Axel Jacobsen

axel-jacobsen.github.io | linkedin.com/in/Axel-Jacobsen axelnjacobsen@gmail.com

PROGRAMMING Advanced in Python, experienced in C, Javascript, learning Julia, Lisp, Rust **ELECTROMECHANICAL** Experience with robotics, PCB design, mechanical prototyping and Onshape/Solidworks

RFI FVANT FXPFRIFNCE

R&D ENGINEERING INTERN | CHAN-ZUCKERBERG BIOHUB | JUN 2020 - DEC 2020, JUL 2021 - PRESENT

Owner of the Biohub's reprogramming project of the Opentrons OT-2, an open-source pipetting robot for lab automation

- Wrote code base with a focus on simplicity, reliability, and speed current code base has doubled the speed of
 certain frequent operations, with a reduction of the codebase size by ~75% while expanding the capabilities of
 the robot
- Designed and implemented architecture so any software-controlled instrument can be used during protocols (e.g. cameras, GPUs, thermocyclers)
- Designed and implemented tests to measure the accuracy of the OT-2 using cross-correlation techniques, accurate to the μ m range over the robot's movement range of ~1 meter

ENGINEERING INTERN | WILDLIFE COMPUTERS | May 2019 - Aug 2019

Wildlife Computers is the leading provider of advanced wildlife telemetry solutions

- Designed an isolator PCB to isolate digital lines from sensitive measurement devices, allowing low-noise and accurate voltage measurements
- Wrote C++ to test PCBs that arrive from fabrication autonomously verifies PCB component placment to increase production throughput

DATA SCIENCE CO-OP | CONTROL MOBILE | JAN 2018 - APR 2018

Control Mobile aggregated and displayed transaction data for over 100 companies that used Stripe/Square/Paypal

- Wrote Python scripts to analyze and rank order over 300 individual SQL queries by their runtime to optimize the SQL database; reduced the runtime to fetch and display customer data by 65%
- Worked with the backend team to fix existing bugs, write new code, and refactor current code

PROJECTS

DEEP LEARNING

- Asynchronous Advantage Actor-Critic Model written in Pytorch, optimized for multicore CPUs via multiprocessing
- LSTM-based Deep Q-Network, trained on Denmark Technical University's High-Performance Computing Cluster
- Feed-forward neural net written with Numpy solves MNIST with 97.2% accuracy, vectorized for fast training

16-WEEK AUTONOMOUS ROBOT COMPETITION | Engineering Physics

- Deployed a real-time object detection algorithm on Raspberry Pi
- Created signal processing software to detect IR signals with sub-millisecond detection time
- Wrote C controls software and created circuits to control the mechanical subsystems

EDUCATION

UNIVERSITY OF BRITISH COLUMBIA | EXPECTED MAY 2022

B.ASc Engineering Physics

Coursework includes Lagrangian Mechanics, Computational Modelling, Digital Systems and Microcomputers, Signals and Systems, Applied Quantum Mechanics, Linear Algebra, Honours Multivariable and Vector Calculus, Complex Analysis, Optics, Statistical Mechanics

DENMARK TECHNICAL UNIVERSITY | WINTER 2019

Exchange Semester

Coursework includes Operating Systems, Deep Learning, Robotics, Computationally Hard Problems. Won DTU OS Course Competition for writing the fastest reverse hash server in C