

# Axel Jacobsen

axel-jacobsen.github.io | linkedin.com/in/Axel-Jacobsen  
axelnjacobsen@gmail.com

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**PROGRAMMING** Python 5 years, C/C++ 2 years, Java/MATLAB 1 year  
**ELECTRICAL / MECHANICAL** Experience with PCB design, mechanical prototyping and CAD software, fluid system design  
**OTHER** Have EU passport (Citizen of Denmark, Canada)

## EXPERIENCE

**R&D ENGINEERING INTERN** | CHAN-ZUCKERBERG BIOHUB | JUN 2020 - DEC 2020

*Reprogrammed the Opentrons OT-2, an open-source pipetting robot for lab automation*

- Rewrote OT-2 code base with a focus on speeding up epithelial cell growth protocols - doubled speed of certain frequent operations, reduced code base size by ~75% while expanding the capabilities of the robot
- Created computing architecture so arbitrary instruments (e.g. cell counters) can be used during protocols instead of just the Opentrons instruments

**ENGINEERING INTERN** | WILDLIFE COMPUTERS | MAY 2019 - AUG 2019

*Wildlife Computers is the leading provider of advanced wildlife telemetry solutions*

- Wrote C++ to test PCBs that arrive from fabrication - autonomously verifies PCB component placement to increase production throughput
- Designed an isolator PCB to isolate digital lines from sensitive measurement devices, allowing low-noise and accurate voltage measurements

**DATA SCIENCE CO-OP** | CONTROL MOBILE | JAN 2018 - APR 2018

*Control Mobile aggregated and displayed transaction data for over 100 companies that used Stripe/Square/Paypal*

- Wrote Python scripts to analyze and rank order over 300 individual SQL queries by their runtime to optimize the SQL database; reduced the runtime to fetch and display customer data by 65%
- Worked with the backend team to fix existing bugs, write new code, and refactor current code

## PROJECTS

### DEEP LEARNING

- Asynchronous Advantage Actor-Critic Model written in Pytorch, optimized for multicore CPUs via multiprocessing
- LSTM-based Deep Q-Network, trained on Denmark Technical University's High-Performance Computing Cluster
- Feed-forward neural net written with Numpy solves MNIST with 97.2% accuracy, vectorized for fast training

### 16-WEEK AUTONOMOUS ROBOT COMPETITION | ENGINEERING PHYSICS

- Deployed a real-time object detection algorithm on Raspberry Pi
- Created signal processing software to detect IR signals with sub-millisecond detection time
- Wrote C controls software and created circuits to control the mechanical subsystems

## EDUCATION

**UNIVERSITY OF BRITISH COLUMBIA** | EXPECTED MAY 2022

**B.ASc Engineering Physics, GPA 3.70**

*Coursework includes* Lagrangian Mechanics, Computational Modelling (currently with fluids), Digital Systems and Microcomputers, Signals and Systems, Applied Quantum Mechanics, Linear Algebra, Honours Multivariable and Vector Calculus, Complex Analysis, Optics, Statistical Mechanics

**DENMARK TECHNICAL UNIVERSITY** | WINTER 2019

**Exchange Semester**

*Coursework includes* Operating Systems, Deep Learning, Robotics, Computationally Hard Problems.  
Won the DTU OS Challenge for writing the fastest reverse hash server in C, using both multiprocessing and multithreading