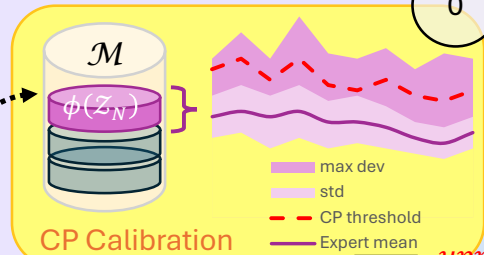
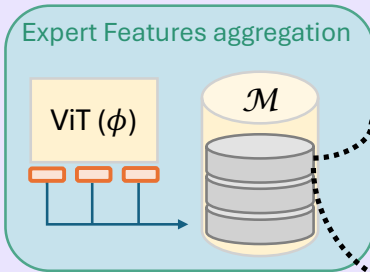


1 step – offline

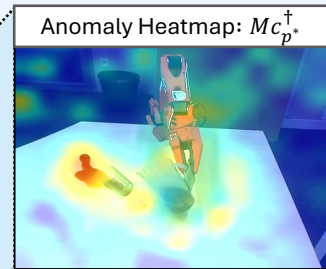
Teleoperation of the robot by the expert to realize the task



Expert



$upper_{p,t}$

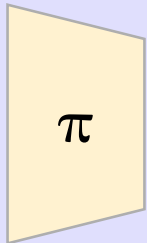


\mathcal{M}

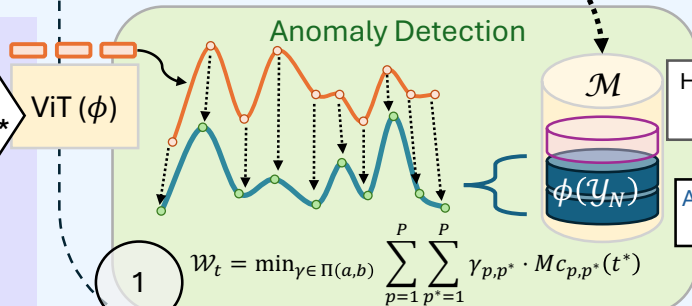
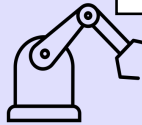
FIDeL

2 step – online

Imitation learning policy inference

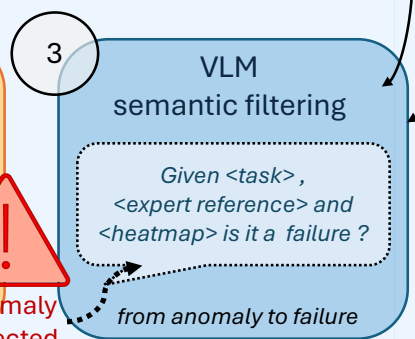
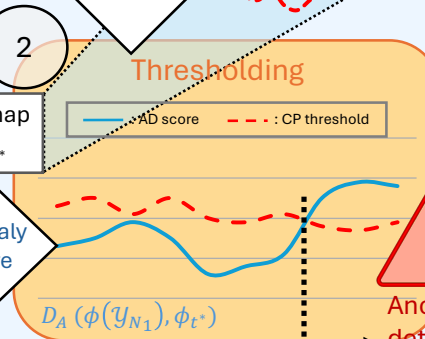


π



Heatmap Mc_p^+

Anomaly score



Failure score