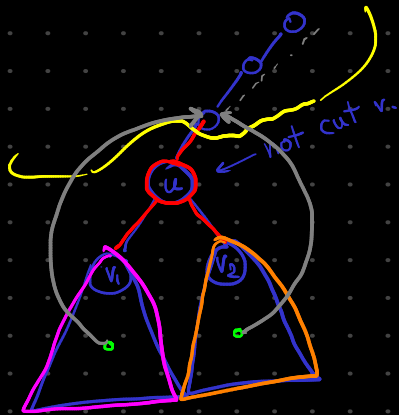
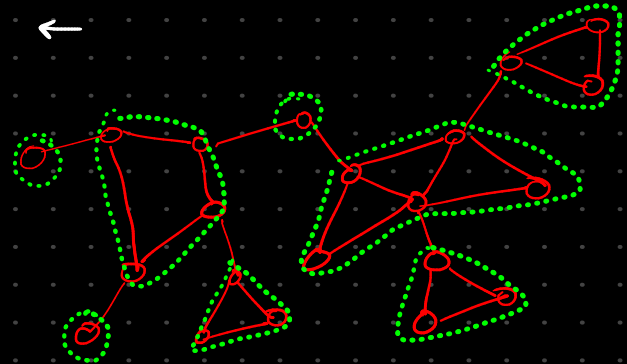


Introduction To Graph Theory

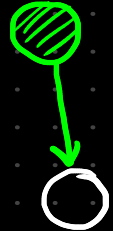
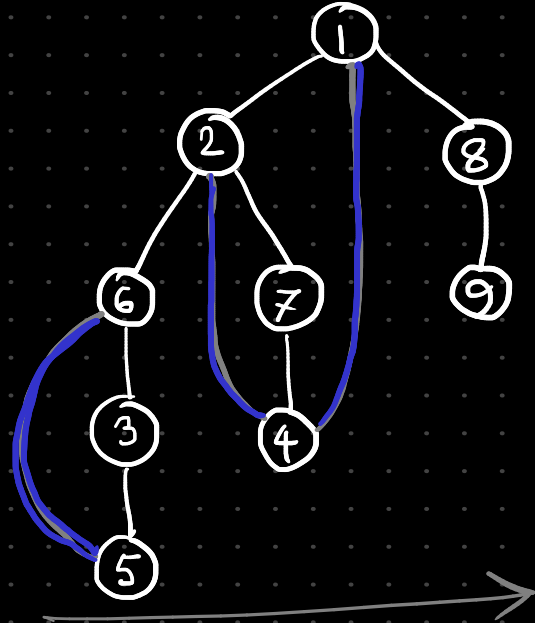
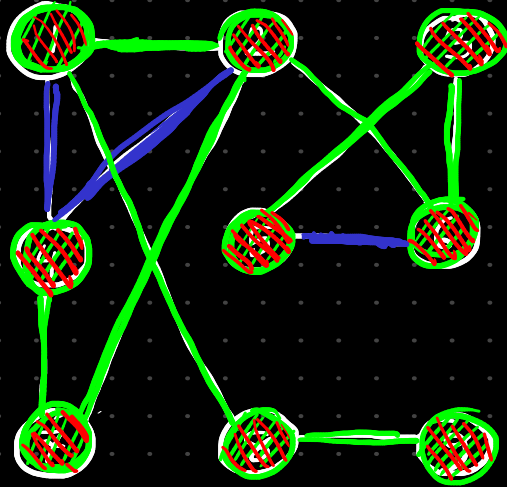


- - DFS Tree applications
- - Bridge, Articulation Points ←
- ✓ - Topological Sorting ←



The DFS Tree

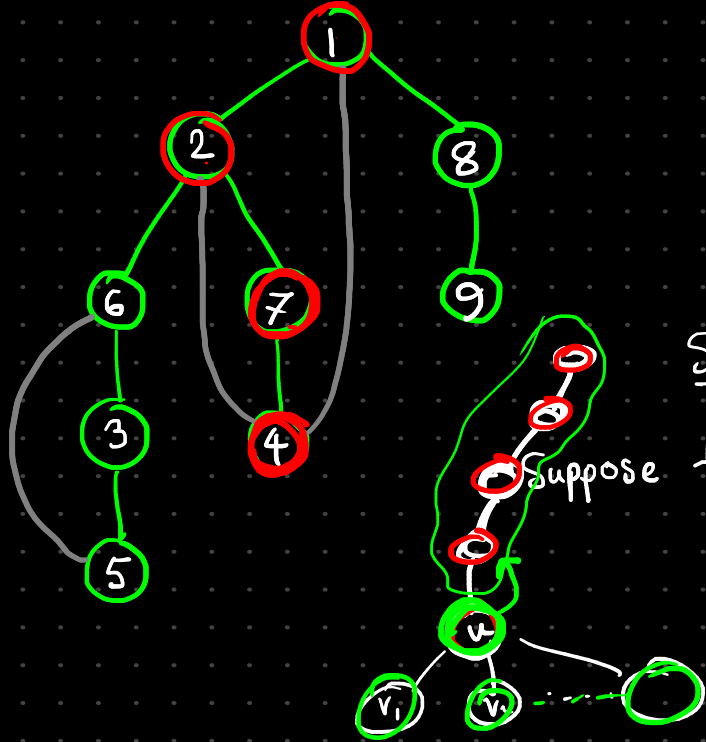
Running dfs in an undirected graph will always generate a tree.
(assuming only 1 component)



The DFS Tree

Span edge: Edges of the DFS tree

Back edge: Not part of the tree (ignored edges during dfs)



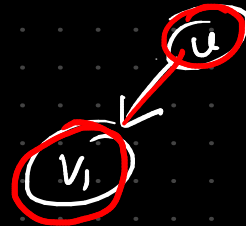
Observation 1:

When the dfs reaches u in the graph, only u and it's ancestors are active.

Why??? We can prove by induction

Start : For the root, statement above is TRUE

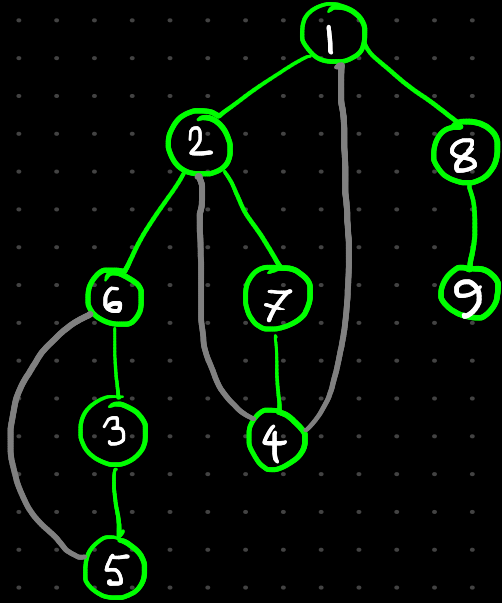
Suppose for node u , the claim is good.



The DFS Tree

Span edge: Edges of the DFS tree

⇒ Back edge: Not part of the tree (ignored edges during dfs)



Observation 2:

Back edge from u only goes to one of its ancestors in the DFS tree

Why???

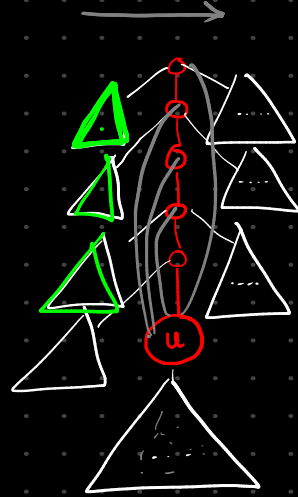
$u - v$

$u \leftrightarrow v$

Suppose u is visited first.

$u \rightarrow v$ v visited

⇒ v has its DFS running



⇒ This also means that back edges will go to an active node in dfs stack

Fixing cycle printing from last day

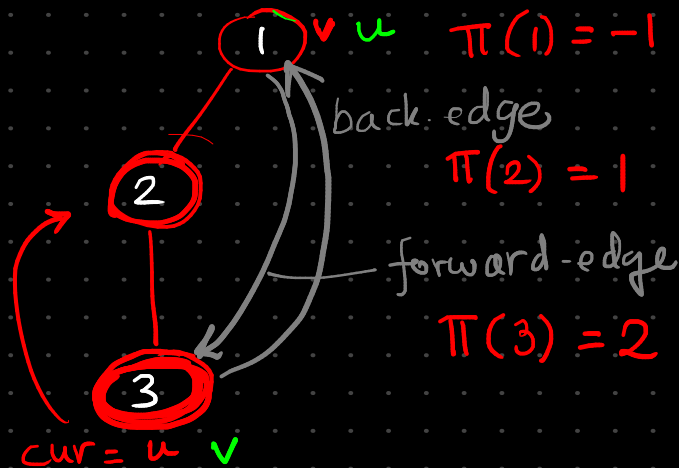
0 = unvisited
1 = active
2 = done

```
void dfs (int u) {
    visited[u] = true; state[u] = 1
    for (int v : g[u]) {
        if (v == pi[u]) continue;

        if (visited[v] == false) { state[v] == 0
            pi[v] = u;
            dfs(v);
        }
        else if (state[v] == 1) {
            // Detected cycle
            cout << "Found a cycle between: " << u << " " << v << "\n";

            int cur = u;
            while (cur != v) {
                cout << cur << ", ";
                cur = pi[cur];
            }
            cout << cur << "\n";
        }
        else if (state[v] == 2) → forward-edge
    }
}
```

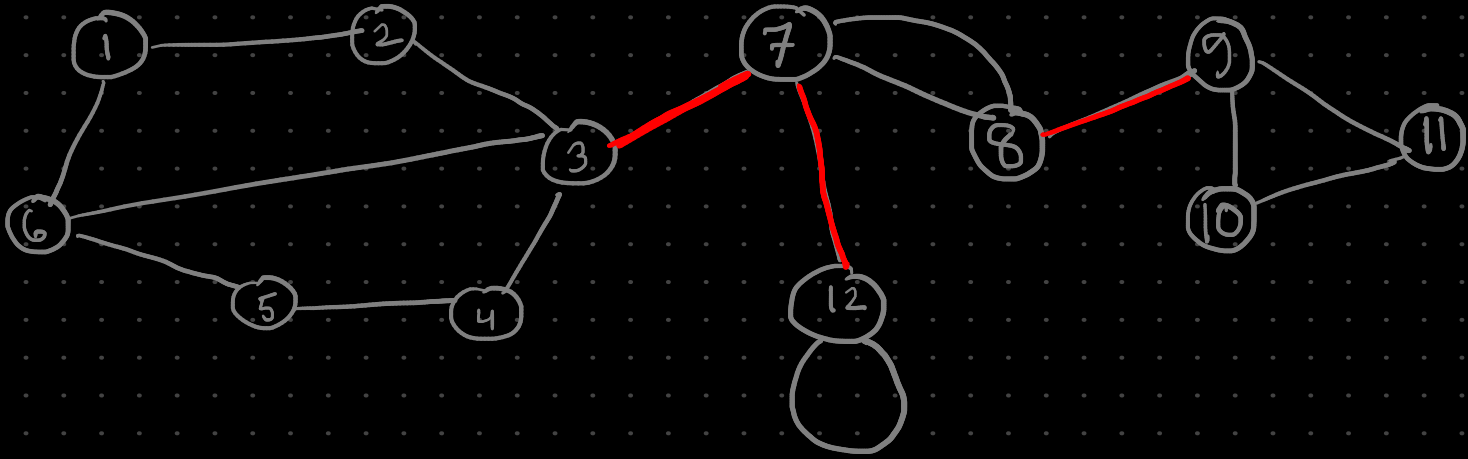
state[u] = 2
u — v when backedge?
when v is active in DFS!



3	2	1
1	-1	-1

Bridges in Undirected Graphs

Edges which upon deletion increase the number of connected components.

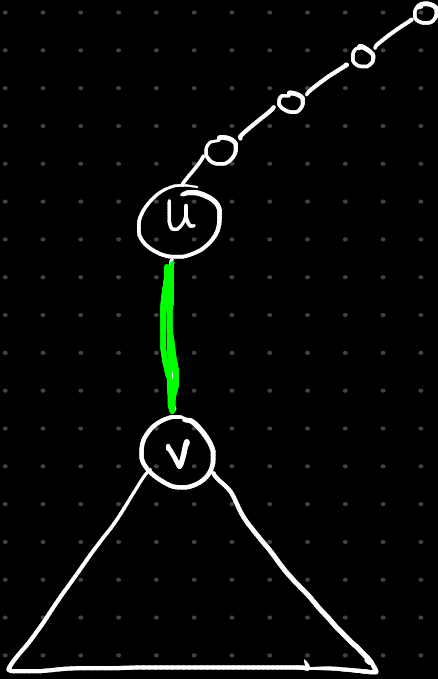


Brute force ? For all edge \rightarrow try removing and then count #components using DFS

$$O(E * (V + E)) \approx O(E^2)$$

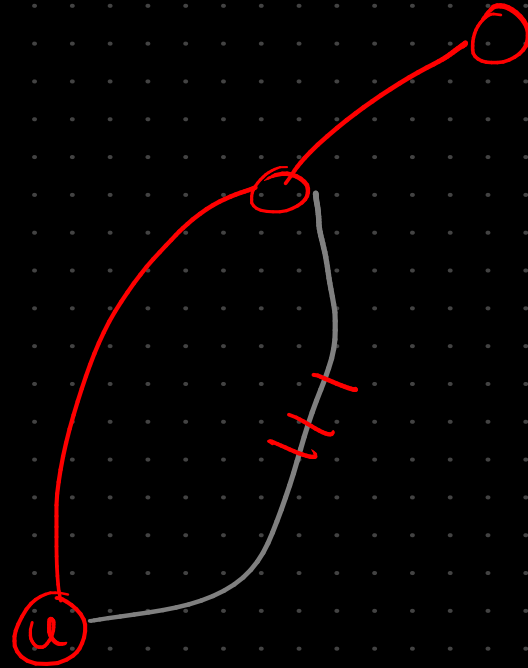
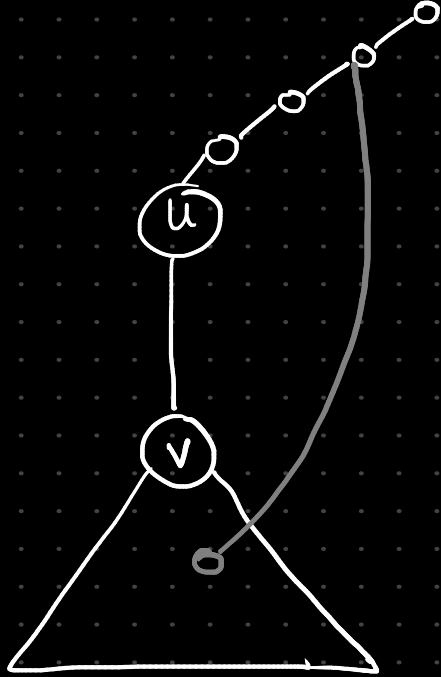
Finding Bridges Quickly

Lemma: A span edge $u-v$ is a bridge iff there exists no back-edge that connects a descendent of $u-v$ with an ancestor of $u-v$.



Finding Bridges Quickly

Observation: A back-edge is never a bridge.

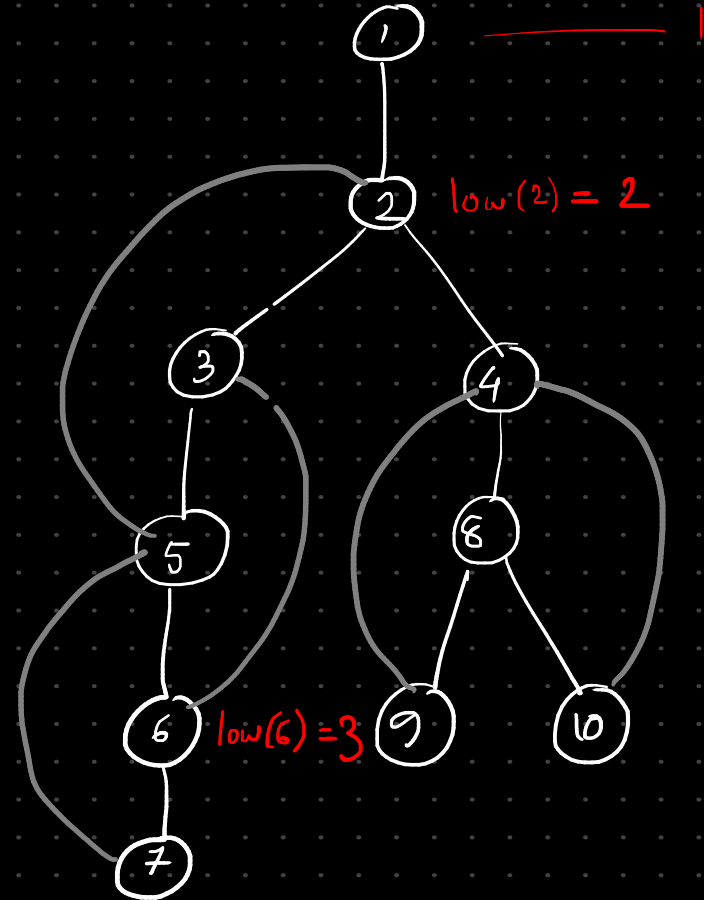
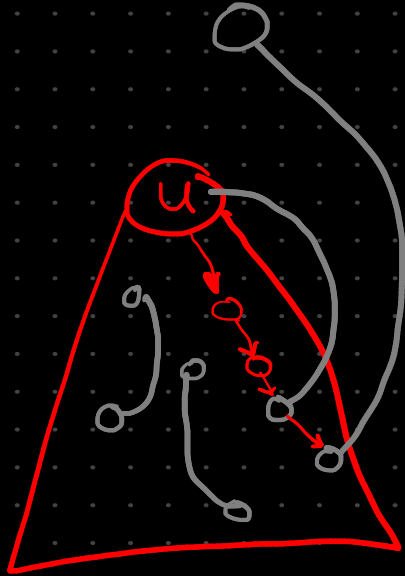


Bridge Finding Algorithm

Define,

$d(u)$ = depth of node u from root in dfs tree.

$\text{low}(u)$ = min depth node u that can be reached
from u 's subtree, using at most 1 back-edge



Bridge Finding Algorithm

Define,

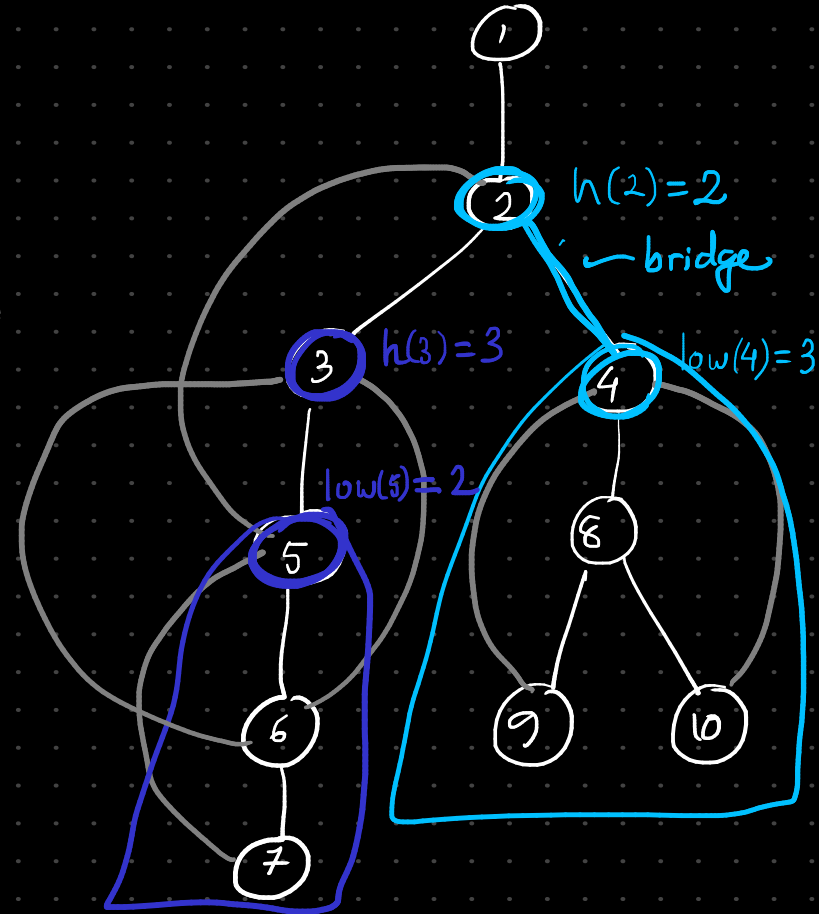
$d(u)$ = depth of node u from root in dfs tree.

$low(u)$ = min depth node u that can be reached from u 's subtree, using at most 1 back-edge

An edge $u-v$ is a bridge iff
 v can't reach $d(u)$ or higher from its subtree

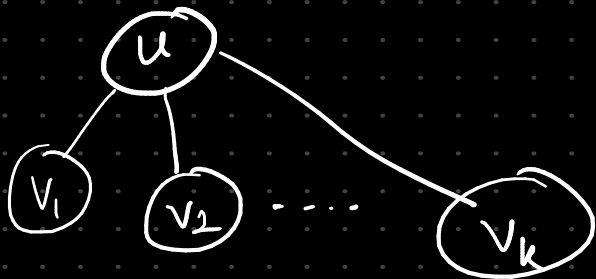
(assuming $h(u) < h(v)$)

$$d(u) < low(v)$$



How to calculate $\text{low}(u)$?

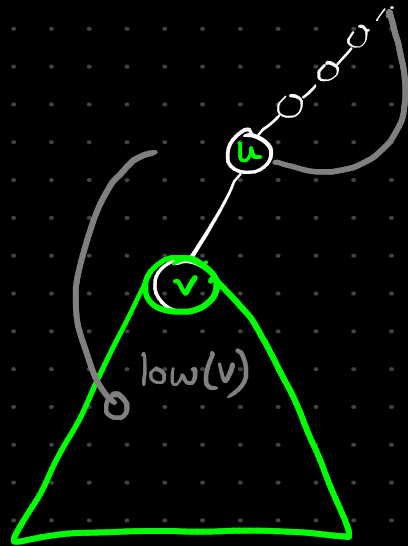
$\text{low}(u)$ = min depth node u that can be reached from u 's subtree, using at most 1 back-edge



initially $\text{low}(u) = d(u) \quad \forall u$.

$u - v$ (tree edge): $\text{low}(u) = \min(\text{low}(u), \text{low}(v))$

✓ $u - v$ (back edge): $\text{low}(u) = \min(\text{low}(u), d(v))$



Implementation

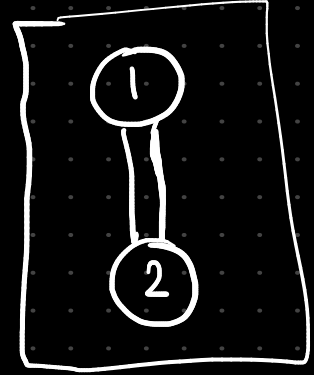
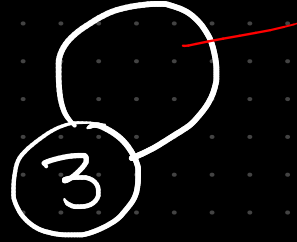
```
1  int d[N], low[N];
2  bool vis[N];
3
4  ▼ void dfs (int u) {
5      vis[u] = true;
6      d[u] = d[pi[u]] + 1;
7
8      ▼ for (int v : g[u]) {
9           $v \neq u \rightarrow$  if (v == f) continue; // ignore edge to parent
10         if (vis[v]) low[u] = min(low[u], d[v]); // back-edge
11     }
12     ▼ else {
13         dfs(v);
14         low[u] = min(low[u], low[v]);
15
16         if (d[u] < low[v]) {
17             // This edge is a bridge
18         }
19     }
20 }
```

$f = pi[u]$

Handling Multi-Edges and Self Loops



Multi-edge ??



Fix by making a list of all bridges.

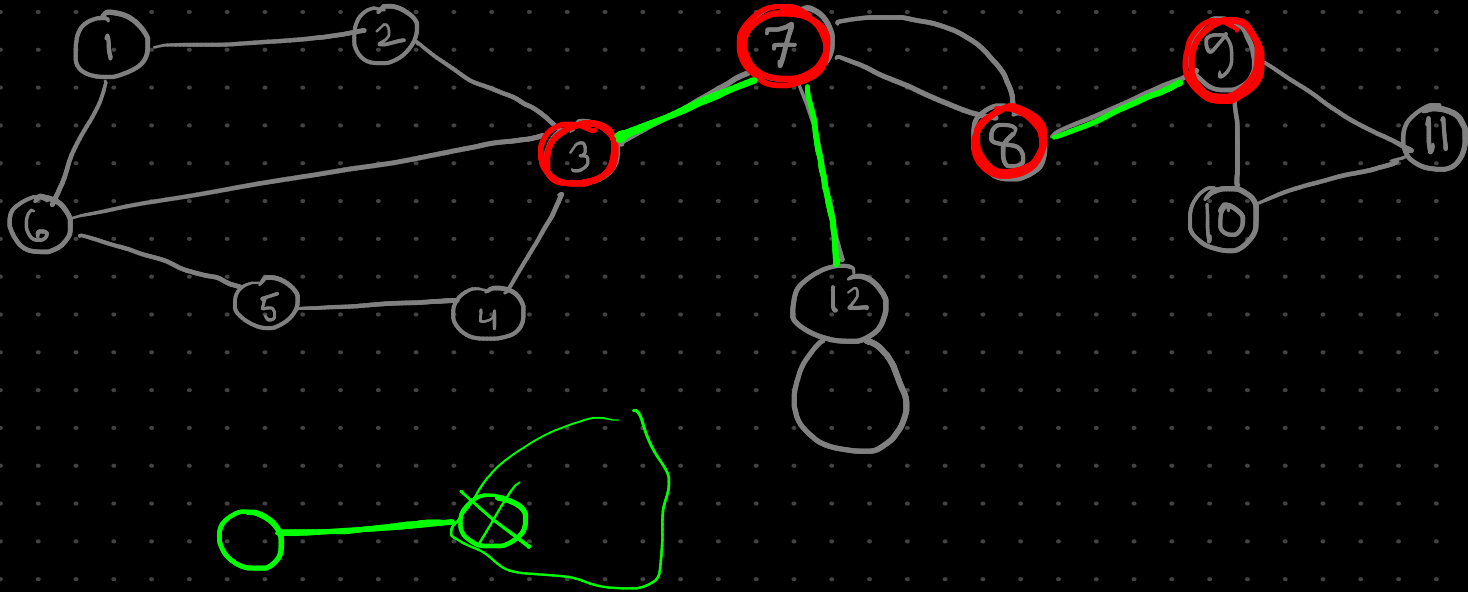
Sort all edges.

If for any (u,v) you find the same (u,v) adjacent to it,
delete all copies.

Articulation Points in Undirected Graph

↳ cut point / vertex

Nodes which upon deletion increase the number of connected components.



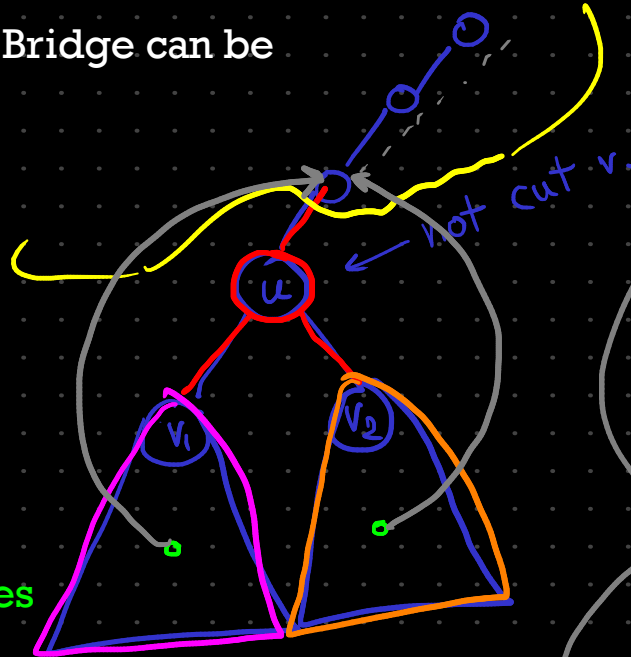
Articulation Point Finding Algorithm

It seems most of the ideas of Bridge can be re-used here.

A node u is a cut vertex if

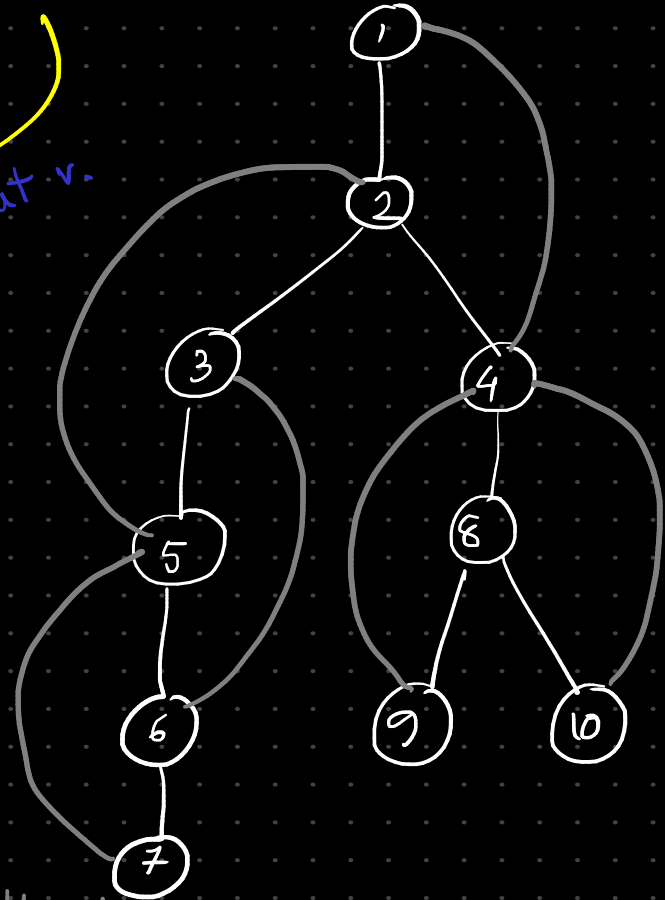
for any children v :
 $d(u) \leq \text{low}(v)$

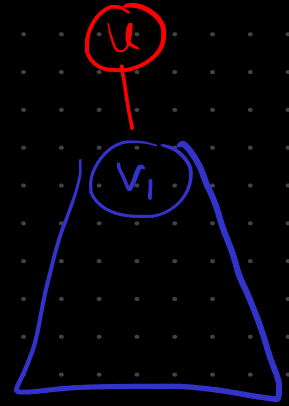
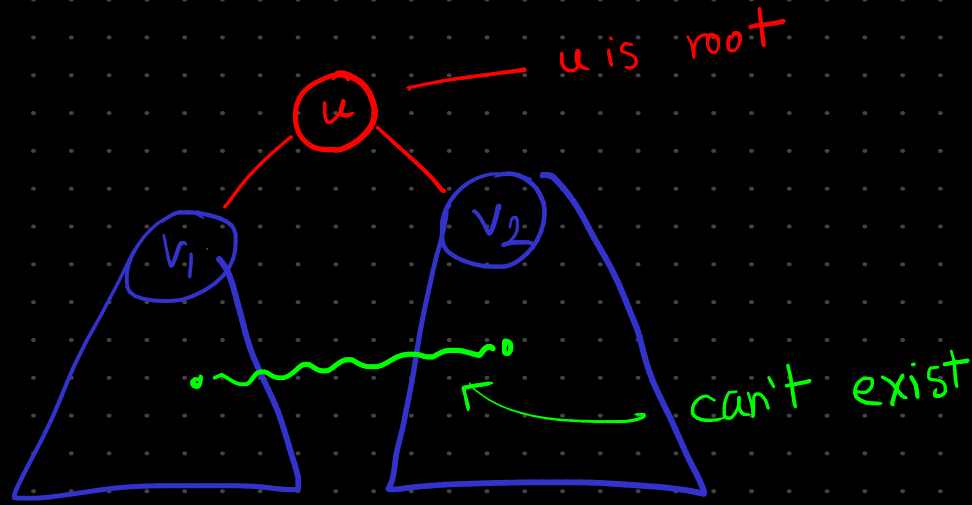
only works for non-root nodes



$$\neg \begin{cases} \text{low}(v_1) < d(u) \\ \text{low}(v_2) < d(u) \end{cases}$$

$$\Rightarrow \{d(u) \leq \text{low}(v)\} \text{ for at least one } v.$$





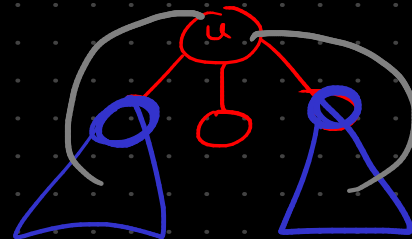
If u is root,
then u is cut point as long as it has > 1 children.

Implementation

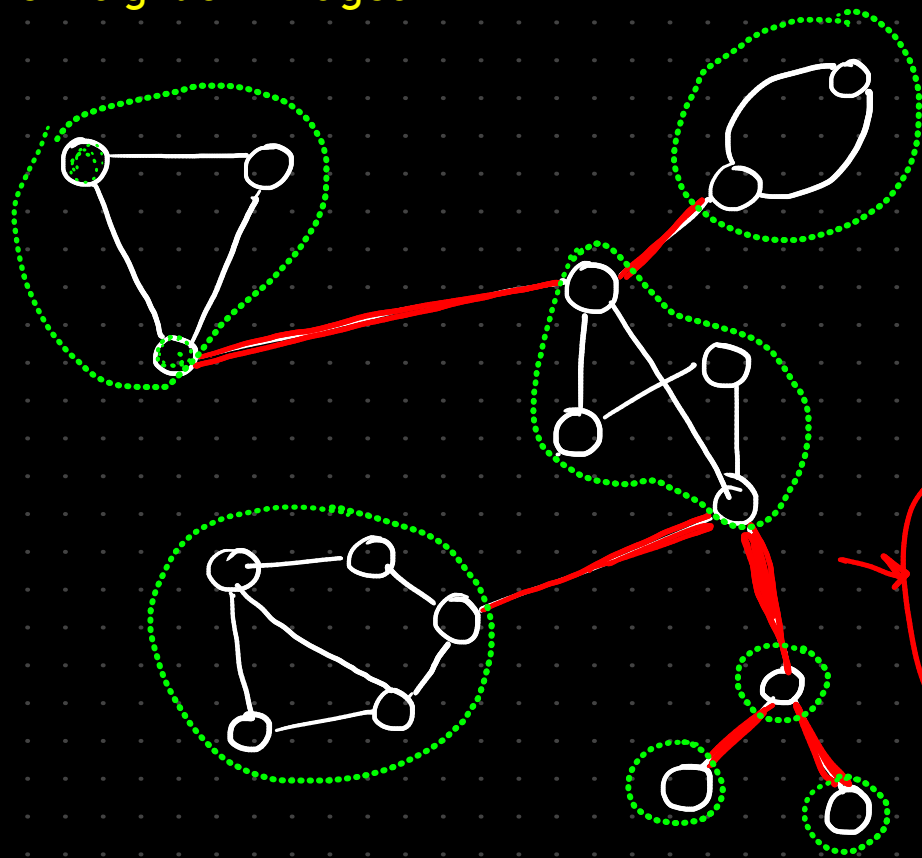
```

1 int d[N], low[N];
2 bool vis[N];
3
4 void dfs (int u) {
5     vis[u] = true;
6     d[u] = d[pi[u]] + 1;
7
8     int nchild = 0;
9     for (int v : g[u]) {
10         if (v == pi[u]) continue; // ignore edge to parent
11         if (vis[v]) low[u] = min(low[u], d[v]); // back-edge
12         else {
13             ++nchild;
14             dfs(v);
15             low[u] = min(low[u], low[v]);
16         }
17
18         if (d[u] <= low[v] && pi[u] != 0) {
19             // u is a cut point and not a root
20         }
21     }
22     if (pi[u] == 0 && nchild > 1)
23         // root is a cut point
24 }

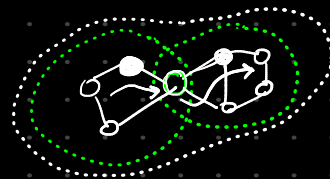
```



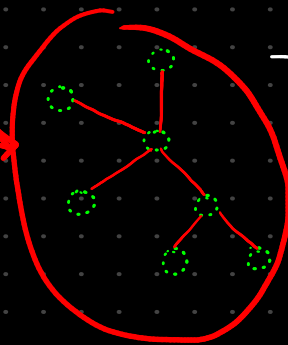
More Insight on Bridges



- All nodes belong to some component.
- All components are disjoint.



- The new graph has edges from the original graph.
- New graph is a tree

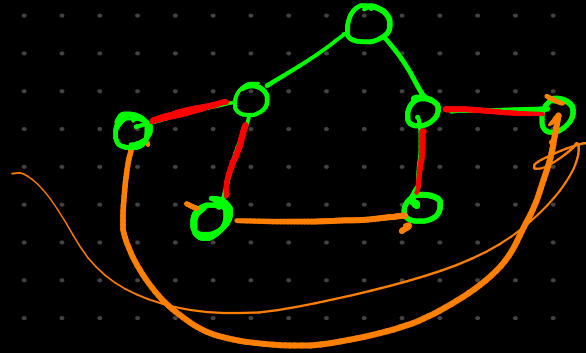
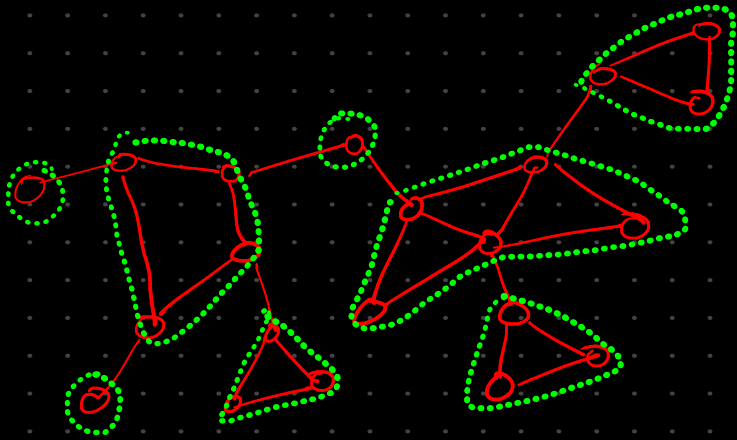


Bridge Tree

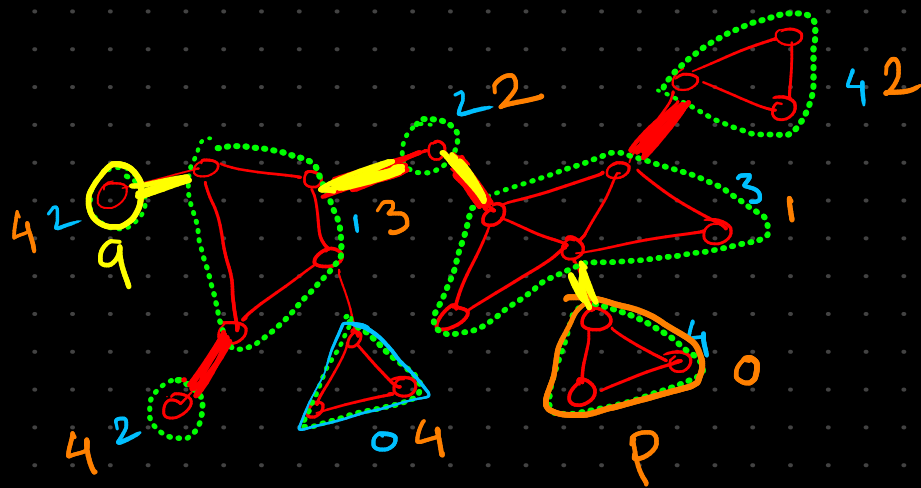
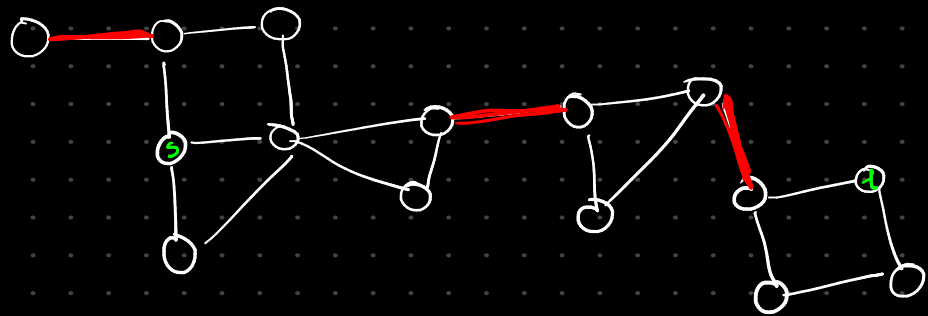
Some Problems

- Find the minimum number of edges to add in a graph so that no bridges exist.
- Find the maximum number of edges you can mark so that there exists a path between two nodes which MUST use all the marked edges. (1000E - CF)

Implementation Practice: LightOJ 1063, 1026



$$\left\lceil \frac{2}{2} \right\rceil$$



Set $S = \{ \dots \}$

S is valid if s, t exist s.t.
all paths from s to t must cross
everything from S .

find $\max(|S|)$

Tree diameter

DFS(u)

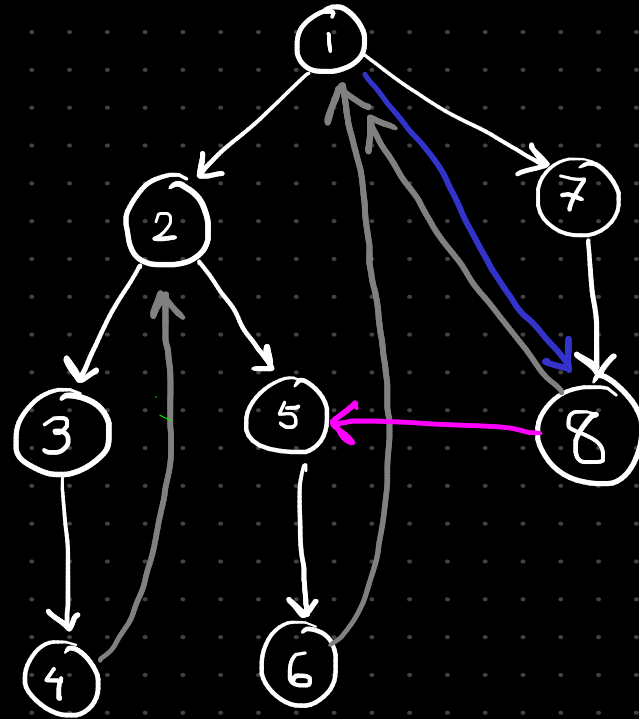
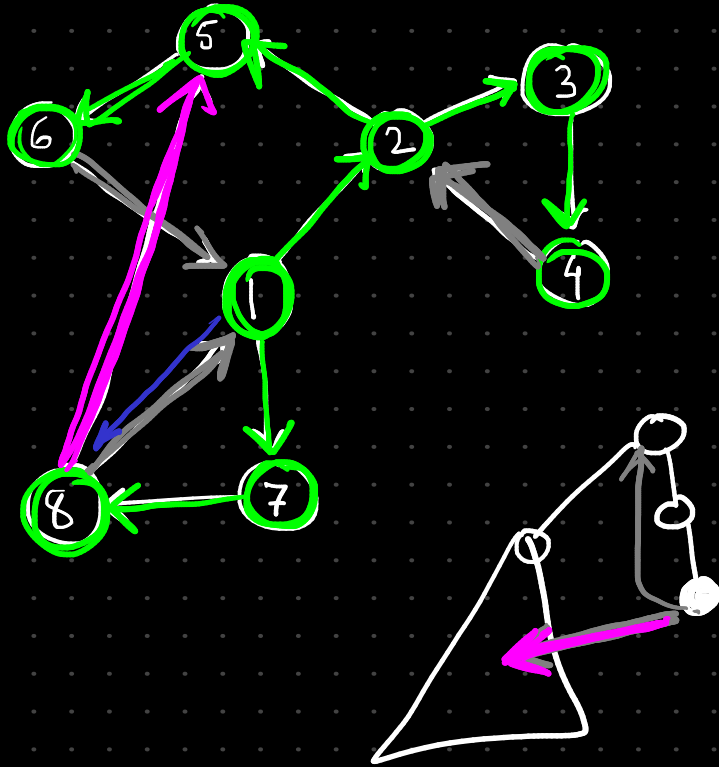
find p with max dist from u .

DFS(p)

find q with max dist from p .

diameter = $\text{dist}(p, q)$

DFS Tree on Directed Graphs

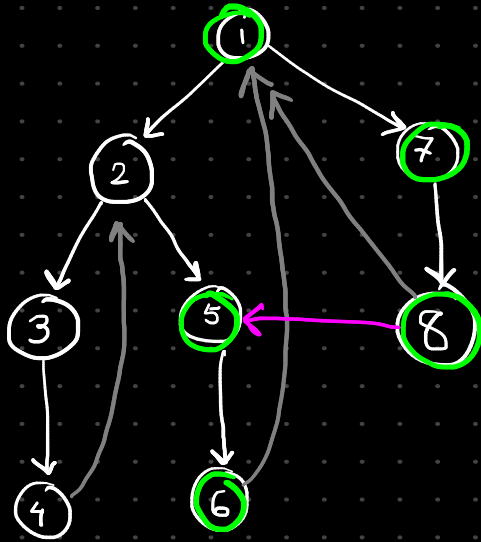


Cycles in Directed Graph

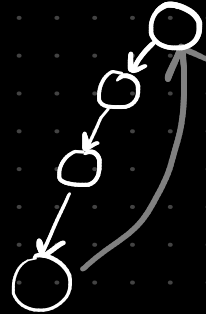
Observe that cross edges can't create cycles (?).

Only back-edges can create cycles.

Thus our previous cycle finding algorithm works here as well.



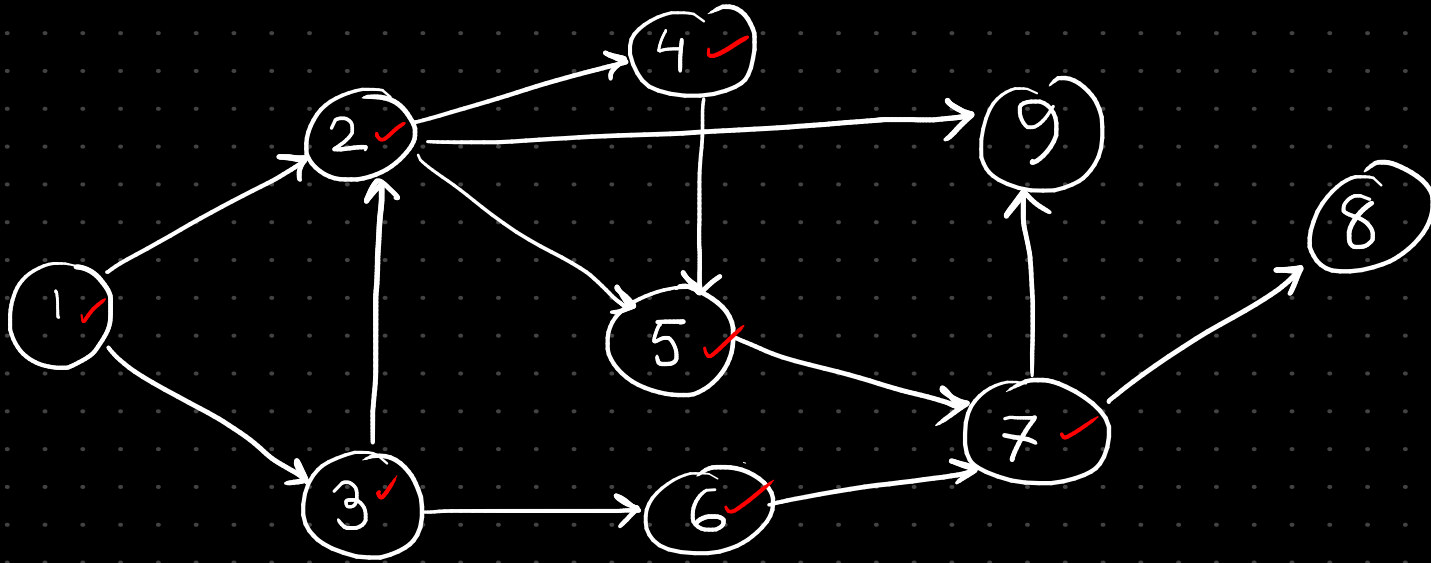
cross-edge, tree edge
back-edge



Topological Sort

Given a list of dependencies ($a \rightarrow b$) which represent:
a must be done before b is started
find an ordering that completes all the tasks.

CSE 111 \rightarrow CSE 220
 \downarrow
CSE 221



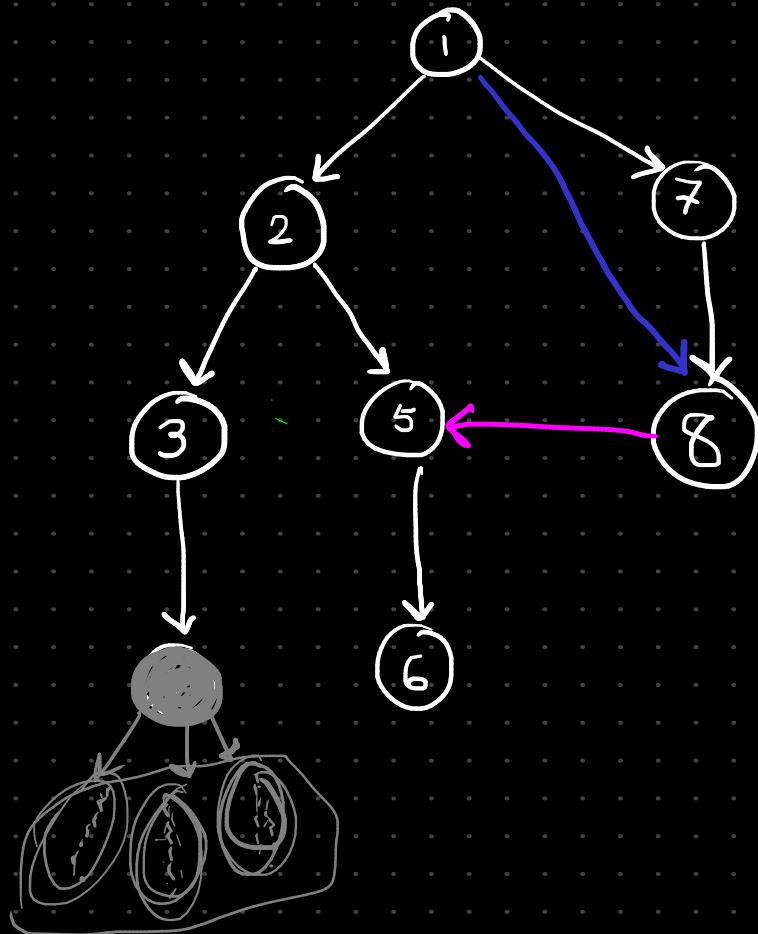
$1 \rightarrow 3 \rightarrow 2 \rightarrow 4 \rightarrow 5 \rightarrow 6 \rightarrow 7 \rightarrow 8 \rightarrow 9$

When is it impossible?

If there is a cycle in the directed graph.



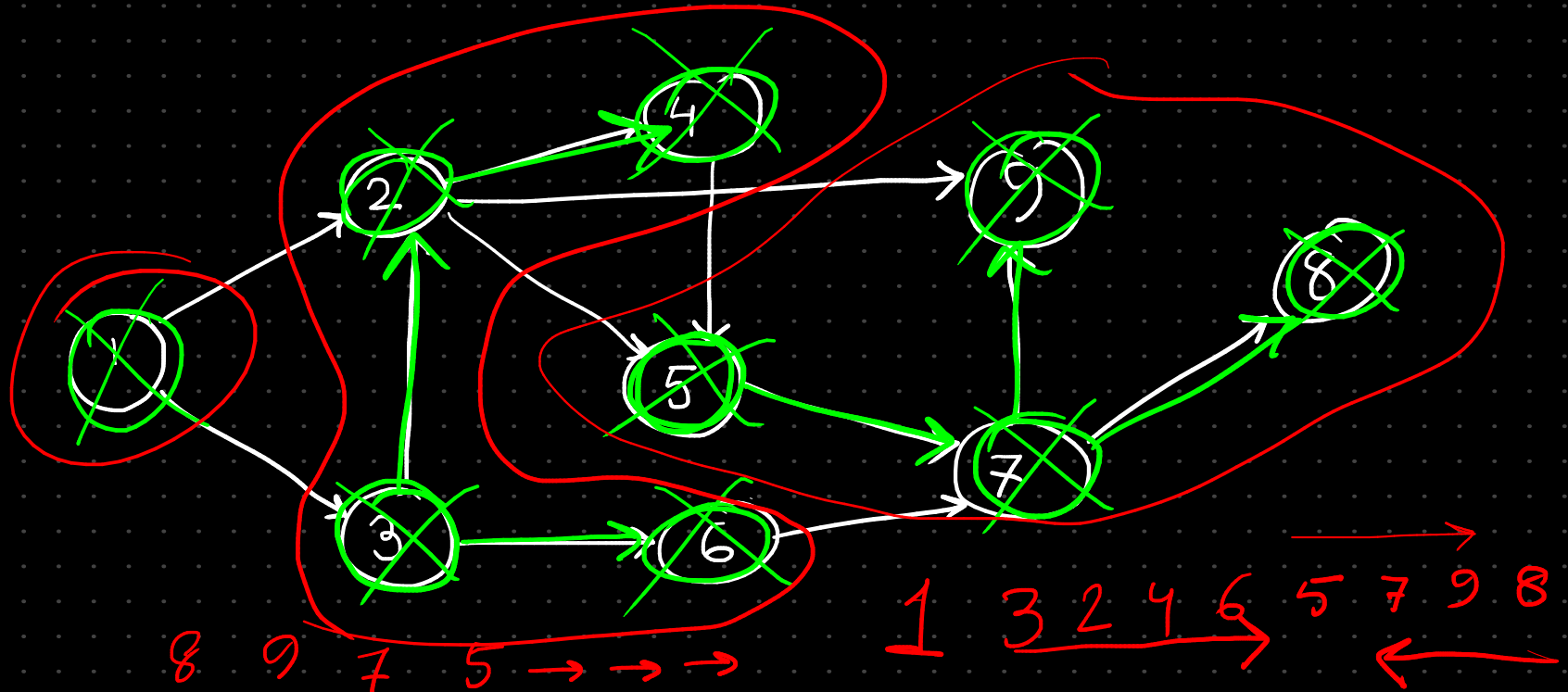
directed acyclic graph (DAG)

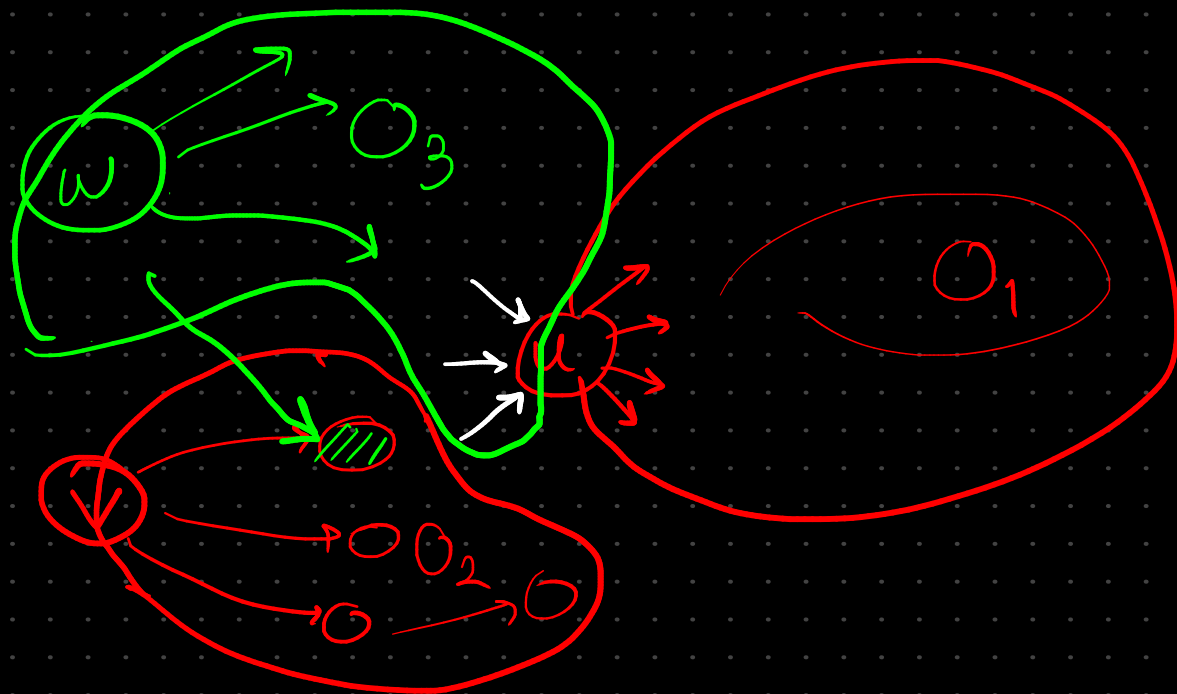


Topological Sort using DFS

Run a dfs.

Whenever a node finishes, we know all tasks that were supposed to happen after u is done.
So we can do this task u before all of them.

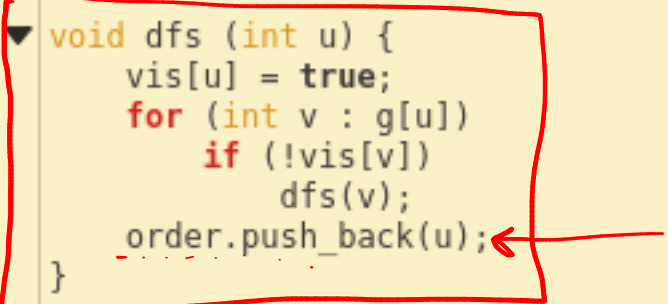




O_3 , O_2 , O_1

Implementation

```
1  bool vis[N];
2  vector<int> order;
3
4  ▼ void dfs (int u) {
5      vis[u] = true;
6      for (int v : g[u])
7          if (!vis[v])
8              dfs(v);
9      order.push_back(u);
10 }
11
12 ▼ void topsort () {
13     for (int i = 1; i <= n; ++i)
14         if (!vis[i])
15             dfs(i);
16     reverse(order.begin(), order.end());
17 }
```



Problems

- CF510C
- CSES1679, 1680, 1681

$\left\{ \begin{array}{l} s_1 \quad a b \\ s_2 \quad a b b c \\ s_3 \quad a c d \\ s_4 \quad b a a c \end{array} \right\}$

$O(n^2 \times |s_i|)$

$$s_1 \leq s_2$$

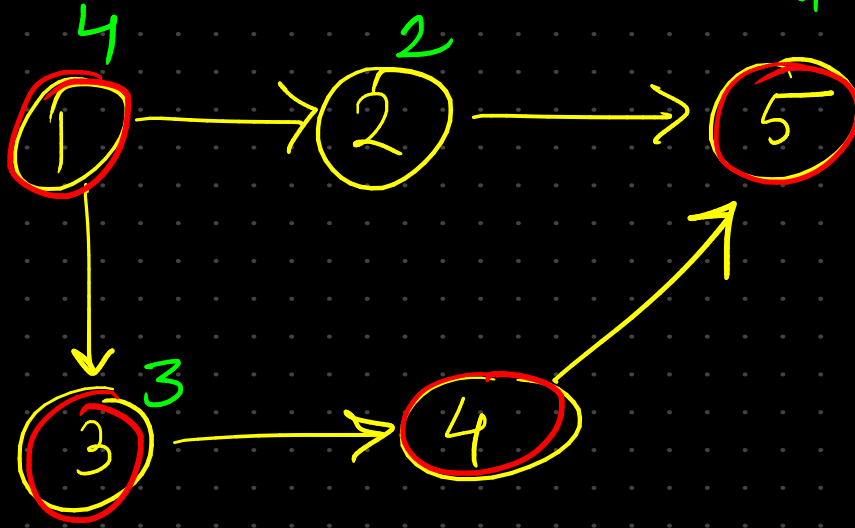
$$s_1 \leq s_3$$

$$\begin{array}{l} b < c \\ a < b \end{array}$$

$a \rightarrow b \rightarrow c$

$a b c x y z \dots$

$dp[u] = \max \text{ dist from } u.$



$$dp[1] = \max \begin{cases} 1 + dp[2] \\ 1 + dp[3] \end{cases}$$

$$dp[5] = 1$$

$$dp[4] = 1 + 1 = 2$$

$$dp[2] = 2$$

$$dp[3] = 3$$

$$dp[1] = 1 + 3 = 4$$

1 2 3 4 5

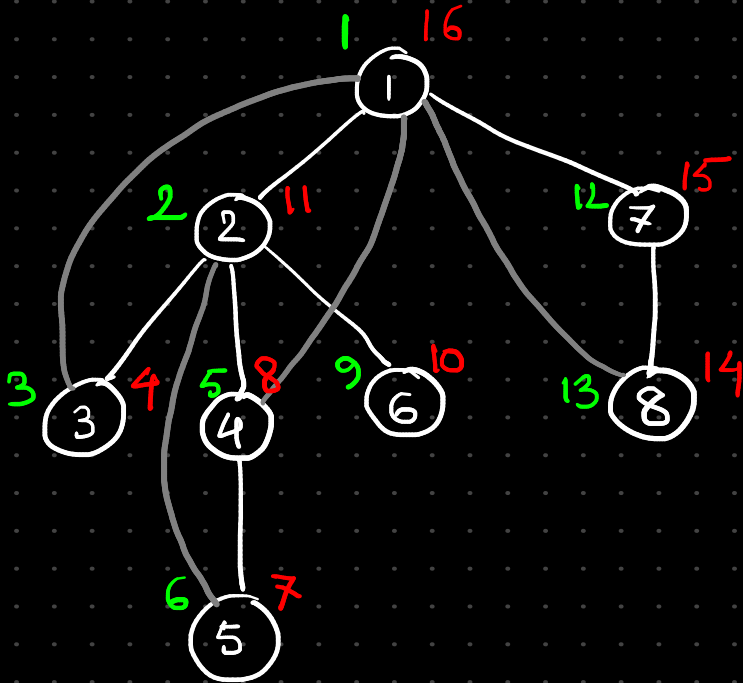
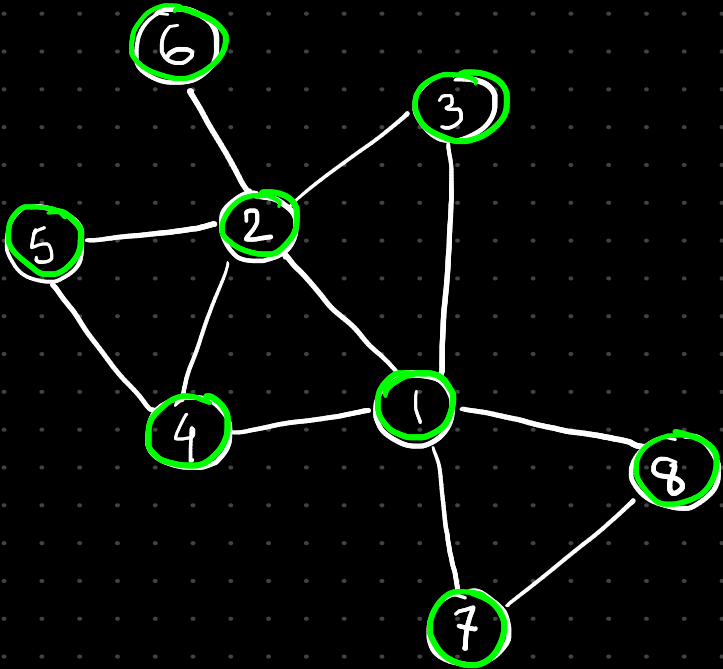


DFS Timers

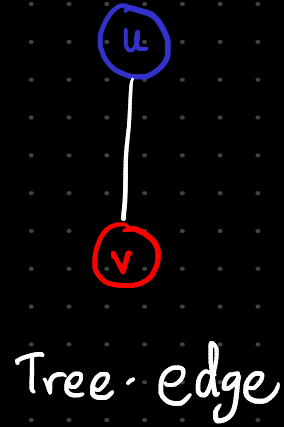
Timers are an easy way to keep track of which edge is which type.
Also has some cool properties.

```
1  int Timer, in[N], out[N];
2  int state[N], pi[N];
3
4  ▼ void dfs (int u) {
5      in[u] = Timer++;
6      state[u] = 1;
7      ▼ for (int v : g[u]) {
8          if (v == pi[u]) continue; // remember to ignore immediate edge to parent
9
10         ▼ if (state[v] == 0) {
11             pi[v] = u;
12             dfs(v); // span-edge ←
13         }
14         else if (state[v] == 1) {} // back-edge ←
15         else {} // forward-edge, cross-edge
16     }
17     state[u] = 2;
18     out[u] = Timer++;
19 }
```

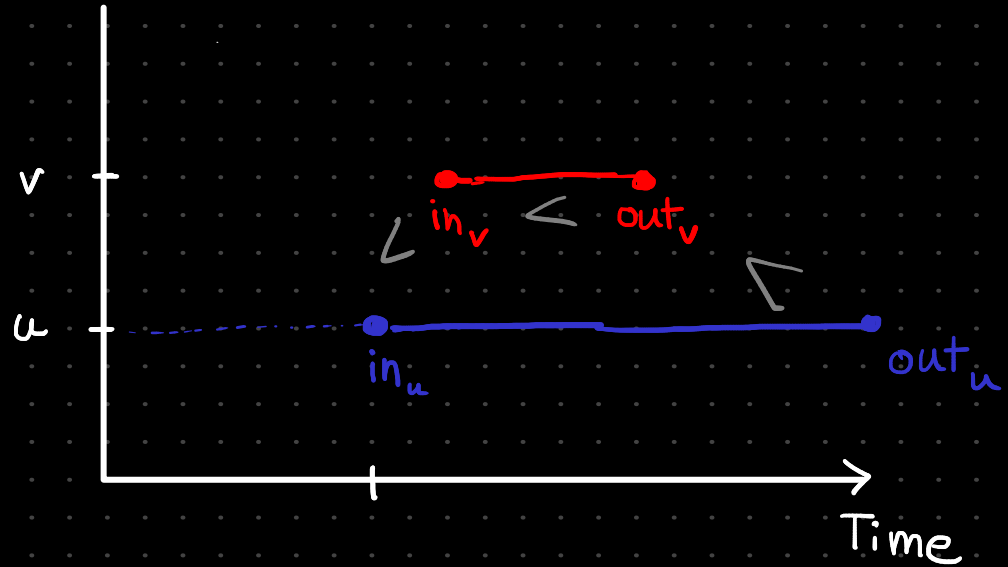
DFS Timers



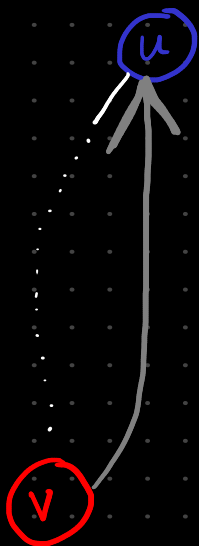
DFS Timers and Edge Types



how does (in_u, out_u) and (in_v, out_v) pairs look like?

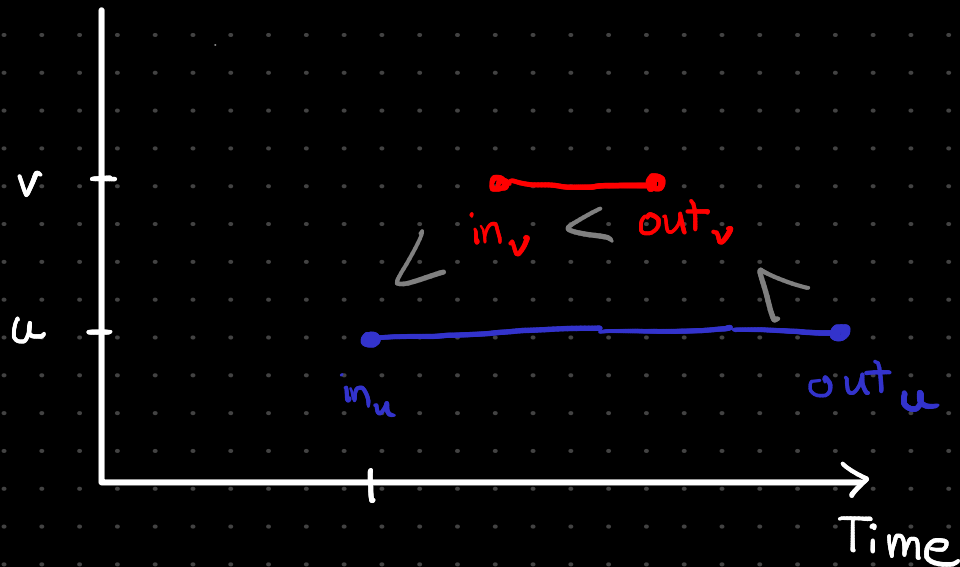


DFS Timers and Edge Types



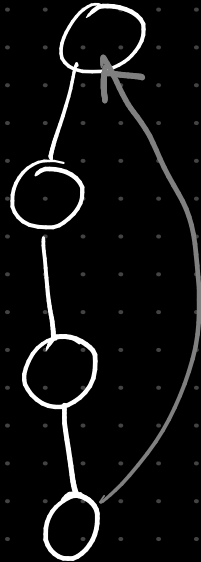
Back-edge $v \rightarrow u$

how does (in_u, out_u) and (in_v, out_v) pairs look like?



WAIT!!!

Span edges and Back edges look like the same?
How to differentiate?

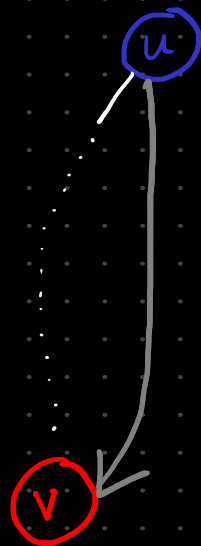


$$in_u < in_v < out_v < out_u$$

For backedges:

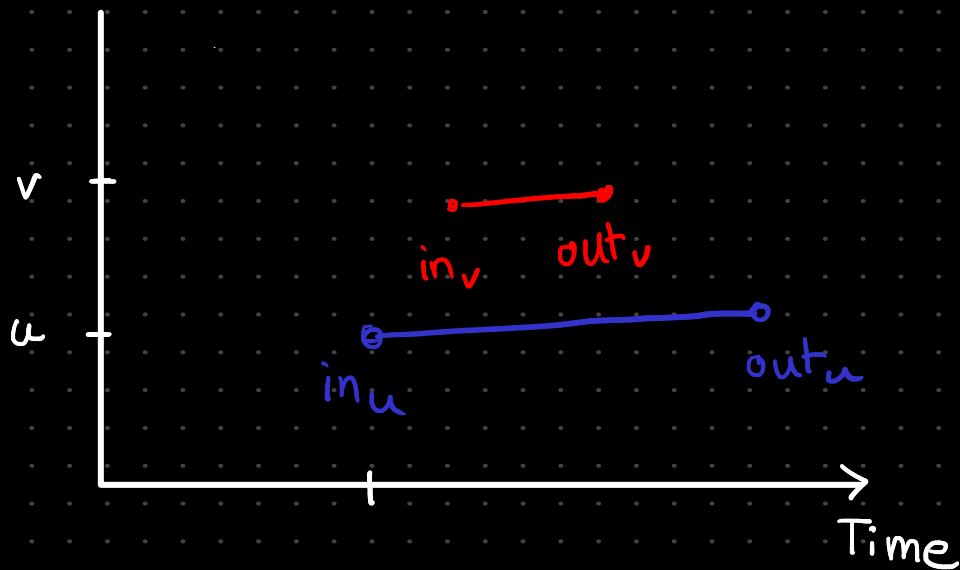
- $\pi(u) \neq v$ and
- $\pi(v) \neq u$

DFS Timers and Edge Types



Forward Edge $u \rightarrow v$

how does (in_u, out_u) and (in_v, out_v) pairs look like?



$u \rightarrow v$

TE

$$\pi(v) = u$$

BE

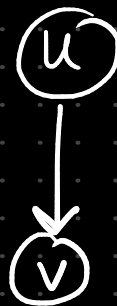
$$\text{in}_v < \text{in}_u < \text{out}_u < \text{out}_v$$

FE

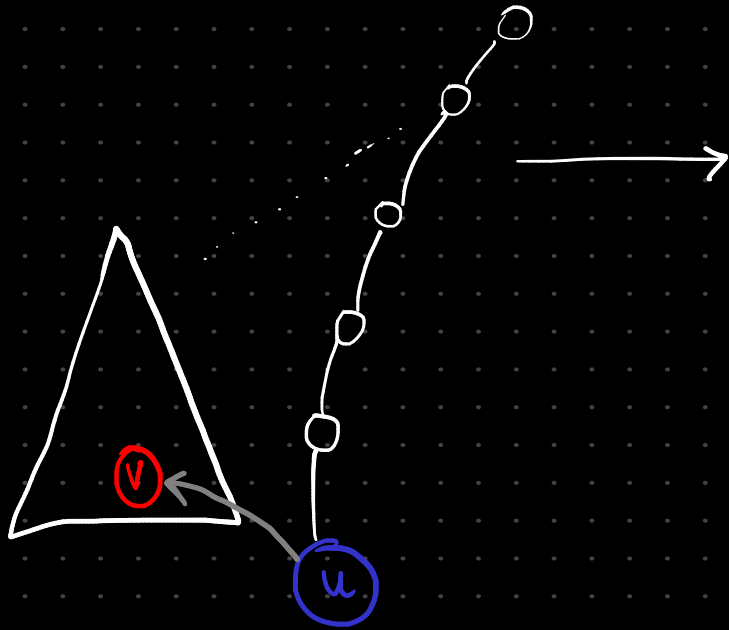
$$\text{in}_u < \text{in}_v < \text{out}_v < \text{in}_v$$

CE

$$\text{out}_v < \text{in}_u$$



DFS Timers and Edge Types



Cross Edge

how does (in_u, out_u) and (in_v, out_v) pairs look like?

