

Write programs to generate the following gradient magnitude images and choose proper thresholds to get the binary edge images:

- Roberts operator (threshold: 12)
- Prewitt edge detector (threshold: 24)
- Sobel edge detector (threshold: 38)
- Frei and Chen gradient operator (threshold: 30)
- Kirsch compass operator (threshold: 135)
- Robinson compass operator (threshold: 43)
- Nevatia-Babu 5X5 operator (threshold: 12500)

Source code: hw9.py

執行方式: python hw9.py

版本: Python 2.7.10

Output(bmp folder):

```
lena_robert.bmp--> Robert's Operator: 12lena_prewitt.bmp--> Prewitt's Edge Detector: 24lena_sobel.bmp--> Sobel's Edge Detector: 38lena_frei_chen.bmp--> Frei and Chen's Gradient Operator: 30lena_kirsch.bmp--> Kirsch's Compass Operator: 135lena_robinson.bmp--> Robinson's Compass Operator: 43lena_nevatia.bmp--> Nevatia-Babu 5x5 Operator: 12500
```

簡述:

1. Define Kernels

在main function中定義 kernels偏移量、大小權重,以及Threshold kernels中有三個元素 [x偏移量, y偏移量, 權重] 因為有太多kernels,所以這邊拿前兩個示意圖舉例

2. Edge Detector

接著這邊寫兩個不同方法的Edge Detector,分別為:

sqrt_edge_detector(img, kernel1, kernel2, threshold)

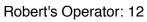
這個function除了img外,需要兩個kernel及threshold,由兩個kernel可以產生出兩個值,再將此兩個值平方相加開根號,可以產生gradient magnitude,若此值超過threshold則此點設為0 (edge),反之,設為255

max_edge_detector(img, kernel_set, threshold)

大部分操作跟上面的function差不多,不過這邊需要的kernel可能比較多,所以這邊選擇輸入kernel list,而計算gradient magnitude 的方法也不太一樣,這邊會將所有傳入的kernel都計算出一個值,比較取得最大的值設為該點的 gradient magnitude,如果此gradient magnitude超過threshold,則此點設為0 (edge),反之,設為255,另外值得一提的是,這兩個function為了避免邊界都被設為edge,這邊會利用鏡像的方式,這樣超出邊緣的部分也可以取值,避免邊界都被判斷成edge

結果:





Prewitt's Edge Detector: 24

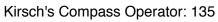


Sobel's Edge Detector: 38



Frei and Chen's Gradient Operator: 30







Robinson's Compass Operator: 43



Nevatia-Babu 5x5 Operator: 12500