1) A_x , B_x , F_x he rebresonce unewithhe, m.k ux keepghamm cogether koncumenture gravenus. G_x he she unewisch, n.k uneverse measure keepghamm uneem concress 4. C_x a E_x order uneverse.

Thelepa

$$C_{XX} = (\alpha_{X_1} - 3\alpha_{X_2} - \alpha_{X_3}; \alpha_{X_3}; \alpha_{X_3}; \alpha_{X_4} + 2\alpha_{X_2} + 3\alpha_{X_3})^{\top} =$$

$$= \alpha (x_1 - 3x_2 - x_3; x_3; x_4 + 2x_5 + 3x_3)^{\top} = \alpha C_X \qquad (+)$$

 $C_{x+y} = (x_1 + y_1 - 3(x_2 + y_2) - (x_3 + y_3); x_3 + y_3; x_1 + y_2 + 2(x_2 + y_2) + 3(x_3 + y_3))^{T} = (x_1 - 3x_2 - x_3; x_3; x_1 + 2x_2 + 3x_3)^{T} + (y_1 - 3y_2 - y_3; y_3; y_4 + 2y_2 + 3y_3)^{T} = C_x + C_y$

 $E_{\alpha x} = (2\alpha x_1; 3\alpha x_1 + 2\alpha x_2 + 3\alpha x_3; 4\alpha x_1 + 52\alpha x_2 + 2\alpha x_3)^{T} =$ $= \alpha (2x_1; 3x_1 + 2x_2 + 3x_3; 4x_1 + 52x_2 + 2x_3)^{T} = \alpha E_{X} \oplus$

 $\begin{bmatrix} x_{1} + y_{2} &= (2(x_{1} + y_{1}); 3(x_{1} + y_{1}) + 2(x_{2} + y_{2}) + 3(x_{3} + y_{3}); 4(x_{1} + y_{1}) + 52(x_{2} + y_{2}) + 2(x_{3} + y_{3}) \end{bmatrix}^{T} = (2x_{1}; 3x_{1} + 2x_{1} + 3x_{3}; 4x_{1} + 52x_{2} + 2x_{3})^{T} + (2y_{1}; 3y_{1} + 2y_{2} + 3y_{3}; 4y_{1} + 52y_{2} + 2y_{3})^{T} = E_{x} + E_{y}$ $+ 2y_{2} + 3y_{3}; 4y_{1} + 52y_{2} + 2y_{3})^{T} = E_{x} + E_{y}$

2)
$$A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$
 $\ker A = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ $\dim A = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ $\dim A = 3$

$$\begin{array}{l} 3) \ A = \begin{pmatrix} 1 & 0 & -2 \\ 0 & 4 & 0 \\ 0 & 1 & -4 \end{pmatrix} \qquad B = \begin{pmatrix} 0 & 0 & 3 \\ 4 & 0 & 0 \\ 0 & -2 & 0 \end{pmatrix} \\ C = B^2 + 3A^2 = \begin{pmatrix} 0 & 0 & 3 \\ 4 & 0 & 0 \\ 0 & 2 & 0 \end{pmatrix} + 3 \begin{pmatrix} 4 & 0 & -1 \\ 0 & 4 & 0 \\ 0 & 1 & -4 \end{pmatrix} = \begin{pmatrix} 3 & -72 & a \\ a & 5 & 5 \\ -2 & a & 3 \end{pmatrix} \\ C_X = \begin{pmatrix} 3 \times x_1 - 72 \times x_1 \\ 3 \times x_2 + 3 \times x_1 \\ -2x_1 + 3 \times x_1 \end{pmatrix} \\ \emptyset = BA + A^2 = \begin{pmatrix} 0 & 0 & 3 \\ 4 & 0 & 0 \\ 0 & 2 & 0 \end{pmatrix} + \begin{pmatrix} 4 & 0 & -2 \\ 0 & 4 & -4 \end{pmatrix} + \begin{pmatrix} 4 & 0 & -2 \\ 0 & 4 & -4 \end{pmatrix} = \begin{pmatrix} 4 & 4 & -3 \\ 4 & 4 & -2 \\ 0 & -2 & 4 \end{pmatrix} \\ \emptyset = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_1 + x_2 - 2 \times x_3 \\ -2x_1 + 3x_2 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_1 + x_2 - 2 \times x_3 \\ -2x_1 + 3x_2 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_1 + x_2 - 2 \times x_3 \\ -2x_1 + 3x_2 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_1 + x_2 - 2 \times x_3 \\ -2x_1 + 3x_2 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_1 + x_2 - 2 \times x_3 \\ -2x_1 + 3x_2 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_1 + x_2 - 2 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_1 + x_2 - 2 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 2 & 3 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x_2 - 4 \end{pmatrix} \\ \psi = \begin{pmatrix} x_1 + x_2 - 3 \times x_3 \\ x$$