# Shaurya Sinha

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## **EDUCATION**

#### **PURDUE UNIVERSITY**

B.S. IN COMPUTER ENGINEERING

Expected May 2020 | West Lafayette

Cum. GPA: 3.74 Honors College Dean's List (All Semesters) Semester Honors (All Semesters)

# LINKS

Github://ayruahs LinkedIn://shaurya-sinha

# SKILLS

#### **PROGRAMMING**

Java • Python • C • MATLAB • Swift

#### **WEB TECHNOLOGIES**

HTML • CSS • Bootstrap

#### **MISCELLANEOUS**

Git • Linux • Bash • Xcode

## **EXPERIENCE**

# MINISTRY OF EXTERNAL AFFAIRS | SOFTWARE DEVELOPMENT INTERN

Expected May 2020 | West Lafayette, May 2017 - Jun 2017 | New Delhi, India

- Developed a desktop application in Java that checks the names of visa applicants against a list of known/potential criminals and terrorists using fuzzy string matching and a custom Soundex algorithm.
- Prototyped the system to be used at visa offices and embassies in neighboring countries as one in a series of security checks.
- The system is able to detect changes in spelling or pronunciation and still raise flags, in case a criminal changes their name to enter the country.

#### **IEEE COMPUTER SOCIETY** | Sponsorship Delegate

Jan 2017 - Present | West Lafayette, IN

- Responsible for securing funds and sponsorship for the activities and events of the Computer Society.
- Applied for monetary awards and reached out to representatives from industry as well as Purdue University to inquire about sponsorship opportunities.
- Raised \$500 in my first semester as sponsorship delegate.

## **PROJECTS**

#### **PURDUE PANCAKES** | IOS DEVELOPER

- iOS app made using the Purdue Dining Courts API.
- Users are able to select favorite foods from the upcoming menu and a notification containing serving time and location is sent three hours before the food is served.

# THERMAL DEPOLYMERIZATION ROBOT | SOFTWARE TEAM Sep 2016 - Dec 2016

- Designed the prototype of a robot that classifies bins containing different kinds of debris produced in natural disasters and transports them to a Thermal Depolymerization Plant.
- Wrote the line-following and bin-lifting algorithms for the robot using a Python-to-NXT library.
- Robot was able to achieve 21/29 points in the final project demonstration.

#### **AUTONOMOUS LUNAR VEHICLE** | SOFTWARE TEAM

Feb 2017 - May 2017

- Designed the prototype of an autonomous vehicle that uses GPS to traverse the lunar surface to drop antennae at specific points in order to facilitate future space research.
- Wrote the shortest path-finding algorithm and the system to interpret GPS messages using RobotC.
- Vehicle was able to achieve 12/17 points in the final project demonstration.

# **AWARDS & SOCIETIES**

- 2017 Charles W. Brown ECE Scholarship
- 2017 IEEE Purdue Chapter
- 2016 Purdue Climbing Club
- 2016 Purdue University Honors College