

Shaurya Sinha

<https://ayruahs.github.io>
sinha35@purdue.edu | 408-636-8488

EDUCATION

PURDUE UNIVERSITY

B.S. IN COMPUTER ENGINEERING

Expected May 2020 | West Lafayette, IN

Cum. GPA: 3.74

Honors College

Dean's List (All Semesters)

Semester Honors (All Semesters)

EXPERIENCE

MINISTRY OF EXTERNAL AFFAIRS | SOFTWARE DEVELOPMENT

INTERN

May 2017 – Jun 2017 | New Delhi, India

- Developed a desktop application in Java that checks the names of visa applicants against a list of known/potential criminals and terrorists using fuzzy string matching and a custom Soundex algorithm.
- Prototype for a system to be used at visa offices and embassies in neighboring countries as one in a series of security checks.
- The system is able to detect changes in spelling or pronunciation and still raise flags, in case a criminal changes their name to enter the country.

IEEE COMPUTER SOCIETY | SPONSORSHIP DELEGATE

Jan 2017 – Present | West Lafayette, IN

- Responsible for securing funds and sponsorship for the activities and events of the Computer Society.
- Applied for monetary awards and reached out to representatives from industry as well as Purdue University to inquire about sponsorship opportunities.
- Raised \$500 in my first semester as sponsorship delegate.

LINKS

Github:// [ayruahs](#)

LinkedIn:// [shaurya-sinha](#)

SKILLS

PROGRAMMING

Java • Python • C • MATLAB

• Swift

WEB TECHNOLOGIES

HTML • CSS • Bootstrap

MISCELLANEOUS

Git • Linux • Bash • Xcode

PROJECTS

PURDUE PANCAKES | IOS DEVELOPER

- iOS app made using the Purdue Dining Courts API.
- Users are able to select favorite foods from the upcoming menu and a notification containing serving time and location is sent three hours before the food is served.

THERMAL DEPOLYMERIZATION ROBOT | SOFTWARE TEAM

Sep 2016 – Dec 2016

- Designed the prototype of a robot that classifies bins containing different kinds of debris produced in natural disasters and transports them to a Thermal Depolymerization Plant.
- Wrote the line-following and bin-lifting algorithms for the robot using a Python-to-NXT library.
- Robot was able to achieve 21/29 points in the final project demonstration.

AUTONOMOUS LUNAR VEHICLE | SOFTWARE TEAM

Feb 2017 – May 2017

- Designed the prototype of an autonomous vehicle that uses GPS to traverse the lunar surface to drop antennae at specific points in order to facilitate future space research.
- Wrote the shortest path-finding algorithm and the system to interpret GPS messages using RobotC.
- Vehicle was able to achieve 12/17 points in the final project demonstration.

AWARDS & SOCIETIES

2017 Charles W. Brown ECE Scholarship

2017 IEEE Purdue Chapter

2016 Purdue Climbing Club

2016 Purdue University Honors College