Contents

1 Basic

1.1 default code

```
#pragma GCC optimize("O3,unroll-loops")
#pragma GCC target("avx2,bmi,bmi2,lzcnt,popcnt")
#include <bits/stdc++.h>
using namespace std;

ios_base::sync_with_stdio(0); cin.tie(0); cout.tie(0);
```

1.2 .vimrc

```
set nu rnu ts=4 sw=4 bs=2 ai hls cin mouse=a
color default
sy on
inoremap {<CR> {<CR>}<C-o>O
inoremap jk <Esc>
nnoremap J 5j
nnoremap K 5k
nnoremap run :w<bar>!g++ -std=c++14 -DLOCAL -Wfatal-errors -o test "%" && echo "done." && time ./test<CR>
```

1.3 Increase Stack Size (linux)

```
#include <sys/resource.h>
void increase_stack_size() {
  const rlim_t ks = 64*1024*1024;
  struct rlimit rl;
  int res=getrlimit(RLIMIT_STACK, &rl);
  if(res==0){
    if(rl.rlim_cur<ks){
      rl.rlim_cur=ks;
      res=setrlimit(RLIMIT_STACK, &rl);
} } }
```

1.4 Misc

```
編譯參數：-std=c++14 -Wall -Wshadow (-fsanitize=undefined)

mt19937 gen(chrono::steady_clock::now().time_since_epoch().count());
int randint(int lb, int ub)
{ return uniform_int_distribution<int>(lb, ub)(gen); }

#define SECs ((double)clock() / CLOCKS_PER_SEC)

struct KeyHasher {
  size_t operator()(const Key& k) const {
    return k.first + k.second * 100000;
} };
typedef unordered_map<Key,int,KeyHasher> map_t;
```

```
__builtin_popcountll    // 二進位有幾個1
__builtin_clzll         // 左起第一個1之前0的個數
__builtin_parityll      // 1的個數的奇偶性
__builtin_mul_overflow(a,b,&h) // a*b是否溢位
```

1.5 check

```
for ((i=0;;i++))
do
    echo "$i"
    python3 gen.py > input
    ./ac < input > ac.out
    ./wa < input > wa.out
    diff ac.out wa.out || break
done
```

2 flow

2.1 ISAP

```
struct Maxflow {
  static const int MAXV = 20010;
  static const int INF  = 1000000;
  struct Edge {
    int v, c, r;
    Edge(int _v, int _c, int _r):
      v(_v), c(_c), r(_r) {}
  };
  int s, t;
  vector<Edge> G[MAXV*2];
  int iter[MAXV*2], d[MAXV*2], gap[MAXV*2], tot;
  void init(int x) {
    tot = x+2;
    s = x+1, t = x+2;
    for(int i = 0; i <= tot; i++) {
      G[i].clear();
      iter[i] = d[i] = gap[i] = 0;
  } }
  void addEdge(int u, int v, int c) {
    G[u].push_back(Edge(v, c, SZ(G[v]) ));
    G[v].push_back(Edge(u, 0, SZ(G[u]) - 1));
  }
  int dfs(int p, int flow) {
    if(p == t) return flow;
    for(int &i = iter[p]; i < SZ(G[p]); i++) {
      Edge &e = G[p][i];
      if(e.c > 0 && d[p] == d[e.v]+1) {
        int f = dfs(e.v, min(flow, e.c));
        if(f) {
          e.c -= f;
          G[e.v][e.r].c += f;
          return f;
    } } }
    if( (--gap[d[p]]) == 0) d[s] = tot;
    else {
      d[p]++;
      iter[p] = 0;
      ++gap[d[p]];
    }
    return 0;
  }
  int solve() {
    int res = 0;
    gap[0] = tot;
    for(res = 0; d[s] < tot; res += dfs(s, INF));
    return res;
  }
  void reset() {
    for(int i=0;i<=tot;i++) {
      iter[i]=d[i]=gap[i]=0;
} } }flow;
```

2.2 MinCostFlow

```
struct zkwflow{
  static const int maxN=10000;
  struct Edge{ int v,f,re; ll w;};
  int n,s,t,ptr[maxN]; bool vis[maxN]; ll dis[maxN];
  vector<Edge> E[maxN];
  void init(int _n,int _s,int _t){
    n=_n,s=_s,t=_t;
    for(int i=0;i<n;i++) E[i].clear();
  }
  void addEdge(int u,int v,int f,ll w){
    E[u].push_back({v,f,(int)E[v].size(),w});
    E[v].push_back({u,0,(int)E[u].size()-1,-w});
  }
  bool SPFA(){
    fill_n(dis,n,LLONG_MAX); fill_n(vis,n,false);
    queue<int> q; q.push(s); dis[s]=0;
    while (!q.empty()){
      int u=q.front(); q.pop(); vis[u]=false;
      for(auto &it:E[u]){
        if(it.f>0&&dis[it.v]>dis[u]+it.w){
          dis[it.v]=dis[u]+it.w;
          if(!vis[it.v]){
            vis[it.v]=true; q.push(it.v);
    } } } }
    return dis[t]!=LLONG_MAX;
  }
  int DFS(int u,int nf){
    if(u==t) return nf;
    int res=0; vis[u]=true;
    for(int &i=ptr[u];i<(int)E[u].size();i++){
      auto &it=E[u][i];
      if(it.f>0&&dis[it.v]==dis[u]+it.w&&!vis[it.v]){
        int tf=DFS(it.v,min(nf,it.f));
        res+=tf,nf-=tf,it.f-=tf;
        E[it.v][it.re].f+=tf;
        if(nf==0){ vis[u]=false; break; }
      }
    }
    return res;
  }
  pair<int,ll> flow(){
    int flow=0; ll cost=0;
    while (SPFA()){
      fill_n(ptr,n,0);
      int f=DFS(s,INT_MAX);
      flow+=f; cost+=dis[t]*f;
    }
    return{ flow,cost };
  } // reset: do nothing
} flow;
```

2.3 Dinic

```
struct Dinic{
  struct Edge{ int v,f,re; };
  int n,s,t,level[MXN];
  vector<Edge> E[MXN];
  void init(int _n, int _s, int _t){
    n = _n; s = _s; t = _t;
    for (int i=0; i<n; i++) E[i].clear();
  }
  void add_edge(int u, int v, int f){
    E[u].PB({v,f,SZ(E[v])});
    E[v].PB({u,0,SZ(E[u])-1});
  }
  bool BFS(){
    for (int i=0; i<n; i++) level[i] = -1;
    queue<int> que;
    que.push(s);
    level[s] = 0;
    while (!que.empty()){
      int u = que.front(); que.pop();
      for (auto it : E[u]){
        if (it.f > 0 && level[it.v] == -1){
          level[it.v] = level[u]+1;
          que.push(it.v);
    } } }
    return level[t] != -1;
  }
  int DFS(int u, int nf){
    if (u == t) return nf;
    int res = 0;
    for (auto &it : E[u]){
      if (it.f > 0 && level[it.v] == level[u]+1){
        int tf = DFS(it.v, min(nf,it.f));
        res += tf; nf -= tf; it.f -= tf;
        E[it.v][it.re].f += tf;
        if (nf == 0) return res;
    } }
    if (!res) level[u] = -1;
    return res;
  }
  int flow(int res=0){
    while ( BFS() )
      res += DFS(s,2147483647);
    return res;
} }flow;
```

2.4 Kuhn Munkres 最大完美二分匹配

```
struct KM{ // max weight, for min negate the weights
  int n, mx[MXN], my[MXN], pa[MXN];
  ll g[MXN][MXN], lx[MXN], ly[MXN], sy[MXN];
  bool vx[MXN], vy[MXN];
  void init(int _n) { // 1-based
    n = _n;
    for(int i=1; i<=n; i++) fill(g[i], g[i]+n+1, 0);
  }
  void addEdge(int x, int y, ll w) {g[x][y] = w;}
  void augment(int y) {
    for(int x, z; y; y = z)
      x=pa[y], z=mx[x], my[y]=x, mx[x]=y;
  }
  void bfs(int st) {
    for(int i=1; i<=n; ++i) sy[i]=INF, vx[i]=vy[i]=0;
    queue<int> q; q.push(st);
    for(;;) {
      while(q.size()) {
        int x=q.front(); q.pop(); vx[x]=1;
        for(int y=1; y<=n; ++y) if(!vy[y]){
          ll t = lx[x]+ly[y]-g[x][y];
          if(t==0){
            pa[y]=x;
            if(!my[y]){augment(y);return;}
            vy[y]=1, q.push(my[y]);
          }else if(sy[y]>t) pa[y]=x,sy[y]=t;
      } }
      ll cut = INF;
      for(int y=1; y<=n; ++y)
        if(!vy[y]&&cut>sy[y]) cut=sy[y];
      for(int j=1; j<=n; ++j){
        if(vx[j]) lx[j] -= cut;
        if(vy[j]) ly[j] += cut;
        else sy[j] -= cut;
      }
      for(int y=1; y<=n; ++y) if(!vy[y]&&sy[y]==0){
        if(!my[y]){augment(y);return;}
        vy[y]=1, q.push(my[y]);
  } } }
  ll solve(){
    fill(mx, mx+n+1, 0); fill(my, my+n+1, 0);
    fill(ly, ly+n+1, 0); fill(lx, lx+n+1, -INF);
    for(int x=1; x<=n; ++x) for(int y=1; y<=n; ++y)
      lx[x] = max(lx[x], g[x][y]);
    for(int x=1; x<=n; ++x) bfs(x);
    ll ans = 0;
    for(int y=1; y<=n; ++y) ans += g[my[y]][y];
    return ans;
} }graph;
```

2.5 SW min-cut (不限 S-T 的 min-cut)

```
// global min cut
struct SW{ // O(V^3)
  int n,vst[MXN],del[MXN];
  int edge[MXN][MXN],wei[MXN];
  void init(int _n){
    n = _n; FZ(edge); FZ(del);
  }
  void addEdge(int u, int v, int w){
    edge[u][v] += w; edge[v][u] += w;
  }
  void search(int &s, int &t){
    FZ(vst); FZ(wei);
    s = t = -1;
    while (true){
      int mx=-1, cur=0;
      for (int i=0; i<n; i++)
        if (!del[i] && !vst[i] && mx<wei[i])
          cur = i, mx = wei[i];
      if (mx == -1) break;
      vst[cur] = 1;
      s = t; t = cur;
      for (int i=0; i<n; i++)
        if (!vst[i] && !del[i]) wei[i] += edge[cur][i];
    }
  }
  int solve(){
    int res = 2147483647;
    for (int i=0,x,y; i<n-1; i++){
      search(x,y);
      res = min(res,wei[y]);
      del[y] = 1;
      for (int j=0; j<n; j++)
        edge[x][j] = (edge[j][x] += edge[y][j]);
    }
    return res;
} }graph;
```

2.6 Max flow with lower/upper bound

```
// flow use ISAP
// Max flow with lower/upper bound on edges
// source = 1 , sink = n
int in[ N ] , out[ N ];
int l[ M ] , r[ M ] , a[ M ] , b[ M ];//0-base,a下界,b
    上界
int solve(){
  flow.init( n );   //n為點的數量,m為邊的數量,點是1-
      base
  for( int i = 0 ; i < m ; i ++ ){
    in[ r[ i ] ] += a[ i ];
    out[ l[ i ] ] += a[ i ];
    flow.addEdge( l[ i ] , r[ i ] , b[ i ] - a[ i ] );
    // flow from l[i] to r[i] must in [a[ i ], b[ i ]]
  }
  int nd = 0;
  for( int i = 1 ; i <= n ; i ++ ){
    if( in[ i ] < out[ i ] ){
      flow.addEdge( i , flow.t , out[ i ] - in[ i ] );
      nd += out[ i ] - in[ i ];
    }
    if( out[ i ] < in[ i ] )
      flow.addEdge( flow.s , i , in[ i ] - out[ i ] );
  }
  // original sink to source
  flow.addEdge( n , 1 , INF );
  if( flow.maxflow() != nd )
    return -1; // no solution
  int ans = flow.G[ 1 ].back().c; // source to sink
  flow.G[ 1 ].back().c = flow.G[ n ].back().c = 0;
  // take out super source and super sink
  for( size_t i = 0 ; i < flow.G[ flow.s ].size() ; i
      ++ ){
    flow.G[ flow.s ][ i ].c = 0;
    Edge &e = flow.G[ flow.s ][ i ];
    flow.G[ e.v ][ e.r ].c = 0;
  }
  for( size_t i = 0 ; i < flow.G[ flow.t ].size() ; i
      ++ ){
    flow.G[ flow.t ][ i ].c = 0;
    Edge &e = flow.G[ flow.t ][ i ];
    flow.G[ e.v ][ e.r ].c = 0;
  }
  flow.addEdge( flow.s , 1 , INF );
  flow.addEdge( n , flow.t , INF );
  flow.reset();
  return ans + flow.maxflow();
}
```

2.7 Flow Method

```
Maximize c^T x subject to Ax ≤ b, x ≥ 0;
with the corresponding symmetric dual problem,
Minimize b^T y subject to A^T y ≥ c, y ≥ 0.

Maximize c^T x subject to Ax ≤ b;
with the corresponding asymmetric dual problem,
Minimize b^T y subject to A^T y = c, y ≥ 0.

Minimum vertex cover on bipartite graph =
Maximum matching on bipartite graph

Minimum edge cover on bipartite graph =
vertex number - Minimum vertex cover(Maximum matching)

Independent set on bipartite graph =
vertex number - Minimum vertex cover(Maximum matching)

找出最小點覆蓋，做完dinic之後，從源點dfs只走還有流量的
邊，左邊沒被走到的點跟右邊被走到的點就是答案，其他點為
    最大獨立集

Maximum density subgraph ( \sum W_e + \sum W_v ) / |V|

Binary search on answer:
For a fixed D, construct a Max flow model as follow:
Let S be Sum of all weight( or inf)
1. from source to each node with cap = S
2. For each (u,v,w) in E, (u->v,cap=w), (v->u,cap=w)
3. For each node v, from v to sink with cap = S + 2 * D
     - deg[v] - 2 * (W of v)
where deg[v] = \sum weight of edge associated with v
If maxflow < S * |V|, D is an answer.

Requiring subgraph: all vertex can be reached from
    source with
edge whose cap > 0.
```

3 Math

3.1 FFT

```
// const int MAXN = 262144;
// (must be 2^k)
// before any usage, run pre_fft() first
typedef long double ld;
typedef complex<ld> cplx; //real() ,imag()
const ld PI = acosl(-1);
const cplx I(0, 1);
cplx omega[MAXN+1];
void pre_fft(){
  for(int i=0; i<=MAXN; i++)
    omega[i] = exp(i * 2 * PI / MAXN * I);
}
// n must be 2^k
void fft(int n, cplx a[], bool inv=false){
  int basic = MAXN / n;
  int theta = basic;
  for (int m = n; m >= 2; m >>= 1) {
    int mh = m >> 1;
    for (int i = 0; i < mh; i++) {
      cplx w = omega[inv ? MAXN-(i*theta%MAXN)
                         : i*theta%MAXN];
      for (int j = i; j < n; j += m) {
        int k = j + mh;
        cplx x = a[j] - a[k];
        a[j] += a[k];
        a[k] = w * x;
    } }
    theta = (theta * 2) % MAXN;
  }
  int i = 0;
  for (int j = 1; j < n - 1; j++) {
    for (int k = n >> 1; k > (i ^= k); k >>= 1);
    if (j < i) swap(a[i], a[j]);
  }
  if(inv) for (i = 0; i < n; i++) a[i] /= n;
}
cplx arr[MAXN+1];
inline void mul(int _n,ll a[],int _m,ll b[],ll ans[]){
  int n=1,sum=_n+_m-1;
  while(n<sum)
    n<<=1;
  for(int i=0;i<n;i++) {
    double x=(i<_n?a[i]:0),y=(i<_m?b[i]:0);
    arr[i]=complex<double>(x+y,x-y);
  }
  fft(n,arr);
  for(int i=0;i<n;i++)
    arr[i]=arr[i]*arr[i];
  fft(n,arr,true);
  for(int i=0;i<sum;i++)
    ans[i]=(long long int)(arr[i].real()/4+0.5);
}
```

3.2 O(1)mul

```
LL mul(LL x,LL y,LL mod){
  LL ret=x*y-(LL)((long double)x/mod*y)*mod;
  // LL ret=x*y-(LL)((long double)x*y/mod+0.5)*mod;
  return ret<0?ret+mod:ret;
}
```

3.3 Faulhaber ($\sum_{i=1}^{n} i^p$)

```
/* faulhaber’ s formula -
 * cal power sum formula of all p=1~k in O(k^2) */
#define MAXK 2500
const int mod = 1000000007;
int b[MAXK]; // bernoulli number
int inv[MAXK+1]; // inverse
int cm[MAXK+1][MAXK+1]; // combinactories
int co[MAXK][MAXK+2]; // coeeficient of x^j when p=i
inline int getinv(int x) {
  int a=x,b=mod,a0=1,a1=0,b0=0,b1=1;
  while(b) {
    int q,t;
    q=a/b; t=b; b=a-b*q; a=t;
    t=b0; b0=a0-b0*q; a0=t;
    t=b1; b1=a1-b1*q; a1=t;
  }
  return a0<0?a0+mod:a0;
}
inline void pre() {
  /* combinational */
  for(int i=0;i<=MAXK;i++) {
    cm[i][0]=cm[i][i]=1;
    for(int j=1;j<i;j++)
      cm[i][j]=add(cm[i-1][j-1],cm[i-1][j]);
  }
  /* inverse */
  for(int i=1;i<=MAXK;i++) inv[i]=getinv(i);
  /* bernoulli */
  b[0]=1; b[1]=getinv(2); // with b[1] = 1/2
  for(int i=2;i<MAXK;i++) {
    if(i&1) { b[i]=0; continue; }
    b[i]=1;
    for(int j=0;j<i;j++)
      b[i]=sub(b[i],
               mul(cm[i][j],mul(b[j], inv[i-j+1])));
  }
  /* faulhaber */
  // sigma_x=1~n {x^p} =
  //   1/(p+1) * sigma_j=0~p {C(p+1,j)*Bj*n^(p-j+1)}
  for(int i=1;i<MAXK;i++) {
    co[i][0]=0;
    for(int j=0;j<=i;j++)
      co[i][i-j+1]=mul(inv[i+1], mul(cm[i+1][j], b[j]))
          ;
  }
}
/* sample usage: return f(n,p) = sigma_x=1~n (x^p) */
inline int solve(int n,int p) {
  int sol=0,m=n;
  for(int i=1;i<=p+1;i++) {
    sol=add(sol,mul(co[p][i],m));
    m = mul(m, n);
  }
  return sol;
}
```

3.4 Chinese Remainder

```
LL x[N],m[N];
LL CRT(LL x1, LL m1, LL x2, LL m2) {
  LL g = __gcd(m1, m2);
  if((x2 - x1) % g) return -1;// no sol
  m1 /= g; m2 /= g;
  pair<LL,LL> p = gcd(m1, m2);
  LL lcm = m1 * m2 * g;
  LL res = p.first * (x2 - x1) * m1 + x1;
  return (res % lcm + lcm) % lcm;
}
LL solve(int n){ // n>=2,be careful with no solution
  LL res=CRT(x[0],m[0],x[1],m[1]),p=m[0]/__gcd(m[0],m
      [1])*m[1];
  for(int i=2;i<n;i++){
    res=CRT(res,p,x[i],m[i]);
    p=p/__gcd(p,m[i])*m[i];
  }
  return res;
}
```

3.5 Miller Rabin

```
// n < 4,759,123,141        3 :  2, 7, 61
// n < 1,122,004,669,633    4 :  2, 13, 23, 1662803
// n < 3,474,749,660,383          6 :  pirmes <= 13
// n < 2^64                       7 :
// 2, 325, 9375, 28178, 450775, 9780504, 1795265022
// Make sure testing integer is in range [2, n□2] if
// you want to use magic.
LL magic[]={}
bool witness(LL a,LL n,LL u,int t){
  if(!a) return 0;
  LL x=mypow(a,u,n);
  for(int i=0;i<t;i++) {
    LL nx=mul(x,x,n);
    if(nx==1&&x!=1&&x!=n-1) return 1;
    x=nx;
  }
  return x!=1;
}
bool miller_rabin(LL n) {
  int s=(magic number size)
  // iterate s times of witness on n
  if(n<2) return 0;
  if(!(n&1)) return n == 2;
  ll u=n-1; int t=0;
  // n-1 = u*2^t
  while(!(u&1)) u>>=1, t++;
  while(s--){
    LL a=magic[s]%n;
    if(witness(a,n,u,t)) return 0;
  }
  return 1;
}
```

3.6 Pollard Rho

```
// does not work when n is prime  O(n^(1/4))
LL f(LL x, LL mod){ return add(mul(x,x,mod),1,mod); }
LL pollard_rho(LL n) {
  if(!(n&1)) return 2;
  while(true){
    LL y=2, x=rand()%(n-1)+1, res=1;
    for(int sz=2; res==1; sz*=2) {
      for(int i=0; i<sz && res<=1; i++) {
        x = f(x, n);
        res = __gcd(abs(x-y), n);
      }
      y = x;
    }
    if (res!=0 && res!=n) return res;
} }
```

3.7 Josephus Problem

```
int josephus(int n, int m){ //n人每m次
    int ans = 0;
    for (int i=1; i<=n; ++i)
        ans = (ans + m) % i;
    return ans;
}
```

3.8 Matrix

```
//矩陣乘法
for(int i = 0; i < n; i++){
    for(int j = 0; j < n; j++){
        for(int k = 0; k < n; k++){
            ret[i][j] += a[i][k] * b[k][j];
        }
    }
}
//矩陣快速冪
int base[2][2] = {   int ans[2][2] = {
  {1, 1},              {1, 0},
  {1, 0}               {0, 1}
};                   };

int mypow(int y){
  while(y){
    if( y&1 ) { ans = mul(ans, base); } //實作矩陣乘法
    base = mul(base, base);//實作矩陣乘法
    y >>= 1;
  }
  return ans[0][0];
}
```

3.9 Gaussian Elimination

```
const int GAUSS_MOD = 100000007LL;
struct GAUSS{
  int n;
  vector<vector<int>> v;
  int ppow(int a , int k){
    if(k == 0) return 1;
    if(k % 2 == 0) return ppow(a * a % GAUSS_MOD , k >>
         1);
    if(k % 2 == 1) return ppow(a * a % GAUSS_MOD , k >>
         1) * a % GAUSS_MOD;
  }
  vector<int> solve(){
    vector<int> ans(n);
    REP(now , 0 , n){
      REP(i , now , n) if(v[now][now] == 0 && v[i][now]
           != 0)
        swap(v[i] , v[now]); // det = -det;
      if(v[now][now] == 0) return ans;
      int inv = ppow(v[now][now] , GAUSS_MOD - 2);
      REP(i , 0 , n) if(i != now){
        int tmp = v[i][now] * inv % GAUSS_MOD;
        REP(j , now , n + 1) (v[i][j] += GAUSS_MOD -
            tmp * v[now][j] % GAUSS_MOD) %= GAUSS_MOD;
      }
    }
    REP(i , 0 , n) ans[i] = v[i][n + 1] * ppow(v[i][i]
        , GAUSS_MOD - 2) % GAUSS_MOD;
    return ans;
  }
  // gs.v.clear() , gs.v.resize(n , vector<int>(n + 1 ,
       0));
} gs;
```

3.10 ax+by=gcd

```
PII gcd(int a, int b){
  if(b == 0) return {1, 0};
  PII q = gcd(b, a % b);
  return {q.second, q.first - q.second * (a / b)};
}
```

3.11 Discrete sqrt

```
void calcH(LL &t, LL &h, const LL p) {
  LL tmp=p-1; for(t=0;(tmp&1)==0;tmp/=2) t++; h=tmp;
}
// solve equation x^2 mod p = a
bool solve(LL a, LL p, LL &x, LL &y) {
  if(p == 2) { x = y = 1; return true; }
  int p2 = p / 2, tmp = mypow(a, p2, p);
  if (tmp == p - 1) return false;
  if ((p + 1) % 4 == 0) {
    x=mypow(a,(p+1)/4,p); y=p-x; return true;
  } else {
    LL t, h, b, pb; calcH(t, h, p);
    if (t >= 2) {
      do {b = rand() % (p - 2) + 2;
      } while (mypow(b, p / 2, p) != p - 1);
      pb = mypow(b, h, p);
    } int s = mypow(a, h / 2, p);
    for (int step = 2; step <= t; step++) {
      int ss = (((LL)(s * s) % p) * a) % p;
      for(int i=0;i<t-step;i++) ss=mul(ss,ss,p);
      if (ss + 1 == p) s = (s * pb) % p;
      pb = ((LL)pb * pb) % p;
    } x = ((LL)s * a) % p; y = p - x;
  } return true;
}
```

3.12 Prefix Inverse

```
void solve( int m ){
  inv[ 1 ] = 1;
  for( int i = 2 ; i < m ; i ++ )
    inv[ i ] = ((LL)(m - m / i) * inv[m % i]) % m;
}
```

3.13 Roots of Polynomial 找多項式的根

```
const double eps = 1e-12;
const double inf = 1e+12;
double a[ 10 ], x[ 10 ]; // a[0..n](coef) must be
    filled
int n; // degree of polynomial must be filled
int sign( double x ){return (x < -eps)?(-1):(x>eps);}
double f(double a[], int n, double x){
  double tmp=1,sum=0;
  for(int i=0;i<=n;i++)
  { sum=sum+a[i]*tmp; tmp=tmp*x; }
  return sum;
}
double binary(double l,double r,double a[],int n){
  int sl=sign(f(a,n,l)),sr=sign(f(a,n,r));
  if(sl==0) return l; if(sr==0) return r;
  if(sl*sr>0) return inf;
  while(r-l>eps){
    double mid=(l+r)/2;
    int ss=sign(f(a,n,mid));
    if(ss==0) return mid;
    if(ss*sl>0) l=mid; else r=mid;
  }
  return l;
}
void solve(int n,double a[],double x[],int &nx){
  if(n==1){ x[1]=-a[0]/a[1]; nx=1; return; }
  double da[10], dx[10]; int ndx;
  for(int i=n;i>=1;i--) da[i-1]=a[i]*i;
  solve(n-1,da,dx,ndx);
  nx=0;
  if(ndx==0){
    double tmp=binary(-inf,inf,a,n);
    if (tmp<inf) x[++nx]=tmp;
    return;
  }
  double tmp;
  tmp=binary(-inf,dx[1],a,n);
  if(tmp<inf) x[++nx]=tmp;
  for(int i=1;i<=ndx-1;i++){
    tmp=binary(dx[i],dx[i+1],a,n);
    if(tmp<inf) x[++nx]=tmp;
  }
  tmp=binary(dx[ndx],inf,a,n);
  if(tmp<inf) x[++nx]=tmp;
} // roots are stored in x[1..nx]
```

3.14 Combination thearom

```
const ll mod = 1e9 + 7;
ll fac[(int)2e6 + 1], inv[(int)2e6 + 1];
ll getinv(ll a){ return qpow(a, mod-2); }
void init(int n){
  fac[0] = 1;
  for(int i = 1; i <= n; i++){
    fac[i] = fac[i-1] * i % mod;
  }
  inv[n] = getinv(fac[n]);
  for(int i = n - 1; i >= 0; i--){
    inv[i] = inv[i + 1] * (i + 1) % mod;
  }
}
ll C(int n, int m){
  if(m > n) return 0;
  return fac[n] * inv[m] % mod * inv[n-m] % mod;
}
```

3.15 Primes

```
/* 12721, 13331, 14341, 75577, 123457, 222557, 556679
* 999983, 1097774749, 1076767633, 100102021, 999997771
* 1001010013, 1000512343, 987654361, 999991231
* 999888733, 98789101, 987777733, 999991921, 1010101333
* 1010102101, 1000000000039, 1000000000000037
* 2305843009213693951, 4611686018427387847
* 9223372036854775783, 18446744073709551557 */
int mu[ N ] , p_tbl[ N ];
vector<int> primes;
void sieve() {
  mu[ 1 ] = p_tbl[ 1 ] = 1;
  for( int i = 2 ; i < N ; i ++ ){
    if( !p_tbl[ i ] ){
      p_tbl[ i ] = i;
      primes.push_back( i );
      mu[ i ] = -1;
    }
    for( int p : primes ){
      int x = i * p;
      if( x >= M ) break;
      p_tbl[ x ] = p;
      mu[ x ] = -mu[ i ];
      if( i % p == 0 ){
        mu[ x ] = 0;
        break;
} } } }
vector<int> factor( int x ){
  vector<int> fac{ 1 };
  while( x > 1 ){
    int fn = SZ(fac), p = p_tbl[ x ], pos = 0;
    while( x % p == 0 ){
      x /= p;
      for( int i = 0 ; i < fn ; i ++ )
        fac.PB( fac[ pos ++ ] * p );
  } }
  return fac;
}
```

3.16 Phi

```
ll phi(ll n){   // 計算小於n的數中與n互質的有幾個
  ll res = n, a=n;
  for(ll i=2;i*i<=a;i++){ // O(sqrtN)
    if(a%i==0){
      res = res/i*(i-1);
      while(a%i==0) a/=i;
  }}
  if(a>1) res=res/a*(a-1);
  return res;
}
```

3.17 Result

- Lucas′ Theorem :
  For $n, m \in \mathbb{Z}^*$ and prime P, $C(m,n)$ mod $P = \Pi(C(m_i, n_i))$ where m_i is the i-th digit of m in base P.

- Stirling approximation :
  $n! \approx \sqrt{2\pi n}(\frac{n}{e})^n e^{\frac{1}{12n}}$

- Stirling Numbers(permutation $|P| = n$ with k cycles):
  $S(n,k) =$ coefficient of x^k in $\Pi_{i=0}^{n-1}(x+i)$

- Stirling Numbers(Partition n elements into k non-empty set):
  $S(n,k) = \frac{1}{k!}\sum\limits_{j=0}^{k}(-1)^{k-j}\binom{k}{j}j^n$

- Pick′ s Theorem : $A = i + b/2 - 1$
  A: Area、i: grid number in the inner、b: grid number on the side

- Catalan number : $C_n = \binom{2n}{n}/(n+1)$
  $C_n^{n+m} - C_{n+1}^{n+m} = (m+n)!\frac{n-m+1}{n+1} \quad for \quad n \geq m$
  $C_n = \frac{1}{n+1}\binom{2n}{n} = \frac{(2n)!}{(n+1)!n!}$
  $C_0 = 1 \quad and \quad C_{n+1} = 2(\frac{2n+1}{n+2})C_n$
  $C_0 = 1 \quad and \quad C_{n+1} = \sum_{i=0}^{n} C_i C_{n-i} \quad for \quad n \geq 0$

- Euler Characteristic:
  planar graph: $V - E + F - C = 1$
  convex polyhedron: $V - E + F = 2$
  V, E, F, C: number of vertices, edges, faces(regions), and components

- Kirchhoff's theorem :
  $A_{ii} = deg(i), A_{ij} = (i,j) \in E \ ? -1 : 0$, Deleting any one row, one column, and cal the det(A)

- Polya' theorem (c is number of color，m is the number of cycle size):
  $(\sum_{i=1}^{m} c^{gcd(i,m)})/m$

- Burnside lemma:
  $|X/G| = \frac{1}{|G|}\sum\limits_{g \in G}|X^g|$

- 錯排公式: (n 個人中，每個人皆不再原來位置的組合數):
  $dp[0] = 1; dp[1] = 0;$
  $dp[i] = (i-1) * (dp[i-1] + dp[i-2]);$

- Bell 數 (有 n 個人, 把他們拆組的方法總數) :
  $B_0 = 1$
  $B_n = \sum_{k=0}^{n} s(n,k) \quad (second - stirling)$
  $B_{n+1} = \sum_{k=0}^{n}\binom{n}{k}B_k$

- Wilson's theorem :
  $(p-1)! \equiv -1(mod \ p)$

- Fermat's little theorem :
  $a^p \equiv a(mod \ p)$

- Euler's totient function:
  $A^{B^C} mod \ p = pow(A, pow(B, C, p-1)) mod \ p$

- 歐拉函數降冪公式:
  $A^B \bmod C = A^{B \bmod \phi(c) + \phi(c)} \bmod C$

- 6 的倍數:
  $(a-1)^3 + (a+1)^3 + (-a)^3 + (-a)^3 = 6a$

4 Geometry

4.1 definition

```
typedef long double ld;
const ld eps = 1e-8;
int dcmp(ld x) {
  if(abs(x) < eps) return 0;
  else return x < 0 ? -1 : 1;
}
struct Pt {
  ld x, y;
  Pt(ld _x=0, ld _y=0):x(_x), y(_y) {}
  Pt operator+(const Pt &a) const {
    return Pt(x+a.x, y+a.y);  }
  Pt operator-(const Pt &a) const {
    return Pt(x-a.x, y-a.y);  }
  Pt operator*(const ld &a) const {
    return Pt(x*a, y*a);  }
  Pt operator/(const ld &a) const {
    return Pt(x/a, y/a);  }
  ld operator*(const Pt &a) const {
    return x*a.x + y*a.y;  }
  ld operator^(const Pt &a) const {
    return x*a.y - y*a.x;  }
  bool operator<(const Pt &a) const {
    return x < a.x || (x == a.x && y < a.y); }
    //return dcmp(x-a.x) < 0 || (dcmp(x-a.x) == 0 &&
        dcmp(y-a.y) < 0); }
  bool operator==(const Pt &a) const {
    return dcmp(x-a.x) == 0 && dcmp(y-a.y) == 0;  }
};
ld norm2(const Pt &a) {
  return a*a; }
ld norm(const Pt &a) {
  return sqrt(norm2(a)); }
Pt perp(const Pt &a) {
  return Pt(-a.y, a.x); }
Pt rotate(const Pt &a, ld ang) {
  return Pt(a.x*cos(ang)-a.y*sin(ang), a.x*sin(ang)+a.y
      *cos(ang)); }
struct Line {
  Pt s, e, v; // start, end, end-start
  ld ang;
  Line(Pt _s=Pt(0, 0), Pt _e=Pt(0, 0)):s(_s), e(_e) { v
      = e-s; ang = atan2(v.y, v.x); }
  bool operator<(const Line &L) const {
    return ang < L.ang;
} };
struct Circle {
  Pt o; ld r;
  Circle(Pt _o=Pt(0, 0), ld _r=0):o(_o), r(_r) {}
};
```

4.2 Intersection of 2 lines

```
Pt LLIntersect(Line a, Line b) {
  Pt p1 = a.s, p2 = a.e, q1 = b.s, q2 = b.e;
  ld f1 = (p2-p1)^(q1-p1),f2 = (p2-p1)^(p1-q2),f;
  if(dcmp(f=f1+f2) == 0)
    return dcmp(f1)?Pt(NAN,NAN):Pt(INFINITY,INFINITY);
  return q1*(f2/f) + q2*(f1/f);
}
```

4.3 halfPlaneIntersection

```
// for point or line solution, change > to >=
bool onleft(Line L, Pt p) {
  return dcmp(L.v^(p-L.s)) > 0;
} // segment should add Counterclockwise
// assume that Lines intersect
vector<Pt> HPI(vector<Line>& L) {
  sort(L.begin(), L.end()); // sort by angle
  int n = L.size(), fir, las;
  Pt *p = new Pt[n];
  Line *q = new Line[n];
  q[fir=las=0] = L[0];
  for(int i = 1 ; i < n ; i++) {
    while(fir < las && !onleft(L[i], p[las-1])) las--;
    while(fir < las && !onleft(L[i], p[fir])) fir++;
    q[++las] = L[i];
    if(dcmp(q[las].v^q[las-1].v) == 0) {
      las--;
      if(onleft(q[las], L[i].s)) q[las] = L[i];
    }
    if(fir < las) p[las-1] = LLIntersect(q[las-1], q[
        las]);
  }
  while(fir < las && !onleft(q[fir], p[las-1])) las--;
  if(las-fir <= 1) return {};
  p[las] = LLIntersect(q[las], q[fir]);
  int m = 0;
  vector<Pt> ans(las-fir+1);
  for(int i = fir ; i <= las ; i++) ans[m++] = p[i];
  return ans;
}
```

4.4 Convex Hull

```
double cross(Pt o, Pt a, Pt b){
  return (a-o) ^ (b-o);
}
vector<Pt> convex_hull(vector<Pt> pt){
  sort(pt.begin(),pt.end());
  int top=0;
  vector<Pt> stk(2*pt.size());
  for (int i=0; i<(int)pt.size(); i++){
    while (top >= 2 && cross(stk[top-2],stk[top-1],pt[i
        ]) <= 0)
      top--;
    stk[top++] = pt[i];
  }
  for (int i=pt.size()-2, t=top+1; i>=0; i--){
    while (top >= t && cross(stk[top-2],stk[top-1],pt[i
        ]) <= 0)
      top--;
    stk[top++] = pt[i];
  }
  stk.resize(top-1);
  return stk;
}
```

4.5 Convex Hull trick

```
/* Given a convexhull, answer querys in O(\lg N)
CH should not contain identical points, the area should
be > 0, min pair(x, y) should be listed first */
double det( const Pt& p1 , const Pt& p2 )
{ return p1.X * p2.Y - p1.Y * p2.X; }
struct Conv{
  int n;
  vector<Pt> a;
  vector<Pt> upper, lower;
  Conv(vector<Pt> _a) : a(_a){
    n = a.size();
    int ptr = 0;
    for(int i=1; i<n; ++i) if (a[ptr] < a[i]) ptr = i;
    for(int i=0; i<=ptr; ++i) lower.push_back(a[i]);
    for(int i=ptr; i<n; ++i) upper.push_back(a[i]);
    upper.push_back(a[0]);
  }
  int sign( LL x ){ // fixed when changed to double
    return x < 0 ? -1 : x > 0; }
  pair<LL,int> get_tang(vector<Pt> &conv, Pt vec){
    int l = 0, r = (int)conv.size() - 2;
    for( ; l + 1 < r; ){
      int mid = (l + r) / 2;
      if(sign(det(conv[mid+1]-conv[mid],vec))>0)r=mid;
      else l = mid;
    }
    return max(make_pair(det(vec, conv[r]), r),
               make_pair(det(vec, conv[0]), 0));
  }
  void upd_tang(const Pt &p, int id, int &i0, int &i1){
    if(det(a[i0] - p, a[id] - p) > 0) i0 = id;
    if(det(a[i1] - p, a[id] - p) < 0) i1 = id;
  }
  void bi_search(int l, int r, Pt p, int &i0, int &i1){
    if(l == r) return;
    upd_tang(p, l % n, i0, i1);
    int sl=sign(det(a[l % n] - p, a[(l + 1) % n] - p));
    for( ; l + 1 < r; ) {
      int mid = (l + r) / 2;
      int smid=sign(det(a[mid%n]-p, a[(mid+1)%n]-p));
      if (smid == sl) l = mid;
      else r = mid;
    }
    upd_tang(p, r % n, i0, i1);
  }
  int bi_search(Pt u, Pt v, int l, int r) {
    int sl = sign(det(v - u, a[l % n] - u));
    for( ; l + 1 < r; ) {
      int mid = (l + r) / 2;
      int smid = sign(det(v - u, a[mid % n] - u));
      if (smid == sl) l = mid;
      else r = mid;
    }
    return l % n;
  }
  // 1. whether a given point is inside the CH
  bool contain(Pt p) {
    if (p.X < lower[0].X || p.X > lower.back().X)
        return 0;
    int id = lower_bound(lower.begin(), lower.end(), Pt
        (p.X, -INF)) - lower.begin();
    if (lower[id].X == p.X) {
      if (lower[id].Y > p.Y) return 0;
    }else if(det(lower[id-1]-p,lower[id]-p)<0)return 0;
    id = lower_bound(upper.begin(), upper.end(), Pt(p.X
        , INF), greater<Pt>()) - upper.begin();
    if (upper[id].X == p.X) {
      if (upper[id].Y < p.Y) return 0;
    }else if(det(upper[id-1]-p,upper[id]-p)<0)return 0;
    return 1;
  }
  // 2. Find 2 tang pts on CH of a given outside point
  // return true with i0, i1 as index of tangent points
  // return false if inside CH
  bool get_tang(Pt p, int &i0, int &i1) {
    if (contain(p)) return false;
    i0 = i1 = 0;
    int id = lower_bound(lower.begin(), lower.end(), p)
         - lower.begin();
    bi_search(0, id, p, i0, i1);
    bi_search(id, (int)lower.size(), p, i0, i1);
    id = lower_bound(upper.begin(), upper.end(), p,
        greater<Pt>()) - upper.begin();
    bi_search((int)lower.size() - 1, (int)lower.size()
        - 1 + id, p, i0, i1);
    bi_search((int)lower.size() - 1 + id, (int)lower.
        size() - 1 + (int)upper.size(), p, i0, i1);
    return true;
  }
  // 3. Find tangent points of a given vector
  // ret the idx of vertex has max cross value with vec
  int get_tang(Pt vec){
    pair<LL, int> ret = get_tang(upper, vec);
    ret.second = (ret.second+(int)lower.size()-1)%n;
    ret = max(ret, get_tang(lower, vec));
    return ret.second;
  }
  // 4. Find intersection point of a given line
  // return 1 and intersection is on edge (i, next(i))
  // return 0 if no strictly intersection
  bool get_intersection(Pt u, Pt v, int &i0, int &i1){
   int p0 = get_tang(u - v), p1 = get_tang(v - u);
   if(sign(det(v-u,a[p0]-u))*sign(det(v-u,a[p1]-u))<0){
     if (p0 > p1) swap(p0, p1);
     i0 = bi_search(u, v, p0, p1);
     i1 = bi_search(u, v, p1, p0 + n);
     return 1;
   }
   return 0;
}  };
```

4.6 Intersection of 2 segments

```
int ori( const Pt& o , const Pt& a , const Pt& b ){
  LL ret = ( a - o ) ^ ( b - o );
  return (ret > 0) - (ret < 0);
}
// p1 == p2 || q1 == q2 need to be handled
bool banana( const Pt& p1 , const Pt& p2 ,
             const Pt& q1 , const Pt& q2 ){
  if( ( ( p2 - p1 ) ^ ( q2 - q1 ) ) == 0 ){ // parallel
    if( ori( p1 , p2 , q1 ) ) return false;
    return ( ( p1 - q1 ) * ( p2 - q1 ) ) <= 0 ||
           ( ( p1 - q2 ) * ( p2 - q2 ) ) <= 0 ||
           ( ( q1 - p1 ) * ( q2 - p1 ) ) <= 0 ||
           ( ( q1 - p2 ) * ( q2 - p2 ) ) <= 0;
  }
  return (ori( p1, p2, q1 ) * ori( p1, p2, q2 )<=0) &&
         (ori( q1, q2, p1 ) * ori( q1, q2, p2 )<=0);
}
```

4.7 Point In Polygon

```
int ptInPoly(vector<Pt> ps,Pt p){
  int c=0;
  for(int i=0;i<ps.size();++i){
    int a=i,b=(i+1)%ps.size(); Line l(ps[a],ps[b]);
    Pt q=l.s+l.v*((l.v*(p-l.s))/norm2(l.v)); // project
    if(norm(p-q)<eps&&onseg(q,l)) return 1; // boundary
    if(dcmp(ps[a].y-ps[b].y)==0&&dcmp(ps[a].y-p.y)==0)
      continue;
    if(ps[a].y>ps[b].y) swap(a,b);
    if(ps[a].y<=p.y&&p.y<ps[b].y&&p.x<=ps[a].x+(ps[b].x
        -ps[a].x)/(ps[b].y-ps[a].y)*(p.y-ps[a].y)) ++c;
  }
  return (c&1)*2; // 0: outside, 1: boundary, 2: inside
} // check whether a point is in a polygon
```

4.8 Tangent line of two circles

```
vector<Line> go( const Cir& c1 , const Cir& c2 , int
    sign1 ){
  // sign1 = 1 for outer tang, -1 for inter tang
  vector<Line> ret;
  double d_sq = norm2( c1.O - c2.O );
  if( d_sq < eps ) return ret;
  double d = sqrt( d_sq );
  Pt v = ( c2.O - c1.O ) / d;
  double c = ( c1.R - sign1 * c2.R ) / d;
  if( c * c > 1 ) return ret;
  double h = sqrt( max( 0.0 , 1.0 - c * c ) );
  for( int sign2 = 1 ; sign2 >= -1 ; sign2 -= 2 ){
    Pt n = { v.X * c - sign2 * h * v.Y ,
             v.Y * c + sign2 * h * v.X };
    Pt p1 = c1.O + n * c1.R;
    Pt p2 = c2.O + n * ( c2.R * sign1 );
    if( fabs( p1.X - p2.X ) < eps and
        fabs( p1.Y - p2.Y ) < eps )
      p2 = p1 + perp( c2.O - c1.O );
    ret.push_back( { p1 , p2 } );
  }
  return ret;
}
```

4.9 Minimum distance of two convex

```
double TwoConvexHullMinDis(Pt P[],Pt Q[],int n,int m){
  int mn=0,mx=0; double tmp,ans=1e9;
  for(int i=0;i<n;++i) if(P[i].y<P[mn].y) mn=i;
  for(int i=0;i<m;++i) if(Q[i].y>Q[mx].y) mx=i;
  P[n]=P[0]; Q[m]=Q[0];
  for (int i=0;i<n;++i) {
    while(tmp=((Q[mx+1]-P[mn+1])^(P[mn]-P[mn+1]))>((Q[
        mx]-P[mn+1])^(P[mn]-P[mn+1]))) mx=(mx+1)%m;
    if(tmp<0) // pt to segment distance
      ans=min(ans,dis(Line(P[mn],P[mn+1]),Q[mx]));
    else // segment to segment distance
      ans=min(ans,dis(Line(P[mn],P[mn+1]),Line(Q[mx],Q[
          mx+1])));
    mn=(mn+1)%n;
  }
  return ans;
}
```

4.10 Area of Rectangles

```
struct AreaofRectangles{
#define cl(x) (x<<1)
#define cr(x) (x<<1|1)
    ll n, id, sid;
    pair<ll,ll> tree[MXN<<3];   // count, area
    vector<ll> ind;
    tuple<ll,ll,ll,ll> scan[MXN<<1];
    void pull(int i, int l, int r){
        if(tree[i].first)  tree[i].second = ind[r+1] -
            ind[l];
        else if(l != r){
            int mid = (l+r)>>1;
            tree[i].second = tree[cl(i)].second + tree[
                cr(i)].second;
        }
        else    tree[i].second = 0;
    }
    void upd(int i, int l, int r, int ql, int qr, int v
        ){
        if(ql <= l && r <= qr){
            tree[i].first += v;
            pull(i, l, r); return;
        }
        int mid = (l+r) >> 1;
        if(ql <= mid) upd(cl(i), l, mid, ql, qr, v);
        if(qr > mid) upd(cr(i), mid+1, r, ql, qr, v);
        pull(i, l, r);
    }
    void init(int _n){
        n = _n; id = sid = 0;
        ind.clear(); ind.resize(n<<1);
        fill(tree, tree+(n<<2), make_pair(0, 0));
    }
    void addRectangle(int lx, int ly, int rx, int ry){
        ind[id++] = lx; ind[id++] = rx;
        scan[sid++] = make_tuple(ly, 1, lx, rx);
        scan[sid++] = make_tuple(ry, -1, lx, rx);
    }
    ll solve(){
        sort(ind.begin(), ind.end());
        ind.resize(unique(ind.begin(), ind.end()) - ind
            .begin());
        sort(scan, scan + sid);
        ll area = 0, pre = get<0>(scan[0]);
        for(int i = 0; i < sid; i++){
            auto [x, v, l, r] = scan[i];
            area += tree[1].second * (x-pre);
            upd(1, 0, ind.size()-1, lower_bound(ind.
                begin(), ind.end(), l)-ind.begin(),
                lower_bound(ind.begin(),ind.end(),r)-
                ind.begin()-1, v);
            pre = x;
        }
        return area;
}   }rect;
```

4.11 Min dist on Cuboid

```
typedef LL T;
T r;
void turn(T i, T j, T x, T y, T z,
          T x0, T y0, T L, T W, T H) {
  if (z==0) { T R = x*x+y*y; if (R<r) r=R; return; }
  if(i>=0 && i< 2) turn(i+1, j, x0+L+z, y, x0+L-x,
                        x0+L, y0, H, W, L);
  if(j>=0 && j< 2) turn(i, j+1, x, y0+W+z, y0+W-y,
                        x0, y0+W, L, H, W);
  if(i<=0 && i>-2) turn(i-1, j, x0-z, y, x-x0,
            x0-H, y0, H, W, L);
 if(j<=0 && j>-2) turn(i, j-1, x, y0-z, y-y0,
            x0, y0-H, L, H, W);
}
T solve(T L, T W, T H,
    T x1, T y1, T z1, T x2, T y2, T z2){
 if( z1!=0 && z1!=H ){
  if( y1==0 || y1==W )
   swap(y1,z1), swap(y2,z2), swap(W,H);
 else swap(x1,z1), swap(x2,z2), swap(L,H);
 }
 if (z1==H) z1=0, z2=H-z2;
 r=INF; turn(0,0,x2-x1,y2-y1,z2,-x1,-y1,L,W,H);
 return r;
}
```

4.12 Heart of Triangle

```
Pt inCenter( Pt &A,  Pt &B,  Pt &C) { // 內心
 double a = norm(B-C), b = norm(C-A), c = norm(A-B);
 return (A * a + B * b + C * c) / (a + b + c);
}
Pt circumCenter( Pt &a,  Pt &b,  Pt &c) { // 外心
 Pt bb = b - a, cc = c - a;
 double db=norm2(bb), dc=norm2(cc), d=2*(bb ^ cc);
 return a-Pt(bb.Y*dc-cc.Y*db, cc.X*db-bb.X*dc) / d;
}
Pt othroCenter( Pt &a,  Pt &b,  Pt &c) { // 垂心
 Pt ba = b - a, ca = c - a, bc = b - c;
 double Y = ba.Y * ca.Y * bc.Y,
  A = ca.X * ba.Y - ba.X * ca.Y,
  x0= (Y+ca.X*ba.Y*b.X-ba.X*ca.Y*c.X) / A,
  y0= -ba.X * (x0 - c.X) / ba.Y + ca.Y;
 return Pt(x0, y0);
}
```

5 Graph

5.1 DSU 並查集 & MST

```
struct DSU {// 並查集
  vector<int> fa, sz;
  DSU(int n = 0) : fa(n), sz(n, 1) {
    iota(fa.begin(), fa.end(), 0);
  }
  int Find(int x) { // 路徑壓縮
    while (x != fa[x])
      x = fa[x] = fa[fa[x]];
    return x;
  }
  bool Merge(int x, int y) { //合併
    x = Find(x), y = Find(y);
    if (x == y) return false; // 是否為連通
    if (sz[x] > sz[y]) swap(x, y);
    fa[x] = y;
    sz[y] += sz[x];
    return true;
  }
};
int MST(int n, int m,vector<tuple<int, int, int>> &edge
  ){ //0 base
  sort(edge.begin(), edge.end());
  DSU dsu(n+1); // 初始化並查集
  int res = 0, flag=1; // 最小生成樹邊權和
  for (auto &[w, u, v] : edge)
    if(dsu.Merge(u, v)) {
      res += w; //合併並統計答案
      //graph[u].push_back({v,w});
      //graph[v].push_back({u,w});
    }
    //else edges.push_back({w,u,v});
  return res;
}
int main(){
  int n, m; //點數,邊數
  cin >> n >> m;
  vector<tuple<int, int, int>> edge(m);
  for (auto &[w, u, v] : edge) cin >> u >> v >> w;
  cout << MST(n, m, edge);
}
```

5.2 Lowest Common Ancestor $O(lgn)$

```
struct LCA {
 int n, ti, lgN;
 int anc[MXN + 5][__lg(MXN) + 1] = {0};
 int MaxLength[MXN][__lg(MXN) + 1] = {0};
 int time_in[MXN] = {0};
 int time_out[MXN] = {0};
 LCA( int _n, int f ):n(_n), ti(0), lgN(__lg(n)) {
  dfs(f,f,0);
  build();
 }
 void dfs(int now, int f, int len_to_father) {  // dfs
    for anc, time, Lenth
  ti++;
  anc[now][0] = f;
  time_in[now] = ti;
  MaxLength[now][0] = len_to_father;
  for (auto i : graph[now]) {
    if (i.first == f) continue;
    dfs(i.first, now, i.second);
  }
  time_out[now] = ti;
 }
 void build() {  // build anc[][], MaxLength[][]
  for (int i = 1; i <= lgN; ++i) {
   for (int u = 1; u <= n; ++u) {
    anc[u][i] = anc[anc[u][i - 1]][i - 1];
    MaxLength[u][i] = max(MaxLength[u][i - 1],
         MaxLength[anc[u][i - 1]][i - 1]);
   }
  }
 }
 bool isAncestor(int x, int y) {
  if (time_in[x] <= time_in[y] && time_out[x] >=
    time_out[y]) return true;
  return false;
 }
 int getLCA(int u, int v) {
  if (isAncestor(u, v)) return u;
  if (isAncestor(v, u)) return v;
  for (int i = lgN; i >= 0; --i) {
   if (!isAncestor(anc[u][i], v)) {
    u = anc[u][i];
   }
  }
  return anc[u][0];
 }
 int getMAX(int u, int v) { //獲得路徑上最大邊權
  int lca = getLCA(u, v);
  int maxx = -1;
  for (int i = lgN; i >= 0; --i) {
   // u to lca
   if (!isAncestor(anc[u][i], lca)) {
    maxx = max(maxx, MaxLength[u][i]);
    u = anc[u][i];
   }
   // v to lca
   if (!isAncestor(anc[v][i], lca)) {
    maxx = max(maxx, MaxLength[v][i]);
    v = anc[v][i];
   }
  }
  if (u != lca) maxx = max(maxx, MaxLength[u][0]);
  if (v != lca) maxx = max(maxx, MaxLength[v][0]);
  return maxx;
 }
};
```

5.3 Hamiltonian path $O(n^2 2^n)$

```
//dp[i][j] = 目前在i節點走過{j}節點的路徑
for(int i=1 ; i < (1 << (n) ; i++ ) {
  for(int j = 1 ; j < n ; j++ ) {
    if(!((1 << j) & i)&&(i&1)) {
      for( int k = 0 ; k < n ; k++ ) {
        if(j == k) continue;
        if( (1<<k)&i ) dp[j][i|(1<<j)]=
          min(dp[j][i|(1<<j)],dp[k][i]+dis[k][j]);
      }
    }
  }
}
```

5.4 MaximumClique 最大團

```
#define N 111
struct MaxClique{ // 0-base
  typedef bitset<N> Int;
  Int linkto[N] , v[N];
  int n;
  void init(int _n){
    n = _n;
    for(int i = 0 ; i < n ; i ++){
      linkto[i].reset(); v[i].reset();
  } }
  void addEdge(int a , int b)
  { v[a][b] = v[b][a] = 1; }
  int popcount(const Int& val)
  { return val.count(); }
  int lowbit(const Int& val)
  { return val._Find_first(); }
  int ans , stk[N];
  int id[N] , di[N] , deg[N];
  Int cans;
  void maxclique(int elem_num, Int candi){
    if(elem_num > ans){
      ans = elem_num; cans.reset();
      for(int i = 0 ; i < elem_num ; i ++)
        cans[id[stk[i]]] = 1;
    }
    int potential = elem_num + popcount(candi);
    if(potential <= ans) return;
    int pivot = lowbit(candi);
    Int smaller_candi = candi & (~linkto[pivot]);
    while(smaller_candi.count() && potential > ans){
      int next = lowbit(smaller_candi);
      candi[next] = !candi[next];
      smaller_candi[next] = !smaller_candi[next];
      potential --;
      if(next == pivot || (smaller_candi & linkto[next
          ]).count()){
        stk[elem_num] = next;
        maxclique(elem_num + 1, candi & linkto[next]);
  } } }
  int solve(){
    for(int i = 0 ; i < n ; i ++){
      id[i] = i; deg[i] = v[i].count();
    }
    sort(id , id + n , [&](int id1, int id2){
          return deg[id1] > deg[id2]; });
    for(int i = 0 ; i < n ; i ++) di[id[i]] = i;
    for(int i = 0 ; i < n ; i ++)
      for(int j = 0 ; j < n ; j ++)
        if(v[i][j]) linkto[di[i]][di[j]] = 1;
    Int cand; cand.reset();
    for(int i = 0 ; i < n ; i ++) cand[i] = 1;
    ans = 1;
    cans.reset(); cans[0] = 1;
    maxclique(0, cand);
    return ans;
} }solver;
```

5.5 MaximalClique 極大團

```
#define N 80
struct MaxClique{ // 0-base
  typedef bitset<N> Int;
  Int lnk[N] , v[N];
  int n;
  void init(int _n){
    n = _n;
    for(int i = 0 ; i < n ; i ++){
      lnk[i].reset(); v[i].reset();
  } }
  void addEdge(int a , int b)
  { v[a][b] = v[b][a] = 1; }
  int ans , stk[N], id[N] , di[N] , deg[N];
  Int cans;
  void dfs(int elem_num, Int candi, Int ex){
    if(candi.none()&&ex.none()){
      cans.reset();
      for(int i = 0 ; i < elem_num ; i ++)
        cans[id[stk[i]]] = 1;
      ans = elem_num; // cans is a maximal clique
      return;
    }
    int pivot = (candi|ex)._Find_first();
    Int smaller_candi = candi & (~lnk[pivot]);
    while(smaller_candi.count()){
      int nxt = smaller_candi._Find_first();
      candi[nxt] = smaller_candi[nxt] = 0;
      ex[nxt] = 1;
      stk[elem_num] = nxt;
      dfs(elem_num+1,candi&lnk[nxt],ex&lnk[nxt]);
  } }
  int solve(){
    for(int i = 0 ; i < n ; i ++){
      id[i] = i; deg[i] = v[i].count();
    }
    sort(id , id + n , [&](int id1, int id2){
          return deg[id1] > deg[id2]; });
    for(int i = 0 ; i < n ; i ++) di[id[i]] = i;
    for(int i = 0 ; i < n ; i ++)
      for(int j = 0 ; j < n ; j ++)
        if(v[i][j]) lnk[di[i]][di[j]] = 1;
    ans = 1; cans.reset(); cans[0] = 1;
    dfs(0, Int(string(n,'1')), 0);
    return ans;
} }solver;
```

5.6 Strongly Connected Component

```
struct Scc{
  int n, nScc, vst[MXN], bln[MXN];
  vector<int> E[MXN], rE[MXN], vec;
  void init(int _n){
    n = _n;
    for (int i=0; i<MXN; i++)
      E[i].clear(), rE[i].clear();
  }
  void addEdge(int u, int v){
    E[u].PB(v); rE[v].PB(u);
  }
  void DFS(int u){
    vst[u]=1;
    for (auto v : E[u]) if (!vst[v]) DFS(v);
    vec.PB(u);
  }
  void rDFS(int u){
    vst[u] = 1; bln[u] = nScc;
    for (auto v : rE[u]) if (!vst[v]) rDFS(v);
  }
  void solve(){
    nScc = 0;
    vec.clear();
    FZ(vst);
    for (int i=0; i<n; i++)
      if (!vst[i]) DFS(i);
    reverse(vec.begin(),vec.end());
    FZ(vst);
    for (auto v : vec)
      if (!vst[v]){
        rDFS(v); nScc++;
      }
  }
};
```

5.7 Maximum General graph Matching

```
// should shuffle vertices and edges
const int N=100005,E=(2e5)*2+40;
struct Graph{ // 1-based; match: i <-> lnk[i]
  int to[E],bro[E],head[N],e,lnk[N],vis[N],stp,n;
  void init(int _n){
    stp=0; e=1; n=_n;
    for(int i=1;i<=n;i++) head[i]=lnk[i]=vis[i]=0;
  }
  void add_edge(int u,int v){
    to[e]=v,bro[e]=head[u],head[u]=e++;
    to[e]=u,bro[e]=head[v],head[v]=e++;
  }
  bool dfs(int x){
    vis[x]=stp;
    for(int i=head[x];i;i=bro[i]){
      int v=to[i];
      if(!lnk[v]){ lnk[x]=v,lnk[v]=x; return true; }
    }
    for(int i=head[x];i;i=bro[i]){
      int v=to[i];
      if(vis[lnk[v]]<stp){
        int w=lnk[v]; lnk[x]=v,lnk[v]=x,lnk[w]=0;
        if(dfs(w)) return true;
        lnk[w]=v,lnk[v]=w,lnk[x]=0;
      }
    }
    return false;
  }
  int solve(){
    int ans=0;
    for(int i=1;i<=n;i++) if(!lnk[i]) stp++,ans+=dfs(i)
        ;
    return ans;
  }
}graph;
```

5.8 Minimum General Weighted Matching

```
struct Graph {
  // Minimum General Weighted Matching (Perfect Match)
  static const int MXN = 105;
  int n, edge[MXN][MXN];
  int match[MXN],dis[MXN],onstk[MXN];
  vector<int> stk;
  void init(int _n) {
    n = _n;
    for( int i = 0 ; i < n ; i ++ )
      for( int j = 0 ; j < n ; j ++ )
        edge[ i ][ j ] = 0;
  }
  void add_edge(int u, int v, int w)
  { edge[u][v] = edge[v][u] = w; }
  bool SPFA(int u){
    if (onstk[u]) return true;
    stk.PB(u);
    onstk[u] = 1;
    for (int v=0; v<n; v++){
      if (u != v && match[u] != v && !onstk[v]){
        int m = match[v];
        if (dis[m] > dis[u] - edge[v][m] + edge[u][v]){
          dis[m] = dis[u] - edge[v][m] + edge[u][v];
          onstk[v] = 1;
          stk.PB(v);
          if (SPFA(m)) return true;
          stk.pop_back();
          onstk[v] = 0;
    } } }
    onstk[u] = 0;
    stk.pop_back();
    return false;
  }
  int solve() {
    // find a match
    for (int i=0; i<n; i+=2){
      match[i] = i+1;
      match[i+1] = i;
    }
    while (true){
      int found = 0;
      for( int i = 0 ; i < n ; i ++ )
        onstk[ i ] = dis[ i ] = 0;
      for (int i=0; i<n; i++){
        stk.clear();
        if (!onstk[i] && SPFA(i)){
          found = 1;
          while (SZ(stk)>=2){
            int u = stk.back(); stk.pop_back();
            int v = stk.back(); stk.pop_back();
            match[u] = v;
            match[v] = u;
      } } }
      if (!found) break;
    }
    int ret = 0;
    for (int i=0; i<n; i++)
      ret += edge[i][match[i]];
    ret /= 2;
    return ret;
  }
}graph;
```

5.9 Maximum General Weighted Matching

```
struct WeightGraph {
  static const int INF = INT_MAX;
  static const int N = 514;
  struct edge{
    int u,v,w; edge(){}
    edge(int ui,int vi,int wi)
      :u(ui),v(vi),w(wi){}
  };
  int n,n_x;
  edge g[N*2][N*2];
  int lab[N*2];
  int match[N*2],slack[N*2],st[N*2],pa[N*2];
  int flo_from[N*2][N+1],S[N*2],vis[N*2];
  vector<int> flo[N*2];
  queue<int> q;
  int e_delta(const edge &e){
    return lab[e.u]+lab[e.v]-g[e.u][e.v].w*2;
  }
  void update_slack(int u,int x){
    if(!slack[x]||e_delta(g[u][x])<e_delta(g[slack[x]][
        x]))slack[x]=u;
  }
  void set_slack(int x){
    slack[x]=0;
    for(int u=1;u<=n;++u)
      if(g[u][x].w>0&&st[u]!=x&&S[st[u]]==0)
        update_slack(u,x);
  }
  void q_push(int x){
    if(x<=n)q.push(x);
    else for(size_t i=0;i<flo[x].size();i++)
      q_push(flo[x][i]);
  }
  void set_st(int x,int b){
    st[x]=b;
    if(x>n)for(size_t i=0;i<flo[x].size();++i)
      set_st(flo[x][i],b);
  }
  int get_pr(int b,int xr){
    int pr=find(flo[b].begin(),flo[b].end(),xr)-flo[b].
        begin();
    if(pr%2==1){
      reverse(flo[b].begin()+1,flo[b].end());
      return (int)flo[b].size()-pr;
    }else return pr;
  }
  void set_match(int u,int v){
    match[u]=g[u][v].v;
    if(u<=n) return;
    edge e=g[u][v];
    int xr=flo_from[u][e.u],pr=get_pr(u,xr);
    for(int i=0;i<pr;++i)set_match(flo[u][i],flo[u][i
        ^1]);
    set_match(xr,v);
    rotate(flo[u].begin(),flo[u].begin()+pr,flo[u].end
        ());
  }
  void augment(int u,int v){
    for(;;){
      int xnv=st[match[u]];
      set_match(u,v);
      if(!xnv)return;
      set_match(xnv,st[pa[xnv]]);
      u=st[pa[xnv]],v=xnv;
  } }
  int get_lca(int u,int v){
    static int t=0;
    for(++t;u||v;swap(u,v)){
      if(u==0)continue;
      if(vis[u]==t)return u;
      vis[u]=t;
      u=st[match[u]];
      if(u)u=st[pa[u]];
    }
    return 0;
  }
  void add_blossom(int u,int lca,int v){
    int b=n+1;
    while(b<=n_x&&st[b])++b;
    if(b>n_x)++n_x;
    lab[b]=0,S[b]=0;
    match[b]=match[lca];
    flo[b].clear();
    flo[b].push_back(lca);
    for(int x=u,y;x!=lca;x=st[pa[y]])
      flo[b].push_back(x),flo[b].push_back(y=st[match[x
          ]]),q_push(y);
    reverse(flo[b].begin()+1,flo[b].end());
    for(int x=v,y;x!=lca;x=st[pa[y]])
      flo[b].push_back(x),flo[b].push_back(y=st[match[x
          ]]),q_push(y);
    set_st(b,b);
    for(int x=1;x<=n_x;++x)g[b][x].w=g[x][b].w=0;
    for(int x=1;x<=n;++x)flo_from[b][x]=0;
    for(size_t i=0;i<flo[b].size();++i){
      int xs=flo[b][i];
      for(int x=1;x<=n_x;++x)
        if(g[b][x].w==0||e_delta(g[xs][x])<e_delta(g[b
            ][x]))
          g[b][x]=g[xs][x],g[x][b]=g[x][xs];
      for(int x=1;x<=n;++x)
        if(flo_from[xs][x])flo_from[b][x]=xs;
    }
    set_slack(b);
  }
  void expand_blossom(int b){
    for(size_t i=0;i<flo[b].size();++i)
      set_st(flo[b][i],flo[b][i]);
    int xr=flo_from[b][g[b][pa[b]].u],pr=get_pr(b,xr);
    for(int i=0;i<pr;i+=2){
      int xs=flo[b][i],xns=flo[b][i+1];
      pa[xs]=g[xns][xs].u;
      S[xs]=1,S[xns]=0;
      slack[xs]=0,set_slack(xns);
      q_push(xns);
    }
    S[xr]=1,pa[xr]=pa[b];
    for(size_t i=pr+1;i<flo[b].size();++i){
      int xs=flo[b][i];
      S[xs]=-1,set_slack(xs);
    }
    st[b]=0;
  }
  bool on_found_edge(const edge &e){
    int u=st[e.u],v=st[e.v];
    if(S[v]==-1){
      pa[v]=e.u,S[v]=1;
      int nu=st[match[v]];
      slack[v]=slack[nu]=0;
      S[nu]=0,q_push(nu);
    }else if(S[v]==0){
      int lca=get_lca(u,v);
      if(!lca)return augment(u,v),augment(v,u),true;
      else add_blossom(u,lca,v);
    }
    return false;
  }
  bool matching(){
    memset(S+1,-1,sizeof(int)*n_x);
    memset(slack+1,0,sizeof(int)*n_x);
    q=queue<int>();
    for(int x=1;x<=n_x;++x)
      if(st[x]==x&&!match[x])pa[x]=0,S[x]=0,q_push(x);
    if(q.empty())return false;
    for(;;){
      while(q.size()){
        int u=q.front();q.pop();
        if(S[st[u]]==1)continue;
        for(int v=1;v<=n;++v)
          if(g[u][v].w>0&&st[u]!=st[v]){
            if(e_delta(g[u][v])==0){
              if(on_found_edge(g[u][v]))return true;
            }else update_slack(u,st[v]);
      }   }
      int d=INF;
      for(int b=n+1;b<=n_x;++b)
        if(st[b]==b&&S[b]==1)d=min(d,lab[b]/2);
      for(int x=1;x<=n_x;++x)
        if(st[x]==x&&slack[x]){
          if(S[x]==-1)d=min(d,e_delta(g[slack[x]][x]));
          else if(S[x]==0)d=min(d,e_delta(g[slack[x]][x
              ])/2);
        }
      for(int u=1;u<=n;++u){
        if(S[st[u]]==0){
          if(lab[u]<=d)return 0;
          lab[u]-=d;
        }else if(S[st[u]]==1)lab[u]+=d;
      }
      for(int b=n+1;b<=n_x;++b)
        if(st[b]==b){
          if(S[st[b]]==0)lab[b]+=d*2;
          else if(S[st[b]]==1)lab[b]-=d*2;
        }
      q=queue<int>();
      for(int x=1;x<=n_x;++x)
        if(st[x]==x&&slack[x]&&st[slack[x]]!=x&&e_delta
            (g[slack[x]][x])==0)
          if(on_found_edge(g[slack[x]][x]))return true;
      for(int b=n+1;b<=n_x;++b)
        if(st[b]==b&&S[b]==1&&lab[b]==0)expand_blossom(
            b);
    }
    return false;
  }
  pair<long long,int> solve(){
    memset(match+1,0,sizeof(int)*n);
    n_x=n;
    int n_matches=0;
    long long tot_weight=0;
    for(int u=0;u<=n;++u)st[u]=u,flo[u].clear();
    int w_max=0;
    for(int u=1;u<=n;++u)
      for(int v=1;v<=n;++v){
        flo_from[u][v]=(u==v?u:0);
        w_max=max(w_max,g[u][v].w);
      }
    for(int u=1;u<=n;++u)lab[u]=w_max;
    while(matching())++n_matches;
    for(int u=1;u<=n;++u)
      if(match[u]&&match[u]<u)
        tot_weight+=g[u][match[u]].w;
    return make_pair(tot_weight,n_matches);
  }
  void add_edge( int ui , int vi , int wi ){
    g[ui][vi].w = g[vi][ui].w = wi;
  }
  void init( int _n ){
    n = _n;
    for(int u=1;u<=n;++u)
      for(int v=1;v<=n;++v)
        g[u][v]=edge(u,v,0);
  }
} graph;
```

5.10 BCC based on vertex

```
struct BccVertex {
  int n,nScc,step,dfn[MXN],low[MXN];
  vector<int> E[MXN],sccv[MXN];
  int top,stk[MXN];
  void init(int _n) {
    n = _n; nScc = step = 0;
    for (int i=0; i<n; i++) E[i].clear();
  }
  void addEdge(int u, int v)
  { E[u].PB(v); E[v].PB(u); }
  void DFS(int u, int f) {
    dfn[u] = low[u] = step++;
    stk[top++] = u;
    for (auto v:E[u]) {
      if (v == f) continue;
      if (dfn[v] == -1) {
        DFS(v,u);
        low[u] = min(low[u], low[v]);
        if (low[v] >= dfn[u]) {
          int z;
          sccv[nScc].clear();
          do {
            z = stk[--top];
            sccv[nScc].PB(z);
          } while (z != v);
          sccv[nScc++].PB(u);
        }
      }else
        low[u] = min(low[u],dfn[v]);
  } }
  vector<vector<int>> solve() {
    vector<vector<int>> res;
    for (int i=0; i<n; i++)
      dfn[i] = low[i] = -1;
    for (int i=0; i<n; i++)
      if (dfn[i] == -1) {
        top = 0;
        DFS(i,i);
      }
    REP(i,nScc) res.PB(sccv[i]);
    return res;
  }
}graph;
```

5.11 Min Mean Cycle

```
/* minimum mean cycle O(VE) */
struct MMC{
#define E 101010
#define V 1021
#define inf 1e9
#define eps 1e-6
  struct Edge { int v,u; double c; };
  int n, m, prv[V][V], prve[V][V], vst[V];
  Edge e[E];
  vector<int> edgeID, cycle, rho;
  double d[V][V];
  void init( int _n )
  { n = _n; m = 0; }
  // WARNING: TYPE matters
  void addEdge( int vi , int ui , double ci )
  { e[ m ++ ] = { vi , ui , ci }; }
  void bellman_ford() {
    for(int i=0; i<n; i++) d[0][i]=0;
    for(int i=0; i<n; i++) {
      fill(d[i+1], d[i+1]+n, inf);
      for(int j=0; j<m; j++) {
        int v = e[j].v, u = e[j].u;
        if(d[i][v]<inf && d[i+1][u]>d[i][v]+e[j].c) {
          d[i+1][u] = d[i][v]+e[j].c;
          prv[i+1][u] = v;
          prve[i+1][u] = j;
  } } } }
  double solve(){
    // returns inf if no cycle, mmc otherwise
    double mmc=inf;
    int st = -1;
    bellman_ford();
    for(int i=0; i<n; i++) {
      double avg=-inf;
      for(int k=0; k<n; k++) {
        if(d[n][i]<inf-eps) avg=max(avg,(d[n][i]-d[k][i
            ])/(n-k));
        else avg=max(avg,inf);
      }
      if (avg < mmc) tie(mmc, st) = tie(avg, i);
    }
    fill(vst,0); edgeID.clear(); cycle.clear(); rho.
        clear();
    for (int i=n; !vst[st]; st=prv[i--][st]) {
      vst[st]++;
      edgeID.PB(prve[i][st]);
      rho.PB(st);
    }
    while (vst[st] != 2) {
      if(rho.empty()) return inf;
      int v = rho.back(); rho.pop_back();
      cycle.PB(v);
      vst[v]++;
    }
    reverse(ALL(edgeID));
    edgeID.resize(SZ(cycle));
    return mmc;
} }mmc;
```

5.12 Directed Graph Min Cost Cycle

```
// works in O(N M)
#define INF 100000000000000LL
#define N 5010
#define M 200010
struct edge{
  int to; LL w;
  edge(int a=0, LL b=0): to(a), w(b){}
};
struct node{
  LL d; int u, next;
  node(LL a=0, int b=0, int c=0): d(a), u(b), next(c){}
}b[M];
struct DirectedGraphMinCycle{
  vector<edge> g[N], grev[N];
  LL dp[N][N], p[N], d[N], mu;
  bool inq[N];
  int n, bn, bsz, hd[N];
  void b_insert(LL d, int u){
    int i = d/mu;
    if(i >= bn) return;
    b[++bsz] = node(d, u, hd[i]);
    hd[i] = bsz;
  }
  void init( int _n ){
    n = _n;
    for( int i = 1 ; i <= n ; i ++ )
      g[ i ].clear();
  }
  void addEdge( int ai , int bi , LL ci )
  { g[ai].push_back(edge(bi,ci)); }
  LL solve(){
    fill(dp[0], dp[0]+n+1, 0);
    for(int i=1; i<=n; i++){
      fill(dp[i]+1, dp[i]+n+1, INF);
      for(int j=1; j<=n; j++) if(dp[i-1][j] < INF){
        for(int k=0; k<(int)g[j].size(); k++)
          dp[i][g[j][k].to] =min(dp[i][g[j][k].to],
                                 dp[i-1][j]+g[j][k].w);
    } }
    mu=INF; LL bunbo=1;
    for(int i=1; i<=n; i++) if(dp[n][i] < INF){
      LL a=-INF, b=1;
      for(int j=0; j<=n-1; j++) if(dp[j][i] < INF){
        if(a*(n-j) < b*(dp[n][i]-dp[j][i])){
          a = dp[n][i]-dp[j][i];
          b = n-j;
      } }
      if(mu*b > bunbo*a)
        mu = a, bunbo = b;
    }
    if(mu < 0) return -1; // negative cycle
    if(mu == INF) return INF; // no cycle
    if(mu == 0) return 0;
    for(int i=1; i<=n; i++)
      for(int j=0; j<(int)g[i].size(); j++)
      g[i][j].w *= bunbo;
    memset(p, 0, sizeof(p));
    queue<int> q;
    for(int i=1; i<=n; i++){
      q.push(i);
      inq[i] = true;
    }
    while(!q.empty()){
      int i=q.front(); q.pop(); inq[i]=false;
      for(int j=0; j<(int)g[i].size(); j++){
        if(p[g[i][j].to] > p[i]+g[i][j].w-mu){
          p[g[i][j].to] = p[i]+g[i][j].w-mu;
          if(!inq[g[i][j].to]){
            q.push(g[i][j].to);
            inq[g[i][j].to] = true;
    } } } } }
    for(int i=1; i<=n; i++) grev[i].clear();
    for(int i=1; i<=n; i++)
      for(int j=0; j<(int)g[i].size(); j++){
        g[i][j].w += p[i]-p[g[i][j].to];
        grev[g[i][j].to].push_back(edge(i, g[i][j].w));
      }
    LL mldc = n*mu;
    for(int i=1; i<=n; i++){
      bn=mldc/mu, bsz=0;
      memset(hd, 0, sizeof(hd));
      fill(d+i+1, d+n+1, INF);
      b_insert(d[i]=0, i);
      for(int j=0; j<=bn-1; j++) for(int k=hd[j]; k; k=
          b[k].next){
        int u = b[k].u;
        LL du = b[k].d;
        if(du > d[u]) continue;
        for(int l=0; l<(int)g[u].size(); l++) if(g[u][l
            ].to > i){
          if(d[g[u][l].to] > du + g[u][l].w){
            d[g[u][l].to] = du + g[u][l].w;
            b_insert(d[g[u][l].to], g[u][l].to);
      } } }
      for(int j=0; j<(int)grev[i].size(); j++) if(grev[
          i][j].to > i)
        mldc=min(mldc,d[grev[i][j].to] + grev[i][j].w);
    }
    return mldc / bunbo;
} }graph;
```

5.13 K-th Shortest Path

```
// time: O(|E| \lg |E| + |V| \lg |V| + K)
// memory: O(|E| \lg |E| + |V|)
struct KSP{ // 1-base
  struct nd{
    int u, v; ll d;
    nd(int ui = 0, int vi = 0, ll di = INF)
    { u = ui; v = vi; d = di; }
  };
  struct heap{
    nd* edge; int dep; heap* chd[4];
  };
  static int cmp(heap* a,heap* b)
  { return a->edge->d > b->edge->d; }
  struct node{
    int v; ll d; heap* H; nd* E;
    node(){}
    node(ll _d, int _v, nd* _E)
    { d =_d; v = _v; E = _E; }
    node(heap* _H, ll _d)
    { H = _H; d = _d; }
    friend bool operator<(node a, node b)
    { return a.d > b.d; }
  };
  int n, k, s, t;
  ll dst[ N ];
  nd *nxt[ N ];
  vector<nd*> g[ N ], rg[ N ];
  heap *nullNd, *head[ N ];
  void init( int _n , int _k , int _s , int _t ){
    n = _n; k = _k; s = _s; t = _t;
    for( int i = 1 ; i <= n ; i ++ ){
      g[ i ].clear(); rg[ i ].clear();
      nxt[ i ] = NULL; head[ i ] = NULL;
      dst[ i ] = -1;
  } }
  void addEdge( int ui , int vi , ll di ){
    nd* e = new nd(ui, vi, di);
    g[ ui ].push_back( e );
    rg[ vi ].push_back( e );
  }
  queue<int> dfsQ;
  void dijkstra(){
    while(dfsQ.size()) dfsQ.pop();
    priority_queue<node> Q;
    Q.push(node(0, t, NULL));
    while (!Q.empty()){
      node p = Q.top(); Q.pop();
      if(dst[p.v] != -1) continue;
      dst[ p.v ] = p.d;
      nxt[ p.v ] = p.E;
      dfsQ.push( p.v );
      for(auto e: rg[ p.v ])
        Q.push(node(p.d + e->d, e->u, e));
  } }
  heap* merge(heap* curNd, heap* newNd){
    if(curNd == nullNd) return newNd;
    heap* root = new heap;
    memcpy(root, curNd, sizeof(heap));
    if(newNd->edge->d < curNd->edge->d){
      root->edge = newNd->edge;
      root->chd[2] = newNd->chd[2];
      root->chd[3] = newNd->chd[3];
      newNd->edge = curNd->edge;
      newNd->chd[2] = curNd->chd[2];
      newNd->chd[3] = curNd->chd[3];
    }
    if(root->chd[0]->dep < root->chd[1]->dep)
      root->chd[0] = merge(root->chd[0],newNd);
    else
      root->chd[1] = merge(root->chd[1],newNd);
    root->dep = max(root->chd[0]->dep, root->chd[1]->
        dep) + 1;
    return root;
  }
  vector<heap*> V;
  void build(){
    nullNd = new heap;
    nullNd->dep = 0;
    nullNd->edge = new nd;
    fill(nullNd->chd, nullNd->chd+4, nullNd);
    while(not dfsQ.empty()){
      int u = dfsQ.front(); dfsQ.pop();
      if(!nxt[ u ]) head[ u ] = nullNd;
      else head[ u ] = head[nxt[ u ]->v];
      V.clear();
      for( auto&& e : g[ u ] ){
        int v = e->v;
        if( dst[ v ] == -1 ) continue;
        e->d += dst[ v ] - dst[ u ];
        if( nxt[ u ] != e ){
          heap* p = new heap;
          fill(p->chd, p->chd+4, nullNd);
          p->dep = 1;
          p->edge = e;
          V.push_back(p);
      } }
      if(V.empty()) continue;
      make_heap(V.begin(), V.end(), cmp);
#define L(X) ((X<<1)+1)
#define R(X) ((X<<1)+2)
      for( size_t i = 0 ; i < V.size() ; i ++ ){
        if(L(i) < V.size()) V[i]->chd[2] = V[L(i)];
        else V[i]->chd[2]=nullNd;
        if(R(i) < V.size()) V[i]->chd[3] = V[R(i)];
        else V[i]->chd[3]=nullNd;
      }
      head[u] = merge(head[u], V.front());
  } }
  vector<ll> ans;
  void first_K(){
    ans.clear();
    priority_queue<node> Q;
    if( dst[ s ] == -1 ) return;
    ans.push_back( dst[ s ] );
    if( head[s] != nullNd )
      Q.push(node(head[s], dst[s]+head[s]->edge->d));
    for( int _ = 1 ; _ < k and not Q.empty() ; _ ++ ){
      node p = Q.top(), q; Q.pop();
      ans.push_back( p.d );
      if(head[ p.H->edge->v ] != nullNd){
        q.H = head[ p.H->edge->v ];
        q.d = p.d + q.H->edge->d;
        Q.push(q);
      }
      for( int i = 0 ; i < 4 ; i ++ )
        if( p.H->chd[ i ] != nullNd ){
          q.H = p.H->chd[ i ];
          q.d = p.d - p.H->edge->d + p.H->chd[ i ]->
              edge->d;
          Q.push( q );
  } }   }
  void solve(){ // ans[i] stores the i-th shortest path
    dijkstra();
    build();
    first_K(); // ans.size() might less than k
} }solver;
```

5.14 Floryd Warshall

```
for( int k=0 ; k < n ; k++ )
  for( int i=0 ; i < n ; i++ )
    for( int j=0 ; j < n ; j++ )
        if( dis[i][j] > dis[i][k]+dis[k][j] && dis[i][k
            ] < INF && dis[k][j] < INF )
          dis[i][j]=dis[i][k]+dis[k][j];
  for( int i=0 ; i < n ; i++ )
    for( int j=0 ; j < n ; j++ )
      for( int k=0 ; k < n && dis[i][j] != negINF ; k++
           )
        if( dis[k][k] < 0 && dis[i][k] != INF && dis[k
            ][j] != INF )
          dis[i][j]=negINF;
```

5.15 SPFA

```
#define MXN 200005
struct SPFA{
  int n;
  LL inq[MXN], len[MXN];
  vector<LL> dis;
  vector<pair<int, LL>> edge[MXN];
  void init(int _n){
    n = _n;
    dis.clear(); dis.resize(n, 1e18);
    for(int i = 0; i < n; i++){
      edge[i].clear();
      inq[i] = len[i] = 0;
  } }
  void addEdge(int u, int v, LL w){
    edge[u].push_back({v, w});
  }
  vector<LL> solve(int st = 0){
    deque<int> dq; //return {-1} if has negative cycle
    dq.push_back(st); //otherwise return dis from st
    inq[st] = 1; dis[st] = 0;
    while(!dq.empty()){
      int u = dq.front();  dq.pop_front();
      inq[u] = 0;
      for(auto [to, d] : edge[u]){
        if(dis[to] > d+dis[u]){
          dis[to] = d+dis[u];
          len[to] = len[u]+1;
          if(len[to] > n) return {-1};
          if(inq[to]) continue;
          (!dq.empty()&&dis[dq.front()] > dis[to]?
              dq.push_front(to) : dq.push_back(to));
          inq[to] = 1;
    } } }
    return dis;
} }spfa;
```

5.16 Tree Hash

```
//限定root = 1
//從 dfs(1,1) 開始
int subtree_sz[MXN];
vector<int> edge[MXN];

int dfs(int u, int f) {
  vector<pair<int, int>> h;
  subtree_sz[u] = 1;
  for (int child : edge[u]) {
    if (child == f) continue;
    int tmp = dfs(child, u);
    h.push_back(make_pair(tmp, subtree_sz[child]));
    subtree_sz[u] += subtree_sz[child];
  }
  sort(h.begin(), h.end());
  int ret = subtree_sz[u];
  for (auto v : h) {
    ret = ((ret * p) % MOD + v.first) % MOD;
    ret = ret * v.second % MOD;
  }
  return ret;
}
```

5.17 HeavyLightDecomposition

```
#define REP(i, s, e) for(int i = (s); i <= (e); i++)
#define REPD(i, s, e) for(int i = (s); i >= (e); i--)
const int MAXN = 100010;
const int LOG  = 19;
struct HLD{
  int n;
  vector<int> g[MAXN];
  int sz[MAXN], dep[MAXN];
  int ts, tid[MAXN], tdi[MAXN], tl[MAXN], tr[MAXN];
  //  ts : timestamp , useless after yutruli
  //  tid[ u ] : pos. of node u in the seq.
  //  tdi[ i ] : node at pos i of the seq.
  //  tl , tr[ u ] : subtree interval in the seq. of
      node u
  int prt[MAXN][LOG], head[MAXN];
  // head[ u ] : head of the chain contains u
  void dfssz(int u, int p){
    dep[u] = dep[p] + 1;
    prt[u][0] = p; sz[u] = 1; head[u] = u;
    for(int& v:g[u]) if(v != p){
      dep[v] = dep[u] + 1;
      dfssz(v, u);
      sz[u] += sz[v];
    }
  }
  void dfshl(int u){
    ts++;
    tid[u] = tl[u] = tr[u] = ts;
    tdi[tid[u]] = u;
    sort(ALL(g[u]),
         [&](int a, int b){return sz[a] > sz[b];});
    bool flag = 1;
    for(int& v:g[u]) if(v != prt[u][0]){
      if(flag) head[v] = head[u], flag = 0;
      dfshl(v);
      tr[u] = tr[v];
    }
  }
  inline int lca(int a, int b){
    if(dep[a] > dep[b]) swap(a, b);
    int diff = dep[b] - dep[a];
    REPD(k, LOG-1, 0) if(diff & (1<<k)){
      b = prt[b][k];
    }
    if(a == b) return a;
    REPD(k, LOG-1, 0) if(prt[a][k] != prt[b][k]){
      a = prt[a][k]; b = prt[b][k];
    }
    return prt[a][0];
  }
  void init( int _n ){
    n = _n; REP( i , 1 , n ) g[ i ].clear();
  }
  void addEdge( int u , int v ){
    g[ u ].push_back( v );
    g[ v ].push_back( u );
  }
  void yutruli(){ //build function
    dfssz(1, 0);
    ts = 0;
    dfshl(1);
    REP(k, 1, LOG-1) REP(i, 1, n)
      prt[i][k] = prt[prt[i][k-1]][k-1];
  }
  vector< PII > getPath( int u , int v ){
    vector< PII > res;
    while( tid[ u ] < tid[ head[ v ] ] ){
      res.push_back( PII(tid[ head[ v ] ] , tid[ v ]) )
        ;
      v = prt[ head[ v ] ][ 0 ];
    }
    res.push_back( PII( tid[ u ] , tid[ v ] ) );
    reverse( ALL( res ) );
    return res;
    /* res : list of intervals from u to v
     * u must be ancestor of v
     * usage :
     * vector< PII >& path = tree.getPath( u , v )
     * for( PII tp : path ) {
     *   int l , r;tie( l , r ) = tp;
     *   upd( l , r );
     *   uu = tree.tdi[ l ] , vv = tree.tdi[ r ];
     *   uu ~> vv is a heavy path on tree
     * }
     */
  }
} tree;
```

5.18 差分約束

約束條件 $V_j - V_i \le W$ addEdge(V_i, V_j, W) and run bellman-ford or spfa

6 String

6.1 PalTree

```
// len[s]是對應的回文長度
// num[s]是有幾個回文後綴
// cnt[s]是這個回文子字串在整個字串中的出現次數
// fail[s]是他長度次長的回文後綴，aba的fail是a
const int MXN = 1000010;
struct PalT{
  int nxt[MXN][26],fail[MXN],len[MXN];
  int tot,lst,n,state[MXN],cnt[MXN],num[MXN];
  int diff[MXN],sfail[MXN],fac[MXN],dp[MXN];
  char s[MXN]={-1};
  int newNode(int l,int f){
    len[tot]=l,fail[tot]=f,cnt[tot]=num[tot]=0;
    memset(nxt[tot],0,sizeof(nxt[tot]));
    diff[tot]=(l>0?l-len[f]:0);
    sfail[tot]=(l>0&&diff[tot]==diff[f]?sfail[f]:f);
    return tot++;
  }
  int getfail(int x){
    while(s[n-len[x]-1]!=s[n]) x=fail[x];
    return x;
  }
  int getmin(int v){
    dp[v]=fac[n-len[sfail[v]]-diff[v]];
    if(diff[v]==diff[fail[v]])
        dp[v]=min(dp[v],dp[fail[v]]);
    return dp[v]+1;
  }
  int push(){
    int c=s[n]-'a',np=getfail(lst);
    if(!(lst=nxt[np][c])){
      lst=newNode(len[np]+2,nxt[getfail(fail[np])][c]);
      nxt[np][c]=lst; num[lst]=num[fail[lst]]+1;
    }
    fac[n]=n;
    for(int v=lst;len[v]>0;v=sfail[v])
        fac[n]=min(fac[n],getmin(v));
    return ++cnt[lst],lst;
  }
  void init(const char *_s){
    tot=lst=n=0;
    newNode(0,1),newNode(-1,1);
    for(;_s[n];) s[n+1]=_s[n],++n,state[n-1]=push();
    for(int i=tot-1;i>1;i--) cnt[fail[i]]+=cnt[i];
  }
}palt;
```

6.2 Longest Increasing Subsequence $O(lgn)$

```
vector<int> getLIS(vector<int> a){
  vector<int> lis;
  for(int i : a){
    if(lis.empty() || lis.back() < i)    lis.push_Back(
        i);
    else     *lower_bound(lis.begin(), lis.end(), i) =
         i;
  }
  return lis;
}
```

6.3 Longest Common Subsequence $O(lgn)$

```
int LCS(string& s1, string& s2) {
  vector<int> p[128];  // 假設字元範圍為 0 ~ 127
  for (int i = 0; i < s2.size(); ++i) p[s2[i]].
      push_back(i);
  vector<int> v;
  v.push_back(-1);

  for (int i = 0; i < s1.size(); ++i)
    for (int j = p[s1[i]].size() - 1; j >= 0; --j) {
      int n = p[s1[i]][j];

      if (n > v.back())
        v.push_back(n);
      else
        *lower_bound(v.begin(), v.end(), n) = n;
    }
  return v.size() - 1;
};
```

6.4 KMP

```
/* len-failure[k]:
在k結尾的情況下，這個子字串可以由開頭
長度為(len-failure[k])的部分重複出現來表達

failure[k]為次長相同前綴後綴
如果我們不只想求最多，而且以0-base做為考量
，那可能的長度由大到小會是
failuer[k]、failure[failuer[k]-1]
、failure[failure[failuer[k]-1]-1]..
直到有值為0為止 */
int failure[MXN];
vector<int> KMP(string& t, string& p){
    vector<int> ret;
    if (p.size() > t.size()) return;
    for (int i=1, j=failure[0]=-1; i<p.size(); ++i){
        while (j >= 0 && p[j+1] != p[i])
            j = failure[j];
        if (p[j+1] == p[i]) j++;
        failure[i] = j;
    }
    for (int i=0, j=-1; i<t.size(); ++i){
        while (j >= 0 && p[j+1] != t[i])
            j = failure[j];
        if (p[j+1] == t[i]) j++;
        if (j == p.size()-1){
            ret.push_bck( i - p.size() + 1 );
            j = failure[j];
}   }   }
```

6.5 SAIS

```
const int N = 300010;
struct SA{
#define REP(i,n) for ( int i=0; i<int(n); i++ )
#define REP1(i,a,b) for ( int i=(a); i<=int(b); i++ )
  bool _t[N*2];
  int _s[N*2], _sa[N*2], _c[N*2], x[N], _p[N], _q[N*2],
       hei[N], r[N];
  int operator [] (int i){ return _sa[i]; }
  void build(int *s, int n, int m){
    memcpy(_s, s, sizeof(int) * n);
    sais(_s, _sa, _p, _q, _t, _c, n, m);
    mkhei(n);
  }
  void mkhei(int n){
    REP(i,n) r[_sa[i]] = i;
    hei[0] = 0;
    REP(i,n) if(r[i]) {
      int ans = i>0 ? max(hei[r[i-1]] - 1, 0) : 0;
      while(_s[i+ans] == _s[_sa[r[i]-1]+ans]) ans++;
      hei[r[i]] = ans;
    }
  }
  void sais(int *s, int *sa, int *p, int *q, bool *t,
      int *c, int n, int z){
    bool uniq = t[n-1] = true, neq;
    int nn = 0, nmxz = -1, *nsa = sa + n, *ns = s + n,
        lst = -1;
#define MS0(x,n) memset((x),0,n*sizeof(*(x)))
#define MAGIC(XD) MS0(sa, n); \
    memcpy(x, c, sizeof(int) * z); \
    XD; \
    memcpy(x + 1, c, sizeof(int) * (z - 1)); \
    REP(i,n) if(sa[i] && !t[sa[i]-1]) sa[x[s[sa[i
        ]-1]]++] = sa[i]-1; \
    memcpy(x, c, sizeof(int) * z); \
    for(int i = n - 1; i >= 0; i--) if(sa[i] && t[sa[i
        ]-1]) sa[--x[s[sa[i]-1]]] = sa[i]-1;
    MS0(c, z);
    REP(i,n) uniq &= ++c[s[i]] < 2;
    REP(i,z-1) c[i+1] += c[i];
    if (uniq) { REP(i,n) sa[--c[s[i]]] = i; return; }
    for(int i = n - 2; i >= 0; i--) t[i] = (s[i]==s[i
        +1] ? t[i+1] : s[i]<s[i+1]);
    MAGIC(REP1(i,1,n-1) if(t[i] && !t[i-1]) sa[--x[s[i
        ]]]=p[q[i]=nn++]=i);
    REP(i, n) if (sa[i] && t[sa[i]] && !t[sa[i]-1]) {
      neq=lst<0||memcmp(s+sa[i],s+lst,(p[q[sa[i]]+1]-sa
          [i])*sizeof(int));
      ns[q[lst=sa[i]]]=nmxz+=neq;
    }
    sais(ns, nsa, p + nn, q + n, t + n, c + z, nn, nmxz
         + 1);
    MAGIC(for(int i = nn - 1; i >= 0; i--) sa[--x[s[p[
        nsa[i]]]]] = p[nsa[i]]);
  }
}sa;
int H[ N ], SA[ N ];
void suffix_array(int* ip, int len) {
  // should padding a zero in the back
  // ip is int array, len is array length
  // ip[0..n-1] != 0, and ip[len] = 0
  ip[len++] = 0;
  sa.build(ip, len, 128);
  for (int i=0; i<len; i++) {
    H[i] = sa.hei[i + 1];
    SA[i] = sa._sa[i + 1];
  }
  // resulting height, sa array \in [0,len)
}
```

6.6 Z Value

```
int z[MAXN];
void Z_value(const string& s) { //z[i] = lcp(s[1...],s[
    i...])
  int i, j, left, right, len = s.size();
  left=right=0; z[0]=len;
  for(i=1;i<len;i++) {
    j=max(min(z[i-left],right-i),0);
    for(;i+j<len&&s[i+j]==s[j];j++);
    z[i]=j;
    if(i+z[i]>right) {
      right=i+z[i];
      left=i;
}   }   }
```

6.7 ZValue Palindrome

```
void z_value_pal(char *s,int len,int *z){
  len=(len<<1)+1;
  for(int i=len-1;i>=0;i--)
    s[i]=i&1?s[i>>1]:'@';
  z[0]=1;
  for(int i=1,l=0,r=0;i<len;i++){
    z[i]=i<r?min(z[l+l-i],r-i):1;
    while(i-z[i]>=0&&i+z[i]<len&&s[i-z[i]]==s[i+z[i]])
        ++z[i];
    if(i+z[i]>r) l=i,r=i+z[i];
} }
```

6.8 Smallest Rotation

```
//rotate(begin(s),begin(s)+minRotation(s),end(s))
int minRotation(string s) {
  int a = 0, N = s.size(); s += s;
  rep(b,0,N) rep(k,0,N) {
    if(a+k == b || s[a+k] < s[b+k])
      {b += max(0, k-1); break;}
    if(s[a+k] > s[b+k]) {a = b; break;}
  } return a;
}
```

6.9 Cyclic LCS

```
#define L 0
#define LU 1
#define U 2
const int mov[3][2]={0,-1, -1,-1, -1,0};
int al,bl;
char a[MAXL*2],b[MAXL*2]; // 0-indexed
int dp[MAXL*2][MAXL];
char pred[MAXL*2][MAXL];
inline int lcs_length(int r) {
  int i=r+al,j=bl,l=0;
  while(i>r) {
    char dir=pred[i][j];
    if(dir==LU) l++;
    i+=mov[dir][0];
    j+=mov[dir][1];
  }
  return l;
}
inline void reroot(int r) { // r = new base row
  int i=r,j=1;
  while(j<=bl&&pred[i][j]!=LU) j++;
  if(j>bl) return;
  pred[i][j]=L;
  while(i<2*al&&j<=bl) {
    if(pred[i+1][j]==U) {
      i++;
      pred[i][j]=L;
    } else if(j<bl&&pred[i+1][j+1]==LU) {
      i++;
      j++;
      pred[i][j]=L;
    } else {
      j++;
} } }
int cyclic_lcs() {
  // a, b, al, bl should be properly filled
  // note: a WILL be altered in process
  //        -- concatenated after itself
  char tmp[MAXL];
  if(al>bl) {
    swap(al,bl);
    strcpy(tmp,a);
    strcpy(a,b);
    strcpy(b,tmp);
  }
  strcpy(tmp,a);
  strcat(a,tmp);
  // basic lcs
  for(int i=0;i<=2*al;i++) {
    dp[i][0]=0;
    pred[i][0]=U;
  }
  for(int j=0;j<=bl;j++) {
    dp[0][j]=0;
    pred[0][j]=L;
  }
  for(int i=1;i<=2*al;i++) {
    for(int j=1;j<=bl;j++) {
      if(a[i-1]==b[j-1]) dp[i][j]=dp[i-1][j-1]+1;
      else dp[i][j]=max(dp[i-1][j],dp[i][j-1]);
      if(dp[i][j-1]==dp[i][j]) pred[i][j]=L;
      else if(a[i-1]==b[j-1]) pred[i][j]=LU;
      else pred[i][j]=U;
  } }
  // do cyclic lcs
  int clcs=0;
  for(int i=0;i<al;i++) {
    clcs=max(clcs,lcs_length(i));
    reroot(i+1);
  }
  // recover a
  a[al]='\0';
  return clcs;
}
```

6.10 Hash

```
//hash
//字串s區間 [l,r] 的Hash值為
//H[r] - H[l-1] * p^(r-l+1)
const ll P;
const ll MOD;
ll Hash[MXN];    //Hash[i] 為字串 [0,i] 的 hash值
void build(const string& s){
    int val = 0;
    for(int i=0; i&lt;s.size(); i++){
        val = (val * P + s[i]) % MOD;
        Hash[i] = val;
    }
}

//double hash
const ll P1;
const ll P2;
const ll MOD;
pair<ll,ll> Hash[MXN];

void build(const string& s){
    pair<ll,ll> val = make_pair(0,0);
    for(int i=0; i<s.size(); i++){
        val.first = (val.first * P1 + s[i]) % MOD;
        val.second = (val.second * P2 + s[i]) % MOD;
        Hash[i] = val;
    }
}
```

7 Data Structure

7.1 Segment tree

```
#define cl(x) (x*2)
#define cr(x) (x*2+1)
struct segmentTree{
  int n;
  vector<int> seg, tag;
  segmentTree( int _n ): n(_n) {
    seg=vector<int>(n*4,0), tag=vector<int>(n*4,0);
  }
  void push( int i, int L, int R ) {
    if( tag[i] ) {
      seg[i]+=tag[i]*(R-L+1);
      if( L < R ) {
        tag[cl(i)]+=tag[i];
        tag[cr(i)]+=tag[i];
      }
      tag[i]=0;
    }
  }
  void pull( int i, int L, int R ) {
    if( L == R ) return;
    int mid=(L+R)>>1;
    push(cl(i),L,mid);
    push(cr(i),mid+1,R);
    seg[i]=seg[cl(i)]+seg[cr(i)];
  }
  void build( int i, int L, int R, vector<int>& arr ) {
    if( L == R ) {
      seg[i]=arr[L];
      return;
    }
    int mid=(L+R)>>1;
    build(cl(i),L,mid,arr);
    build(cr(i),mid+1,R,arr);
    pull(i,L,R);
  }
  int query( int i, int rL, int rR, int L, int R ) {
    push(i,L,R);
    if( rL <= L && R <= rR ) return seg[i];
    int mid=(L+R)>>1, ret=0;
    if( mid >= rL ) ret+=query(cl(i),rL,rR,L,mid);
    if( mid < rR ) ret+=query(cr(i),rL,rR,mid+1,R);
    return ret;
  }
  void update( int i, int rL, int rR, int L, int R, int
       val ) {
    push(i,L,R);
    if( rL <= L && R <= rR ) {
      tag[i]=val;
      return;
    }
    int mid=(L+R)>>1;
    if( mid >= rL ) update(cl(i),rL,rR,L,mid,val);
    if( mid < rR ) update(cr(i),rL,rR,mid+1,R,val);
    pull(i,L,R);
  }
};
```

7.2 Trie

```
struct trie{
  trie *nxt[26];
  int cnt;    //紀錄有多少個字串以此節點結尾
  int sz;     //有多少字串的前綴包括此節點
  trie():cnt(0),sz(0){
      memset(nxt,0,sizeof(nxt));
  }
};

trie *root = new trie(); //創建新的字典樹

void insert(string& s){
  trie *now = root;  // 每次從根結點出發
  for(auto i:s){
    now->sz++;
    if(now->nxt[i-'a'] == NULL){
      now->nxt[i-'a'] = new trie();
    }
    now = now->nxt[i-'a'];  //走到下一個字母
  }
  now->cnt++; now->sz++;
}

int query_prefix(string& s){  //查詢有多少前綴為 s
  trie *now = root;    // 每次從根結點出發
  for(auto i:s){
    if(now->nxt[i-'a'] == NULL){
      return 0;
    }
    now = now->nxt[i-'a'];
  }
  return now->sz;
}

int query_count(string& s){  //查詢字串 s 出現次數
  trie *now = root;    // 每次從根結點出發
  for(auto i:s){
    if(now->nxt[i-'a'] == NULL){
      return 0;
    }
    now = now->nxt[i-'a'];
  }
  return now->cnt;
}
```

7.3 Treap

```
struct Treap{
  int sz , val , pri , tag;
  Treap *l , *r;
  Treap( int _val ){
    val = _val; sz = 1;
    pri = rand(); l = r = NULL; tag = 0;
  }
};
void push( Treap * a ){
  if( a->tag ){
    Treap *swp = a->l; a->l = a->r; a->r = swp;
    int swp2;
    if( a->l ) a->l->tag ^= 1;
    if( a->r ) a->r->tag ^= 1;
    a->tag = 0;
} }
inline int Size( Treap * a ){ return a ? a->sz : 0; }
void pull( Treap * a ){
  a->sz = Size( a->l ) + Size( a->r ) + 1;
}
Treap* merge( Treap *a , Treap *b ){
  if( !a || !b ) return a ? a : b;
  if( a->pri > b->pri ){
    push( a );
    a->r = merge( a->r , b );
    pull( a );
    return a;
  }else{
    push( b );
    b->l = merge( a , b->l );
    pull( b );
    return b;
} }
void split_kth( Treap *t , int k, Treap*&a, Treap*&b ){
  if( !t ){ a = b = NULL; return; }
  push( t );
  if( Size( t->l ) + 1 <= k ){
    a = t;
    split_kth( t->r , k - Size( t->l ) - 1 , a->r , b );
    pull( a );
  }else{
    b = t;
    split_kth( t->l , k , a , b->l );
    pull( b );
} }
void split_key(Treap *t, int k, Treap*&a, Treap*&b){
  if(!t){ a = b = NULL; return; }
  push(t);
  if(k<=t->val){
    b = t;
    split_key(t->l,k,a,b->l);
    pull(b);
  }
  else{
    a = t;
    split_key(t->r,k,a->r,b);
    pull(a);
} }
```

7.4 BIT

```
#define lowbit(x) (x&-x)
struct BIT {
    int n;
    vector<int> bit;
    BIT( int t ) {
        n=t;
        bit=vector<int>(n+1,0);
    }
    ~BIT() {bit.clear();}
    void update( int pos, int val ) {
        while ( pos <= n ) {
            bit[pos]+=val;
            pos+=lowbit(pos);
        }
    }
    void range_update( int L, int R, int val ) {
        update(L,val);
        update(R+1,-val);
    }
    int query( int pos ) {
        int res=0;
        while( pos ) {
            res+=bit[pos];
            pos-=lowbit(pos);
        }
        return res;
    }
    int range_query( int L, int R ) {
        return query(R)-query(L-1);
    }
};
```

7.5 持久化 SMT

```
struct node{
  node *l, *r;
  int val;
};

vector<node *> ver;
int arr[MXN] = {0};

struct SegmentTree{
  int n;
  node *root;
  void build(int _n){
    n = _n;
    root = build(0, n-1);
  }
  node* build(int L, int R){
    node *x = new node();
    if(L == R){ x->val = arr[L]; return x;}
    int mid = (L+R)/2;
    x->l = build(L, mid);
    x->r  = build(mid + 1, R);
    x->val = x->l->val + x->r->val;
    return x;
  }
  int query(node *ro, int L, int R){return query(ro, 0, n-1, L, R);}
  int query(int L, int R){return query(root, 0, n-1, L, R);}
  int query(node *x, int L, int R, int recL, int recR){
```

```
  if(recL <= L && R <= recR) return x->val;
  int mid = (L+R)/2, res = 0;
  if(recL <= mid) res += query(x->l, L, mid, recL,
      recR);
  if(mid  < recR) res += query(x->r, mid+1, R, recL,
      recR);
  return res;
 }
 void update(int pos, int v){update(root, 0, n-1, pos,
    v);}
 void update(node *x, int L, int R, int pos, int v){
  if(L == R){ x->val = v; arr[L] = v; return;}
  int mid = (L+R)/2;
  if(pos <= mid) update(x->l, L, mid, pos, v);
  else           update(x->r, mid+1, R, pos, v);
  x->val = x->l->val + x->r->val;
 }
 node *update_ver(node *pre, int l, int r, int pos,
    int v){
  node *x = new node();    //當前位置建立新節點
  if(l == r){
   x->val = v;
   return x;
  }
  int mid = (l+r)>>1;
  if(pos <= mid){ //更新左邊
   x->l = update_ver(pre->l, l, mid, pos, v); //左邊
     節點連向新節點
   x->r = pre->r; //右邊連到原本的右邊
  }
  else{ //更新右邊
   x->l = pre->l; //左邊連到原本的左邊
   x->r = update_ver(pre->r, mid+1, r, pos, v);  //
     右邊節點連向新節點
  }
  x->val = x->l->val + x->r->val;
  return x;
}} seg;

void add_ver(int x,int v){    //修改位置 x 的值為 v
  ver.push_back(seg.update_ver(ver.back(), 0, seg.n
      -1, x, v));
}
```

7.6 Black Magic

```
#include <bits/extc++.h>
using namespace __gnu_pbds;
typedef tree<int,null_type,less<int>,rb_tree_tag,
  tree_order_statistics_node_update> set_t;
#include <ext/pb_ds/assoc_container.hpp>
typedef cc_hash_table<int,int> umap_t;
typedef priority_queue<int> heap;
#include<ext/rope>
using namespace __gnu_cxx;
int main(){
 // Insert some entries into s.
 set_t s; s.insert(12); s.insert(505);
 // The order of the keys should be: 12, 505.
 assert(*s.find_by_order(0) == 12);
 assert(*s.find_by_order(3) == 505);
 // The order of the keys should be: 12, 505.
 assert(s.order_of_key(12) == 0);
 assert(s.order_of_key(505) == 1);
 // Erase an entry.
 s.erase(12);
 // The order of the keys should be: 505.
 assert(*s.find_by_order(0) == 505);
 // The order of the keys should be: 505.
 assert(s.order_of_key(505) == 0);

 heap h1 , h2; h1.join( h2 );

 rope<char> r[ 2 ];
 r[ 1 ] = r[ 0 ]; // persistenet
 string t = "abc";
 r[ 1 ].insert( 0 , t.c_str() );
 r[ 1 ].erase( 1 , 1 );
 cout << r[ 1 ].substr( 0 , 2 );
}
```

8 Others

8.1 SOS dp

```
for(int i = 0; i<(1<<N); ++i)
 F[i] = A[i];
for(int i = 0;i < N; ++i) for(int mask = 0; mask < (1<<
  N); ++mask){
 if(mask & (1<<i))
  F[mask] += F[mask^(1<<i)];
}
```

8.2 Max subrectangle

```
const int N = 1e5+5;
int n, a[N],l[N], r[N];
long long ans;
int main() {
 while (cin>>n) {
  ans = 0;
  for (int i = 1; i <= n; i++) cin>>a[i], l[i] = r[i]
    = i;
  for (int i = 1; i <= n; i++)
   while (l[i] > 1 && a[i] <= a[l[i] - 1]) l[i] = l[
     l[i] - 1];
  for (int i = n; i >= 1; i--)
   while (r[i] < n && a[i] <= a[r[i] + 1]) r[i] = r[
     r[i] + 1];
  for (int i = 1; i <= n; i++)
   ans = max(ans, (long long)(r[i] - l[i] + 1) * a[i
     ]);
  cout<<ans<<"\n";
 }
}
```

8.3 De Brujin sequence

```
// return cyclic array of length k^n such that every
// array of length n using 0~k-1 appears as a subarray.
vector<int> DeBruijn(int k,int n){
 if(k==1) return {0};
 vector<int> aux(k*n),res;
 function<void(int,int)> f=[&](int t,int p)->void{
  if(t>n){ if(n%p==0)
    for(int i=1;i<=p;++i) res.push_back(aux[i]);
  }else{
   aux[t]=aux[t-p]; f(t+1,p);
   for(aux[t]=aux[t-p]+1;aux[t]<k;++aux[t]) f(t+1,t)
     ;
  }
 };
 f(1,1); return res;
}
```

8.4 Aho-Corasick

```
struct ACautomata{
  struct Node{
    int cnt,i;
    Node *go[26], *fail, *dic;
    Node (){
      cnt = 0; fail = 0; dic = 0; i = 0;
      memset(go,0,sizeof(go));
    }
  }pool[1048576],*root;
  int nMem,n_pattern;
  Node* new_Node(){
    pool[nMem] = Node();
    return &pool[nMem++];
  }
  void init() {
    nMem=0;root=new_Node();n_pattern=0;
    add("");
  }
  void add(const string &str) { insert(root,str,0); }
  void insert(Node *cur, const string &str, int pos){
    for(int i=pos;i<str.size();i++){
      if(!cur->go[str[i]-'a'])
        cur->go[str[i]-'a'] = new_Node();
      cur=cur->go[str[i]-'a'];
    }
    cur->cnt++; cur->i=n_pattern++;
  }
  void make_fail(){
    queue<Node*> que;
    que.push(root);
    while (!que.empty()){
      Node* fr=que.front(); que.pop();
      for (int i=0; i<26; i++){
        if (fr->go[i]){
          Node *ptr = fr->fail;
          while (ptr && !ptr->go[i]) ptr = ptr->fail;
          fr->go[i]->fail=ptr=(ptr?ptr->go[i]:root);
          fr->go[i]->dic=(ptr->cnt?ptr:ptr->dic);
          que.push(fr->go[i]);
  } } } }
  void query(string s){
      Node *cur=root;
      for(int i=0;i<(int)s.size();i++){
          while(cur&&!cur->go[s[i]-'a']) cur=cur->fail;
          cur=(cur?cur->go[s[i]-'a']:root);
          if(cur->i>=0) ans[cur->i]++;
          for(Node *tmp=cur->dic;tmp;tmp=tmp->dic)
              ans[tmp->i]++;
  } }// ans[i] : number of occurrence of pattern i
}AC;
```