

# **J1a**

## **SwapForth**

### **Reference**

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ANS Forth Compliance Label

J1a SwapForth is an ANS Forth System

Providing names from the **Core Extensions** word set

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# Chapter 1

## Getting started



Connect to the SwapForth board using a terminal program of your choice. Set the serial parameters to:

- 115200 baud
- 8 data bits, no parity, no stop bit (often called “8N1”, and often the default)

```
-----  
swapForth v0.1
```



## Chapter 2

# Available Words

### 2.1 ANS Core Words

J1a SwapForth implements most of the core ANS 94 Forth standard. Implemented words are:

```
! # #> #s ' ( * */ */mod + +! +loop , - . ."
/ /mod 0< 0= 1+ 1- 2! 2* 2/ 2@ 2drop 2dup 2over
2swap : ; < <# = > >in >number >r ?dup @ abort" abs
accept align aligned allot and base begin bl c! c, c@
cell+ cells char constant count cr create decimal depth
do does> drop dup else emit evaluate execute exit fill
find fm/mod here hold i if immediate invert j key literal
loop lshift m* max min mod move negate or over postpone
quit r> r@ recurse repeat rot rshift s" s>d sign sm/rem
source space spaces state swap then type u. u< um*
um/mod unloop until variable while word xor [ ['] [char]
]
```

These core words are not implemented:

```
>body abort" char+ chars environment? leave
```

J1a SwapForth also implements the following standard words:

```
ahead dump .s /string parse-name sliteral throw words
```

## 2.2 Additional Words

The following words are not part of the standard, and are specific to J1a SwapForth. Some are traditional Forth words, others are specific to the J1a SwapForth implementation.

**.x**

( n -- )

display n as a 4-digit hex number

---

**-rot**

( x1 x2 x3 -- x3 x1 x2 )

rotate the top three stack entries

---

**bounds**

( start cnt -- start+cnt start )

prepare to loop on a range

---

**code@**

( addr -- u )

fetch from code memory

---

**cp**

( -- a )

variable: code memory current pointer

---

**dp**

( -- a )

variable: data memory current pointer

---



**forth**

```
( -- a )
```

variable: most recent dictionary entry

---

**io!**

```
( x a -- )
```

store **x** to IO port **a**

---

**io@**

```
( a -- x )
```

fetch from IO port **a**

---

**leds**

```
( x -- )
```

write **x** to the onboard LEDs

---

**new**

```
( -- )
```

restore code and data pointers to the power-up state

---

**s,**

```
( a u -- )
```

add **u**-character the string **a** to the data space

---

**serialize**

```
( -- )
```

display all of current memory in base 36

---

**tth**

( -- a )

variable: tethered mode

---

## Chapter 3

# The SwapForth Shell

### 3.1 Command reference

### 3.2 Notes on Tethered Mode



# Chapter 4

## Memory

### 4.1 RAM Types

The J1a implementation uses 8Kbytes of RAM in a split configuration.

The lower 4K is for code. This RAM is writable, and executable, but not (directly) readable. The variable **CP** (code pointer) points into this area. To read from this region, use the special word **code@**.

The upper 4K is for data. This RAM is writable and readable. The dictionary and all variables are located in this section. The variable **DP** points into this area.

### 4.2 Dictionary Layout

The SwapForth dictionary is a linked list; the variable **forth** holds the start of this list. Each dictionary entry contains:

- **next pointer** - address of the next dictionary entry, or zero for the last dictionary entry
- **imm** - immediate bit
- **count** - length of the name, in characters, 1-31
- **name<sub>1</sub> - name<sub>n</sub>** - characters in name. If the length of the name is even, then a padding byte is appended
- **xt** - execution token for the word



## Chapter 5

# iCEstick Hardware interface



The J1a for iCEstick includes connections to the iCEstick peripherals:

- SPI flash
- LEDs
- IrDA transceiver
- Pmod connector
- prototyping connectors
- UART

Access to peripherals is via the `io@` and `io!` words. Peripherals are port-mapped into a 16-bit IO address space.

Most ports are either read-only or write-only. For read-only ports, writing to the port has no effect. For write-only ports, reading from the port gives zero.

As an example of direct port access, this word blinks the on-board LEDs when a signal on IrDA is detected.

```

: x
begin
  $2000 io@      \ read from input port
  8 and 0=       \ true if bit 3 (IrDA RXD) is 0
  $0004 io!      \ write to LEDS
again
;

```

## 5.1 Port Map

### 5.1.1 \$0001: Pmod data

Not yet implemented.

### 5.1.2 \$0002: Pmod direction

Not yet implemented.

### 5.1.3 \$0008: PIO output

Write-only port \$0008 controls the flash and IrDA outputs.

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
											IrDA SD	IrDA TXD	flash SCK	flash MOSI	flash CS

### 5.1.4 \$0004: LEDs

The five on-board LEDS are controlled by write-only port at address \$0004. Setting a bit to 1 lights the corresponding LED.

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
											LED5	LED4	LED3	LED2	LED1



5.1.5 \$1000: UART data

5.1.6 \$2000: IrDA, flash and UART inputs

Read-only port \$2000 contains the input signals from the IrDA receiver, SPI flash, and UART.

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
												IrDA RXD	flash MISO	UART key?	UART busy

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