

Verilog: A Practice Approach

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official website

- <https://www.veripool.org/verilator/>
- <https://verilator.org>

installation

- verilator

```
sudo apt-get install verilator # On Debian or Ubuntu
```

- gtkwave

```
sudo apt-get install gtkwave # On Debian or Ubuntu
```

hello world

```
mkdir playground  
touch top.v main.cpp
```

■ top.v

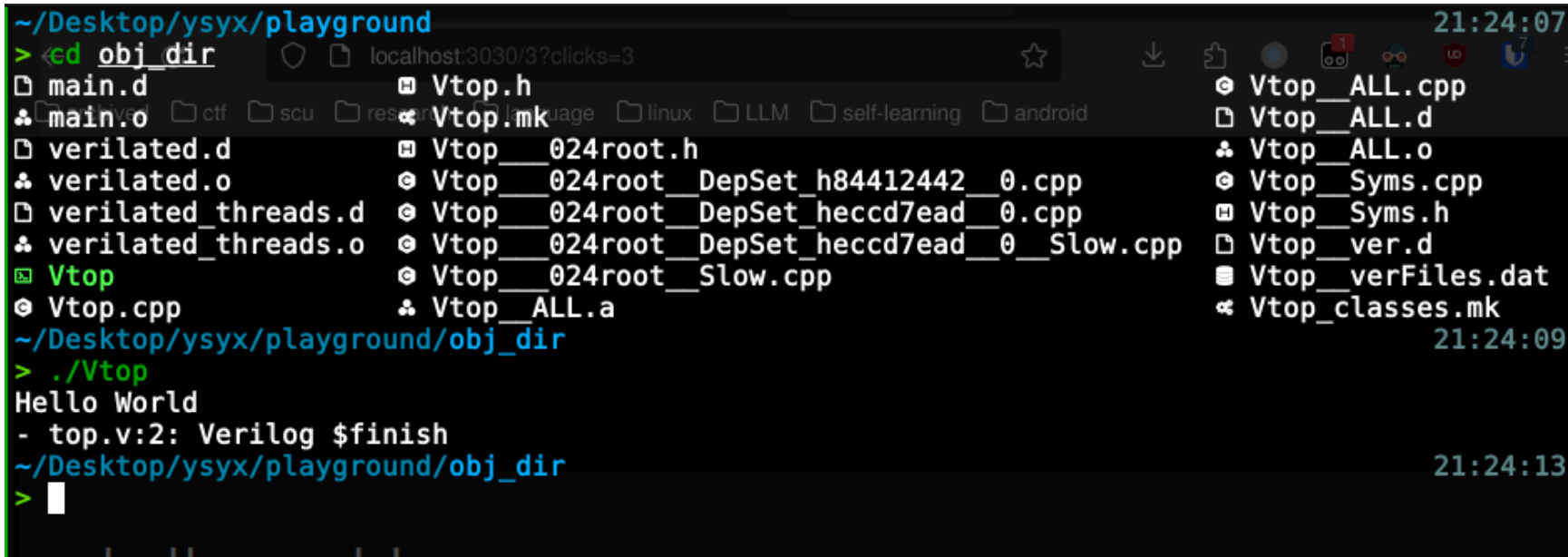
```
module top;  
  initial begin $display("Hello World"); $finish; end  
endmodule
```

■ main.cpp

```
#include "Vtop.h"  
#include "verilated.h"  
int main(int argc, char** argv) {  
  VerilatedContext* contextp = new VerilatedContext;  
  contextp->commandArgs(argc, argv);  
  Vtop* top = new Vour{contextp};  
  while (!contextp->gotFinish()) { top->eval(); }  
  delete top;  
  delete contextp;  
  return 0;  
}
```

first run

```
verilator --cc --exe --build -j 0 -Wall main.cpp top.v
```



```
~/Desktop/ysyx/playground 21:24:07
> cd obj_dir
main.d      Vtop.h
main.o      Vtop.mk
verilated.d Vtop__024root.h
verilated.o Vtop__024root__DepSet_h84412442__0.cpp
verilated_threads.d Vtop__024root__DepSet_heccd7ead__0.cpp
verilated_threads.o Vtop__024root__DepSet_heccd7ead__0__Slow.cpp
Vtop        Vtop__024root__Slow.cpp
Vtop.cpp    Vtop__ALL.a
~/Desktop/ysyx/playground/obj_dir 21:24:09
> ./Vtop
Hello World
- top.v:2: Verilog $finish
~/Desktop/ysyx/playground/obj_dir 21:24:13
> 
```

and gate

- top.v

```
module top(  
    input a,  
    input b,  
    output c  
);  
    assign c = a & b;  
endmodule
```

- main.cpp

```
#include "Vtop.h"  
#include "verilated.h"  
#include "verilated_vcd_c.h"  
#define TIME_LIMIT 100  
int main(int argc, char** argv) {  
    VerilatedContext* contextp = new VerilatedContext;  
    contextp->commandArgs(argc, argv);  
    Vtop* top = new Vtop{contextp};  
    VerilatedVcdC* tfp = new VerilatedVcdC; // class for tackle vcd  
    Verilated::traceEverOn(true);  
    top->trace(tfp, TIME_LIMIT - 1);          // trace the signal  
    tfp->open("trace.vcd");
```

```

while (contextp->time() < TIME_LIMIT && !Verilated::gotFinish()) {
    /* your variable here */
    top->a = rand() % 2; // generate input
    top->b = rand() % 2;
    top->eval();          // run the circuit
    tfp->dump(contextp->time()); // save the result
    contextp->timeInc(1); // increase a clock cycle
}

tfp->close();
delete top;
delete contextp;
return 0;
}

```

■ Makefile

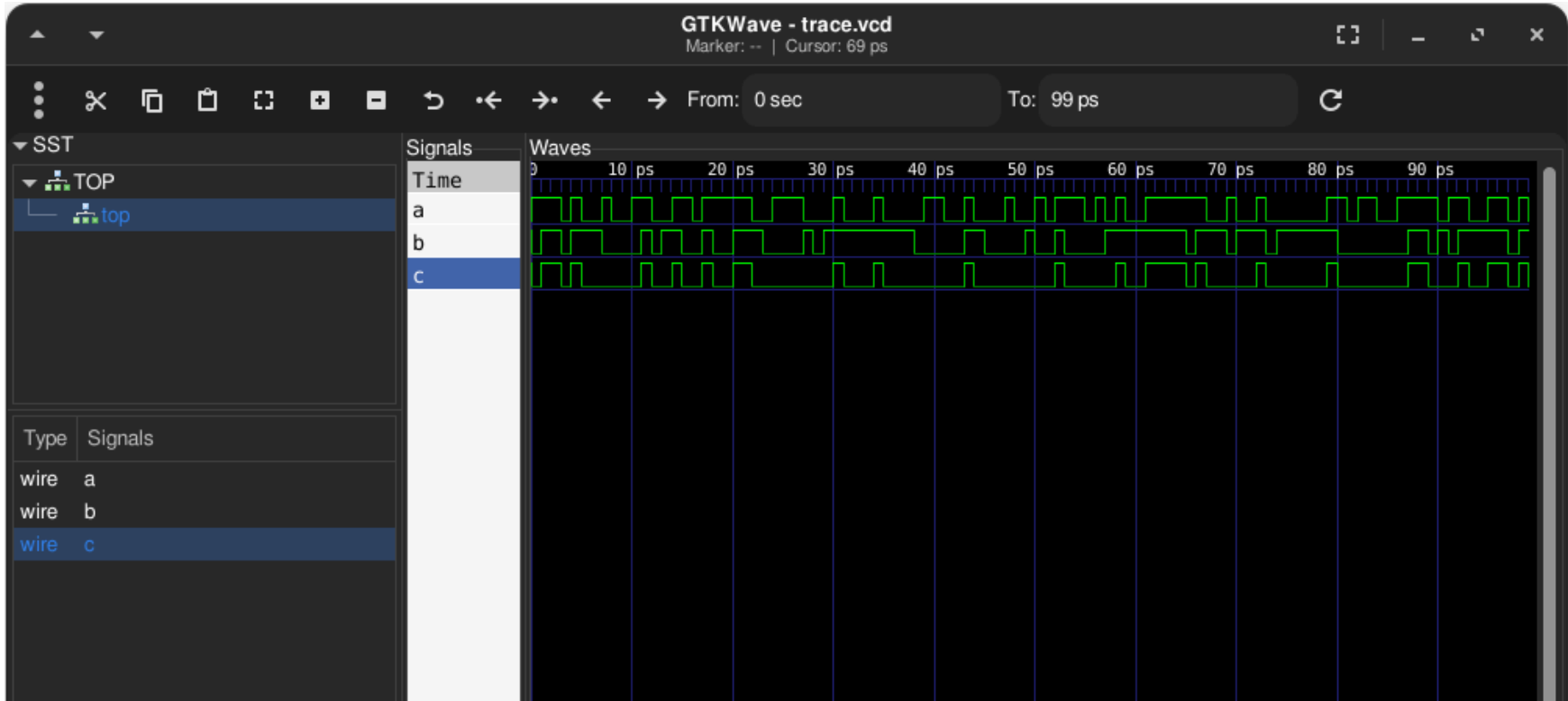
```

clean:
    rm -rf obj_dir
build:
    verilator --cc --exe --trace --build -j 0 -Wall main.cpp top.v
run: build
    ./obj_dir/Vtop

```

second run (with signals)

```
make run  
gtkwave ./trace.vcd
```



full adder

- top.v

```
module top(  
    input a, b, carry_in  
    output sum, carry_out  
);  
    assign sum = a ^ b ^ carry_in;  
    assign carry_out = (a & b) | (a & carry_in) | (b & carry_in);  
endmodule
```

OR

```
module top(  
    input a, b, carry_in  
    output sum, carry_out  
);  
    assign {carry_out, sum} = a + b + carry_in; // {} and ',' mean concat  
endmodule
```

The former is more like structural modeling, while dataflow modeling for the latter.

multi-bit addr

```
module full_addr(  
    input a, b, carry_in,  
    output sum, carry_out  
);  
    assign sum = a ^ b ^ carry_in;  
    assign carry_out = (a & b) | (a & carry_in) | (b & carry_in);  
endmodule  
  
module top(  
    input [7:0] a, b,  
    input carry_in,  
    output [7:0] sum,  
    output carry_out  
);  
    wire [6:0] carry_tmp;  
    full_addr fa0(a[0], b[0], carry_in, sum[0], carry_tmp[0]);  
    full_addr fa1(a[1], b[1], carry_tmp[0], sum[1], carry_tmp[1]);  
    full_addr fa2(a[2], b[2], carry_tmp[1], sum[2], carry_tmp[2]);  
    full_addr fa3(a[3], b[3], carry_tmp[2], sum[3], carry_tmp[3]);  
    full_addr fa4(a[4], b[4], carry_tmp[3], sum[4], carry_tmp[4]);  
    full_addr fa5(a[5], b[5], carry_tmp[4], sum[5], carry_tmp[5]);  
    full_addr fa6(a[6], b[6], carry_tmp[5], sum[6], carry_tmp[6]);  
    full_addr fa7(a[7], b[7], carry_tmp[6], sum[7], carry_out);  
endmodule
```

- dataflow modeling

```
module top(  
    input [7:0] a, b,  
    input carry_in,  
    output [7:0] sum,  
    output carry_out  
);  
    assign {carry_out, sum} = a + b + {7'b0, carry_in};  
endmodule
```

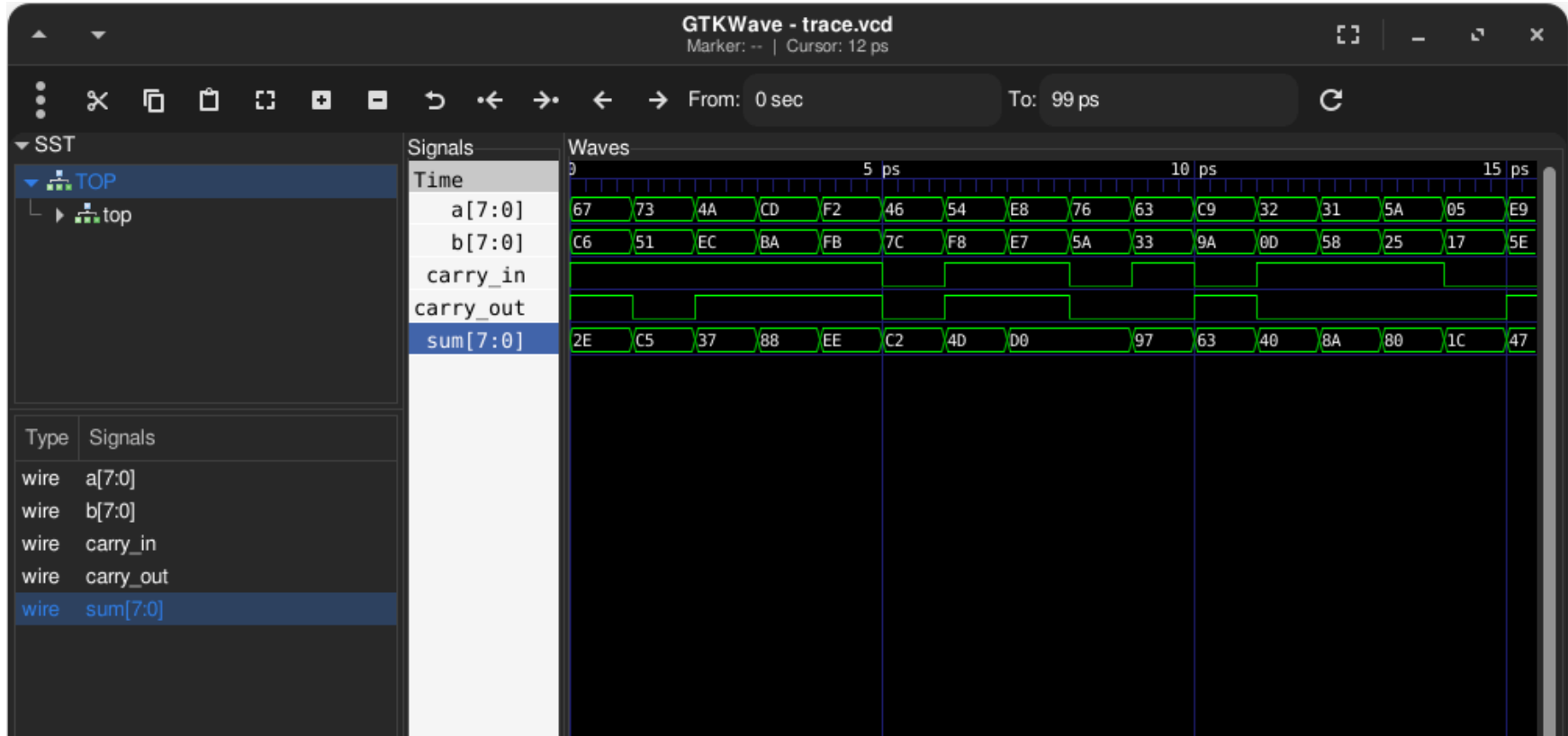
to simplify the procedure, I'll use dataflow modeling more to save the space

- main.cpp

```
while (contextp->time() < TIME_LIMIT && !Verilated::gotFinish()) {  
    /* your variable here */  
    top->a = rand() % 256; // can directly transfer an integer to signals  
    top->b = rand() % 256;  
    top->carry_in = rand() % 2;  
    top->eval();  
    tfp->dump(contextp->time());  
    contextp->timeInc(1);  
}
```

3rd run

- 0x67 + 0xc6 + 1 = 0x12e



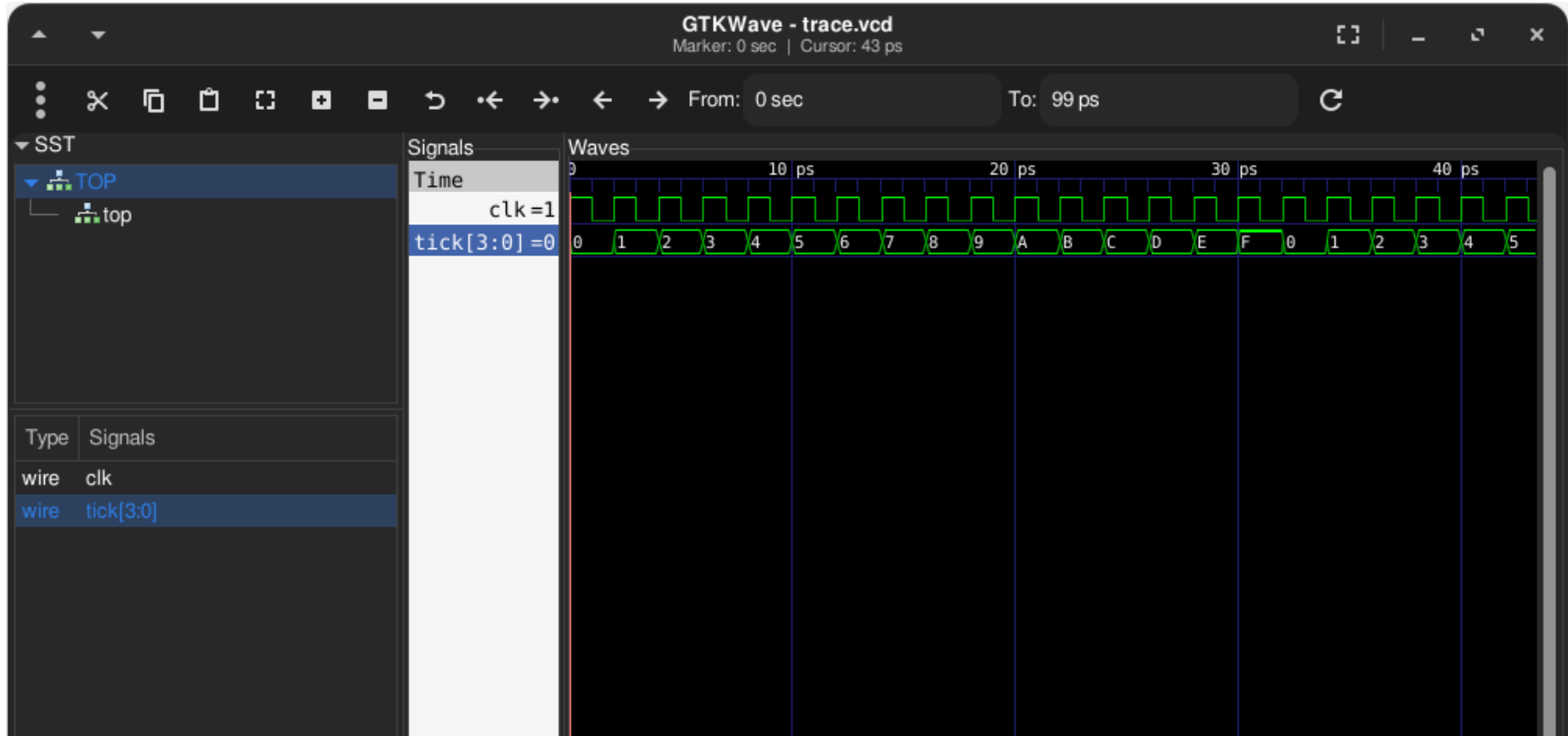
counter

```
module top(  
    input clk,  
    output [3:0] tick  
);  
    reg [3:0] saved_tick; // reg can keep its state during different clocks  
    always @(posedge clk) begin  
        // notice the symbol "<=", it is like a delayed assignment by one clock cycle  
        saved_tick <= saved_tick + 1;  
    end  
    assign tick = saved_tick;  
endmodule
```

```
while (contextp->time() < TIME_LIMIT && !Verilated::gotFinish()) {  
    top->clk = 1; top->eval(); // because it is initially 1, so no posedge  
    tfp->dump(contextp->time());  
    contextp->timeInc(1);  
  
    top->clk = 0; top->eval();  
    tfp->dump(contextp->time());  
    contextp->timeInc(1);  
    // two clock cycles later, the counter will increase 1  
}
```

4th run

- as you can see, after 32 clock cycles, it returned to initial state



OK, we used four pieces of code to reviewed "digital circuit design" course.

So, lets do something more interesting!!!

instruction cycle

- Let's implement a finite-state machine with one 2-bit reg, with totally 4 instructions!

```
int pseudo_mem[16] = {  
    // 0b00: mem = 0  
    // 0b01: mem = 1  
    // 0b10: mem = mem - 1  
    // 0b11: mem = mem + 1  
    1, 3, 0, 2  
};
```

```
while (contextp->time() < TIME_LIMIT && !Verilated::gotFinish()) {  
    /* your variable here */  
    top->clk = 0;  
    top->inst = pseudo_mem[contextp->time() / 2] % 4; // FETCH  
    top->eval();  
    tfp->dump(contextp->time());  
    contextp->timeInc(1);  
  
    top->clk = 1;  
    top->eval();  
    tfp->dump(contextp->time());  
    contextp->timeInc(1);  
}
```

- Here is the implement of reading/writing a register

```
module mem(  
    input clk,  
    input [1:0] data_in,  
    output[1:0] data_out  
);  
    reg [1:0] mem;    // acutual register like rax,rbx,... etc. in AMD64  
    assign data_out = mem;  
    always @(posedge clk) begin  
        mem ≤ data_in;  
    end  
endmodule
```

- To simplify, we suppose every instruction we need to write something into the register, so we omit the `write_enable` signal.
- other modules can always read `mem` from `data_out` , but can only write into register when a positive edge of clock occurs.

- Then let's look at the ALU (arithmetic logic unit) part

```
module alu(  
    input op,  
    input [1:0] data_in,  
    output[1:0] data_out  
);  
    assign data_out = op ? data_in + 1 : data_in - 1;  
endmodule
```

- Mostly the ALU part is designed by combinational logic circuit.
- If you still remember the opcode I previously provided, you can find that `0b10` and `0b11` correspond with the content in ALU.

```
// 0b00: mem = 0  
// 0b01: mem = 1  
// 0b10: mem = mem - 1  
// 0b11: mem = mem + 1
```

- Before going to the next page, can you try to figure out what the top module will be like?

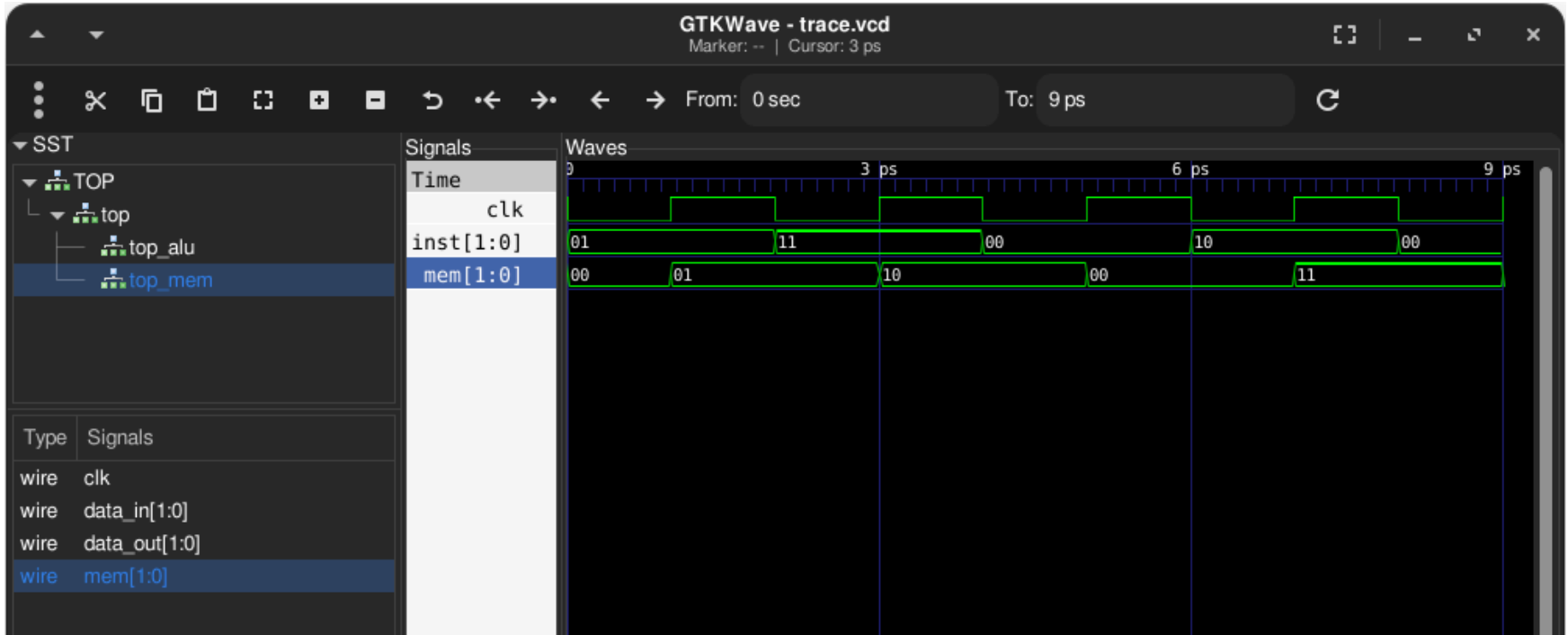
- OK, let me show the possible answer:

```
module top(  
    input clk,  
    input[1:0] inst  
);  
    wire [1:0] alu_out, pre_reg, post_reg;  
  
    // READ && WRITE BACK  
    mem top_mem(clk, post_reg, pre_reg);  
    // EXECUTE  
    alu top_alu(inst[0], pre_reg, alu_out);  
    // DECODE  
    assign post_reg = inst[1] ? alu_out : {1'b0, inst[0]};  
endmodule
```

- first, the `top` module FETCH the instruction from `main.cpp` .
- second, read the reg value from `top_mem` .
- third, DECODE `inst[1]` to decide whether the opcode needs calculation.
- fourth, EXECUTE (i.e. posedge) to write the final value back into reg.

5th run

```
mem = 1 // 1  
mem += 1 // 2  
mem = 0 // 0  
mem -= 1 // 3
```



final challenge: int64 to double

- i.e. `cvtsi2sd` in x86 asm
- IEEE 754 standard: 1-bit sign, 11-bit exponent, 52-bit mantissa
- e.g.: $(100111001)_2$'s exponent is 8,
- first, it is a positive integer, so the sign-bit is `0`,
- we add 8 into `1023` to make the exponent bits,
- cut off the MSB and get the mantissa.

So, the final result is:

```
0 10000000111 001110010000 ... 0
```

but... we still have a problem,

rounding

supoose we have $(11110000111100001111000011110000111100001111000010101010)_2$

after counting for 53 bits, we find:

11110000111100001111000011110000111100001111000010101 are accurate but the last 010 bits are rounded.

according to the round rule, $(0.010)_2$ is smaller then $(0.1)_2$, so we round down this.

but what will happen if the omitted bits just euqal to $(0.1)_2$?

Please guess a little bit.

The answer is Banker's Rounding: Round to nearest, ties to even.

Do you remember the first lecture in 大学物理实验 course ? That's it.

Banker's Rounding

- Suppose we have $(11110000111100001111000011110000111100001111000010100100)_2$, the accurate bits are $11110000111100001111000011110000111100001111000010100$ and omitted bits are 100 , the latter is just equal to $(0.1)_2$.
- if we round it up, the LSB will be 1 , otherwise the LSB will be 0 , so we should round it down.
- Another example, we have $(11110000111100001111000011110000111100001111000010101100)_2$, the accurate bits are $11110000111100001111000011110000111100001111000010101$ and omitted bits are still 100 .
- if we round it up, the LSB will be 0 , otherwise the LSB will be 1 , so we should round it up.
- That's it. Let's take a look at its implementation.

implementation

- calc_significant_bit

```
module calc_significant_bit (  
    input [63:0] a,  
    output [5:0] b  
);  
    always @* begin  
        begin  
            for (int i = 63; i ≥ 0; i--) begin  
                if (a[i]) begin  
                    b = i[5:0];  
                    break;  
                end  
            end  
        end  
    end  
end  
endmodule
```

- This is a typical example of **behavioral modeling**, it is easy for us to understand the procedure. But it is hard for us to debug, and for EDA tools to synthesize. What's more, the performance will drop, especially when you want to write every complex module in a programmer's way, not thinking of we're actually building the hardware.

- calc_mantissa

```
module mantissa (  
    input [63:0] a,  
    input [5:0] exp,  
    output [51:0] b  
);  
    always @* begin  
        if (exp <= 52) begin  
            b[51:51-exp+1] = a[exp-1:0];  
        end else begin  
            b[51:0] = a[exp-1:exp-52];  
            // Banker's rounding  
            if (a[exp-53] == 1 && (exp == 53 || a[exp-54:0] == 0)) begin  
                b = b + {51'b0, b[0]};  
            end else begin  
                b = b + {51'b0, a[exp-53]};  
            end  
        end  
    end  
end  
endmodule
```

- Of course, verilog itself doesn't support slicing with dynamic variables, can you come up with the solution?

- top

```
module top (  
    input [63:0] a,  
    output [63:0] b  
);  
    wire sign;  
    wire [5:0] exp;  
    wire [10:0] fixed_exp;  
    wire [51:0] mant;  
    wire [63:0] result;  
    calc_significant_bit calc_significant_bit_0 (a, exp);  
    mantissa mantissa_0 (a, exp, mant);  
    assign sign = a[63];  
    assign fixed_exp = {5'b0, exp} + 1023;  
    assign result = {sign, fixed_exp, mant};  
    assign b = result;  
endmodule
```

- how to transfer `int64` to double numbers from memory directly without conversion?
- Hint: `union`
- One last question, this pseudocode only handles positive integers, what about negatives?