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```
clear;  
clc;  
close all;
```

## eigenvalues eigenvectors

```
syms alpha t  
  
% A  
A = [-1, -2, 0;  
     -2, -5, 0;  
     alpha, 2*alpha, -1];  
  
% right vectors  
[W, D] = eig(A);  
W(:,2) = W(:,2) / W(1,2);  
W(:,3) = W(:,3) / W(1,3);  
W = simplify(W);  
  
% left vectors  
[V, D_left] = eig(A');  
V(:,2) = V(:,2) / (2*2^(1/2));  
V(:,3) = V(:,3) / -(2*2^(1/2));  
V = simplify(V);
```

## Phi

```
third_row = W(3, :);  
Phi_last_row = third_row * expm(D * t) * V';
```

## Output

initial condition

```
x0 = [1; 0; 0];  
  
t_vals = linspace(0, 10, 1000);  
alpha_values = [0.001, 0.01, 0.1, 0.5, 1, 2, 5];  
colors = {'r', 'g', 'b', 'm', 'c', 'y', 'k'};  
  
figure;  
for i = 1:length(alpha_values)  
    alpha_val = alpha_values(i);  
  
    % y  
    y_t = Phi_last_row * x0;
```

```
y_numeric = subs(y_t, {alpha, t}, {alpha_val, t_vals});  
y_numeric = double(y_numeric);  
plot(t_vals, y_numeric, 'Color', colors{i}, 'DisplayName', ['\alpha = ', num2str(alpha_val)]);  
hold on;  
  
end  
  
xlabel('Time (s)');  
ylabel('Output y(t)');  
title('System Output for Different \alpha Values');  
legend('show');  
grid on;  
hold off;
```

