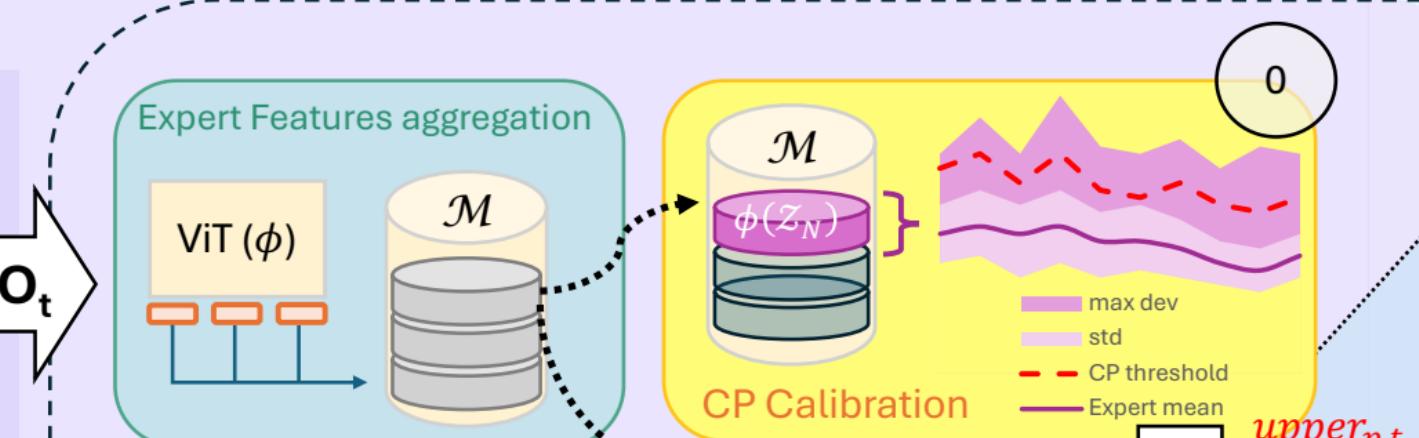
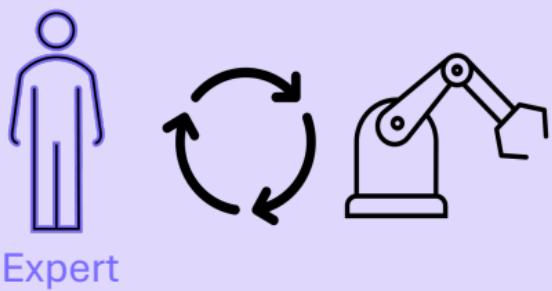


## 1 step - offline

Teleoperation of the robot by the expert to realize the task



FIDeL

## 2 step - online

Imitation learning policy inference

