R(h))^{m-k}}_{p\left(\hat{R}_{S}(h) = \frac{k}{m}\right)} \underbrace{\left(\frac{\frac{k}{m}}{R(h)}\right)^{m\frac{k}{m}} \left(\frac{1 - \frac{k}{m}}{1 - R(h)}\right)^{m(1 - \frac{k}{m})}}_{p\left(f(\hat{R}_{S}(h)) \mid \hat{R}_{S}(h) = \frac{k}{m}\right)}$$
(36)

assume that under the same hypothesis h:

$$\mathbf{Pr}_{(x,y)\sim\mathcal{D}}(l(h;(x,y)) = 1) = \mathbf{Pr}_{(x,y)\sim\mathcal{D}}(h(x) \neq y)$$

$$= R(h)$$
(37)

$$= \sum_{k=0}^{m} {m \choose k} R(h)^k (1 - R(h))^{m-k} \left(\frac{\frac{k}{m}}{R(h)}\right)^k \left(\frac{1 - \frac{k}{m}}{1 - R(h)}\right)^{m-k}$$

$$= \sum_{k=0}^{m} {m \choose k} \left(\frac{k}{m}\right)^k \left(1 - \frac{k}{m}\right)^{m-k}$$
(38)

that's fantastic, as it contains no $\hat{R}_S(h)$ nor R(h), i.e., no h

$$\mathbb{E}_{S \sim \mathcal{D}} \mathbb{E}_{h \sim P} \left[\exp^{m\mathcal{C} \left(\hat{R}_{S}(h), R(h) \right)} \right] = \sum_{k=0}^{m} \underbrace{\left(\frac{k}{m} \right) \left(\frac{k}{m} \right)^{k} \left(1 - \frac{k}{m} \right)^{m-k}}_{\leq 1}$$
(39)

note that unlike:

$$\sum_{k=0}^{m} {m \choose k} p^k (1-p)^{m-k} = 1 \tag{40}$$

however,

$$\sum_{k=0}^{m} {m \choose k} \left(\frac{k}{m}\right)^k \left(1 - \frac{k}{m}\right)^{m-k} \neq 1 \tag{41}$$

by substitution:

$$\mathcal{C}(\hat{R}_{S}(Q), R(Q))]] \leq \frac{\text{KL}(Q||P) + \log\left[\frac{1}{\delta}\mathbb{E}_{S \sim \mathcal{D}}\mathbb{E}_{h \sim P}\left[\exp^{m\mathcal{C}\left(\hat{R}_{S}(h), R(h)\right)}\right]\right]}{m} \\
= \frac{\text{KL}(Q||P) + \log\left(\frac{m+1}{\delta}\right)}{m} \tag{42}$$

2.7 lower bound of $C(\hat{R}_S(Q), R(Q))$

When consider risk function to be $C(\hat{R}_S(h), R(h)) \equiv KL(Bernoulli(\hat{R}_S(h)), Bernoulli(R(h)))$, Eq.(42) gives:

$$\mathcal{C}(\hat{R}_{S}(Q), R(Q))]] \equiv \text{KL}\left(\text{Ber}(\hat{R}_{S}(Q)) \| \text{Ber}(R(Q))\right)$$

$$\leq \frac{\text{KL}(Q\|P) + \log\left(\frac{m+1}{\delta}\right)}{m}$$
(43)

obviously, $KL(Ber(\hat{R}_S(Q))||Ber(R(Q))|$ are not useful. we can not disentangle between $\hat{R}_S(Q)$ and R(Q).

We hope to bring in its lower bound in terms of $R(Q) - \hat{R}_S(Q)$, then we can just leave R(Q) alone in the LHS. Therefore, anything on the RHS becoes the upper-bound of R(Q) we can **minimize**

2.7.1 tighter bound $\frac{m+1}{\delta} \to \frac{2\sqrt{n}}{\delta}$

with a tighter bound, we can have $\frac{m+1}{\delta} \to \frac{2\sqrt{n}}{\delta}$:

$$KL(\operatorname{Ber}(\hat{R}_{S}(Q))||\operatorname{Ber}(R(Q)) \leq \frac{KL(Q||P) + \log\left(\frac{2\sqrt{n}}{\delta}\right)}{n}$$
(44)

need to check its literature later

2.8 Pinsker's inequality converts KL back to its argument

2.8.1 tighter venison:

$$KL(\hat{p}||p) \ge \frac{(p-\hat{p})^2}{2p}$$

$$\implies p - \hat{p} \le \sqrt{2pKL(Ber(\hat{p})||Ber(p))}$$

$$\implies R(Q) - \hat{R}_S(Q) \le \sqrt{2R(Q)KL(Ber(\hat{R}_S(Q))||Ber(R(Q))} \quad \hat{p} \to \hat{R}_S(Q) \quad p \to R(Q)$$
(45)

substitute: Eq.(45)

$$R(Q) - \hat{R}_S(Q) \le \sqrt{2R(Q)\mathsf{KL}\big(\mathsf{Ber}(\hat{R}_S(Q))||\mathsf{Ber}(R(Q))\big)} \le \sqrt{2R(Q)\frac{\mathsf{KL}(Q||Q^0) + \log\left(\frac{2\sqrt{n}}{\delta}\right)}{n}}$$

$$\implies R(Q) \le \hat{R}_S(Q) + \sqrt{2R(Q)\frac{\mathsf{KL}(Q||Q^0) + \log\left(\frac{2\sqrt{n}}{\delta}\right)}{n}} \quad \text{remove the middle inequality}$$

$$\tag{46}$$

Bound is tight when population risk R(Q) is smaller, because of $\sqrt{R(Q)}$. This form of expression is only for showcase such tight bound, it is however not useful in practice. You can **not** express in the form where R(Q) appears in the right.

2.8.2 loose version:

We need anther form of looser version of "Pinsker's inequality" that does not require to have R(Q) on the RHS:

$$KL(Ber(\hat{p})||Ber(p)) \ge 2(p - \hat{p})^{2}$$

$$\Rightarrow \sqrt{KL(Ber(\hat{p})||Ber(p))} \ge \sqrt{2}(p - \hat{p})$$

$$\Rightarrow \sqrt{2}p \le \sqrt{KL(Ber(\hat{p})||Ber(p))} + \sqrt{2}\hat{p}$$

$$\Rightarrow p \le \sqrt{\frac{KL(Ber(\hat{p})||Ber(p))}{2}} + \hat{p}$$
(47)

substitution from Eq.(45):

$$\implies R(Q) \leq \hat{R}_S(Q) + \sqrt{\frac{\mathrm{KL}(\mathrm{Ber}(\hat{R}_S(Q)) \| \mathrm{Ber}(R(Q)))}{2}}$$

$$\leq \hat{R}_S(Q) + \sqrt{\frac{\mathrm{KL}(Q \| Q^0) + \log\left(\frac{2\sqrt{n}}{\delta}\right)}{2n}}$$
substitute
$$\mathrm{KL}(\mathrm{Ber}(\hat{R}_S(Q)) \| \mathrm{Ber}(R(Q))) \leq \frac{\mathrm{KL}(Q \| P) + \log\left(\frac{2\sqrt{n}}{\delta}\right)}{n}$$

$$(48)$$