requirements enginering

matrix class

pure virtual

int dimensions (x and y)
int size

map info_map
holds string to detail keys for info map

throughout use
Shared_ptrs
So we can use weak_ptrs on the matrix and not worry about memory or multi-deleting of the array

Sparse

three lists as before

write an index method

banded

dense

- just a data pointer
- with basic index and set functions

Solve (b, method)
act as Solve method switchboard

Solve (b, method, non-zero_elements, number_non-zero_elements)
through some kind of pre calculation we know which outputs will be non-zero

can see how sost the operation is an a boolean matrix

quick

slow

use boolean dense matrix to find non-zero outputs

use some other method to find non-zero elements

virtual must be set per matrix class

Set (x, y, v) = 0
Set the value of an element (will be more complex for dense or banded matrixs)

index (x, y) = 0
used for default unoptemised methods

pivot_row (r_1 , r_2) = 0
will need to be different for each matrix type

Can be general then overwritten if needed

print matrix ()
used the above index as default

info()
give vairous details such as Sparcity

Solve methods
→ gaussian_Sentinal
→ LU decon
→ Some form of iterative (maybe Jacobi)

because of the index method these can be written for all types basically

then optimised by identifying