

The ALSA Driver API

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Chapter 1. Management of Cards and Devices

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Card Management

Name

`snd_card_create` — create and initialize a soundcard structure

Synopsis

```
int snd_card_create (idx,  
                    xid,  
                    module,  
                    extra_size,  
                    card_ret);
```

```
int                idx;  
const char *      xid;  
struct module *   module;  
int               extra_size;  
struct snd_card ** card_ret;
```

Arguments

idx

card index (address) [0 ... (SNDRV_CARDS-1)]

xid

card identification (ASCII string)

module

top level module for locking

extra_size

allocate this extra size after the main soundcard structure

card_ret

the pointer to store the created card instance

Description

Creates and initializes a soundcard structure.

The function allocates `snd_card` instance via `kzalloc` with the given space for the driver to use freely. The allocated struct is stored in the given `card_ret` pointer.

Returns zero if successful or a negative error code.

Name

`snd_card_disconnect` — disconnect all APIs from the file-operations (user space)

Synopsis

```
int snd_card_disconnect (card);
```

```
struct snd_card * card;
```

Arguments

card

soundcard structure

Description

Disconnects all APIs from the file-operations (user space).

Returns zero, otherwise a negative error code.

Note

The current implementation replaces all active file->f_op with special dummy file operations (they do nothing except release).

Name

`snd_card_set_id` — set card identification name

Synopsis

```
void snd_card_set_id (card,  
                     nid);  
  
struct snd_card * card;  
const char *      nid;
```

Arguments

card

soundcard structure

nid

new identification string

Description

This function sets the card identification and checks for name collisions.

Name

`snd_card_register` — register the soundcard

Synopsis

```
int snd_card_register (card);  
  
struct snd_card * card;
```

Arguments

card

soundcard structure

Description

This function registers all the devices assigned to the soundcard. Until calling this, the ALSA control interface is blocked from the external accesses. Thus, you should call this function at the end of the initialization of the card.

Returns zero otherwise a negative error code if the registration failed.

Name

`snd_component_add` — add a component string

Synopsis

```
int snd_component_add (card,  
                      component);
```

```
struct snd_card * card;  
const char *      component;
```

Arguments

card

soundcard structure

component

the component id string

Description

This function adds the component id string to the supported list. The component can be referred from the alsa-lib.

Returns zero otherwise a negative error code.

Name

`snd_card_file_add` — add the file to the file list of the card

Synopsis

```
int snd_card_file_add (card,  
                      file);
```

```
struct snd_card * card;  
struct file *      file;
```

Arguments

card

soundcard structure

file

file pointer

Description

This function adds the file to the file linked-list of the card. This linked-list is used to keep tracking the connection state, and to avoid the release of busy resources by hotplug.

Returns zero or a negative error code.

Name

`snd_card_file_remove` — remove the file from the file list

Synopsis

```
int snd_card_file_remove (card,
                          file);
```

```
struct snd_card * card;
struct file *     file;
```

Arguments

card

soundcard structure

file

file pointer

Description

This function removes the file formerly added to the card via `snd_card_file_add` function. If all files are removed and `snd_card_free_when_closed` was called beforehand, it processes the pending release of resources.

Returns zero or a negative error code.

Name

`snd_power_wait` — wait until the power-state is changed.

Synopsis

```
int snd_power_wait (card,  
                    power_state);  
  
struct snd_card * card;  
unsigned int      power_state;
```

Arguments

card

soundcard structure

power_state

expected power state

Description

Waits until the power-state is changed.

Note

the power lock must be active before call.

Device Components

Name

`snd_device_new` — create an ALSA device component

Synopsis

```
int snd_device_new (card,  
                    type,  
                    device_data,  
                    ops);  
  
struct snd_card *      card;  
snd_device_type_t      type;  
void *                 device_data;  
struct snd_device_ops * ops;
```

Arguments

card

the card instance

type

the device type, SNDRV_DEV_XXX

device_data

the data pointer of this device

ops

the operator table

Description

Creates a new device component for the given data pointer. The device will be assigned to the card and managed together by the card.

The data pointer plays a role as the identifier, too, so the pointer address must be unique and unchanged.

Returns zero if successful, or a negative error code on failure.

Name

snd_device_free — release the device from the card

Synopsis

```
int snd_device_free (card,  
                    device_data);
```

```
struct snd_card * card;  
void *           device_data;
```

Arguments

card

the card instance

device_data

the data pointer to release

Description

Removes the device from the list on the card and invokes the callbacks, dev_disconnect and dev_free, corresponding to the state. Then release the device.

Returns zero if successful, or a negative error code on failure or if the device not found.

Name

`snd_device_register` — register the device

Synopsis

```
int snd_device_register (card,  
                        device_data);
```

```
struct snd_card * card;  
void * device_data;
```

Arguments

card

the card instance

device_data

the data pointer to register

Description

Registers the device which was already created via `snd_device_new`. Usually this is called from `snd_card_register`, but it can be called later if any new devices are created after invocation of `snd_card_register`.

Returns zero if successful, or a negative error code on failure or if the device not found.

Module requests and Device File Entries

Name

`snd_request_card` — try to load the card module

Synopsis

```
void snd_request_card (card);
```

```
int card;
```

Arguments

card

the card number

Description

Tries to load the module “snd-card-X” for the given card number via `request_module`. Returns immediately if already loaded.

Name

`snd_lookup_minor_data` — get user data of a registered device

Synopsis

```
void * snd_lookup_minor_data (minor,  
                               type);
```

```
unsigned int minor;  
int         type;
```

Arguments

minor

the minor number

type

device type (SNDRV_DEVICE_TYPE_XXX)

Description

Checks that a minor device with the specified type is registered, and returns its user data pointer.

Name

`snd_register_device_for_dev` — Register the ALSA device file for the card

Synopsis

```
int snd_register_device_for_dev (type,  
                                 card,  
                                 dev,  
                                 f_ops,
```

```

                                private_data,
                                name,
                                device);

int                                type;
struct snd_card *                 card;
int                                dev;
const struct file_operations *    f_ops;
void *                            private_data;
const char *                      name;
struct device *                   device;

```

Arguments

type

the device type, SNDRV_DEVICE_TYPE_XXX

card

the card instance

dev

the device index

f_ops

the file operations

private_data

user pointer for *f_ops*->open

name

the device file name

device

the struct device to link this new device to

Description

Registers an ALSA device file for the given card. The operators have to be set in *reg* parameter.

Returns zero if successful, or a negative error code on failure.

Name

`snd_unregister_device` — unregister the device on the given card

Synopsis

```
int snd_unregister_device (type,
                           card,
                           dev);
```

```
int                type;
struct snd_card * card;
int                dev;
```

Arguments

type

the device type, `SNDRV_DEVICE_TYPE_XXX`

card

the card instance

dev

the device index

Description

Unregisters the device file already registered via `snd_register_device`.

Returns zero if successful, or a negative error code on failure

Memory Management Helpers

Name

`copy_to_user_fromio` — copy data from mmio-space to user-space

Synopsis

```
int copy_to_user_fromio (dst,
                          src,
                          count);
```

```
void __user *          dst;
const volatile void __iomem * src;
size_t                count;
```

Arguments

dst

the destination pointer on user-space

src

the source pointer on mmio

count

the data size to copy in bytes

Description

Copies the data from mmio-space to user-space.

Returns zero if successful, or non-zero on failure.

Name

`copy_from_user_toio` — copy data from user-space to mmio-space

Synopsis

```
int copy_from_user_toio (dst,  
                          src,  
                          count);
```

```
volatile void __iomem * dst;  
const void __user * src;  
size_t count;
```

Arguments

dst

the destination pointer on mmio-space

src

the source pointer on user-space

count

the data size to copy in bytes

Description

Copies the data from user-space to mmio-space.

Returns zero if successful, or non-zero on failure.

Name

`snd_malloc_pages` — allocate pages with the given size

Synopsis

```
void * snd_malloc_pages (size,  
                           gfp_flags);
```

```
size_t size;  
gfp_t gfp_flags;
```

Arguments

size

the size to allocate in bytes

gfp_flags

the allocation conditions, GFP_XXX

Description

Allocates the physically contiguous pages with the given size.

Returns the pointer of the buffer, or NULL if no enough memory.

Name

`snd_free_pages` — release the pages

Synopsis

```
void snd_free_pages (ptr,  
                     size);
```

```
void * ptr;  
size_t size;
```

Arguments

ptr

the buffer pointer to release

size

the allocated buffer size

Description

Releases the buffer allocated via `snd_malloc_pages`.

Name

`snd_dma_alloc_pages` — allocate the buffer area according to the given type

Synopsis

```
int snd_dma_alloc_pages (type,  
                        device,  
                        size,  
                        dmab);
```

```
int                                type;  
struct device *                   device;  
size_t                            size;  
struct snd_dma_buffer * dmab;
```

Arguments

type

the DMA buffer type

device

the device pointer

size

the buffer size to allocate

dmab

buffer allocation record to store the allocated data

Description

Calls the memory-allocator function for the corresponding buffer type.

Returns zero if the buffer with the given size is allocated successfully, other a negative value at error.

Name

`snd_dma_alloc_pages_fallback` — allocate the buffer area according to the given type with fallback

Synopsis

```
int snd_dma_alloc_pages_fallback (type,
                                   device,
                                   size,
                                   dmab);
```

```
int                                type;
struct device *                   device;
size_t                            size;
struct snd_dma_buffer * dmab;
```

Arguments

type

the DMA buffer type

device

the device pointer

size

the buffer size to allocate

dmab

buffer allocation record to store the allocated data

Description

Calls the memory-allocator function for the corresponding buffer type. When no space is left, this function reduces the size and tries to allocate again. The size actually allocated is stored in `res_size` argument.

Returns zero if the buffer with the given size is allocated successfully, other a negative value at error.

Name

`snd_dma_free_pages` — release the allocated buffer

Synopsis

```
void snd_dma_free_pages (dmab);  
  
struct snd_dma_buffer * dmab;
```

Arguments

dmab
the buffer allocation record to release

Description

Releases the allocated buffer via `snd_dma_alloc_pages`.

Name

`snd_dma_get_reserved_buf` — get the reserved buffer for the given device

Synopsis

```
size_t snd_dma_get_reserved_buf (dmab,  
                                id);  
  
struct snd_dma_buffer * dmab;  
unsigned int id;
```

Arguments

dmab
the buffer allocation record to store

id
the buffer id

Description

Looks for the reserved-buffer list and re-uses if the same buffer is found in the list. When the buffer is

found, it's removed from the free list.

Returns the size of buffer if the buffer is found, or zero if not found.

Name

`snd_dma_reserve_buf` — reserve the buffer

Synopsis

```
int snd_dma_reserve_buf (dmab,  
                        id);
```

```
struct snd_dma_buffer * dmab;  
unsigned int           id;
```

Arguments

dmab

the buffer to reserve

id

the buffer id

Description

Reserves the given buffer as a reserved buffer.

Returns zero if successful, or a negative code at error.

Chapter 2. PCM API

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PCM Core

Name

`snd_pcm_new_stream` — create a new PCM stream

Synopsis

```
int snd_pcm_new_stream (pcm,  
                        stream,  
                        substream_count);
```

```
struct snd_pcm * pcm;  
int             stream;  
int             substream_count;
```

Arguments

pcm

the pcm instance

stream

the stream direction, SNDRV_PCM_STREAM_XXX

substream_count

the number of substreams

Description

Creates a new stream for the pcm. The corresponding stream on the pcm must have been empty before calling this, i.e. zero must be given to the argument of `snd_pcm_new`.

Returns zero if successful, or a negative error code on failure.

Name

`snd_pcm_new` — create a new PCM instance

Synopsis

```
int snd_pcm_new (card,  
                id,  
                device,  
                playback_count,  
                capture_count,  
                rpcm);
```

```
struct snd_card * card;  
const char *     id;  
int              device;  
int              playback_count;
```

```
int                capture_count;
struct snd_pcm ** rpcm;
```

Arguments

card

the card instance

id

the id string

device

the device index (zero based)

playback_count

the number of substreams for playback

capture_count

the number of substreams for capture

rpcm

the pointer to store the new pcm instance

Description

Creates a new PCM instance.

The pcm operators have to be set afterwards to the new instance via `snd_pcm_set_ops`.

Returns zero if successful, or a negative error code on failure.

Name

`snd_pcm_set_ops` — set the PCM operators

Synopsis

```
void snd_pcm_set_ops (pcm,
                     direction,
                     ops);

struct snd_pcm *    pcm;
int                direction;
```

```
struct snd_pcm_ops * ops;
```

Arguments

pcm

the pcm instance

direction

stream direction, SNDRV_PCM_STREAM_XXX

ops

the operator table

Description

Sets the given PCM operators to the pcm instance.

Name

snd_pcm_set_sync — set the PCM sync id

Synopsis

```
void snd_pcm_set_sync (substream);
```

```
struct snd_pcm_substream * substream;
```

Arguments

substream

the pcm substream

Description

Sets the PCM sync identifier for the card.

Name

snd_interval_refine — refine the interval value of configurator

Synopsis

```
int snd_interval_refine (i,
                        v);

struct snd_interval * i;
const struct snd_interval * v;
```

Arguments

i

the interval value to refine

v

the interval value to refer to

Description

Refines the interval value with the reference value. The interval is changed to the range satisfying both intervals. The interval status (min, max, integer, etc.) are evaluated.

Returns non-zero if the value is changed, zero if not changed.

Name

snd_interval_ratnum — refine the interval value

Synopsis

```
int snd_interval_ratnum (i,
                        rats_count,
                        rats,
                        nump,
                        denp);

struct snd_interval * i;
unsigned int rats_count;
struct snd_ratnum * rats;
unsigned int * nump;
unsigned int * denp;
```

Arguments

i

interval to refine

rats_count

number of *ratnum_t*

rats

ratnum_t array

nump

pointer to store the resultant numerator

denp

pointer to store the resultant denominator

Description

Returns non-zero if the value is changed, zero if not changed.

Name

snd_interval_list — refine the interval value from the list

Synopsis

```
int snd_interval_list (i,
                      count,
                      list,
                      mask);
```

```
struct snd_interval * i;
unsigned int          count;
unsigned int *        list;
unsigned int          mask;
```

Arguments

i

the interval value to refine

count

the number of elements in the list

list

the value list

mask

the bit-mask to evaluate

Description

Refines the interval value from the list. When mask is non-zero, only the elements corresponding to bit 1 are evaluated.

Returns non-zero if the value is changed, zero if not changed.

Name

snd_pcm_hw_rule_add — add the hw-constraint rule

Synopsis

```
int snd_pcm_hw_rule_add (runtime,
                        cond,
                        var,
                        func,
                        private,
                        dep,
                        ...);

struct snd_pcm_runtime * runtime;
unsigned int cond;
int var;
snd_pcm_hw_rule_func_t func;
void * private;
int dep;
...;
```

Arguments

runtime

the pcm runtime instance

cond

condition bits

var

the variable to evaluate

func

the evaluation function

private

the private data pointer passed to function

dep

the dependent variables

...

variable arguments

Description

Returns zero if successful, or a negative error code on failure.

Name

`snd_pcm_hw_constraint_integer` — apply an integer constraint to an interval

Synopsis

```
int snd_pcm_hw_constraint_integer (runtime,
                                   var);
```

```
struct snd_pcm_runtime * runtime;
snd_pcm_hw_param_t      var;
```

Arguments

runtime

PCM runtime instance

var

hw_params variable to apply the integer constraint

Description

Apply the constraint of integer to an interval parameter.

Name

`snd_pcm_hw_constraint_minmax` — apply a min/max range constraint to an interval

Synopsis

```
int snd_pcm_hw_constraint_minmax (runtime,
                                var,
                                min,
                                max);
```

```
struct snd_pcm_runtime * runtime;
snd_pcm_hw_param_t      var;
unsigned int             min;
unsigned int             max;
```

Arguments

runtime

PCM runtime instance

var

hw_params variable to apply the range

min

the minimal value

max

the maximal value

Description

Apply the min/max range constraint to an interval parameter.

Name

`snd_pcm_hw_constraint_list` — apply a list of constraints to a parameter

Synopsis

```
int snd_pcm_hw_constraint_list (runtime,
                                cond,
                                var,
                                l);
```

```
struct snd_pcm_runtime * runtime;
unsigned int             cond;
```

```

snd_pcm_hw_param_t          var;
struct snd_pcm_hw_constraint_list * l;

```

Arguments

runtime

PCM runtime instance

cond

condition bits

var

hw_params variable to apply the list constraint

l

list

Description

Apply the list of constraints to an interval parameter.

Name

snd_pcm_hw_constraint_ratnums — apply ratnums constraint to a parameter

Synopsis

```

int snd_pcm_hw_constraint_ratnums (runtime,
                                   cond,
                                   var,
                                   r);

struct snd_pcm_runtime *          runtime;
unsigned int                     cond;
snd_pcm_hw_param_t               var;
struct snd_pcm_hw_constraint_ratnums * r;

```

Arguments

runtime

PCM runtime instance

cond

condition bits

var

hw_params variable to apply the ratnums constraint

r

struct snd_ratnums constraints

Name

snd_pcm_hw_constraint_ratdens — apply ratdens constraint to a parameter

Synopsis

```
int snd_pcm_hw_constraint_ratdens (runtime,
                                   cond,
                                   var,
                                   r);

struct snd_pcm_runtime *           runtime;
unsigned int                       cond;
snd_pcm_hw_param_t                 var;
struct snd_pcm_hw_constraint_ratdens * r;
```

Arguments

runtime

PCM runtime instance

cond

condition bits

var

hw_params variable to apply the ratdens constraint

r

struct snd_ratdens constraints

Name

snd_pcm_hw_constraint_msbits — add a hw constraint msbits rule

Synopsis

```
int snd_pcm_hw_constraint_msbits (runtime,
                                cond,
                                width,
                                msbits);
```

```
struct snd_pcm_runtime * runtime;
unsigned int             cond;
unsigned int             width;
unsigned int             msbits;
```

Arguments

runtime

PCM runtime instance

cond

condition bits

width

sample bits width

msbits

msbits width

Name

`snd_pcm_hw_constraint_step` — add a hw constraint step rule

Synopsis

```
int snd_pcm_hw_constraint_step (runtime,
                                cond,
                                var,
                                step);
```

```
struct snd_pcm_runtime * runtime;
unsigned int             cond;
snd_pcm_hw_param_t      var;
unsigned long            step;
```

Arguments

runtime

PCM runtime instance

cond

condition bits

var

hw_params variable to apply the step constraint

step

step size

Name

`snd_pcm_hw_constraint_pow2` — add a hw constraint power-of-2 rule

Synopsis

```
int snd_pcm_hw_constraint_pow2 (runtime,
                                cond,
                                var);
```

```
struct snd_pcm_runtime * runtime;
unsigned int             cond;
snd_pcm_hw_param_t       var;
```

Arguments

runtime

PCM runtime instance

cond

condition bits

var

hw_params variable to apply the power-of-2 constraint

Name

`snd_pcm_hw_param_value` — return *params* field *var* value

Synopsis

```
int snd_pcm_hw_param_value (params,
                           var,
                           dir);

const struct snd_pcm_hw_params * params;
snd_pcm_hw_param_t             var;
int *                          dir;
```

Arguments

params

the hw_params instance

var

parameter to retrieve

dir

pointer to the direction (-1,0,1) or NULL

Description

Return the value for field *var* if it's fixed in configuration space defined by *params*. Return `-EINVAL` otherwise.

Name

`snd_pcm_hw_param_first` — refine config space and return minimum value

Synopsis

```
int snd_pcm_hw_param_first (pcm,
                           params,
                           var,
                           dir);

struct snd_pcm_substream * pcm;
struct snd_pcm_hw_params * params;
snd_pcm_hw_param_t       var;
int *                     dir;
```

Arguments

pcm

PCM instance

params

the hw_params instance

var

parameter to retrieve

dir

pointer to the direction (-1,0,1) or NULL

Description

Inside configuration space defined by *params* remove from *var* all values > minimum. Reduce configuration space accordingly. Return the minimum.

Name

snd_pcm_hw_param_last — refine config space and return maximum value

Synopsis

```
int snd_pcm_hw_param_last (pcm,
                           params,
                           var,
                           dir);
```

```
struct snd_pcm_substream * pcm;
struct snd_pcm_hw_params * params;
snd_pcm_hw_param_t       var;
int *                    dir;
```

Arguments

pcm

PCM instance

params

the hw_params instance

var

parameter to retrieve

dir

pointer to the direction (-1,0,1) or NULL

Description

Inside configuration space defined by *params* remove from *var* all values < maximum. Reduce configuration space accordingly. Return the maximum.

Name

snd_pcm_lib_ioctl — a generic PCM ioctl callback

Synopsis

```
int snd_pcm_lib_ioctl (substream,
                      cmd,
                      arg);

struct snd_pcm_substream * substream;
unsigned int               cmd;
void *                     arg;
```

Arguments

substream

the pcm substream instance

cmd

ioctl command

arg

ioctl argument

Description

Processes the generic ioctl commands for PCM. Can be passed as the ioctl callback for PCM ops.

Returns zero if successful, or a negative error code on failure.

Name

`snd_pcm_period_elapsed` — update the pcm status for the next period

Synopsis

```
void snd_pcm_period_elapsed (substream);
```

```
struct snd_pcm_substream * substream;
```

Arguments

substream

the pcm substream instance

Description

This function is called from the interrupt handler when the PCM has processed the period size. It will update the current pointer, wake up sleepers, etc.

Even if more than one periods have elapsed since the last call, you have to call this only once.

Name

`snd_pcm_stop` — try to stop all running streams in the substream group

Synopsis

```
int snd_pcm_stop (substream,  
                  state);
```

```
struct snd_pcm_substream * substream;  
int                        state;
```

Arguments

substream

the PCM substream instance

state

PCM state after stopping the stream

Description

The state of each stream is then changed to the given state unconditionally.

Name

`snd_pcm_suspend` — trigger SUSPEND to all linked streams

Synopsis

```
int snd_pcm_suspend (substream);  
  
struct snd_pcm_substream * substream;
```

Arguments

substream

the PCM substream

Description

After this call, all streams are changed to SUSPENDED state.

Name

`snd_pcm_suspend_all` — trigger SUSPEND to all substreams in the given pcm

Synopsis

```
int snd_pcm_suspend_all (pcm);  
  
struct snd_pcm * pcm;
```

Arguments

pcm

the PCM instance

Description

After this call, all streams are changed to SUSPENDED state.

PCM Format Helpers

Name

`snd_pcm_format_signed` — Check the PCM format is signed linear

Synopsis

```
int snd_pcm_format_signed (format);
```

```
snd_pcm_format_t format;
```

Arguments

format

the format to check

Description

Returns 1 if the given PCM format is signed linear, 0 if unsigned linear, and a negative error code for non-linear formats.

Name

`snd_pcm_format_unsigned` — Check the PCM format is unsigned linear

Synopsis

```
int snd_pcm_format_unsigned (format);
```

```
snd_pcm_format_t format;
```

Arguments

format

the format to check

Description

Returns 1 if the given PCM format is unsigned linear, 0 if signed linear, and a negative error code for non-linear formats.

Name

snd_pcm_format_linear — Check the PCM format is linear

Synopsis

```
int snd_pcm_format_linear (format);
```

```
snd_pcm_format_t format;
```

Arguments

format

the format to check

Description

Returns 1 if the given PCM format is linear, 0 if not.

Name

snd_pcm_format_little_endian — Check the PCM format is little-endian

Synopsis

```
int snd_pcm_format_little_endian (format);
```

```
snd_pcm_format_t format;
```

Arguments

format

the format to check

Description

Returns 1 if the given PCM format is little-endian, 0 if big-endian, or a negative error code if endian not specified.

Name

snd_pcm_format_big_endian — Check the PCM format is big-endian

Synopsis

```
int snd_pcm_format_big_endian (format);

snd_pcm_format_t format;
```

Arguments

format

the format to check

Description

Returns 1 if the given PCM format is big-endian, 0 if little-endian, or a negative error code if endian not specified.

Name

snd_pcm_format_width — return the bit-width of the format

Synopsis

```
int snd_pcm_format_width (format);

snd_pcm_format_t format;
```

Arguments

format

the format to check

Description

Returns the bit-width of the format, or a negative error code if unknown format.

Name

snd_pcm_format_physical_width — return the physical bit-width of the format

Synopsis

```
int snd_pcm_format_physical_width (format);
```

```
snd_pcm_format_t format;
```

Arguments

format

the format to check

Description

Returns the physical bit-width of the format, or a negative error code if unknown format.

Name

`snd_pcm_format_size` — return the byte size of samples on the given format

Synopsis

```
ssize_t snd_pcm_format_size (format,  
                             samples);
```

```
snd_pcm_format_t format;  
size_t          samples;
```

Arguments

format

the format to check

samples

sampling rate

Description

Returns the byte size of the given samples for the format, or a negative error code if unknown format.

Name

`snd_pcm_format_silence_64` — return the silent data in 8 bytes array

Synopsis

```
const unsigned char * snd_pcm_format_silence_64 (format);

snd_pcm_format_t format;
```

Arguments

format

the format to check

Description

Returns the format pattern to fill or NULL if error.

Name

`snd_pcm_format_set_silence` — set the silence data on the buffer

Synopsis

```
int snd_pcm_format_set_silence (format,
                                data,
                                samples);

snd_pcm_format_t format;
void *           data;
unsigned int     samples;
```

Arguments

format

the PCM format

data

the buffer pointer

samples

the number of samples to set silence

Description

Sets the silence data on the buffer for the given samples.

Returns zero if successful, or a negative error code on failure.

Name

`snd_pcm_limit_hw_rates` — determine `rate_min`/`rate_max` fields

Synopsis

```
int snd_pcm_limit_hw_rates (runtime);
```

```
struct snd_pcm_runtime * runtime;
```

Arguments

runtime

the runtime instance

Description

Determines the `rate_min` and `rate_max` fields from the rates bits of the given `runtime->hw`.

Returns zero if successful.

Name

`snd_pcm_rate_to_rate_bit` — converts sample rate to `SNDRV_PCM_RATE_XXX` bit

Synopsis

```
unsigned int snd_pcm_rate_to_rate_bit (rate);
```

```
unsigned int rate;
```

Arguments

rate

the sample rate to convert

Description

Returns the `SNDRV_PCM_RATE_XXX` flag that corresponds to the given rate, or

SNDRV_PCM_RATE_KNOT for an unknown rate.

PCM Memory Management

Name

snd_pcm_lib_preallocate_free_for_all — release all pre-allocated buffers on the pcm

Synopsis

```
int snd_pcm_lib_preallocate_free_for_all (pcm);
```

```
struct snd_pcm * pcm;
```

Arguments

pcm

the pcm instance

Description

Releases all the pre-allocated buffers on the given pcm.

Returns zero if successful, or a negative error code on failure.

Name

snd_pcm_lib_preallocate_pages — pre-allocation for the given DMA type

Synopsis

```
int snd_pcm_lib_preallocate_pages (substream,
                                   type,
                                   data,
                                   size,
                                   max);
```

```
struct snd_pcm_substream * substream;
int type;
struct device * data;
size_t size;
size_t max;
```

Arguments

substream

the pcm substream instance

type

DMA type (SND`DRV`_DMA_TYPE_*)

data

DMA type dependant data

size

the requested pre-allocation size in bytes

max

the max. allowed pre-allocation size

Description

Do pre-allocation for the given DMA buffer type.

When `substream->dma_buf_id` is set, the function tries to look for the reserved buffer, and the buffer is not freed but reserved at destruction time. The `dma_buf_id` must be unique for all systems (in the same DMA buffer type) e.g. using `snd_dma_pci_buf_id`.

Returns zero if successful, or a negative error code on failure.

Name

`snd_pcm_lib_preallocate_pages_for_all` — pre-allocation for continous memory type (all substreams)

Synopsis

```
int snd_pcm_lib_preallocate_pages_for_all (pcm,
                                           type,
                                           data,
                                           size,
                                           max);
```

```
struct snd_pcm * pcm;
int             type;
void *         data;
size_t         size;
size_t         max;
```

Arguments

pcm

the pcm instance

type

DMA type (SNDRV_DMA_TYPE_*)

data

DMA type dependant data

size

the requested pre-allocation size in bytes

max

the max. allowed pre-allocation size

Description

Do pre-allocation to all substreams of the given pcm for the specified DMA type.

Returns zero if successful, or a negative error code on failure.

Name

snd_pcm_sgbuf_ops_page — get the page struct at the given offset

Synopsis

```
struct page * snd_pcm_sgbuf_ops_page (substream,  
                                         offset);
```

```
struct snd_pcm_substream * substream;  
unsigned long              offset;
```

Arguments

substream

the pcm substream instance

offset

the buffer offset

Description

Returns the page struct at the given buffer offset. Used as the page callback of PCM ops.

Name

`snd_pcm_lib_malloc_pages` — allocate the DMA buffer

Synopsis

```
int snd_pcm_lib_malloc_pages (substream,  
                             size);
```

```
struct snd_pcm_substream * substream;  
size_t                    size;
```

Arguments

substream

the substream to allocate the DMA buffer to

size

the requested buffer size in bytes

Description

Allocates the DMA buffer on the BUS type given earlier to `snd_pcm_lib_preallocate_XXX_pages`.

Returns 1 if the buffer is changed, 0 if not changed, or a negative code on failure.

Name

`snd_pcm_lib_free_pages` — release the allocated DMA buffer.

Synopsis

```
int snd_pcm_lib_free_pages (substream);
```

```
struct snd_pcm_substream * substream;
```

Arguments

substream

the substream to release the DMA buffer

Description

Releases the DMA buffer allocated via `snd_pcm_lib_malloc_pages`.

Returns zero if successful, or a negative error code on failure.

Chapter 3. Control/Mixer API

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General Control Interface

Name

`snd_ctl_new1` — create a control instance from the template

Synopsis

```
struct snd_kcontrol * snd_ctl_new1 (ncontrol,
                                     private_data);
```

```
const struct snd_kcontrol_new * ncontrol;
void * private_data;
```

Arguments

ncontrol

the initialization record

private_data

the private data to set

Description

Allocates a new struct `snd_kcontrol` instance and initialize from the given template. When the access field of `ncontrol` is 0, it's assumed as READWRITE access. When the count field is 0, it's assumes as one.

Returns the pointer of the newly generated instance, or NULL on failure.

Name

`snd_ctl_free_one` — release the control instance

Synopsis

```
void snd_ctl_free_one (kcontrol);  
  
struct snd_kcontrol * kcontrol;
```

Arguments

kcontrol

the control instance

Description

Releases the control instance created via `snd_ctl_new` or `snd_ctl_new1`. Don't call this after the control was added to the card.

Name

`snd_ctl_add` — add the control instance to the card

Synopsis

```
int snd_ctl_add (card,  
                 kcontrol);  
  
struct snd_card *      card;  
struct snd_kcontrol * kcontrol;
```

Arguments

card

the card instance

kcontrol

the control instance to add

Description

Adds the control instance created via `snd_ctl_new` or `snd_ctl_new1` to the given card. Assigns also an unique numid used for fast search.

Returns zero if successful, or a negative error code on failure.

It frees automatically the control which cannot be added.

Name

`snd_ctl_remove` — remove the control from the card and release it

Synopsis

```
int snd_ctl_remove (card,  
                    kcontrol);
```

```
struct snd_card *      card;  
struct snd_kcontrol *  kcontrol;
```

Arguments

card

the card instance

kcontrol

the control instance to remove

Description

Removes the control from the card and then releases the instance. You don't need to call `snd_ctl_free_one`. You must be in the write lock - `down_write(card->controls_rwsem)`.

Returns 0 if successful, or a negative error code on failure.

Name

`snd_ctl_remove_id` — remove the control of the given id and release it

Synopsis

```
int snd_ctl_remove_id (card,
```



```
    id);
```

```
struct snd_card *      card;  
struct snd_ctl_elem_id * id;
```

Arguments

card

the card instance

id

the control id to remove

Description

Finds the control instance with the given id, removes it from the card list and releases it.

Returns 0 if successful, or a negative error code on failure.

Name

`snd_ctl_rename_id` — replace the id of a control on the card

Synopsis

```
int snd_ctl_rename_id (card,  
                       src_id,  
                       dst_id);
```

```
struct snd_card *      card;  
struct snd_ctl_elem_id * src_id;  
struct snd_ctl_elem_id * dst_id;
```

Arguments

card

the card instance

src_id

the old id

dst_id

the new id

Description

Finds the control with the old id from the card, and replaces the id with the new one.

Returns zero if successful, or a negative error code on failure.

Name

`snd_ctl_find_numid` — find the control instance with the given number-id

Synopsis

```
struct snd_kcontrol * snd_ctl_find_numid (card,  
                                           numid);
```

```
struct snd_card * card;  
unsigned int      numid;
```

Arguments

card

the card instance

numid

the number-id to search

Description

Finds the control instance with the given number-id from the card.

Returns the pointer of the instance if found, or NULL if not.

The caller must down `card->controls_rwsem` before calling this function (if the race condition can happen).

Name

`snd_ctl_find_id` — find the control instance with the given id

Synopsis

```
struct snd_kcontrol * snd_ctl_find_id (card,  
                                         id);
```

```
struct snd_card *      card;  
struct snd_ctl_elem_id * id;
```

Arguments

card

the card instance

id

the id to search

Description

Finds the control instance with the given id from the card.

Returns the pointer of the instance if found, or NULL if not.

The caller must down `card->controls_rwsem` before calling this function (if the race condition can happen).

AC97 Codec API

Name

`snd_ac97_write` — write a value on the given register

Synopsis

```
void snd_ac97_write (ac97,  
                    reg,  
                    value);
```

```
struct snd_ac97 * ac97;  
unsigned short    reg;  
unsigned short    value;
```

Arguments

ac97

the ac97 instance

reg

the register to change

value

the value to set

Description

Writes a value on the given register. This will invoke the write callback directly after the register check. This function doesn't change the register cache unlike `#snd_ca97_write_cache`, so use this only when you don't want to reflect the change to the suspend/resume state.

Name

`snd_ac97_read` — read a value from the given register

Synopsis

```
unsigned short snd_ac97_read (ac97,
                               reg);
```

```
struct snd_ac97 * ac97;
unsigned short    reg;
```

Arguments

ac97

the `ac97` instance

reg

the register to read

Description

Reads a value from the given register. This will invoke the read callback directly after the register check.

Returns the read value.

Name

`snd_ac97_write_cache` — write a value on the given register and update the cache

Synopsis

```
void snd_ac97_write_cache (ac97,
```

```
    reg,  
    value);
```

```
struct snd_ac97 * ac97;  
unsigned short   reg;  
unsigned short   value;
```

Arguments

ac97

the ac97 instance

reg

the register to change

value

the value to set

Description

Writes a value on the given register and updates the register cache. The cached values are used for the cached-read and the suspend/resume.

Name

snd_ac97_update — update the value on the given register

Synopsis

```
int snd_ac97_update (ac97,  
                    reg,  
                    value);
```

```
struct snd_ac97 * ac97;  
unsigned short   reg;  
unsigned short   value;
```

Arguments

ac97

the ac97 instance

reg

the register to change

value

the value to set

Description

Compares the value with the register cache and updates the value only when the value is changed.

Returns 1 if the value is changed, 0 if no change, or a negative code on failure.

Name

`snd_ac97_update_bits` — update the bits on the given register

Synopsis

```
int snd_ac97_update_bits (ac97,
                          reg,
                          mask,
                          value);
```

```
struct snd_ac97 * ac97;
unsigned short    reg;
unsigned short    mask;
unsigned short    value;
```

Arguments

ac97

the *ac97* instance

reg

the register to change

mask

the bit-mask to change

value

the value to set

Description

Updates the masked-bits on the given register only when the value is changed.

Returns 1 if the bits are changed, 0 if no change, or a negative code on failure.

Name

`snd_ac97_get_short_name` — retrieve codec name

Synopsis

```
const char * snd_ac97_get_short_name (ac97);
```

```
struct snd_ac97 * ac97;
```

Arguments

ac97

the codec instance

Description

Returns the short identifying name of the codec.

Name

`snd_ac97_bus` — create an AC97 bus component

Synopsis

```
int snd_ac97_bus (card,  
                  num,  
                  ops,  
                  private_data,  
                  rbus);
```

```
struct snd_card *      card;  
int                  num;  
struct snd_ac97_bus_ops * ops;  
void *                private_data;  
struct snd_ac97_bus ** rbus;
```

Arguments

card

the card instance

num

the bus number

ops

the bus callbacks table

private_data

private data pointer for the new instance

rbus

the pointer to store the new AC97 bus instance.

Description

Creates an AC97 bus component. An struct `snd_ac97_bus` instance is newly allocated and initialized.

The ops table must include valid callbacks (at least read and write). The other callbacks, wait and reset, are not mandatory.

The clock is set to 48000. If another clock is needed, set `(*rbus)->clock` manually.

The AC97 bus instance is registered as a low-level device, so you don't have to release it manually.

Returns zero if successful, or a negative error code on failure.

Name

`snd_ac97_mixer` — create an Codec97 component

Synopsis

```
int snd_ac97_mixer (bus,  
                  template,  
                  rac97);  
  
struct snd_ac97_bus *      bus;  
struct snd_ac97_template * template;  
struct snd_ac97 **        rac97;
```

Arguments

bus

the AC97 bus which codec is attached to

template

the template of ac97, including index, callbacks and the private data.

rac97

the pointer to store the new ac97 instance.

Description

Creates an Codec97 component. An struct `snd_ac97` instance is newly allocated and initialized from the template. The codec is then initialized by the standard procedure.

The template must include the codec number (`num`) and address (`addr`), and the private data (`private_data`).

The ac97 instance is registered as a low-level device, so you don't have to release it manually.

Returns zero if successful, or a negative error code on failure.

Name

`snd_ac97_update_power` — update the powerdown register

Synopsis

```
int snd_ac97_update_power (ac97,  
                           reg,  
                           powerup);
```

```
struct snd_ac97 * ac97;  
int              reg;  
int              powerup;
```

Arguments

ac97

the codec instance

reg

the rate register, e.g. `AC97_PCM_FRONT_DAC_RATE`

powerup

non-zero when power up the part

Description

Update the AC97 powerdown register bits of the given part.

Name

`snd_ac97_suspend` — General suspend function for AC97 codec

Synopsis

```
void snd_ac97_suspend (ac97);
```

```
struct snd_ac97 * ac97;
```

Arguments

ac97

the *ac97* instance

Description

Suspends the codec, power down the chip.

Name

`snd_ac97_resume` — General resume function for AC97 codec

Synopsis

```
void snd_ac97_resume (ac97);
```

```
struct snd_ac97 * ac97;
```

Arguments

ac97

the *ac97* instance

Description

Do the standard resume procedure, power up and restoring the old register values.

Name

`snd_ac97_tune_hardware` — tune up the hardware

Synopsis

```
int snd_ac97_tune_hardware (ac97,  
                           quirk,  
                           override);
```

```
struct snd_ac97 *   ac97;  
struct ac97_quirk * quirk;  
const char *        override;
```

Arguments

ac97

the `ac97` instance

quirk

quirk list

override

explicit quirk value (overrides the list if non-NULL)

Description

Do some workaround for each pci device, such as renaming of the headphone (true line-out) control as “Master”. The quirk-list must be terminated with a zero-filled entry.

Returns zero if successful, or a negative error code on failure.

Name

`snd_ac97_set_rate` — change the rate of the given input/output.

Synopsis

```
int snd_ac97_set_rate (ac97,  
                      reg,  
                      rate);
```

```
struct snd_ac97 * ac97;
int reg;
unsigned int rate;
```

Arguments

ac97

the ac97 instance

reg

the register to change

rate

the sample rate to set

Description

Changes the rate of the given input/output on the codec. If the codec doesn't support VAR, the rate must be 48000 (except for SPDIF).

The valid registers are AC97_PMC_MIC_ADC_RATE, AC97_PCM_FRONT_DAC_RATE, AC97_PCM_LR_ADC_RATE. AC97_PCM_SURR_DAC_RATE and AC97_PCM_LFE_DAC_RATE are accepted if the codec supports them. AC97_SPDIF is accepted as a pseudo register to modify the SPDIF status bits.

Returns zero if successful, or a negative error code on failure.

Name

snd_ac97_pcm_assign — assign AC97 slots to given PCM streams

Synopsis

```
int snd_ac97_pcm_assign (bus,
                        pcms_count,
                        pcms);
```

```
struct snd_ac97_bus * bus;
unsigned short pcms_count;
const struct ac97_pcm * pcms;
```

Arguments

bus

the ac97 bus instance

pcms_count

count of PCMs to be assigned

pcms

PCMs to be assigned

Description

It assigns available AC97 slots for given PCMs. If none or only some slots are available, pcm->xxx.slots and pcm->xxx.rslots[] members are reduced and might be zero.

Name

snd_ac97_pcm_open — opens the given AC97 pcm

Synopsis

```
int snd_ac97_pcm_open (pcm,
                      rate,
                      cfg,
                      slots);
```

```
struct ac97_pcm * pcm;
unsigned int      rate;
enum ac97_pcm_cfg cfg;
unsigned short    slots;
```

Arguments

pcm

the ac97 pcm instance

rate

rate in Hz, if codec does not support VRA, this value must be 48000Hz

cfg

output stream characteristics

slots

a subset of allocated slots (snd_ac97_pcm_assign) for this pcm

Description

It locks the specified slots and sets the given rate to AC97 registers.

Name

`snd_ac97_pcm_close` — closes the given AC97 pcm

Synopsis

```
int snd_ac97_pcm_close (pcm);  
  
struct ac97_pcm * pcm;
```

Arguments

pcm
the ac97 pcm instance

Description

It frees the locked AC97 slots.

Name

`snd_ac97_pcm_double_rate_rules` — set double rate constraints

Synopsis

```
int snd_ac97_pcm_double_rate_rules (runtime);  
  
struct snd_pcm_runtime * runtime;
```

Arguments

runtime
the runtime of the ac97 front playback pcm

Description

Installs the hardware constraint rules to prevent using double rates and more than two channels at the

same time.

Virtual Master Control API

Name

`snd_ctl_make_virtual_master` — Create a virtual master control

Synopsis

```
struct snd_kcontrol * snd_ctl_make_virtual_master (name,
                                                    tlv);
```

```
char *                name;
const unsigned int *  tlv;
```

Arguments

name

name string of the control element to create

tlv

optional TLV int array for dB information

Description

Creates a virtual master control with the given name string. Returns the created control element, or NULL for errors (ENOMEM).

After creating a vmaster element, you can add the slave controls via `snd_ctl_add_slave` or `snd_ctl_add_slave_uncached`.

The optional argument *tlv* can be used to specify the TLV information for dB scale of the master control. It should be a single element with `#SNDRV_CTL_TLVT_DB_SCALE`, `#SNDRV_CTL_TLVT_DB_MINMAX` or `#SNDRV_CTL_TLVT_DB_MINMAX_MUTE` type, and should be the max 0dB.

Name

`snd_ctl_add_slave` — Add a virtual slave control

Synopsis

```
int snd_ctl_add_slave (master,
```

```
    slave);
```

```
struct snd_kcontrol * master;  
struct snd_kcontrol * slave;
```

Arguments

master

vmaster element

slave

slave element to add

Description

Add a virtual slave control to the given master element created via `snd_ctl_create_virtual_master` beforehand. Returns zero if successful or a negative error code.

All slaves must be the same type (returning the same information via info callback). The function doesn't check it, so it's your responsibility.

Also, some additional limitations: at most two channels, logarithmic volume control (dB level) thus no linear volume, master can only attenuate the volume without gain

Name

`snd_ctl_add_slave_uncached` — Add a virtual slave control

Synopsis

```
int snd_ctl_add_slave_uncached (master,  
                                slave);
```

```
struct snd_kcontrol * master;  
struct snd_kcontrol * slave;
```

Arguments

master

vmaster element

slave

slave element to add

Description

Add a virtual slave control to the given master. Unlike `snd_ctl_add_slave`, the element added via this function is supposed to have volatile values, and get callback is called at each time queried from the master.

When the control peeks the hardware values directly and the value can be changed by other means than the put callback of the element, this function should be used to keep the value always up-to-date.

Chapter 4. MIDI API

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Raw MIDI API

Name

`snd_rawmidi_receive` — receive the input data from the device

Synopsis

```
int snd_rawmidi_receive (substream,
                        buffer,
                        count);

struct snd_rawmidi_substream * substream;
const unsigned char * buffer;
int count;
```

Arguments

substream

the rawmidi substream

buffer

the buffer pointer

count

the data size to read

Description

Reads the data from the internal buffer.

Returns the size of read data, or a negative error code on failure.

Name

`snd_rawmidi_transmit_empty` — check whether the output buffer is empty

Synopsis

```
int snd_rawmidi_transmit_empty (substream);
```

```
struct snd_rawmidi_substream * substream;
```

Arguments

substream

the rawmidi substream

Description

Returns 1 if the internal output buffer is empty, 0 if not.

Name

`snd_rawmidi_transmit_peek` — copy data from the internal buffer

Synopsis

```
int snd_rawmidi_transmit_peek (substream,  
                                buffer,  
                                count);
```

```
struct snd_rawmidi_substream * substream;  
unsigned char *                buffer;  
int                             count;
```

Arguments

substream

the rawmidi substream

buffer

the buffer pointer

count

data size to transfer

Description

Copies data from the internal output buffer to the given buffer.

Call this in the interrupt handler when the midi output is ready, and call `snd_rawmidi_transmit_ack` after the transmission is finished.

Returns the size of copied data, or a negative error code on failure.

Name

`snd_rawmidi_transmit_ack` — acknowledge the transmission

Synopsis

```
int snd_rawmidi_transmit_ack (substream,
                             count);

struct snd_rawmidi_substream * substream;
int count;
```

Arguments

substream

the rawmidi substream

count

the tranferred count

Description

Advances the hardware pointer for the internal output buffer with the given size and updates the condition. Call after the transmission is finished.

Returns the advanced size if successful, or a negative error code on failure.

Name

`snd_rawmidi_transmit` — copy from the buffer to the device

Synopsis

```
int snd_rawmidi_transmit (substream,  
                           buffer,  
                           count);  
  
struct snd_rawmidi_substream * substream;  
unsigned char *                buffer;  
int                             count;
```

Arguments

substream

the rawmidi substream

buffer

the buffer pointer

count

the data size to transfer

Description

Copies data from the buffer to the device and advances the pointer.

Returns the copied size if successful, or a negative error code on failure.

Name

`snd_rawmidi_new` — create a rawmidi instance

Synopsis

```
int snd_rawmidi_new (card,  
                     id,  
                     device,  
                     output_count,  
                     input_count,  
                     rrawmidi);  
  
struct snd_card *      card;  
char *                 id;  
int                    device;
```

```
int                output_count;
int                input_count;
struct snd_rawmidi ** rrawmidi;
```

Arguments

card

the card instance

id

the id string

device

the device index

output_count

the number of output streams

input_count

the number of input streams

rrawmidi

the pointer to store the new rawmidi instance

Description

Creates a new rawmidi instance. Use `snd_rawmidi_set_ops` to set the operators to the new instance.

Returns zero if successful, or a negative error code on failure.

Name

`snd_rawmidi_set_ops` — set the rawmidi operators

Synopsis

```
void snd_rawmidi_set_ops (rmidi,
                          stream,
                          ops);

struct snd_rawmidi *    rmidi;
int                    stream;
struct snd_rawmidi_ops * ops;
```

Arguments

rmidi

the rawmidi instance

stream

the stream direction, SNDRV_RAWMIDI_STREAM_XXX

ops

the operator table

Description

Sets the rawmidi operators for the given stream direction.

MPU401-UART API

Name

snd_mpu401_uart_interrupt — generic MPU401-UART interrupt handler

Synopsis

```
irqreturn_t snd_mpu401_uart_interrupt (irq,  
                                         dev_id);
```

```
int      irq;  
void *   dev_id;
```

Arguments

irq

the irq number

dev_id

mpu401 instance

Description

Processes the interrupt for MPU401-UART i/o.

Name

`snd_mpu401_uart_interrupt_tx` — generic MPU401-UART transmit irq handler

Synopsis

```
irqreturn_t snd_mpu401_uart_interrupt_tx (irq,
                                           dev_id);
```

```
int      irq;
void *   dev_id;
```

Arguments

irq

the irq number

dev_id

mpu401 instance

Description

Processes the interrupt for MPU401-UART output.

Name

`snd_mpu401_uart_new` — create an MPU401-UART instance

Synopsis

```
int snd_mpu401_uart_new (card,
                        device,
                        hardware,
                        port,
                        info_flags,
                        irq,
                        irq_flags,
                        rrawmidi);
```

```
struct snd_card *   card;
int                 device;
unsigned short      hardware;
unsigned long        port;
unsigned int         info_flags;
int                  irq;
```

```
int                irq_flags;  
struct snd_rawmidi ** rrawmidi;
```

Arguments

card

the card instance

device

the device index, zero-based

hardware

the hardware type, MPU401_HW_XXXX

port

the base address of MPU401 port

info_flags

bitflags MPU401_INFO_XXX

irq

the irq number, -1 if no interrupt for mpu

irq_flags

the irq request flags (SA_XXX), 0 if irq was already reserved.

rrawmidi

the pointer to store the new rawmidi instance

Description

Creates a new MPU-401 instance.

Note that the rawmidi instance is returned on the rrawmidi argument, not the mpu401 instance itself. To access to the mpu401 instance, cast from rawmidi->private_data (with struct snd_mpu401 magic-cast).

Returns zero if successful, or a negative error code.

Chapter 5. Proc Info API

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[Proc Info Interface](#)

Proc Info Interface

Name

`snd_iprintf` — `printf` on the `procfs` buffer

Synopsis

```
int snd_iprintf (buffer,  
                fmt,  
                ...);
```

```
struct snd_info_buffer * buffer;  
const char *             fmt;  
                        ...;
```

Arguments

buffer

the `procfs` buffer

fmt

the `printf` format

...

variable arguments

Description

Outputs the string on the `procfs` buffer just like `printf`.

Returns the size of output string.

Name

`snd_info_get_line` — read one line from the `procfs` buffer

Synopsis

```
int snd_info_get_line (buffer,  
                      line,  
                      len);
```

```
struct snd_info_buffer * buffer;  
char * line;  
int len;
```

Arguments

buffer

the procfs buffer

line

the buffer to store

len

the max. buffer size - 1

Description

Reads one line from the buffer and stores the string.

Returns zero if successful, or 1 if error or EOF.

Name

snd_info_get_str — parse a string token

Synopsis

```
const char * snd_info_get_str (dest,  
                                src,  
                                len);
```

```
char * dest;  
const char * src;  
int len;
```

Arguments

dest

the buffer to store the string token

src

the original string

len

the max. length of token - 1

Description

Parses the original string and copy a token to the given string buffer.

Returns the updated pointer of the original string so that it can be used for the next call.

Name

`snd_info_create_module_entry` — create an info entry for the given module

Synopsis

```
struct snd_info_entry * snd_info_create_module_entry (module,  
                                                    name,  
                                                    parent);  
  
struct module *           module;  
const char *             name;  
struct snd_info_entry *   parent;
```

Arguments

module

the module pointer

name

the file name

parent

the parent directory

Description

Creates a new info entry and assigns it to the given module.

Returns the pointer of the new instance, or NULL on failure.

Name

`snd_info_create_card_entry` — create an info entry for the given card

Synopsis

```
struct snd_info_entry * snd_info_create_card_entry (card,  
                                                    name,  
                                                    parent);
```

```
struct snd_card *      card;  
const char *          name;  
struct snd_info_entry * parent;
```

Arguments

card

the card instance

name

the file name

parent

the parent directory

Description

Creates a new info entry and assigns it to the given card.

Returns the pointer of the new instance, or NULL on failure.

Name

`snd_card_proc_new` — create an info entry for the given card

Synopsis

```
int snd_card_proc_new (card,  
                      name,  
                      entryp);
```

```
struct snd_card *      card;  
const char *          name;  
struct snd_info_entry ** entryp;
```

Arguments

card

the card instance

name

the file name

entryp

the pointer to store the new info entry

Description

Creates a new info entry and assigns it to the given card. Unlike `snd_info_create_card_entry`, this function registers the info entry as an ALSA device component, so that it can be unregistered/released without explicit call. Also, you don't have to register this entry via `snd_info_register`, since this will be registered by `snd_card_register` automatically.

The parent is assumed as `card->proc_root`.

For releasing this entry, use `snd_device_free` instead of `snd_info_free_entry`.

Returns zero if successful, or a negative error code on failure.

Name

`snd_info_free_entry` — release the info entry

Synopsis

```
void snd_info_free_entry (entry);
```

```
struct snd_info_entry * entry;
```

Arguments

entry

the info entry

Description

Releases the info entry. Don't call this after registered.

Name

`snd_info_register` — register the info entry

Synopsis

```
int snd_info_register (entry);

struct snd_info_entry * entry;
```

Arguments

entry
the info entry

Description

Registers the proc info entry.

Returns zero if successful, or a negative error code on failure.

Chapter 6. Miscellaneous Functions

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Hardware-Dependent Devices API

Name

`snd_hwdep_new` — create a new hwdep instance

Synopsis

```
int snd_hwdep_new (card,
                  id,
                  device,
                  rhwddep);

struct snd_card *    card;
char *              id;
int                 device;
struct snd_hwdep ** rhwddep;
```

Arguments

card

the card instance

id

the id string

device

the device index (zero-based)

rhwddep

the pointer to store the new hwdep instance

Description

Creates a new hwdep instance with the given index on the card. The callbacks (hwdep->ops) must be set on the returned instance after this call manually by the caller.

Returns zero if successful, or a negative error code on failure.

Jack Abstraction Layer API

Name

snd_jack_new — Create a new jack

Synopsis

```
int snd_jack_new (card,  
                 id,  
                 type,  
                 jjack);  
  
struct snd_card *   card;  
const char *        id;  
int                 type;  
struct snd_jack **  jjack;
```

Arguments

card

the card instance

id

an identifying string for this jack

type

a bitmask of enum `snd_jack_type` values that can be detected by this jack

jjack

Used to provide the allocated jack object to the caller.

Description

Creates a new jack object.

Returns zero if successful, or a negative error code on failure. On success `jjack` will be initialised.

Name

`snd_jack_set_parent` — Set the parent device for a jack

Synopsis

```
void snd_jack_set_parent (jack,  
                        parent);
```

```
struct snd_jack * jack;  
struct device * parent;
```

Arguments

jack

The jack to configure

parent

The device to set as parent for the jack.

Description

Set the parent for the jack input device in the device tree. This function is only valid prior to registration of the jack. If no parent is configured then the parent device will be the sound card.

Name

`snd_jack_report` — Report the current status of a jack

Synopsis

```
void snd_jack_report (jack,  
                     status);
```

```
struct snd_jack * jack;  
int              status;
```

Arguments

jack

The jack to report status for

status

The current status of the jack

ISA DMA Helpers

Name

`snd_dma_program` — program an ISA DMA transfer

Synopsis

```
void snd_dma_program (dma,  
                     addr,  
                     size,  
                     mode);
```

```
unsigned long dma;  
unsigned long addr;  
unsigned int  size;  
unsigned short mode;
```

Arguments

dma

the dma number

addr

the physical address of the buffer

size

the DMA transfer size

mode

the DMA transfer mode, DMA_MODE_XXX

Description

Programs an ISA DMA transfer for the given buffer.

Name

snd_dma_disable — stop the ISA DMA transfer

Synopsis

```
void snd_dma_disable (dma);
```

```
unsigned long dma;
```

Arguments

dma

the dma number

Description

Stops the ISA DMA transfer.

Name

snd_dma_pointer — return the current pointer to DMA transfer buffer in bytes

Synopsis

```
unsigned int snd_dma_pointer (dma,  
                               size);
```

```
unsigned long dma;
```

```
unsigned int size;
```

Arguments

dma

the dma number

size

the dma transfer size

Description

Returns the current pointer in DMA tranfer buffer in bytes

Other Helper Macros

Name

`snd_register_device` — Register the ALSA device file for the card

Synopsis

```
int snd_register_device (type,
                        card,
                        dev,
                        f_ops,
                        private_data,
                        name);

int                                type;
struct snd_card *                 card;
int                                dev;
const struct file_operations *    f_ops;
void *                            private_data;
const char *                      name;
```

Arguments

type

the device type, `SNDRV_DEVICE_TYPE_XXX`

card

the card instance

dev

the device index

f_ops

the file operations

private_data

user pointer for *f_ops->open*

name

the device file name

Description

Registers an ALSA device file for the given card. The operators have to be set in *reg* parameter.

This function uses the card's device pointer to link to the correct struct device.

Returns zero if successful, or a negative error code on failure.

Name

snd_printk — *printk* wrapper

Synopsis

```
snd_printk (fmt,  
            args...);
```

```
fmt;  
args...;
```

Arguments

fmt

format string

args...

variable arguments

Description

Works like *printk* but prints the file and the line of the caller when configured with *CONFIG_SND_VERBOSE_PRINTK*.

Name

`snd_printd` — debug printk

Synopsis

```
snd_printd (fmt,  
            args...);
```

```
fmt;  
args...;
```

Arguments

fmt

format string

args...

variable arguments

Description

Works like `snd_printk` for debugging purposes. Ignored when `CONFIG_SND_DEBUG` is not set.

Name

`snd_BUG` — give a BUG warning message and stack trace

Synopsis

```
snd_BUG ();
```

Arguments

None

Description

Calls `WARN` if `CONFIG_SND_DEBUG` is set. Ignored when `CONFIG_SND_DEBUG` is not set.

Name

`snd_BUG_ON` — debugging check macro

Synopsis

```
snd_BUG_ON (cond);
```

```
cond;
```

Arguments

cond

condition to evaluate

Description

When `CONFIG_SND_DEBUG` is set, this macro evaluates the given condition, and call `WARN` and returns the value if it's non-zero.

When `CONFIG_SND_DEBUG` is not set, this just returns zero, and the given condition is ignored.

NOTE

the argument won't be evaluated at all when `CONFIG_SND_DEBUG=n`. Thus, don't put any statement that influences on the code behavior, such as pre/post increment, to the argument of this macro. If you want to evaluate and give a warning, use standard `WARN_ON`.

Name

`snd_printdd` — debug printk

Synopsis

```
snd_printdd (format,  
             args...);
```

```
format;
```

```
args...;
```

Arguments

format

format string

args...

variable arguments

Description

Works like `snd_printk` for debugging purposes. Ignored when `CONFIG_SND_DEBUG_VERBOSE` is not set.